

Introduction to Sketching

IAP 2008

Armando Solar-Lezama

Experience with homework

Step 1: Turn holes into special inputs

- The ?? Operator is modeled as a special input
 - we call them control inputs

```
bit[W] iso1Sk(bit[W] x)  →  bit[W] iso1Sk(bit[W] x, bit[W] c1, c2)
{
  return ~(x + ??) & (x + ??);
}
{
  return ~(x + c1) & (x + c2);
}
```

- Bounded candidate spaces are important
 - bounded unrolling of **repeat** is important
 - bounded inlining of generators is important

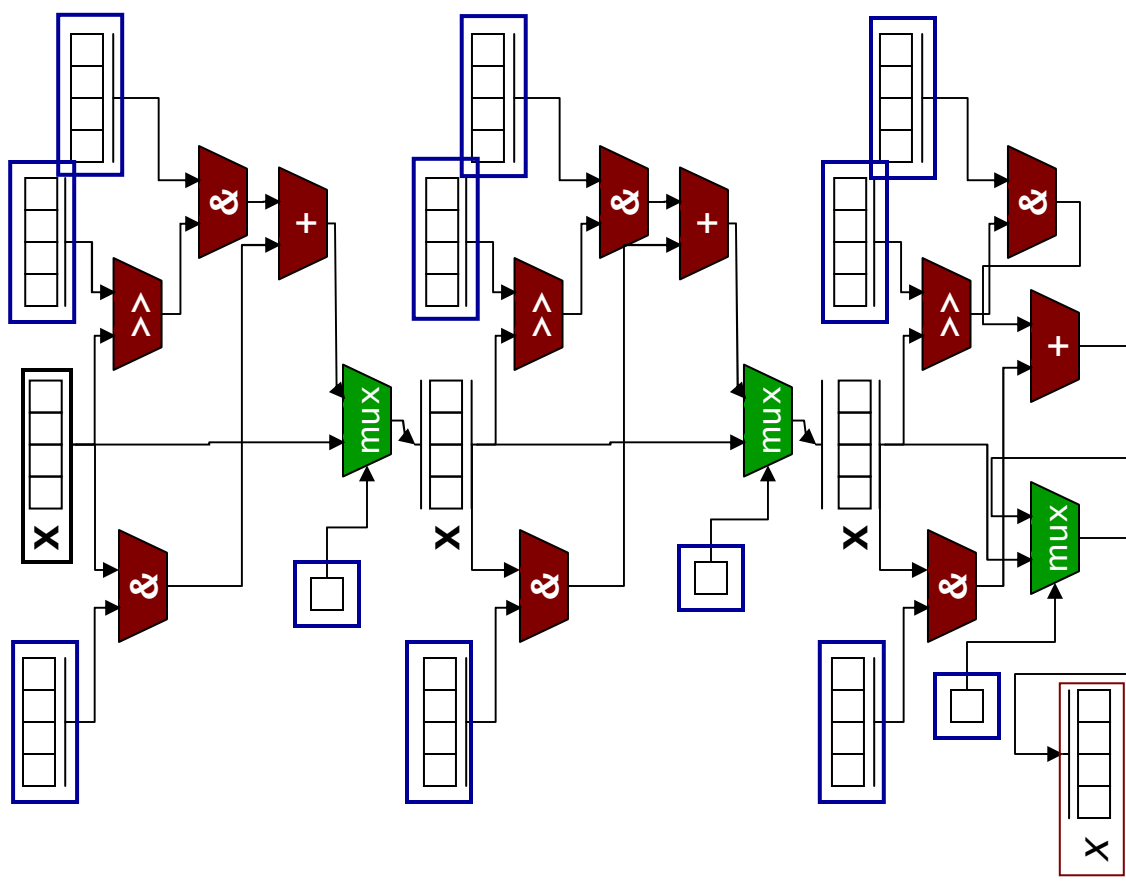
Step 2: Constraining the set of controls

- Correct control
 - causes the spec & sketch to match for all inputs
 - causes all assertions to be satisfied for all inputs
- Constraints are collected into a predicate
$$Q(\text{in}, c)$$
- -showDAG will show you the constraints!

```

int popSketched (bit[W] x)
implements pop {
loop (??) {
    x = (x & ??)
    + ((x >> ??) & ??);
}
return x;
}

```

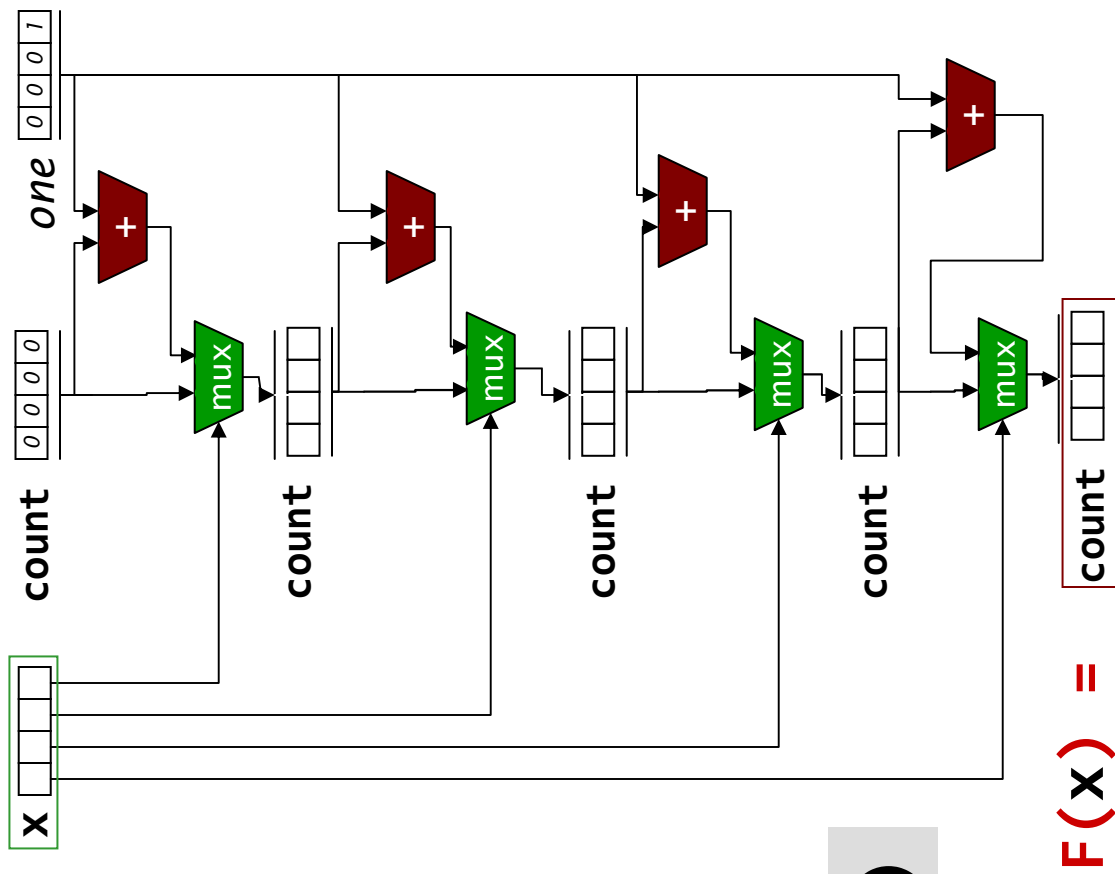


$$S(x, c) = x$$

Ex : Population count.

```
int pop (bit[W] x)
{
    int count = 0;
    for (int i = 0; i < W;
        i++) {
        if (x[i]) count++;
    }
    return count;
}
```

$Q(\text{in}, c) = S(x, c) == F(x)$



A Sketch as a constraint system

Synthesis reduces to constraint satisfaction

$$\exists c. \forall x. Q(x, c)$$

Constraints are too hard for standard techniques

- Universal quantification over inputs
- Too many inputs
- Too many constraints
- Too many holes

Insight

Sketches are not arbitrary constraint systems

- They express the high level structure of a program

A small set of inputs can fully constrain the soln

- focus on corner cases

$$\exists c. \forall x \text{ in } E. Q(x, c)$$

where $E = \{x_1, x_2, \dots, x_k\}$

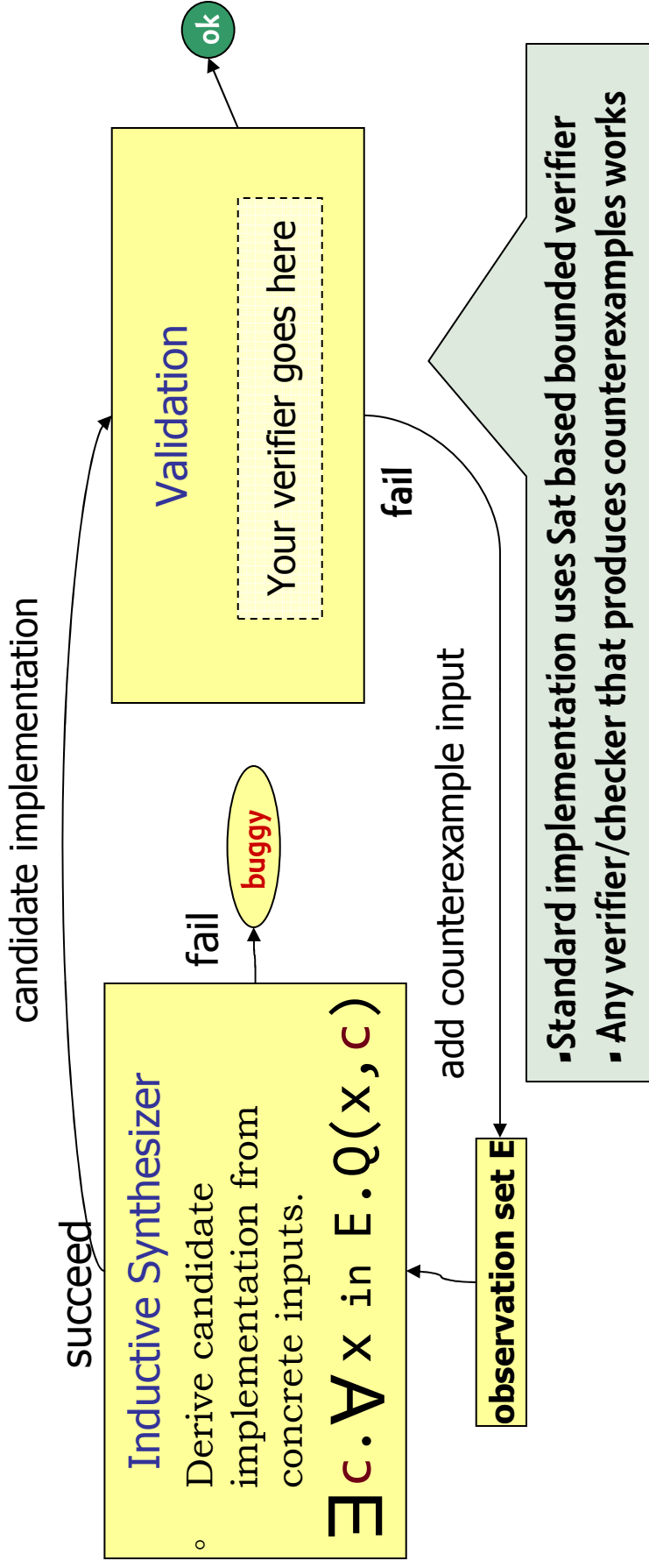
This is an inductive synthesis problem !

- but how do we find the set E?
- and how do we solve the inductive synthesis problem?

Step 3: Counterexample Guided Inductive Synthesis

Idea: Couple Inductive synthesizer with a verifier

- Verifier is charged with detecting convergence



Inductive Synthesis

Deriving a candidate from a set of observations

$$\exists \mathbf{c}. \forall \mathbf{x} \text{ in } E. Q(\mathbf{x}, \mathbf{c})$$

where $E = \{x_1, x_2, \dots, x_k\}$

Encode \mathbf{C} as a bit-vector

- natural encoding given the integer holes

Encode $Q(x_i, \mathbf{c})$ as boolean constraints on the bit-vector

Solve constraints using SAT solver

- with lots of preprocessing in between

Controlling the SAT Solver

- Several options for the SAT Solver
 - `--synth` and `--verif`
 - ABC vs MINI (MiniSat)
 - `--cbits` and `--inbits`
 - `--incremental`

Using synthesizer feedback

- Results of different phases useful for debugging
 - counterexample inputs
 - number of iterations
- Some useful flags
 - --keeptmpfiles
 - --showInputs
 - --fakesolver
 - -checkpoint and -restore