

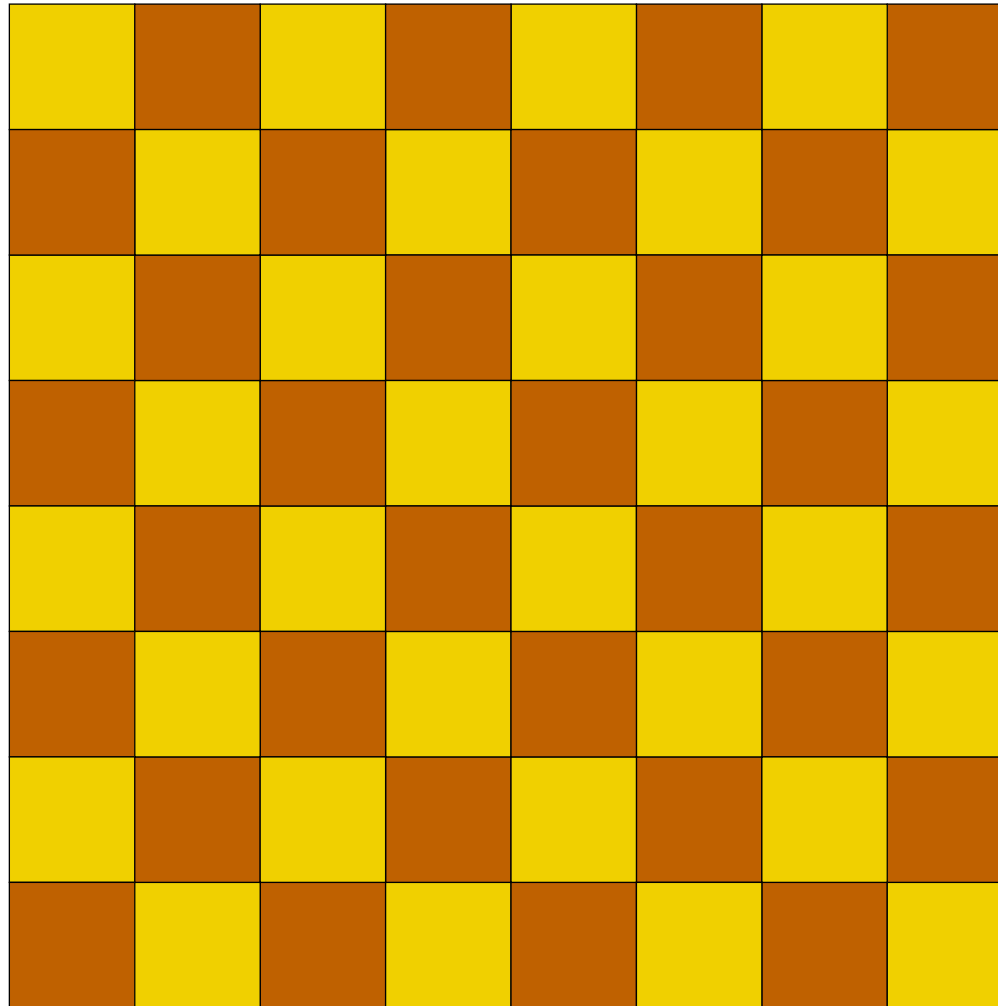
Should We Believe in Numbers Computed by Loopy Belief Propagation?

Pascal O. Vontobel
Information Theory Research Group
Hewlett-Packard Laboratories Palo Alto

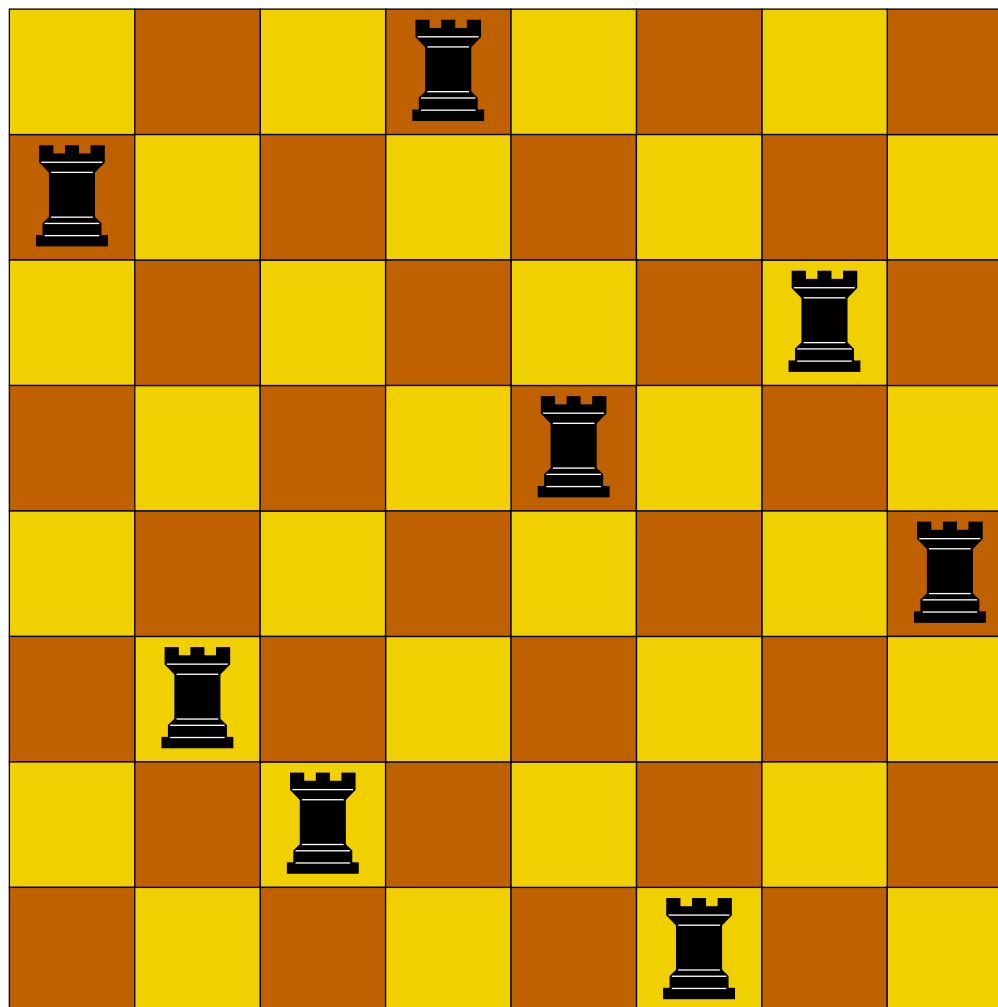
CIOG Workshop, Princeton University, November 3, 2011



Chess Board

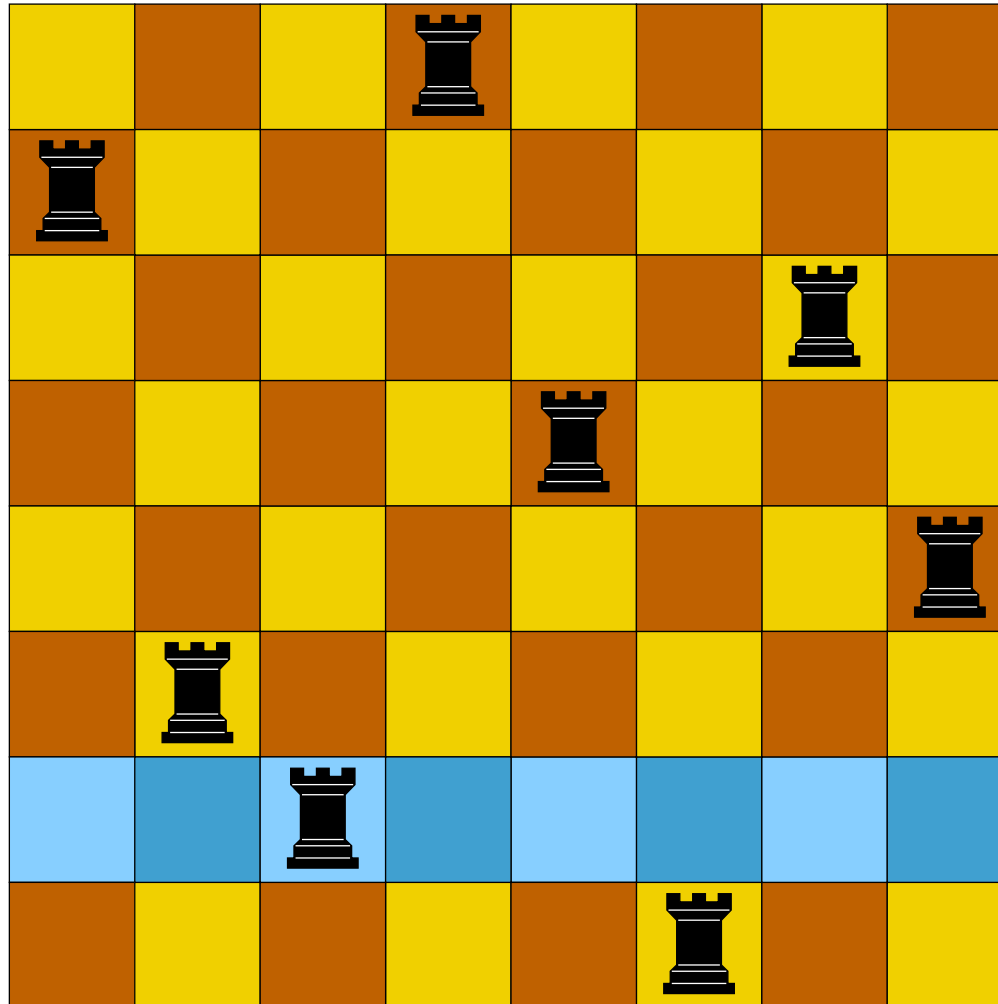


Chess Board



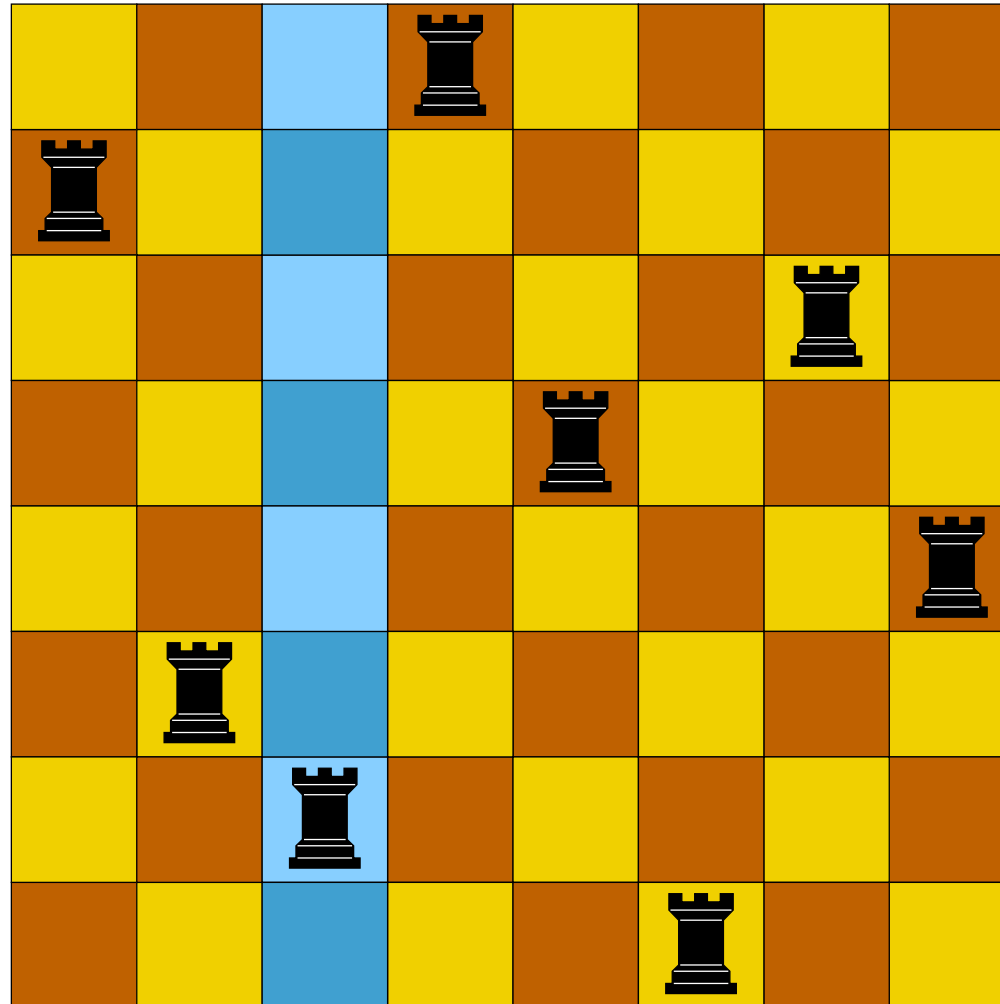
Question: in how many ways can we place 8 non-attacking rooks on a chess board?

Chess Board



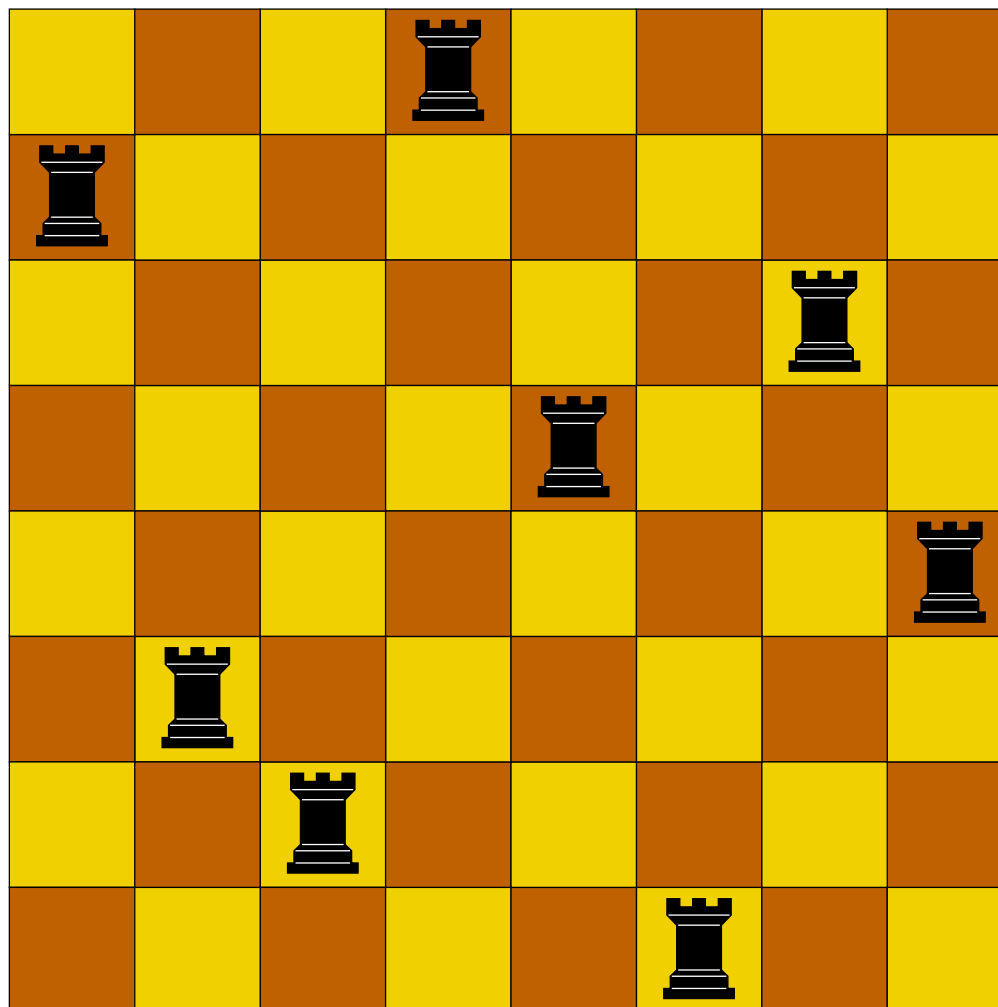
Row condition: exactly one rook per row.

Chess Board



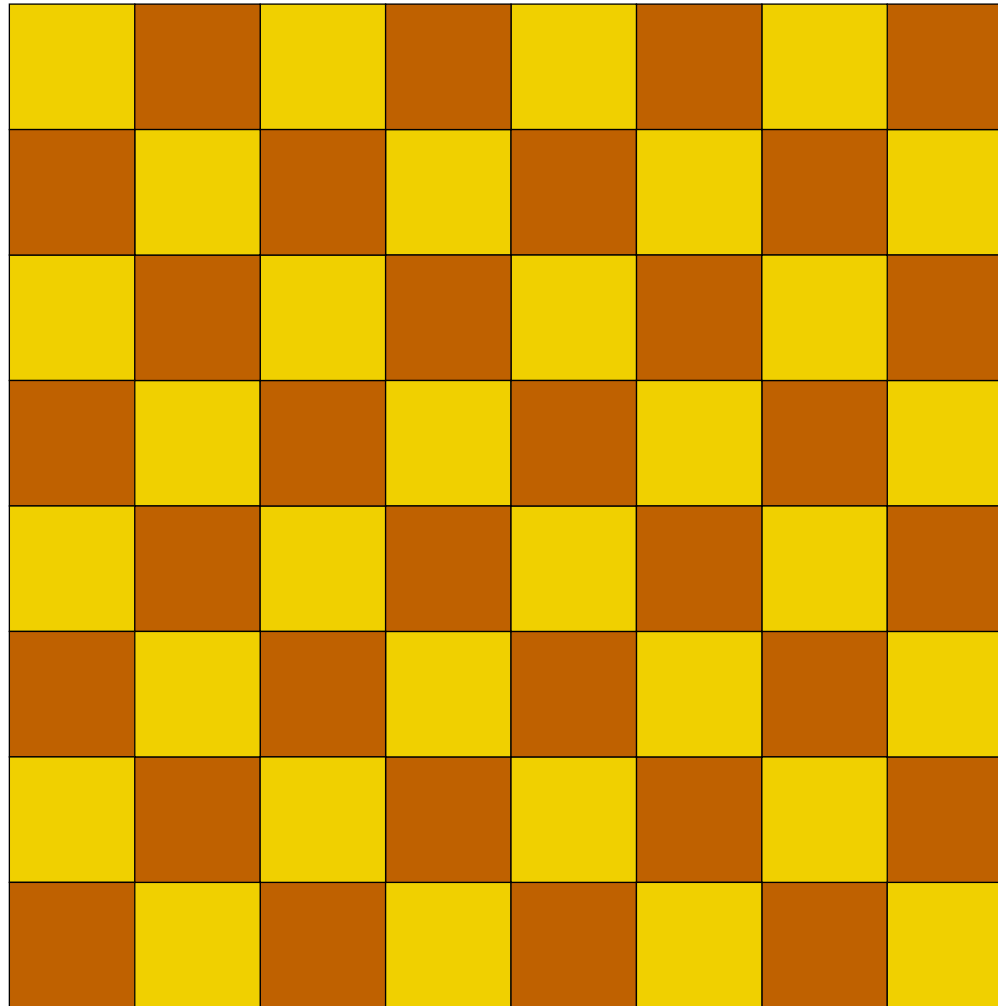
Column condition: exactly one rook per column.

Chess Board

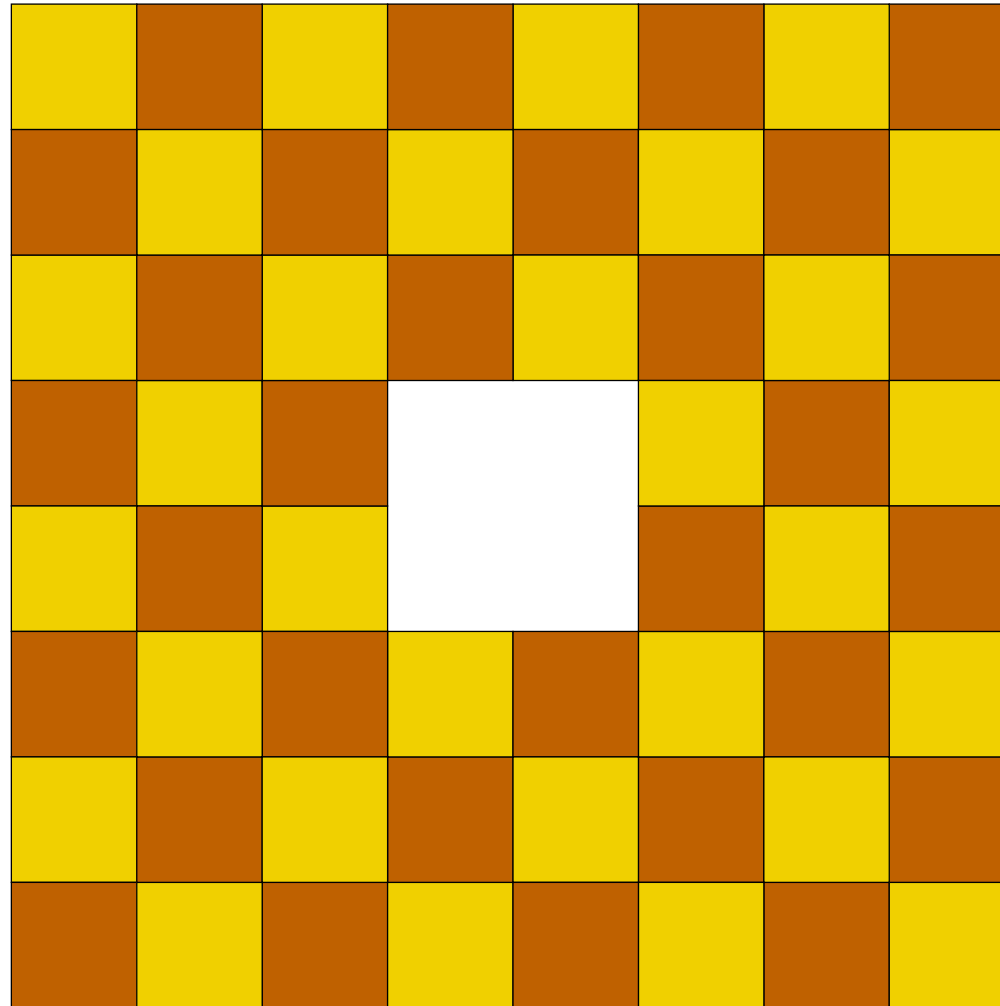


Question: in how many ways can we place 8 non-attacking rooks on a chess board?

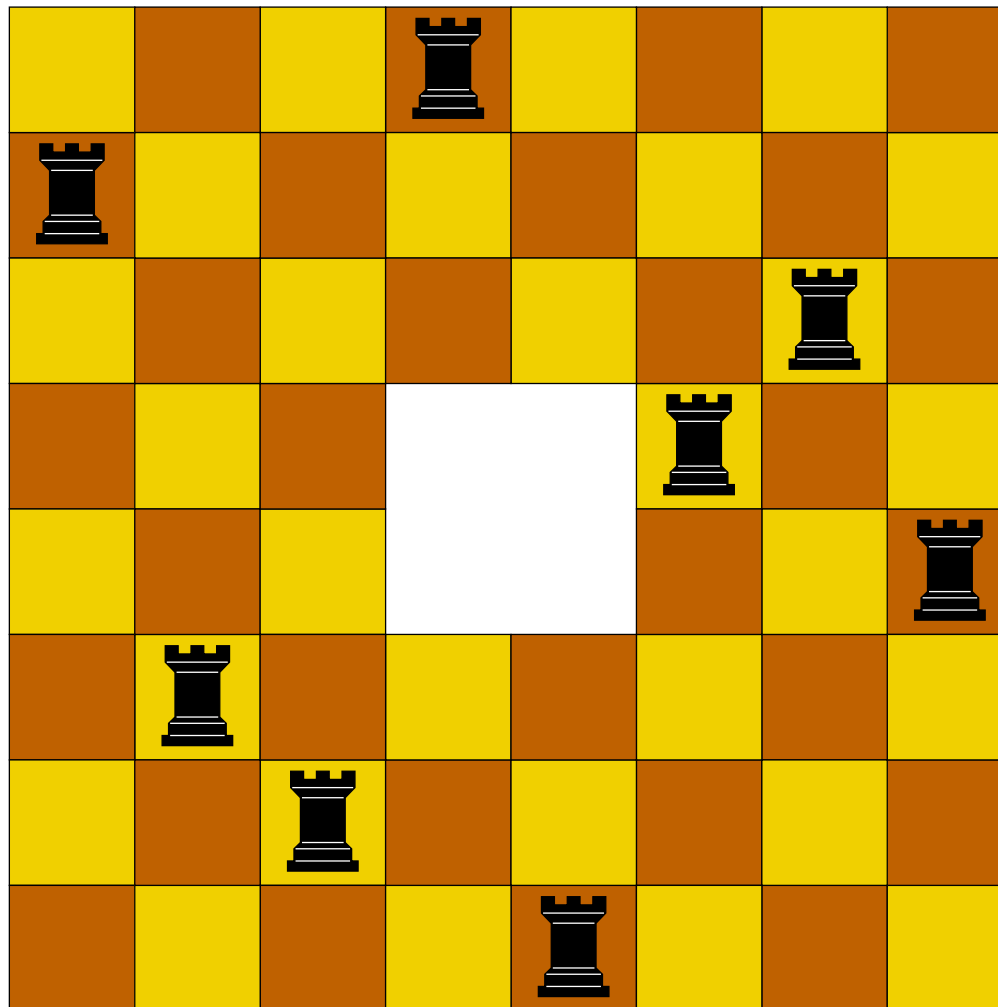
Chess Board



Chess Board

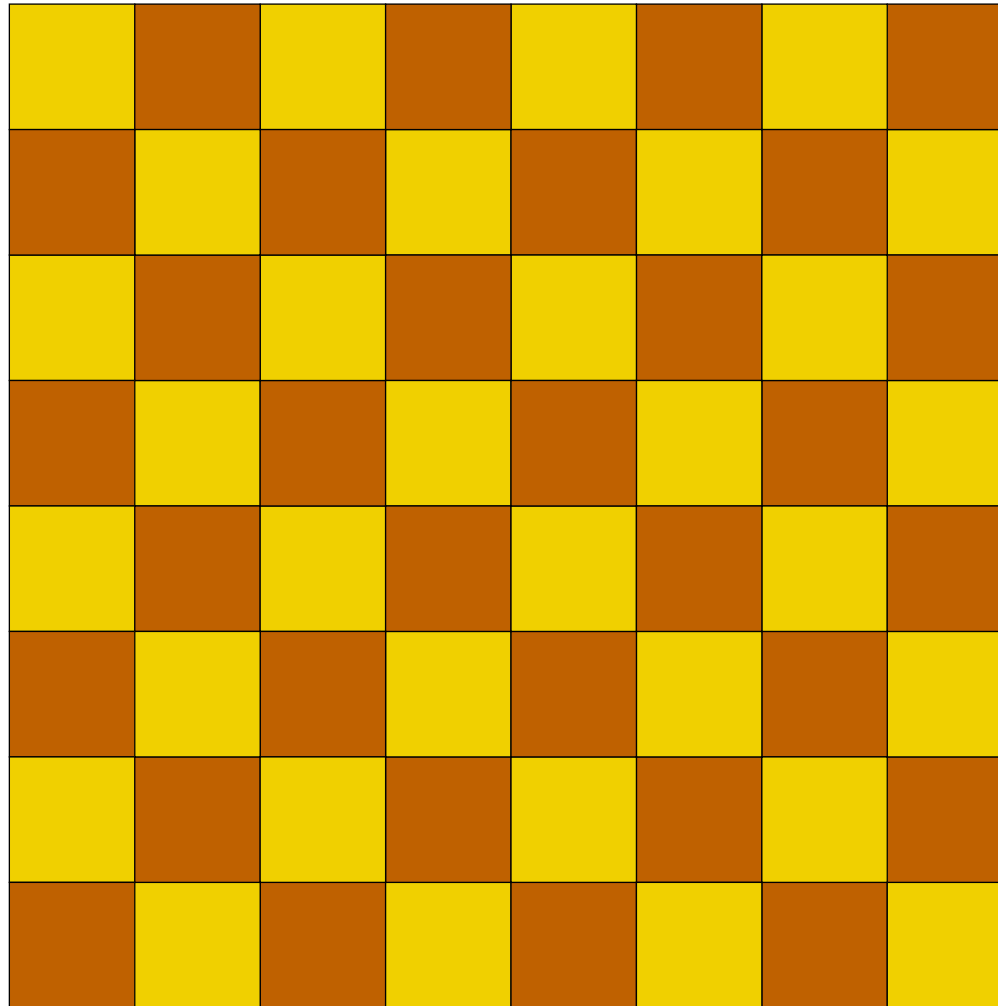


Chess Board

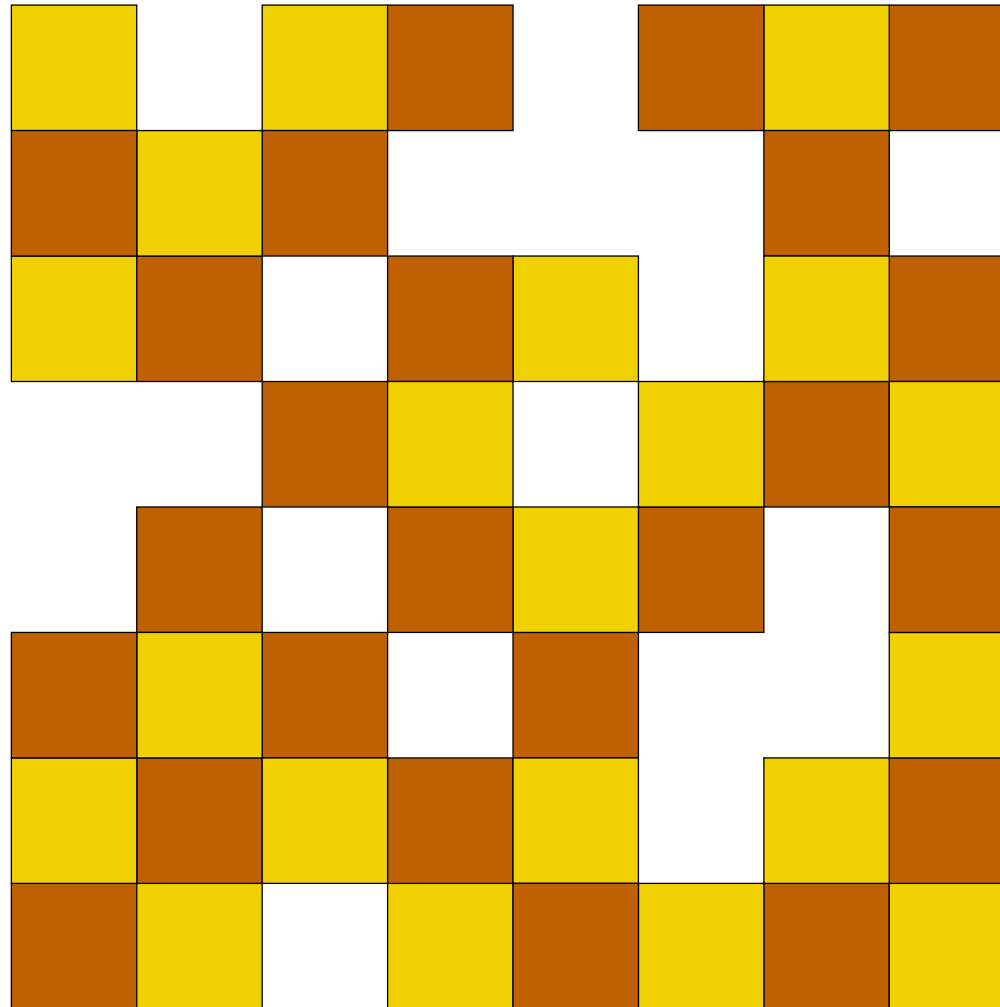


Question: in how many ways can we place 8 non-attacking rooks on this modified chess board?

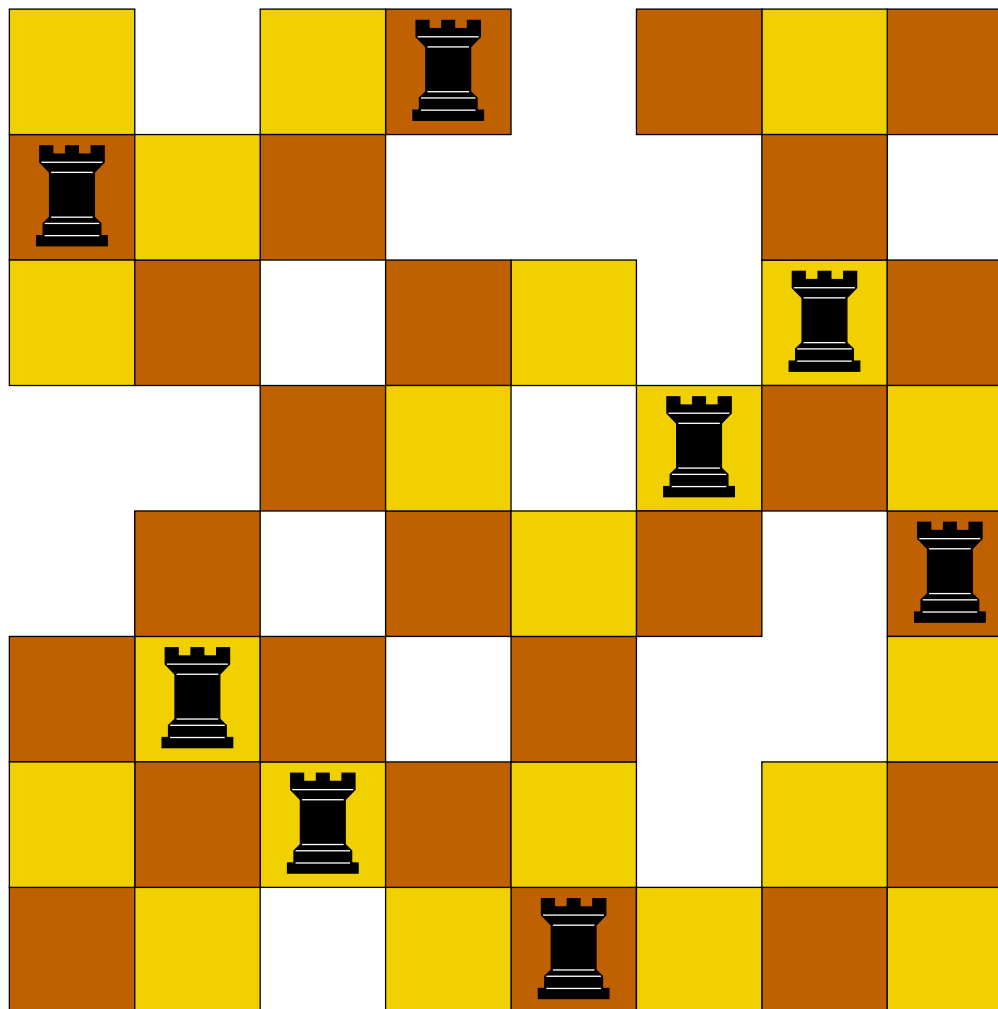
Chess Board



Chess Board

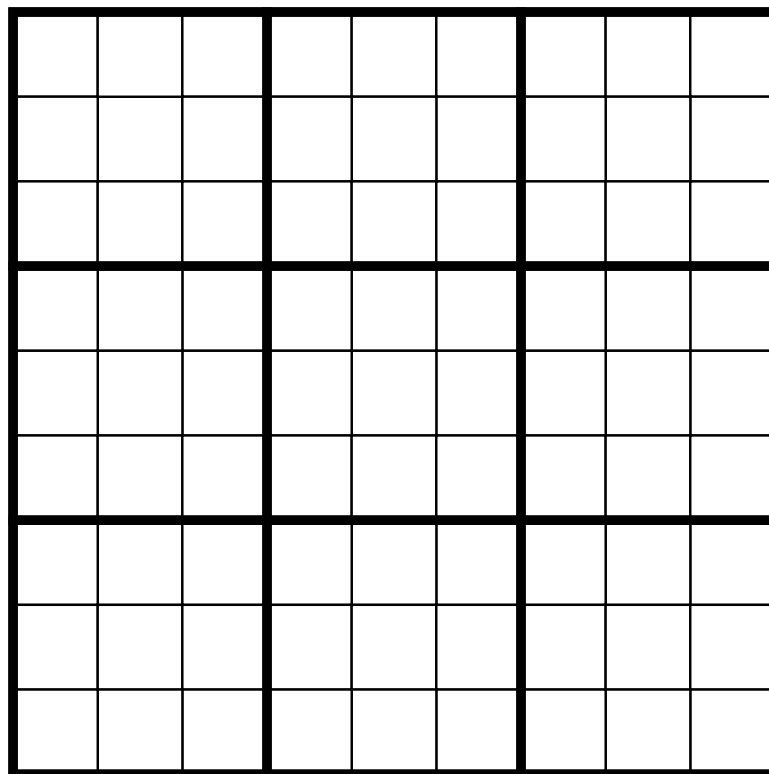


Chess Board



Question: in how many ways can we place 8 non-attacking rooks on this modified chess board?

Sudoku



Sudoku

1	2	5	3	9	6	8	7	4
4	6	3	8	7	5	2	9	1
7	9	8	2	4	1	5	3	6
5	4	7	6	1	2	9	8	3
2	3	9	5	8	4	1	6	7
8	1	6	9	3	7	4	2	5
6	8	1	7	5	9	3	4	2
3	7	4	1	2	8	6	5	9
9	5	2	4	6	3	7	1	8

Sudoku

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2	3	9	5	8	4	1	6	7
8	1	6	9	3	7	4	2	5
6	8	1	7	5	9	3	4	2
3	7	4	1	2	8	6	5	9
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Question: how many **Sudoku arrays** are there?
(More technically: how many **valid configurations** are there?)

Sudoku

1	2	5	3	9	6	8	7	4
4	6	3	8	7	5	2	9	1
7	9	8	2	4	1	5	3	6
5	4	7	6	1	2	9	8	3
2	3	9	5	8	4	1	6	7
8	1	6	9	3	7	4	2	5
6	8	1	7	5	9	3	4	2
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9	5	2	4	6	3	7	1	8

Row condition: numbers 1, ..., 9 appear exactly once.

Sudoku

1	2	5	3	9	6	8	7	4
4	6	3	8	7	5	2	9	1
7	9	8	2	4	1	5	3	6
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2	3	9	5	8	4	1	6	7
8	1	6	9	3	7	4	2	5
6	8	1	7	5	9	3	4	2
3	7	4	1	2	8	6	5	9
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Column condition: numbers 1, ..., 9 appear exactly once.

Sudoku

1	2	5	3	9	6	8	7	4
4	6	3	8	7	5	2	9	1
7	9	8	2	4	1	5	3	6
5	4	7	6	1	2	9	8	3
2	3	9	5	8	4	1	6	7
8	1	6	9	3	7	4	2	5
6	8	1	7	5	9	3	4	2
3	7	4	1	2	8	6	5	9
9	5	2	4	6	3	7	1	8

Sub-block condition: numbers 1, ..., 9 appear exactly once.

Sudoku

1	2	5	3	9	6	8	7	4
4	6	3	8	7	5	2	9	1
7	9	8	2	4	1	5	3	6
5	4	7	6	1	2	9	8	3
2	3	9	5	8	4	1	6	7
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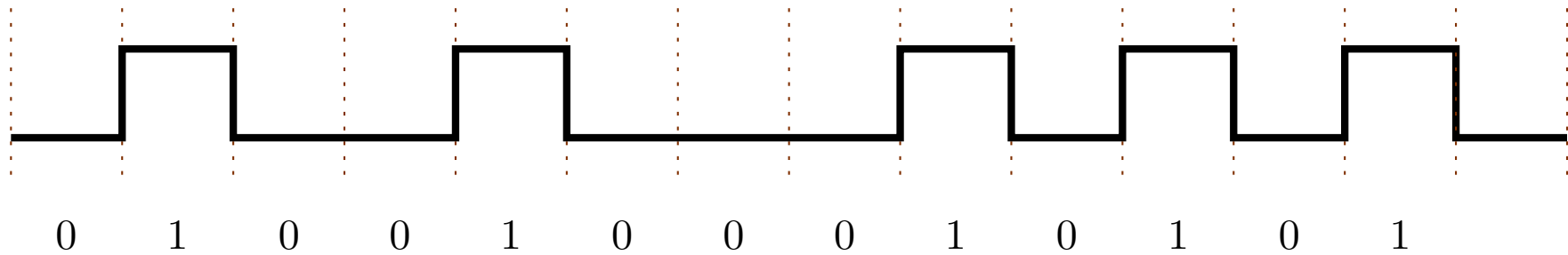
Other Sudoku Setups

Other Sudoku Setups

3	5	8	1	9	6	2	7	4
4	9	2	5	6	7	1	3	8
6	1	3	9	7	8	4	2	5
1	7	5	8	4	2	6	9	3
8	2	6	4	5	3	7	1	9
2	4	9	7	3	1	8	5	6
9	8	7	3	2	4	5	6	1
7	3	4	6	1	5	9	8	2
5	6	1	2	8	9	3	4	7

1D constraints in communications

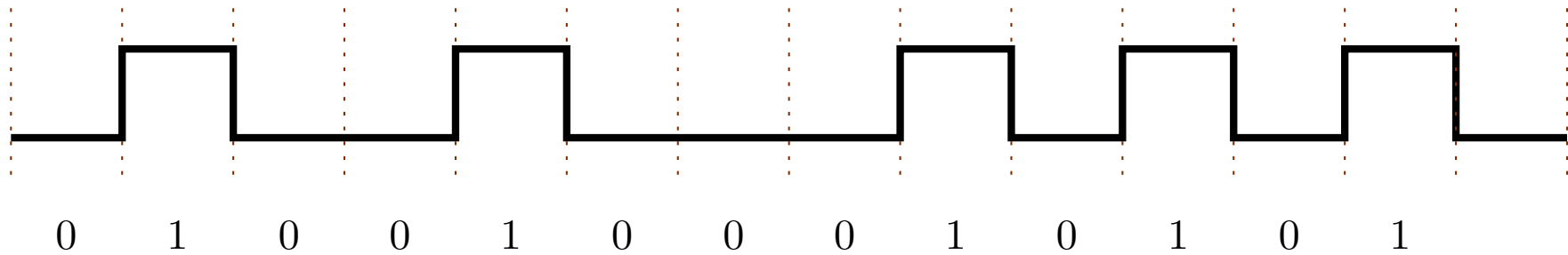
RLL Constraints



A (d, k) RLL constraint imposes:

- At least d zero symbols between two ones.
- At most k zero symbols between two ones.

RLL Constraints

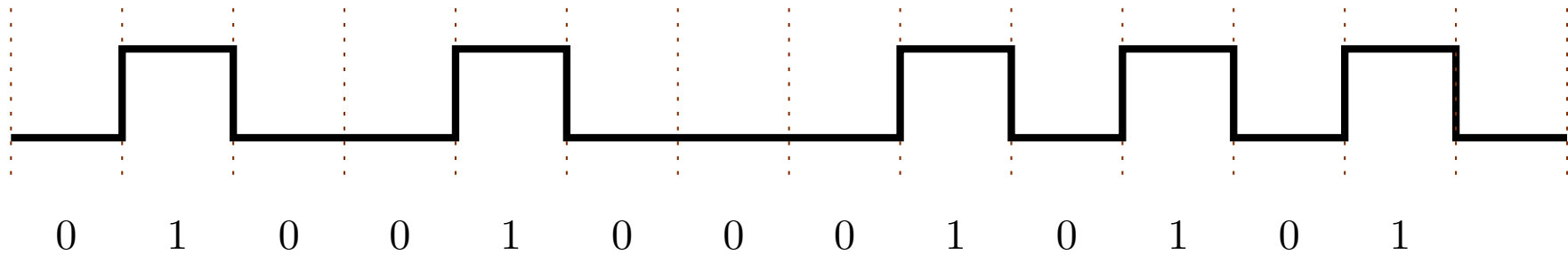


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Question: how many sequences of length T fulfill these constraints?

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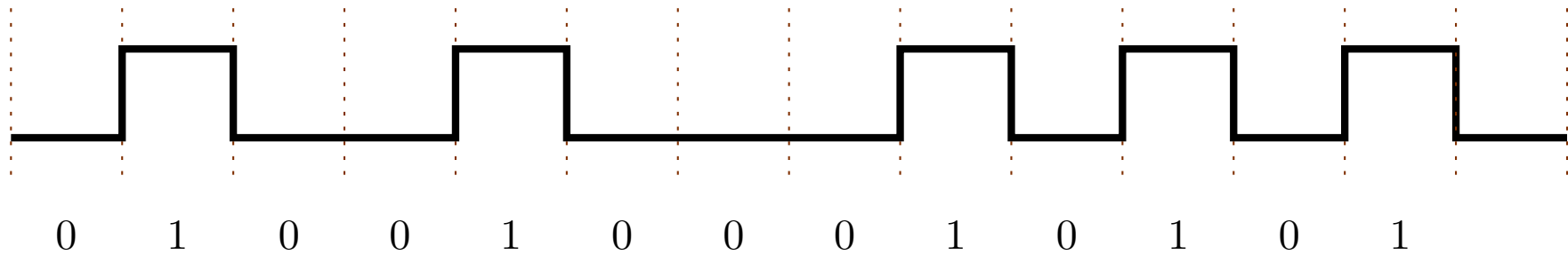
- At least d zero symbols between two ones.
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Answer: typically, the answer to such questions looks like

$$N(T) = \exp(C \cdot T + o(T)).$$

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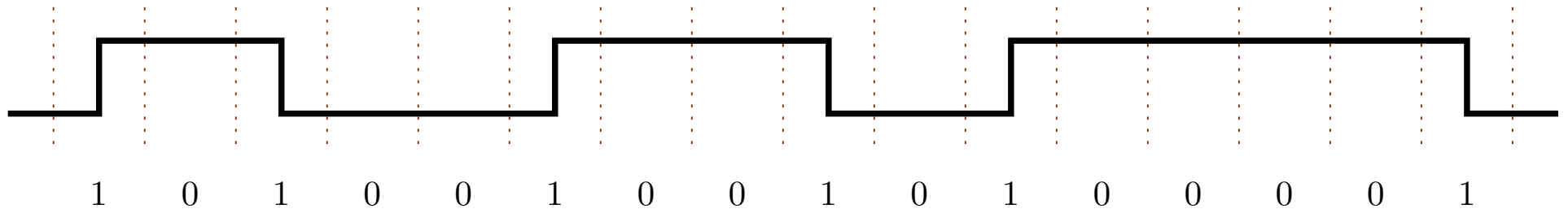
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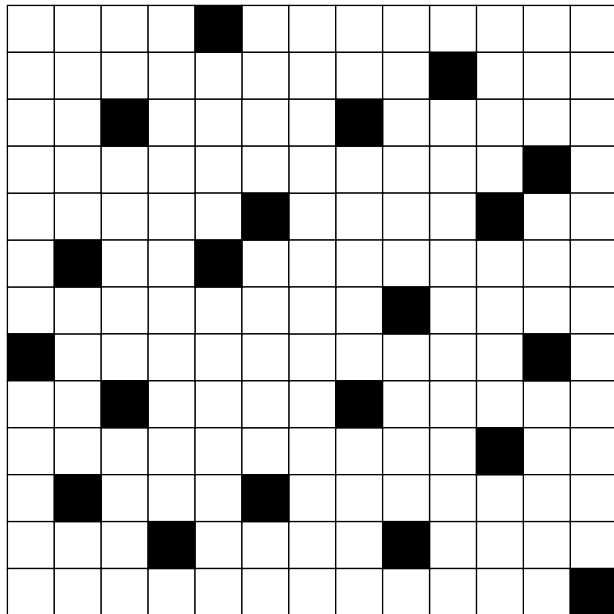
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2D constraints in communications

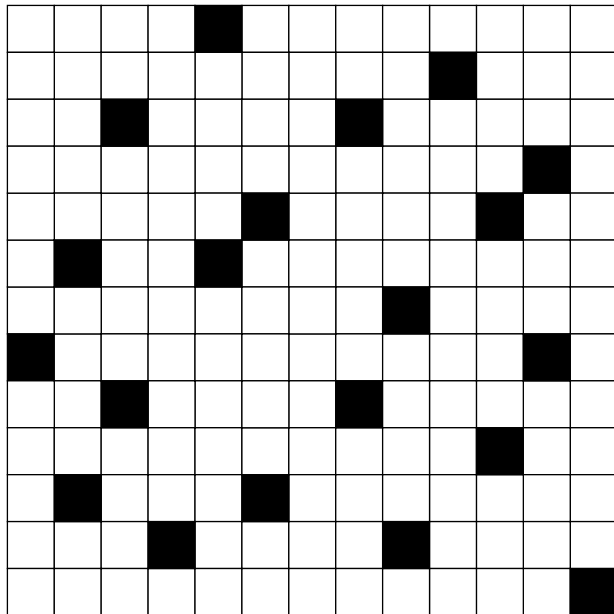
Two-Dimensional RLL Constraints



Two-Dimensional RLL Constraints

A $(d_1, k; d_2, k_2)$ RLL constraint imposes:

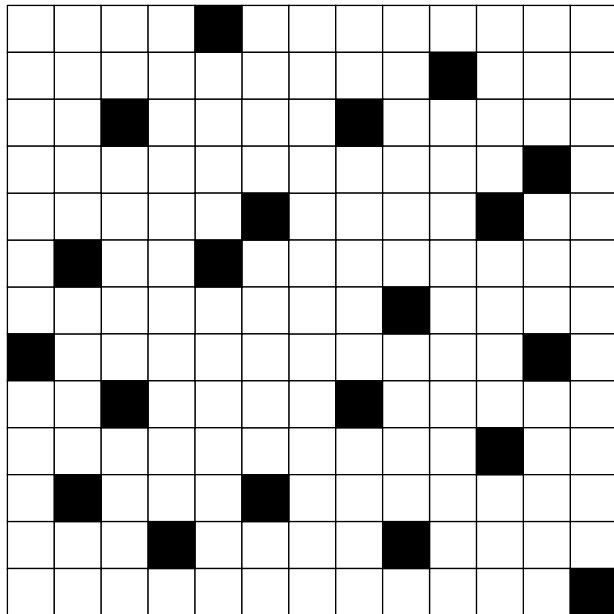
- ...
- ...



Two-Dimensional RLL Constraints

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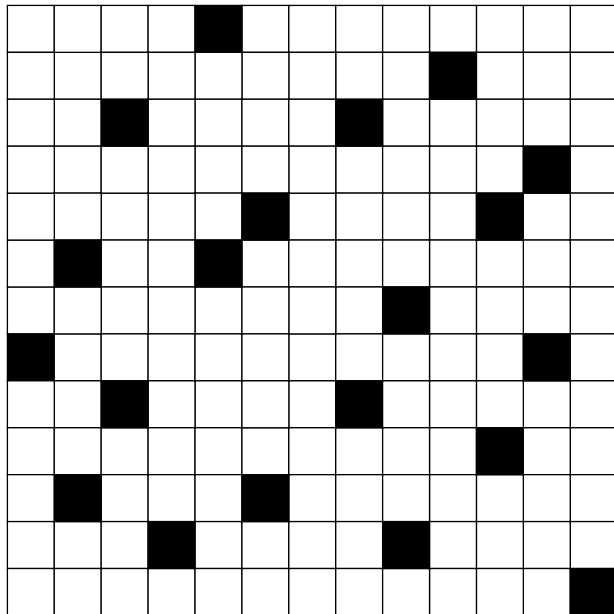


Question: How many **arrays** of size $m \times n$ fulfill these constraints?

Two-Dimensional RLL Constraints

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- ...
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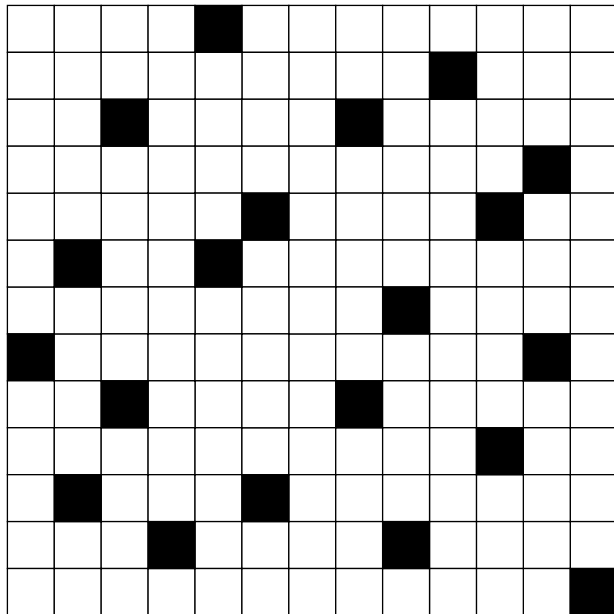
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$$N(m, n) = \exp(C \cdot mn + o(mn)).$$

Two-Dimensional RLL Constraints

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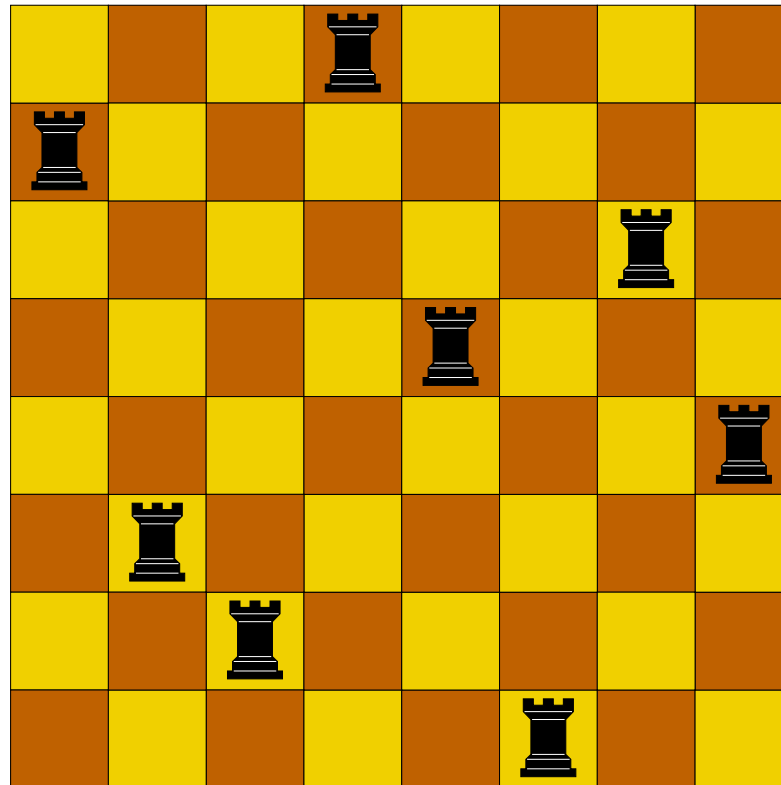
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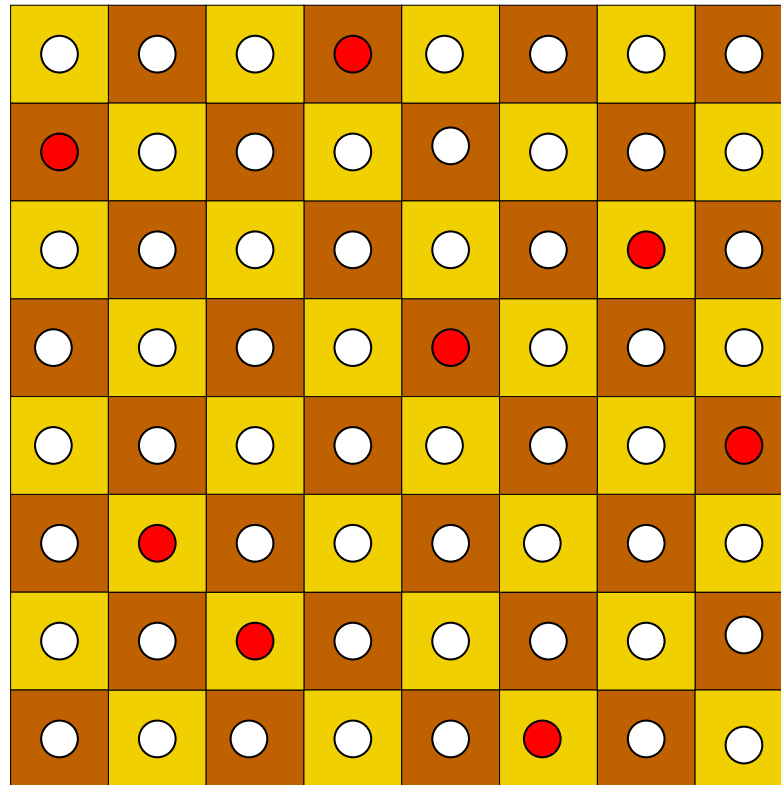
Towards a graphical model

Towards a Graphical Model

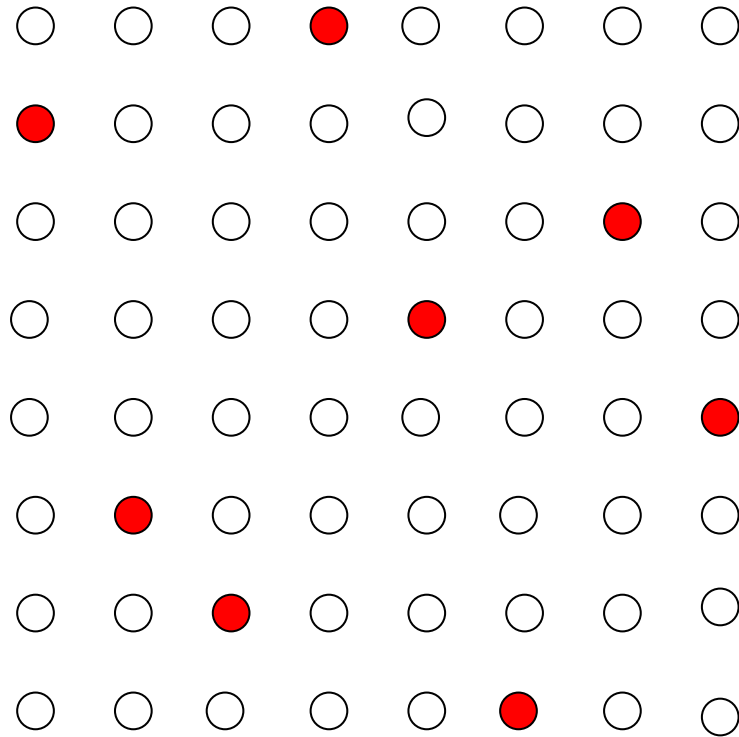


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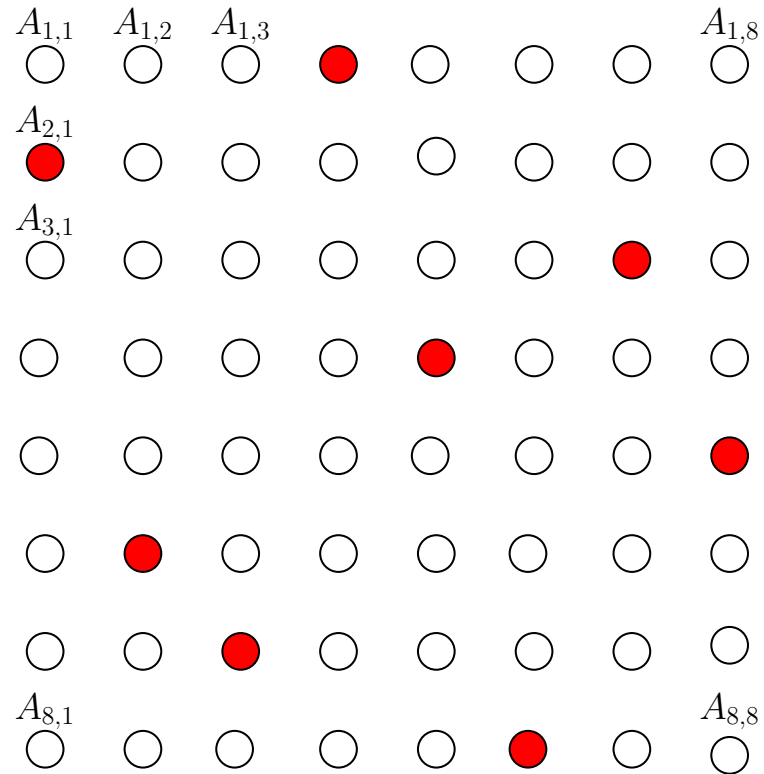
Towards a Graphical Model



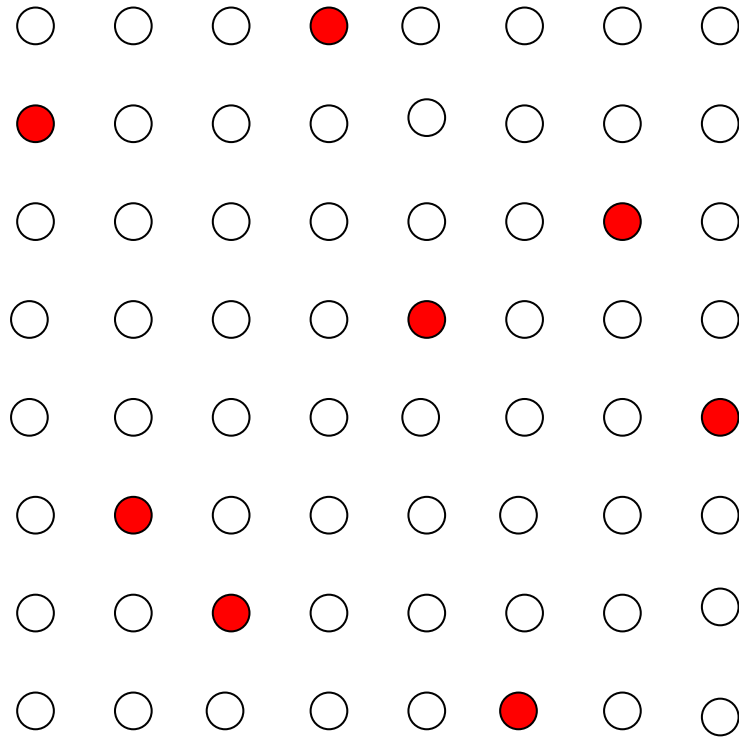
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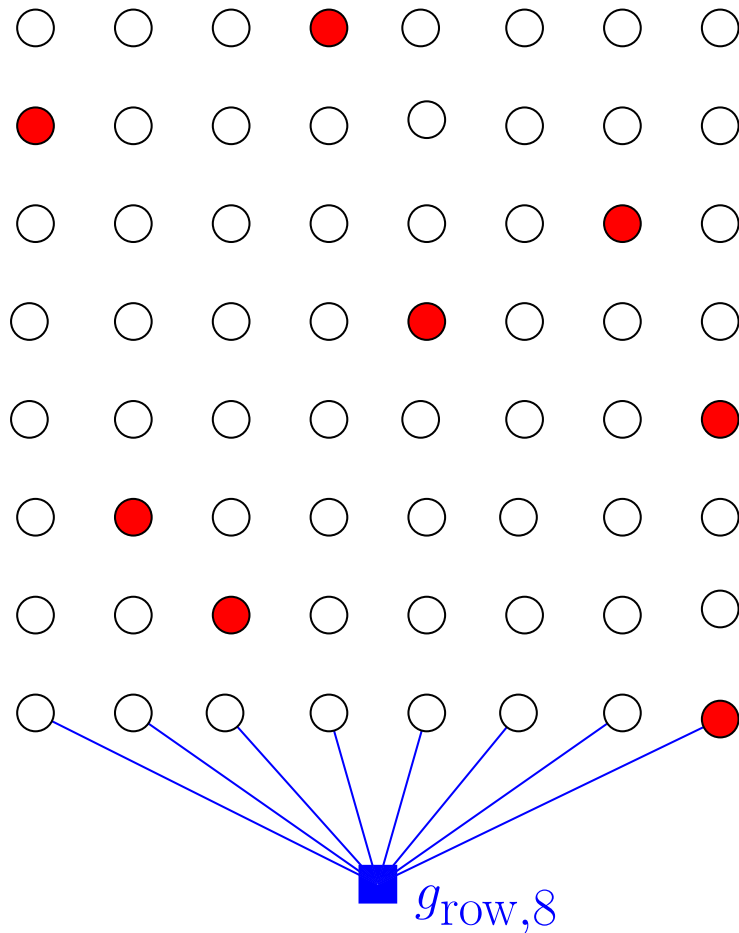
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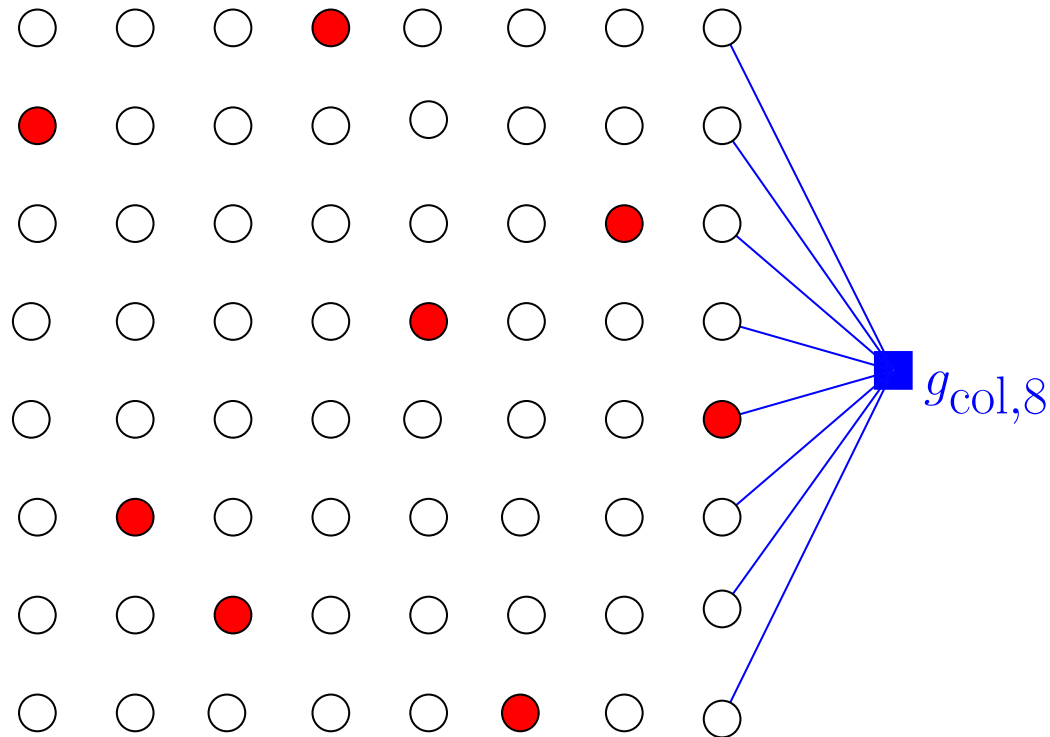


Towards a Graphical Model



$$g_{\text{row},8}(a_{8,1}, \dots, a_{8,8}) \triangleq \begin{cases} 1 & \text{exactly one rook} \\ 0 & \text{otherwise} \end{cases}$$

Towards a Graphical Model



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$$\left\{ \begin{array}{l} A_{1,1} \circ \\ A_{2,1} \circ \\ \vdots \\ A_{7,1} \circ \\ A_{8,1} \circ \end{array} \right.$$

Towards a Graphical Model

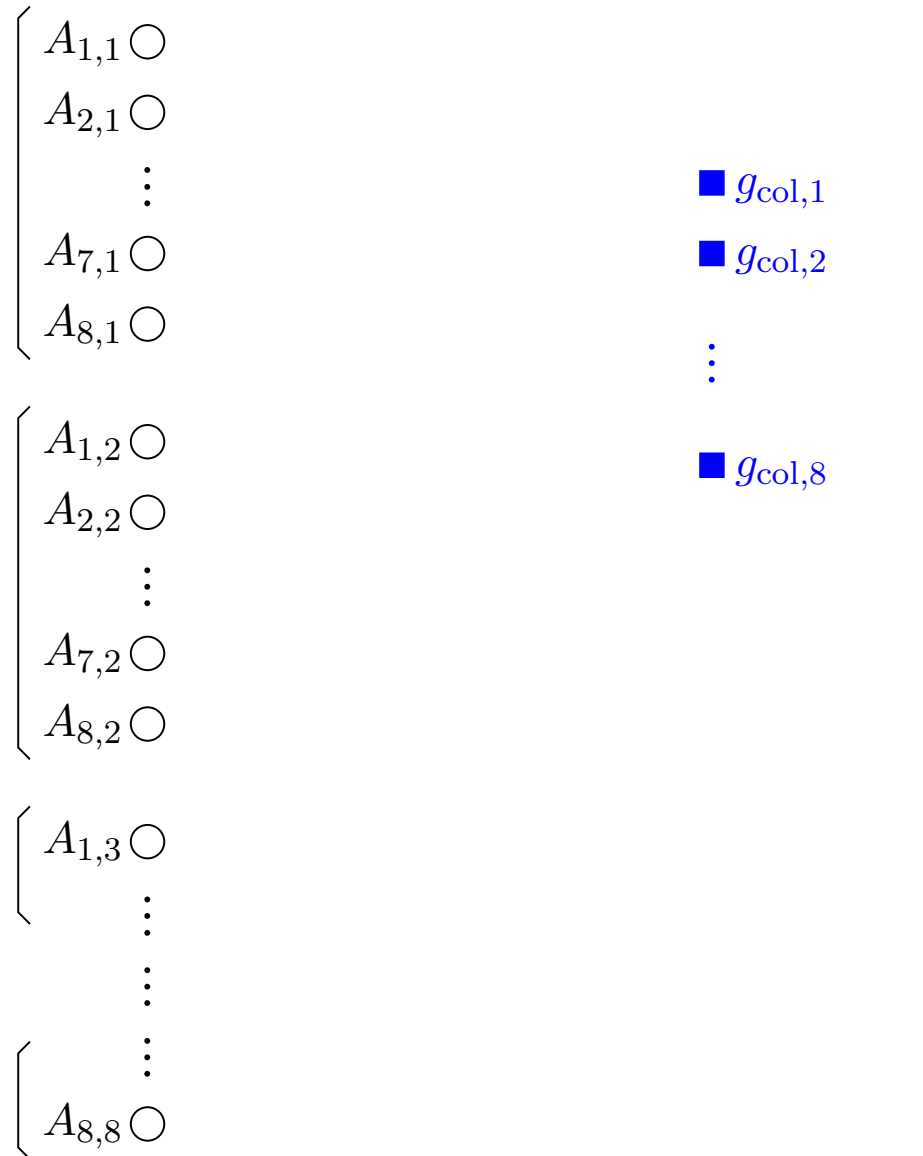
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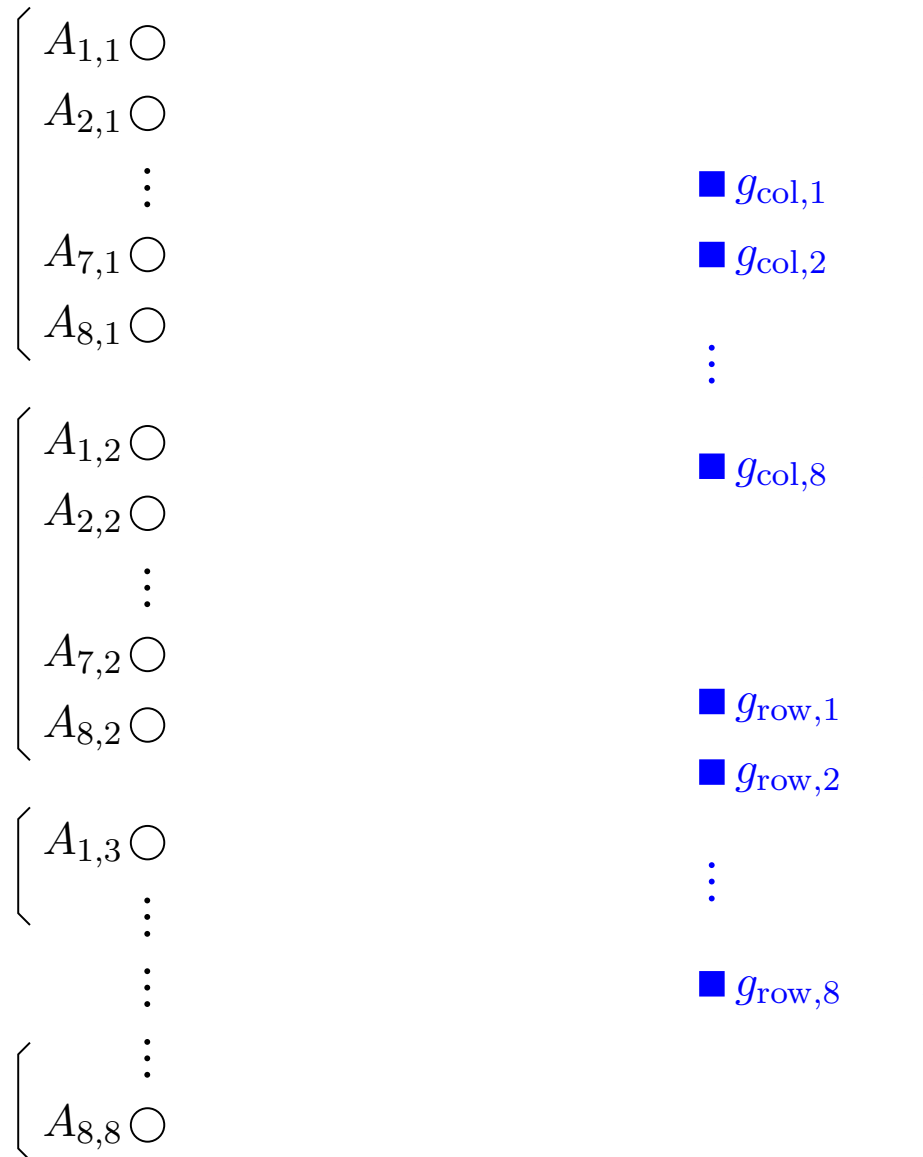
Towards a Graphical Model

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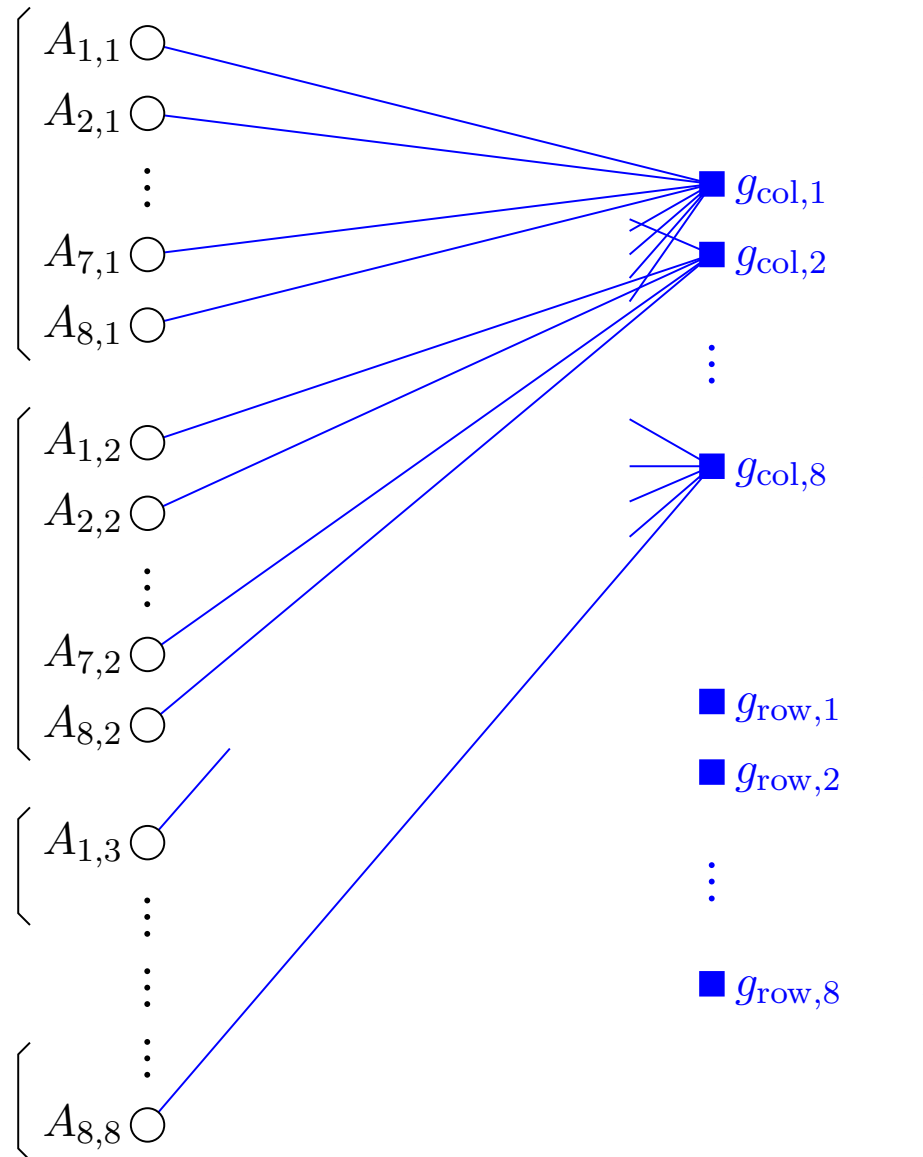
Towards a Graphical Model



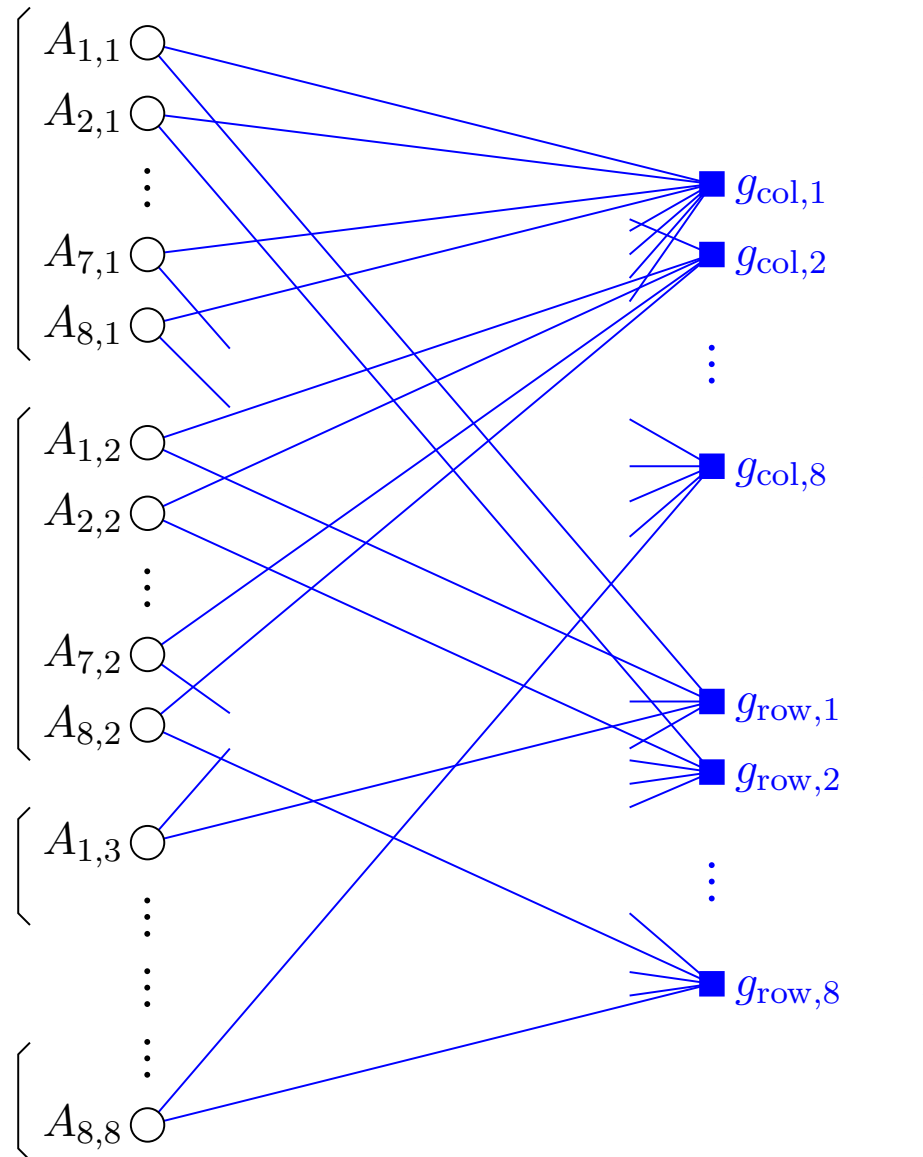
Towards a Graphical Model



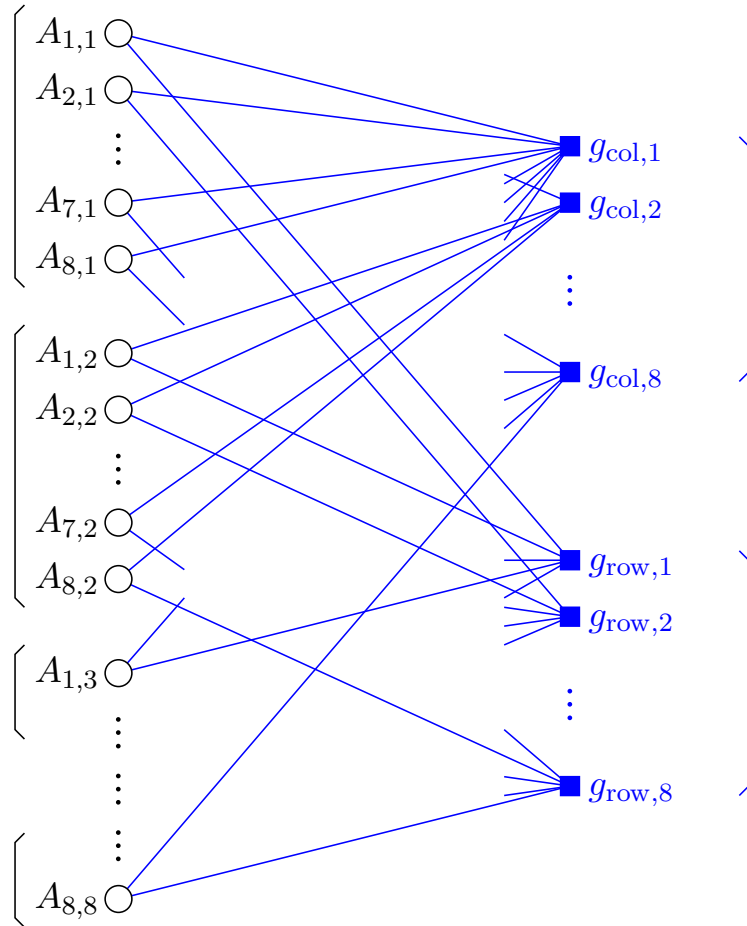
Towards a Graphical Model



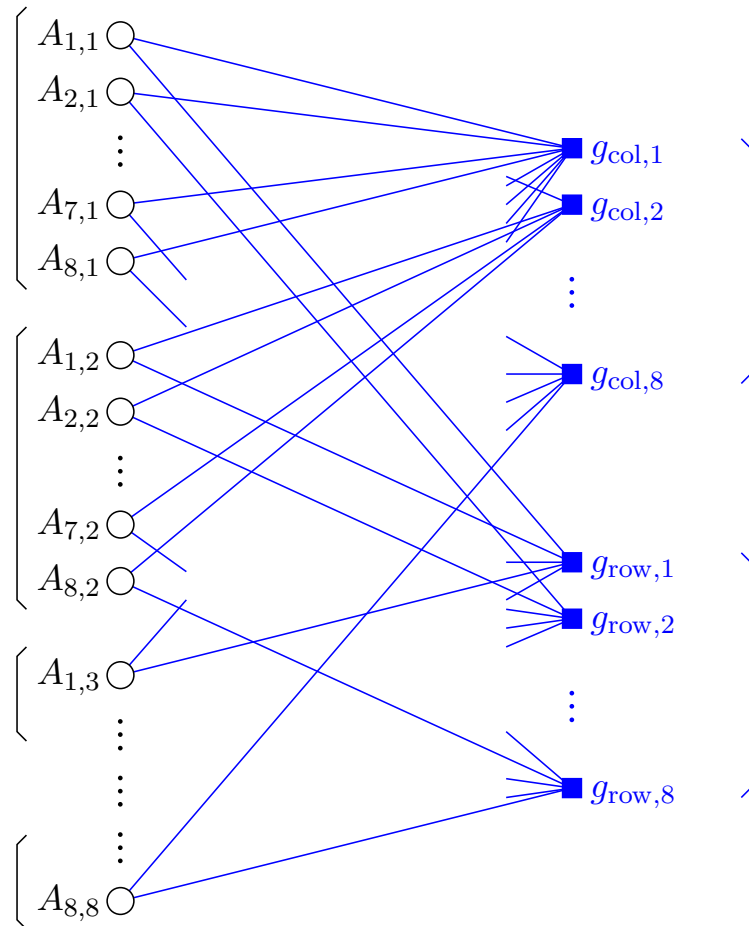
Towards a Graphical Model



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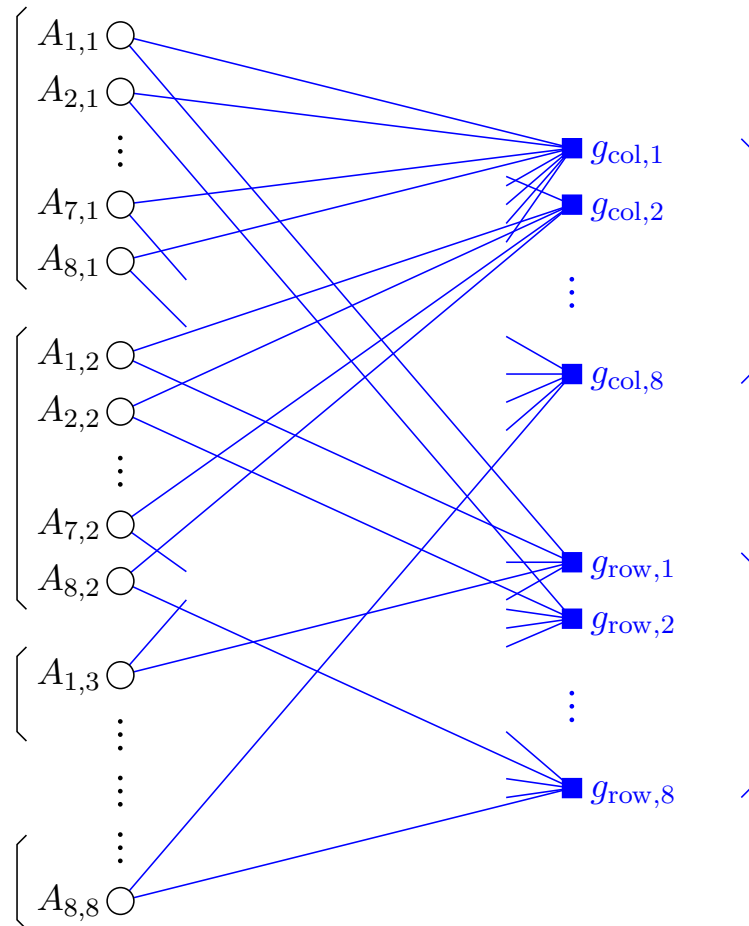
Towards a Graphical Model



Global function:

$$\begin{aligned} &g(a_{1,1}, \dots, a_{8,8}) \\ &= \prod_j g_{\text{col},j}(a_{1,j}, \dots, a_{8,j}) \times \\ &\quad \prod_i g_{\text{row},i}(a_{i,1}, \dots, a_{i,8}) \end{aligned}$$

Towards a Graphical Model



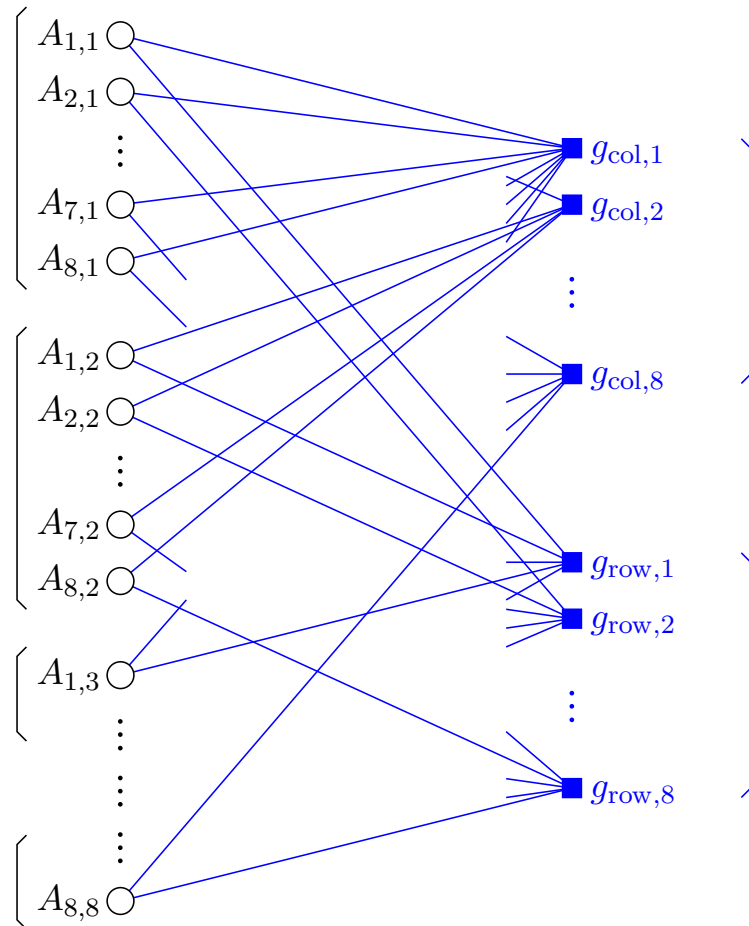
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 \end{aligned}$$

Total sum:

$$Z = \sum_{a_{1,1}, \dots, a_{8,8}} g(a_{1,1}, \dots, a_{8,8})$$

Towards a Graphical Model



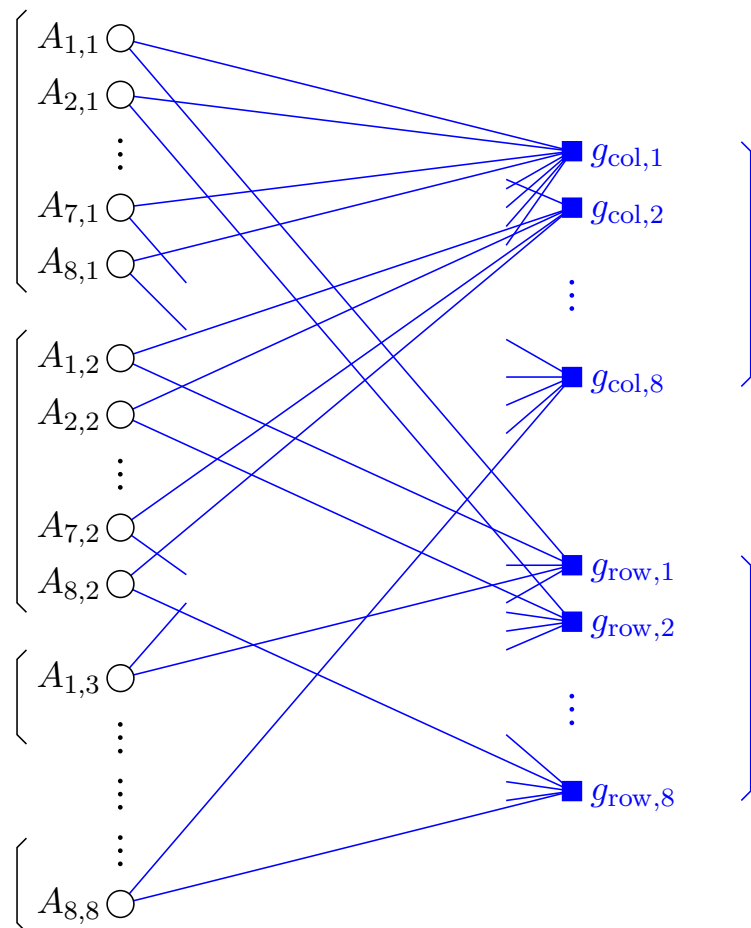
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Total sum (partition function):

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Towards a Graphical Model



Global function:

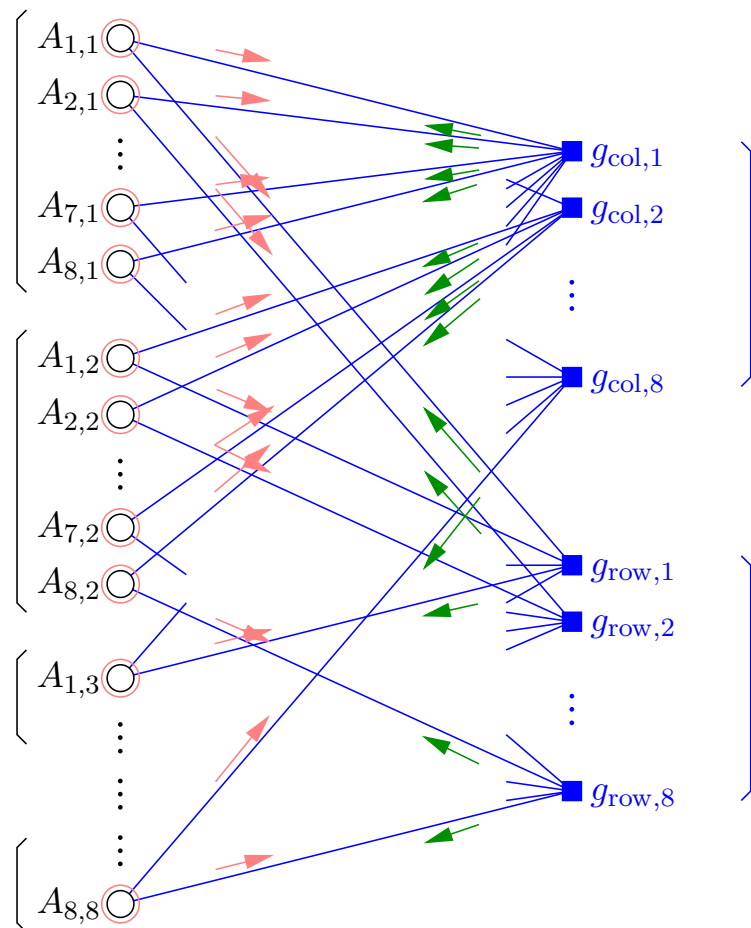
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Use of loopy belief propagation
for approximating Z ?

Towards a Graphical Model



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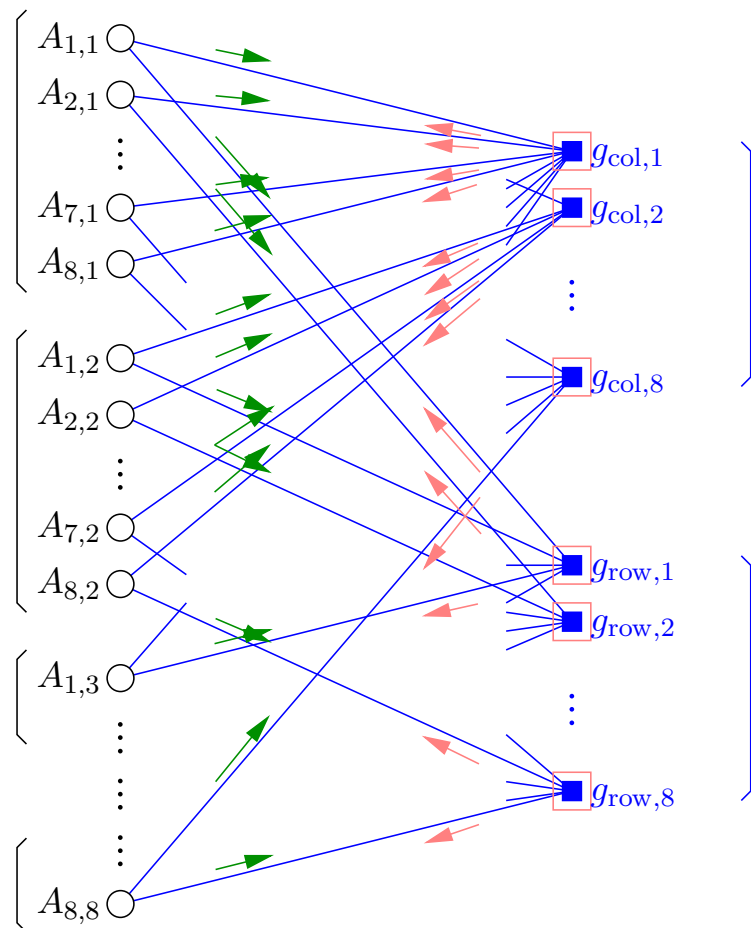
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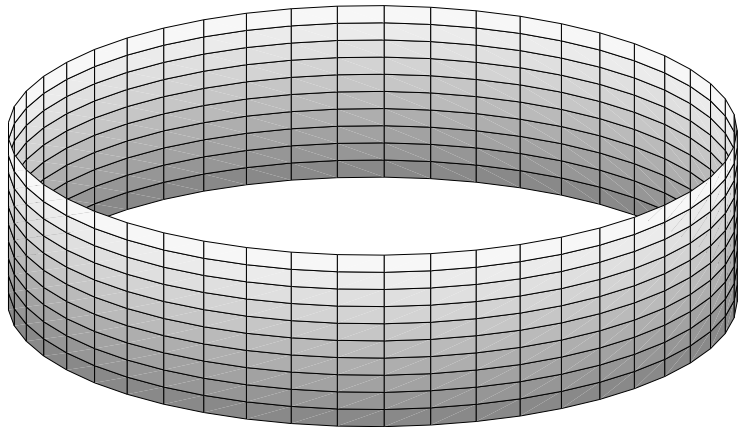
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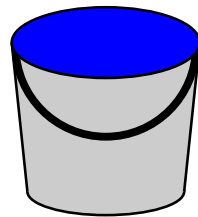
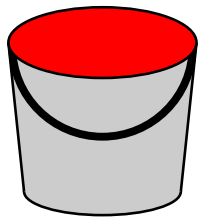
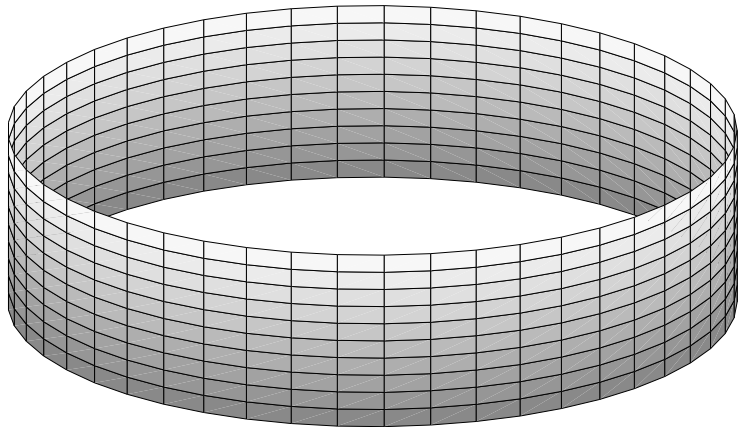
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Some considerations on counting algorithms

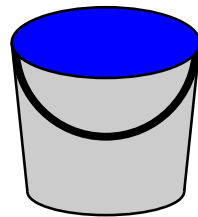
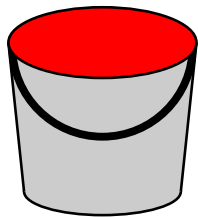
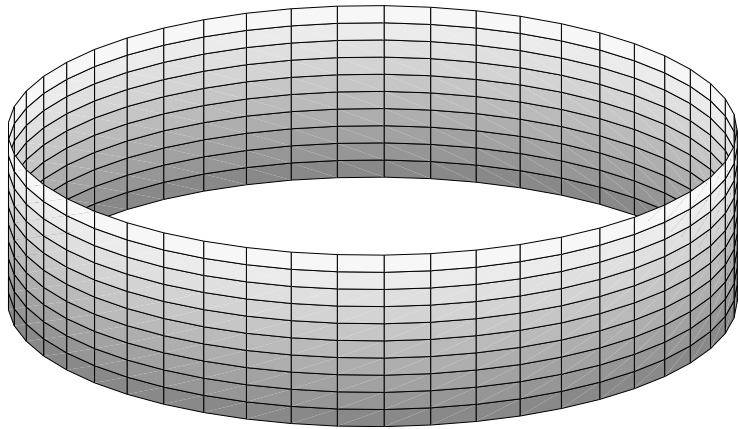
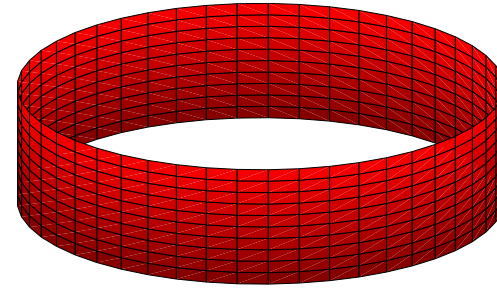
Coloring the Surfaces of a Closed Strip



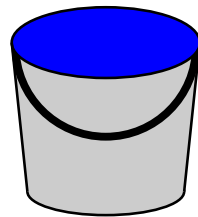
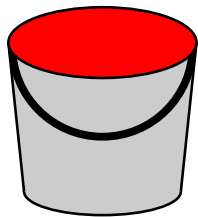
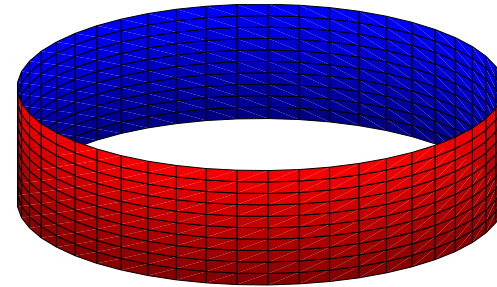
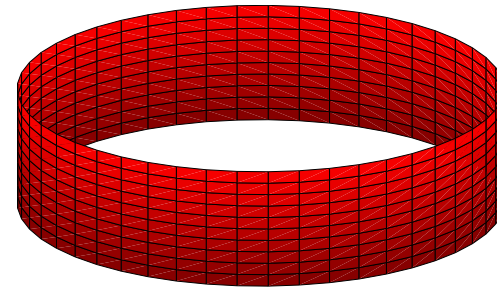
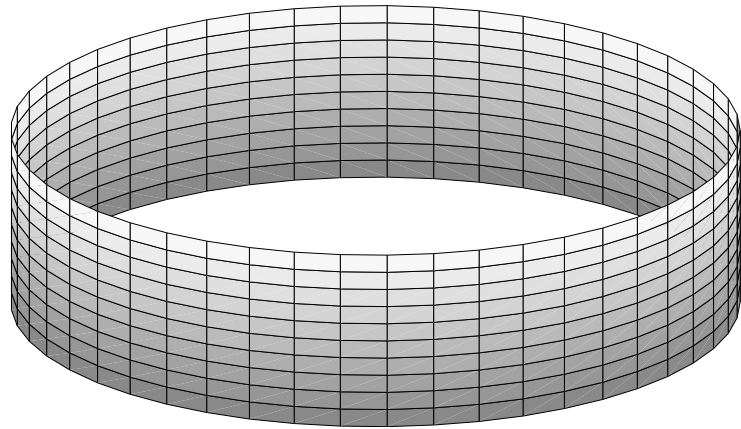
Coloring the Surfaces of a Closed Strip



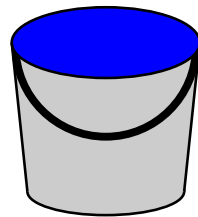
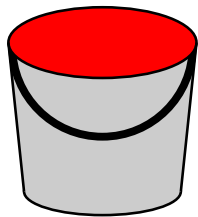
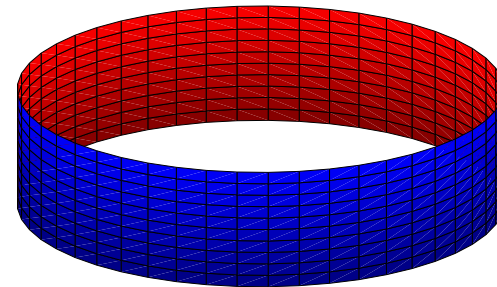
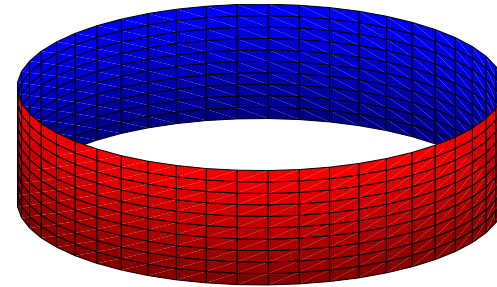
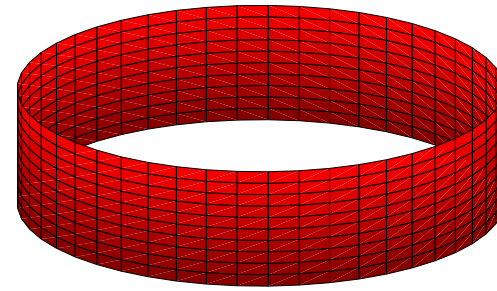
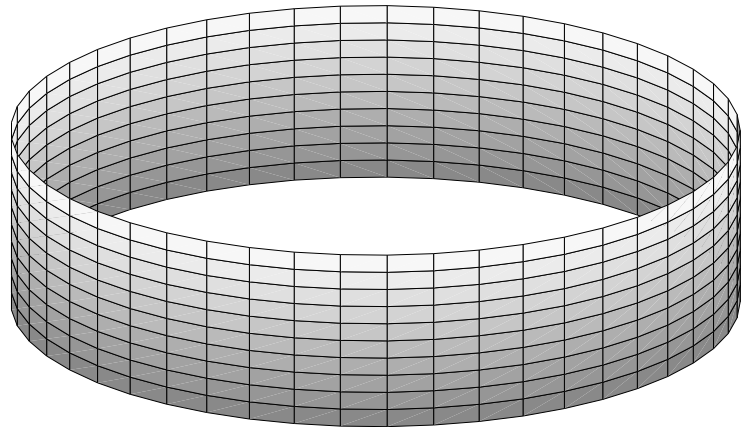
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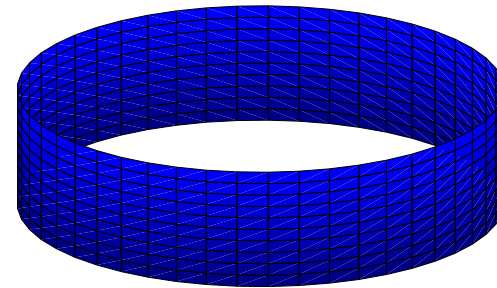
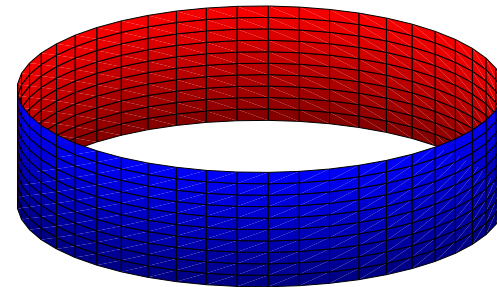
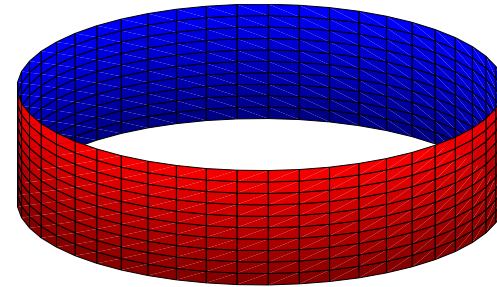
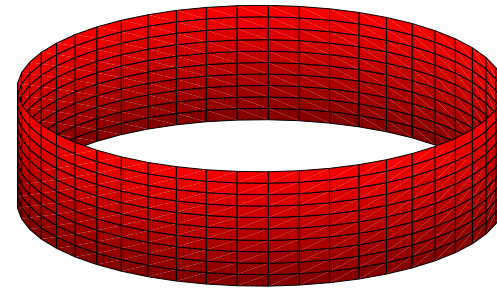
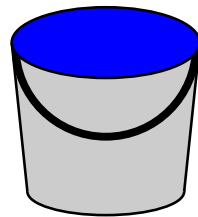
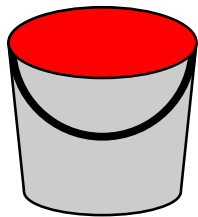
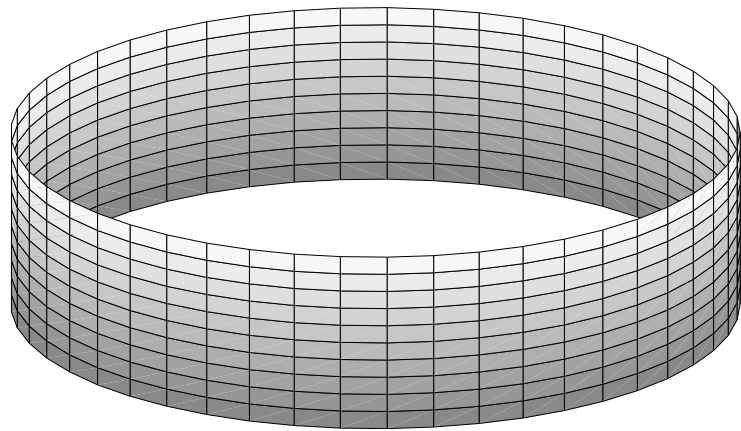
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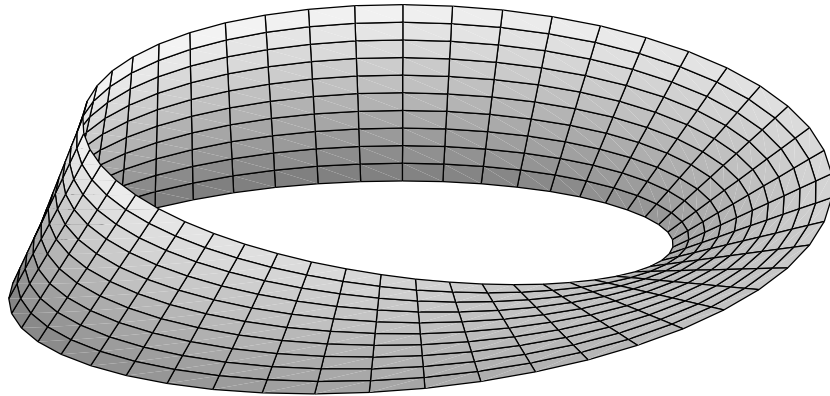
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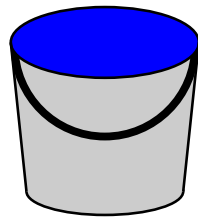
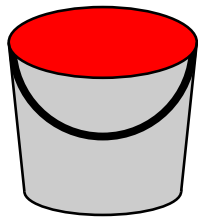
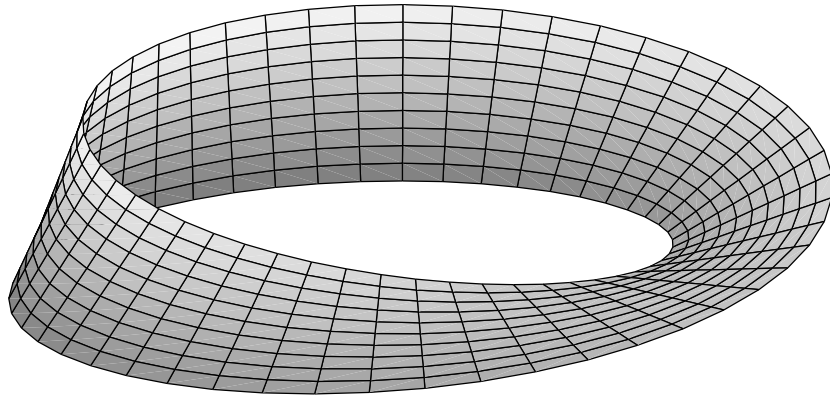
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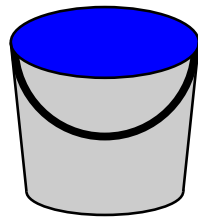
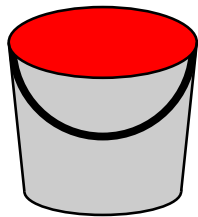
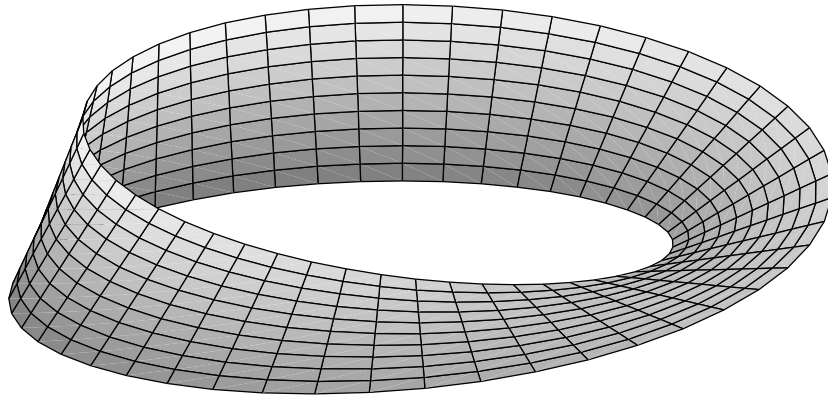
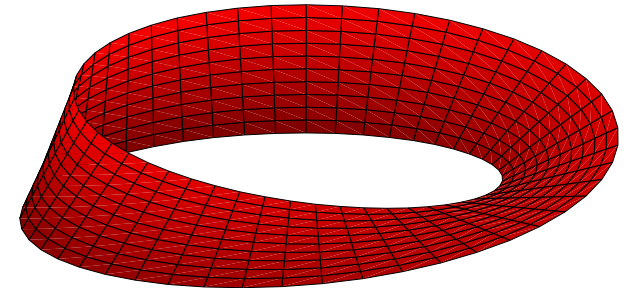
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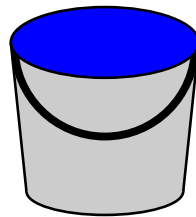
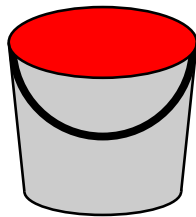
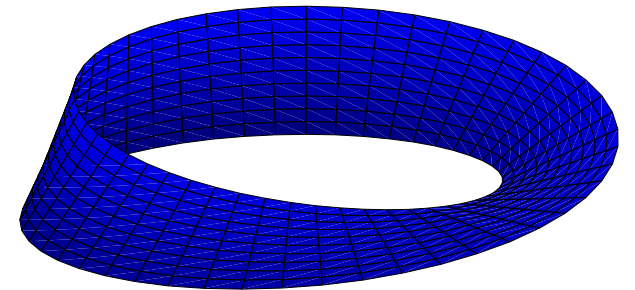
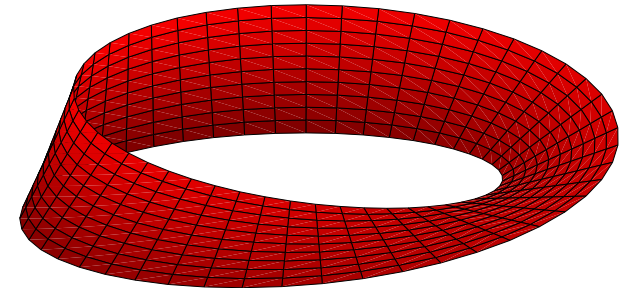
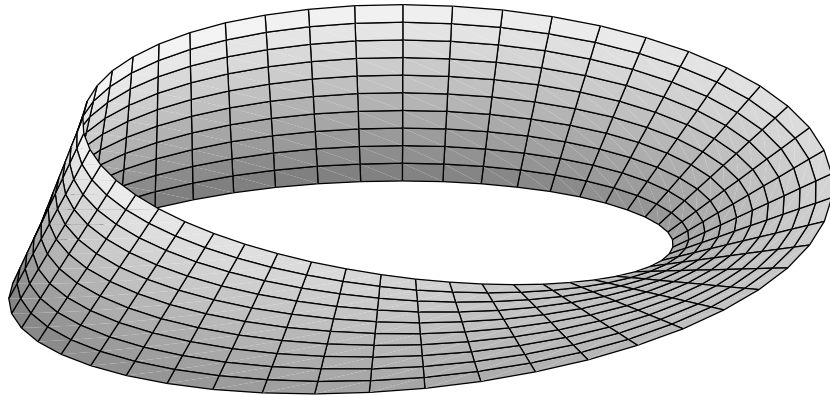
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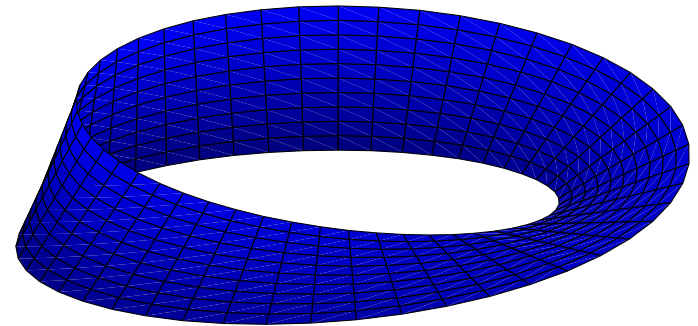
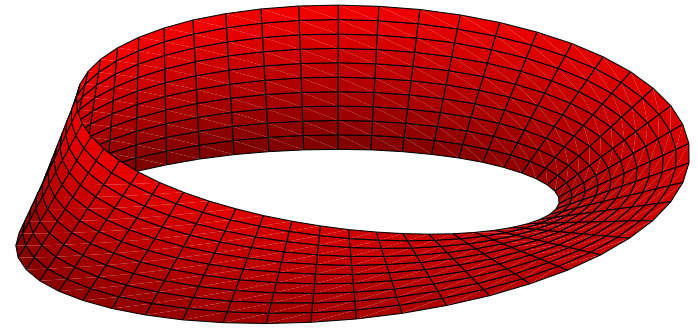
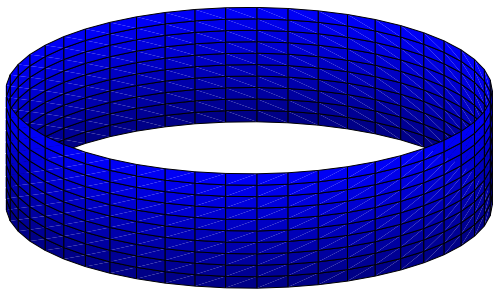
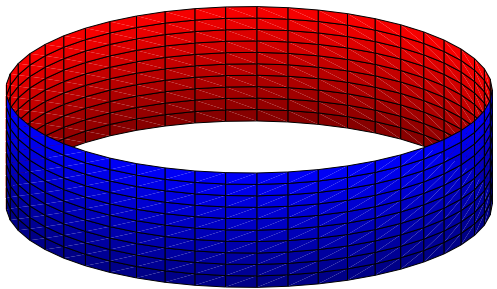
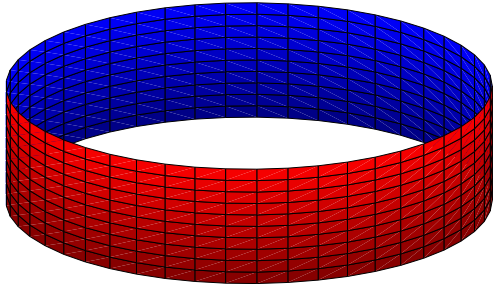
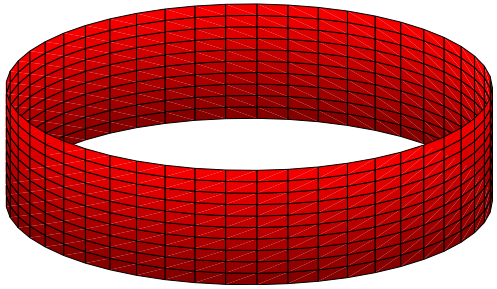


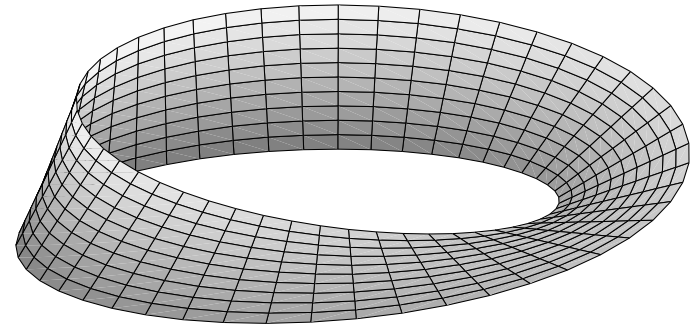
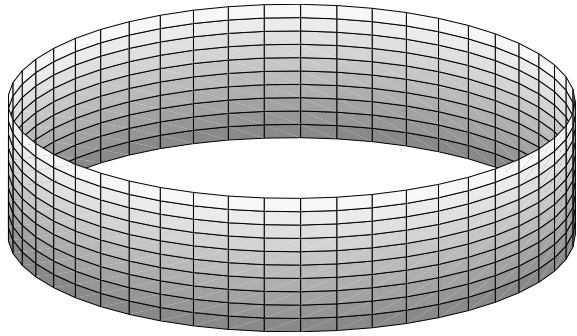
Coloring the Surfaces of a Closed Strip

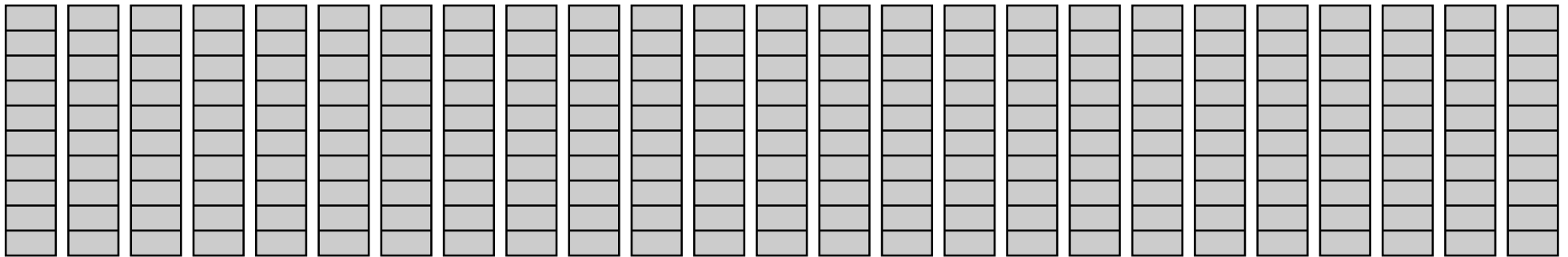
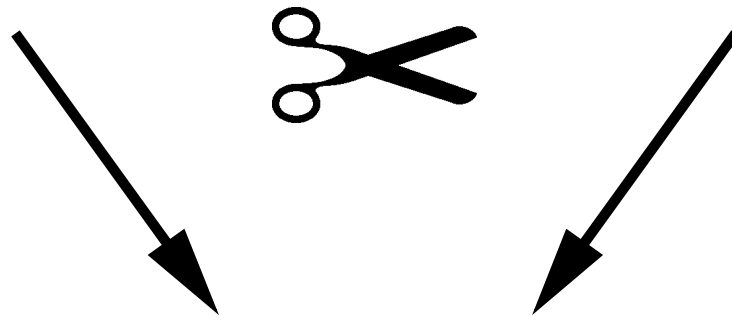
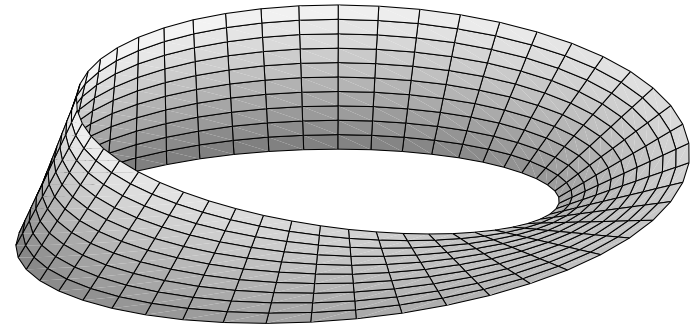
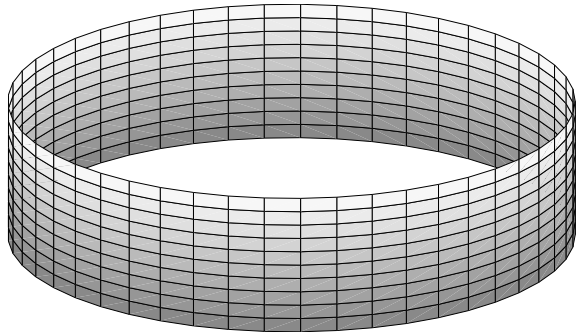


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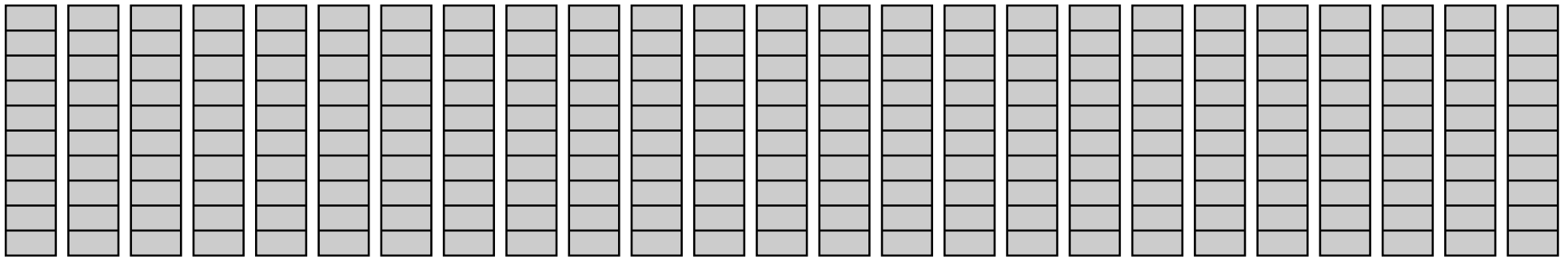
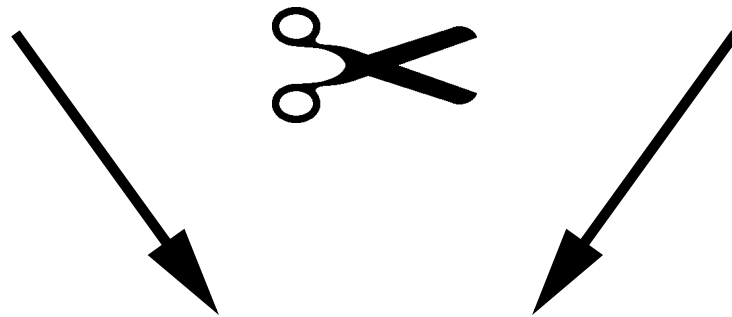
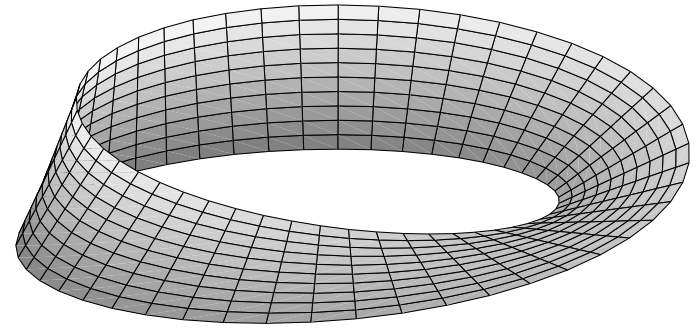
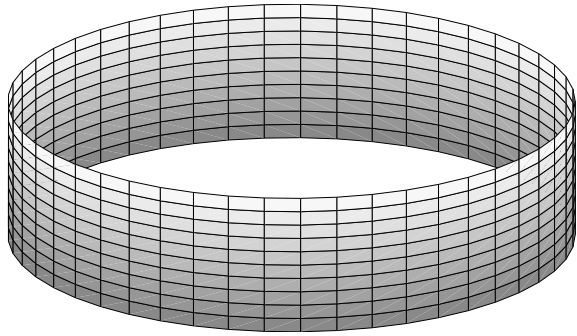




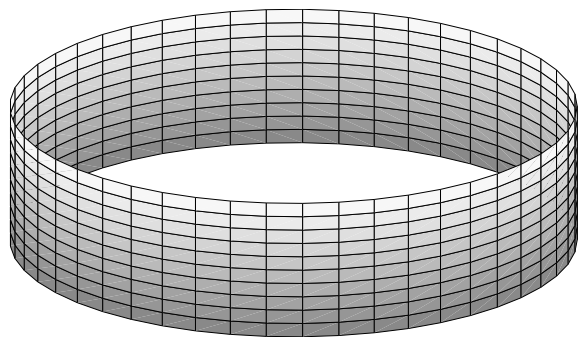




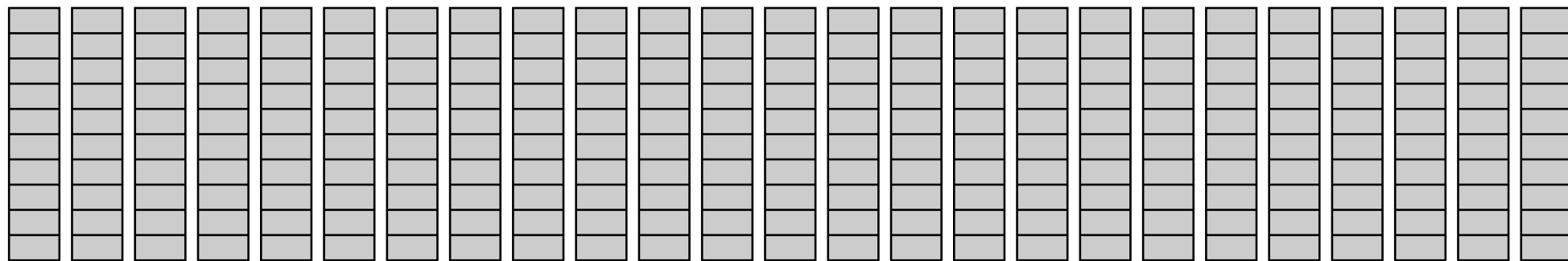
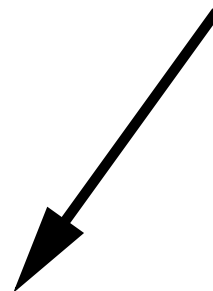
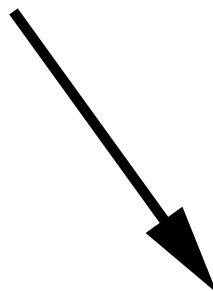
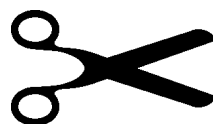
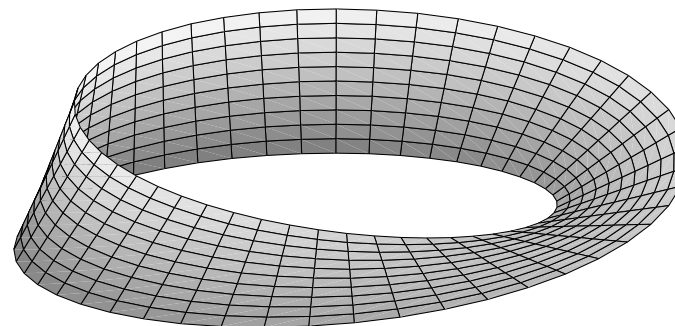
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4



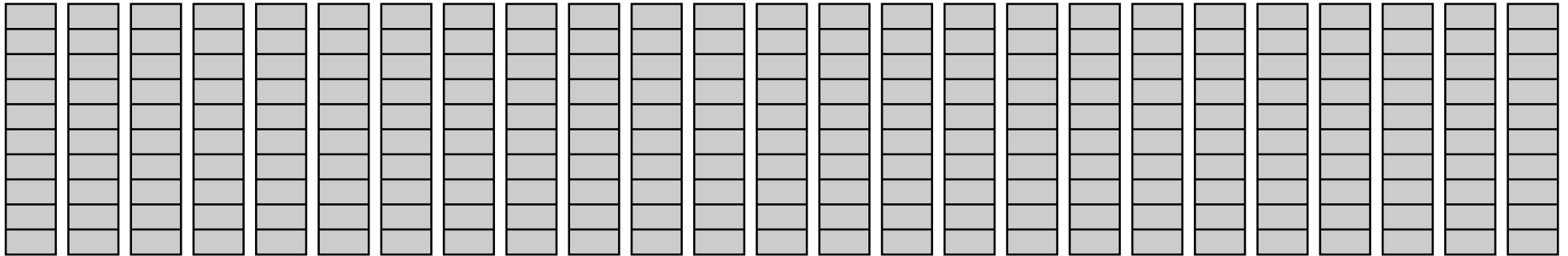
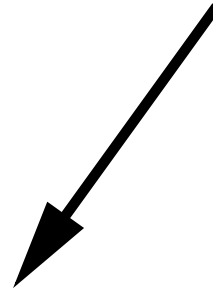
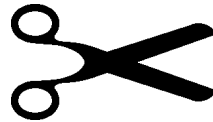
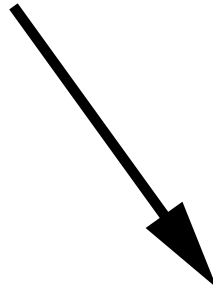
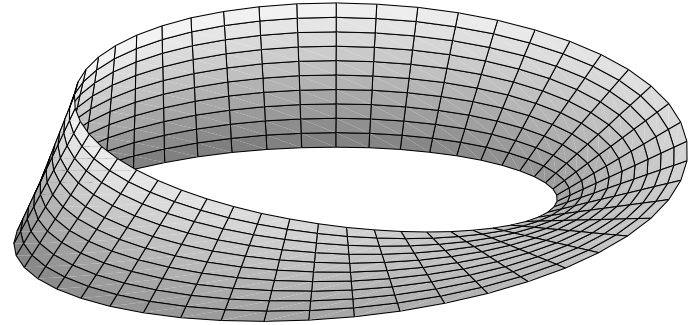
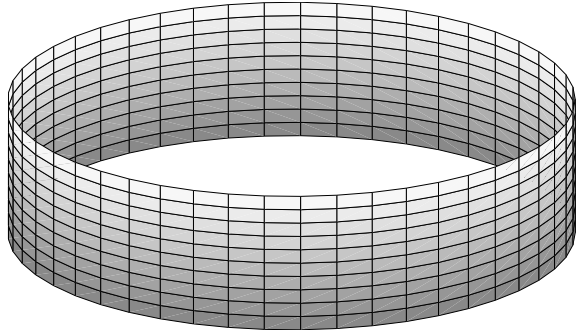
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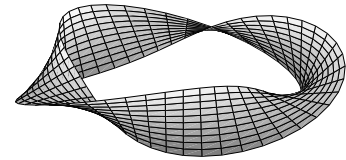
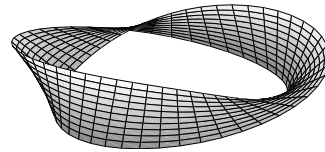
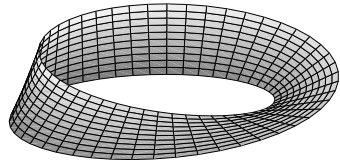
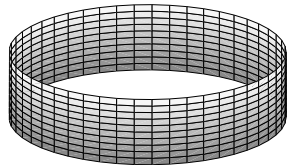


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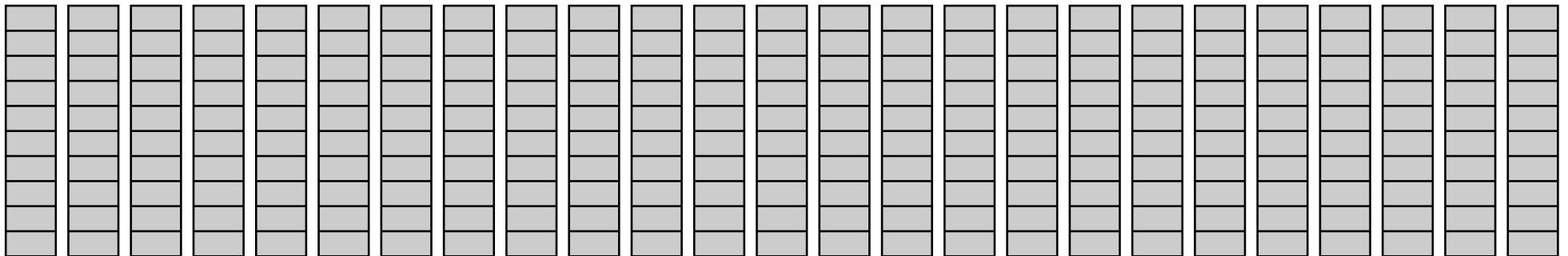
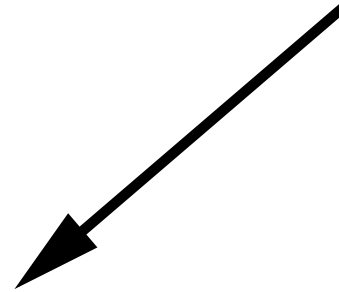
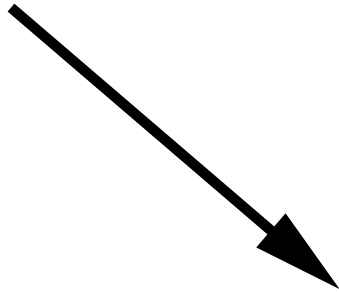
$$\frac{4+2}{2} = 3$$

2





...



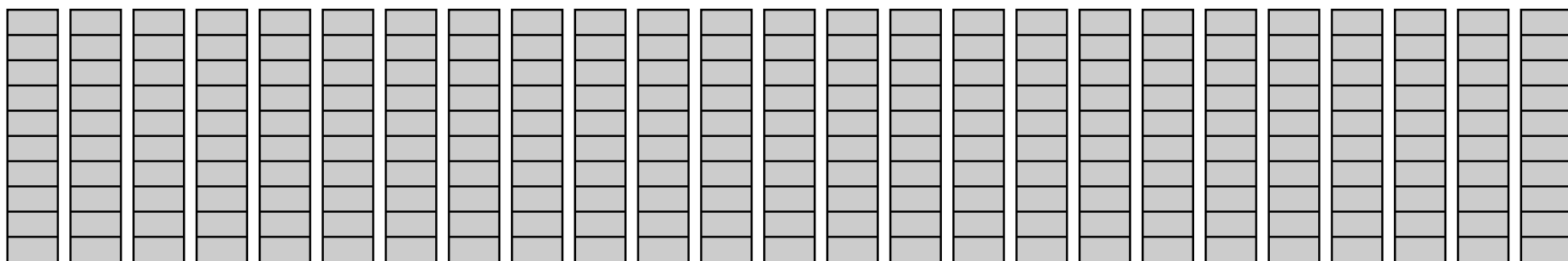
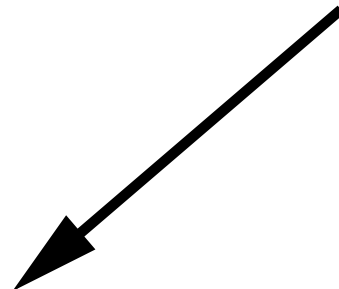
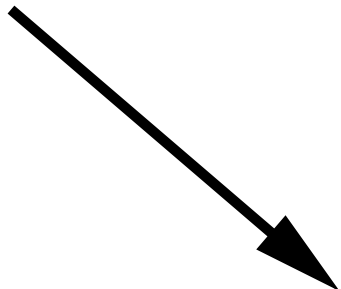
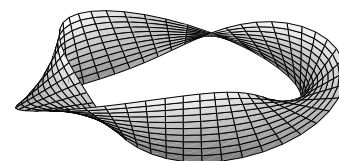
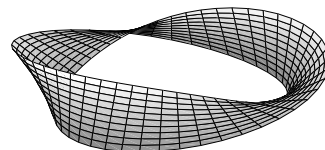
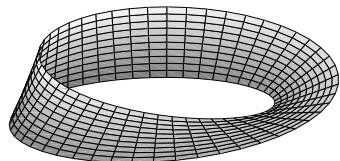
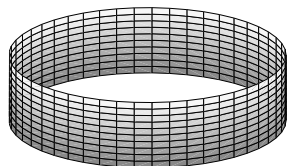
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2

...



The permanent of a matrix

Determinant vs. Permanent of a Matrix

Consider the matrix $\theta = \begin{pmatrix} \theta_{11} & \theta_{12} & \theta_{13} \\ \theta_{21} & \theta_{22} & \theta_{23} \\ \theta_{31} & \theta_{32} & \theta_{33} \end{pmatrix}$.

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The determinant of θ :

$$\det(\theta) = +\theta_{11}\theta_{22}\theta_{33} + \theta_{12}\theta_{23}\theta_{31} + \theta_{13}\theta_{21}\theta_{32} \\ - \theta_{11}\theta_{23}\theta_{32} - \theta_{12}\theta_{21}\theta_{33} - \theta_{13}\theta_{22}\theta_{31}.$$

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Determinant vs. Permanent of a Matrix

The determinant of an $n \times n$ -matrix θ

$$\det(\theta) = \sum_{\sigma} \text{sgn}(\sigma) \prod_{i \in [n]} \theta_{i, \sigma(i)}.$$

where the sum is over all $n!$ permutations of the set $[n] \triangleq \{1, \dots, n\}$.

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The permanent turns up in a variety of context, especially in combinatorial problems, statistical physics (partition function), ...

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- Complexity class [Valiant, 1979]:

$$\#P \quad (\text{"sharp P" or "number P"}),$$

where $\#P$ is the set of the counting problems associated with the decision problems in the set NP. (Note that even the computation of the permanent of zero-one matrices is $\#P$ -complete.)

Estimating the Permanent

More efficient algorithms are possible if one does not want to compute the permanent of a matrix exactly.

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 - “constructive and destructive interference of terms in the summation.”
- For a matrix that contains only non-negative entries:
 - “constructive interference of terms in the summation.”

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FROM NOW ON: we focus on the case where all entries of the matrix are non-negative, i.e.

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- Godsil-Gutman formula based methods: [Karmarkar et al., 1993], [Barvinok, 1997ff.], [Chien, Rasmussen, Sinclair, 2004], ...
- Fully polynomial-time randomized approximation schemes (FPRAS): [Jerrum, Sinclair, Vigoda, 2004], ...

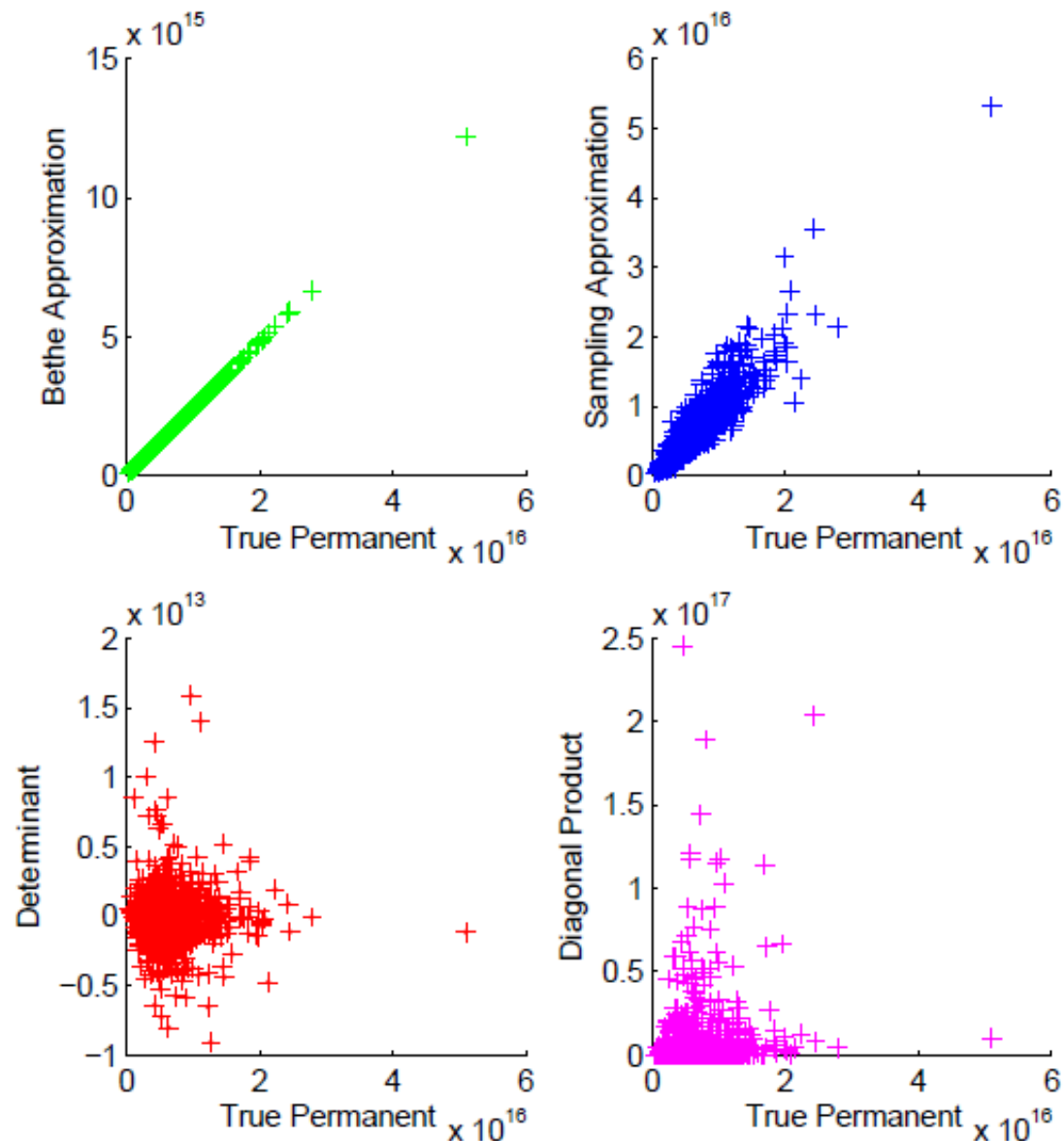
Estimating the Permanent

FROM NOW ON: we focus on the case where all entries of the matrix are non-negative, i.e.

$$\theta_{ij} \geq 0 \quad \forall i, j.$$

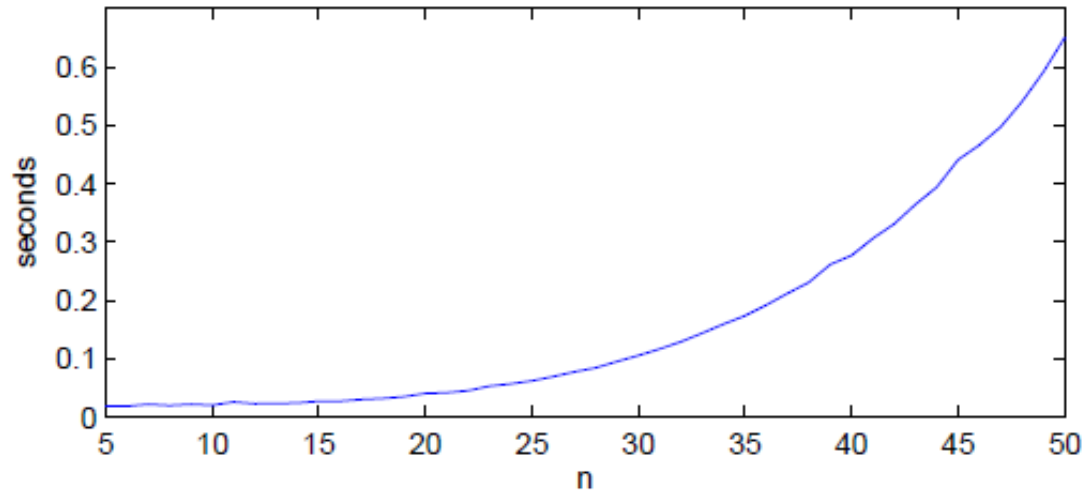
- Markov chain Monte Carlo based methods: [Broder, 1986], ...
- Godsil-Gutman formula based methods: [Karmarkar et al., 1993], [Barvinok, 1997ff.], [Chien, Rasmussen, Sinclair, 2004], ...
- Fully polynomial-time randomized approximation schemes (FPRAS): [Jerrum, Sinclair, Vigoda, 2004], ...
- Bethe-approximation-based / sum-product-algorithm-based methods: [Chertkov et al., 2008], [Huang and Jebara, 2009], ...

Estimating the Permanent of a Matrix

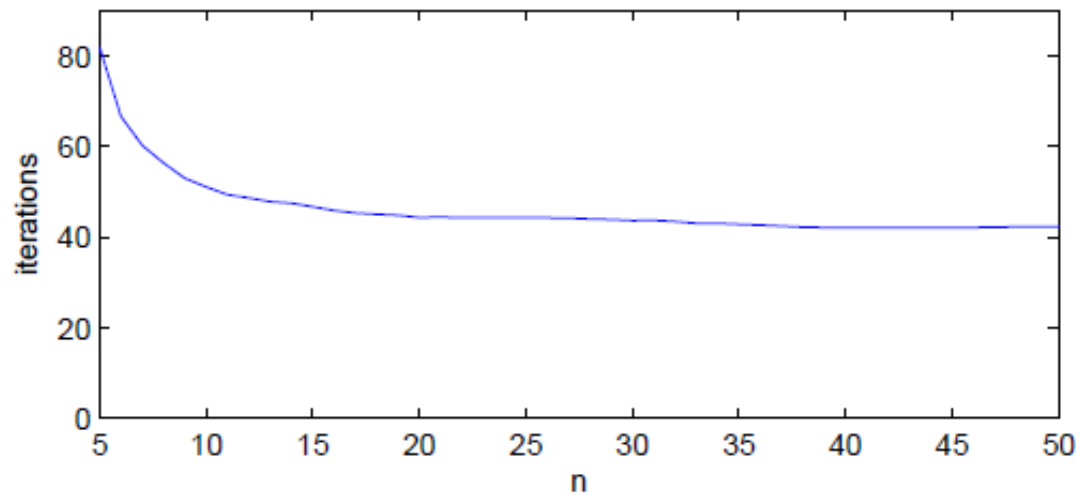


From [Huang/Jebara, 2009].

Estimating the Permanent of a Matrix



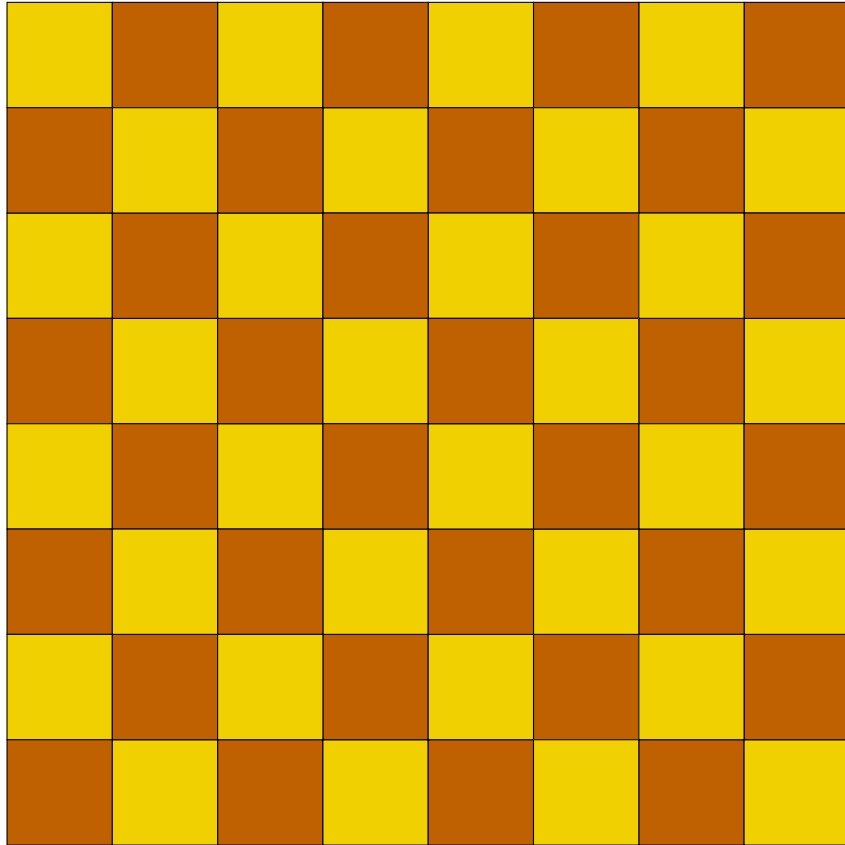
(a) Running time



(b) Iterations

From [Huang/Jebara, 2009].

Valid Rook Configurations and Permanents

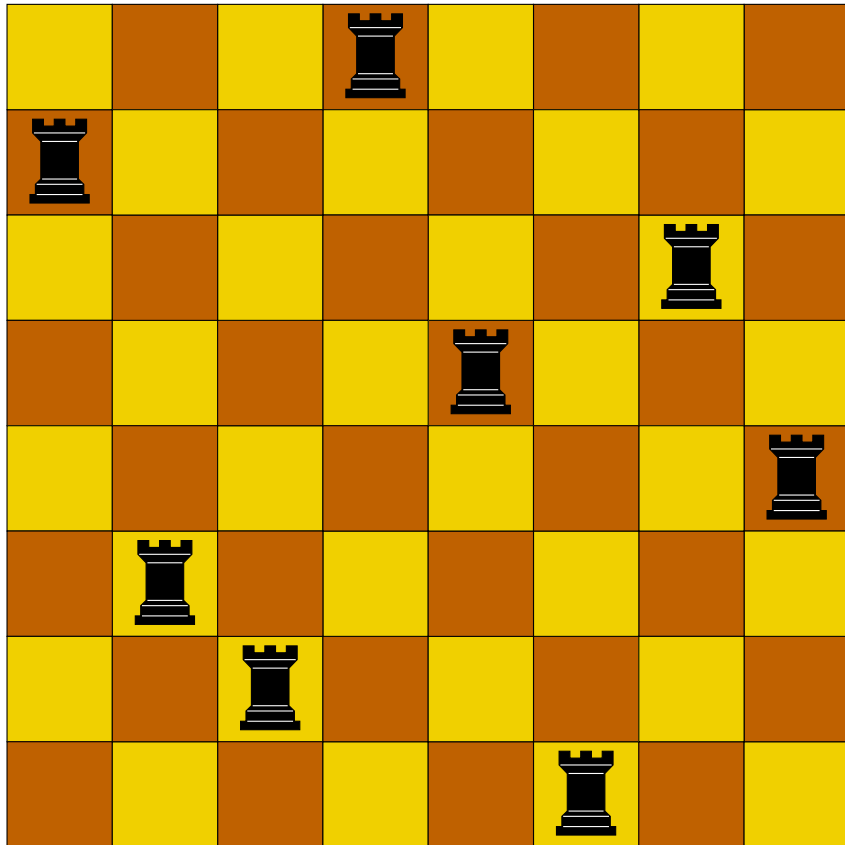


Number of valid rook configurations

$$= \text{perm} \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \end{pmatrix}$$

$$= \sum_{\sigma} \prod_{i \in [8]} \theta_{i, \sigma(i)}$$

Valid Rook Configurations and Permanents

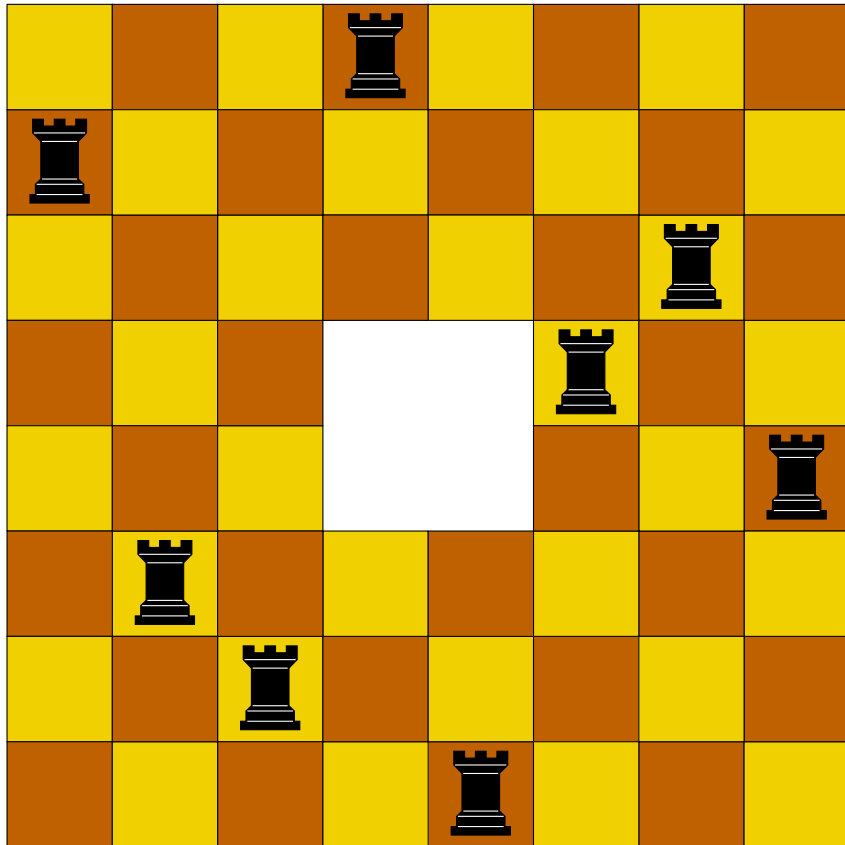


Number of valid rook configurations

$$= \text{perm} \begin{pmatrix} 1 & 1 & 1 & \mathbf{1} & 1 & 1 & 1 & 1 \\ \mathbf{1} & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & \mathbf{1} & 1 \\ 1 & 1 & 1 & 1 & \mathbf{1} & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & \mathbf{1} \\ 1 & \mathbf{1} & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & \mathbf{1} & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & \mathbf{1} & 1 & 1 \end{pmatrix}$$

$$= \sum_{\sigma} \prod_{i \in [8]} \theta_{i, \sigma(i)}$$

Valid Rook Configurations and Permanents

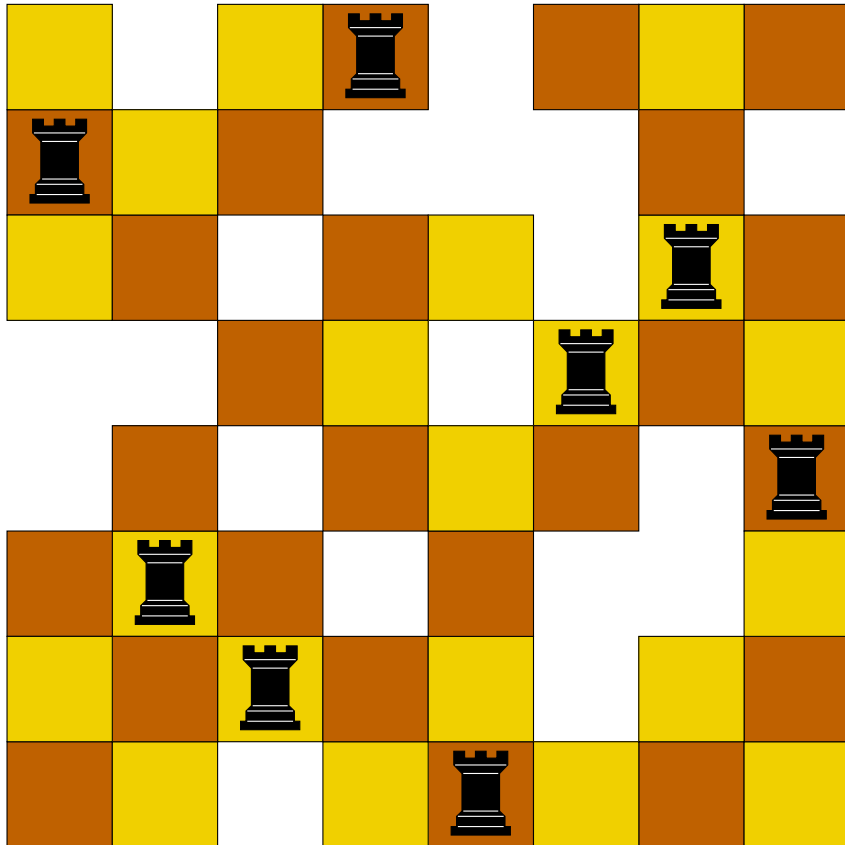


Number of valid rook configurations

$$= \text{perm} \begin{pmatrix} 1 & 1 & 1 & \mathbf{1} & 1 & 1 & 1 & 1 \\ \mathbf{1} & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & \mathbf{1} & 1 \\ 1 & 1 & 1 & 0 & 0 & \mathbf{1} & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 & 1 & 1 & \mathbf{1} \\ 1 & \mathbf{1} & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & \mathbf{1} & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & \mathbf{1} & 1 & 1 & 1 \end{pmatrix}$$

$$= \sum_{\sigma} \prod_{i \in [8]} \theta_{i, \sigma(i)}$$

Valid Rook Configurations and Permanents



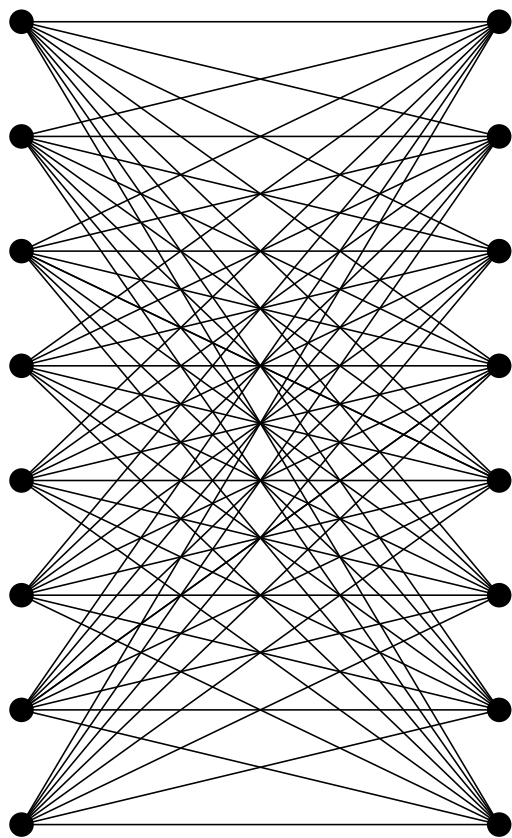
Number of valid rook configurations

$$= \text{perm} \begin{pmatrix} 1 & 0 & 1 & \mathbf{1} & 0 & 1 & 1 & 1 \\ \mathbf{1} & 1 & 1 & 0 & 0 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 & 1 & 0 & \mathbf{1} & 1 \\ 0 & 0 & 1 & 1 & 0 & \mathbf{1} & 0 & 1 \\ 0 & 1 & 0 & 1 & 1 & 1 & 0 & \mathbf{1} \\ 1 & \mathbf{1} & 1 & 0 & 1 & 0 & 0 & 1 \\ 1 & 1 & \mathbf{1} & 1 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & \mathbf{1} & 1 & 1 & 1 \end{pmatrix}$$

$$= \sum_{\sigma} \prod_{i \in [8]} \theta_{i, \sigma(i)}$$

Perfect Matchings and Permanents

Number of valid perfect matchings

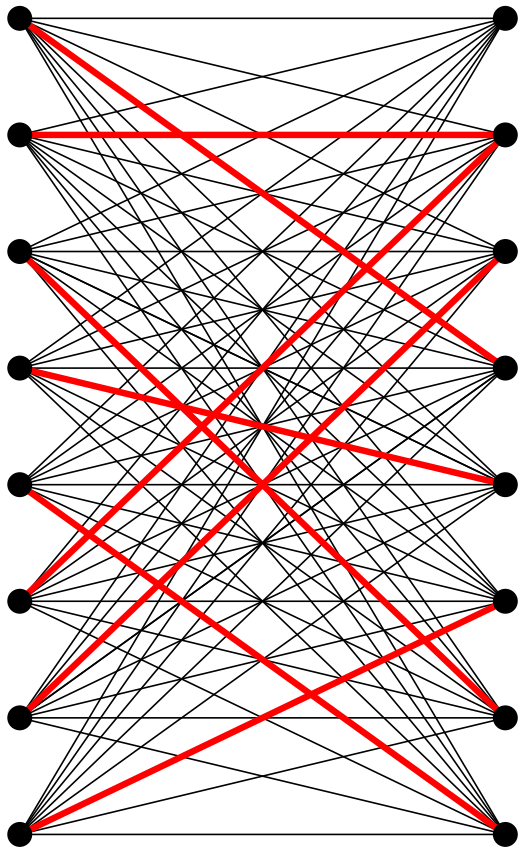


$$= \text{perm} \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \end{pmatrix}$$

$$= \sum_{\sigma} \prod_{i \in [8]} \theta_{i, \sigma(i)}$$

Perfect Matchings and Permanents

Number of valid perfect matchings

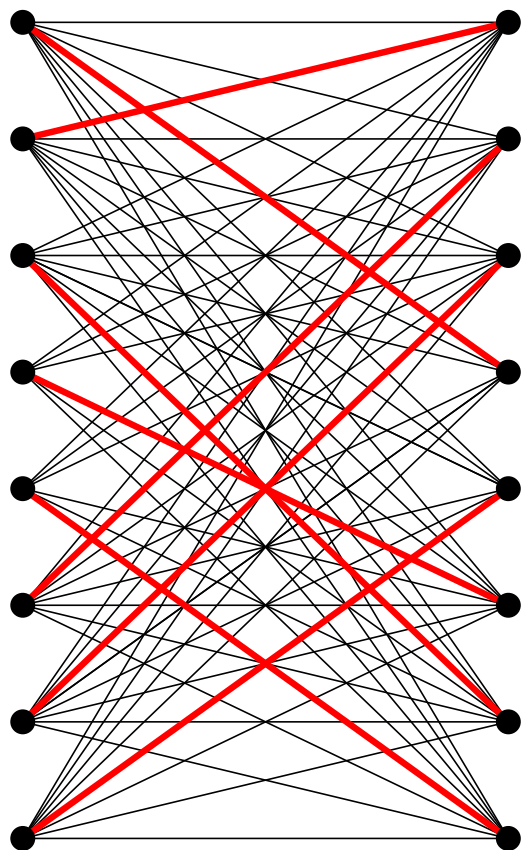


$$= \text{perm} \begin{pmatrix} 1 & 1 & 1 & \mathbf{1} & 1 & 1 & 1 & 1 \\ \mathbf{1} & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & \mathbf{1} & 1 \\ 1 & 1 & 1 & 1 & \mathbf{1} & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & \mathbf{1} \\ 1 & \mathbf{1} & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & \mathbf{1} & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & \mathbf{1} & 1 & 1 \end{pmatrix}$$

$$= \sum_{\sigma} \prod_{i \in [8]} \theta_{i, \sigma(i)}$$

Perfect Matchings and Permanents

Number of valid perfect matchings

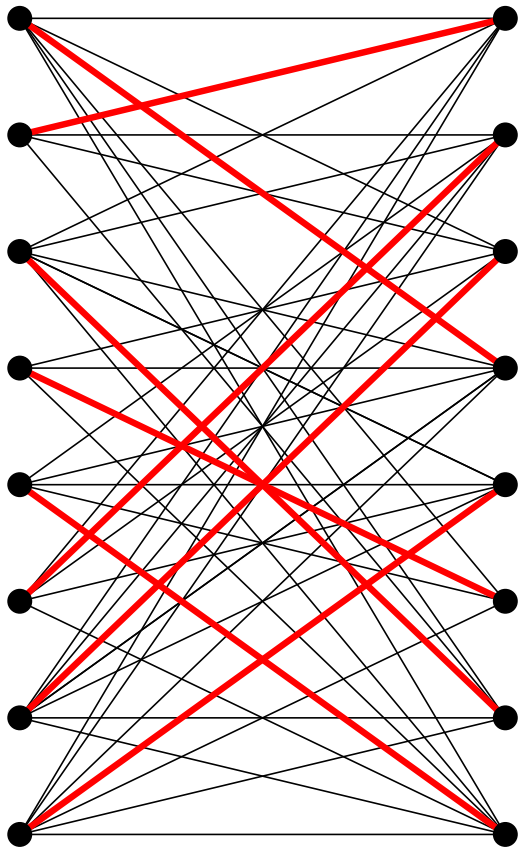


$$= \text{perm} \begin{pmatrix} 1 & 1 & 1 & \mathbf{1} & 1 & 1 & 1 & 1 \\ \mathbf{1} & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & \mathbf{1} & 1 \\ 1 & 1 & 1 & 0 & 0 & \mathbf{1} & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 & 1 & 1 & \mathbf{1} \\ 1 & \mathbf{1} & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & \mathbf{1} & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & \mathbf{1} & 1 & 1 & 1 \end{pmatrix}$$

$$= \sum_{\sigma} \prod_{i \in [8]} \theta_{i, \sigma(i)}$$

Perfect Matchings and Permanents

Number of valid perfect matchings

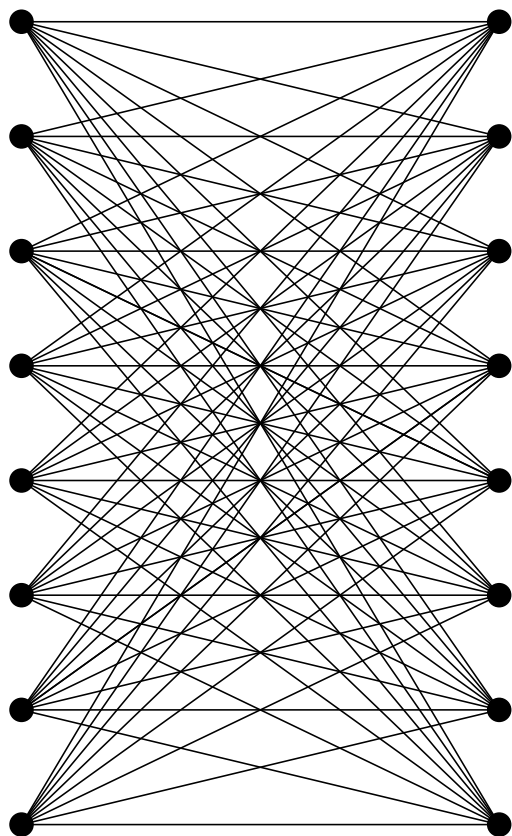


$$= \text{perm} \begin{pmatrix} 1 & 0 & 1 & \mathbf{1} & 0 & 1 & 1 & 1 \\ \mathbf{1} & 1 & 1 & 0 & 0 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 & 1 & 0 & \mathbf{1} & 1 \\ 0 & 0 & 1 & 1 & 0 & \mathbf{1} & 0 & 1 \\ 0 & 1 & 0 & 1 & 1 & 1 & 0 & \mathbf{1} \\ 1 & \mathbf{1} & 1 & 0 & 1 & 0 & 0 & 1 \\ 1 & 1 & \mathbf{1} & 1 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & \mathbf{1} & 1 & 1 & 1 \end{pmatrix}$$

$$= \sum_{\sigma} \prod_{i \in [8]} \theta_{i, \sigma(i)}$$

Perfect Matchings and Permanents

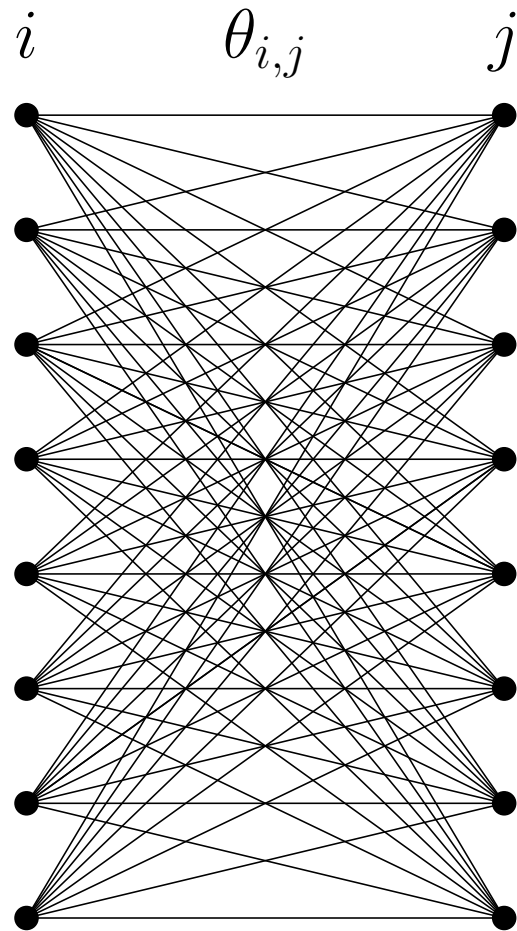
Number of valid perfect matchings



$$= \text{perm} \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \end{pmatrix}$$

$$= \sum_{\sigma} \prod_{i \in [8]} \theta_{i, \sigma(i)}$$

Perfect Matchings and Permanents

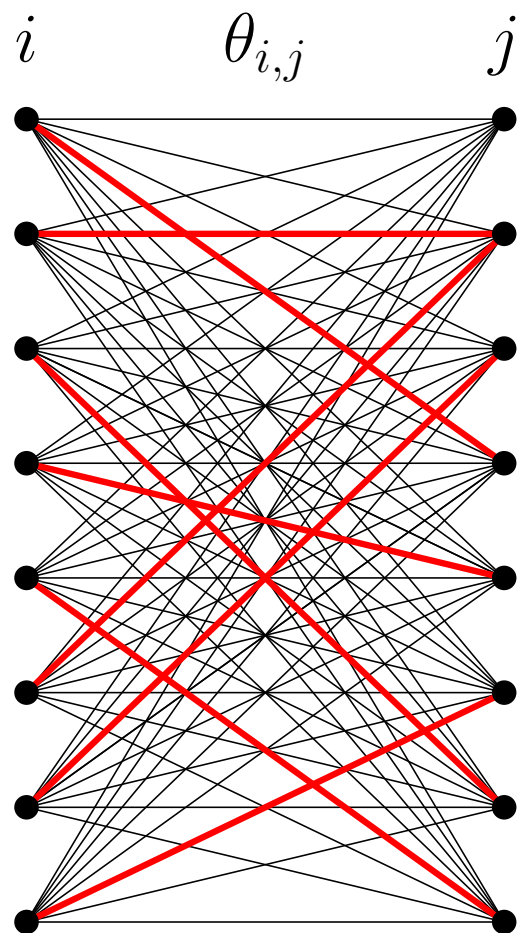


Total sum of weighted perf. matchings

$$= \text{perm} \begin{pmatrix} \theta_{11} & \theta_{12} & \theta_{13} & \theta_{14} & \theta_{15} & \theta_{16} & \theta_{17} & \theta_{18} \\ \theta_{21} & \theta_{22} & \theta_{23} & \theta_{24} & \theta_{25} & \theta_{26} & \theta_{27} & \theta_{28} \\ \theta_{31} & \theta_{32} & \theta_{33} & \theta_{34} & \theta_{35} & \theta_{36} & \theta_{37} & \theta_{38} \\ \theta_{41} & \theta_{42} & \theta_{43} & \theta_{44} & \theta_{45} & \theta_{46} & \theta_{47} & \theta_{48} \\ \theta_{51} & \theta_{52} & \theta_{53} & \theta_{54} & \theta_{55} & \theta_{56} & \theta_{57} & \theta_{58} \\ \theta_{61} & \theta_{62} & \theta_{63} & \theta_{64} & \theta_{65} & \theta_{66} & \theta_{67} & \theta_{68} \\ \theta_{71} & \theta_{72} & \theta_{73} & \theta_{74} & \theta_{75} & \theta_{76} & \theta_{77} & \theta_{78} \\ \theta_{81} & \theta_{82} & \theta_{83} & \theta_{84} & \theta_{85} & \theta_{86} & \theta_{87} & \theta_{88} \end{pmatrix}$$

$$= \sum_{\sigma} \prod_{i \in [8]} \theta_{i, \sigma(i)}$$

Perfect Matchings and Permanents

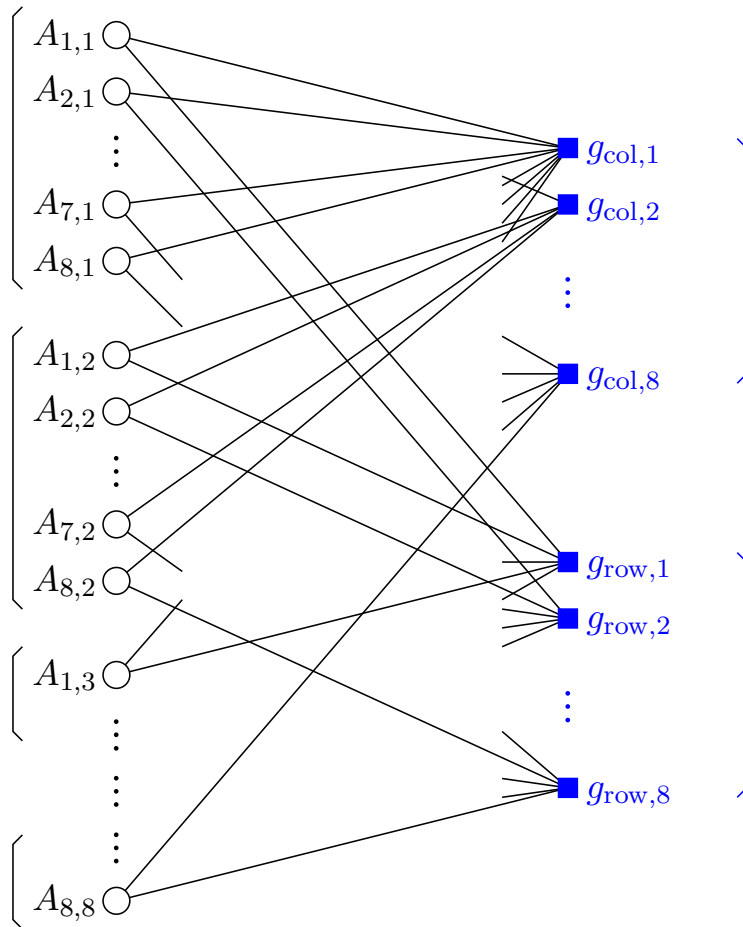


Total sum of weighted perf. matchings

$$= \text{perm} \begin{pmatrix} \theta_{11} & \theta_{12} & \theta_{13} & \theta_{14} & \theta_{15} & \theta_{16} & \theta_{17} & \theta_{18} \\ \theta_{21} & \theta_{22} & \theta_{23} & \theta_{24} & \theta_{25} & \theta_{26} & \theta_{27} & \theta_{28} \\ \theta_{31} & \theta_{32} & \theta_{33} & \theta_{34} & \theta_{35} & \theta_{36} & \theta_{37} & \theta_{38} \\ \theta_{41} & \theta_{42} & \theta_{43} & \theta_{44} & \theta_{45} & \theta_{46} & \theta_{47} & \theta_{48} \\ \theta_{51} & \theta_{52} & \theta_{53} & \theta_{54} & \theta_{55} & \theta_{56} & \theta_{57} & \theta_{58} \\ \theta_{61} & \theta_{62} & \theta_{63} & \theta_{64} & \theta_{65} & \theta_{66} & \theta_{67} & \theta_{68} \\ \theta_{71} & \theta_{72} & \theta_{73} & \theta_{74} & \theta_{75} & \theta_{76} & \theta_{77} & \theta_{78} \\ \theta_{81} & \theta_{82} & \theta_{83} & \theta_{84} & \theta_{85} & \theta_{86} & \theta_{87} & \theta_{88} \end{pmatrix}$$

$$= \sum_{\sigma} \prod_{i \in [8]} \theta_{i, \sigma(i)}$$

Graphical Model for Permanent



Global function:

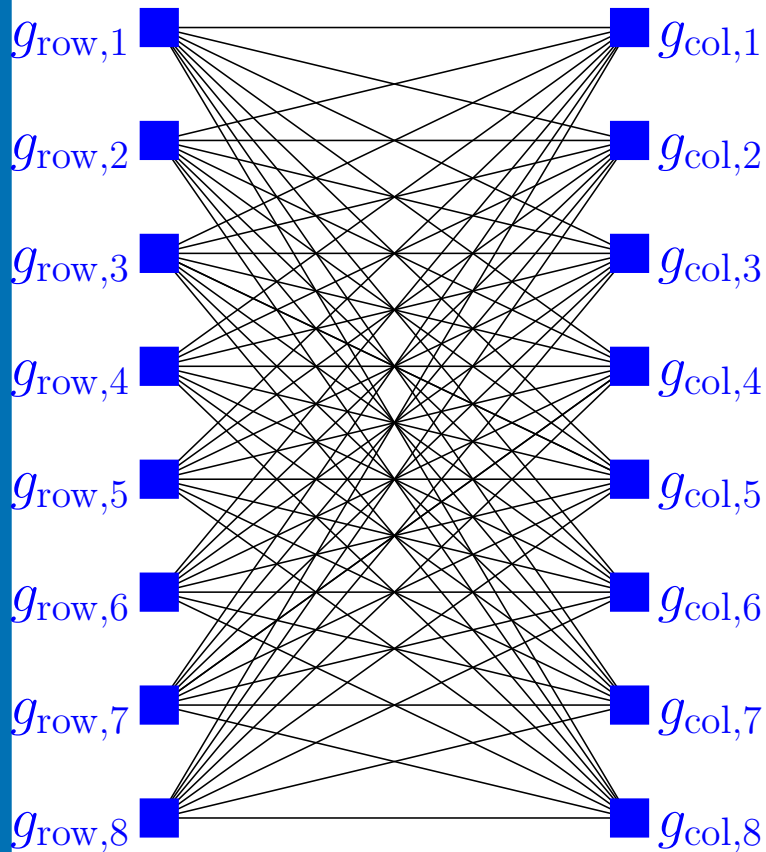
$$\begin{aligned}
 &g(a_{1,1}, \dots, a_{8,8}) \\
 &= \prod_j g_{col,j}(a_{1,j}, \dots, a_{8,j}) \times \\
 &\quad \prod_i g_{row,i}(a_{i,1}, \dots, a_{i,8})
 \end{aligned}$$

Permanent:

$$\text{perm}(\boldsymbol{\theta}) = Z = \sum_{a_{1,1}, \dots, a_{8,8}} g(a_{1,1}, \dots, a_{8,8})$$

(function nodes are suitably defined based on $\boldsymbol{\theta}$)

Graphical Model for Permanent



Global function:

$$\begin{aligned} g(a_{1,1}, \dots, a_{8,8}) \\ &= \prod_j g_{col,j}(a_{1,j}, \dots, a_{8,j}) \times \\ &\quad \prod_i g_{row,i}(a_{i,1}, \dots, a_{i,8}) \end{aligned}$$

Permanent:

$$\text{perm}(\boldsymbol{\theta}) = Z = \sum_{a_{1,1}, \dots, a_{8,8}} g(a_{1,1}, \dots, a_{8,8})$$

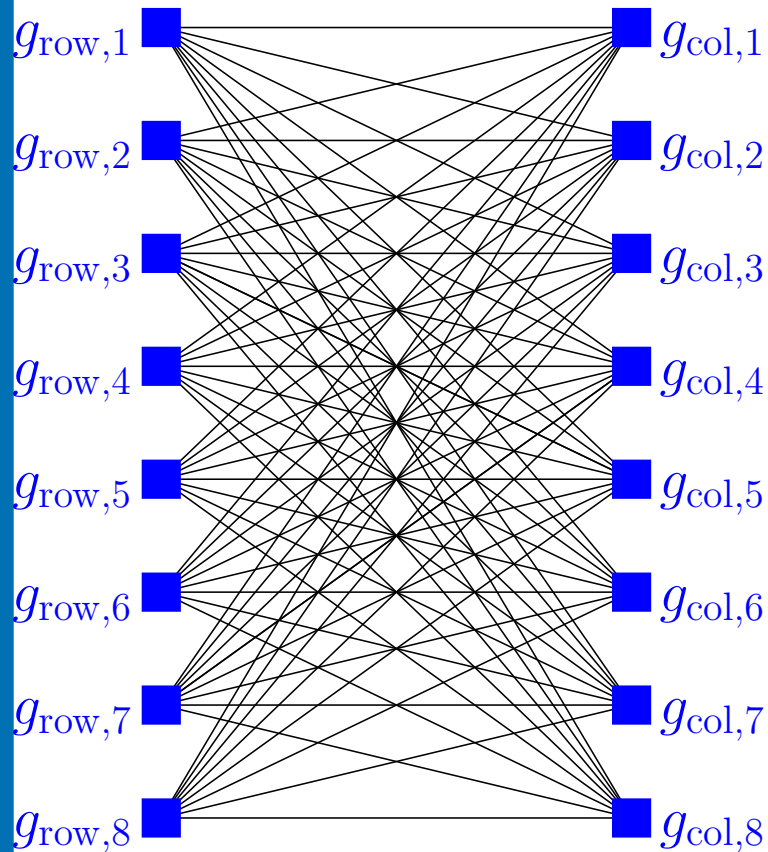
(function nodes are suitably defined based on $\boldsymbol{\theta}$)

(variable nodes have been omitted)

Graphical Model for Permanent

⚡ Many **short** cycles.

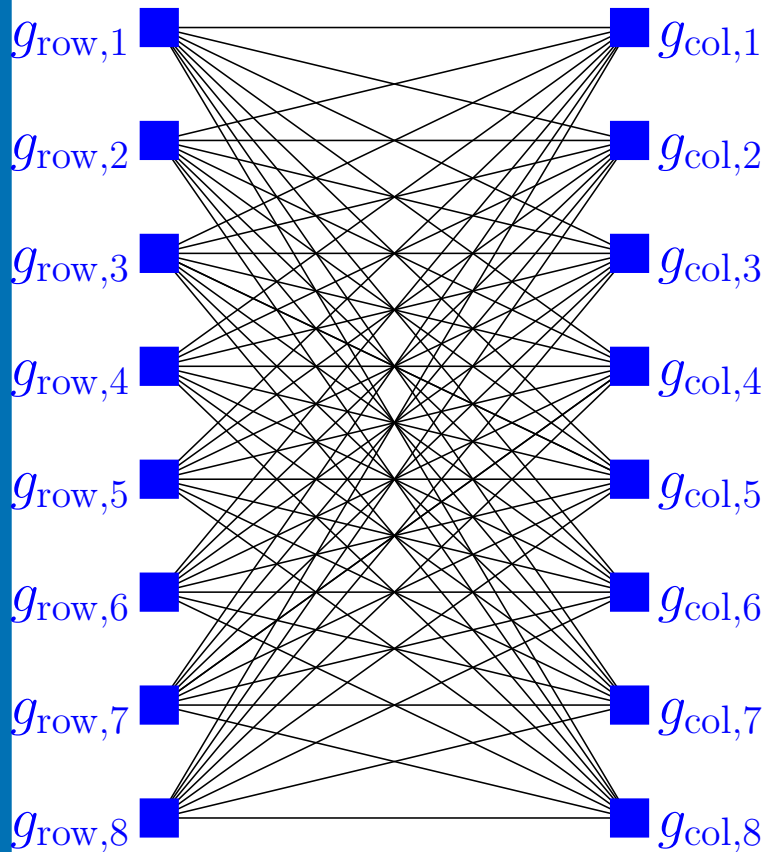
⚡ The vertex degrees are **high**.



(function nodes are suitably defined based on θ)

(variable nodes have been omitted)

Graphical Model for Permanent



⚡ Many **short** cycles.

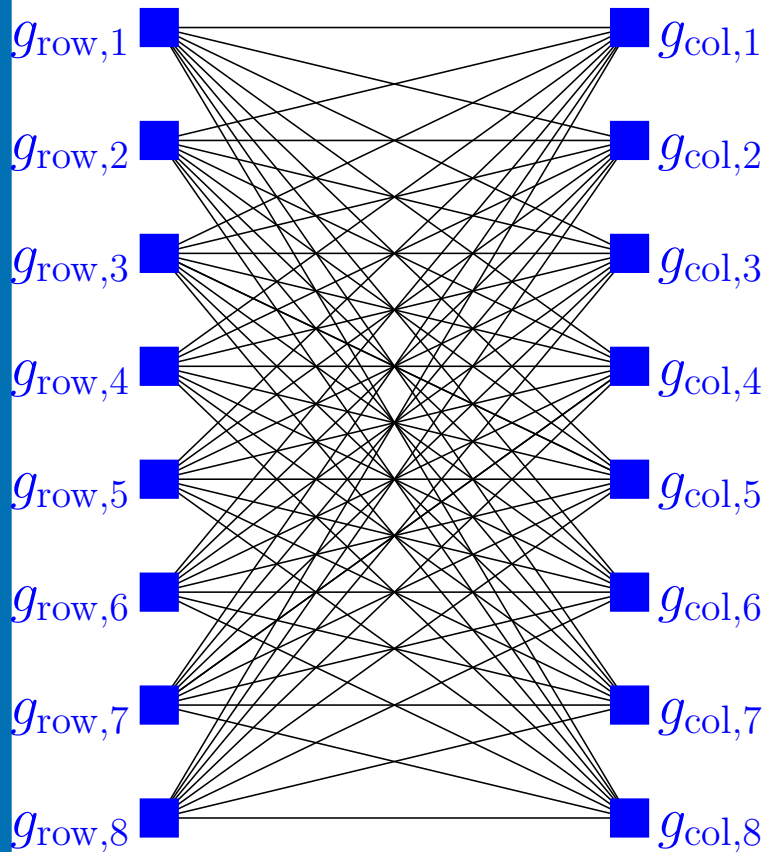
⚡ The vertex degrees are **high**.

Both facts might suggest that the application of the sum-product algorithm to this factor graph is rather problematic.

(function nodes are suitably defined based on θ)

(variable nodes have been omitted)

Graphical Model for Permanent



⚡ Many **short** cycles.

⚡ The vertex degrees are **high**.

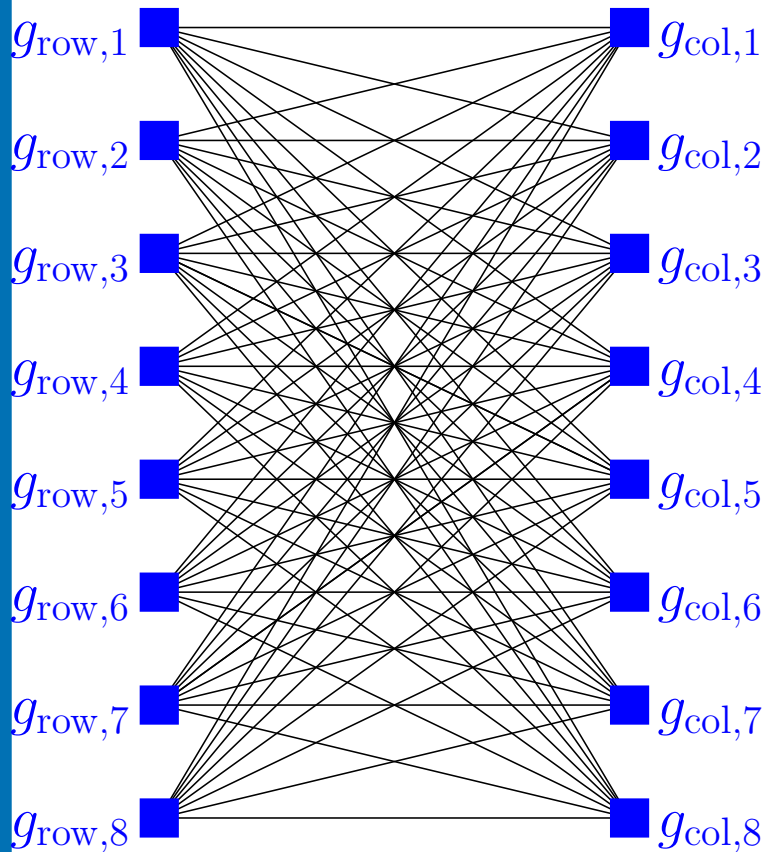
Both facts might suggest that the application of the sum-product algorithm to this factor graph is rather problematic.

However, luckily this is not the case.

(function nodes are suitably defined based on θ)

(variable nodes have been omitted)

Graphical Model for Permanent



(function nodes are suitably defined based on θ)

(variable nodes have been omitted)

⚡ Many **short** cycles.

⚡ The vertex degrees are **high**.

Both facts might suggest that the application of the sum-product algorithm to this factor graph is rather problematic.

However, luckily this is not the case.

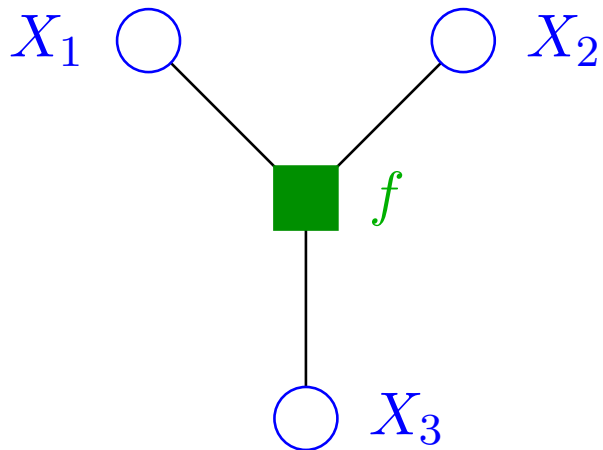
For an SPA suitability assessment, the **overall cycle structure** and the **types of functions nodes** are at least as important.

Factor graphs and the sum-product algorithm

Factor Graphs

A factor graph can be used to represent a multivariate function:

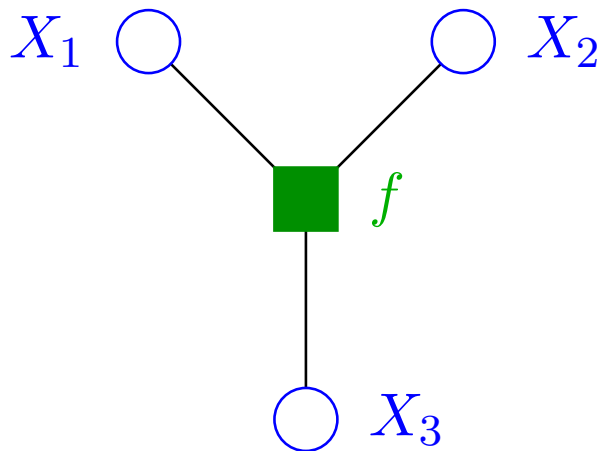
$$f(x_1, x_2, x_3)$$



Factor Graphs

A factor graph can be used to represent a multivariate function:

$$f(x_1, x_2, x_3)$$

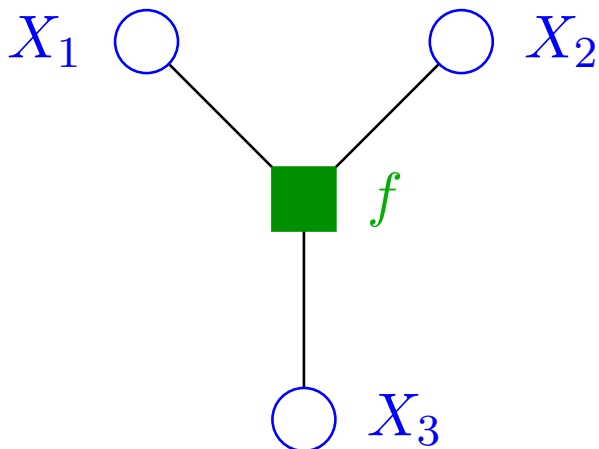


- **Variable nodes:** for each variable we draw a variable node (empty circles).

Factor Graphs

A factor graph can be used to represent a multivariate function:

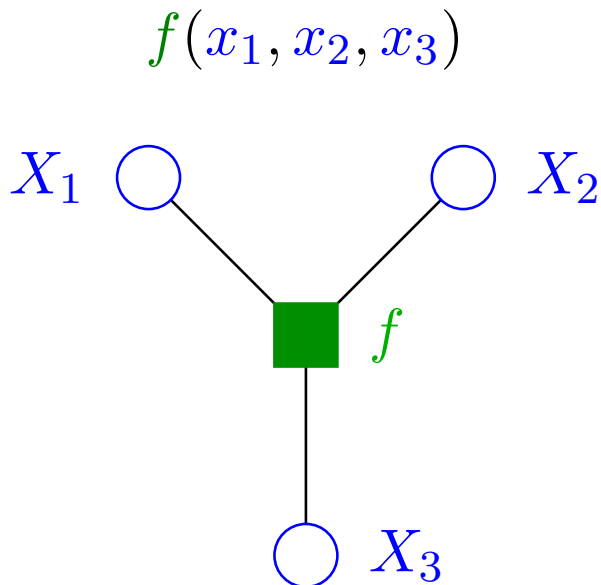
$$f(x_1, x_2, x_3)$$



- **Variable nodes:** for each variable we draw a variable node (empty circles).
- **Function nodes:** for each function we draw a function node (filled squares).

Factor Graphs

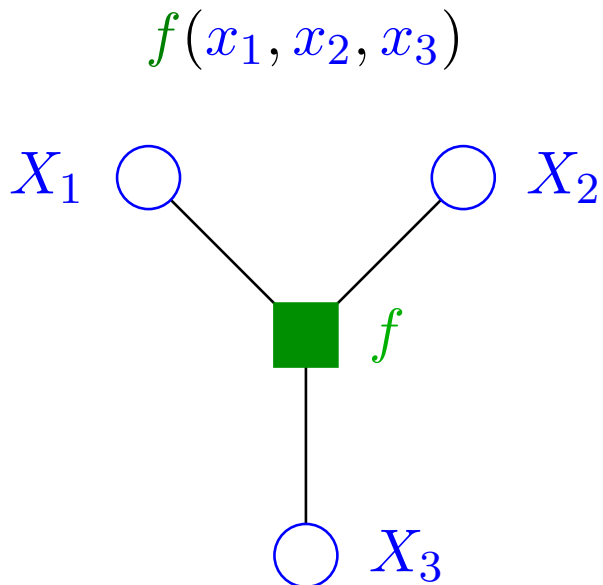
A factor graph can be used to represent a multivariate function:



- **Variable nodes:** for each variable we draw a variable node (empty circles).
- **Function nodes:** for each function we draw a function node (filled squares).
- **Edges:** there is an edge between a variable node and a function node if the corresponding variable is an argument of the corresponding function.

Factor Graphs

A factor graph can be used to represent a multivariate function:



- **Variable nodes:** for each variable we draw a variable node (empty circles).
- **Function nodes:** for each function we draw a function node (filled squares).
- **Edges:** there is an edge between a variable node and a function node if the corresponding variable is an argument of the corresponding function.
- **Bipartite graph:** the resulting graph is a bipartite graph, i.e. there are only edges between vertices of different types.

Factor Graphs

General references for factor graphs are:

- F. R. Kschischang, B. J. Frey and H.-A. Loeliger, “Factor graphs and the sum-product algorithm,” IEEE Trans. on Inform. Theory, IT-47, Feb. 2001.
- H.-A. Loeliger, “An introduction to factor graphs,” IEEE Signal Processing Magazine, Jan. 2004.

Factor Graphs

We assume that we know more about the **internal structure** of the function $f(x_1, x_2, x_3)$, e.g.

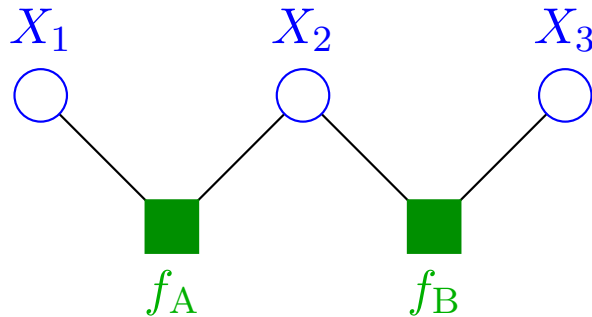
$$f(x_1, x_2, x_3) = f_A(x_1, x_2) \cdot f_B(x_2, x_3).$$

Factor Graphs

We assume that we know more about the **internal structure** of the function $f(x_1, x_2, x_3)$, e.g.

$$f(x_1, x_2, x_3) = f_A(x_1, x_2) \cdot f_B(x_2, x_3).$$

Then we can take advantage of this fact and the factor graph represents this structure.

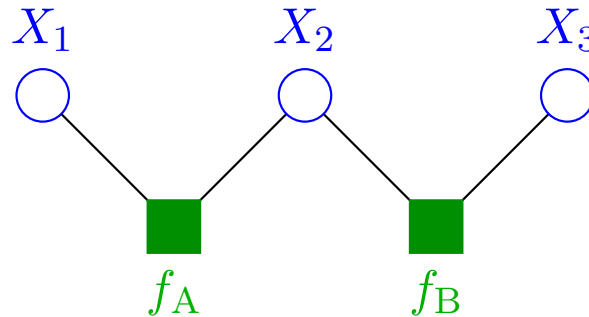


Factor Graphs

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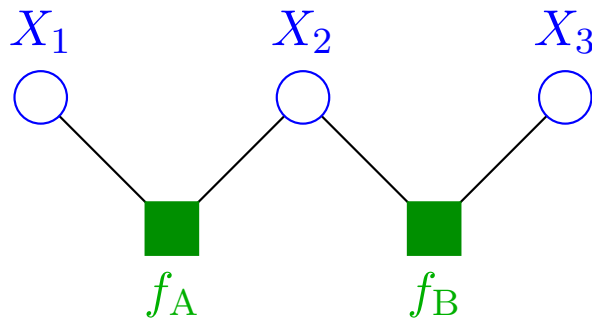
- $f(., ., .)$ is called the **global** function.

Factor Graphs

We assume that we know more about the **internal structure** of the function $f(x_1, x_2, x_3)$, e.g.

$$f(x_1, x_2, x_3) = f_A(x_1, x_2) \cdot f_B(x_2, x_3).$$

Then we can take advantage of this fact and the factor graph represents this structure.



- $f(., ., .)$ is called the **global** function.
- $f_A(., .)$ and $f_B(., .)$ are called **local** functions.

Factor Graphs

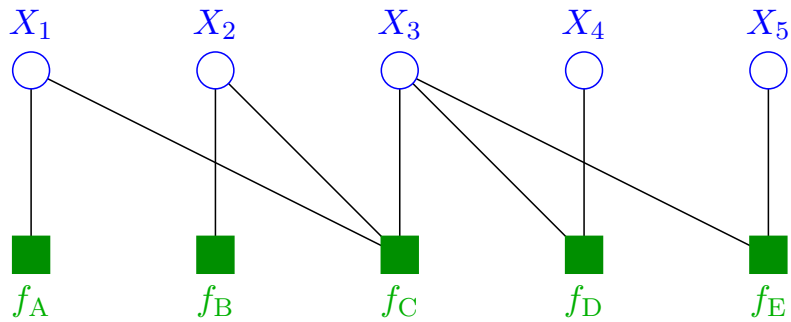
$$f(x_1, x_2, x_3, x_4, x_5)$$

$$= f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5)$$

Factor Graphs

$$f(x_1, x_2, x_3, x_4, x_5)$$

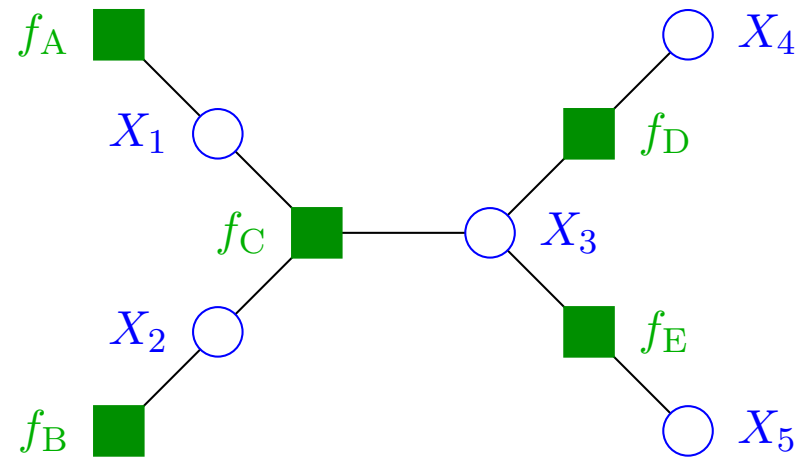
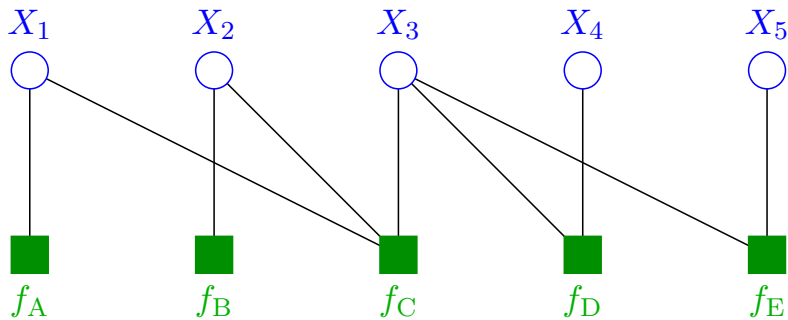
$$= f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5)$$



Factor Graphs

$$f(x_1, x_2, x_3, x_4, x_5)$$

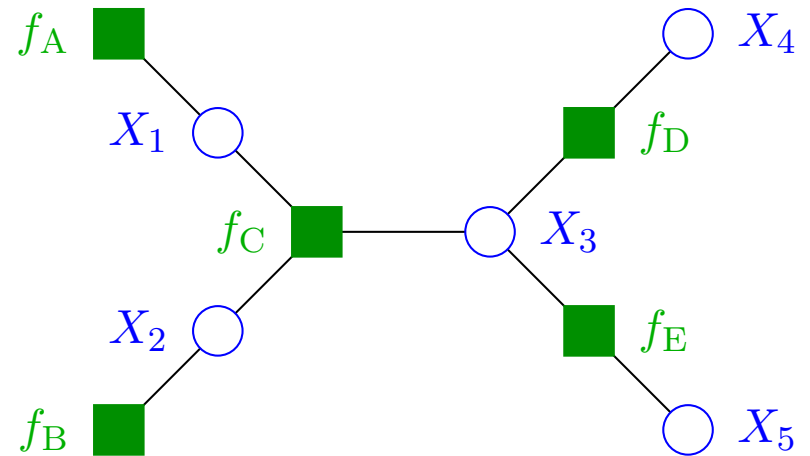
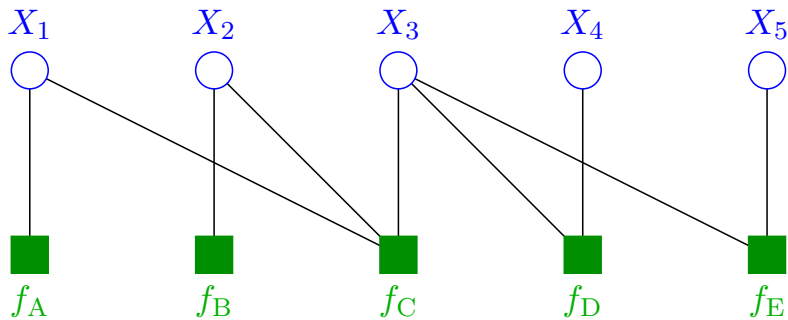
$$= f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5)$$



Factor Graphs

$$f(x_1, x_2, x_3, x_4, x_5)$$

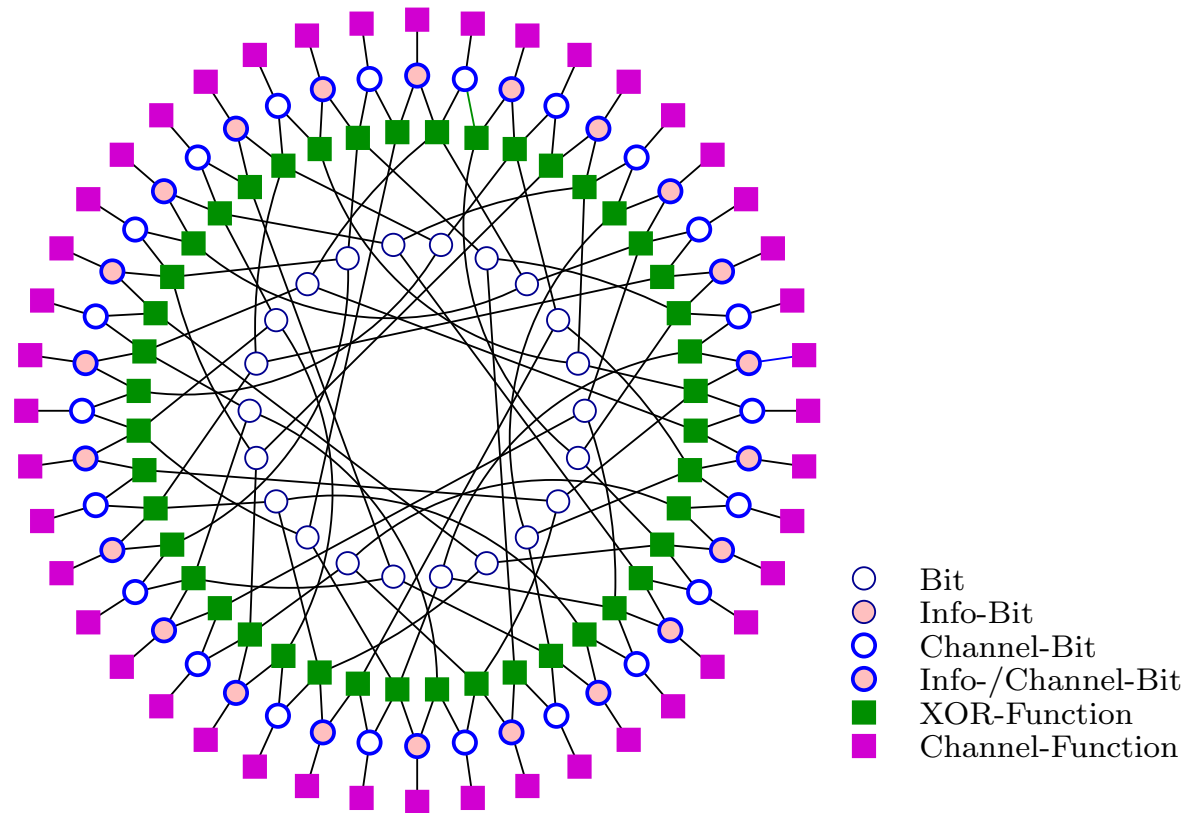
$$= f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5)$$



Note: One and the same function can be represented by graphs with different structures: some are more pleasing than others.

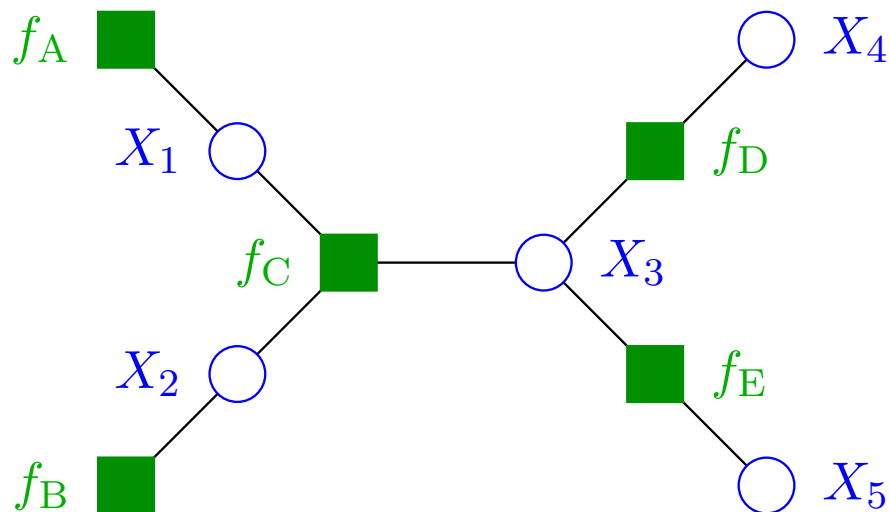
Factor Graph of an LDPC Code

In the context of **channel coding**, we usually take a factor graph to represent the factorization of the **joint pmf/pdf of all occurring variables**, i.e. uncoded symbols, coded symbols, and received symbols. Here it is shown when using a quasi-cyclic repeat-accumulate LDPC code (binary $[44, 22, 8]$ linear code).



The Sum-Product Algorithm

Let us consider again the following factor graph (which is a tree).



The **global function** is

$$\begin{aligned} f(x_1, x_2, x_3, x_4, x_5) \\ = f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5). \end{aligned}$$

The Sum-Product Algorithm

The **global function** is

$$f(x_1, x_2, x_3, x_4, x_5) = f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5).$$

The Sum-Product Algorithm

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$$f(x_1, x_2, x_3, x_4, x_5) = f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5).$$

Very often one wants to calculate **marginal functions**. E.g.

$$\begin{aligned}\eta_{X_1}(x_1) &= \sum_{x_2, x_3, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5) \\ &= \sum_{x_2, x_3, x_4, x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5).\end{aligned}$$

The Sum-Product Algorithm

The **global function** is

$$f(x_1, x_2, x_3, x_4, x_5) = f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5).$$

Very often one wants to calculate **marginal functions**. E.g.

$$\begin{aligned}\eta_{X_1}(x_1) &= \sum_{x_2, x_3, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5) \\ &= \sum_{x_2, x_3, x_4, x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5).\end{aligned}$$

$$\begin{aligned}\eta_{X_3}(x_3) &= \sum_{x_1, x_2, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5) \\ &= \sum_{x_1, x_2, x_4, x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5).\end{aligned}$$

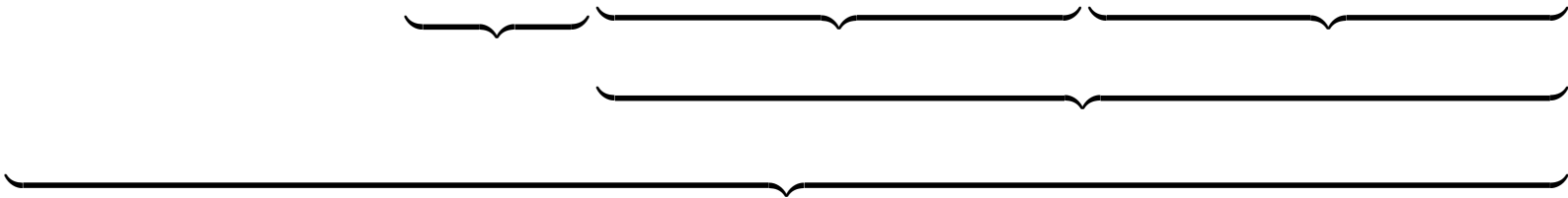
etc.

The Sum-Product Algorithm

$$\eta_{X_1}(x_1) = \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5)$$

The Sum-Product Algorithm

$$\eta_{X_1}(x_1) = \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5)$$

$$= \underbrace{f_A(x_1)} \underbrace{\sum_{x_2} \sum_{x_3} f_C(x_1, x_2, x_3)} \underbrace{f_B(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)} \cdot \underbrace{1} \underbrace{\sum_{x_5} f_E(x_3, x_5)} \cdot \underbrace{1}$$


The Sum-Product Algorithm

$$\begin{aligned}\eta_{X_1}(x_1) &= \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5) \\ &= \underbrace{f_A(x_1)} \underbrace{\sum_{x_2} \sum_{x_3} f_C(x_1, x_2, x_3)} \underbrace{f_B(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)} \cdot \underbrace{1} \underbrace{\sum_{x_5} f_E(x_3, x_5)} \cdot \underbrace{1}_{\mu_{X_5 \rightarrow f_E}(x_5)}\end{aligned}$$

The Sum-Product Algorithm

$$\begin{aligned}
 \eta_{X_1}(x_1) &= \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5) \\
 &= \underbrace{f_A(x_1)} \underbrace{\sum_{x_2} \sum_{x_3} f_C(x_1, x_2, x_3)} \underbrace{f_B(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)} \cdot \underbrace{1}_{\mu_{X_4 \rightarrow f_D}(x_4)} \underbrace{\sum_{x_5} f_E(x_3, x_5)} \cdot \underbrace{1}_{\mu_{X_5 \rightarrow f_E}(x_5)} \\
 &\quad \underbrace{\hspace{15em}}_{\mu_{f_E \rightarrow X_3}(x_3)} \\
 &\quad \underbrace{\hspace{25em}}
 \end{aligned}$$

The Sum-Product Algorithm

$$\begin{aligned}
 \eta_{X_1}(x_1) &= \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5) \\
 &= \underbrace{f_A(x_1)} \underbrace{\sum_{x_2} \sum_{x_3} f_C(x_1, x_2, x_3)} \underbrace{f_B(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)} \cdot \underbrace{1}_{\mu_{X_4 \rightarrow f_D}(x_4)} \underbrace{\sum_{x_5} f_E(x_3, x_5)} \cdot \underbrace{1}_{\mu_{X_5 \rightarrow f_E}(x_5)} \\
 &\quad \underbrace{\hspace{10em}}_{\mu_{f_D \rightarrow X_3}(x_3)} \underbrace{\hspace{10em}}_{\mu_{f_E \rightarrow X_3}(x_3)} \\
 &\quad \underbrace{\hspace{20em}}
 \end{aligned}$$

The Sum-Product Algorithm

$$\begin{aligned}
 \eta_{X_1}(x_1) &= \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5) \\
 &= \underbrace{f_A(x_1)} \underbrace{\sum_{x_2} \sum_{x_3} f_C(x_1, x_2, x_3)} \underbrace{f_B(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)} \cdot \underbrace{1}_{\mu_{X_4 \rightarrow f_D}(x_4)} \underbrace{\sum_{x_5} f_E(x_3, x_5)} \cdot \underbrace{1}_{\mu_{X_5 \rightarrow f_E}(x_5)} \\
 &\quad \underbrace{\hspace{10em}}_{\mu_{f_D \rightarrow X_3}(x_3)} \underbrace{\hspace{10em}}_{\mu_{f_E \rightarrow X_3}(x_3)} \\
 &\quad \underbrace{\hspace{15em}}_{\mu_{f_{X_3 \rightarrow f_C}}(x_3)}
 \end{aligned}$$

The Sum-Product Algorithm

$$\begin{aligned}
 \eta_{X_1}(x_1) &= \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5) \\
 &= \underbrace{f_A(x_1)} \underbrace{\sum_{x_2} \sum_{x_3} f_C(x_1, x_2, x_3)} \underbrace{f_B(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)} \cdot \underbrace{1}_{\mu_{X_4 \rightarrow f_D}(x_4)} \underbrace{\sum_{x_5} f_E(x_3, x_5)} \cdot \underbrace{1}_{\mu_{X_5 \rightarrow f_E}(x_5)} \\
 &\quad \underbrace{\hspace{10em}}_{\mu_{f_B \rightarrow X_2}(x_2)} \underbrace{\hspace{10em}}_{\mu_{f_D \rightarrow X_3}(x_3)} \underbrace{\hspace{10em}}_{\mu_{f_E \rightarrow X_3}(x_3)} \\
 &\quad \underbrace{\hspace{15em}}_{\mu_{f_{X_3 \rightarrow f_C}}(x_3)}
 \end{aligned}$$

The Sum-Product Algorithm

$$\begin{aligned}
 \eta_{X_1}(x_1) &= \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5) \\
 &= \underbrace{f_A(x_1)}_{\mu_{X_1 \rightarrow f_C}(x_1)} \sum_{x_2} \sum_{x_3} f_C(x_1, x_2, x_3) \underbrace{f_B(x_2)}_{\mu_{f_B \rightarrow X_2}(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)}_{\mu_{f_D \rightarrow X_3}(x_3)} \cdot \underbrace{1}_{\mu_{X_4 \rightarrow f_D}(x_4)} \underbrace{\sum_{x_5} f_E(x_3, x_5)}_{\mu_{f_E \rightarrow X_3}(x_3)} \cdot \underbrace{1}_{\mu_{X_5 \rightarrow f_E}(x_5)} \\
 &\quad \underbrace{\hspace{15em}}_{\mu_{f_{X_3 \rightarrow f_C}}(x_3)}
 \end{aligned}$$

The Sum-Product Algorithm

$$\begin{aligned}
 \eta_{X_1}(x_1) &= \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5) \\
 &= \underbrace{f_A(x_1)}_{\mu_{f_A \rightarrow X_1}(x_1)} \sum_{x_2} \sum_{x_3} f_C(x_1, x_2, x_3) \underbrace{f_B(x_2)}_{\mu_{f_B \rightarrow X_2}(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)}_{\mu_{f_D \rightarrow X_3}(x_3)} \cdot \underbrace{1}_{\mu_{X_4 \rightarrow f_D}(x_4)} \underbrace{\sum_{x_5} f_E(x_3, x_5)}_{\mu_{f_E \rightarrow X_3}(x_3)} \cdot \underbrace{1}_{\mu_{X_5 \rightarrow f_E}(x_5)} \\
 &\quad \underbrace{\hspace{15em}}_{\mu_{f_{X_3 \rightarrow f_C}}(x_3)} \\
 &\quad \underbrace{\hspace{25em}}_{\mu_{f_C \rightarrow X_1}(x_1)}
 \end{aligned}$$

The Sum-Product Algorithm

$$\begin{aligned}
 \eta_{X_1}(x_1) &= \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5) \\
 &= \underbrace{f_A(x_1)}_{\mu_{f_A \rightarrow X_1}(x_1)} \sum_{x_2} \sum_{x_3} f_C(x_1, x_2, x_3) \underbrace{f_B(x_2)}_{\mu_{f_B \rightarrow X_2}(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)}_{\mu_{X_4 \rightarrow f_D}(x_4)} \cdot \underbrace{1}_{\mu_{X_4 \rightarrow f_D}(x_4)} \underbrace{\sum_{x_5} f_E(x_3, x_5)}_{\mu_{X_5 \rightarrow f_E}(x_5)} \cdot \underbrace{1}_{\mu_{X_5 \rightarrow f_E}(x_5)} \\
 &\quad \underbrace{\mu_{X_2 \rightarrow f_C}(x_2)} \underbrace{\mu_{f_D \rightarrow X_3}(x_3)} \underbrace{\mu_{f_E \rightarrow X_3}(x_3)} \\
 &\quad \underbrace{\mu_{f_{X_3 \rightarrow f_C}}(x_3)} \\
 &\quad \underbrace{\mu_{f_C \rightarrow X_1}(x_1)}
 \end{aligned}$$

The Sum-Product Algorithm

$$\begin{aligned}
 \eta_{X_1}(x_1) &= \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5) \\
 &= \underbrace{f_A(x_1)}_{\mu_{f_A \rightarrow X_1}(x_1)} \sum_{x_2} \sum_{x_3} f_C(x_1, x_2, x_3) \underbrace{f_B(x_2)}_{\mu_{f_B \rightarrow X_2}(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)}_{\mu_{f_D \rightarrow X_3}(x_3)} \cdot \underbrace{1}_{\mu_{X_4 \rightarrow f_D}(x_4)} \underbrace{\sum_{x_5} f_E(x_3, x_5)}_{\mu_{f_E \rightarrow X_3}(x_3)} \cdot \underbrace{1}_{\mu_{X_5 \rightarrow f_E}(x_5)} \\
 &\quad \underbrace{\hspace{15em}}_{\mu_{f_{X_3} \rightarrow f_C}(x_3)} \\
 &\quad \underbrace{\hspace{25em}}_{\mu_{f_C \rightarrow X_1}(x_1)}
 \end{aligned}$$

The objects $\mu_{X_i \rightarrow f_j}(x_i)$ and $\mu_{f_j \rightarrow X_i}(x_i)$:

The Sum-Product Algorithm

$$\begin{aligned}
 \eta_{X_1}(x_1) &= \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5) \\
 &= \underbrace{f_A(x_1)}_{\mu_{f_A \rightarrow X_1}(x_1)} \sum_{x_2} \sum_{x_3} f_C(x_1, x_2, x_3) \underbrace{f_B(x_2)}_{\mu_{f_B \rightarrow X_2}(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)}_{\mu_{f_D \rightarrow X_3}(x_3)} \cdot \underbrace{1}_{\mu_{X_4 \rightarrow f_D}(x_4)} \underbrace{\sum_{x_5} f_E(x_3, x_5)}_{\mu_{f_E \rightarrow X_3}(x_3)} \cdot \underbrace{1}_{\mu_{X_5 \rightarrow f_E}(x_5)} \\
 &\quad \underbrace{\hspace{15em}}_{\mu_{f_{X_3} \rightarrow f_C}(x_3)} \\
 &\quad \underbrace{\hspace{25em}}_{\mu_{f_C \rightarrow X_1}(x_1)}
 \end{aligned}$$

The objects $\mu_{X_i \rightarrow f_j}(x_i)$ and $\mu_{f_j \rightarrow X_i}(x_i)$:

- They are called **messages**.

The Sum-Product Algorithm

$$\begin{aligned}
 \eta_{X_1}(x_1) &= \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5) \\
 &= \underbrace{f_A(x_1)}_{\mu_{f_A \rightarrow X_1}(x_1)} \sum_{x_2} \sum_{x_3} f_C(x_1, x_2, x_3) \underbrace{f_B(x_2)}_{\mu_{f_B \rightarrow X_2}(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)}_{\mu_{f_D \rightarrow X_3}(x_3)} \cdot \underbrace{1}_{\mu_{X_4 \rightarrow f_D}(x_4)} \underbrace{\sum_{x_5} f_E(x_3, x_5)}_{\mu_{f_E \rightarrow X_3}(x_3)} \cdot \underbrace{1}_{\mu_{X_5 \rightarrow f_E}(x_5)} \\
 &\quad \underbrace{\hspace{15em}}_{\mu_{f_{X_3} \rightarrow f_C}(x_3)} \\
 &\quad \underbrace{\hspace{20em}}_{\mu_{f_C \rightarrow X_1}(x_1)}
 \end{aligned}$$

The objects $\mu_{X_i \rightarrow f_j}(x_i)$ and $\mu_{f_j \rightarrow X_i}(x_i)$:

- They are called **messages**.
- They can be **associated** with the edge between the vertex X_i and the vertex f_j .

The Sum-Product Algorithm

$$\begin{aligned}
 \eta_{X_1}(x_1) &= \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5) \\
 &= \underbrace{f_A(x_1)}_{\mu_{f_A \rightarrow X_1}(x_1)} \sum_{x_2} \sum_{x_3} \underbrace{f_C(x_1, x_2, x_3)}_{\mu_{f_C \rightarrow X_3}(x_3)} \underbrace{f_B(x_2)}_{\mu_{f_B \rightarrow X_2}(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)}_{\mu_{f_D \rightarrow X_4}(x_4)} \cdot \underbrace{1}_{\mu_{X_4 \rightarrow f_D}(x_4)} \underbrace{\sum_{x_5} f_E(x_3, x_5)}_{\mu_{f_E \rightarrow X_5}(x_5)} \cdot \underbrace{1}_{\mu_{X_5 \rightarrow f_E}(x_5)} \\
 &\quad \underbrace{\hspace{10em}}_{\mu_{f_D \rightarrow X_3}(x_3)} \quad \underbrace{\hspace{10em}}_{\mu_{f_E \rightarrow X_3}(x_3)} \\
 &\quad \underbrace{\hspace{15em}}_{\mu_{f_{X_3 \rightarrow f_C}}(x_3)} \\
 &\quad \underbrace{\hspace{20em}}_{\mu_{f_C \rightarrow X_1}(x_1)}
 \end{aligned}$$

The objects $\mu_{X_i \rightarrow f_j}(x_i)$ and $\mu_{f_j \rightarrow X_i}(x_i)$:

- They are called **messages**.
- They can be **associated** with the edge between the vertex X_i and the vertex f_j .
- They are **functions** of x_i , i.e. their domain is the alphabet of X_i .

The Sum-Product Algorithm

$$\begin{aligned}
 \eta_{X_1}(x_1) &= \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} f_A(x_1) \cdot f_B(x_2) \cdot f_C(x_1, x_2, x_3) \cdot f_D(x_3, x_4) \cdot f_E(x_3, x_5) \\
 &= \underbrace{f_A(x_1)}_{\mu_{f_A \rightarrow X_1}(x_1)} \sum_{x_2} \sum_{x_3} f_C(x_1, x_2, x_3) \underbrace{f_B(x_2)}_{\mu_{f_B \rightarrow X_2}(x_2)} \underbrace{\sum_{x_4} f_D(x_3, x_4)}_{\mu_{f_D \rightarrow X_3}(x_3)} \cdot \underbrace{1}_{\mu_{X_4 \rightarrow f_D}(x_4)} \underbrace{\sum_{x_5} f_E(x_3, x_5)}_{\mu_{f_E \rightarrow X_3}(x_3)} \cdot \underbrace{1}_{\mu_{X_5 \rightarrow f_E}(x_5)} \\
 &\quad \underbrace{\hspace{15em}}_{\mu_{f_{X_3} \rightarrow f_C}(x_3)} \\
 &\quad \underbrace{\hspace{20em}}_{\mu_{f_C \rightarrow X_1}(x_1)}
 \end{aligned}$$

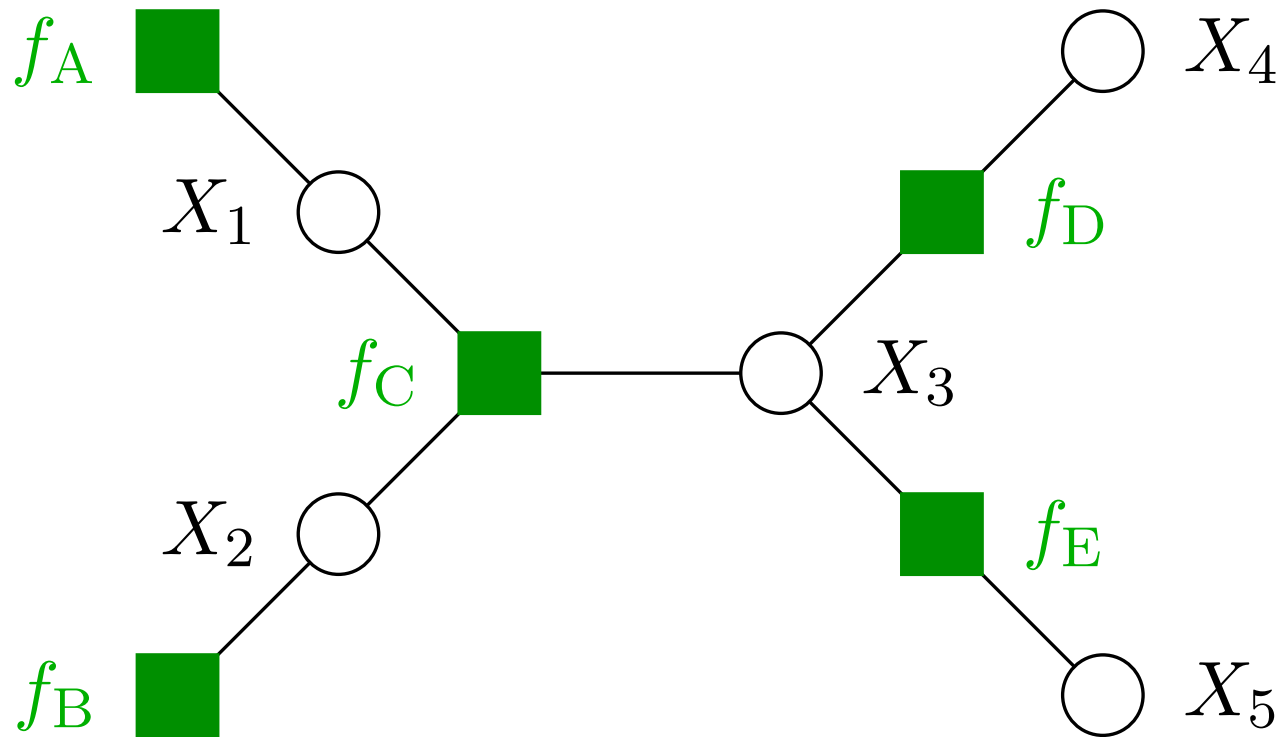
The objects $\mu_{X_i \rightarrow f_j}(x_i)$ and $\mu_{f_j \rightarrow X_i}(x_i)$:

- They are called **messages**.
- They can be **associated** with the edge between the vertex X_i and the vertex f_j .
- They are **functions** of x_i , i.e. their domain is the alphabet of X_i .

Note: similar manipulations can be performed for calculating $\eta_{X_2}(x_2)$, $\eta_{X_3}(x_3)$, $\eta_{X_4}(x_4)$, $\eta_{X_5}(x_5)$.

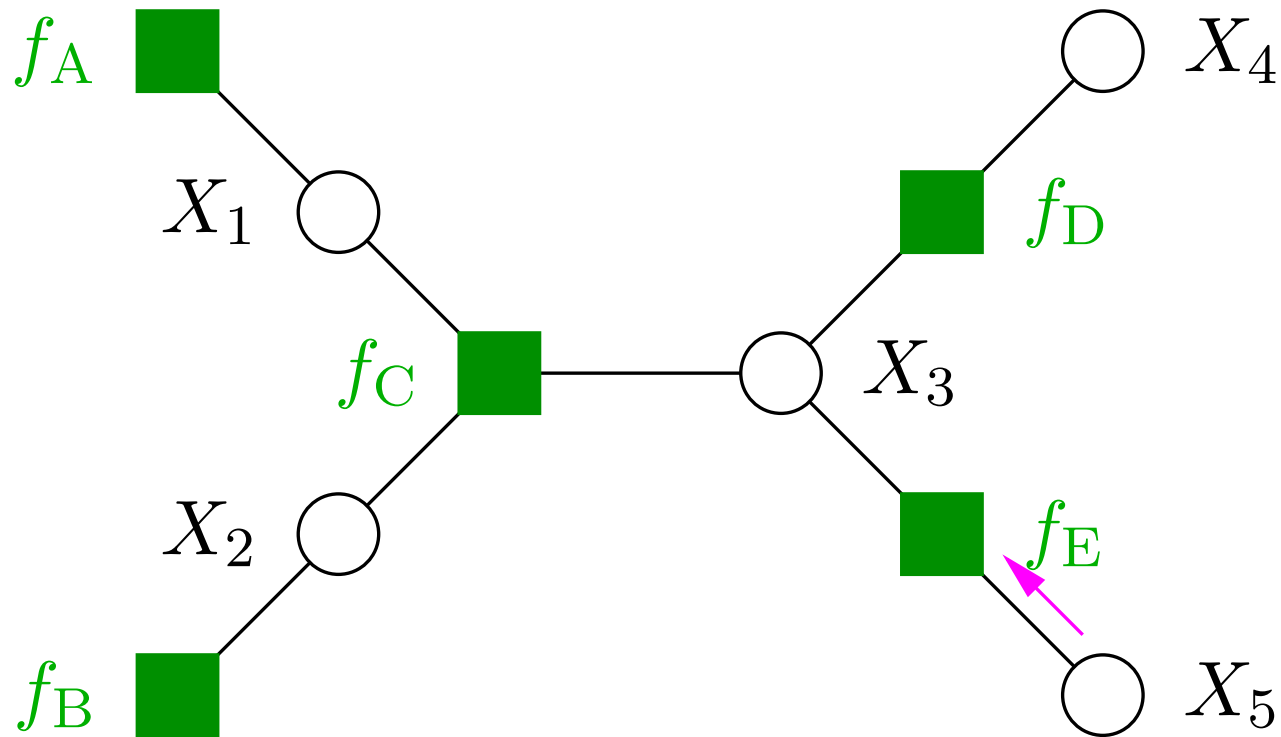
The Sum-Product Algorithm

Messages necessary for calculating $\eta_{X_1}(x_1)$.



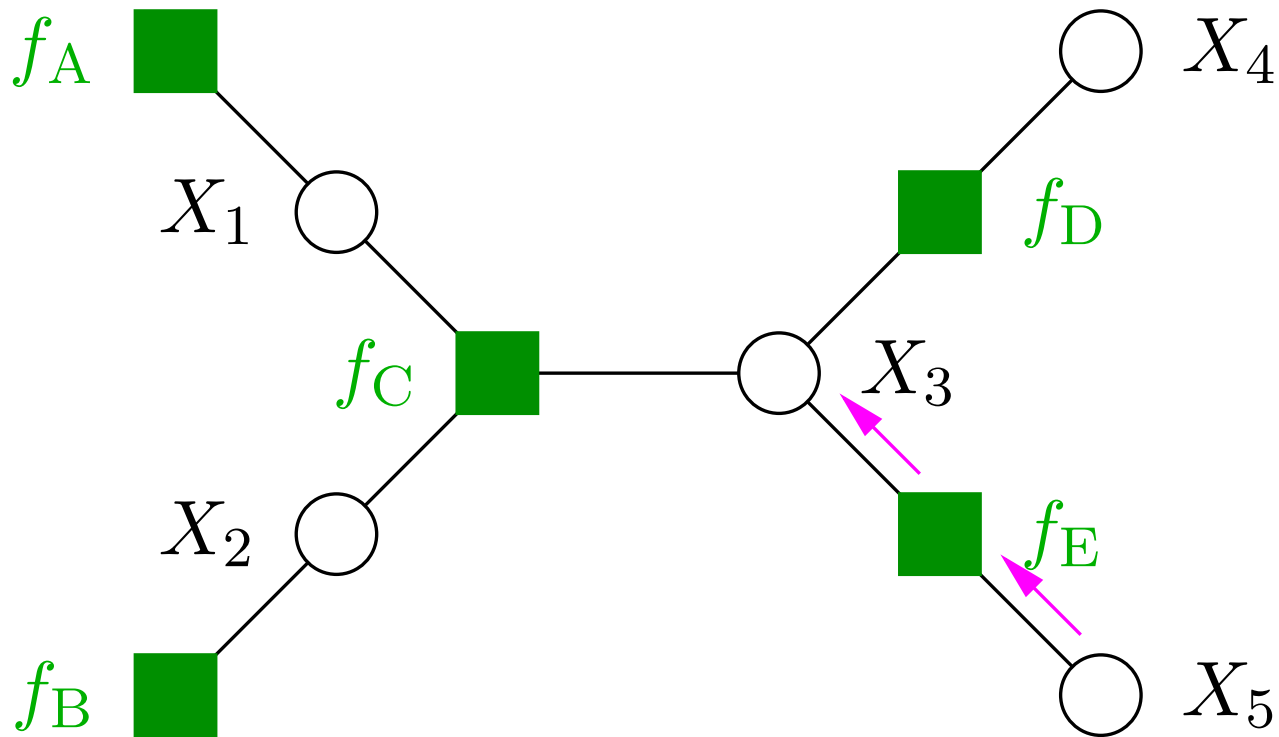
The Sum-Product Algorithm

Messages necessary for calculating $\eta_{X_1}(x_1)$.



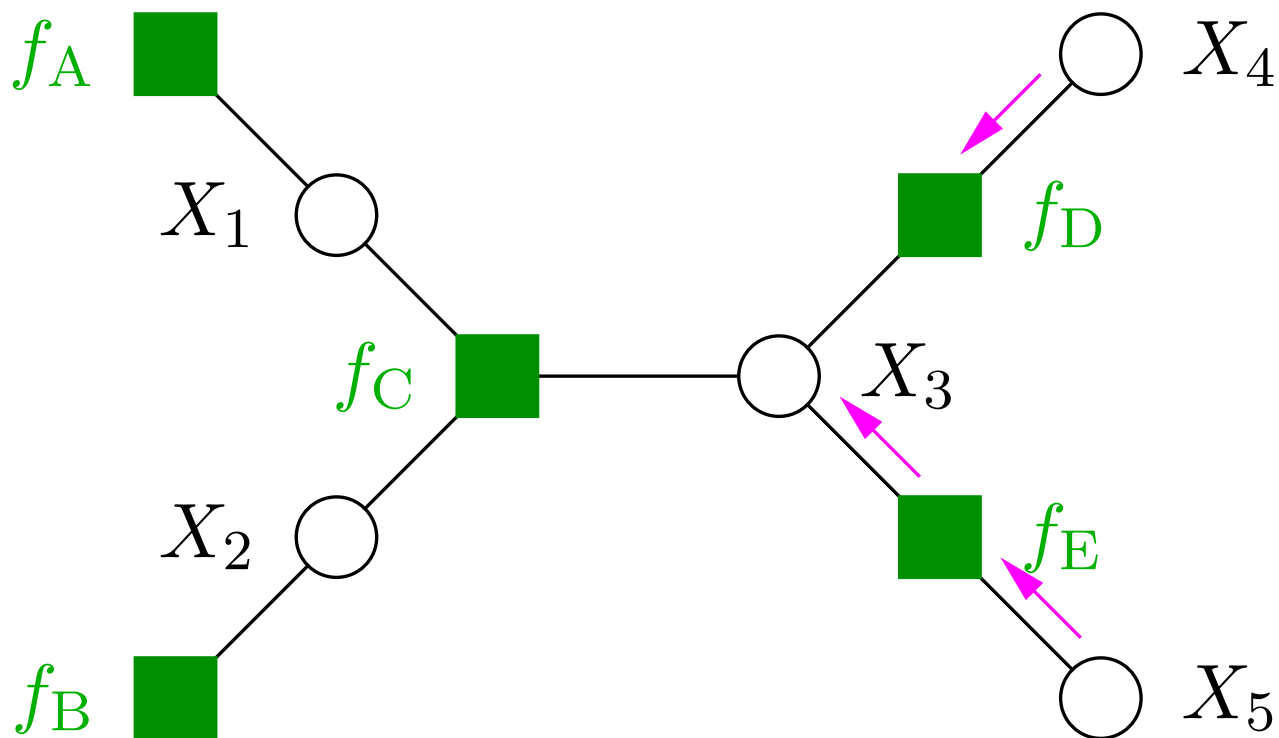
The Sum-Product Algorithm

Messages necessary for calculating $\eta_{X_1}(x_1)$.



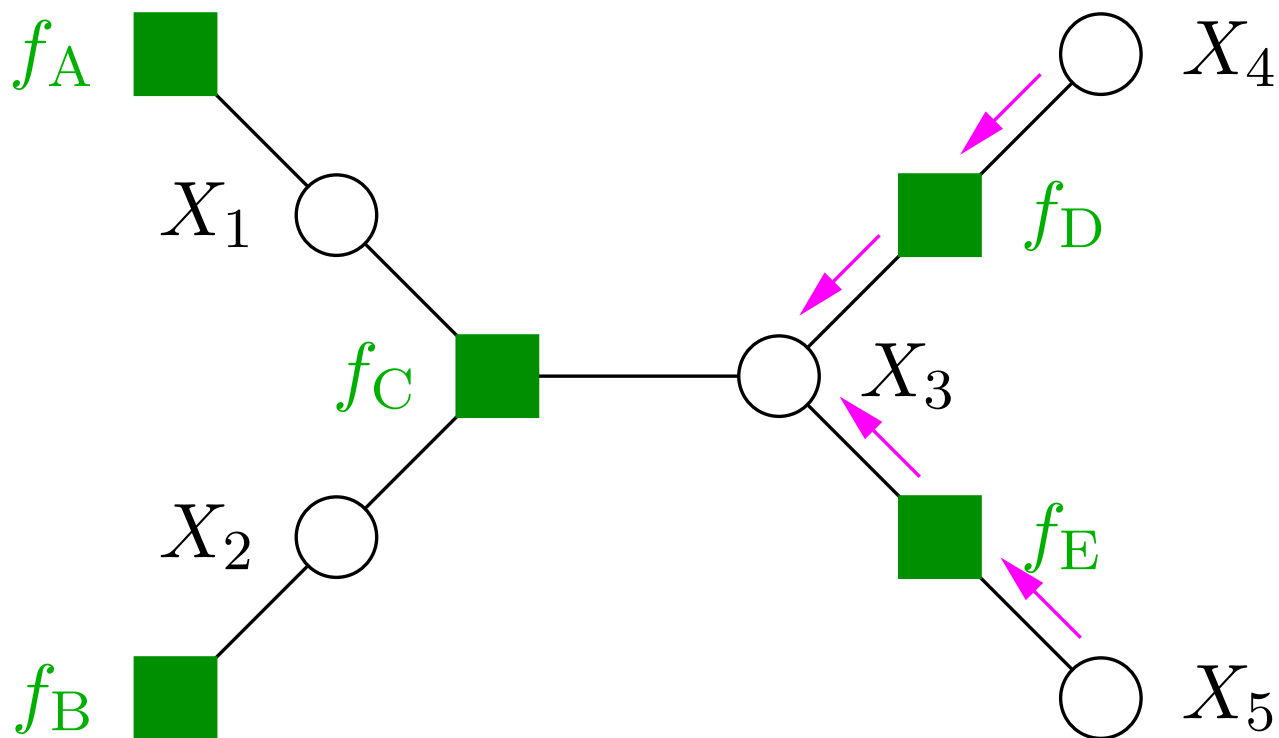
The Sum-Product Algorithm

Messages necessary for calculating $\eta_{X_1}(x_1)$.



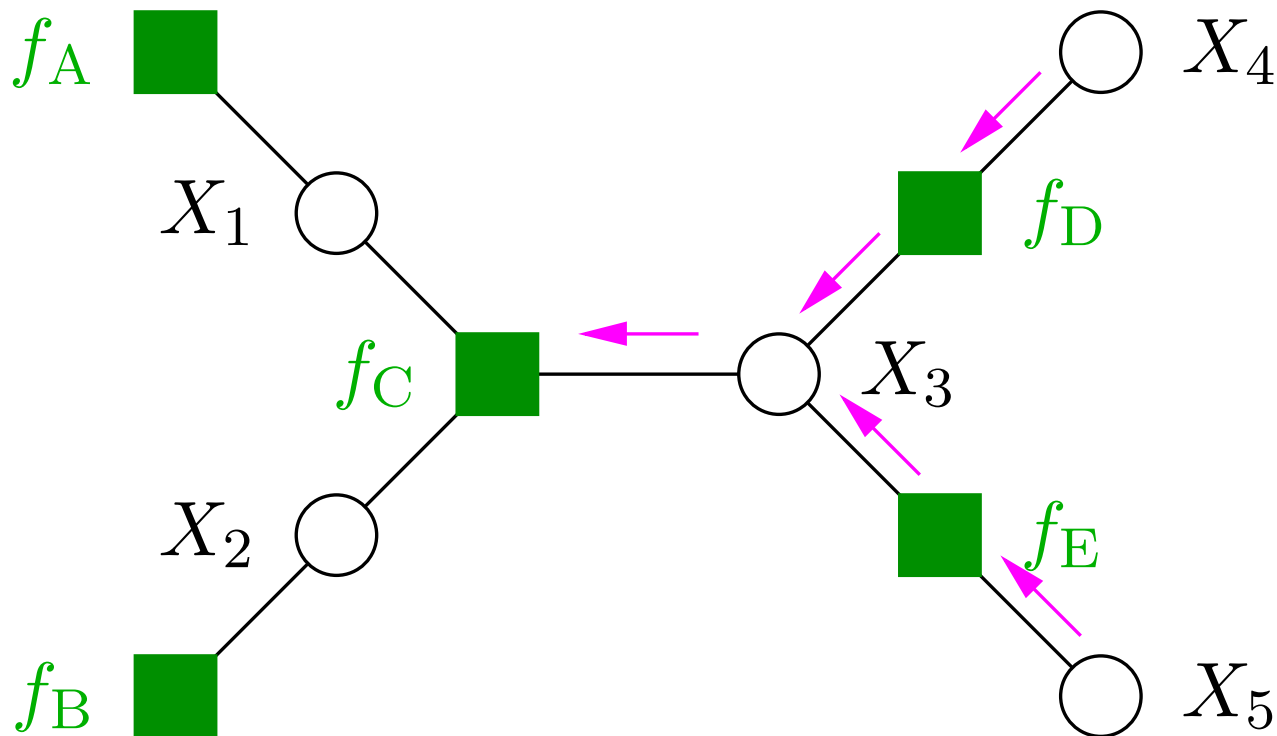
The Sum-Product Algorithm

Messages necessary for calculating $\eta_{X_1}(x_1)$.



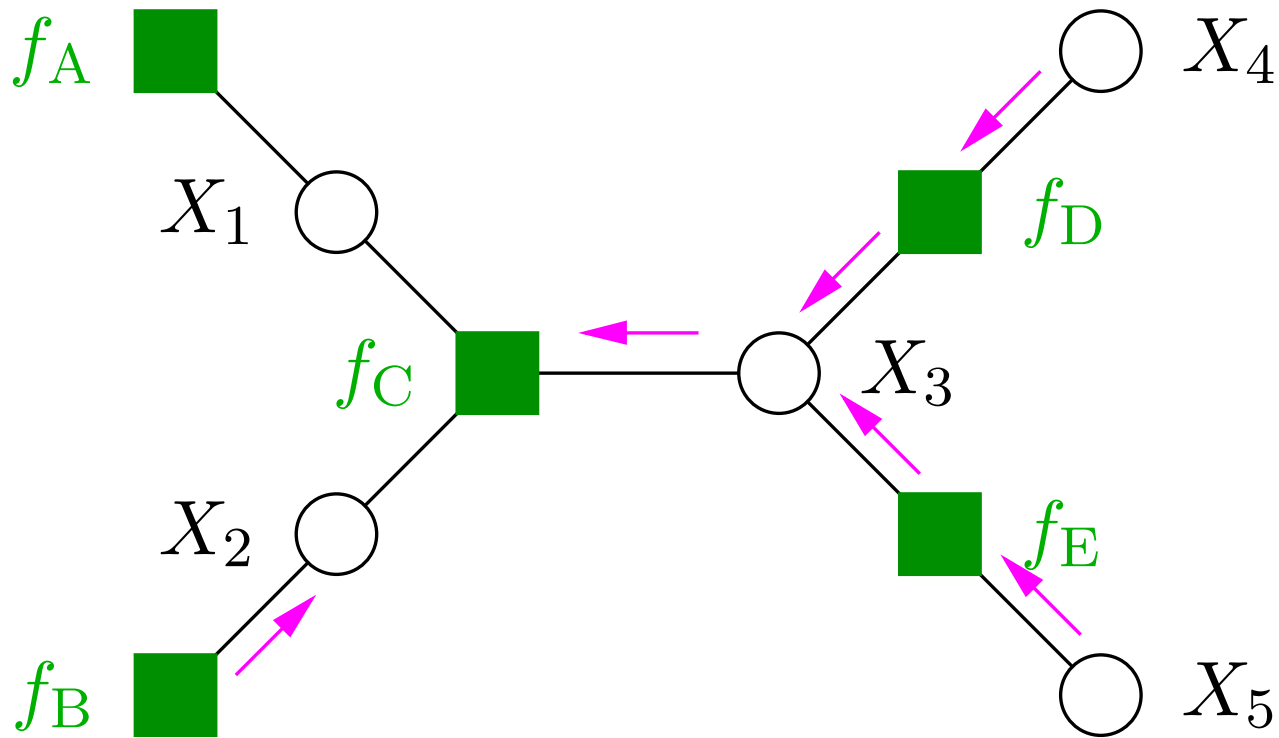
The Sum-Product Algorithm

Messages necessary for calculating $\eta_{X_1}(x_1)$.



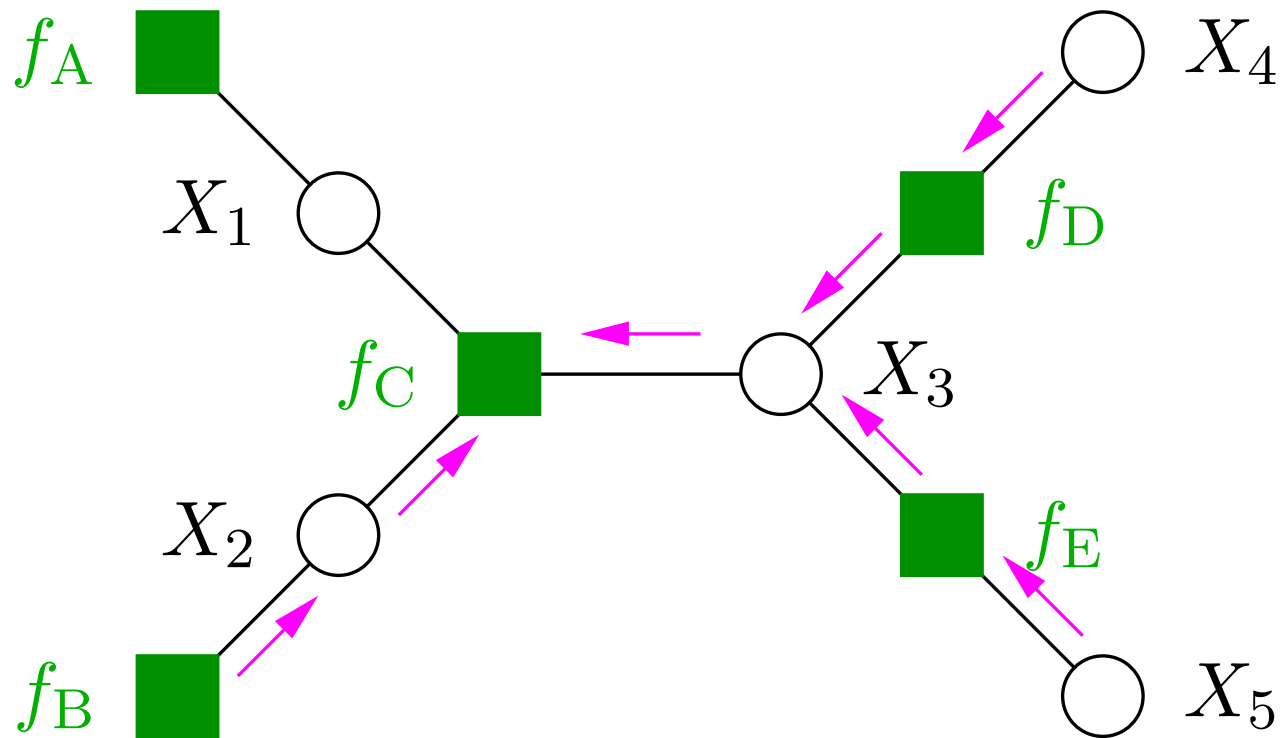
The Sum-Product Algorithm

Messages necessary for calculating $\eta_{X_1}(x_1)$.



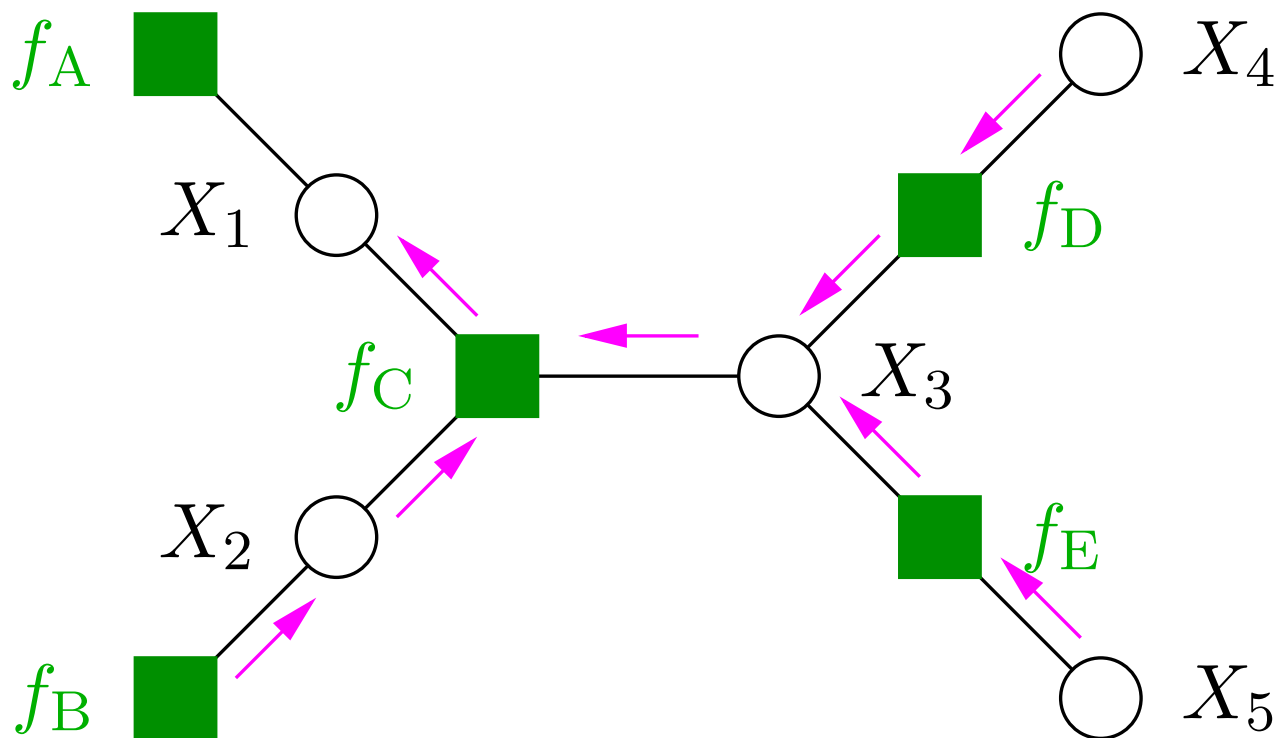
The Sum-Product Algorithm

Messages necessary for calculating $\eta_{X_1}(x_1)$.



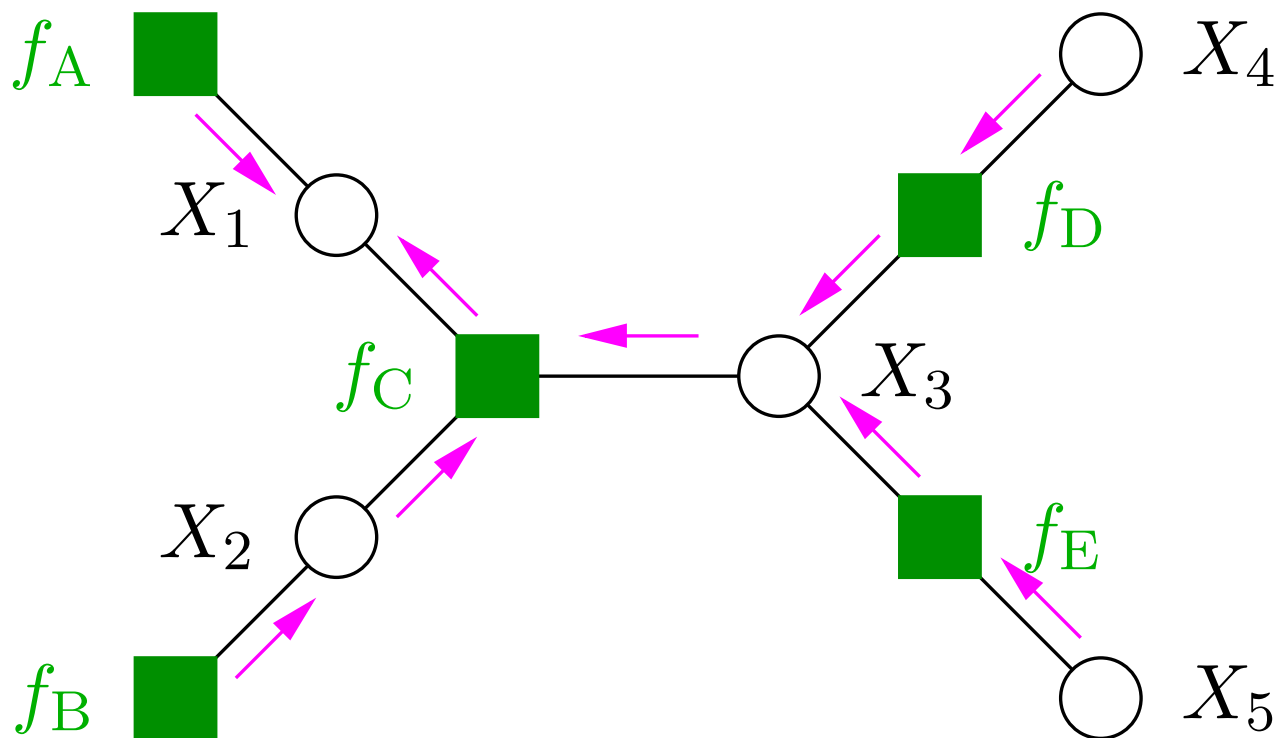
The Sum-Product Algorithm

Messages necessary for calculating $\eta_{X_1}(x_1)$.



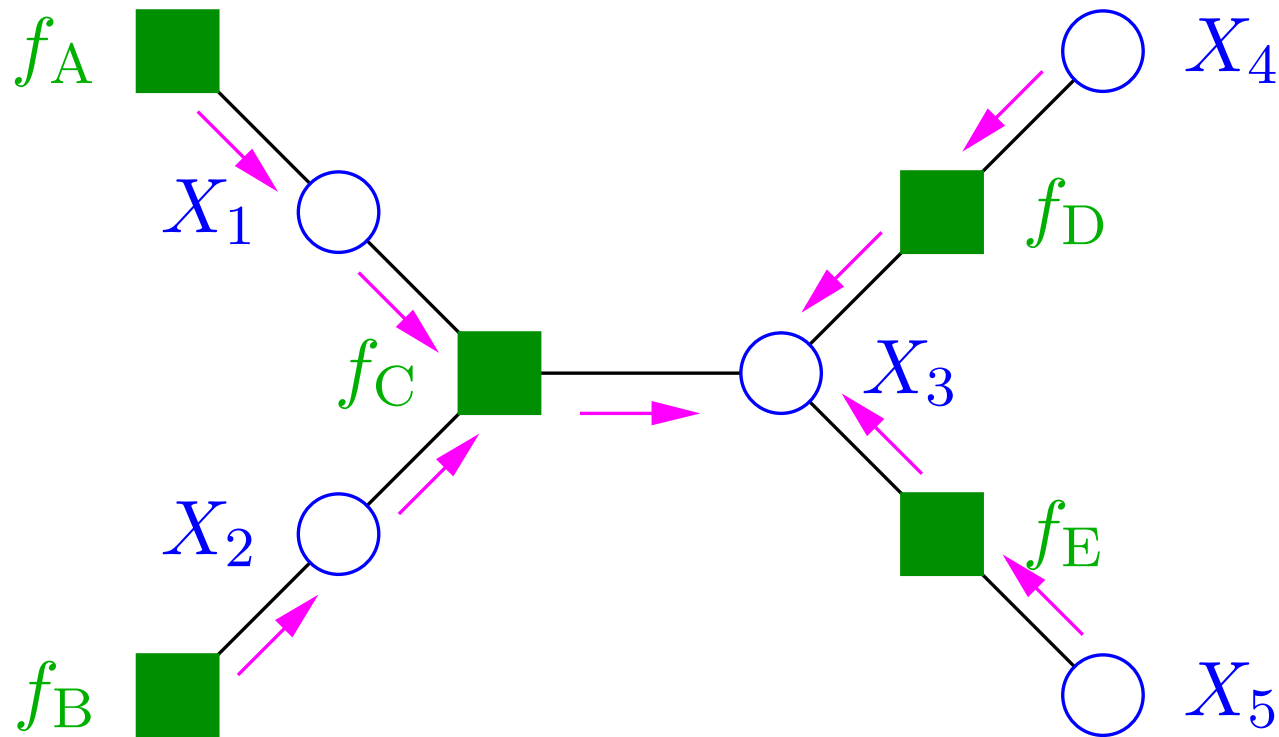
The Sum-Product Algorithm

Messages necessary for calculating $\eta_{X_1}(x_1)$.



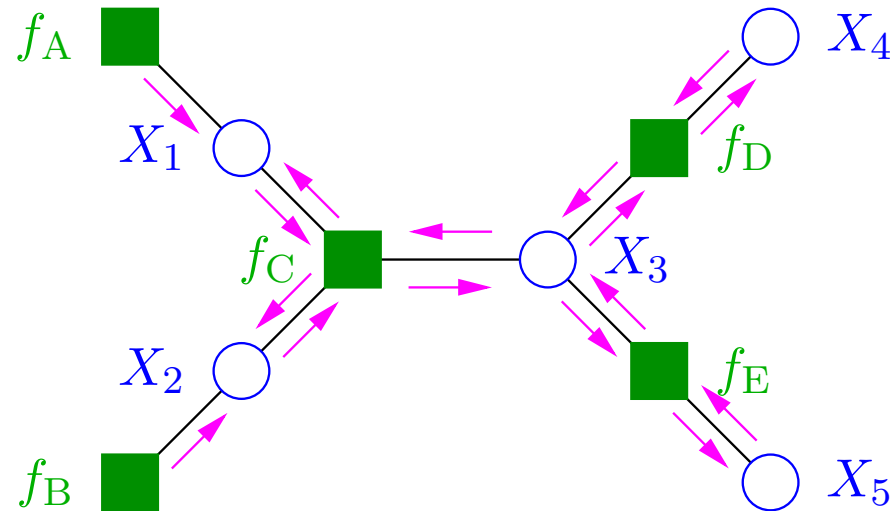
The Sum-Product Algorithm

Messages necessary for calculating $\eta_{X_3}(x_3)$.



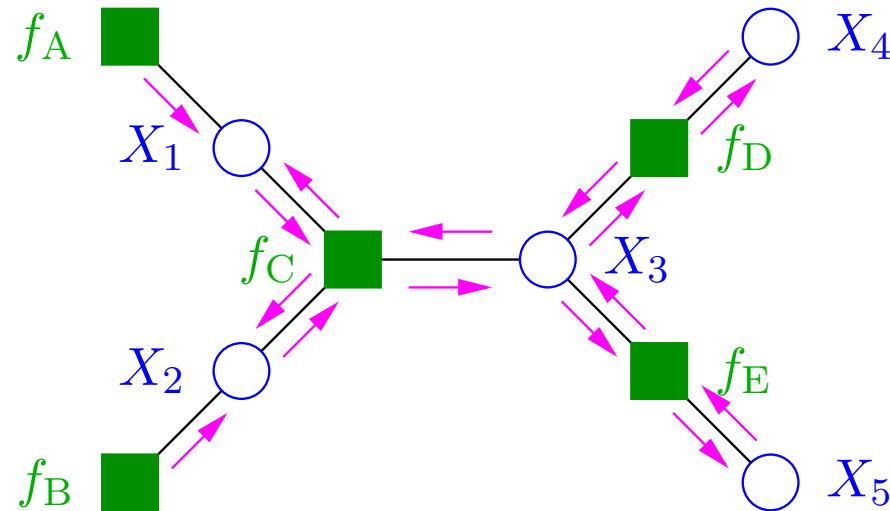
The Sum-Product Algorithm

The figure shows the messages that are necessary for calculating $\eta_{X_1}(x_1)$, $\eta_{X_2}(x_2)$, $\eta_{X_3}(x_3)$, $\eta_{X_4}(x_4)$, and $\eta_{X_5}(x_5)$.



The Sum-Product Algorithm

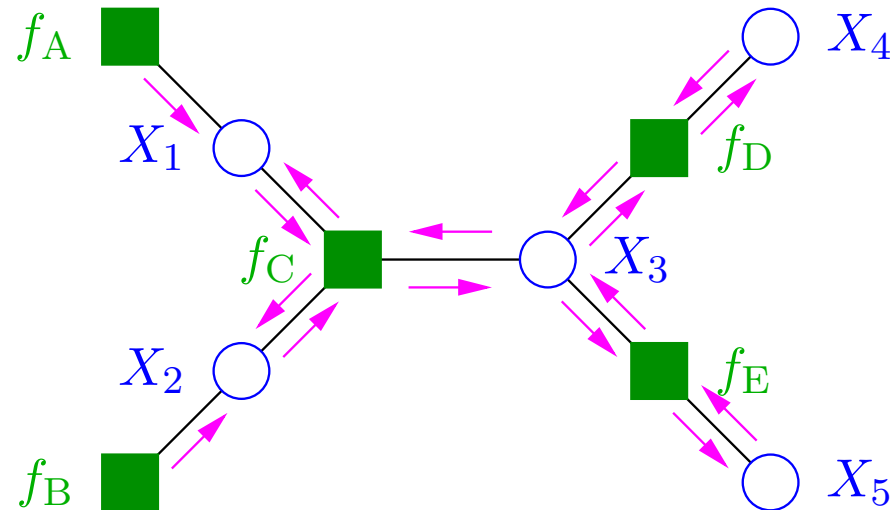
The figure shows the messages that are necessary for calculating $\eta_{X_1}(x_1)$, $\eta_{X_2}(x_2)$, $\eta_{X_3}(x_3)$, $\eta_{X_4}(x_4)$, and $\eta_{X_5}(x_5)$.



- **Edges:** Messages are sent along edges.

The Sum-Product Algorithm

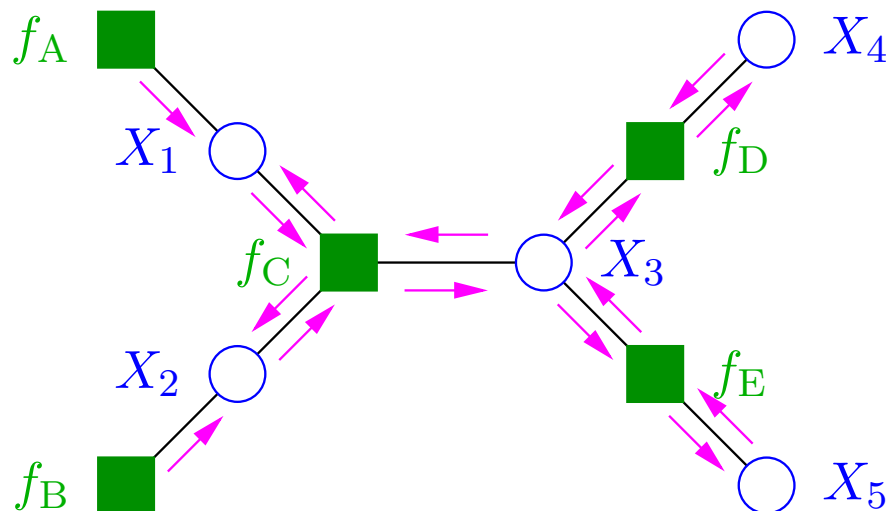
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- **Edges:** Messages are sent along edges.
- **Processing:** Taking products and doing summations is done in the vertices.

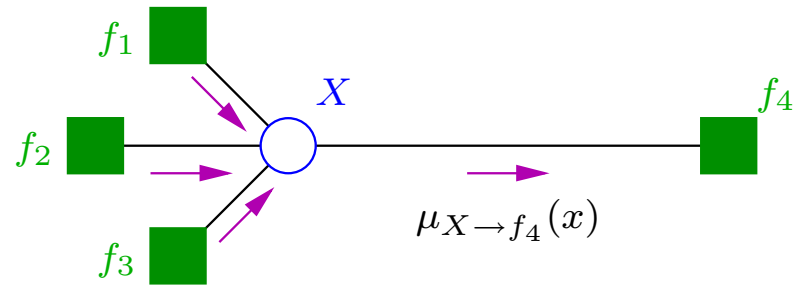
The Sum-Product Algorithm

The figure shows the messages that are necessary for calculating $\eta_{X_1}(x_1)$, $\eta_{X_2}(x_2)$, $\eta_{X_3}(x_3)$, $\eta_{X_4}(x_4)$, and $\eta_{X_5}(x_5)$.



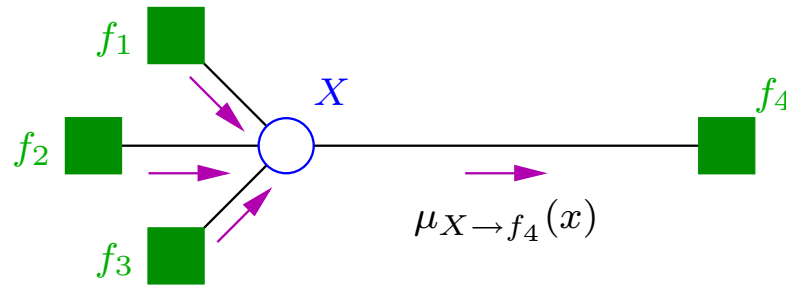
- **Edges:** Messages are sent along edges.
- **Processing:** Taking products and doing summations is done in the vertices.
- **Reuse of messages:** We see that messages can be “reused” in the sense that many partial calculations are the same; so it suffices to perform them only once.

The Sum-Product Algorithm

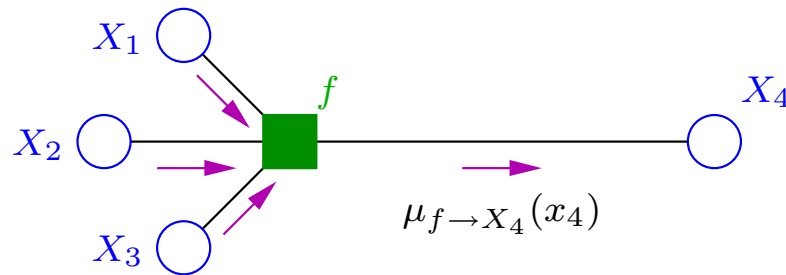


$$\mu_{X \rightarrow f_4}(x) = \mu_{f_1 \rightarrow X}(x) \cdot \mu_{f_2 \rightarrow X}(x) \cdot \mu_{f_3 \rightarrow X}(x)$$

The Sum-Product Algorithm

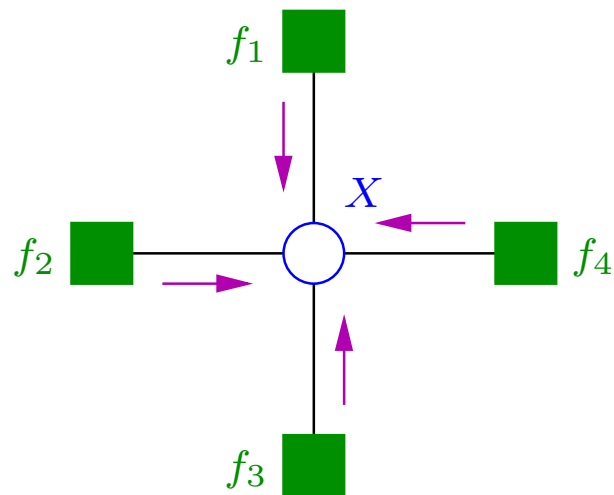


$$\mu_{X \rightarrow f_4}(x) = \mu_{f_1 \rightarrow X}(x) \cdot \mu_{f_2 \rightarrow X}(x) \cdot \mu_{f_3 \rightarrow X}(x)$$



$$\mu_{f \rightarrow X_4}(x_4) = \sum_{x_1} \sum_{x_2} \sum_{x_3} f(x_1, x_2, x_3, x_4) \cdot \mu_{X_1 \rightarrow f}(x_1) \cdot \mu_{X_2 \rightarrow f}(x_2) \cdot \mu_{X_3 \rightarrow f}(x_3)$$

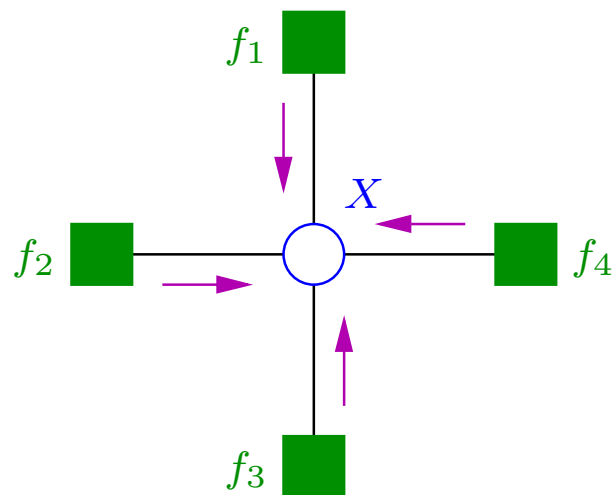
The Sum-Product Algorithm



Computation of marginal at variable node:

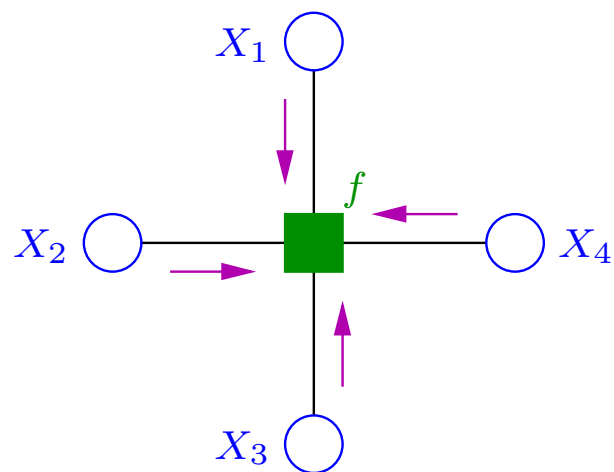
$$\eta_X(\mathbf{x}) = \mu_{f_1 \rightarrow X}(\mathbf{x}) \cdot \mu_{f_2 \rightarrow X}(\mathbf{x}) \\ \cdot \mu_{f_3 \rightarrow X}(\mathbf{x}) \cdot \mu_{f_4 \rightarrow X}(\mathbf{x})$$

The Sum-Product Algorithm



Computation of marginal at variable node:

$$\eta_X(\mathbf{x}) = \mu_{f_1 \rightarrow X}(\mathbf{x}) \cdot \mu_{f_2 \rightarrow X}(\mathbf{x}) \\ \cdot \mu_{f_3 \rightarrow X}(\mathbf{x}) \cdot \mu_{f_4 \rightarrow X}(\mathbf{x})$$



Computation of marginal at function node:

$$\eta_f(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_4) = f(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_4) \\ \cdot \mu_{X_1 \rightarrow f}(\mathbf{x}_1) \cdot \mu_{X_2 \rightarrow f}(\mathbf{x}_2) \\ \cdot \mu_{X_3 \rightarrow f}(\mathbf{x}_3) \cdot \mu_{X_4 \rightarrow f}(\mathbf{x}_4)$$

The Sum-Product Algorithm

- Factor graph **without loops**: in this case it is obvious what messages have to be calculated when.

⇒ Mode of operation 1

The Sum-Product Algorithm

- Factor graph **without loops**: in this case it is obvious what messages have to be calculated when.

⇒ Mode of operation 1

- Factor graph **with loops**: one has to decide what **update schedule** to take.

⇒ Mode of operation 2

Comments on the Sum-Product Algorithm

- If the factor graph **has no loops** then it is obvious what messages have to be calculated when.
- If the factor graphs **has loops** one has to decide what **update schedule** to take.
- Depending on the underlying semi-ring one gets different versions of the summary-product algorithm.
 - For $\langle \mathbb{R}, +, \cdot \rangle$ one gets the **sum-product** algorithm.
(This is the case discussed above.)
 - For $\langle \mathbb{R}^+, \max, \cdot \rangle$ one gets the **max-product** algorithm.
 - For $\langle \mathbb{R}, \min, + \rangle$ one gets the **min-sum** algorithm.
 - etc.

Partition function (total sum)

Partition Function

$$Z = \sum_{x_1, x_2, x_3, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

Partition Function

$$Z = \sum_{x_1, x_2, x_3, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

Recall:

$$\eta_{X_1}(x_1) = \sum_{x_2, x_3, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

$$\eta_{X_2}(x_2) = \sum_{x_1, x_3, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

⋮

⋮

Partition Function

$$Z = \sum_{x_1, x_2, x_3, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

Recall:

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$$\eta_{X_2}(x_2) = \sum_{x_1, x_3, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

⋮

⋮

Define:

$$Z_{X_1} = \sum_{x_1} \eta_{X_1}(x_1)$$

$$Z_{X_2} = \sum_{x_2} \eta_{X_2}(x_2)$$

⋮

⋮

Partition Function

$$Z = \sum_{x_1, x_2, x_3, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

Recall:

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$$\eta_{X_2}(x_2) = \sum_{x_1, x_3, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

⋮

⋮

Define:

$$Z_{X_1} = \sum_{x_1} \eta_{X_1}(x_1) = Z$$

$$Z_{X_2} = \sum_{x_2} \eta_{X_2}(x_2) = Z$$

⋮

⋮

Partition Function

$$Z = \sum_{x_1, x_2, x_3, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

Partition Function

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Recall:

$$\eta_{f_C}(x_1, x_2, x_3) = \sum_{x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

Partition Function

$$Z = \sum_{x_1, x_2, x_3, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

Recall:

Define:

$$\eta_{f_C}(x_1, x_2, x_3) = \sum_{x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

$$Z_{f_C} = \sum_{x_1, x_2, x_3} \eta_{f_C}(x_1, x_2, x_3)$$

Partition Function

$$Z = \sum_{x_1, x_2, x_3, x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

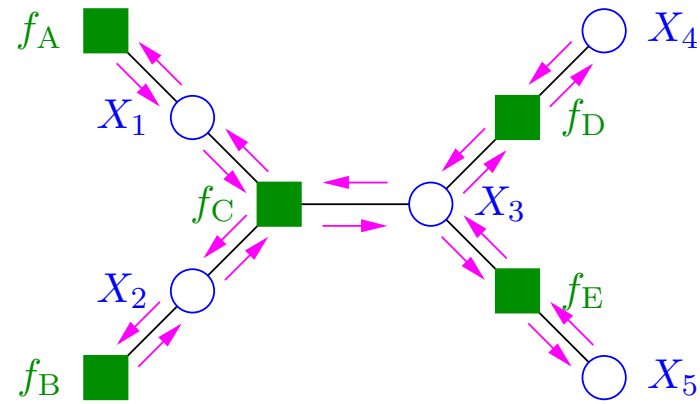
Recall:

Define:

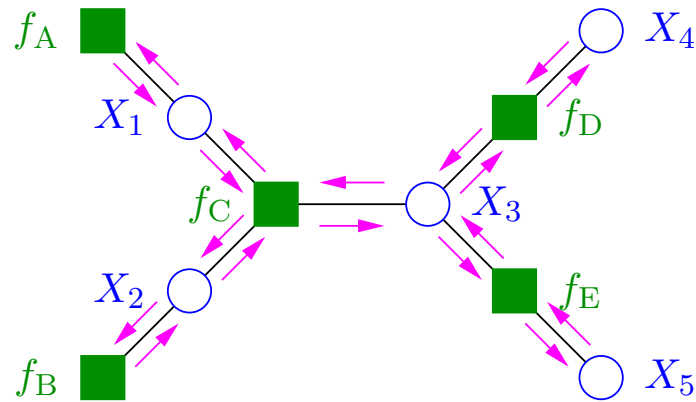
$$\eta_{f_C}(x_1, x_2, x_3) = \sum_{x_4, x_5} f(x_1, x_2, x_3, x_4, x_5)$$

$$Z_{f_C} = \sum_{x_1, x_2, x_3} \eta_{f_C}(x_1, x_2, x_3) = Z$$

Partition Function

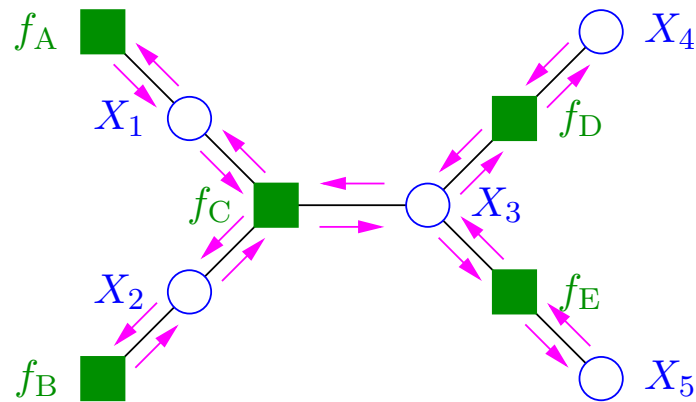


Partition Function



$$Z = Z_{X_1} = Z_{X_2} = Z_{X_3} = Z_{X_4} = Z_{X_5} = Z_{f_A} = Z_{f_B} = Z_{f_C} = Z_{f_D} = Z_{f_E}$$

Partition Function



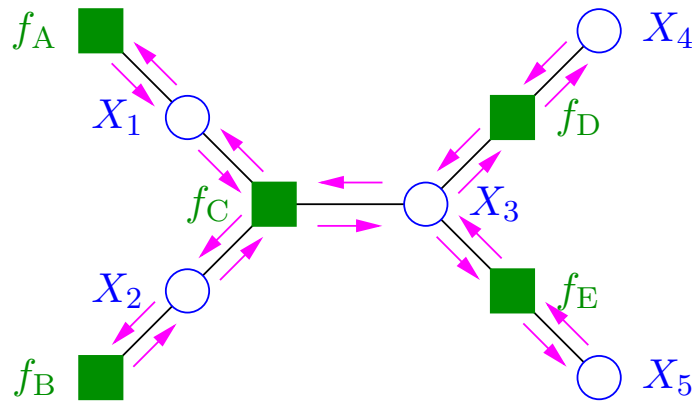
$$Z = Z_{X_1} = Z_{X_2} = Z_{X_3} = Z_{X_4} = Z_{X_5} = Z_{f_A} = Z_{f_B} = Z_{f_C} = Z_{f_D} = Z_{f_E}$$

Claim:

$$Z = \frac{Z_{f_A} \cdot Z_{f_B} \cdot Z_{f_C} \cdot Z_{f_D} \cdot Z_{f_E} \cdot Z_{X_1} \cdot Z_{X_2} \cdot Z_{X_3} \cdot Z_{X_4} \cdot Z_{X_5}}{Z_{X_1}^2 \cdot Z_{X_2}^2 \cdot Z_{X_3}^3 \cdot Z_{X_4}^1 \cdot Z_{X_5}^1}$$

(Note: exponents in denominator equal variable node degrees.)

Partition Function



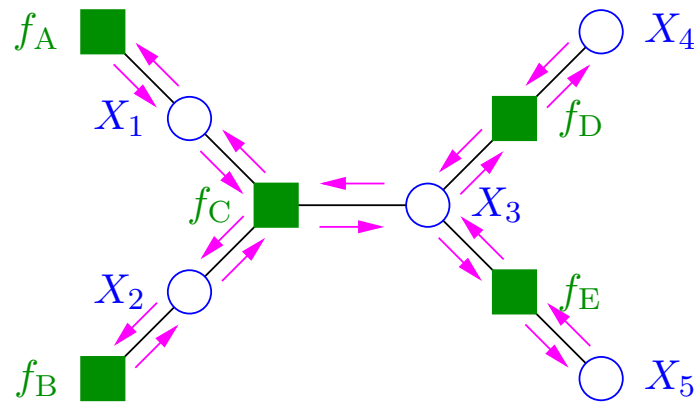
$$Z = Z_{X_1} = Z_{X_2} = Z_{X_3} = Z_{X_4} = Z_{X_5} = Z_{f_A} = Z_{f_B} = Z_{f_C} = Z_{f_D} = Z_{f_E}$$

Claim:

$$Z = \frac{Z^{\#\text{vertices}}}{Z^{\#\text{edges}}} = \frac{Z_{f_A} \cdot Z_{f_B} \cdot Z_{f_C} \cdot Z_{f_D} \cdot Z_{f_E} \cdot Z_{X_1} \cdot Z_{X_2} \cdot Z_{X_3} \cdot Z_{X_4} \cdot Z_{X_5}}{Z_{X_1}^2 \cdot Z_{X_2}^2 \cdot Z_{X_3}^3 \cdot Z_{X_4}^1 \cdot Z_{X_5}^1}$$

(Note: exponents in denominator equal variable node degrees.)

Partition Function



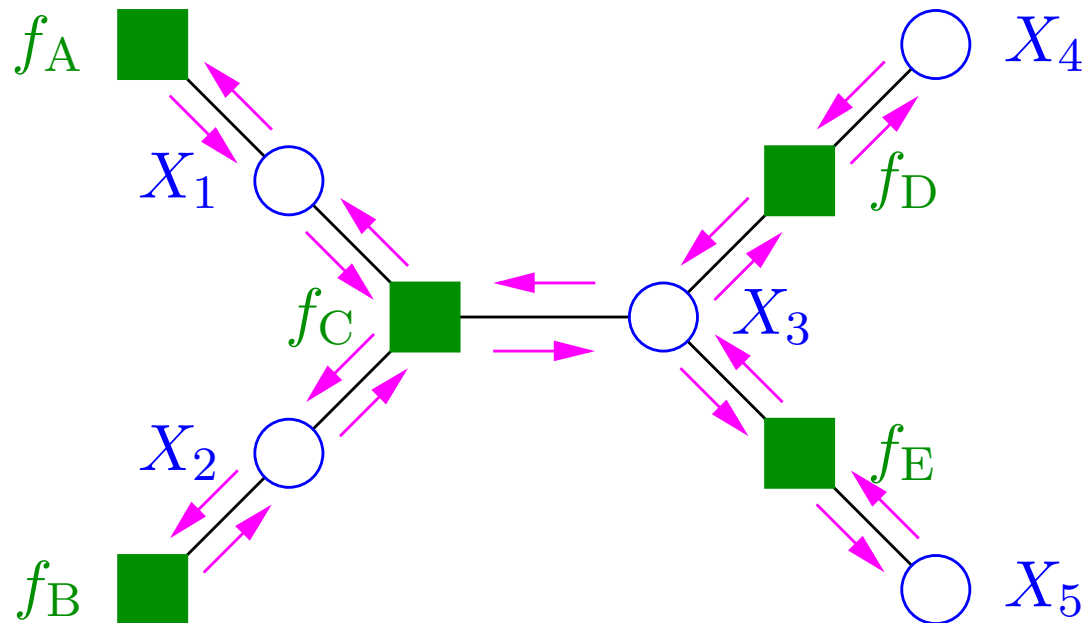
$$Z = Z_{X_1} = Z_{X_2} = Z_{X_3} = Z_{X_4} = Z_{X_5} = Z_{f_A} = Z_{f_B} = Z_{f_C} = Z_{f_D} = Z_{f_E}$$

Claim:

$$Z = \frac{Z^{\#\text{vertices}}}{Z^{\#\text{edges}}} = \frac{Z_{f_A} \cdot Z_{f_B} \cdot Z_{f_C} \cdot Z_{f_D} \cdot Z_{f_E} \cdot Z_{X_1} \cdot Z_{X_2} \cdot Z_{X_3} \cdot Z_{X_4} \cdot Z_{X_5}}{Z_{X_1}^2 \cdot Z_{X_2}^2 \cdot Z_{X_3}^3 \cdot Z_{X_4}^1 \cdot Z_{X_5}^1}$$

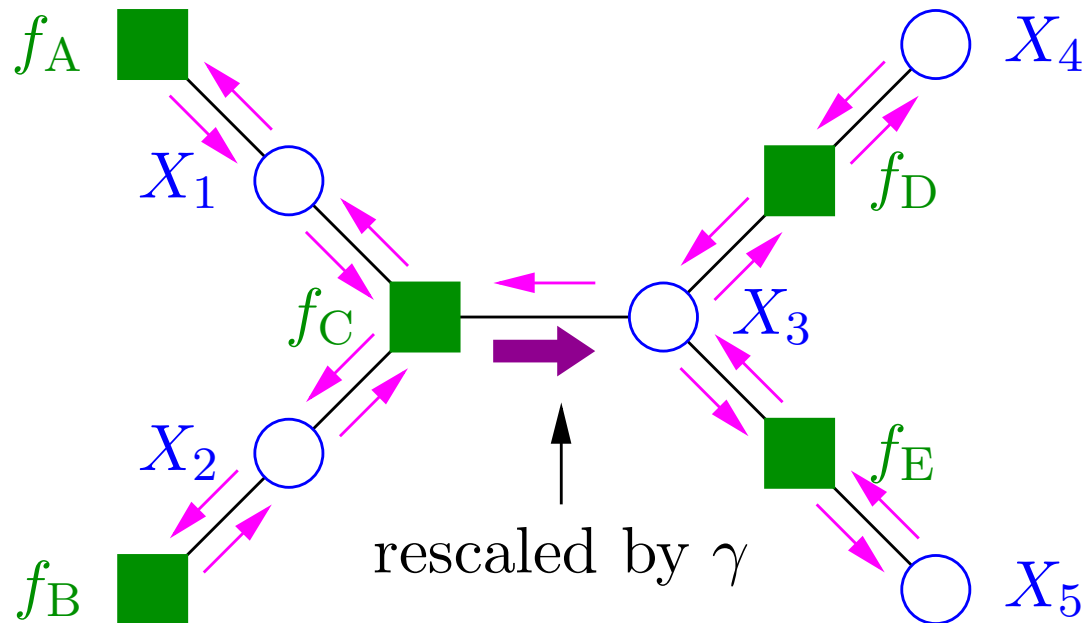
(Here we used the fact that for a graph with one component and no cycles it holds that $\#\text{vertices} = \#\text{edges} + 1$.)

Partition Function



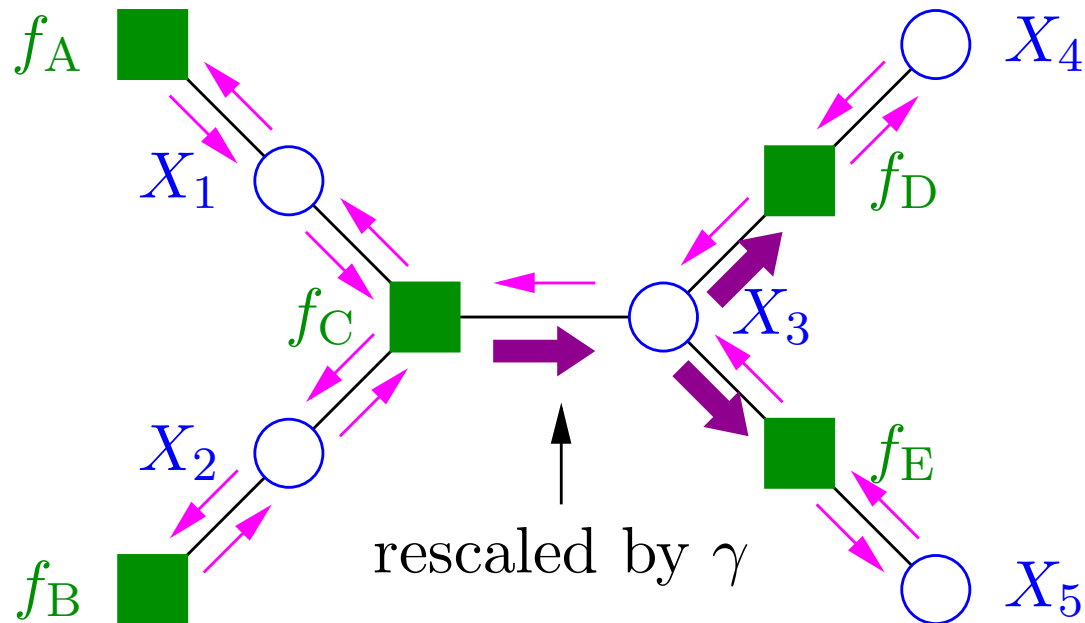
$$Z = \frac{Z_{f_A} \cdot Z_{f_B} \cdot Z_{f_C} \cdot Z_{f_D} \cdot Z_{f_E} \cdot Z_{X_1} \cdot Z_{X_2} \cdot Z_{X_3} \cdot Z_{X_4} \cdot Z_{X_5}}{Z_{X_1}^2 \cdot Z_{X_2}^2 \cdot Z_{X_3}^3 \cdot Z_{X_4}^1 \cdot Z_{X_5}^1}$$

Partition Function



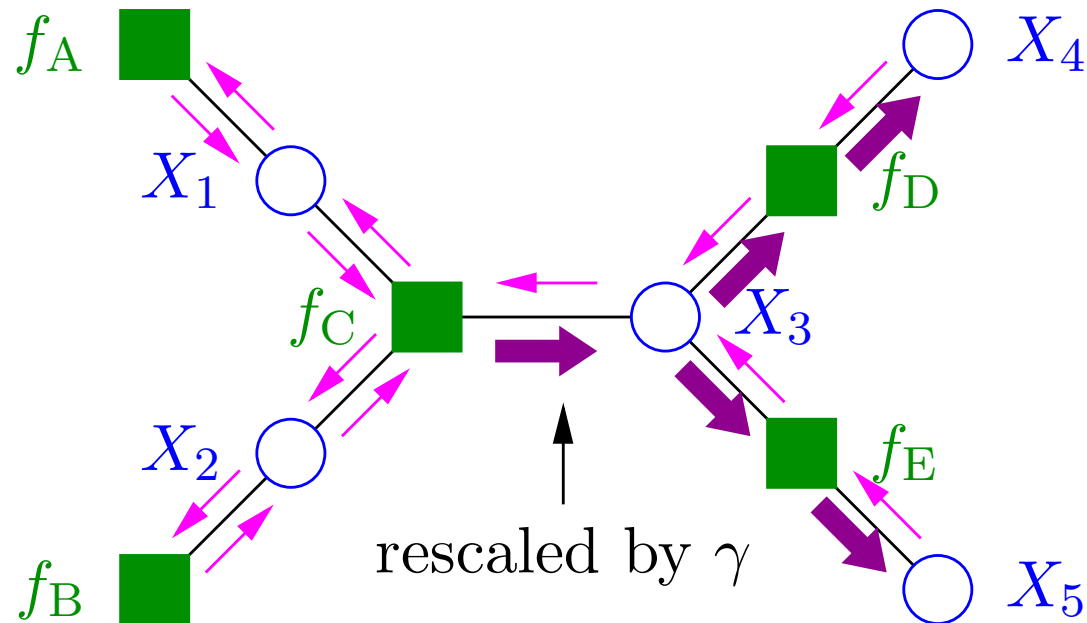
$$Z = \frac{Z_{f_A} \cdot Z_{f_B} \cdot Z_{f_C} \cdot Z_{f_D} \cdot Z_{f_E} \cdot Z_{X_1} \cdot Z_{X_2} \cdot Z_{X_3} \cdot Z_{X_4} \cdot Z_{X_5}}{Z_{X_1}^2 \cdot Z_{X_2}^2 \cdot Z_{X_3}^3 \cdot Z_{X_4}^1 \cdot Z_{X_5}^1}$$

Partition Function



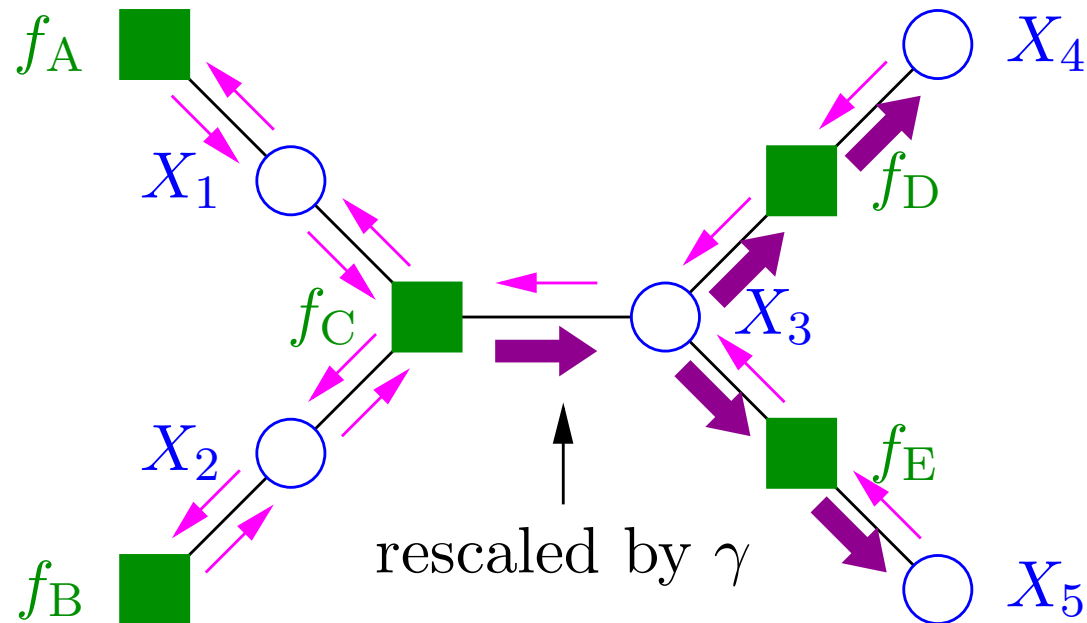
$$Z = \frac{Z_{f_A} \cdot Z_{f_B} \cdot Z_{f_C} \cdot Z_{f_D} \cdot Z_{f_E} \cdot Z_{X_1} \cdot Z_{X_2} \cdot Z_{X_3} \cdot Z_{X_4} \cdot Z_{X_5}}{Z_{X_1}^2 \cdot Z_{X_2}^2 \cdot Z_{X_3}^3 \cdot Z_{X_4}^1 \cdot Z_{X_5}^1}$$

Partition Function



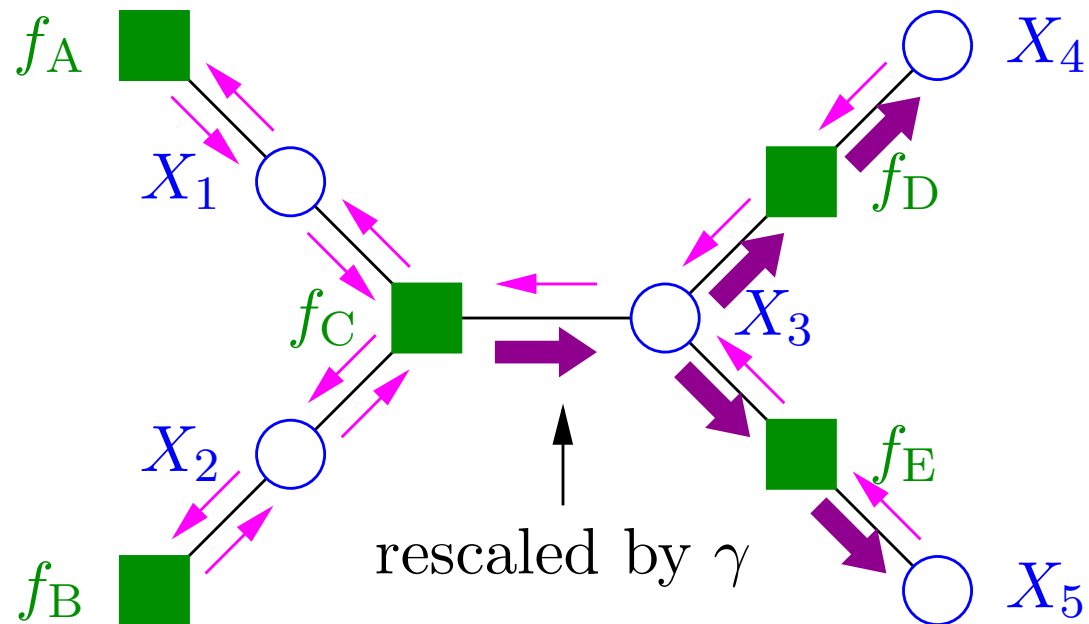
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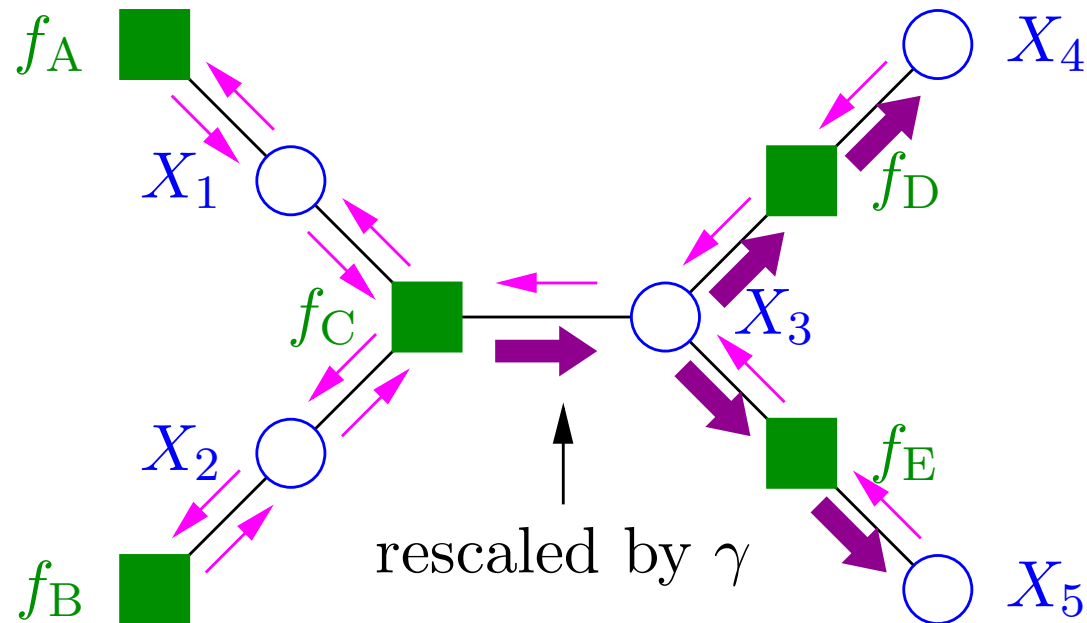
$$Z = \frac{Z_{f_A} \cdot Z_{f_B} \cdot Z_{f_C} \cdot \hat{Z}_{f_D} \cdot \hat{Z}_{f_E} \cdot Z_{X_1} \cdot Z_{X_2} \cdot \hat{Z}_{X_3} \cdot \hat{Z}_{X_4} \cdot \hat{Z}_{X_5}}{Z_{X_1}^2 \cdot Z_{X_2}^2 \cdot \hat{Z}_{X_3}^3 \cdot \hat{Z}_{X_4}^1 \cdot \hat{Z}_{X_5}^1}$$

Partition Function



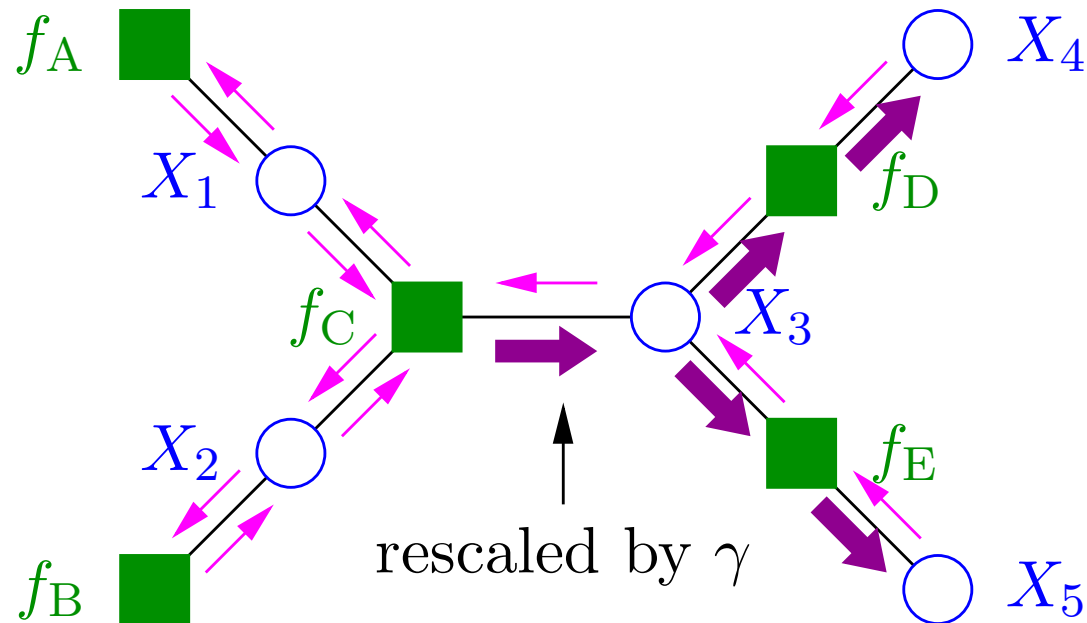
$$Z = \frac{Z_{f_A} \cdot Z_{f_B} \cdot Z_{f_C} \cdot \boxed{\gamma Z_{f_D}} \cdot \boxed{\gamma Z_{f_E}} \cdot Z_{X_1} \cdot Z_{X_2} \cdot \boxed{\gamma Z_{X_3}} \cdot \boxed{\gamma Z_{X_4}} \cdot \boxed{\gamma Z_{X_5}}}{Z_{X_1}^2 \cdot Z_{X_2}^2 \cdot \boxed{\gamma^3 Z_{X_3}^3} \cdot \boxed{\gamma^1 Z_{X_4}^1} \cdot \boxed{\gamma^1 Z_{X_5}^1}}$$

Partition Function



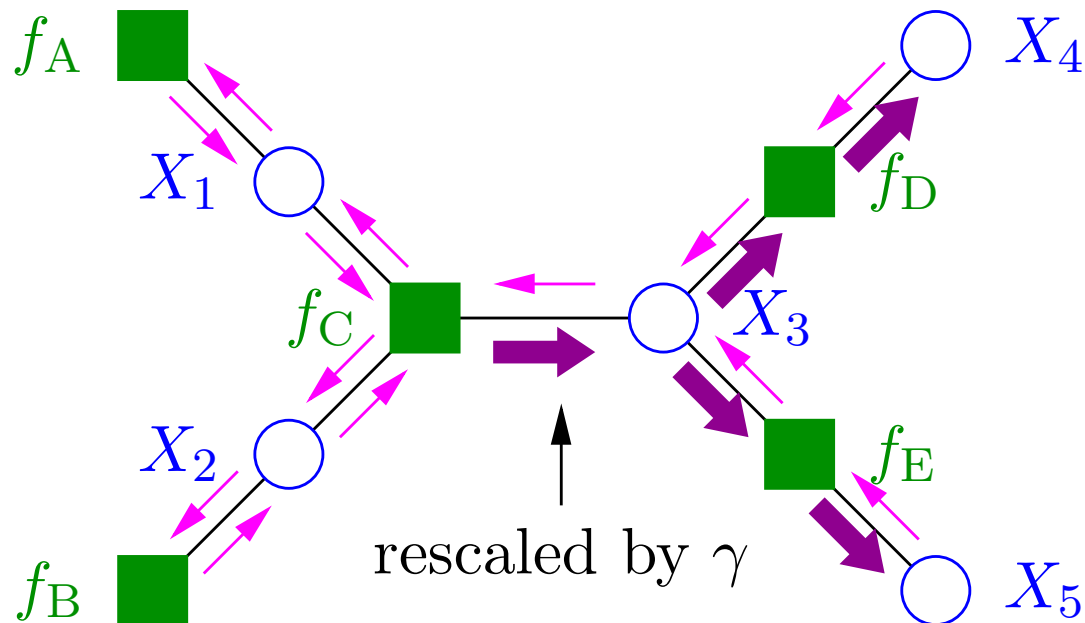
$$Z = \frac{\gamma^5}{\gamma^5} \cdot \frac{Z_{f_A} \cdot Z_{f_B} \cdot Z_{f_C} \cdot Z_{f_D} \cdot Z_{f_E} \cdot Z_{X_1} \cdot Z_{X_2} \cdot Z_{X_3} \cdot Z_{X_4} \cdot Z_{X_5}}{Z_{X_1}^2 \cdot Z_{X_2}^2 \cdot Z_{X_3}^3 \cdot Z_{X_4}^1 \cdot Z_{X_5}^1}$$

Partition Function



$$Z = \frac{Z_{f_A} \cdot Z_{f_B} \cdot Z_{f_C} \cdot Z_{f_D} \cdot Z_{f_E} \cdot Z_{X_1} \cdot Z_{X_2} \cdot Z_{X_3} \cdot Z_{X_4} \cdot Z_{X_5}}{Z_{X_1}^2 \cdot Z_{X_2}^2 \cdot Z_{X_3}^3 \cdot Z_{X_4}^1 \cdot Z_{X_5}^1}$$

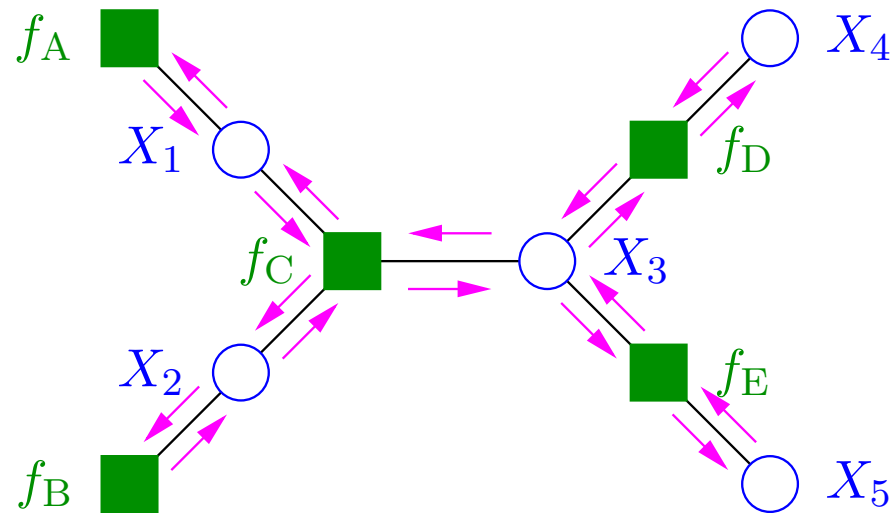
Partition Function



$$Z = \frac{Z_{f_A} \cdot Z_{f_B} \cdot Z_{f_C} \cdot Z_{f_D} \cdot Z_{f_E} \cdot Z_{X_1} \cdot Z_{X_2} \cdot Z_{X_3} \cdot Z_{X_4} \cdot Z_{X_5}}{Z_{X_1}^2 \cdot Z_{X_2}^2 \cdot Z_{X_3}^3 \cdot Z_{X_4}^1 \cdot Z_{X_5}^1}$$

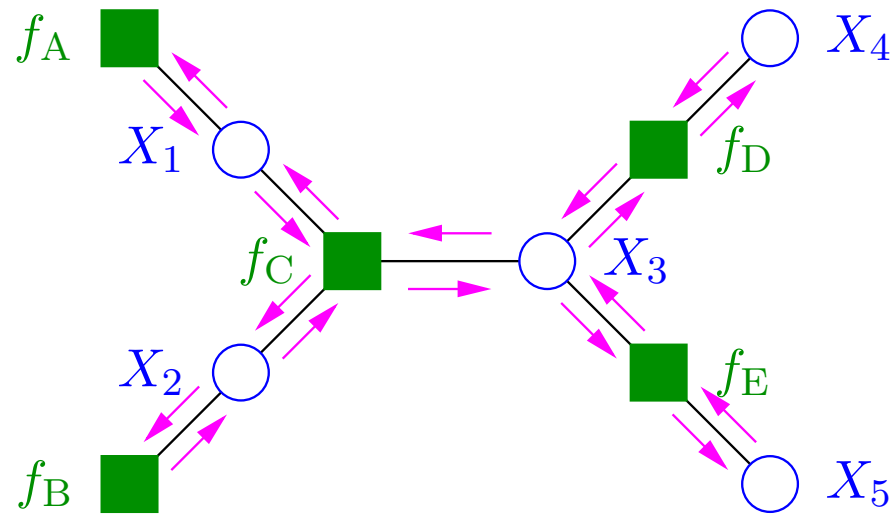
Remarkable: this expression is invariant to rescaling of *function-node-to-variable-node* messages!

Partition Function



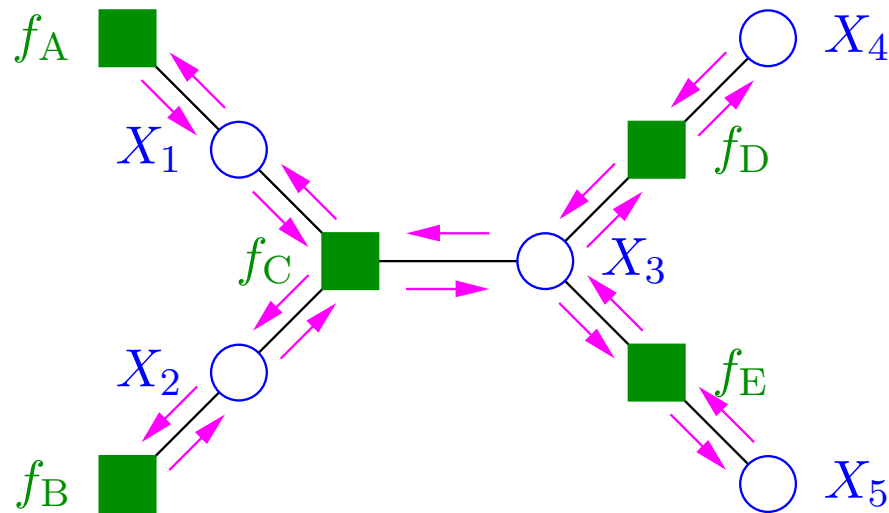
$$Z = \frac{Z_{f_A} \cdot Z_{f_B} \cdot Z_{f_C} \cdot Z_{f_D} \cdot Z_{f_E} \cdot Z_{X_1} \cdot Z_{X_2} \cdot Z_{X_3} \cdot Z_{X_4} \cdot Z_{X_5}}{Z_{X_1}^2 \cdot Z_{X_2}^2 \cdot Z_{X_3}^3 \cdot Z_{X_4}^1 \cdot Z_{X_5}^1}$$

Partition Function



$$Z = \frac{\prod_f Z_f \cdot \prod_X Z_X}{\prod_X Z_X^{\deg(X)}}$$

Partition Function

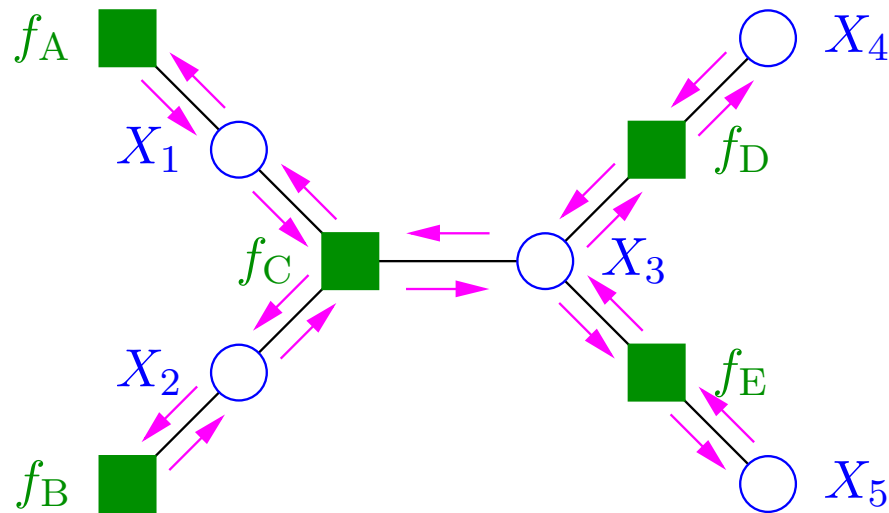


$$Z = \frac{\prod_f Z_f \cdot \prod_X Z_X}{\prod_X Z_X^{\deg(X)}}$$

Bethe approximation:

Use the above type of expression also when factor graph has cycles.

Partition Function



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Bethe approximation:

Use the above type of expression also when factor graph has cycles.

→ Z'_{Bethe}

Bethe Partition Function

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- Basically, we can evaluate the expression for Z'_{Bethe} at any iteration of the SPA.

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We have $Z'_{\text{Bethe}} = Z$ only at a **fixed point** of the SPA.

Bethe Partition Function

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Therefore, we call Z'_{Bethe} a **(local) Bethe partition function** only if we are at a **fixed point of the SPA**.

Bethe Partition Function

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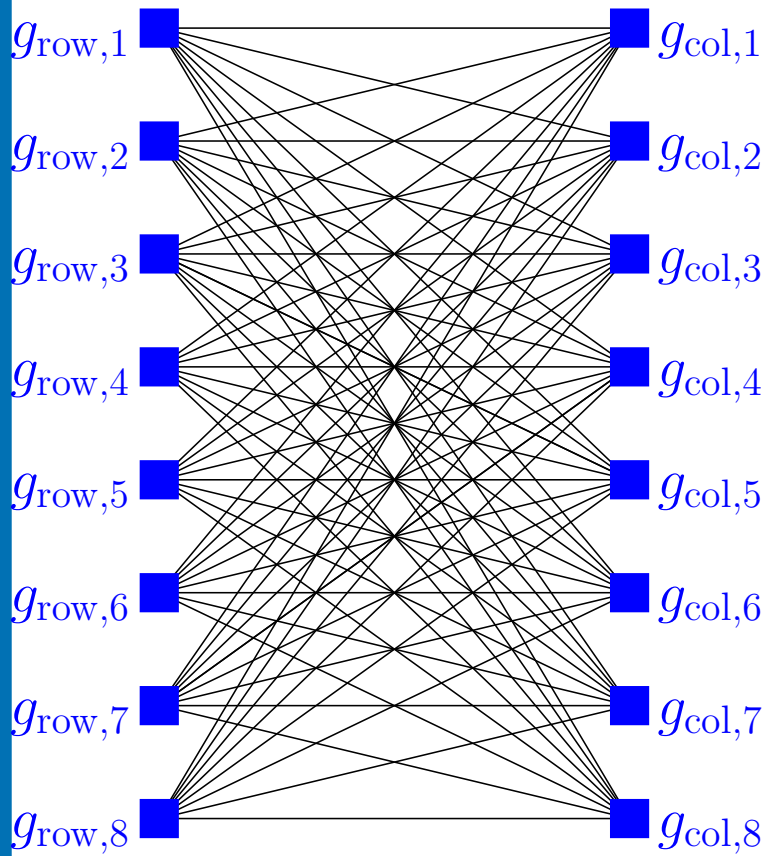
- Factor graph **with cycles**:

Therefore, we call Z'_{Bethe} a **(local) Bethe partition function** only if we are at a **fixed point of the SPA**.

- Factor graph **with cycles**: the SPA can have multiple fixed points. We define the **Bethe partition function** to be

$$Z_{\text{Bethe}} \triangleq \max_{\text{fixed points of SPA}} Z'_{\text{Bethe}}.$$

Graphical Model for Permanent



Global function:

$$\begin{aligned} g(a_{1,1}, \dots, a_{8,8}) \\ &= \prod_j g_{col,j}(a_{1,j}, \dots, a_{8,j}) \times \\ &\quad \prod_i g_{row,i}(a_{i,1}, \dots, a_{i,8}) \end{aligned}$$

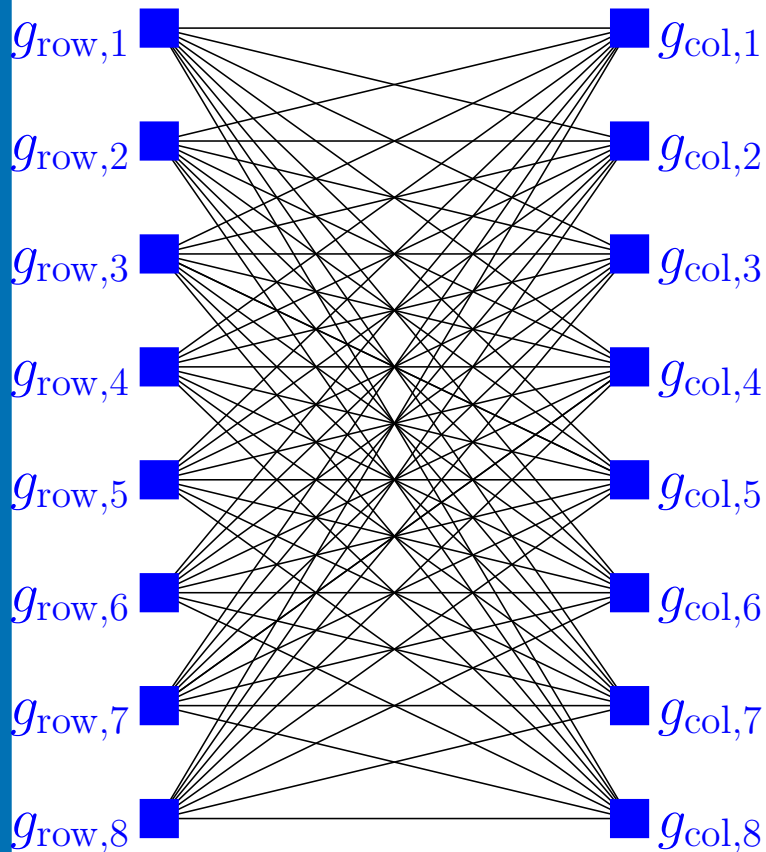
Permanent:

$$\text{perm}(\boldsymbol{\theta}) = Z = \sum_{a_{1,1}, \dots, a_{8,8}} g(a_{1,1}, \dots, a_{8,8})$$

(function nodes are suitably defined based on $\boldsymbol{\theta}$)

(variable nodes have been omitted)

Graphical Model for Permanent



Global function:

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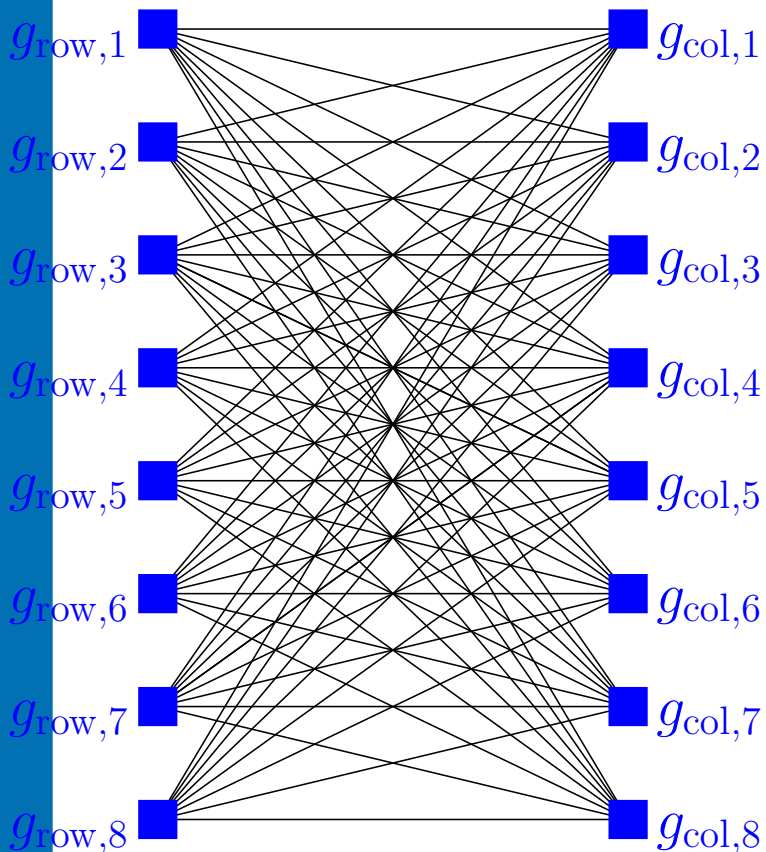
Bethe Permanent:

$$\text{perm}_B(\theta) \triangleq Z_{\text{Bethe}}$$

(function nodes are suitably defined based on θ)

(variable nodes have been omitted)

Graphical Model for Permanent



Global function:

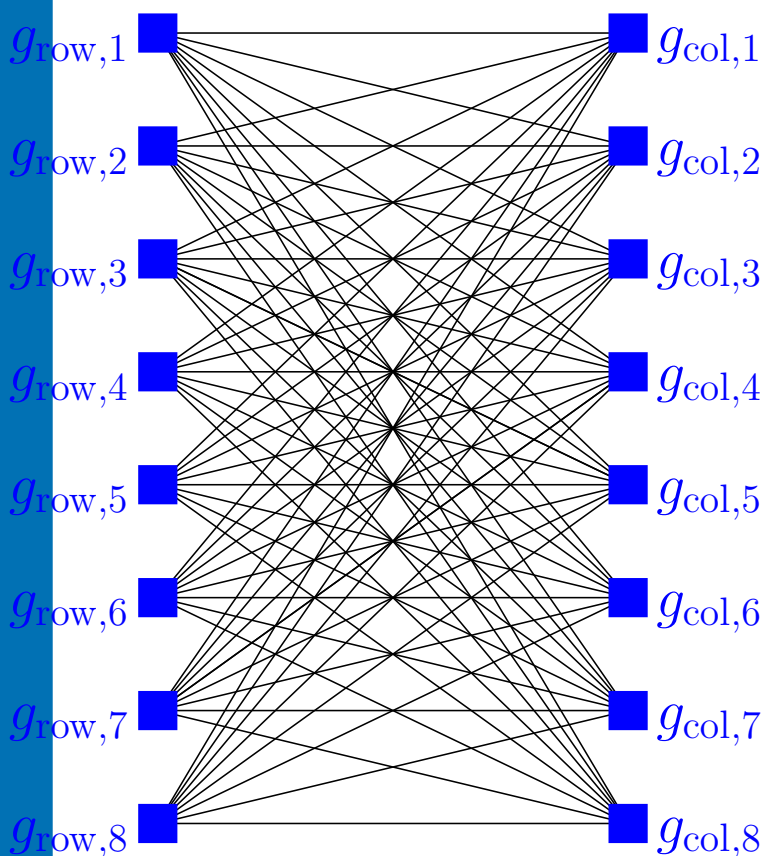
$$\begin{aligned} g(a_{1,1}, \dots, a_{8,8}) \\ &= \prod_j g_{\text{col},j}(a_{1,j}, \dots, a_{8,j}) \times \\ &\quad \prod_i g_{\text{row},i}(a_{i,1}, \dots, a_{i,8}) \end{aligned}$$

Bethe Permanent:

$$\text{perm}_B(\theta) \triangleq Z_{\text{Bethe}}$$

However, the SPA is a *locally operating algorithm* and so has its limitations in the conclusions that it can reach.

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$$\text{perm}_B(\theta) \triangleq Z_{\text{Bethe}}$$

*This locality of the SPA turns out to be well-captured by so-called **finite graph covers**, especially at fixed points of the SPA.*

A combinatorial interpretation of the Bethe permanent

Combinatorial Characterization of the Permanent

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Consider the matrix

$$\boldsymbol{\theta} = \begin{pmatrix} \theta_{1,1} & \theta_{1,2} \\ \theta_{2,1} & \theta_{2,2} \end{pmatrix} \quad \text{with} \quad \text{perm}(\boldsymbol{\theta}) = \theta_{1,1}\theta_{2,2} + \theta_{2,1}\theta_{1,2}.$$

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In particular,

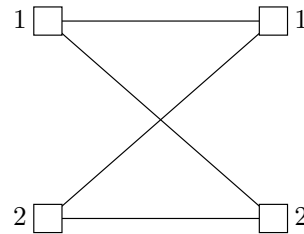
$$\boldsymbol{\theta} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \quad \text{with} \quad \text{perm}(\boldsymbol{\theta}) = 1 \cdot 1 + 1 \cdot 1 = 2.$$

Combinatorial Characterization of the Permanent

Recall that the permanent of a zero/one matrix like

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equals the number of perfect matchings in the following bipartite graph:

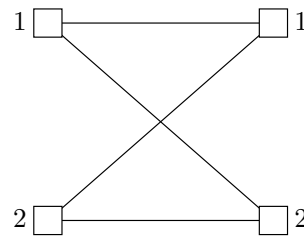


Combinatorial Characterization of the Permanent

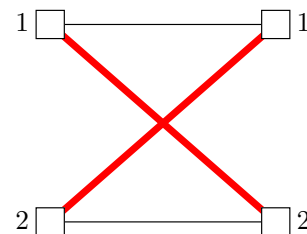
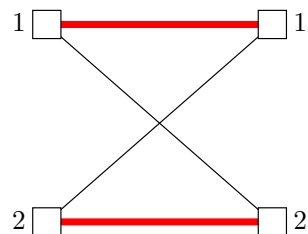
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Namely,



A Combinatorial Interpretation of the Bethe Permanent

- Consider the non-negative matrix θ of size $n \times n$.
- Let $\mathcal{P}_{M \times M}$ be the set of all permutation matrices of size $M \times M$.
- For every positive integer M , we define Ψ_M be the set

$$\Psi_M \triangleq \left\{ \mathbf{P} = \left\{ \mathbf{P}^{(i,j)} \right\}_{(i,j) \in [n]^2} \mid \mathbf{P}^{(i,j)} \in \mathcal{P}_{M \times M} \right\}.$$

- For $\mathbf{P} \in \Psi_M$ we define the \mathbf{P} -lifting of θ to be the following $(nM) \times (nM)$ matrix

$$\theta = \begin{pmatrix} \theta_{1,1} & \cdots & \theta_{1,n} \\ \vdots & & \vdots \\ \theta_{n,1} & \cdots & \theta_{n,n} \end{pmatrix} \xrightarrow[\text{of } \theta]{\mathbf{P}\text{-lifting}} \theta^{\uparrow \mathbf{P}} \triangleq \begin{pmatrix} \theta_{1,1} \mathbf{P}^{(1,1)} & \cdots & \theta_{1,n} \mathbf{P}^{(1,n)} \\ \vdots & & \vdots \\ \theta_{n,1} \mathbf{P}^{(n,1)} & \cdots & \theta_{n,n} \mathbf{P}^{(n,n)} \end{pmatrix}.$$

Degree- M Bethe Permanent

Definition: For any positive integer M , we define the degree- M Bethe permanent of θ to be

$$\text{perm}_{B,M}(\theta) \triangleq \sqrt[M]{\left\langle \text{perm}(\theta^{\uparrow P}) \right\rangle_{P \in \Psi_M}}.$$

Theorem:

$$\text{perm}_B(\theta) = \limsup_{M \rightarrow \infty} \text{perm}_{B,M}(\theta).$$

Special Case:

Deg.- M Bethe Permanent for $n = 2$

We want to obtain some appreciation why the Bethe permanent of θ is close to the permanent of θ , and where the differences are.

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Special Case: Deg.- M Bethe Permanent for $n = 2$

For this θ , a \mathbf{P} -lifting looks like

$$\theta^{\uparrow \mathbf{P}} = \begin{pmatrix} 1 \cdot \mathbf{P}_{1,1} & 1 \cdot \mathbf{P}_{1,2} \\ 1 \cdot \mathbf{P}_{2,1} & 1 \cdot \mathbf{P}_{2,2} \end{pmatrix} = \begin{pmatrix} \mathbf{P}_{1,1} & \mathbf{P}_{1,2} \\ \mathbf{P}_{2,1} & \mathbf{P}_{2,2} \end{pmatrix}.$$

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Applying some row and column permutations, we obtain

$$\text{perm}(\theta^{\uparrow \mathbf{P}}) = \text{perm} \begin{pmatrix} \mathbf{I} & & & \mathbf{I} \\ & & & \\ & & \mathbf{P}_{2,1}^{-1} \mathbf{P}_{2,2} \mathbf{P}_{1,2}^{-1} \mathbf{P}_{1,1} & \\ & & & \end{pmatrix}.$$

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Therefore,

$$\text{perm}_{\mathbf{B},M}(\theta) \triangleq \sqrt[M]{\left\langle \text{perm} \begin{pmatrix} \mathbf{I} & \mathbf{I} \\ \mathbf{I} & \mathbf{P}'_{2,2} \end{pmatrix} \right\rangle_{\mathbf{P}'_{2,2} \in \mathcal{P}_{M \times M}}}.$$

Special Case: Degree-2 Bethe Permanent for $n = 2$

For $M = 2$ we have

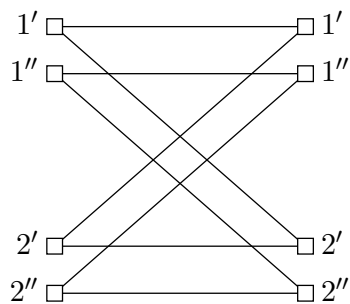
$$\text{perm}_{B,2}(\theta) \triangleq \sqrt[2]{\left\langle \text{perm} \begin{pmatrix} \mathbf{I} & \mathbf{I} \\ \mathbf{I} & \mathbf{P}'_{2,2} \end{pmatrix} \right\rangle_{\mathbf{P}'_{2,2} \in \mathcal{P}_{2 \times 2}}}$$

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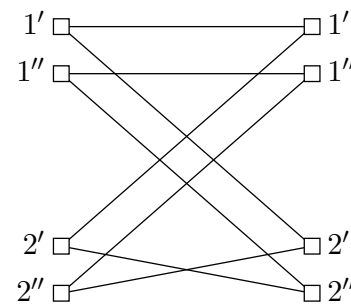
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corresponds to computing the average number of perfect matchings in the following 2-covers (and taking the 2nd root):



4



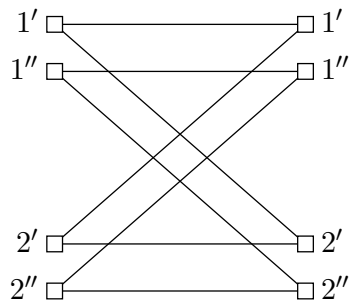
2

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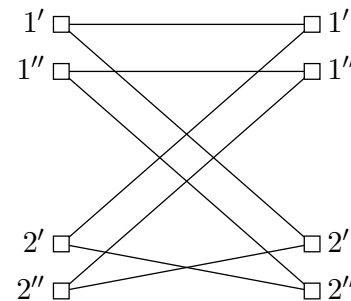
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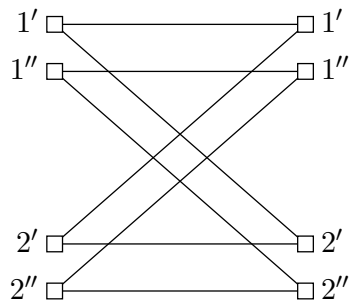
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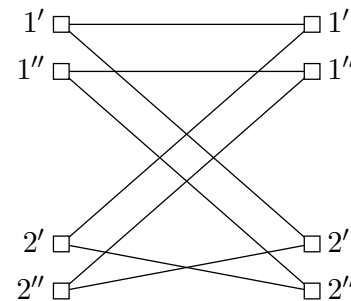
For $M = 2$ we have

$$\begin{aligned}\text{perm}_{B,2}(\theta) &= \sqrt[2]{\frac{1}{2!} \cdot (4 + 2)} \\ &= \sqrt[3]{\frac{1}{2!} \cdot 6} = \sqrt[2]{3} \approx 1.732\end{aligned}$$

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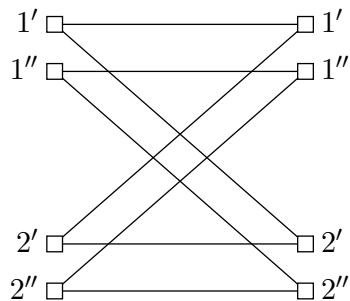
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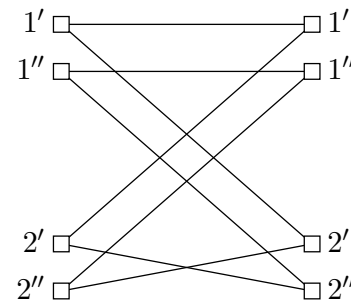
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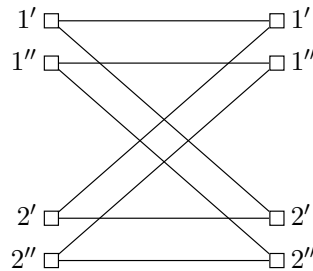
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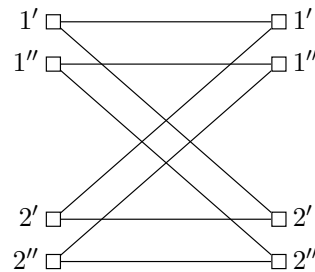
Special Case: Degree-2 Bethe Permanent for $n = 2$

Let us have a closer look at the perfect matchings in the graph

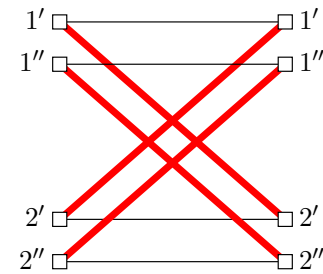
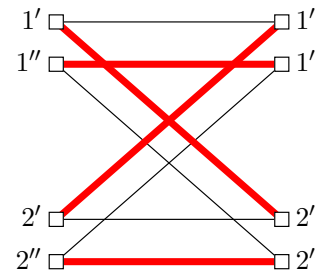
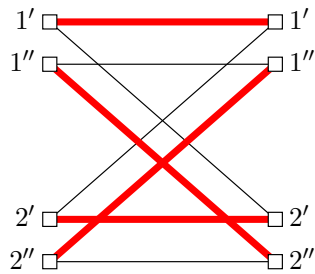
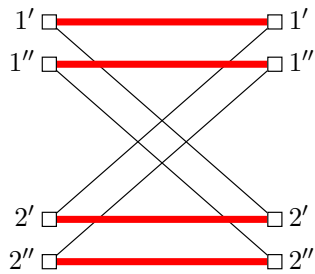


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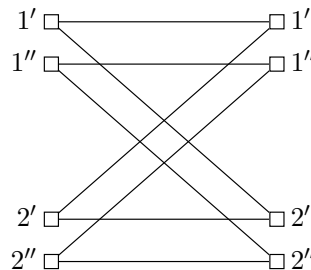


For this graph, the perfect matchings are

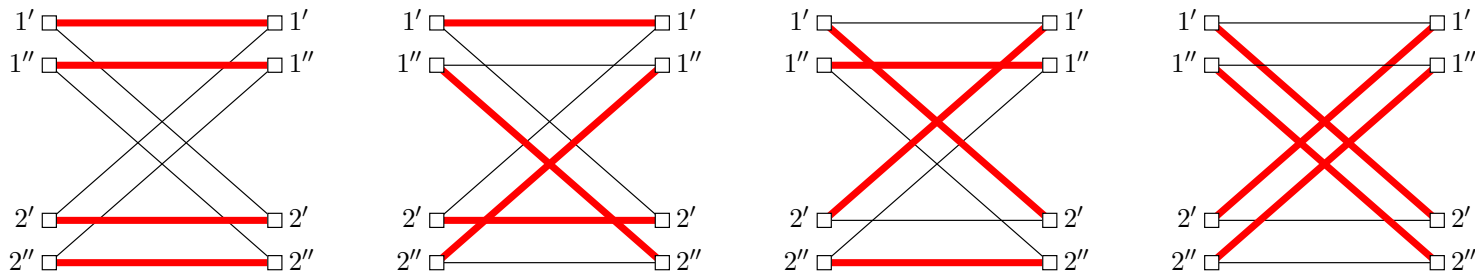


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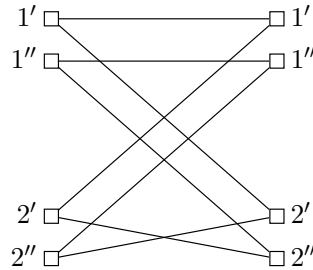
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Because this double cover consists of two **independent copies** of the base graph, the number of perfect matchings is $2^2 = 4$.

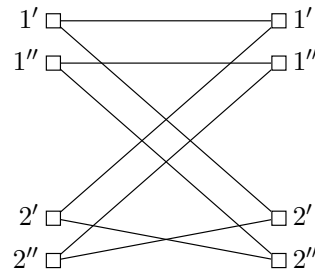
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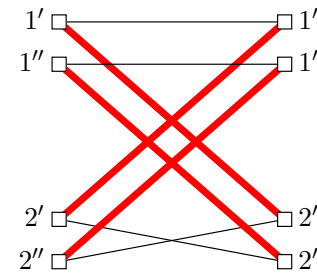
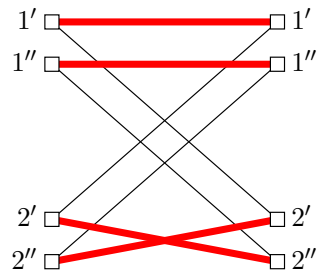


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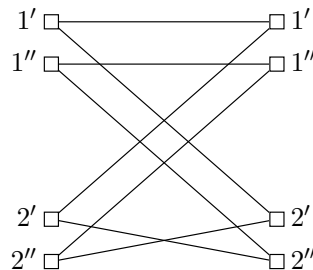


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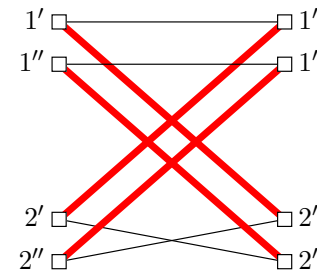
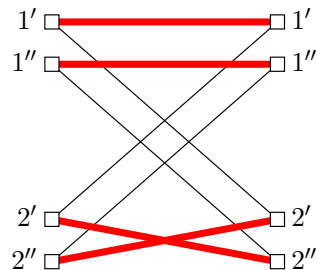


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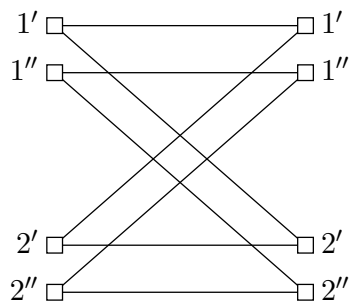
The **coupling of the cycles** causes this graph to have fewer than 2^2 perfect matchings!

Special Case: Degree-2 Bethe Permanent for $n = 2$

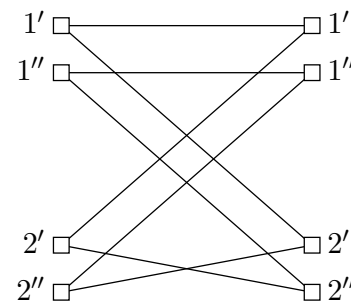
On the other hand, for $M = 2$ we have

$$\begin{aligned}\text{perm}_{\text{B},2}(\boldsymbol{\theta}) &= \sqrt[2]{\frac{1}{2!} \cdot (4 + 2)} \\ &= \sqrt[3]{\frac{1}{2!} \cdot 6} = \sqrt[2]{3} \approx 1.732 < \sqrt[2]{4} = 2 = \text{perm}(\boldsymbol{\theta})\end{aligned}$$

corresponds to computing the average number of perfect matchings in the following 2-covers (and taking the 2nd root):



4



2

Special Case:

Degree-3 Bethe Permanent for $n = 2$

On the other hand, for $M = 3$ we have

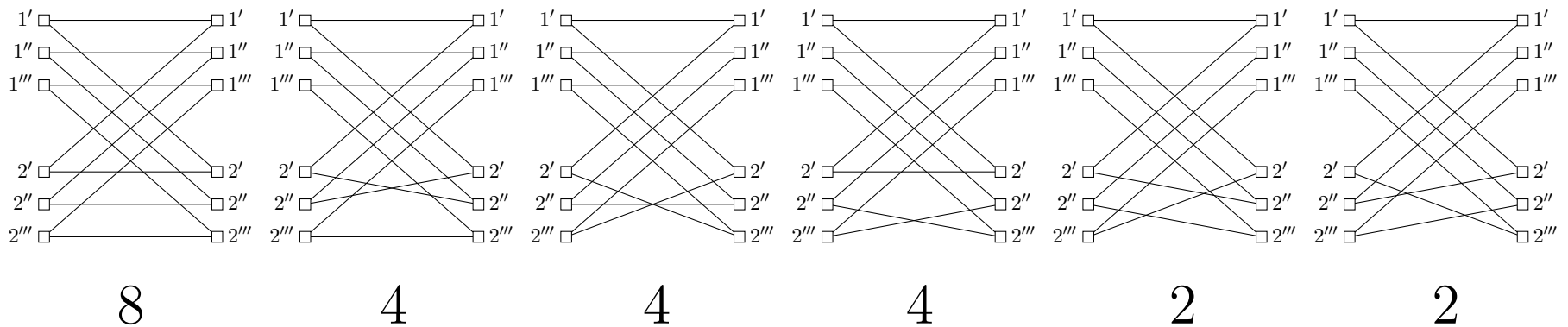
$$\text{perm}_{B,3}(\theta) \triangleq \sqrt[3]{\left\langle \text{perm} \begin{pmatrix} \mathbf{I} & \mathbf{I} \\ \mathbf{I} & \mathbf{P}'_{2,2} \end{pmatrix} \right\rangle_{\mathbf{P}'_{2,2} \in \mathcal{P}_{3 \times 3}}}$$

Special Case: Degree-3 Bethe Permanent for $n = 2$

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corresponds to computing the average number of perfect matchings in the following 3-covers (and taking the 3rd root):

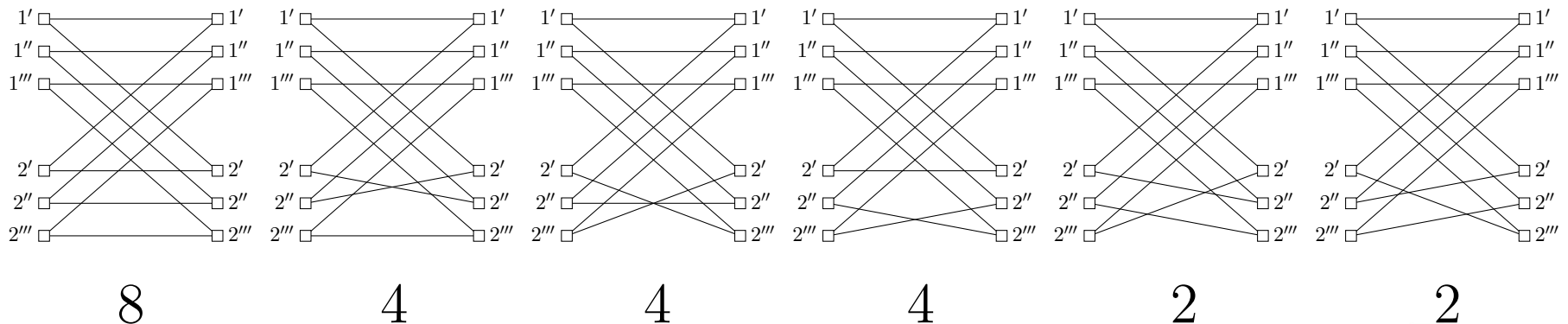


Special Case: Degree-3 Bethe Permanent for $n = 2$

On the other hand, for $M = 3$ we have

$$\text{perm}_{B,3}(\theta) = \sqrt[3]{\frac{1}{3!} \cdot (8 + 4 + 4 + 4 + 2 + 2)}$$

corresponds to computing the average number of perfect matchings in the following 3-covers (and taking the 3rd root):

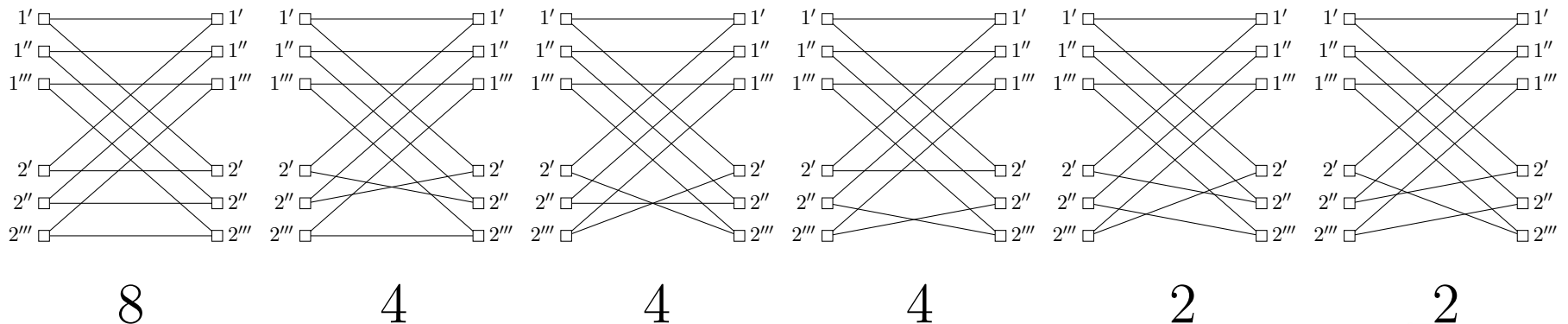


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$$\begin{aligned} \text{perm}_{B,3}(\theta) &= \sqrt[3]{\frac{1}{3!} \cdot (8 + 4 + 4 + 4 + 2 + 2)} \\ &= \sqrt[3]{\frac{1}{3!} \cdot 24} = \sqrt[3]{4} \approx 1.587 \end{aligned}$$

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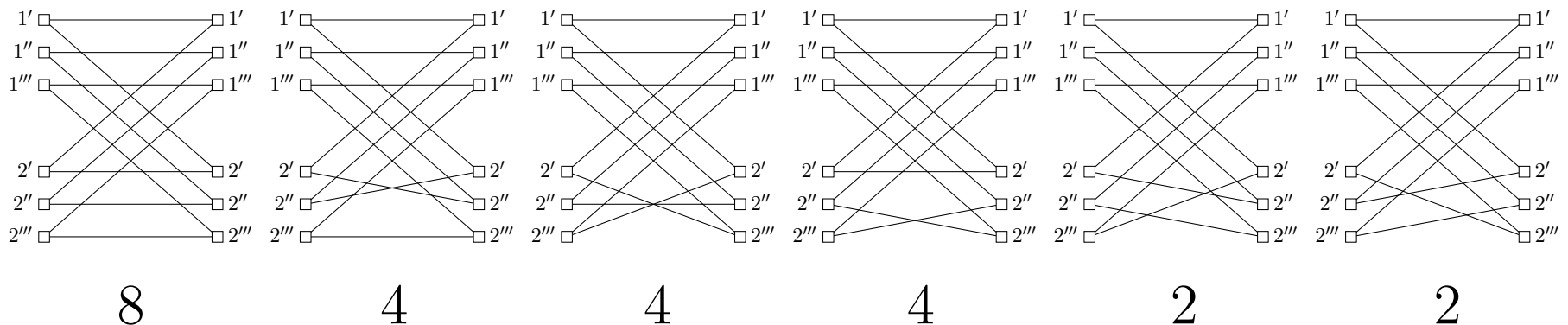


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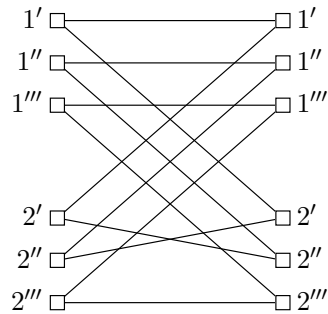
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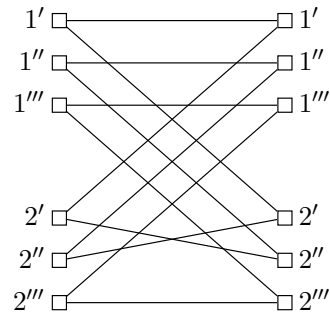
Special Case: Degree-3 Bethe Permanent for $n = 2$

Let us have a closer look at the perfect matchings in the graph

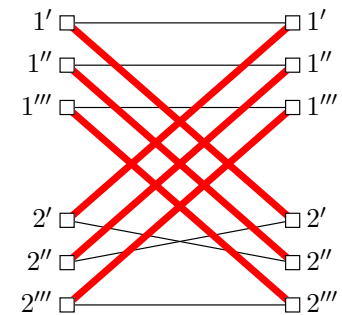
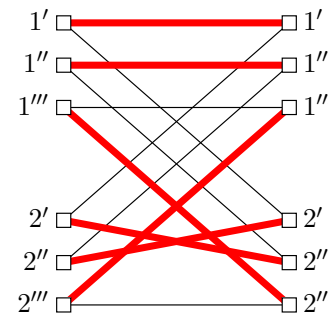
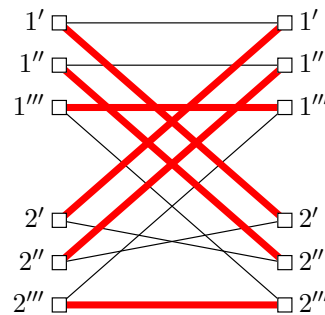
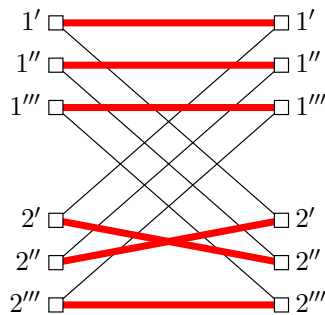


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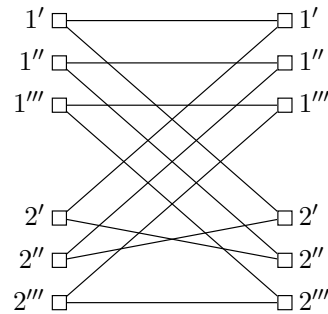


For this graph, the perfect matchings are

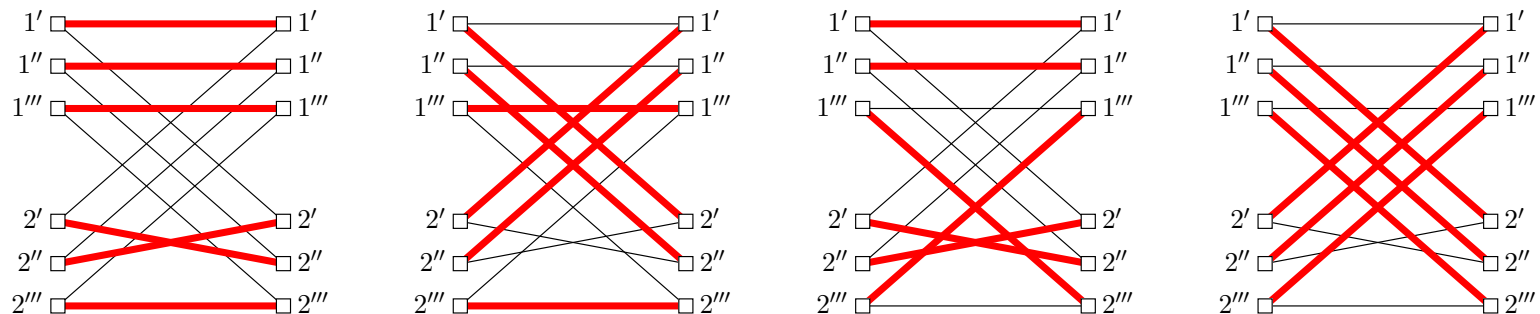


Special Case: Degree-3 Bethe Permanent for $n = 2$

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For this graph, the perfect matchings are



The **coupling of the cycles** causes this graph to have fewer than 2^3 perfect matchings!

Special Case: Deg.- M Bethe Permanent for $n = 2$

For general M we obtain

$$\text{perm}_{\text{B},M}(\boldsymbol{\theta}) = \sqrt[M]{\zeta_{S_M}} = \sqrt[M]{M+1},$$

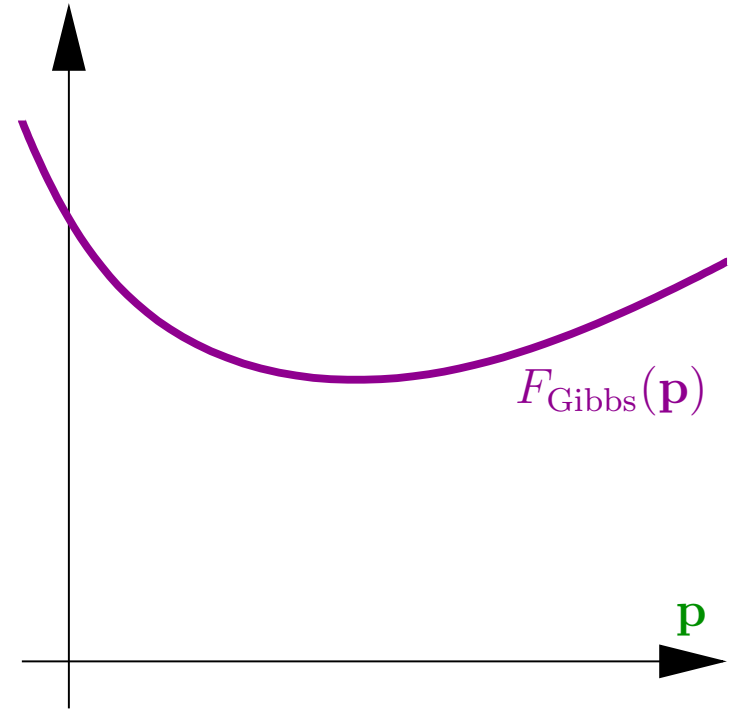
ζ_{S_M} : cycle index of the symmetric group over M elements.

The Gibbs free energy function

Gibbs Free Energy Function

The Gibbs free energy function

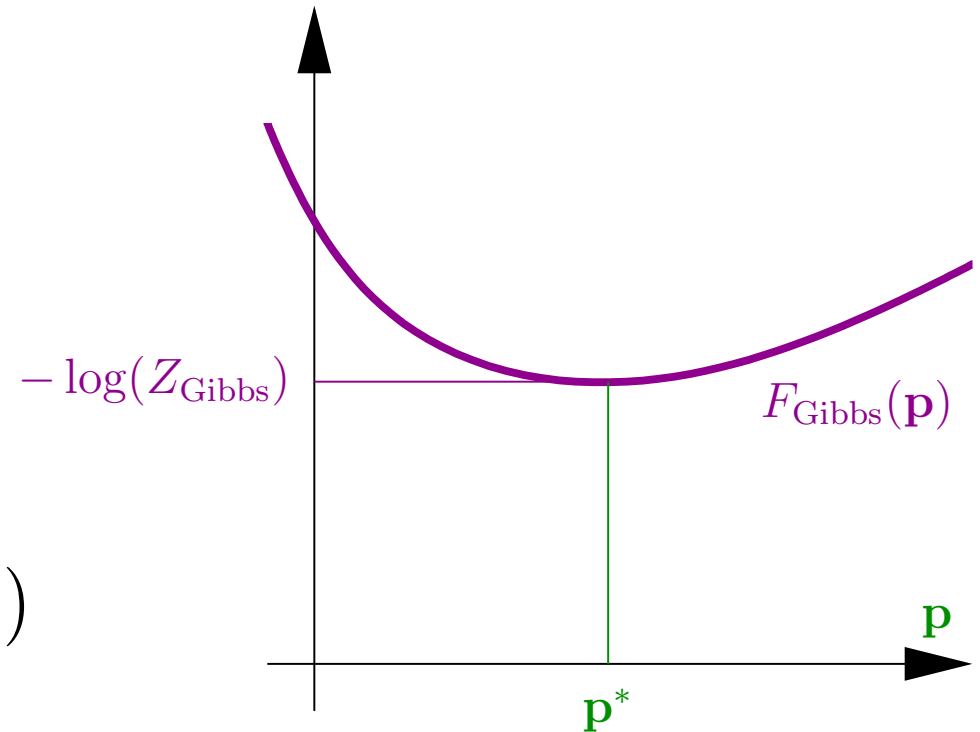
$$F_{\text{Gibbs}}(\mathbf{p}) \triangleq - \sum_{\mathbf{a}} p_{\mathbf{a}} \cdot \log(g(\mathbf{a})) \\ + \sum_{\mathbf{a}} p_{\mathbf{a}} \cdot \log(p_{\mathbf{a}}).$$



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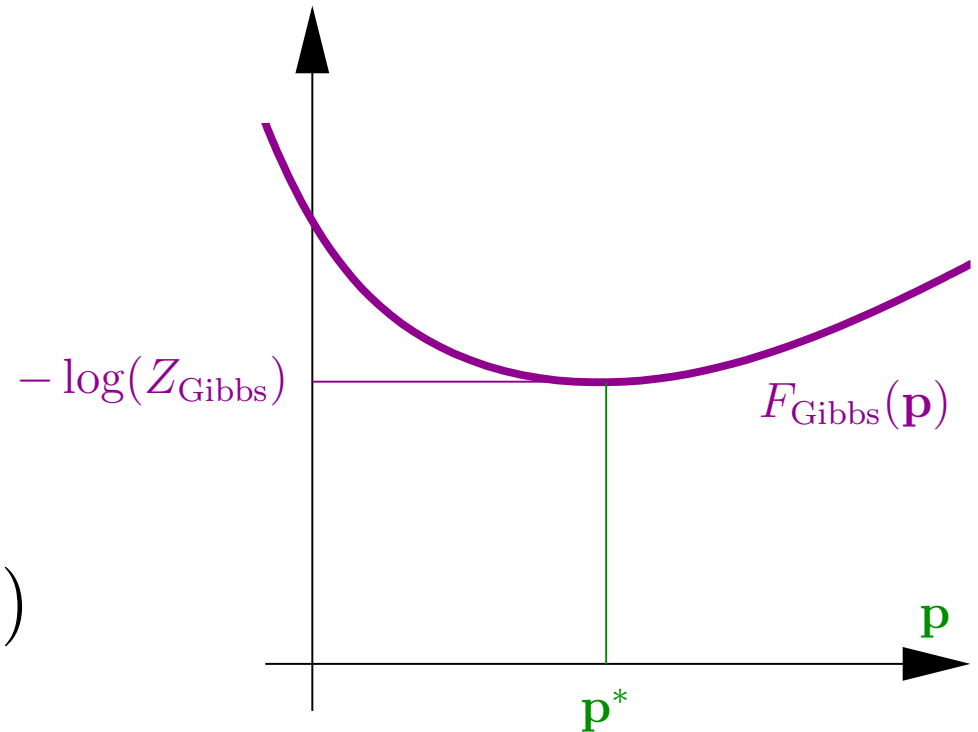
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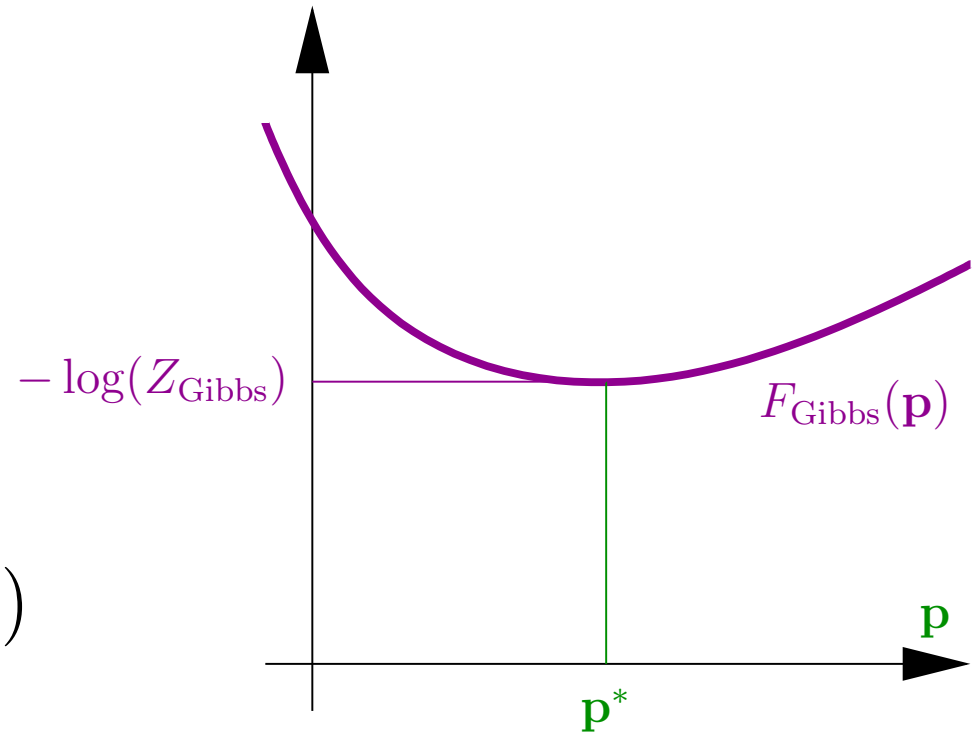
is defined such that its minimal value is related to the partition function:

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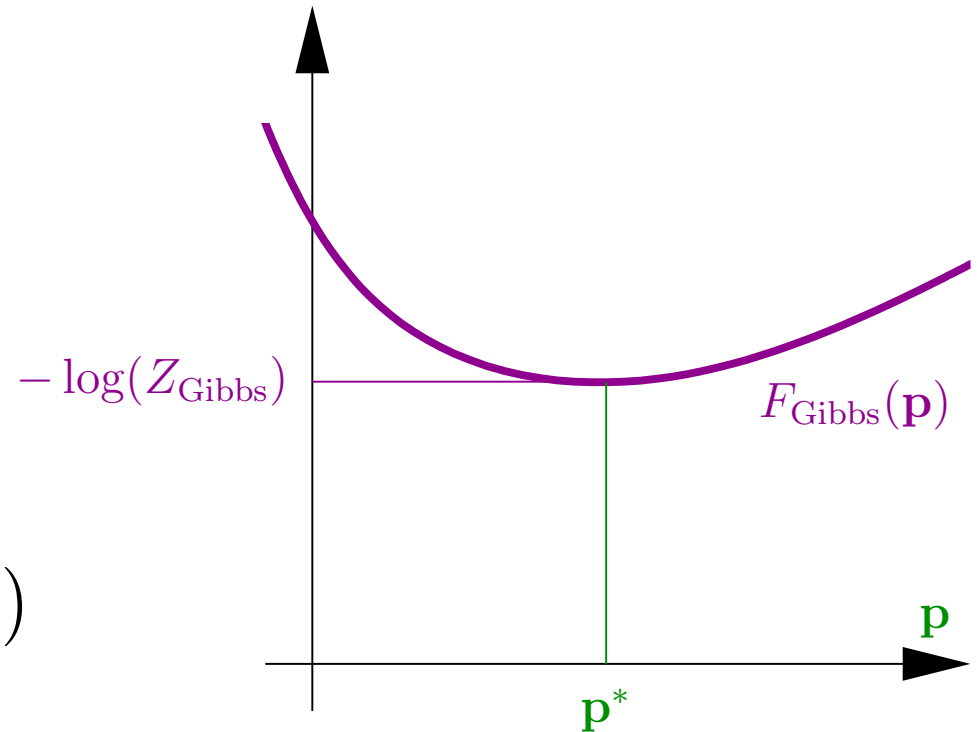
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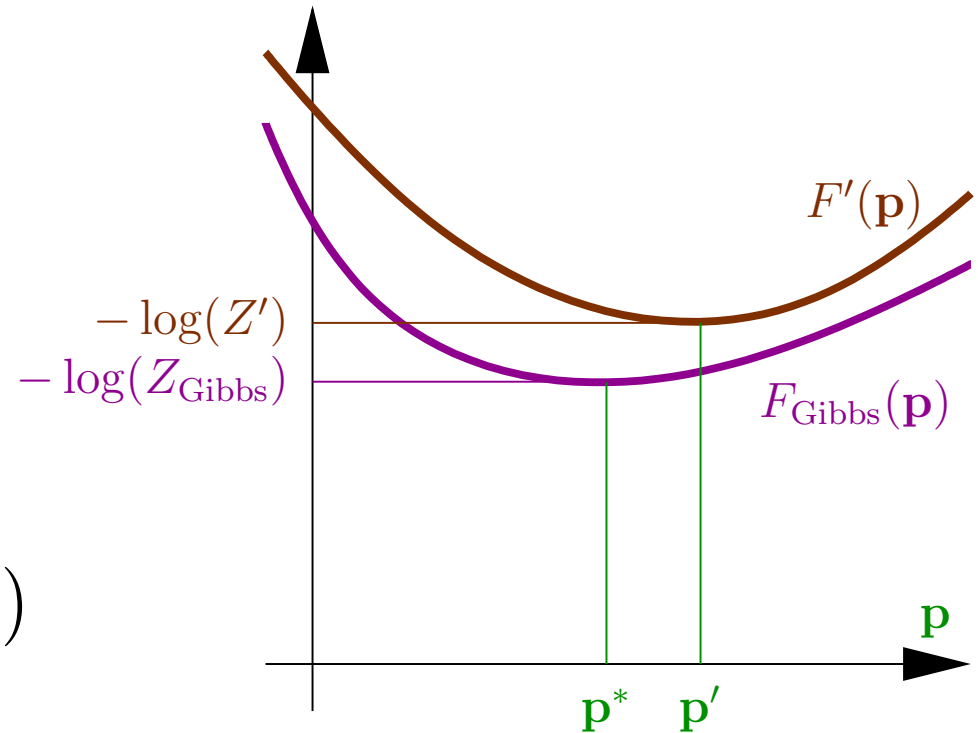


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Nice, but it does not yield any computational savings by itself.

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But it suggests other optimization schemes.

The Bethe approximation

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Theorem (Yedidia/Freeman/Weiss, 2000):

Fixed points of the sum-product algorithm (SPA) correspond to stationary points of the Bethe free energy function.

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Fixed points of the sum-product algorithm (SPA) correspond to stationary points of the Bethe free energy function.

Definition: We define the Bethe permanent of θ to be

$$\text{perm}_B(\theta) = Z_{\text{Bethe}} = \exp \left(- \min_{\beta} F_{\text{Bethe}}(\beta) \right).$$

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- The Bethe free energy function **might have multiple local minima**.
- It is **unclear how close** the (global) minimum of the Bethe free energy is to the minimum of the Gibbs free energy.
- It is **unclear if the sum-product algorithm converges** (even to a local minimum of the Bethe free energy).

Bethe Approximation

Luckily, in the case of the permanent approximation problem, the above-mentioned **normal factor graph $N(\theta)$** is such that the Bethe free energy function is **very well behaved**. In particular, one can show that:

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- The **minimum of the Bethe free energy is quite close** to the minimum of the Gibbs free energy. (*More details later.*)
- The **sum-product algorithm converges** to the minimum of the Bethe free energy. (*More details later.*)

Relationship between Permanent and Bethe Permanent

Theorem (Gurvits, 2011)

$$\text{perm}_B(\boldsymbol{\theta}) \leq$$

↓
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$$\text{perm}(\boldsymbol{\theta})$$

Conjecture (Gurvits, 2011)

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$$\text{perm}_B(\boldsymbol{\theta}) \leq \text{perm}(\boldsymbol{\theta}) \leq \sqrt{2}^n \cdot \text{perm}_B(\boldsymbol{\theta})$$

This can be rewritten as follows:

Theorem

Conjecture

$$\frac{1}{n} \log \text{perm}_B(\boldsymbol{\theta}) \leq \frac{1}{n} \log \text{perm}(\boldsymbol{\theta}) \leq \frac{1}{n} \log \text{perm}_B(\boldsymbol{\theta}) + \log(\sqrt{2})$$

Relationship between Permanent and Bethe Permanent

Problem: find large classes of random matrices such that w.h.p.

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Sum-Product Algorithm Convergence

Theorem: Modulo some minor technical conditions on the initial messages, **the sum-product algorithm converges** to the (global) minimum of the Bethe free energy function [V., 2010, 2011].

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Comment: the first part of the proof of the above theorem is **very similar** to the SPA convergence proof in

Bayati and Nair, “*A rigorous proof of the cavity method for counting matchings*,” Allerton 2006.

Note that they consider **matchings**, not perfect matchings. (Although the perfect matching case can be seen as a limiting case of the matching setup, the convergence proof of the SPA is incomplete for that case.)

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Note: **One can also give a comb. interpr.** of the Kikuchi part. func.
- Inspired by the approaches mentioned in this talk, Ryuhei Mori recently showed that many **replica method** computations can be simplified and made quite a bit more intuitive.

A 3D rendering of a Möbius strip, colored in a gradient of green from dark to light. The strip is twisted and looped, creating a continuous surface. The text "Thank you!" is printed in a bold, green, sans-serif font in the center of the loop. The background is a soft, light-colored gradient.

Thank you!

References

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- R. Mori, “Connection between annealed free energy and belief propagation on random factor graph ensembles,” Proc. ISIT 2011, St. Petersburg, Russia, Jul. 31 – Aug. 5, arxiv: 1102.3132.

