

Learning representations for counterfactual inference

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Talk today about two papers

- Fredrik D. Johansson, Uri Shalit, David Sontag
“Learning Representations for Counterfactual Inference”
ICML 2016
- Uri Shalit, Fredrik D. Johansson, David Sontag
“Estimating individual treatment effect: generalization bounds and algorithms”
arXiv:1606.03976

Code: <https://github.com/clinicalml/cfrnet>

Causal inference from observational data

- Patient “Anna” comes in with hypertension
 - Asian, 54, history of diabetes, blood pressure 150/95, ...
- Which of the treatments t will cause Anna to have lower blood pressure?
 - Calcium channel blocker ($t = 1$)
 - ACE inhibitor ($t = 0$)
- Dataset of ***observational data*** from many patients: medications, blood tests, past diagnoses, demographics ...



Causal inference from observational data

- Patient “Anna” comes in with hypertension
 - Asian, 54 years old, 160/95, ...
- Which of the following treatments would have lower blood pressure?
 - Calcium channel blockers
 - ACE inhibitors
- Dataset of *observational data* from many patients: medications, blood tests, past diagnoses, demographics ...

How to best use
observational data for
individual-level
causal inference?



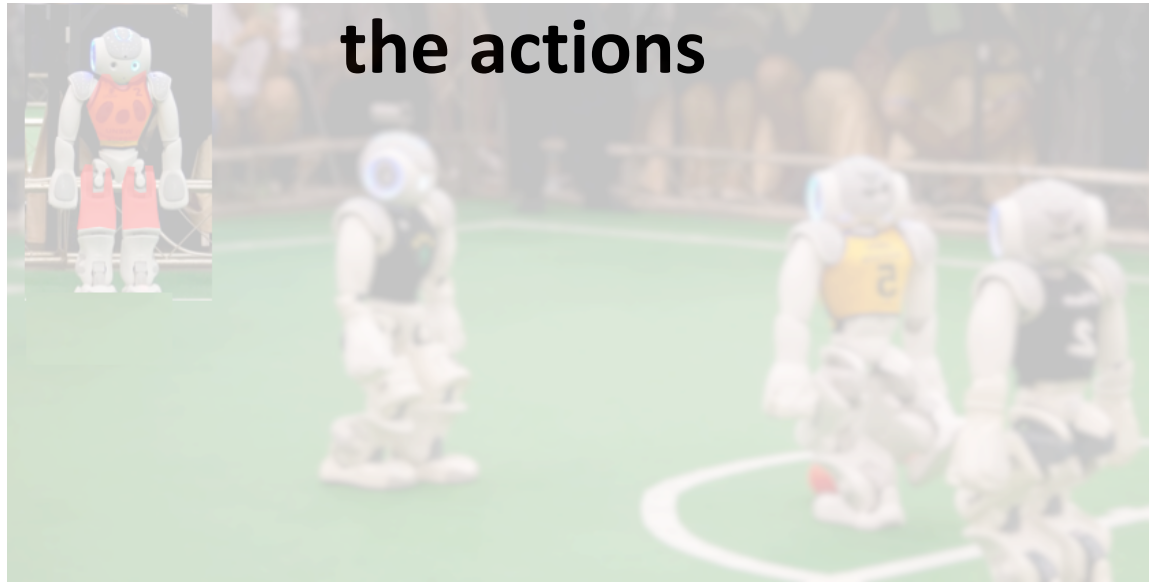
Causal inference from observational data: Job training

- 1,000 unemployed persons
- Job training program with capacity of 100
 - Training ($t = 1$)
 - No training ($t = 0$)
- Who should get job training?
 - For which persons will job training have the most impact?
- Observational data about thousands of people: job history, job training, education, skills, demographics...



Observational data

- **Dataset of features, actions and outcomes**
- **We do not control the actions**
- **We do not know the model generating the actions**



Causal inference from observational data and reinforcement learning

- Robot on the sideline, learning by observing other robots playing robot football
- Sideline-robot does not know the playing-robots' internal model
- Form of off-policy learning, learning from demonstration



Outline

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Causal inference from observational data: Medication

- Patient “Anna” comes in with hypertension
 - Asian, 54, history of diabetes, blood pressure 150/95, ...
- Which of the treatments t will lower Anna’s blood pressure?
 - Calcium channel blocker ($t = 1$)
 - ACE inhibitor ($t = 0$)
- Dataset of ***observational data*** medications, blood tests, past diagnoses, demographics ...

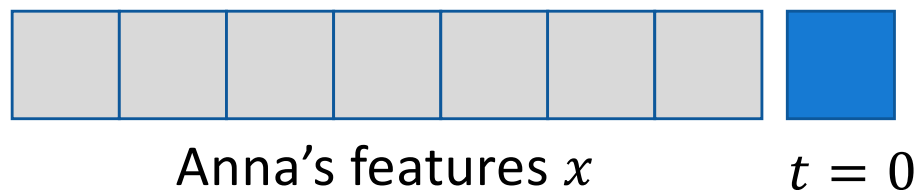
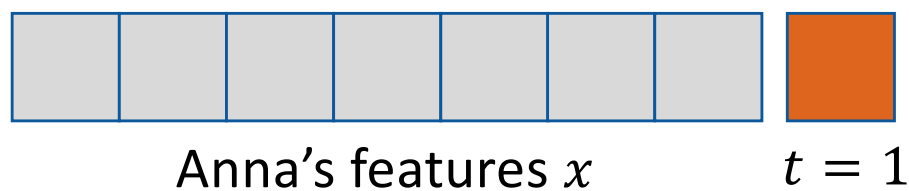
Build a regression model from patient features and treatment decisions to blood pressure



Regression modeling

- Build regression model from patient features and treatment decision to blood pressure (BP) using our observational data

- Input:



Output:


predicted BP

—

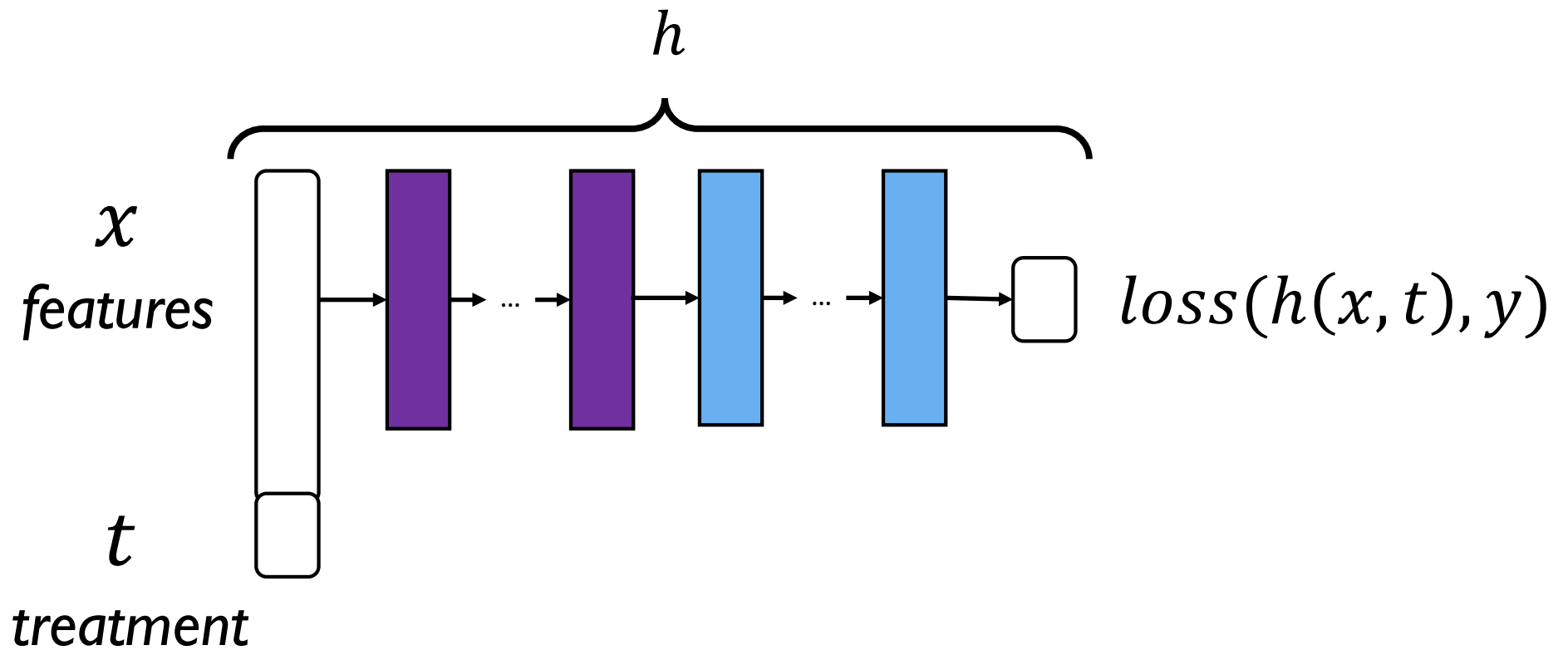

predicted BP

=

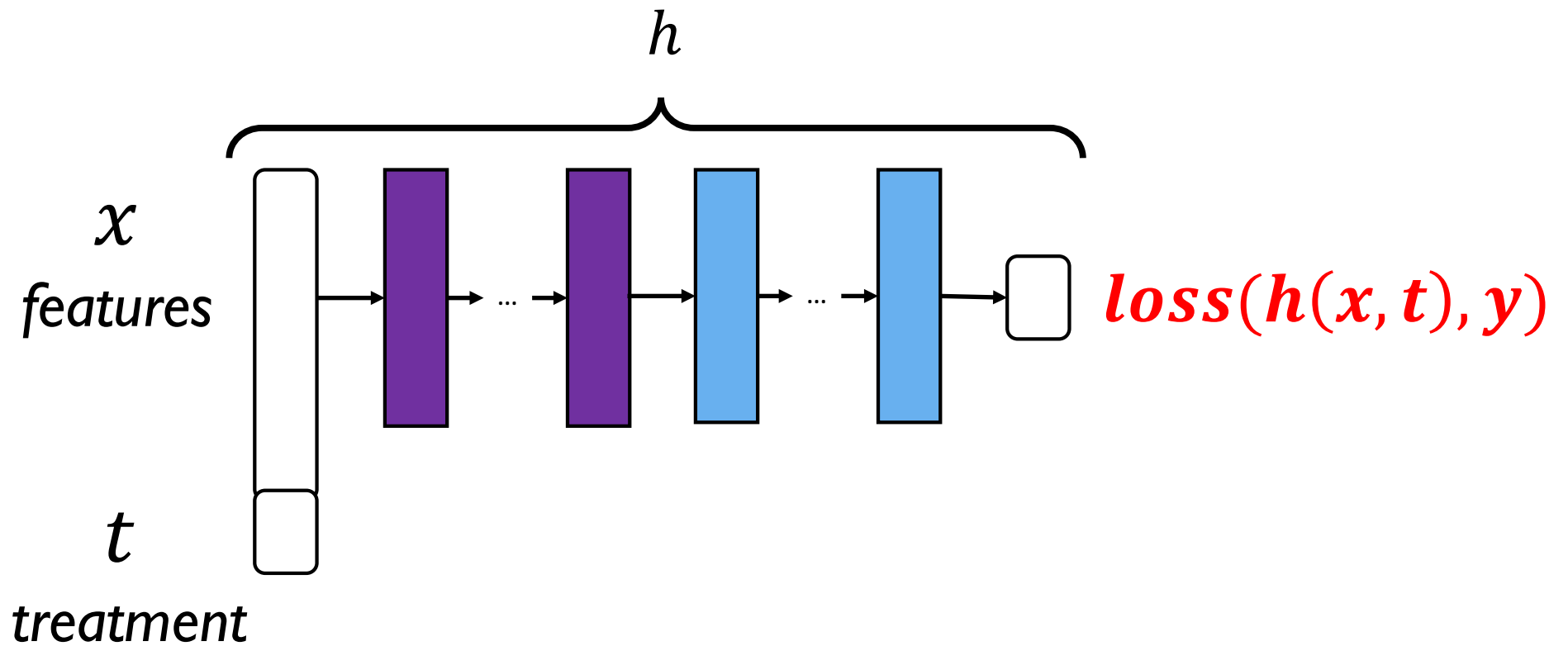
?

- Compare

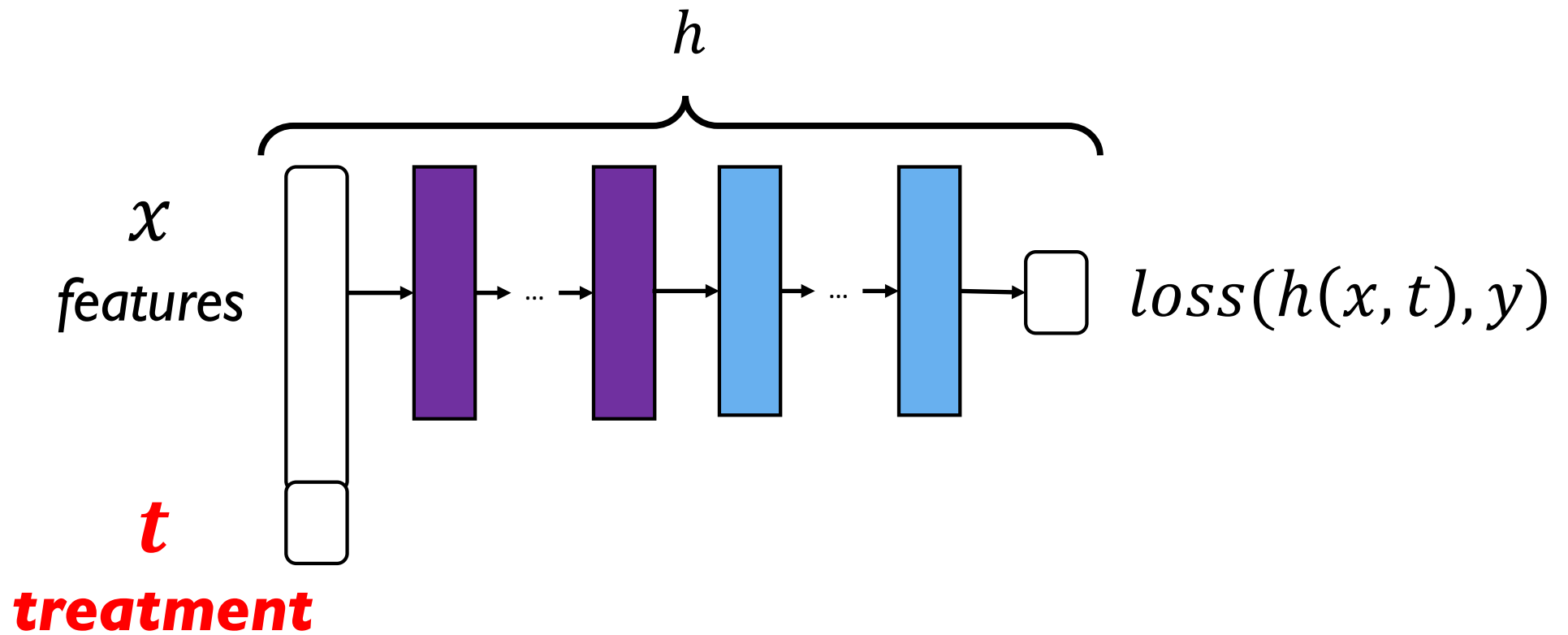
Regression modeling



Regression modeling



Regression modeling



Not supervised learning!

- This is not a classic supervised learning problem
- Supervised learning is optimized to predict outcome, not to differentiate the influence of $t = 1$ vs. $t = 0$
- What if our high-dimensional model threw away the feature of treatment t ?
- Maybe there's **confounding**:
younger patients tend to get medication $t = 1$
older patients tend to get medication $t = 0$

Potential outcomes (Rubin & Neyman)

For every sample $x \in \mathcal{X}$, and treatment $t \in \{0,1\}$, there is a potential outcome $Y_t|x$

Blood pressure had they received treatment 1 $Y_1|x$

Blood pressure had they received treatment 0 $Y_0|x$

Individual treatment effect $ITE(\mathbf{x}) := \mathbb{E}[Y_1 - Y_0|x]$

We observe only one potential outcome, and not at random!

Example – patient blood pressure (BP)

Features: $x = (\text{age}, \text{gender})$, treatment: $t \in \{0,1\}$

Factual (observed) set

(age, gender, treatment)	BP after medication
(40, F, 1)	$Y_1 = 140$
(40, M, 1)	$Y_1 = 145$
(65, F, 0)	$Y_0 = 170$
(65, M, 0)	$Y_0 = 175$
(70, F, 0)	$Y_0 = 165$

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Counterfactual set

(age, gender, treatment)	BP after medication
(40, F, 0)	$Y_0 = ?$
(40, M, 0)	$Y_0 = ?$
(65, F, 1)	$Y_1 = ?$
(65, M, 1)	$Y_1 = ?$
(70, F, 1)	$Y_1 = ?$

Example – patient blood pressure (BP)

Features: $x = (\text{age}, \text{gender}), \text{treatment}$

Prediction set

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(70, F, 1)	$Y_1 = ?$

- Closely related to unsupervised domain adaptation
- No samples from the test set
- Can't perform cross-validation!

Prediction set

Counterfactual set

(age, gender, treatment)	BP after medication
(40, F, 1)	$Y_1 = 140$
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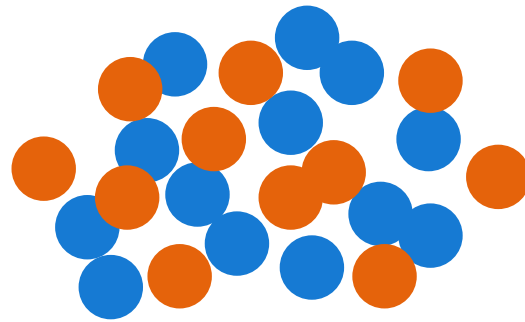
Theory

Our Work

- New neural-net based **representation learning** algorithm with explicit regularization for counterfactual estimation
- State-of-the-art on previous benchmark and on real-world causal inference task
- First error bound for estimating individual treatment effect (ITE)

When is this problem easier? Randomized Controlled Trials

Randomized
treatment \rightarrow
counterfactual and
factual have
identical
distributions



Features

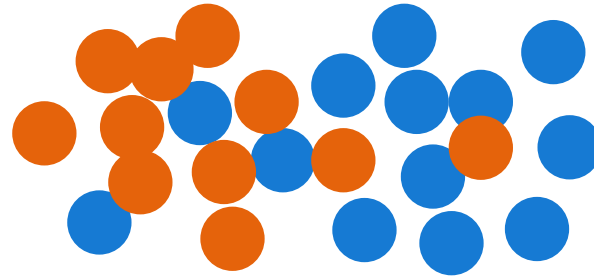
x

● Control, $t = 0$

● Treated, $t = 1$

When is this problem harder? Observational study

Treatment
assignment non-
random →
counterfactual and
factual have
different
distributions



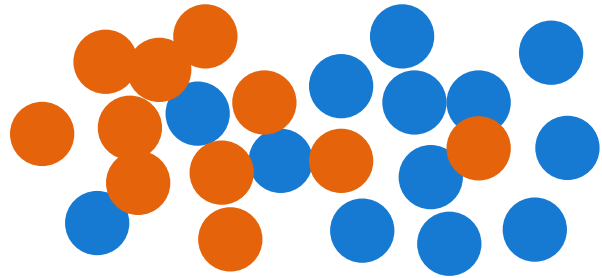
Features

x

● Control, $t = 0$

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Learning more balanced representations



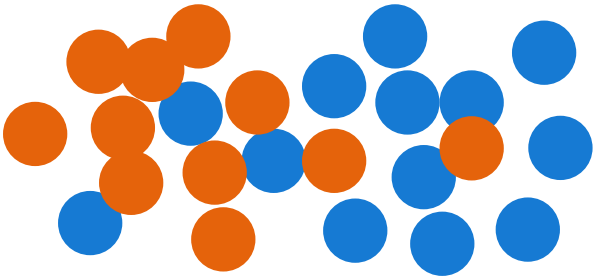
Features

x

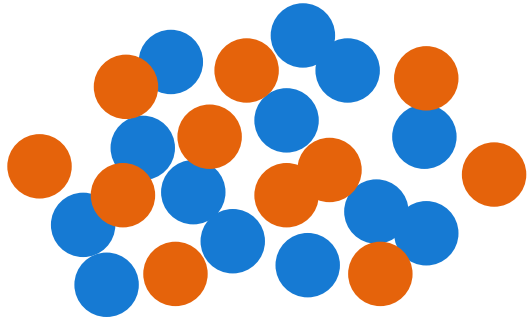
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Learning more balanced representations



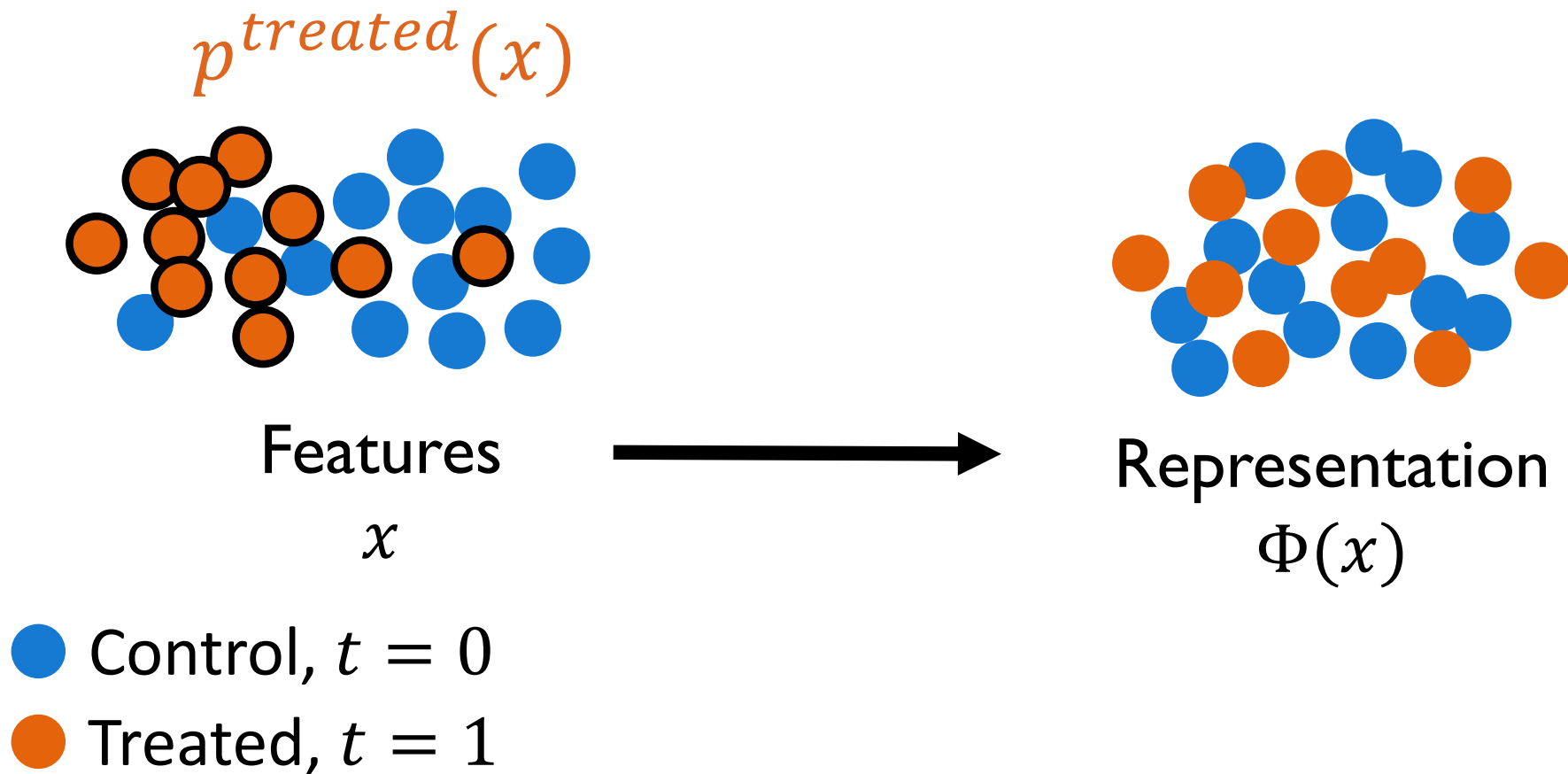
Features
 x



Representation
 $\Phi(x)$

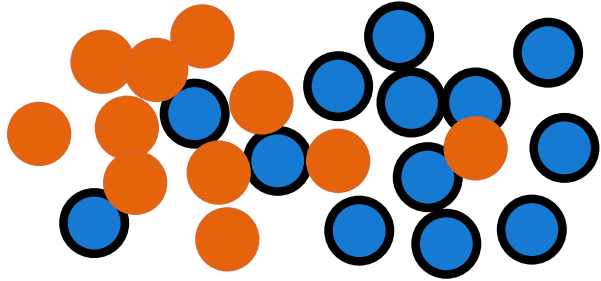
- Control, $t = 0$
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Learning more balanced representations

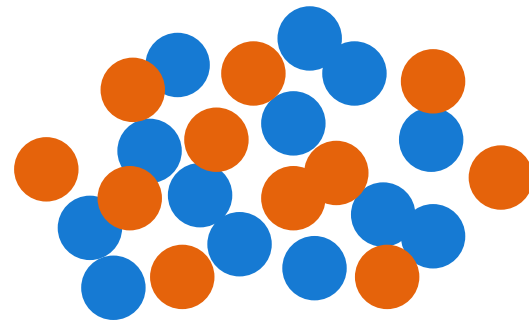


Learning more balanced representations

$p^{control}(x)$



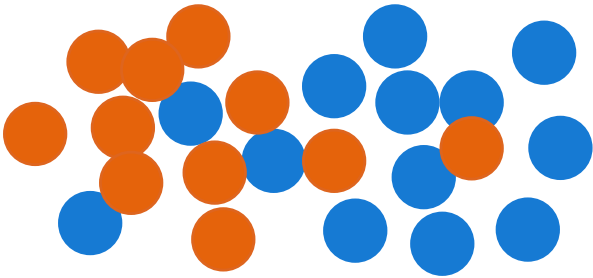
Features
 x



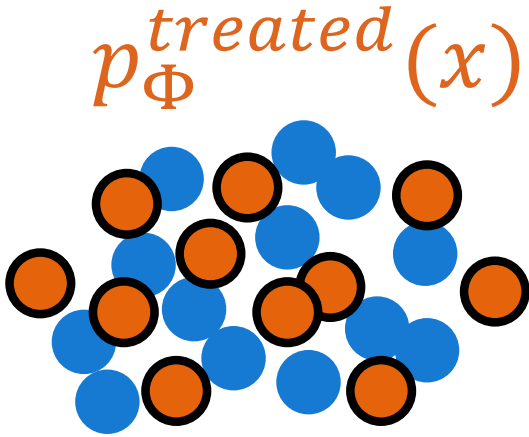
Representation
 $\Phi(x)$

- Control, $t = 0$
- Treated, $t = 1$

Learning more balanced representations



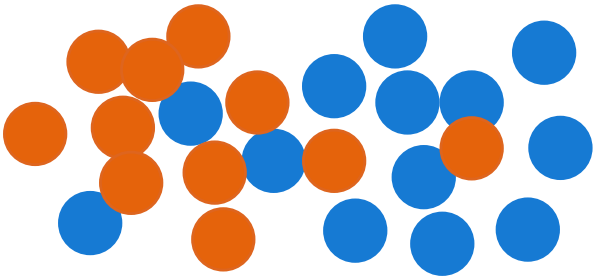
Features
 x



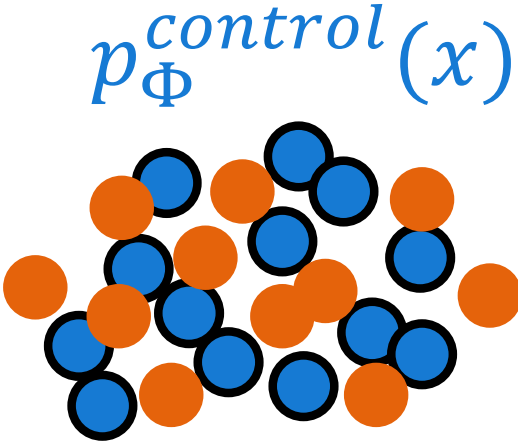
Representation
 $\Phi(x)$

- Control, $t = 0$
- Treated, $t = 1$

Learning more balanced representations



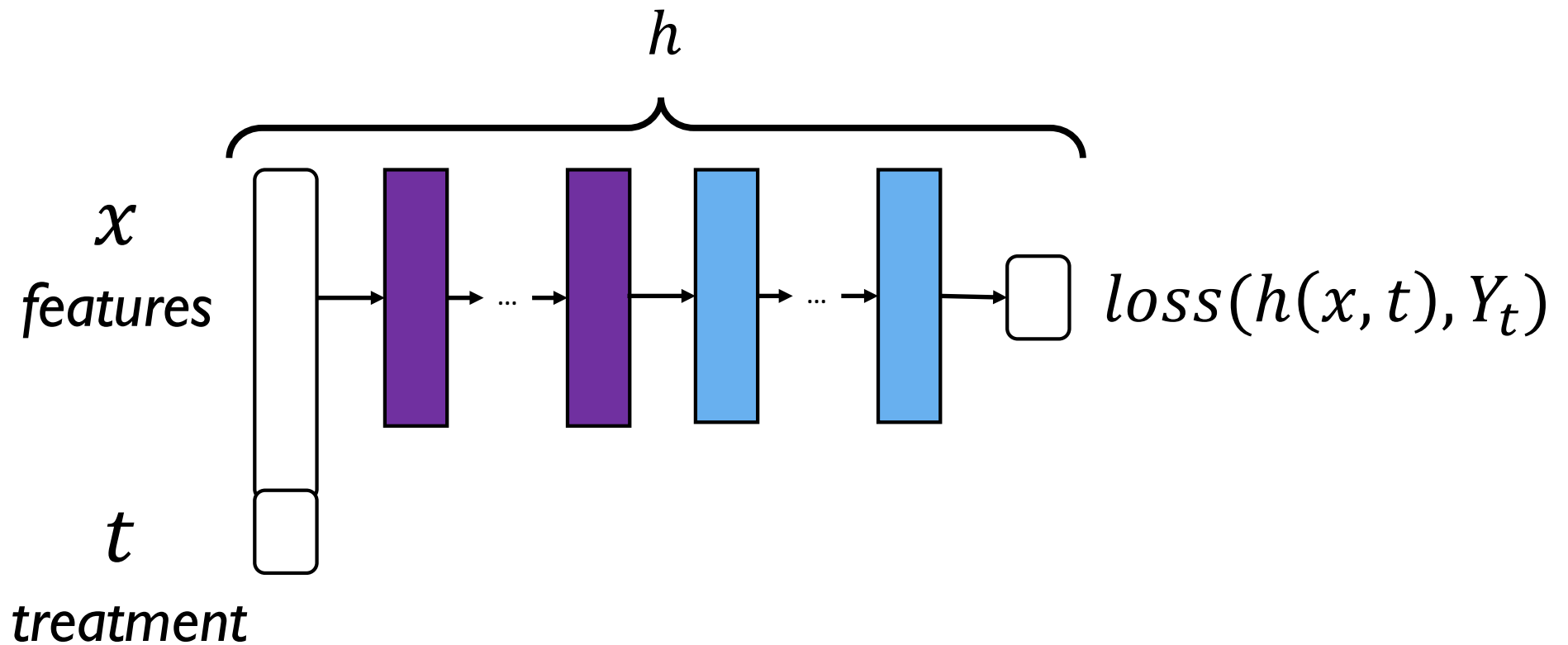
Features
 x



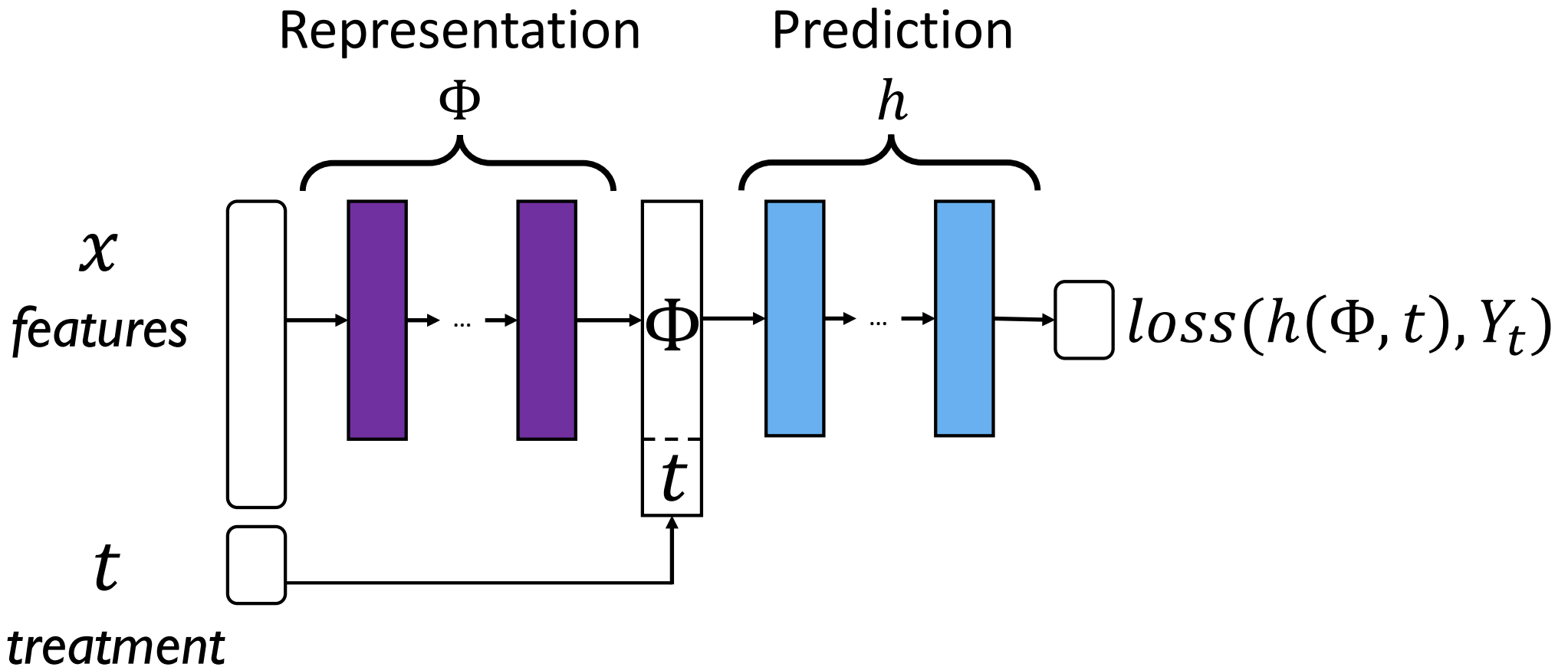
Representation
 $\Phi(x)$

- Control, $t = 0$
- Treated, $t = 1$

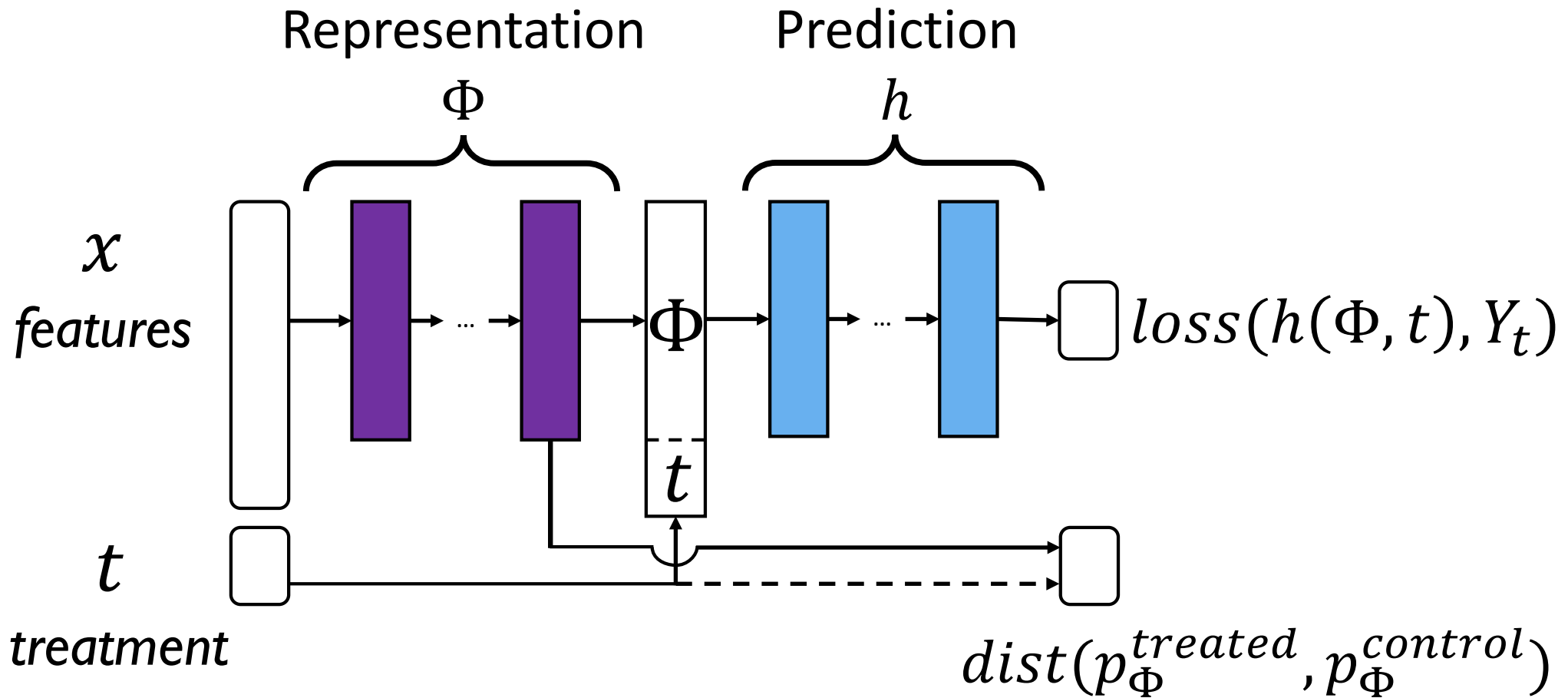
Naïve Neural Network for estimating individual treatment effect (ITE)



Vanilla Neural Network for Counterfactual Regression (CFR)



Balancing Neural Network for Counterfactual Regression (CFR)



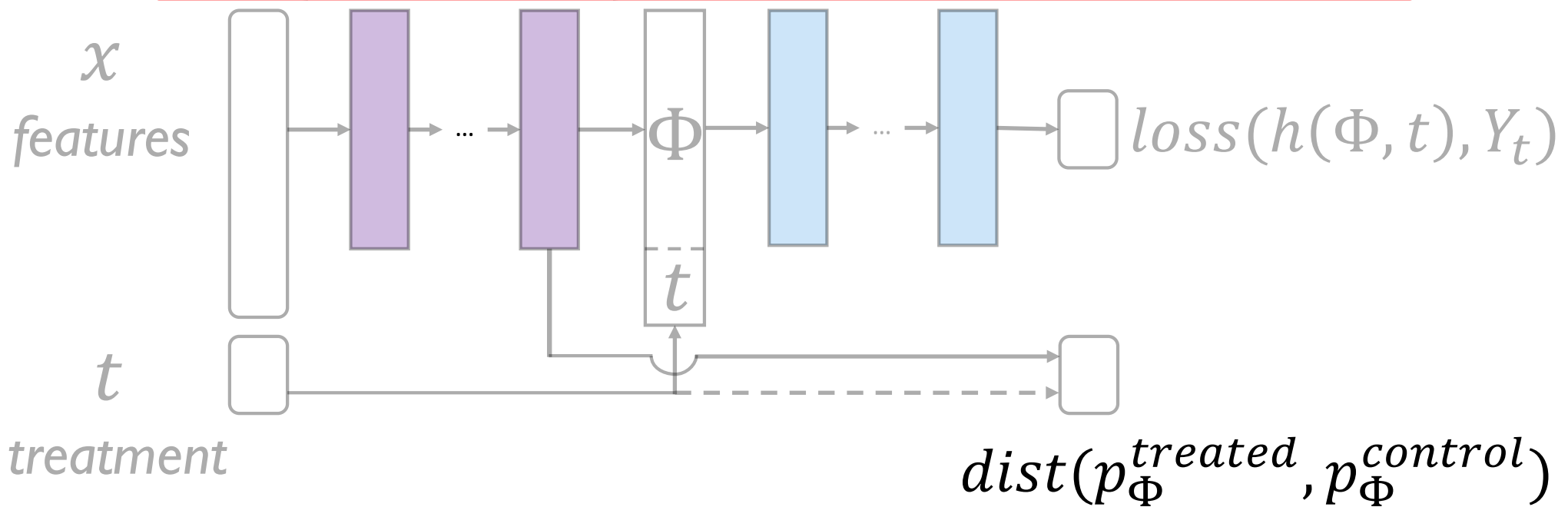
Balanc

ision

$$\text{dist}(p_{\Phi}^{\text{treated}}, p_{\Phi}^{\text{control}}):$$

MMD distance (Gretton et al. 2012)

Wasserstein distance (Villani 2008, Cuturi 2013)



Bala

sion

$dist(p_{\Phi}^{treated}, p_{\Phi}^{control})$:

MMD distance (Gretton et al. 2012)

Wasserstein distance (Villani 2008, Cuturi 2013)

Inspired by Domain Adversarial Networks (Ganin et al., 2016):

(source domain, target domain) \rightarrow

(treated population, control population)

treatment

$dist(p_{\Phi}^{treated}, p_{\Phi}^{control})$

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Evaluating counterfactual inference

Train-test paradigm breaks

No observations from the counterfactual “test” set

Can't do cross-validation for hyper-parameter selection

1) Simulated data: IHDP (Hill, 2011)

2) Real data: National Supported Work study (LaLonde, 1986, Todd & Smith 2005)

The effect of job training on employment and income

Observational study with a *randomized controlled trial subset*

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The effect of job training on employment and income

Observational study with a *randomized controlled trial subset*
3212 samples, 8 features incl. education and previous income

Evaluating models with randomized controlled trials data

- We can't directly evaluate individual treatment effect (ITE) error because we never see the counterfactual
- Every ITE estimator implies a policy
 $\widehat{ITE}(x) = f(x)$

Policy $\pi_{f,\lambda}: \mathcal{X} \rightarrow \{0,1\}$

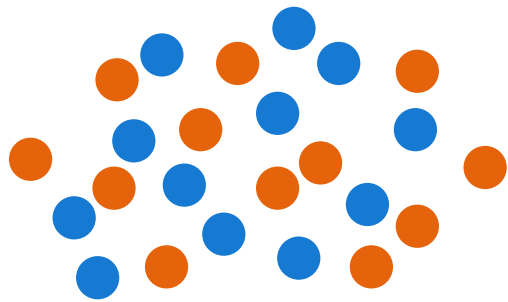
Treat all persons x with $f(x) > \lambda$, for threshold λ

- Every policy π has a policy-value:

$$\mathbb{E}[Y_1 | \pi(x) = 1]p(\pi = 1) + \mathbb{E}[Y_0 | \pi(x) = 0]p(\pi = 0)$$

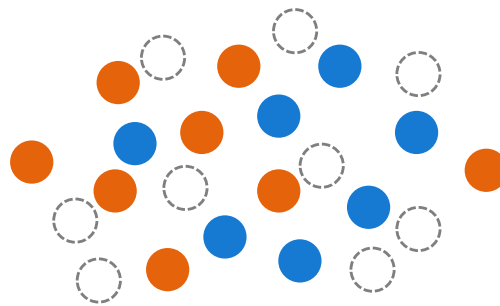
Evaluating model performance using randomized data (off-policy evaluation)

Randomized Controlled Trial

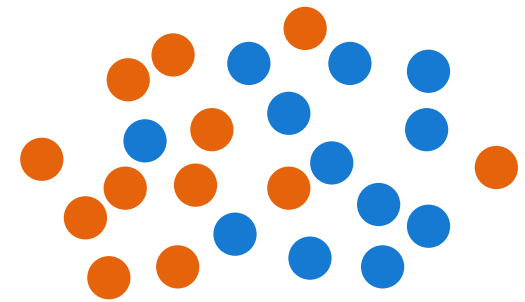


- Control, $t = 0$
- Treated, $t = 1$

Agreement



Policy π



$$\text{Policy value: } \mathbb{E}[Y_1 | \pi(x) = 1]p(\pi = 1) + \mathbb{E}[Y_0 | \pi(x) = 0]p(\pi = 0)$$

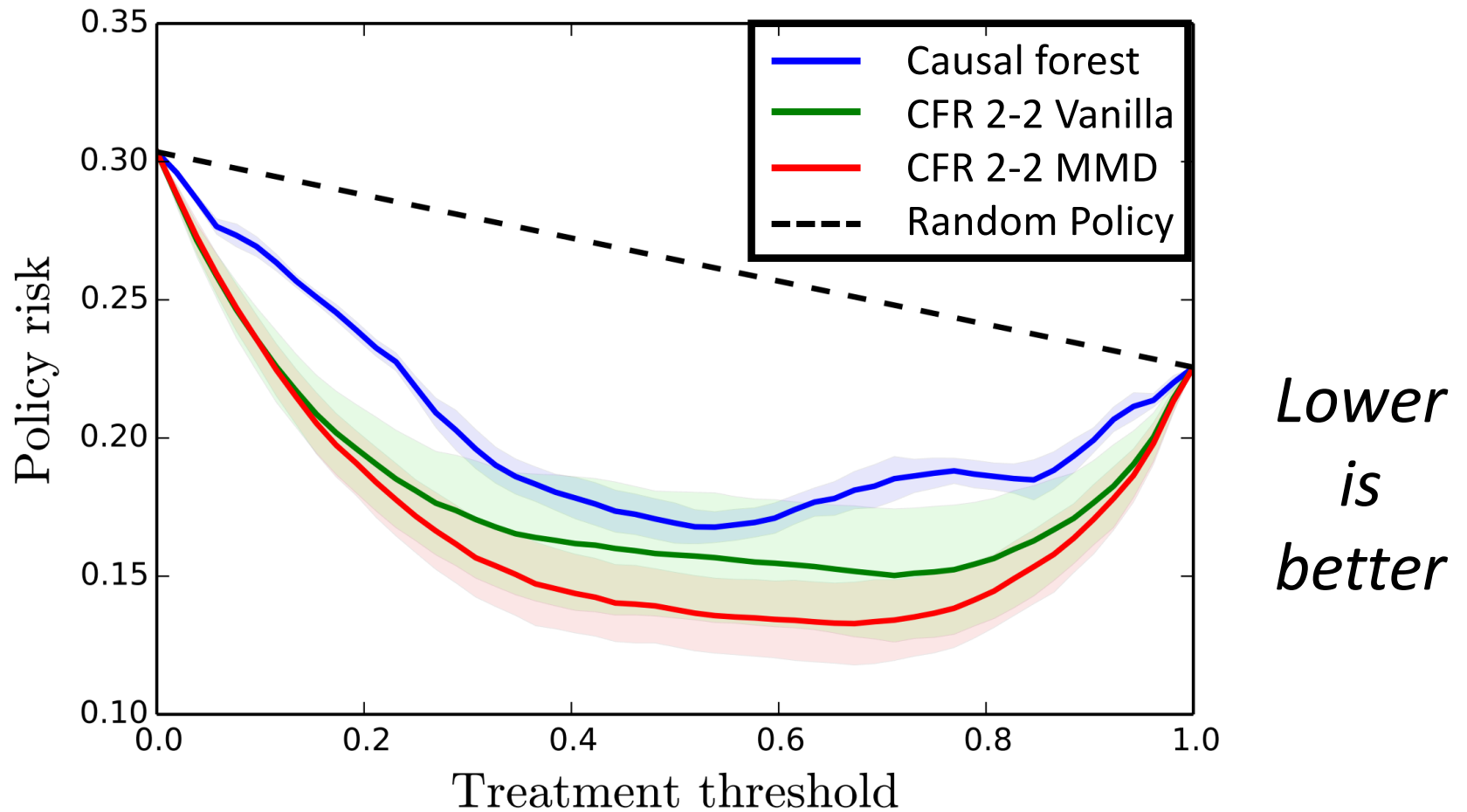
Experimental results – National Supported Work Study

- National Supported Work: randomized trial embedded in an observational study
- *Policy risk estimated on randomized subsample*
- CFR-2-2: our model, with 2 layers before Φ and 2 layers after Φ

Method	Policy risk (std)
ℓ_1 -reg. logistic regression	0.23±0.00
BART (Chipman, George & McCulloch, 2010)	0.24±0.01
Causal forests (Wager & Athey, 2015)	0.17±0.006
CFR-2-2 Vanilla	0.16±0.02
CFR-2-2 Wasserstein	0.15±0.02
CFR-2-2 MMD	0.13±0.02

*Lower
is
better*

Experimental results – National Supported Work Study



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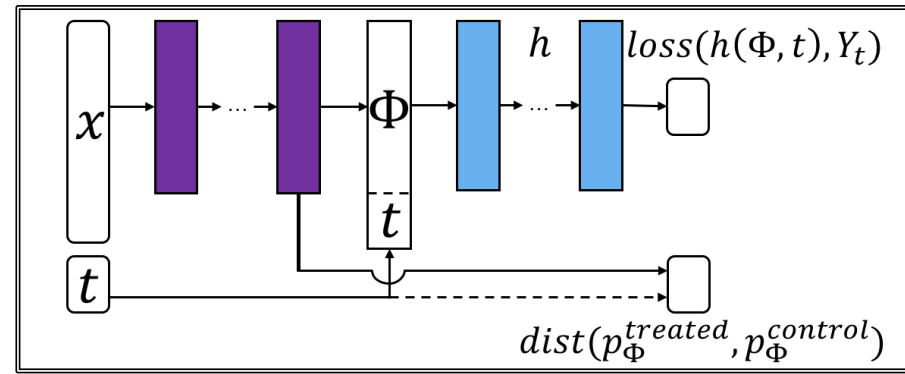
Theory

Theory of causal effect inference

- Standard results in statistics: asymptotic rate of convergence to true average effect
 - Assumptions: we know true model (consistency)
- Our result: generalization error bound for individual-level inference
 - Assumptions: true model lies within large model family, e.g. bounded Lipschitz functions

Theorem (informal)

- Let $\hat{Y}_t^{\Phi, h}(x) = h(\Phi(x), t)$ for $t = 0, 1$
- $\widehat{ITE}^{\Phi, h}(x) := \hat{Y}_1^{\Phi, h}(x) - \hat{Y}_0^{\Phi, h}(x)$

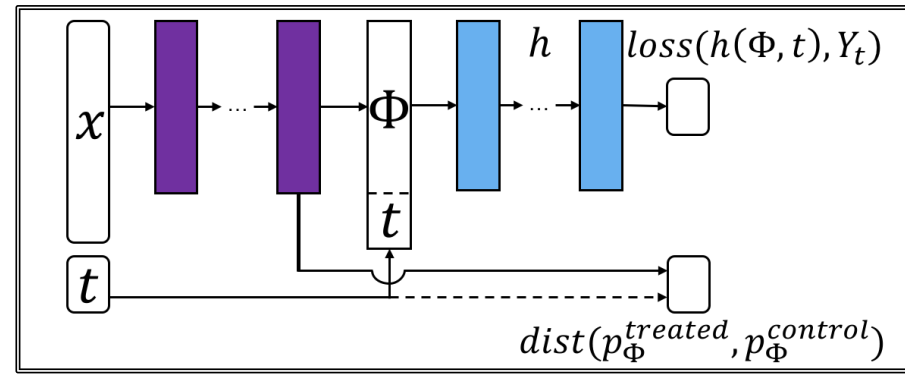


- If “strong ignorability” holds, and if $dist$ is “nice” with respect to the true potential outcomes Y_0 and Y_1 and the representation Φ , then for all normalized Φ and h :

$$\mathbb{E}_x \left[error \left(\widehat{ITE}^{\Phi, h}(x) \right) \right] \leq 2 \cdot \mathbb{E}_{x, t} \left[error \left(\hat{Y}_t^{\Phi, h}(x) \right) \right] + dist(p_{\Phi}^{treated}, p_{\Phi}^{control})$$

Theorem (informal)

- Let $\hat{Y}_t^{\Phi, h}(x) = h(\Phi(x), t)$ for $t = 0, 1$
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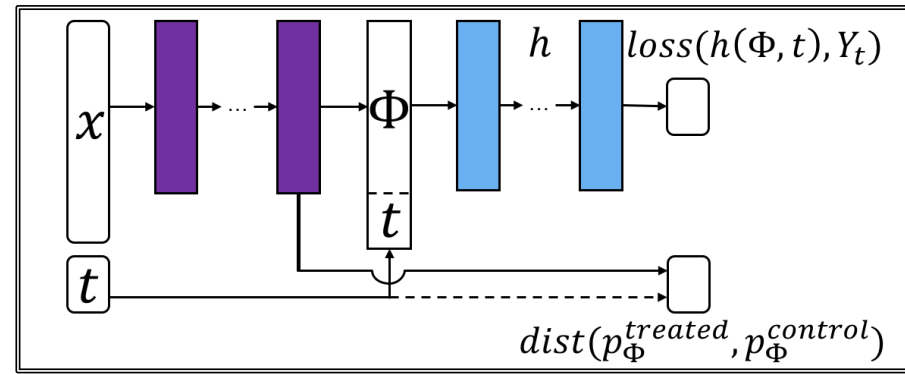


- If “strongly identifiable” and if $dist$ is “nice” with respect to the true probabilities $p_{\Phi}^{treated}$ and $p_{\Phi}^{control}$ and the representation Φ , then for all Φ and h :

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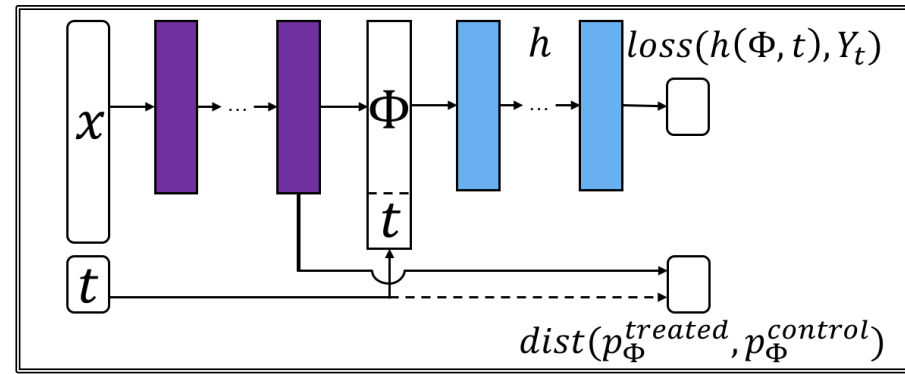
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$$\mathbb{E}_x \left[\text{error} \left(\widehat{ITE}^{\Phi, h}(x) \right) \right] \leq 2 \cdot \underbrace{\mathbb{E}_{x, t} \left[\text{error} \left(\hat{Y}_t^{\Phi, h}(x) \right) \right]}_{\text{“supervised learning generalization error”}} + \text{dist}(p_{\Phi}^{\text{treated}}, p_{\Phi}^{\text{control}})$$

“supervised learning generalization error”

Theorem (informal)

- Let $\hat{Y}_t^{\Phi, h}(x) = h(\Phi(x), t)$ for $t = 0, 1$
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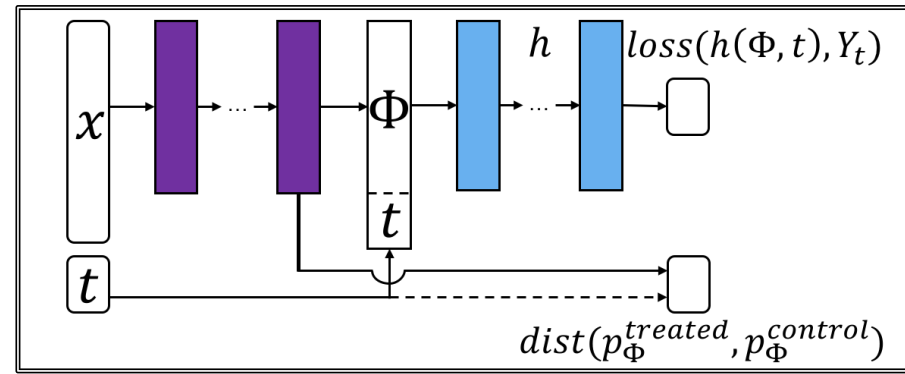
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$$\mathbb{E}_x \left[error \left(\widehat{ITE}^{\Phi, h}(x) \right) \right] \leq 2 \cdot \mathbb{E}_{x, t} \left[error \left(\hat{Y}_t^{\Phi, h}(x) \right) \right] + \underbrace{dist(p_{\Phi}^{treated}, p_{\Phi}^{control})}_{\text{Distance between } \Phi\text{-induced distributions}}$$

Distance between Φ -induced distributions

Theorem (informal)

- Let $\hat{Y}_t^{\Phi, h}(x) = h(\Phi(x), t)$ for $t = 0, 1$
- $\widehat{ITE}^{\Phi, h}(x) := \hat{Y}_1^{\Phi, h}(x) - \hat{Y}_0^{\Phi, h}(x)$



We minimize upper bound with respect to Φ and h

$$\mathbb{E}_x \left[\text{error} \left(\widehat{ITE}^{\Phi, h}(x) \right) \right] \leq 2 \cdot \mathbb{E}_{x, t} \left[\text{error} \left(\hat{Y}_t^{\Phi, h}(x) \right) \right] + \text{dist}(p_{\Phi}^{\text{treated}}, p_{\Phi}^{\text{control}})$$

Summary

- Estimating Individual Treatment Effect is different from supervised learning
 - Bears strong connections to domain adaptation
- We give new representation learning algorithms for estimating Individual Treatment Effect
 - Use the MMD and Wasserstein distributional distances
- Experiments show our method is competitive or better than state-of-the-art
- We give a new error bound for estimating Individual Treatment Effect

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Thank you!

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