Clustering Lecture 12

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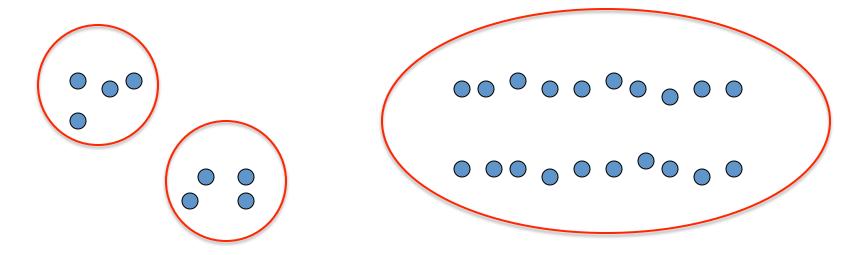
Slides adapted from Luke Zettlemoyer, Vibhav Gogate, Carlos Guestrin, Andrew Moore, Dan Klein

Clustering:

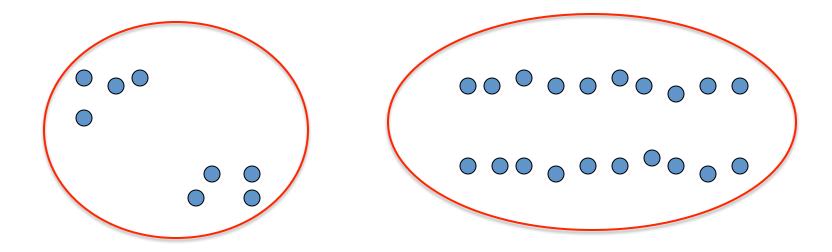
- Unsupervised learning
- Requires data, but no labels
- Detect patterns e.g. in
 - Group emails or search results
 - Customer shopping patterns
 - Regions of images
- Useful when don't know what you're looking for
- But: can get gibberish



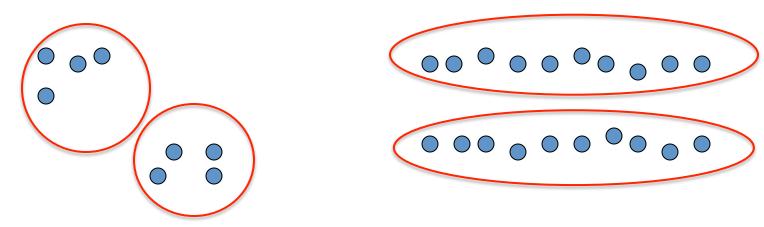
- Basic idea: group together similar instances
- Example: 2D point patterns



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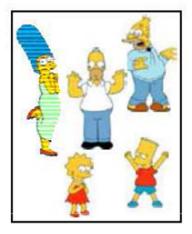
- What could "similar" mean?
 - One option: small Euclidean distance (squared)

$$\operatorname{dist}(\vec{x}, \vec{y}) = ||\vec{x} - \vec{y}||_2^2$$

 Clustering results are crucially dependent on the measure of similarity (or distance) between "points" to be clustered

Clustering algorithms

- Partition algorithms (Flat)
 - K-means
 - Mixture of Gaussian
 - Spectral Clustering





- Hierarchical algorithms
 - Bottom up agglomerative
 - Top down divisive

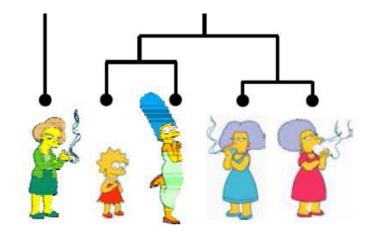
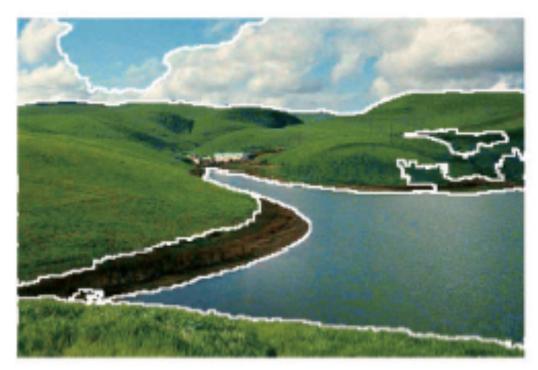
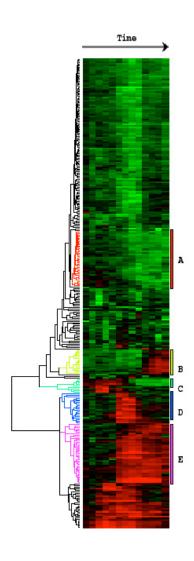


Image segmentation

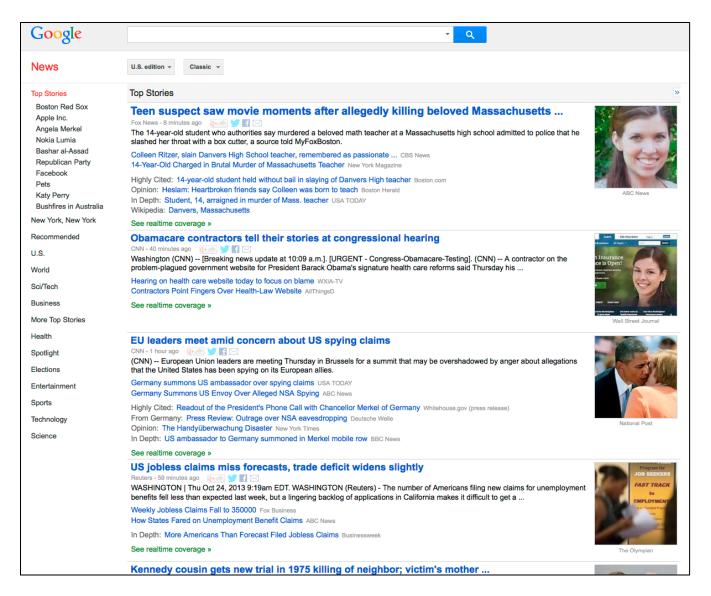
Goal: Break up the image into meaningful or perceptually similar regions



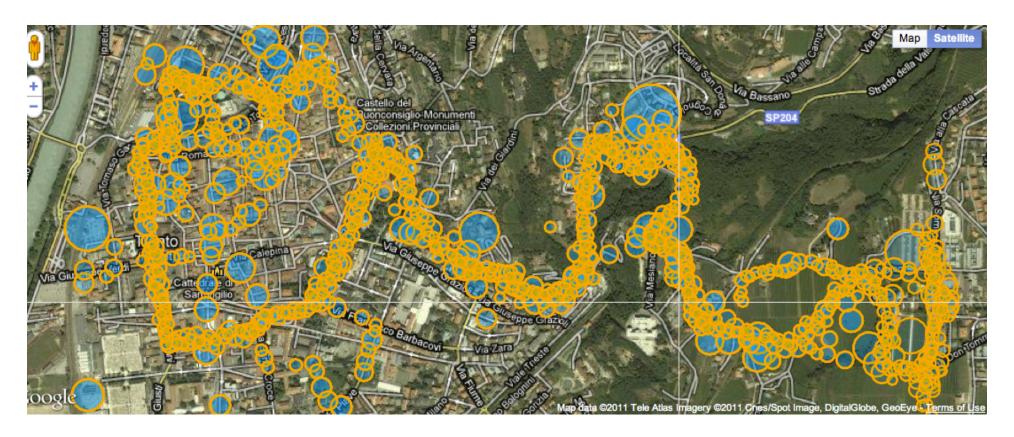
Clustering gene expression data



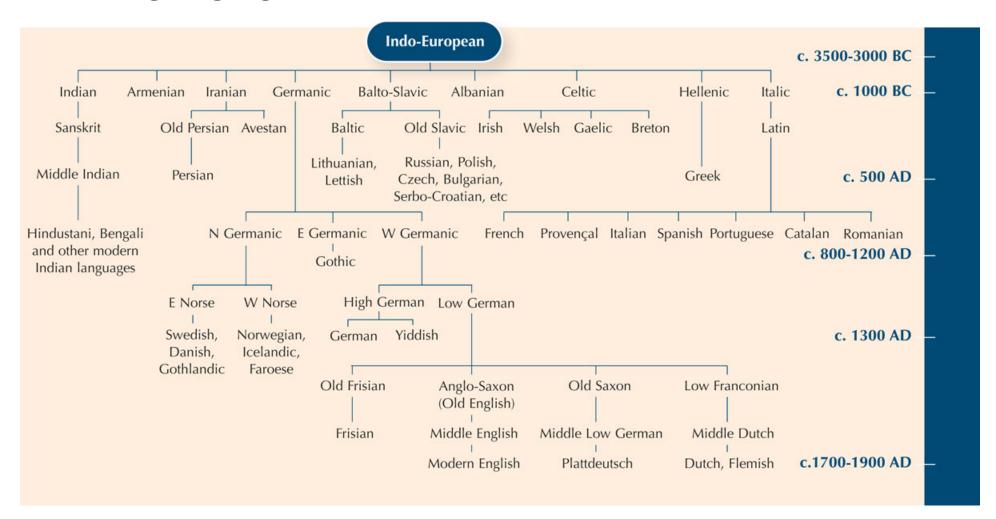
Cluster news articles



Cluster people by space and time

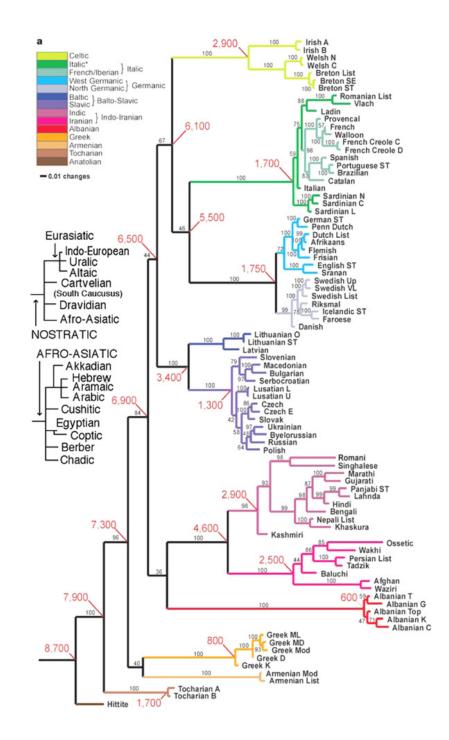


Clustering languages



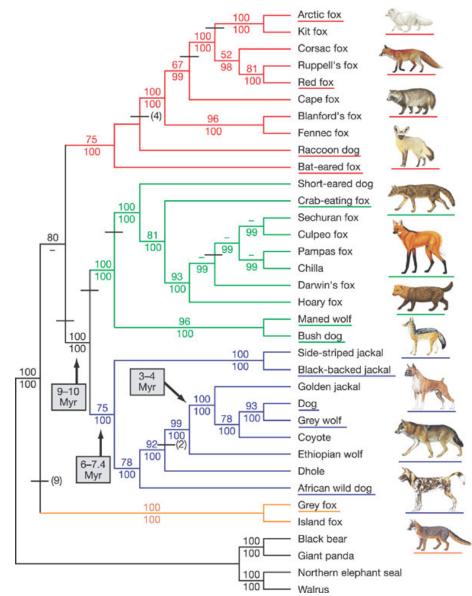
[Image from scienceinschool.org]

Clustering languages



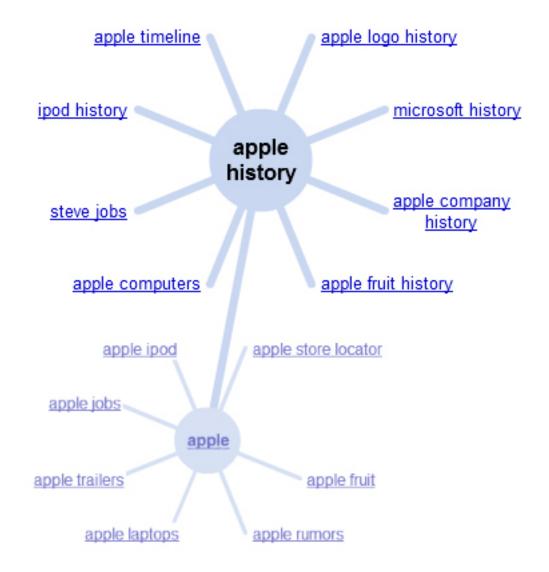
[Image from dhushara.com]

Clustering species ("phylogeny")



[Lindblad-Toh et al., Nature 2005]

Clustering search queries

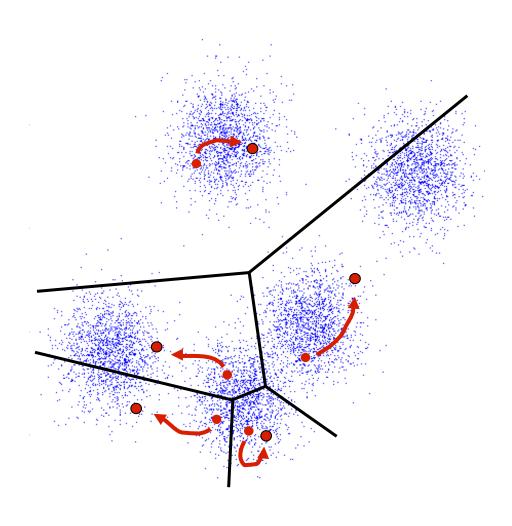


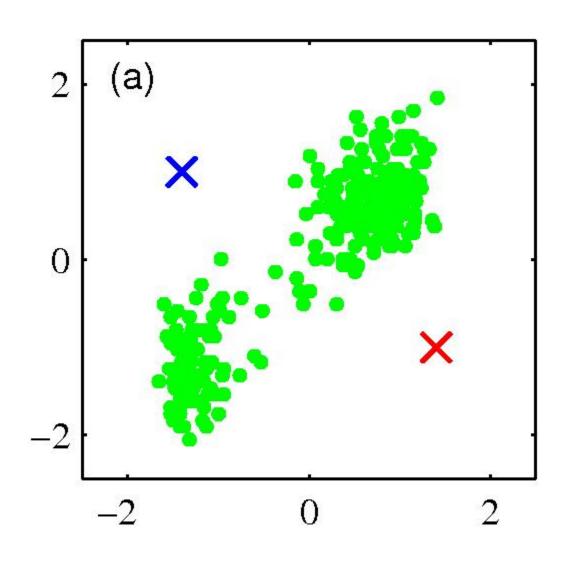
K-Means

- An iterative clustering algorithm
 - Initialize: Pick K random points as cluster centers
 - Alternate:
 - 1. Assign data points to closest cluster center
 - 2. Change the cluster center to the average of its assigned points
 - Stop when no points' assignments change

K-Means

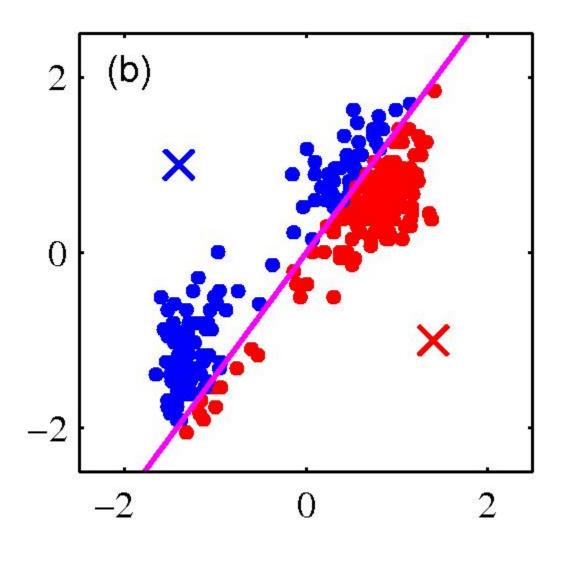
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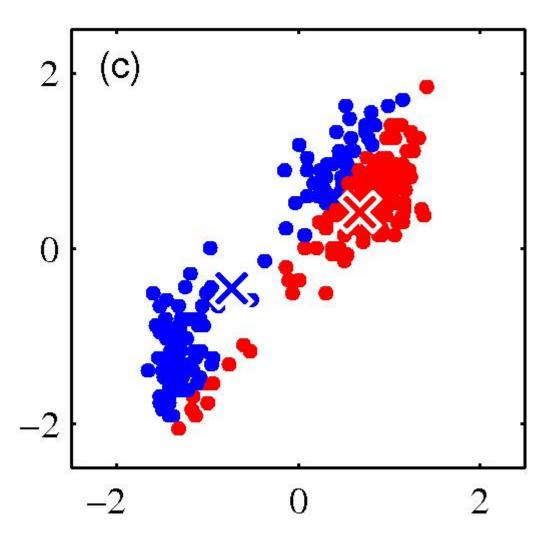
 Pick K random points as cluster centers (means)

Shown here for *K*=2



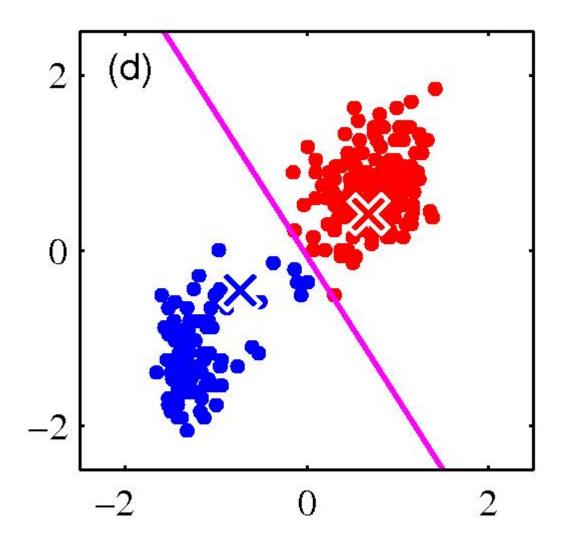
Iterative Step 1

 Assign data points to closest cluster center



Iterative Step 2

 Change the cluster center to the average of the assigned points



 Repeat until convergence

Properties of K-means algorithm

Guaranteed to converge in a finite number of iterations

- Running time per iteration:
 - 1. Assign data points to closest cluster center

O(KN) time

2. Change the cluster center to the average of its assigned points

O(N)

Kmeans Convergence

Objective

$$\min_{\mu} \min_{C} \sum_{i=1}^{k} \sum_{x \in C_i} |x - \mu_i|^2$$

Fix μ , optimize C:

optimize *C*:
$$\min_{C} \sum_{i=1}^{k} \sum_{x \in C_i} |x - \mu_i|^2 = \min_{C} \sum_{i} |x_i - \mu_{x_i}|^2$$
Step 1 of kmeans

2. Fix C, optimize μ :

$$\min_{\mu} \sum_{i=1}^k \sum_{x \in C_i} |x - \mu_i|^2$$

– Take partial derivative $\phi f \mu_i$ and set to zero, we have with respect to

$$\mu_i = \frac{1}{|C_i|} \sum_{x \in C_i} x$$

Step 2 of kmeans

Kmeans takes an alternating optimization approach, each step is guaranteed to decrease the objective – thus guaranteed to converge

Example: K-Means for Segmentation

K=2



Goal of Segmentation is to partition an image into regions each of which has reasonably homogenous visual appearance.

Original







Example: K-Means for Segmentation

K=2



K=3



Original







Example: K-Means for Segmentation

K=2



K=3



K=10



Original











Example: Vector quantization

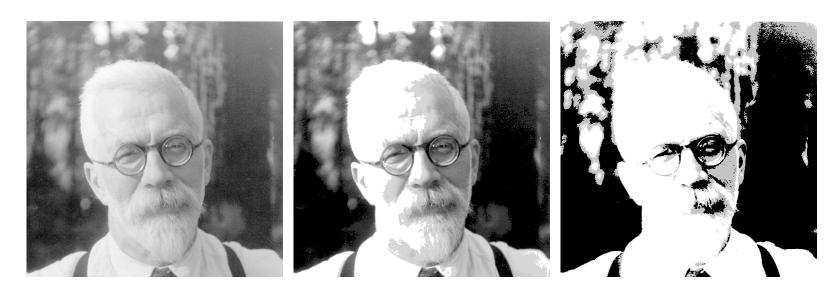
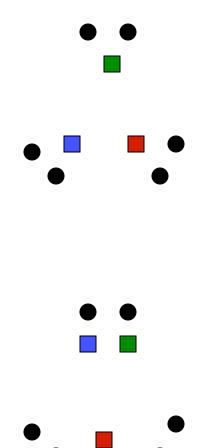


FIGURE 14.9. Sir Ronald A. Fisher (1890 – 1962) was one of the founders of modern day statistics, to whom we owe maximum-likelihood, sufficiency, and many other fundamental concepts. The image on the left is a 1024×1024 grayscale image at 8 bits per pixel. The center image is the result of 2×2 block VQ, using 200 code vectors, with a compression rate of 1.9 bits/pixel. The right image uses only four code vectors, with a compression rate of 0.50 bits/pixel

[Figure from Hastie et al. book]

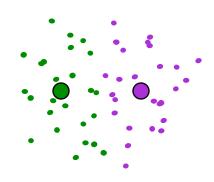
Initialization

- K-means algorithm is a heuristic
 - Requires initial means
 - It does matter what you pick!
 - What can go wrong?
 - Various schemes for preventing this kind of thing: variance-based split / merge, initialization heuristics

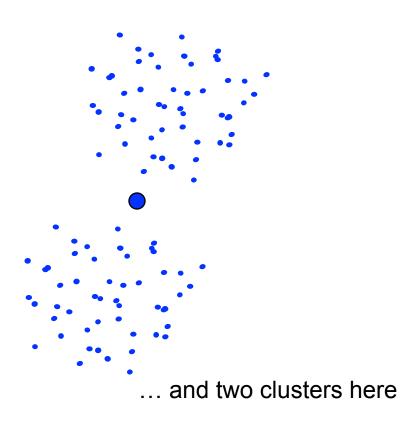


K-Means Getting Stuck

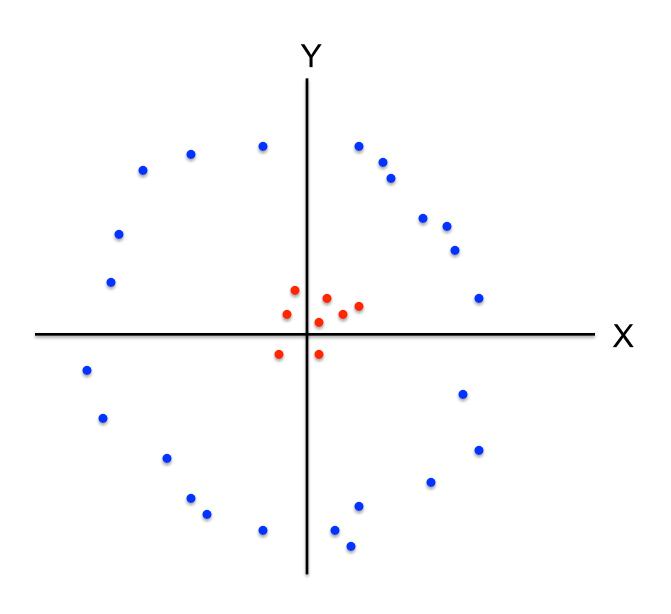
A local optimum:



Would be better to have one cluster here



K-means not able to properly cluster



Changing the features (distance function) can help

