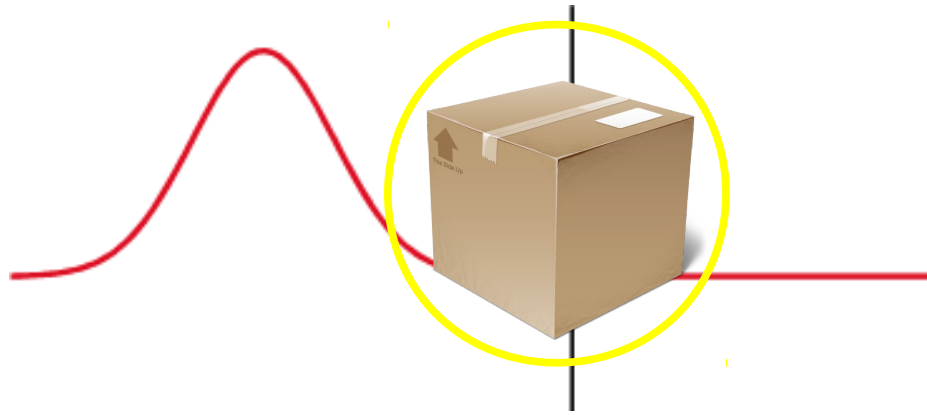


# Toward RF-Based Material Detection



Alejandro Perez

# Toward RF-Based Material Detection



# Related Work

## Radar Cross-Section:

[1] Paul Saville. Review of radar absorbing materials. Technical report, DTIC Document, 2005.

## Building Materials (Penetration Loss, Reflection coefficients, Attenuation):

[2] W. C. Stone, NIST Construction Automation Program: Electromagnetic Signal Attenuation in Construction Materials. U.S. Dept. of Commerce, Technology Administration, NIST Gaithersburg, Md, 1997.

## Ground Penetrating Radar:

[3] John H. Bradford. Frequency-dependent attenuation analysis of ground-penetrating radar data. Geophysics, Vol. 72, No. 3, pages J7-J16, 2007.

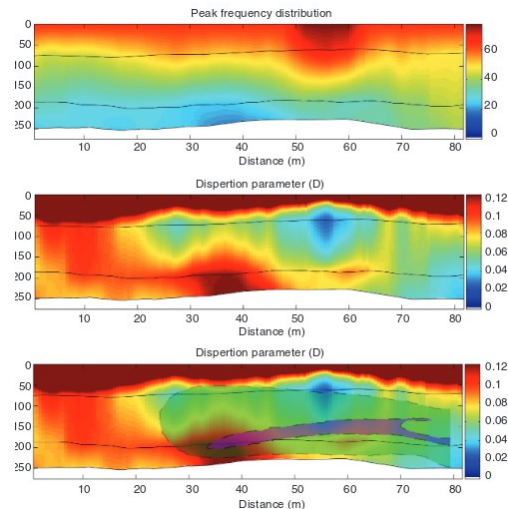
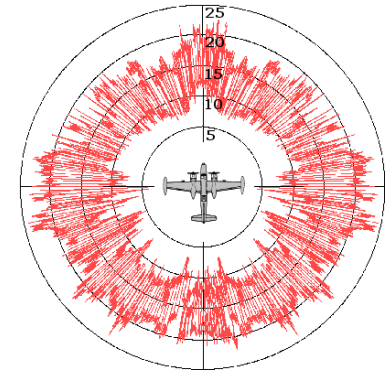
## Backscatter:

[4] Dinesh Bharadia, Kiran Raj Joshi, and Sachin Katti. Full duplex backscatter. In Proceedings of the Twelfth ACM Workshop on Hot Topics in Networks, pages 4:1-4:7, NY, NY, USA, 2013. ACM.

## TTWR RCS/FDTD:

[5] Travis D. Bufler, Ram M. Narayanan, Traian Dogaru. Radar Signatures of indoor clutter for through-the-wall radar. SPIE 9077, Radar Sensor Technology XVIII, 90770E, 2014.

$$P_r = \frac{P_t G_t}{4\pi r^2} \sigma \frac{1}{4\pi r^2} A_{eff}$$



# Toward RF-Based Material Detection

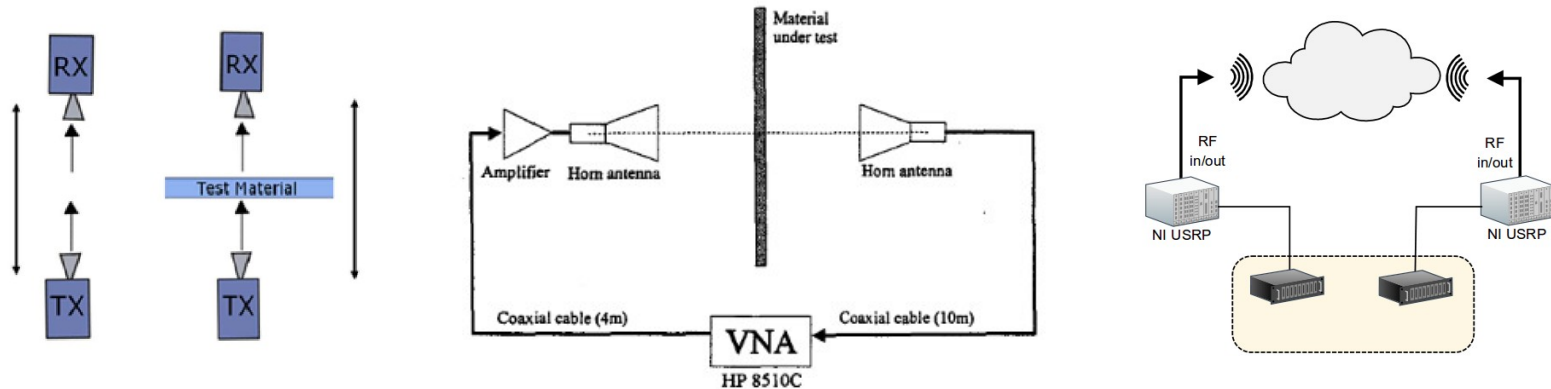


Figure 1: Measurement system set-up

## 45MHz-50GHz

[6] I. Cuinas and M.G. Sanchez. Measurement of transmission coefficients of radiowaves through building materials in the 5.8 ghz frequency band. In Antennas and Propagation Society International Symposium, 1999. IEEE, volume 3, pages 1474-1477 vol.3, July 1999.

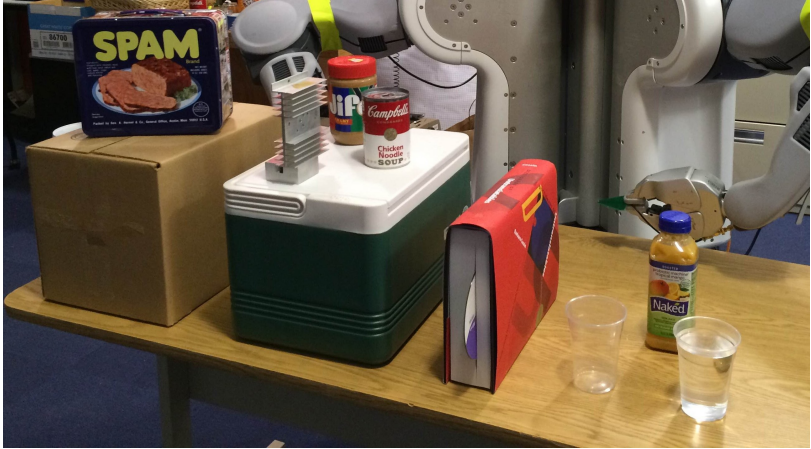
## 869.5 MHz

[7] Martin Tomis, Libor Michalek, and Marek Dvorsky. Design of measurement system for determining the radioclimatology effect on the radio signal propagation using universal software radio. Advances in Electrical and Electronic Engineering, 11(6), 2013.

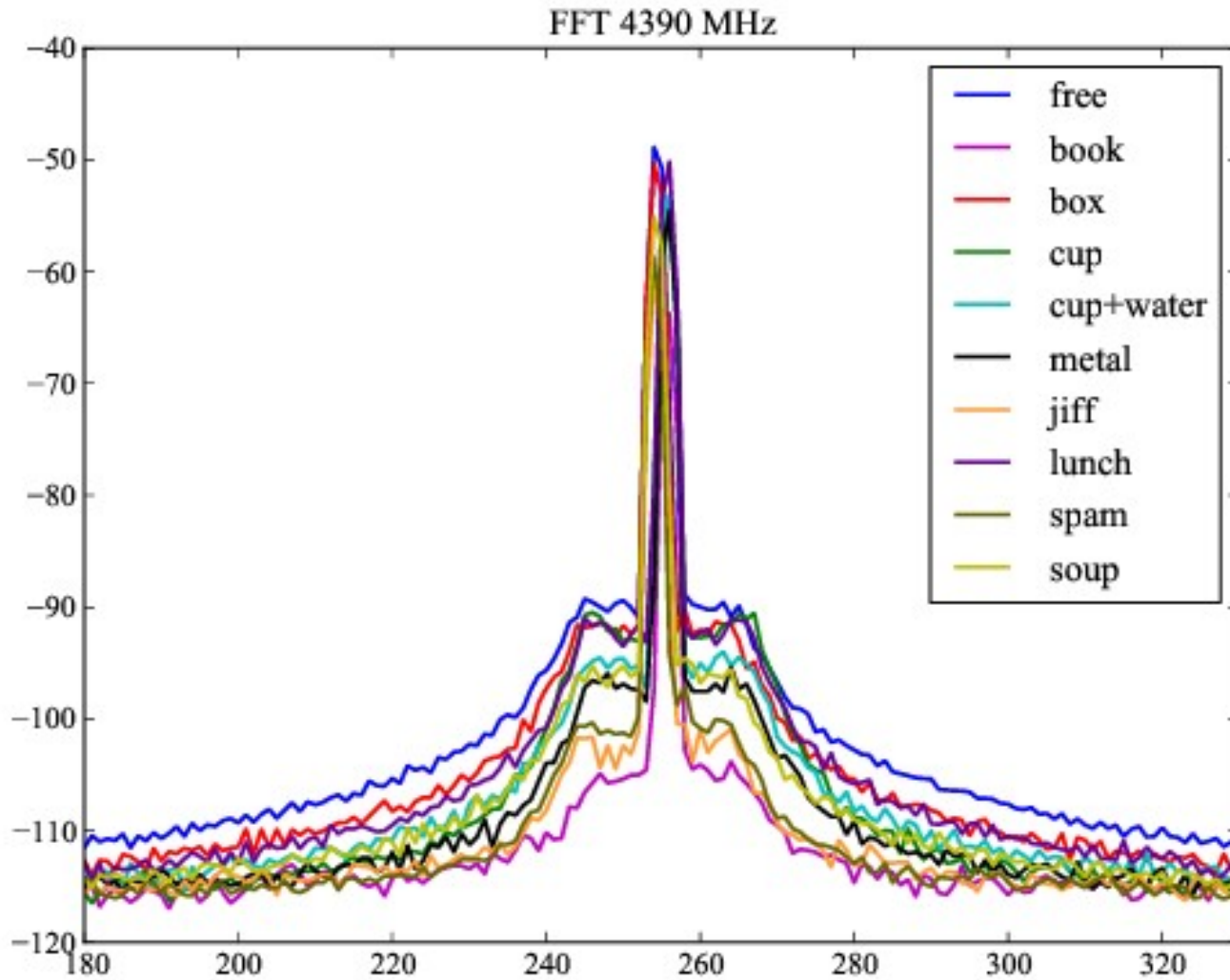
## 28 GHz

[8] H. Zhao, et al. 28 ghz millimeter wave cellular communication measurements for reflection and penetration loss in and around buildings in new york city. In ICC, pages 5163-5167. IEEE, 2013.

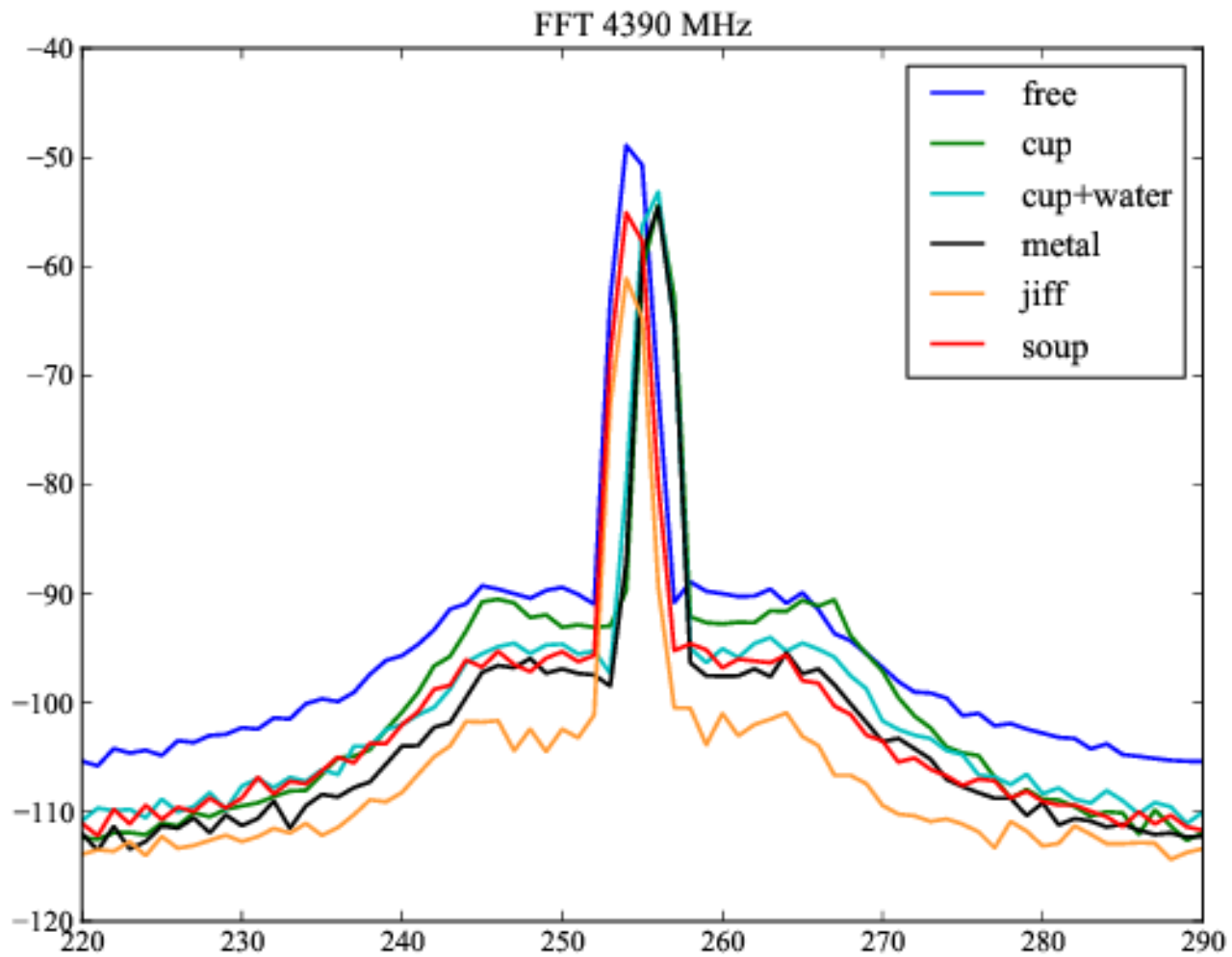
# Transmission Loss



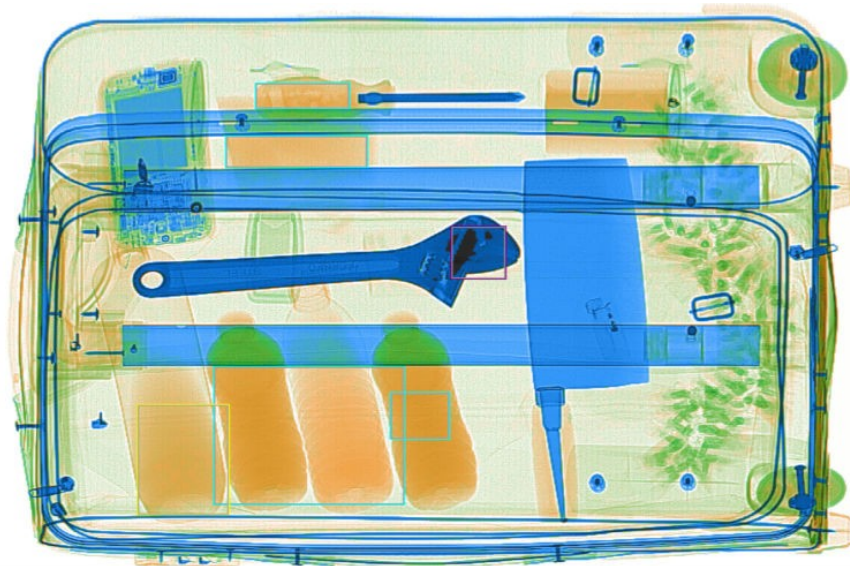
# Transmission Loss



# Transmission Loss



# Scanning





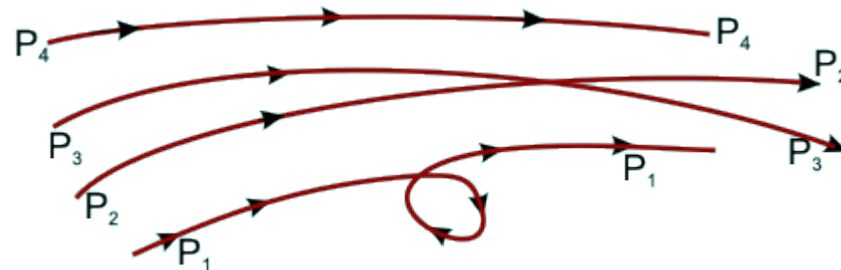
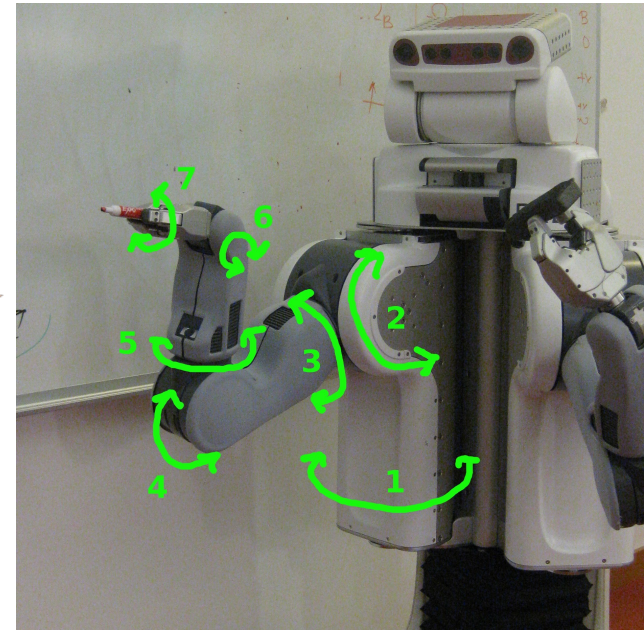
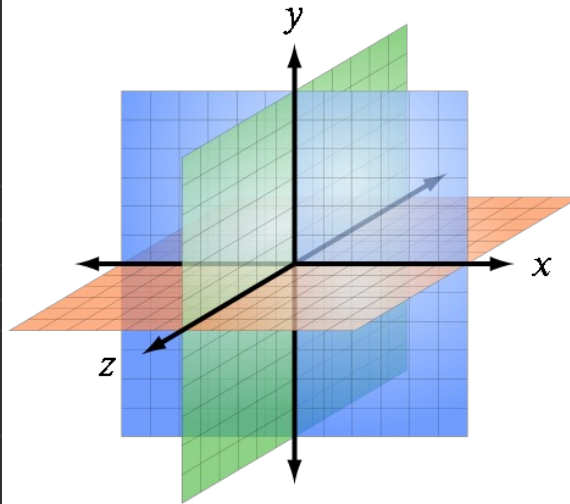
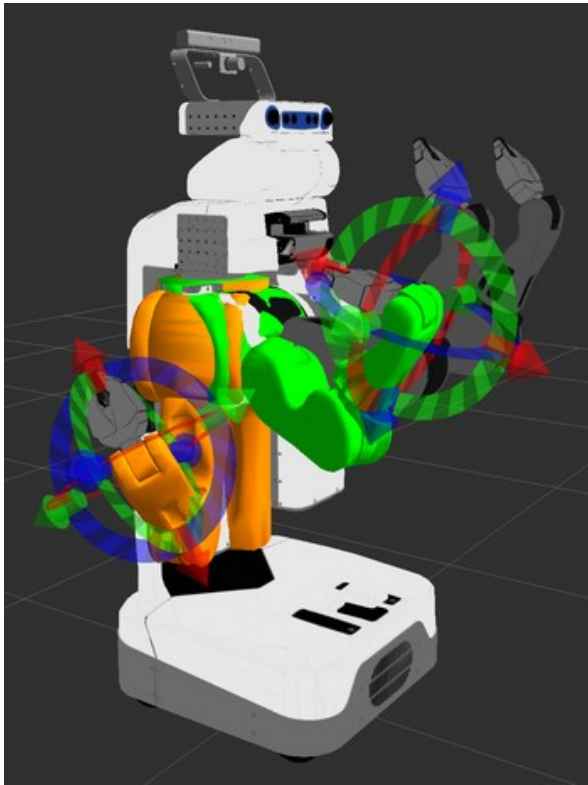
## Scanning: Material-induced Loss

$$\frac{P^{\text{Rx}}}{P^{\text{Tx}}} = G^{\text{Tx}} G^{\text{Rx}} \left( \frac{\lambda}{4\pi d} \right)^2$$

$$P^{\text{Rx}}(d) = P^{\text{Tx}} G^{\text{Tx}} + G^{\text{Rx}} - 20 \log_{10} \left( \frac{4\pi d}{\lambda} \right)$$

$$\mathbb{L} = \bar{P}^{\text{Rx}}(d) - \tilde{P}^{\text{Rx}}(d).$$

# Scanning: Straight-line Trajectories



# Scanning: Straight-line Trajectories

$$j^n = (\theta_1, \theta_2, \theta_3, \dots, \theta_7) \in \mathbb{R}^7,$$

$$q^n = (p, R)$$

$$p^n = (x, y, z)$$

$$R^n = (q_0, q_1, q_2, q_3)$$

$$q = f(j)$$

$$j^{\text{Rx}}, j^{\text{Tx}} : [0, T] \in \mathbb{R}^7$$

$$j^{\text{Rx}}(0), j^{\text{Tx}}(0) = (q_i^{\text{Rx}}, q_f^{\text{Rx}}),$$

$$j^{\text{Rx}}(T), j^{\text{Tx}}(T) = (q_i^{\text{Tx}}, q_f^{\text{Tx}})$$

$$f(j^{\text{Rx}}(0), j^{\text{Tx}}(0)) = q_i^{\text{Rx}}, q_i^{\text{Tx}},$$

$$f(j^{\text{Rx}}(T), j^{\text{Tx}}(T)) = q_f^{\text{Rx}}, q_f^{\text{Tx}}$$

$$\forall f(j^{\text{Rx}}(t), j^{\text{Tx}}(t)) \in [0, T]$$

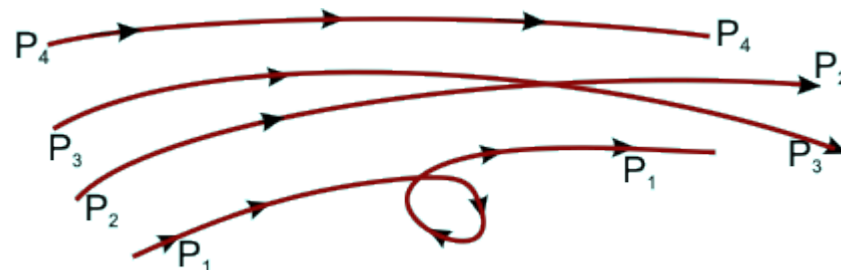
$$(p_x^{\text{Rx}} = p_x^{\text{Tx}}) \wedge (p_z^{\text{Rx}} = p_z^{\text{Tx}})$$

$$p_y^{\text{Rx}} = -p_y^{\text{Tx}}$$

$$|p_y^{\text{Rx}} - p_y^{\text{Tx}}| = d$$

and,

$$\int_0^T \Delta R^{\text{Rx}} + \Delta p_1^{\text{Rx}} + \Delta p_2^{\text{Rx}} = \int_0^T \Delta R^{\text{Tx}} + \Delta p_1^{\text{Tx}} + \Delta p_2^{\text{Tx}} = 0$$



# Scanning: Localized Attenuation

$$\Sigma : [0, T], \sigma(t) = (q(t), \text{DFT}(t))$$

$$S = (s_i, \dots, s_k), d_\Delta = \left(\frac{d_\sigma}{k}\right) \text{ s.t. } q_i \in s_i \text{ and } q_f \in s_k$$

$$s_i := \{\sigma \in \Sigma : s_i^{p3} < q_{p3} < s_i^{p3} + d_\Delta\}$$

$$\bar{S} = (P'_{\bar{s}_i}, \dots, P'_{\bar{s}_k})$$



$$\tilde{S} = (P'_{\tilde{s}_i}, \dots, P'_{\tilde{s}_k})$$



$$S_{\mathbb{L}} = (\mathbb{L}_i = P'_{\bar{s}_i} - P'_{\tilde{s}_i}, \dots, \mathbb{L}_k = P'_{\bar{s}_k} - P'_{\tilde{s}_k})$$



# Scanning



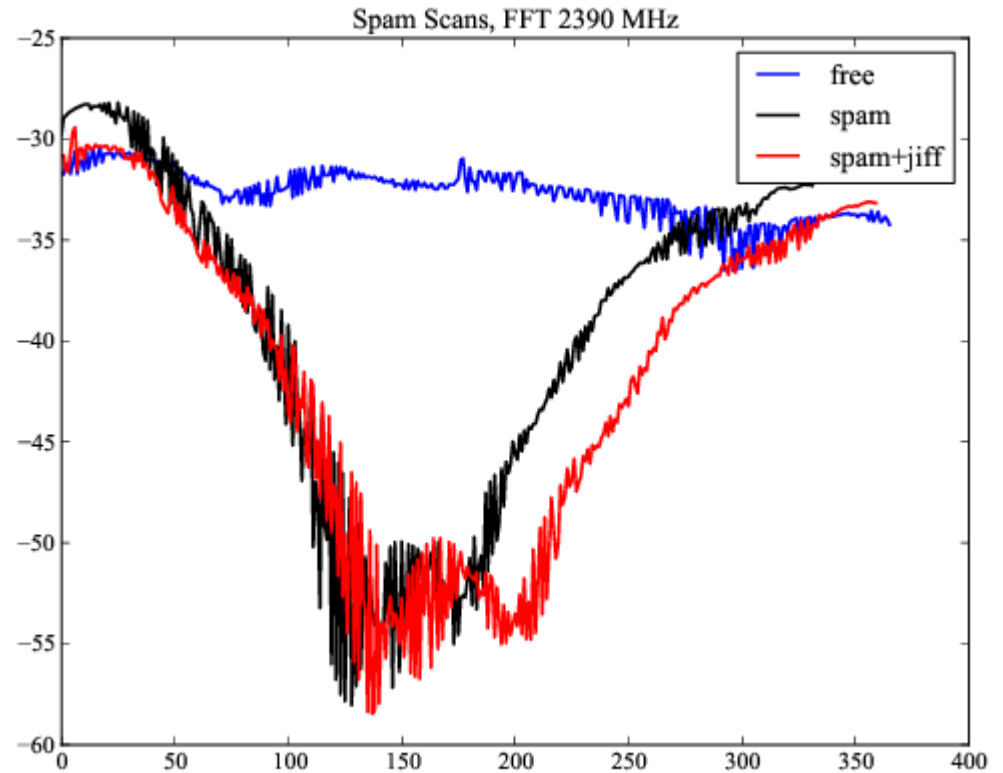
# Scanning



# Scanning

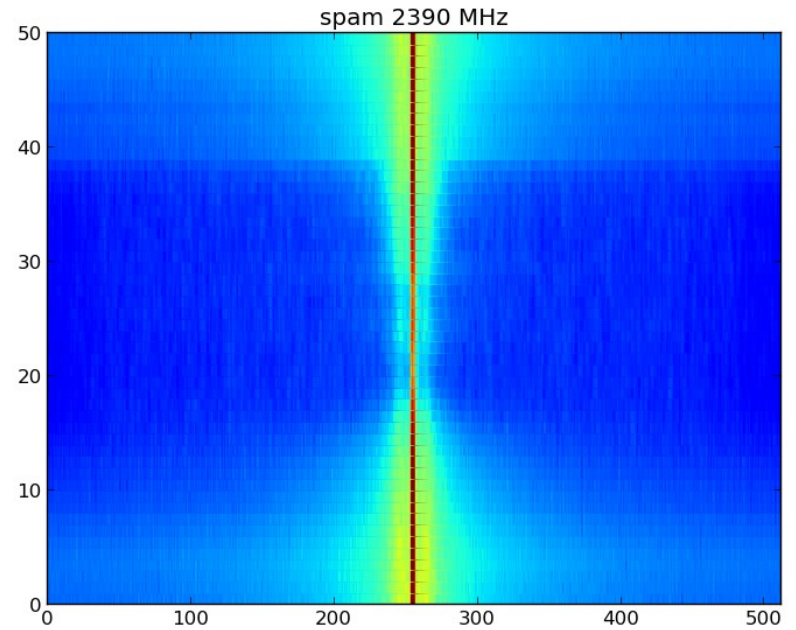
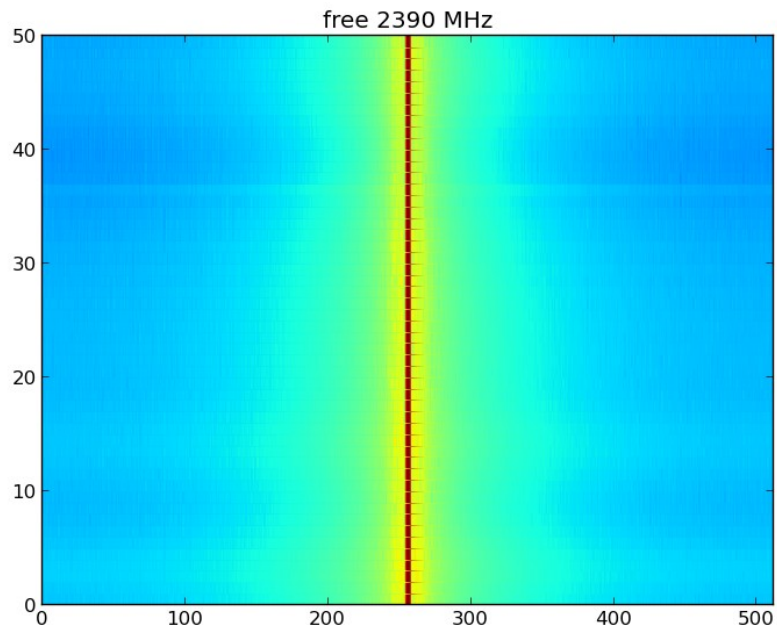


# Scanning: Metallic Lunch Box (2390 MHz)

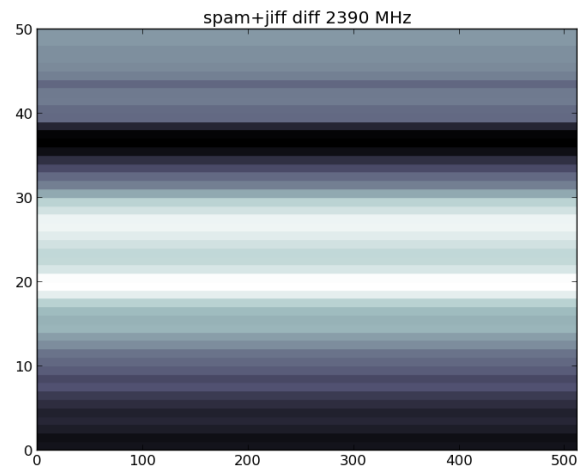
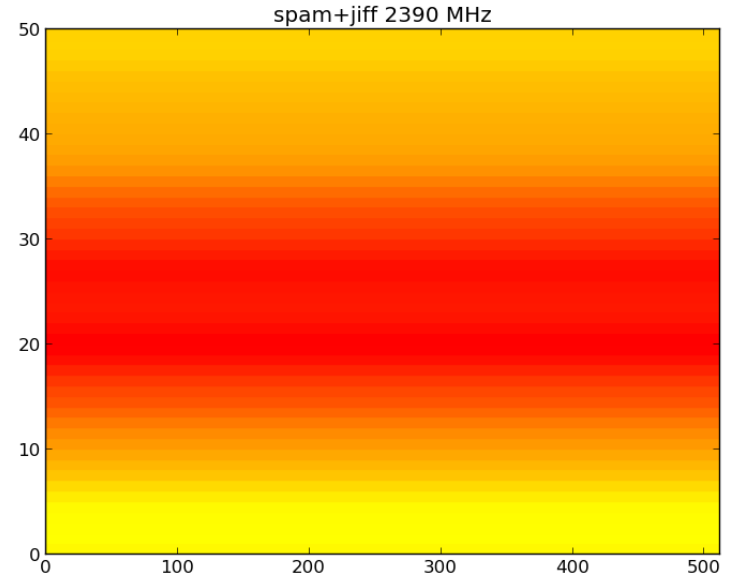
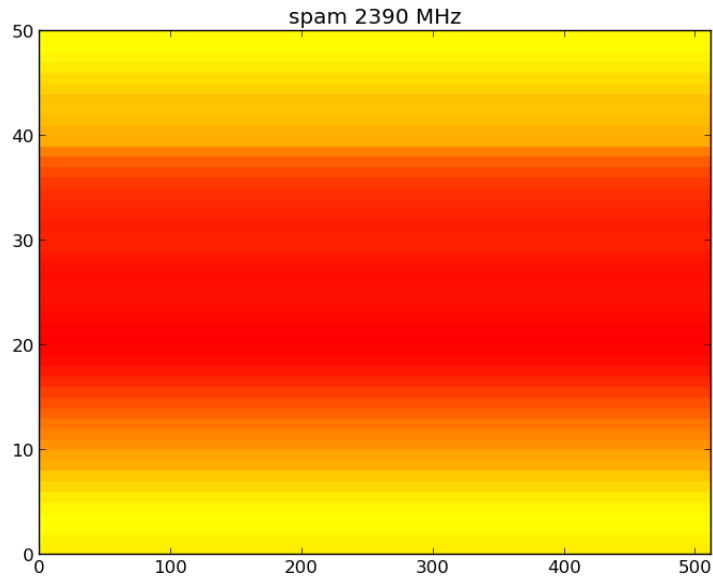




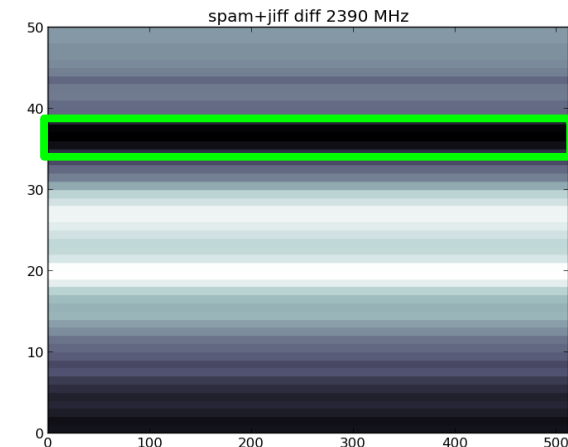
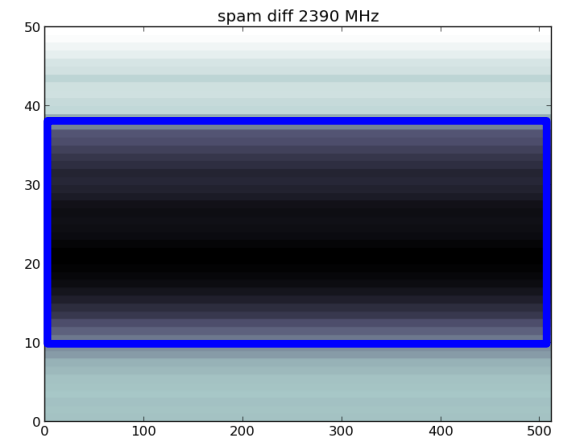
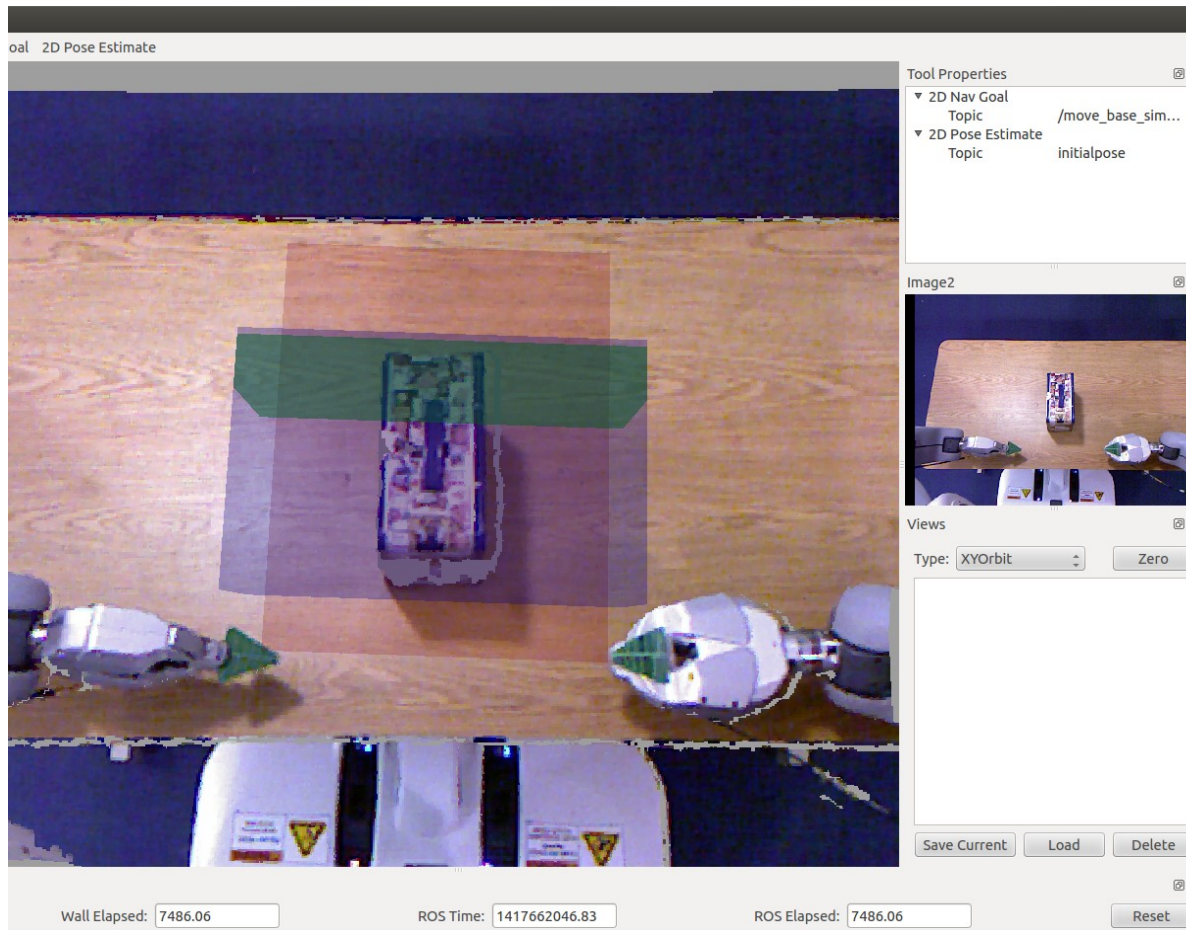
# Scanning: Metallic Lunch Box (2390 MHz)



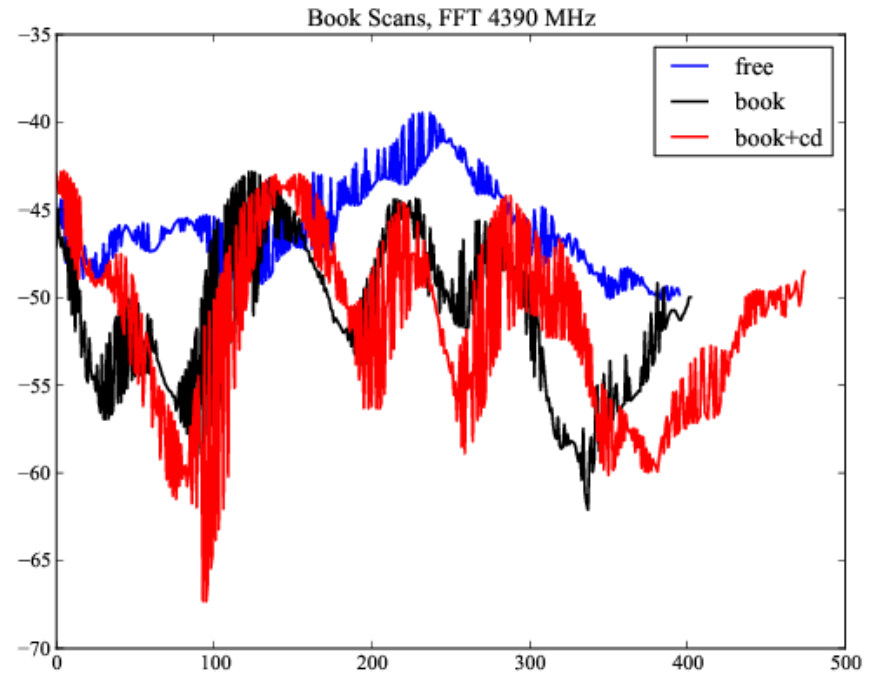
# Scanning: Metallic Lunch Box (2390 MHz)



# Scanning: Metallic Lunch Box (2390 MHz)

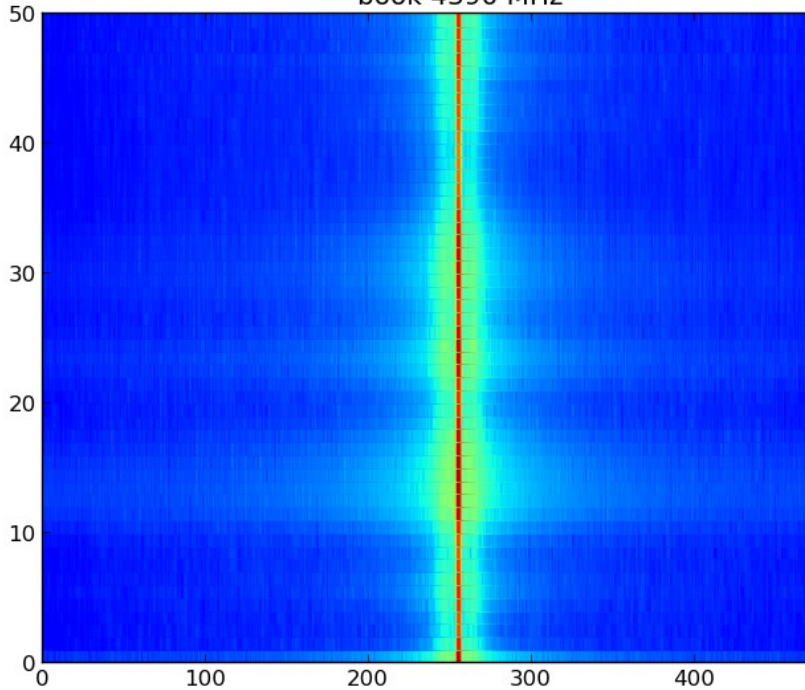


# Scanning: Book + CD (4390 MHz)

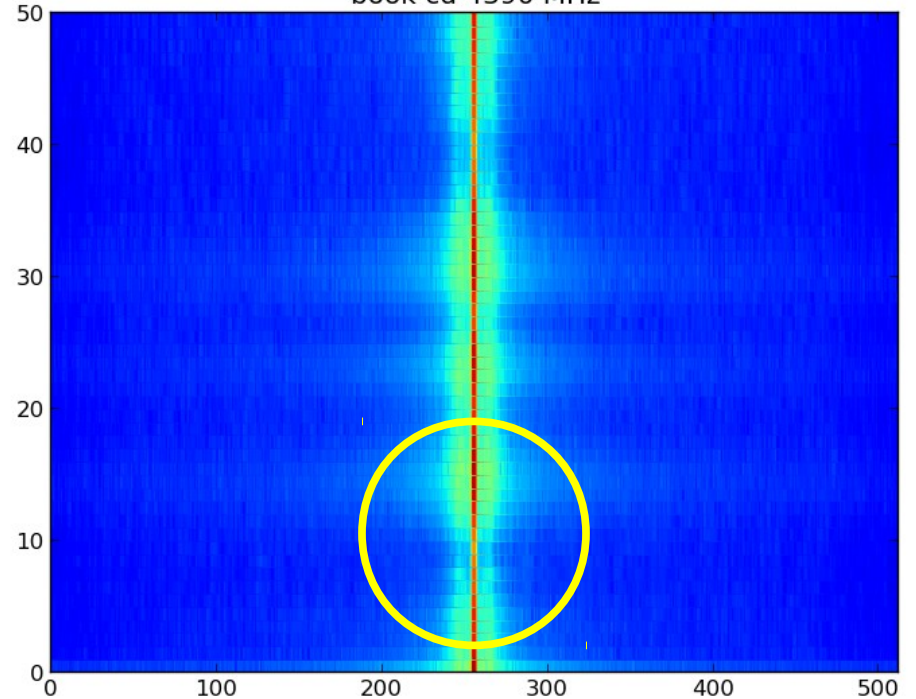


# Scanning: Book + CD (4390 MHz)

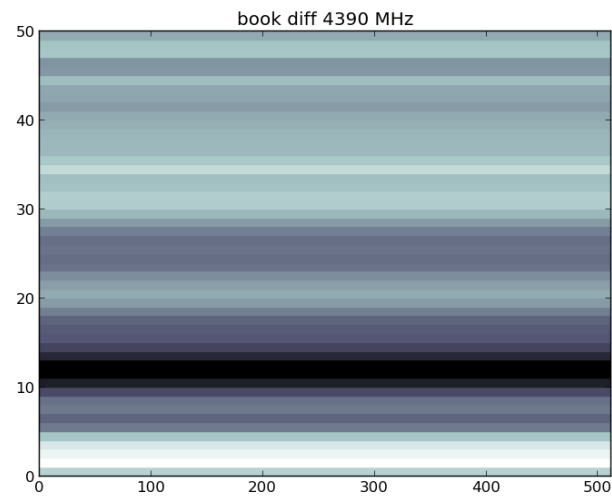
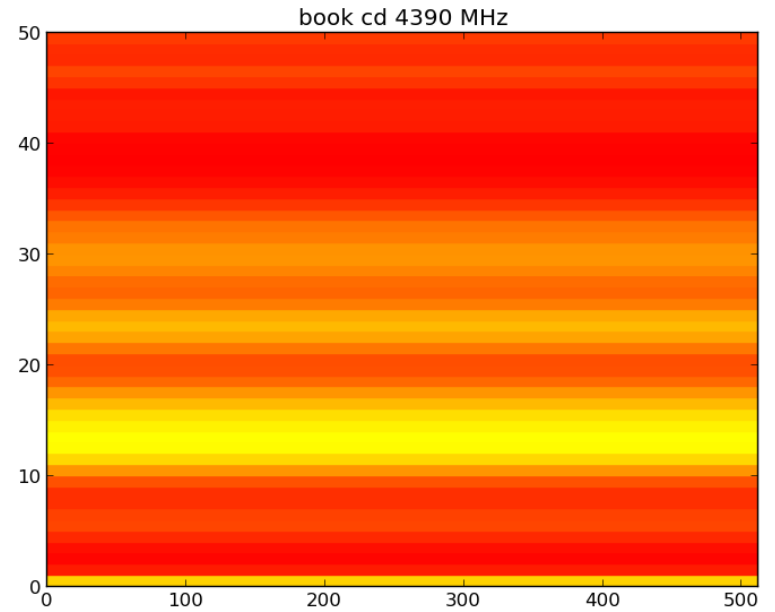
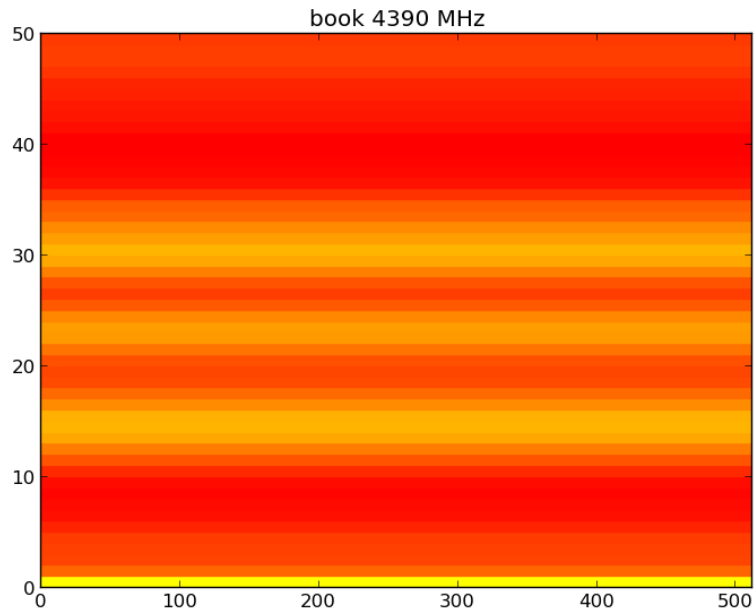
book 4390 MHz



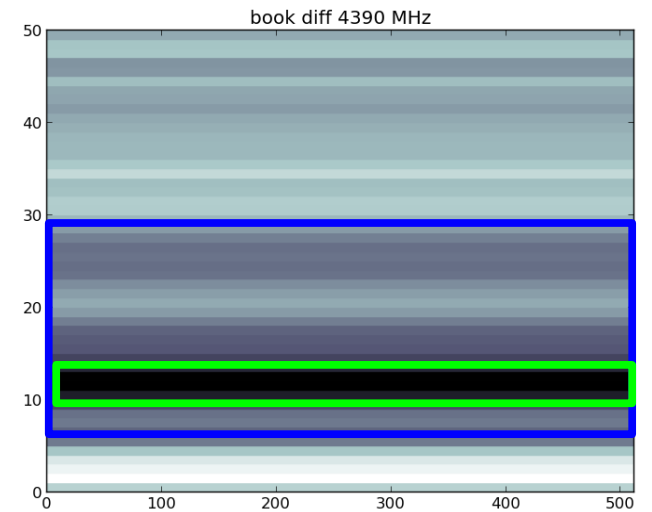
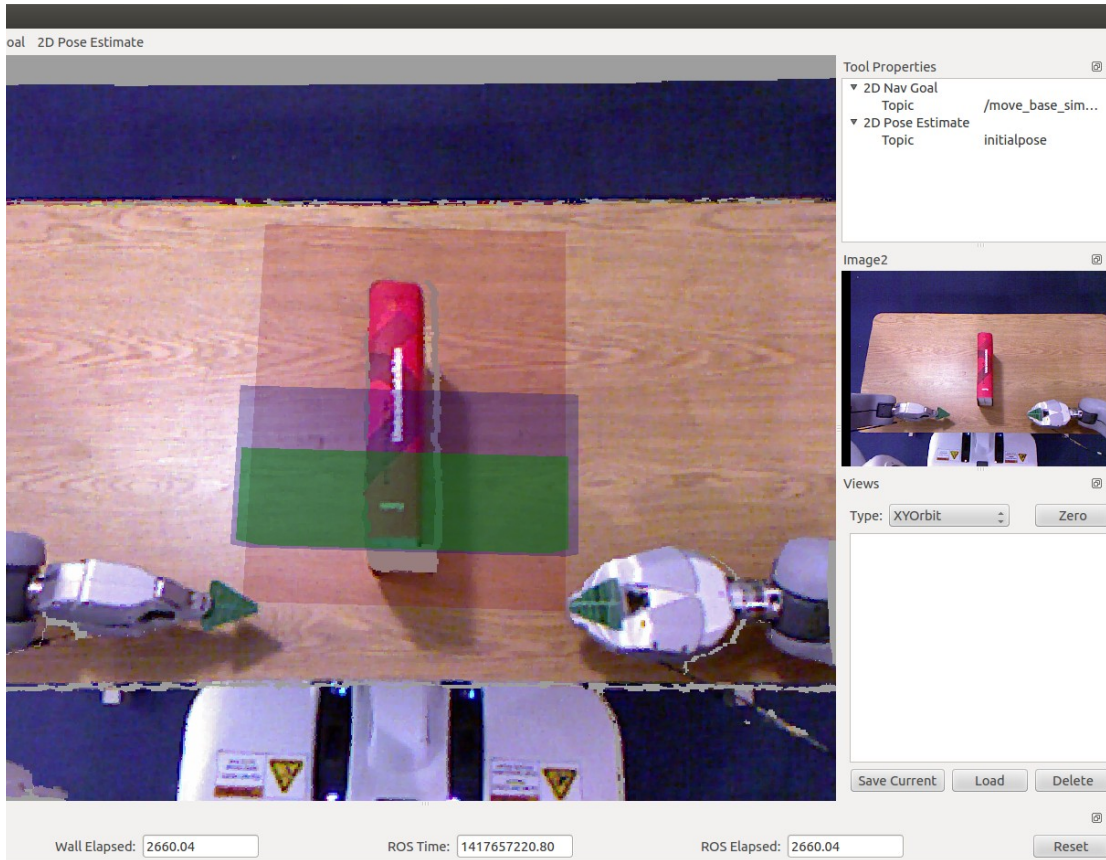
book cd 4390 MHz



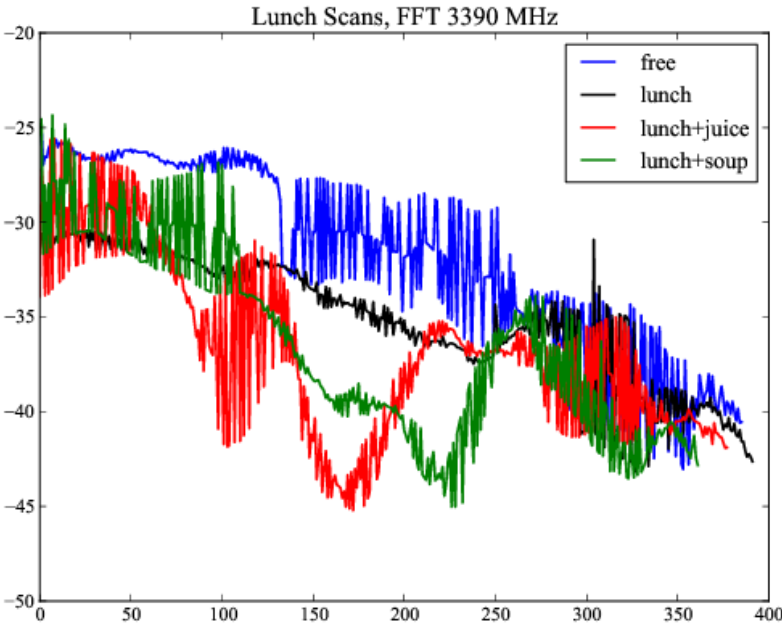
# Scanning: Book + CD (4390 MHz)



# Scanning: Book + CD (4390 MHz)

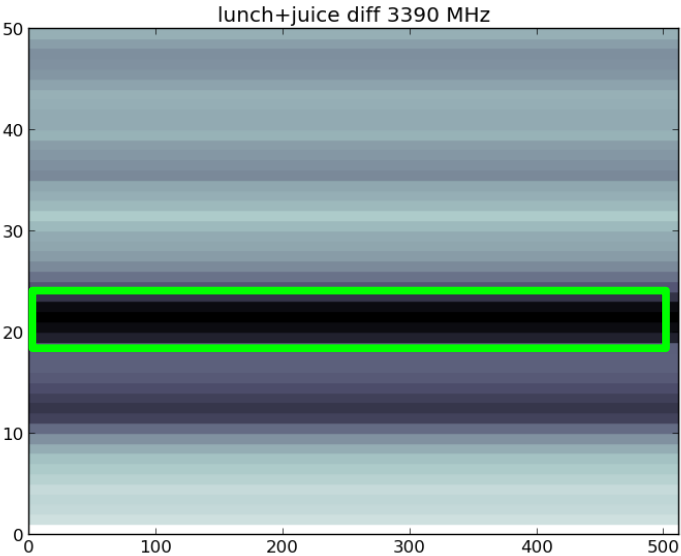
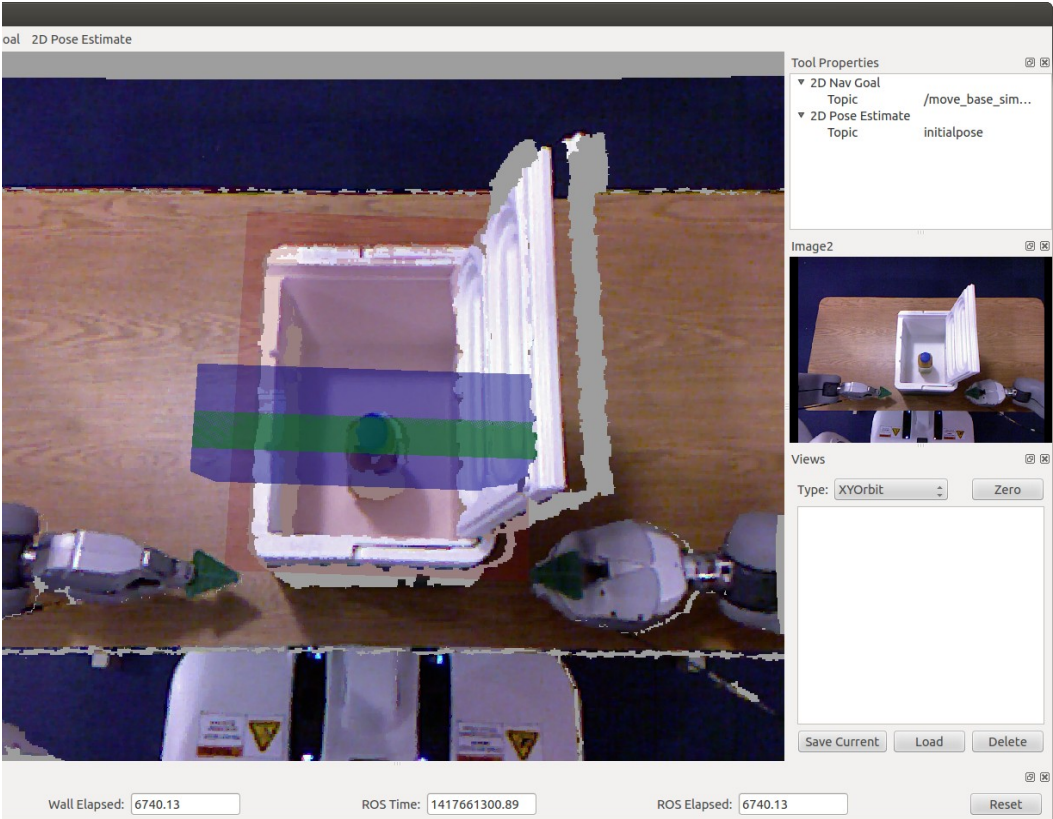


# Scanning: Plastic Lunch Box (3390 MHz)

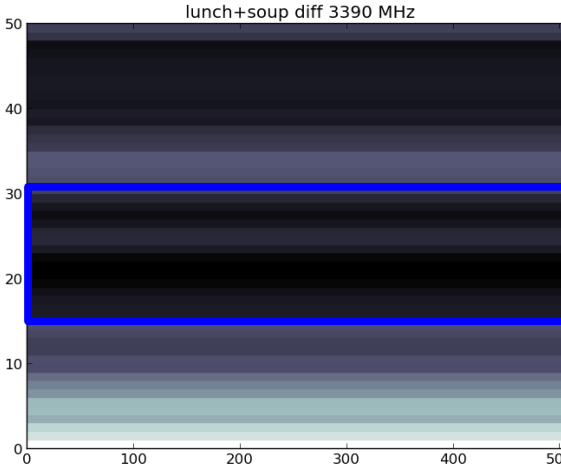
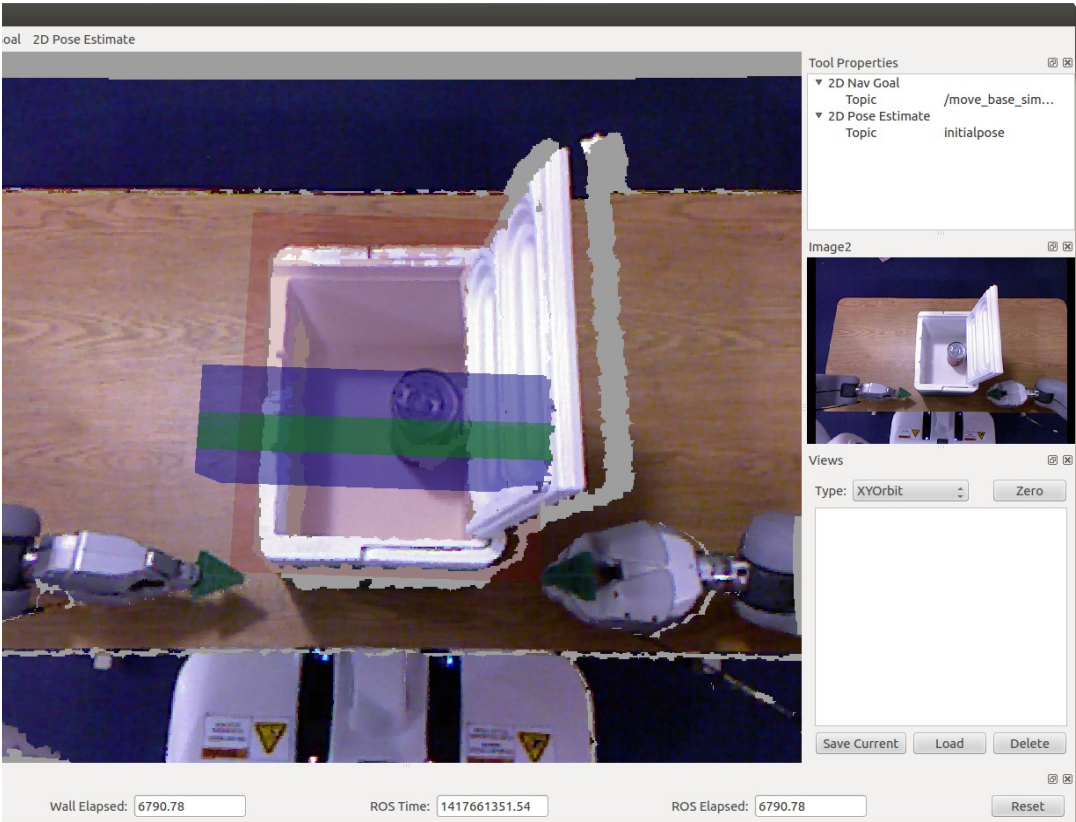




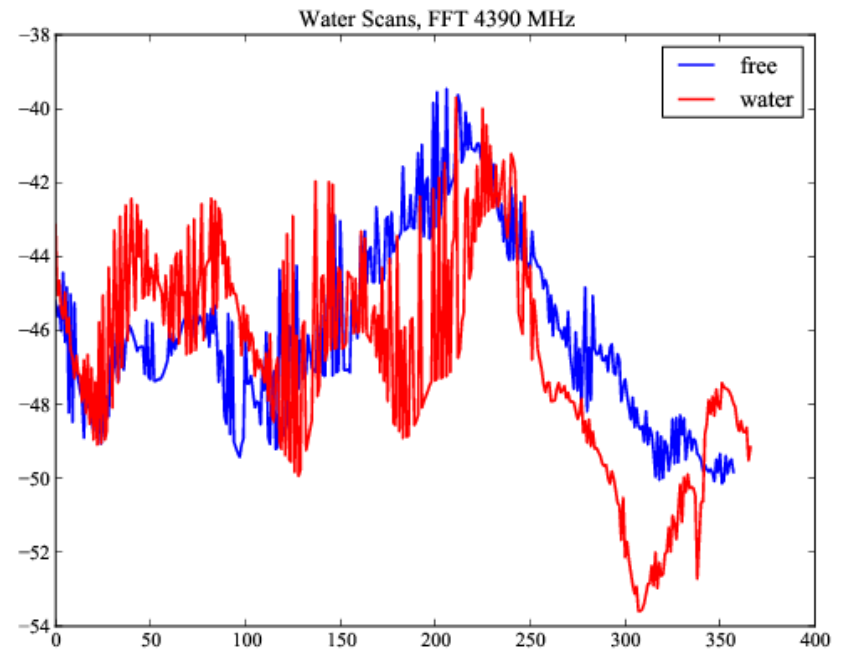
# Scanning: Plastic Lunch Box (3390 MHz)



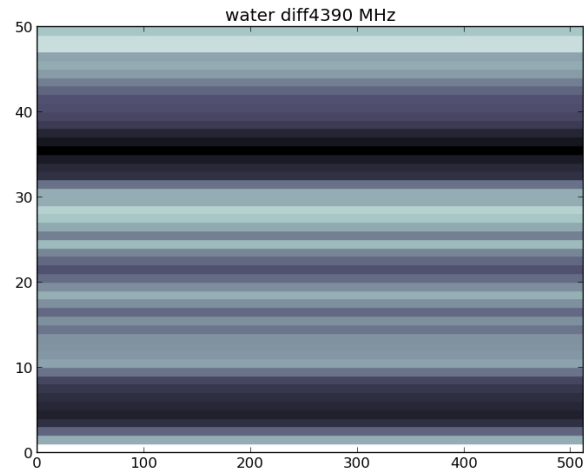
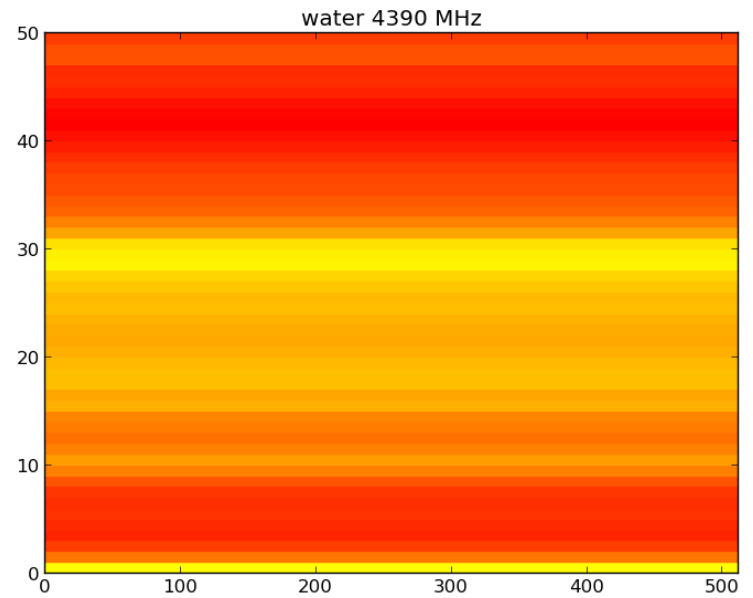
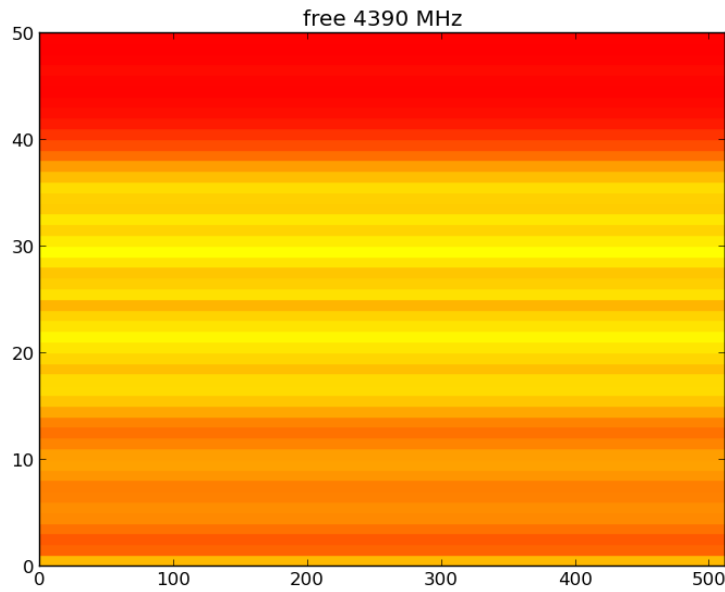
# Scanning: Plastic Lunch Box (3390 MHz)



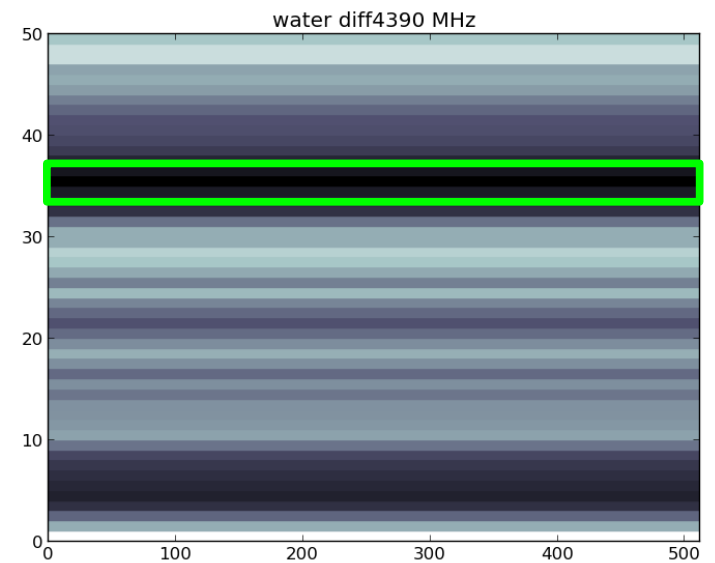
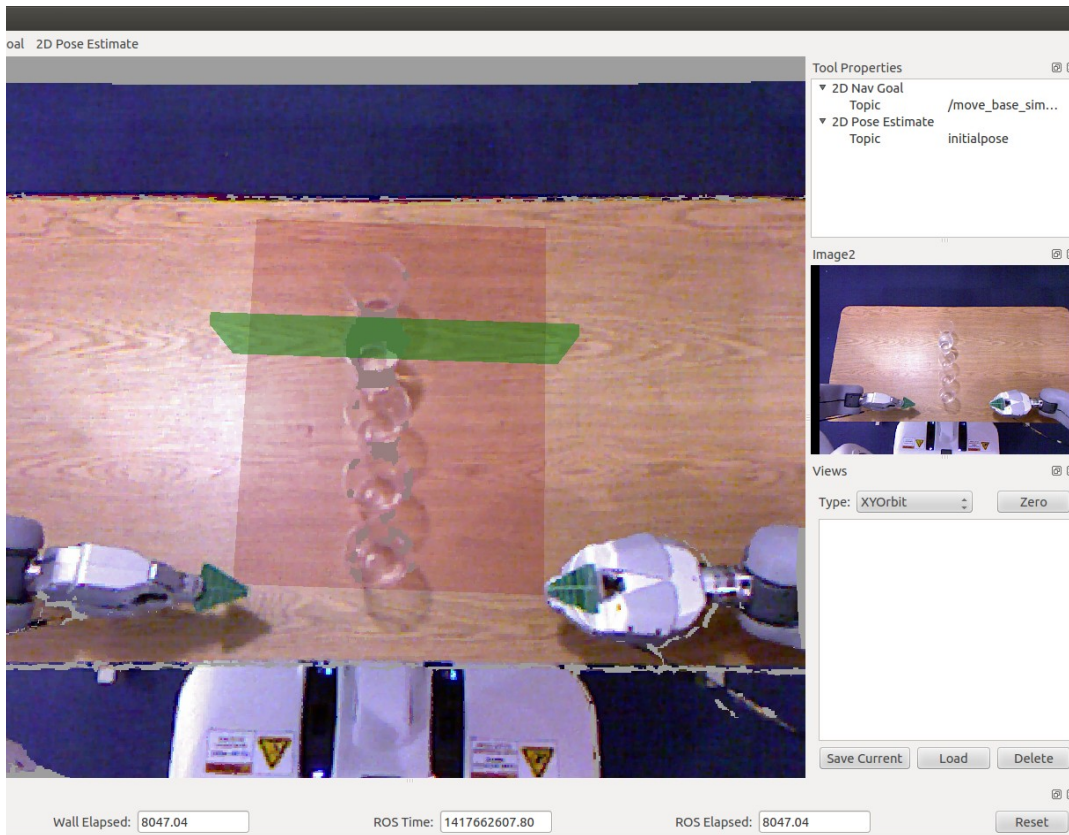
# Scanning: Water (4390 MHz)



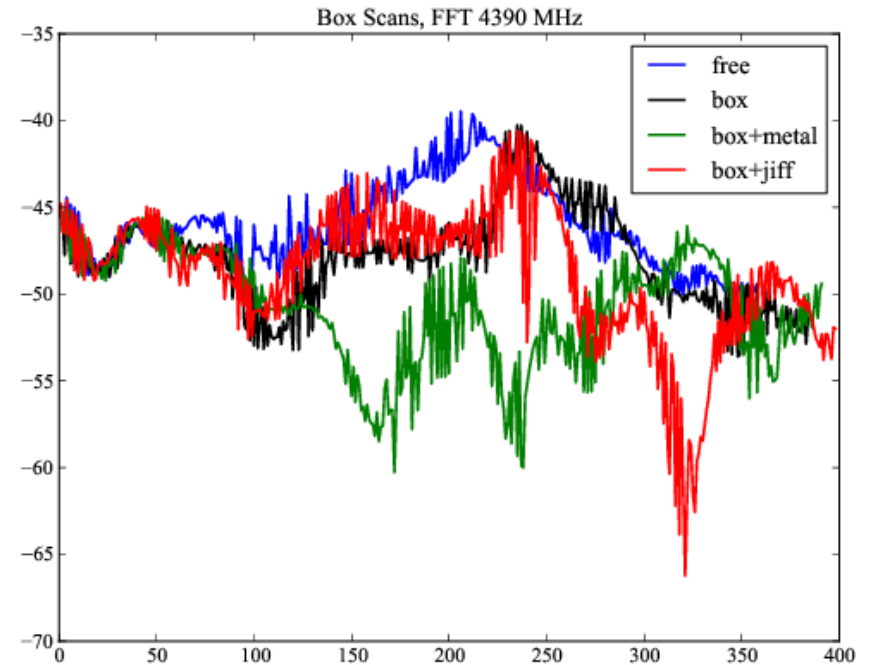
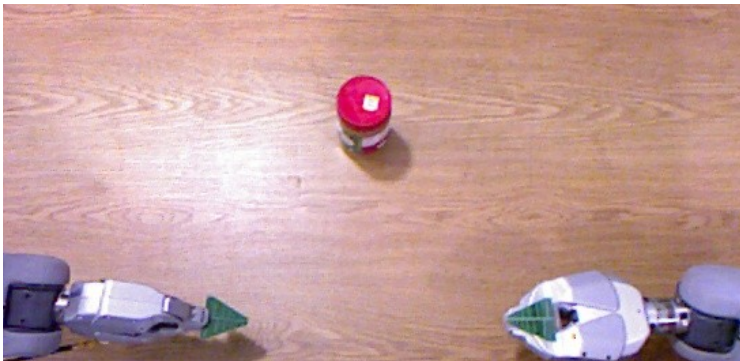
# Scanning: Water (4390 MHz)



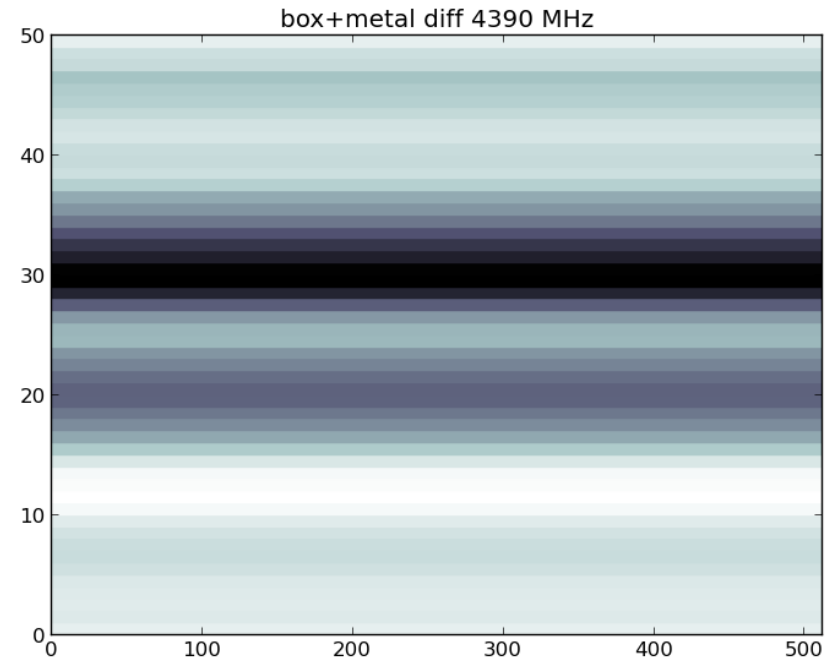
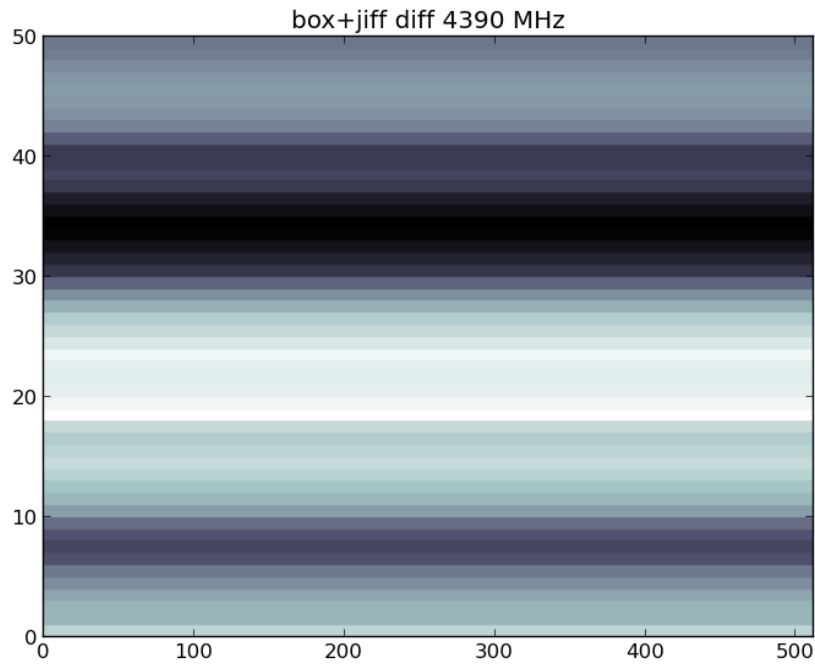
# Scanning: Water (4390 MHz)



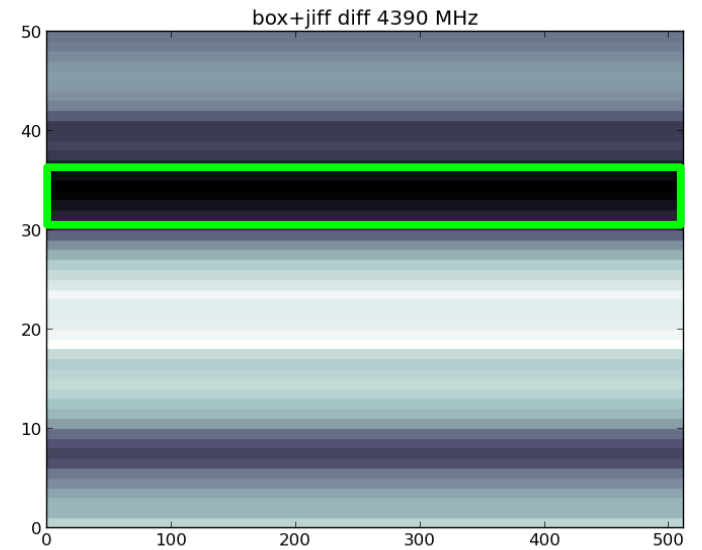
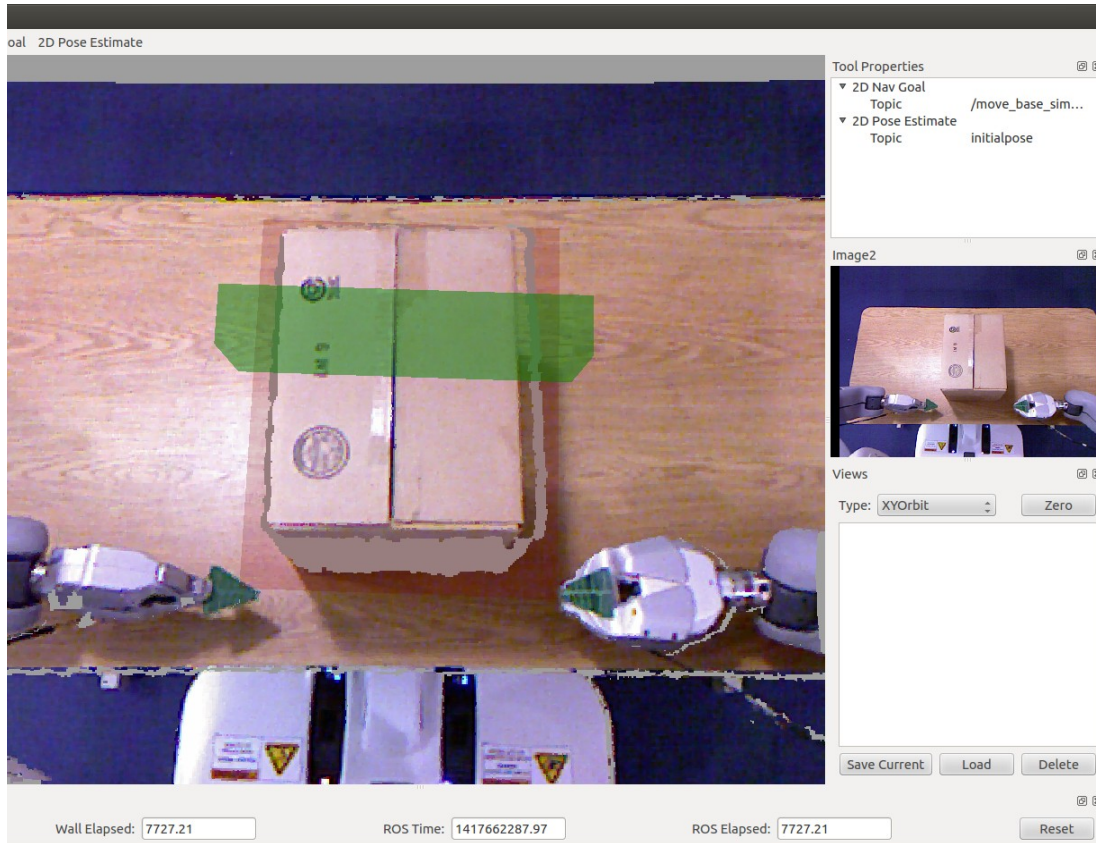
# Scanning: Cardboard Box (4390 MHz)



# Scanning: Cardboard Box (4390 MHz)

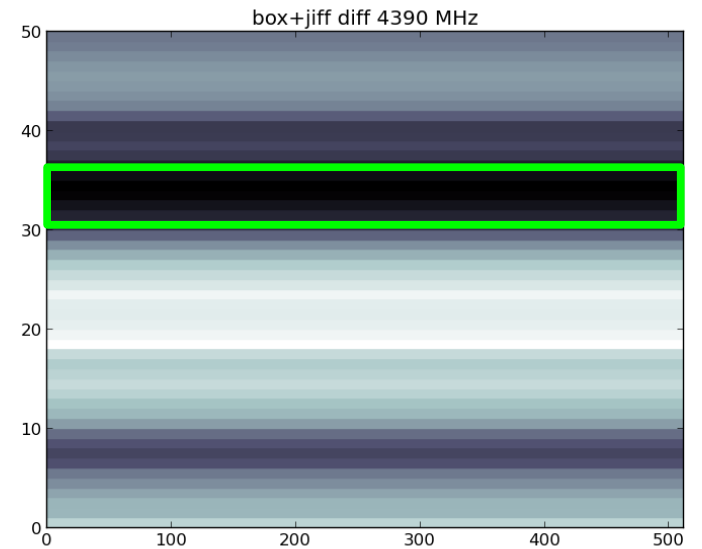
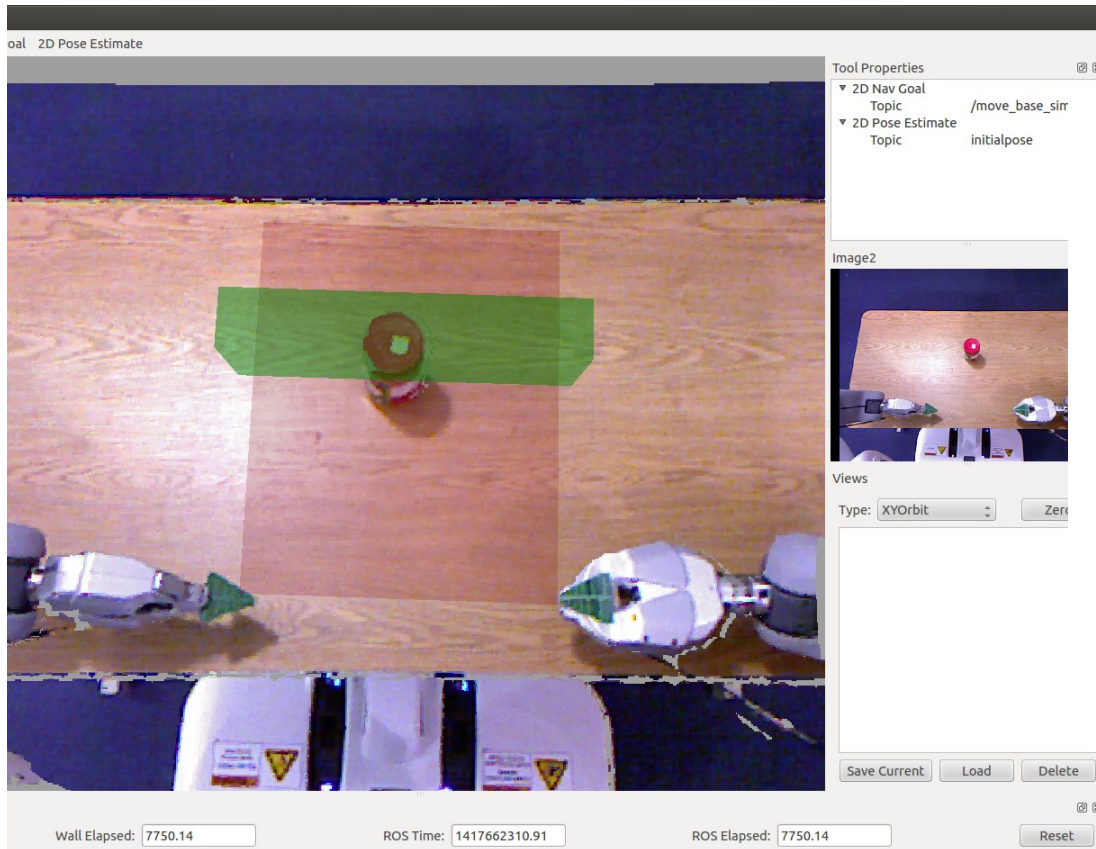


# Scanning: Cardboard Box (4390 MHz)





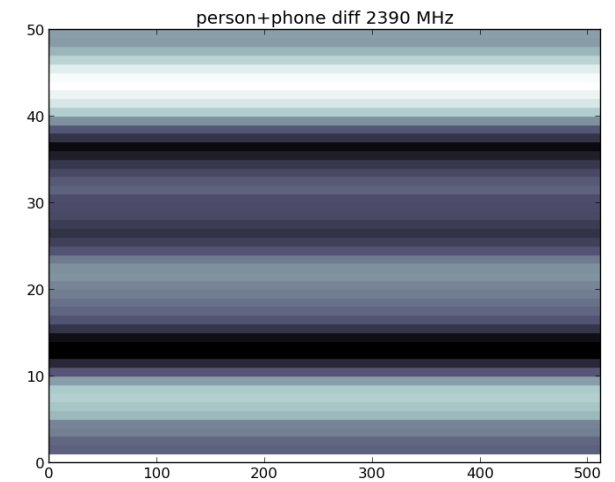
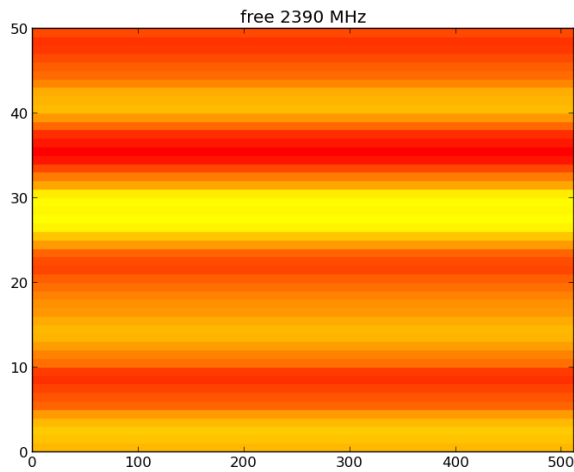
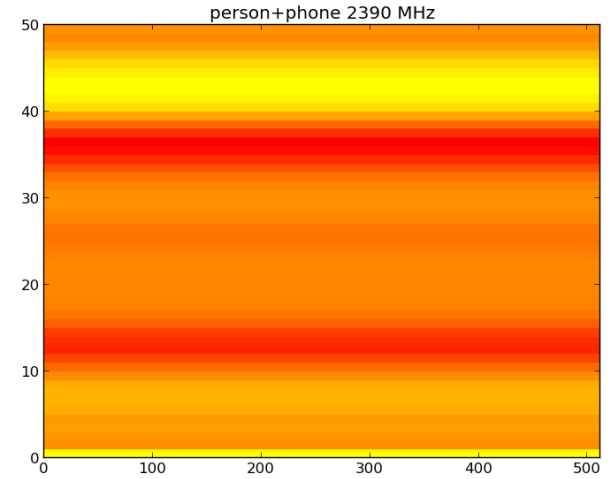
# Scanning: Cardboard Box (4390 MHz)



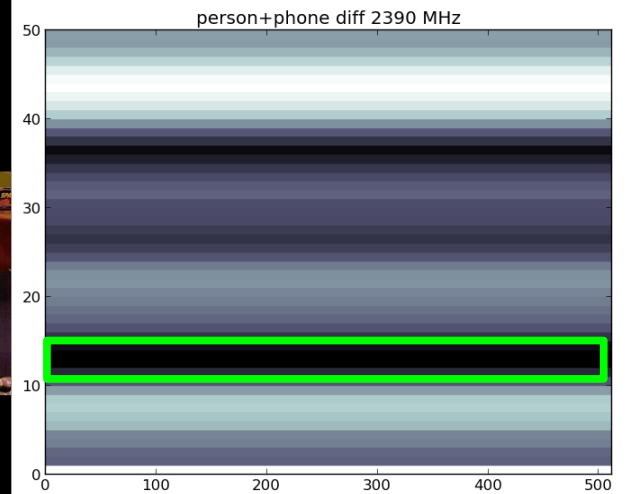
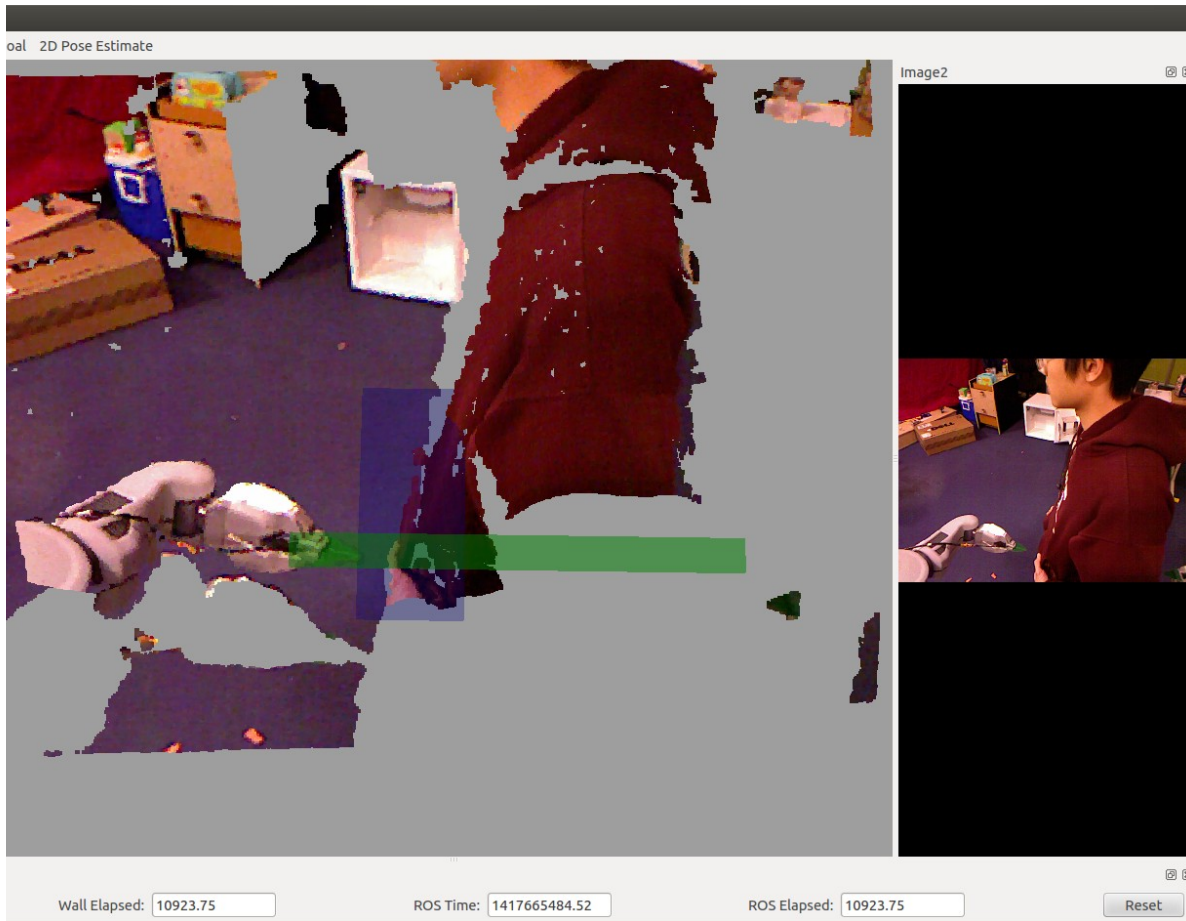
# Scanning: Person (2390 MHz)



# Scanning: Person (2390 MHz)



# Scanning: Person (2390 MHz)



# Current Work

- Varying Frequency
- Reflection, circular trajectories
- Geometry-based attenuation estimates
- Real-time emphasis on areas of interest
- Account for differences in gripper pose, vibration

$$\frac{P_r}{P_t} = G_t(\theta_t, \phi_t)G_r(\theta_r, \phi_r) \left( \frac{\lambda}{4\pi R} \right)^2 (1 - |\Gamma_t|^2)(1 - |\Gamma_r|^2)|\mathbf{a}_t \cdot \mathbf{a}_r^*|^2 e^{-\alpha R}$$

where

- $G_t(\theta_t, \phi_t)$  is the gain of the transmit antenna in the direction  $(\theta_t, \phi_t)$  in which it "sees" the receive antenna.
- $G_r(\theta_r, \phi_r)$  is the gain of the receive antenna in the direction  $(\theta_r, \phi_r)$  in which it "sees" the transmit antenna.