

Lecture 17

Boosting

## Weak Learning

def. algorithm  $A$  weakly PAC learns concept class  $C$  if  $\exists \delta > 0$  s.t.  
 $\forall c \in C \quad \forall \text{ dists } \mathcal{D}$ ,  
given examples of  $c$  according to  $\mathcal{D}$   
 $A$  outputs  $h$  s.t.  $\Pr_{\mathcal{D}}[h(x) \neq c(x)] \leq \frac{1}{2} - \frac{\delta}{2}$   
 $\uparrow$   
advantage

Thm if  $C$  can be weakly PAC learned (on any  $\mathcal{D}$ ) then  
 $C$  can be (strongly) PAC learned.

## Weak vs. Strong Learning

Def. Algorithm  $A$  weakly "PAC learns" concept class  $C$

if  $\forall c \in C \text{ s.t. dists } \mathcal{D} \exists \delta > 0$

$\forall \epsilon, \delta > 0 \quad (\delta = \frac{\epsilon}{4} \text{ or } \frac{1}{n^2} \text{ doesn't affect})$

with prob  $\geq 1 - \delta$

given examples of  $c$

$A$  outputs  $h$  s.t.  $\Pr_{\mathcal{D}} [h(x) \neq c(x)] \leq \frac{1}{2} - \frac{\delta}{2}$

↑  
advantage

It was conjectured that distribution free weak learning was really weaker but surprise!

Can "boost" a weak learner

Thm if  $C$  can be weakly learned on any dist  $\mathcal{D}$  then  $C$  can be (strongly) learned.

## Applications

### 1) "Theoretical"

- Uniform Algorithms for poly term DNF weight w - poly threshold funcs
- (Boosting + KM)
- Ave case vs. worst case

} low degree alg doesn't work well

### 2) practical - Boosting

Freund-Schapire

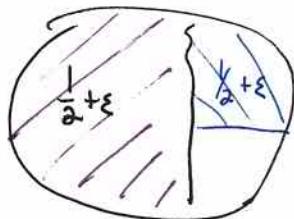
## Good & Bad Ideas

- 1) simulate weak learner several times on same distribution & take majority answer  
-or-  
best answer

gives better confidence

but doesn't reduce error, what if always get same answer?

- 2) filter out examples on which current hypothesis does well & run weak learner on part where you do badly.



Problem: given a new example, how do you know which section it is in?

3) Keep some samples on which you are ok  
 always use majority vote on all previous hypotheses  
 to predict value of new samples

history : Schapire, Freund-Schapire, Impagliazzo -  
 Servedio, Klivans

## Filtering Procedures

- decide which samples to keep, which to throw out
- samples on which so far you guess correctly  $\leftarrow$  need for checking future hypotheses  
 incorrectly  $\leftarrow$  need to improve on these

## The setting

- Given labelled examples  
 $(x_1, f(x_1)), (x_2, f(x_2)), \dots$   
 $x_i \in \mathbb{R}^d$   
 $f \in \mathcal{C}$
- Given weak learning alg WL which weakly learns (advantage  $\frac{\epsilon}{2}$ ) on any dist  $\mathcal{D}'$

## Boosting Algorithm

- Stage 0 (Initialize)

$$\mathcal{D}_0 \leftarrow \mathcal{D}$$

run WL on  $\mathcal{D}_0$  to generate (whp)

$$C_1 \text{ s.t. } \Pr_{\mathcal{D}_0} [f(x) = C_1(x)] \geq \frac{1}{2} + \gamma/2$$

- For  $i = 1 \dots T = O(\frac{1}{\gamma^2} \epsilon^2)$  stages, stage  $i$ : (can stop if Majority( $C_1 \dots C_i$ ) correct on  $\geq 1 - \epsilon$  inputs)

(1) Construct  $\mathcal{D}_i$  via "filtering procedure":

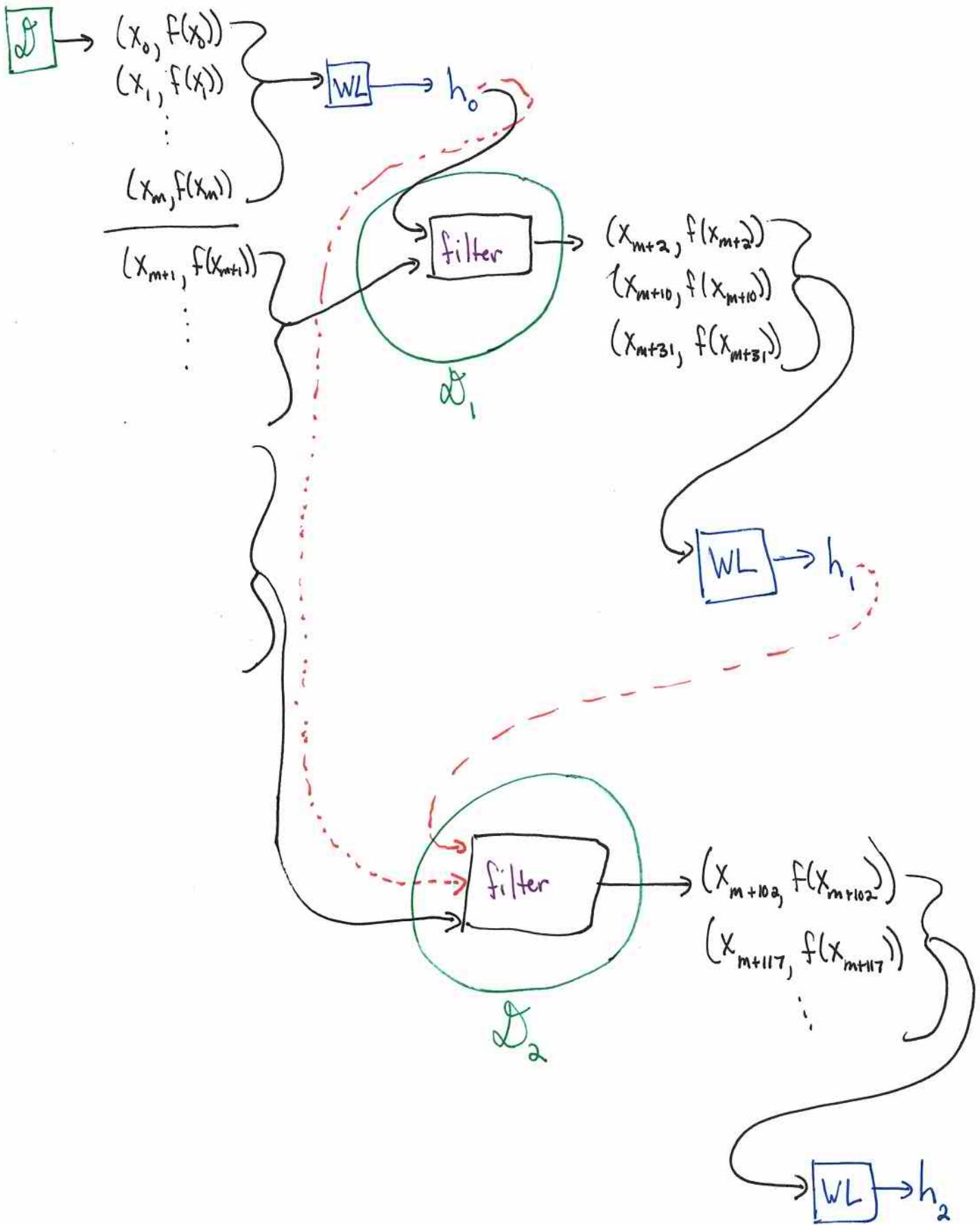
{ favor pts on which maj of  $C_1 \dots C_i$  don't do well  
 but also keep some other points }

Will specify soon

(2) run WL on examples from  $\mathcal{D}_i$  to output

$$C_{i+1} \text{ s.t. } \Pr_{\mathcal{D}_i} [f(x) = C_{i+1}(x)] \geq \frac{1}{2} + \frac{\gamma}{2}$$

- output  $C = \text{MAJ}(C_1 \dots C_T)$



Filtering procedure

Given new example  $x, f(x)$  from example oracle

- if majority of  $c_1 \dots c_i$  wrong, Keep it

$$\text{i.e. } \geq \frac{i}{2}$$

- if large majority right, then discard

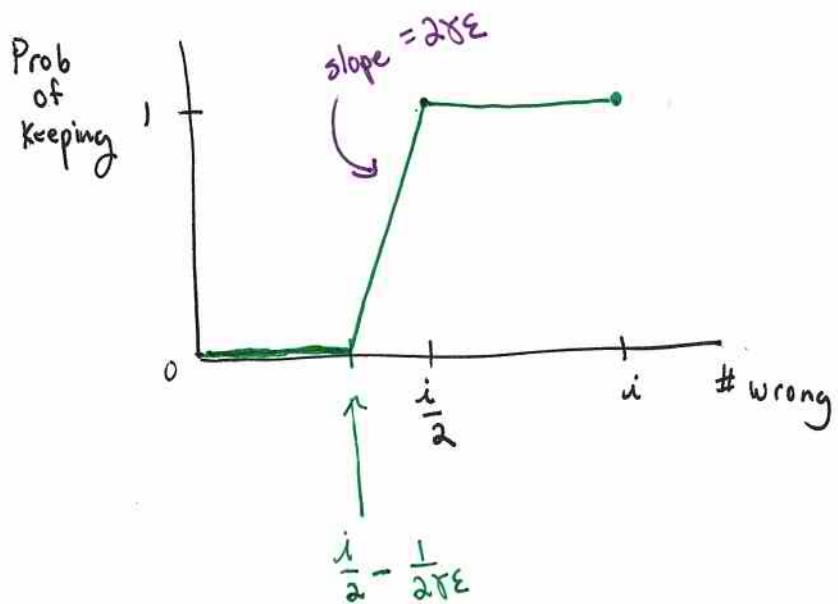
$$\text{i.e. } \# \text{right} - \# \text{wrong} > \frac{1}{\gamma \epsilon}$$

$$\text{or } \# \text{wrong} \leq \frac{i}{2} - \frac{1}{2\gamma \epsilon}$$

- else  $\# \text{right} - \# \text{wrong} = \frac{\alpha}{\gamma \epsilon}$  for  $0 < \alpha < 1$

$$\# \text{wrong} - \# \text{right} = \frac{-\alpha}{\gamma \epsilon}$$

so keep with prob =  $1 - \alpha$



Need to show:

1) Output is has nontrivial agreement with  $f$

2) # samples needed not too bad

why could it be bad?  
 if throw out lots of samples, might  
 need to wait a long time before WL  
 can give an output.  
but if throw out too many samples then  
 you already have a good hypothesis!



will stop if  $\text{Maj}(c_1 \dots c_n)$  correct on  $\geq 1 - \epsilon$  fraction  
 of inputs

o.w.  $\text{Maj}(c_1 \dots c_n)$  incorrect on  $> \epsilon$  fraction

so filtering procedure outputs

sample with prob  $\geq \epsilon$

(+ in expectation, every  $\gamma\epsilon$  samples  
 of  $\Omega(\frac{1}{\epsilon})$  at least one makes  
 it thru the filtering  
 system)

$\Rightarrow$  filtering slows down sample  
 collection by  $\leq O(\gamma\epsilon)$

So lets focus on ①

## Notation

$$\cdot R_c(x) = \begin{cases} +1 & \text{if } f(x) = c(x) \\ -1 & \text{if } f(x) \neq c(x) \end{cases} \quad \text{"is } c \text{ correct on } x?"$$

$$\cdot N_i(x) = \sum_{1 \leq j \leq i} R_{c_j}(x)$$

after iteration  $i$ ,  
how many  $c$ 's correct?  
(#right - #wrong)

$$\cdot M_i(x) = \begin{cases} 1 & \text{if } N_i(x) \leq 0 \\ 0 & \text{if } N_i(x) \geq \frac{1}{\epsilon} \gamma \\ 1 - \epsilon \cdot \gamma \cdot N_i(x) & \text{o.w.} \end{cases}$$

prob of keeping  $x$   
in filtering  
(after stage  $i$ )  
note - all "wrong"  $x$  included  
also some "right"  $x$  included

Note that new distribution on samples is proportional to  $M_i$ :

$$\cdot D_{M_i}(x) = \frac{M_i(x)}{\sum_x M_i(x)}$$

distribution induced by  $M$   
note  $D_{M_i}(x) = \alpha_i$

$\sum_x M_i(x)$  includes all "wrong"  $x$  but also  $x$  for which maj that isn't overwhelming are correct

upper bounds  
# wrong  $x$

How correct are we w.r.t.  $D_{M_i}$ ?

$$\cdot \text{Adv}_c(M_i) = \sum_x R_c(x) M_i(x)$$

$$\cdot \Pr_{x \in D_{M_i}} [c(x) = f(x)] = \frac{1}{2} + \frac{\text{Adv}_c(M_i)}{2 \cdot \sum_x M_i(x)}$$

$\gamma/2$

"Advantage" of  $c$  on  $M$   
 $\approx \Pr[\text{correct}] - \Pr[\text{incorrect}]$

$$\approx 2 \cdot \Pr[\text{correct}] - 1$$

Note:

$$\text{if } \sum M_i(x) \geq \varepsilon 2^n$$

$$Adv_c(M_i) \geq \gamma \cdot \varepsilon \cdot 2^n$$

convert claim about WL  $\Rightarrow$  claim about advantage  
 i.e. if have  $\gamma$  advantage on output of WL  
 + still <sup>almost</sup> wrong on lots of inputs  
 then new advantage is pretty good  
 if not, then you are done

### Begin Proof

For input  $x$

$$\text{let } A_i(x) \leftarrow \sum_{0 \leq j \leq i-1} R_{c_{j+1}}(x) M_j(x)$$

strange -  
 indices don't match  
 $c_1 \dots c_j$  define  $M_j$   
 but  $c_{j+1}$  learned from  
 WL on  $\mathcal{D}_j$

Claim  $A_i(x) \leq \frac{1}{\varepsilon \gamma} + \frac{\varepsilon \gamma}{2} \cdot i$

- bounds advantage per input
- only helps after  $\frac{1}{\varepsilon \gamma}$  rounds

Plan for use of claim :

Consider large matrix:

