

PARALLEL  
~~SEQUENTIAL~~ NESTED DISSECTION  
FOR SOLVING SYSTEM  $Ax=b$

Outline of the talk:

1. Sequential solving
2. Parallelization
3. CM-implementation:
  - data mapping
  - algorithm
  - implementation of primitives  
(matrix operations in CM).

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## This is our problem:

Solve an equation  $Ax = b$ ,  $A$  -  $n \times n$  matrix,  $b$  -  $n$ -vec

where (1)  $A$  is symmetric positive definite  $\Leftrightarrow$

$\Leftrightarrow$  for any subset of variables, corresponding submatrix of  $A$

has  $\det > 0$ . E.g:  $A = \begin{matrix} v_1 & \begin{bmatrix} 1 & -5 & 3 \end{bmatrix} \\ v_2 & \begin{bmatrix} -5 & 2 & 0 \end{bmatrix} \\ v_3 & \begin{bmatrix} 3 & 0 & 10 \end{bmatrix} \end{matrix} \xrightarrow{\{v_1, v_3\}} \begin{bmatrix} 1 & 3 \\ 3 & 10 \end{bmatrix}; \det = 1 > 0$   
 $\xrightarrow{\{v_2\}} [1]; \det = 1 > 0$ .

(2)  $A$  is sparse  $\Leftrightarrow O(n)$  elements are nonzeros.

(3)  $n > 1000$

(4)  $\text{Graph}(A)$  is known beforehand.

Def: Incidence graph  $\text{Graph}(A)$  of matrix  $A$ :

Its vertices correspond to variables of  $A$

— " — edges — " — to nonzero elements of  $A$

E.g: for  $A$  above,  $\text{Graph}(A) = \begin{matrix} & v_2 \\ & \nearrow \\ v_1 & \\ & \searrow \\ & v_3 \end{matrix}$

Note: in most examples, I will be using matrices with  $\text{Graph}(A) = \text{grid}$ .

# ① SEQUENTIAL SOLVING of $Ax=b$ <sup>-2-</sup>

DIRECT INVERSION:  $x = A^{-1}b$ .

CLAIM:  $\exists!$  DECOMPOSITION  $A = L \cdot D \cdot U$ ,

where  $L = \begin{bmatrix} 1 & & 0 \\ * & 1 & \\ & & \ddots \end{bmatrix}$ ,  $U = \begin{bmatrix} 1 & & * \\ 0 & 1 & \\ & & \ddots \end{bmatrix}$ ,  $D = \text{diag.}$

COR:  $A^{-1} = U^{-1}D^{-1}L^{-1} = (L^T)^{-1}D^{-1}L^{-1}$

HOW TO FIND  $L^{-1}$  and  $D^{-1}$ ?

BY GAUSSIAN ELIMINATION.

# GAUSSION ELIMINATION (NO PIVOTING) 3-

$$\left[ \begin{array}{cccc|cccc} 1 & & & & a_{11} & a_{12} & \dots & a_{1n} \\ & 1 & & & a_{21} & & \dots & \\ & & \ddots & & \vdots & & & \\ & & & 1 & a_{n1} & & \dots & a_{nn} \\ & 0 & & & & & & \end{array} \right] \xrightarrow{\text{1st COLUMN}}$$

$$\left[ \begin{array}{cccc|cccc} 1 & 0 & \dots & 0 & a_{11} & a_{12} & \dots & a_{1n} \\ -a_{21}/a_{11} & 1 & 0 & \dots & 0 & * & & \\ & & \ddots & & \vdots & & & \\ -a_{n1}/a_{11} & & & 1 & 0 & & & \end{array} \right] \xrightarrow{\text{2nd COLUMN}}$$

$$\left[ \begin{array}{cccc|cccc} 1 & & & & a_{11} & & & \\ & 1 & & & 0 & & & \\ & & \ddots & & & & & \\ & & & 1 & & & & \end{array} \right] = L^{-1} \quad \left[ \begin{array}{cccc|cccc} & & & & a_{11} & a_{22} & * & \\ & & & & 0 & & & \\ & & & & & & & \\ & & & & & & & a_{nn} \\ & & & & & & & \end{array} \right] = D$$

$$A^{-1} = (L^T)^{-1} D^{-1} L^{-1}$$

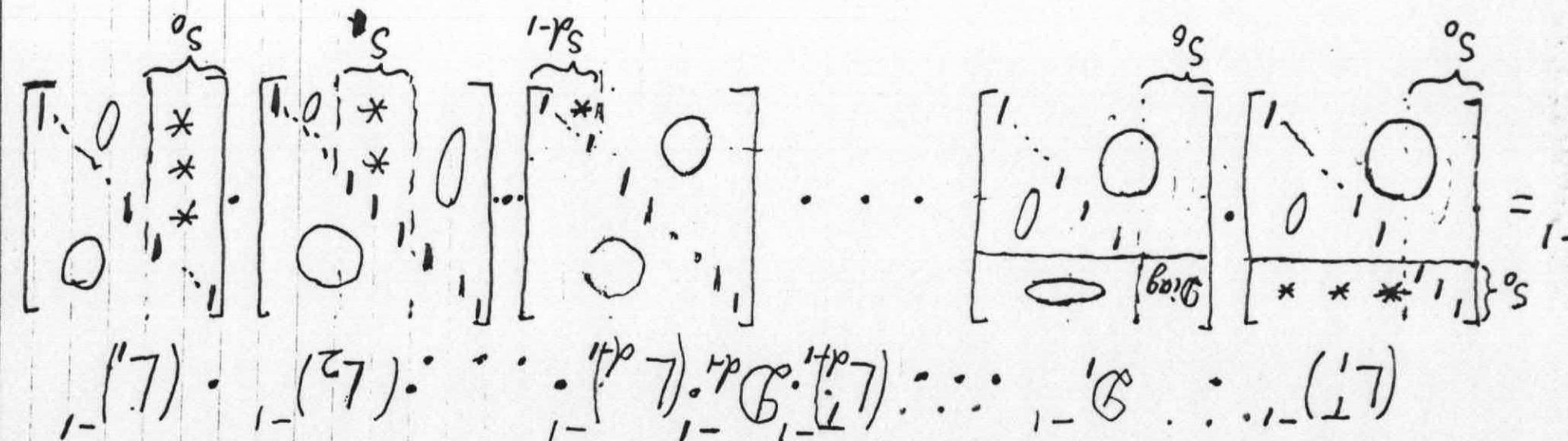
$L^{-1}$  CAN BE DENSE EVEN FOR SPARSE  $L$ .

SEQ:  $O(n^3)$

PAR: SPACE/TIME =  $O(n^2)/O(n \log n)$

Generalization of LDU decomposition of  $A^{-1}$

Decompose  $A^{-1}$  into 3d factors:



Then  $X = A^{-1}B$

This decomposition is obtained by partial G.E. on  $S_0, S_1, \dots$ . Here  $S_0, S_1, \dots, S_{d-1}$  are some subgroups of variables of  $A$ . We want to choose these subgroups so that all  $L_i$  are sparse (i.e., each  $L_i$  has only  $O(n)$  nonzero variables).

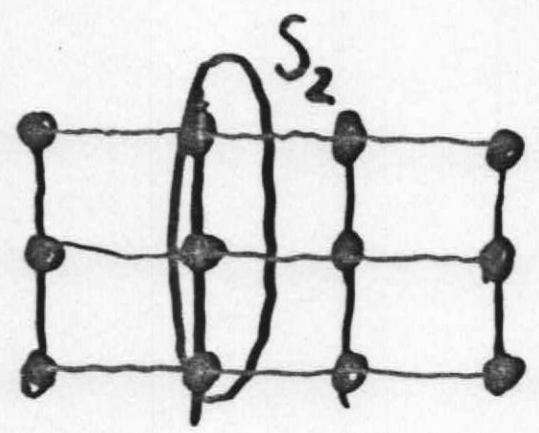
FOR MANY TYPES OF GRAPH(A)  
(e.g. for all planar graphs)  
we <sup>can</sup> ~~shall~~ choose  $S_0, \dots, S_d$   
in SOME special way.

This will make all matrices in (x)  
sparse.

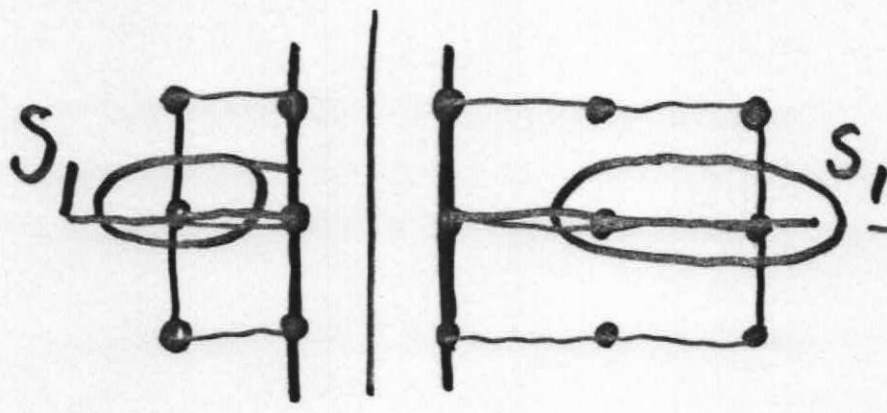
NAMELY,  $S_0, \dots, S_d$  WILL BE CONSTRUCTED  
with the help of SEPARATOR TREE of A

(NO PRECISE DEFINITION GIVEN HERE)

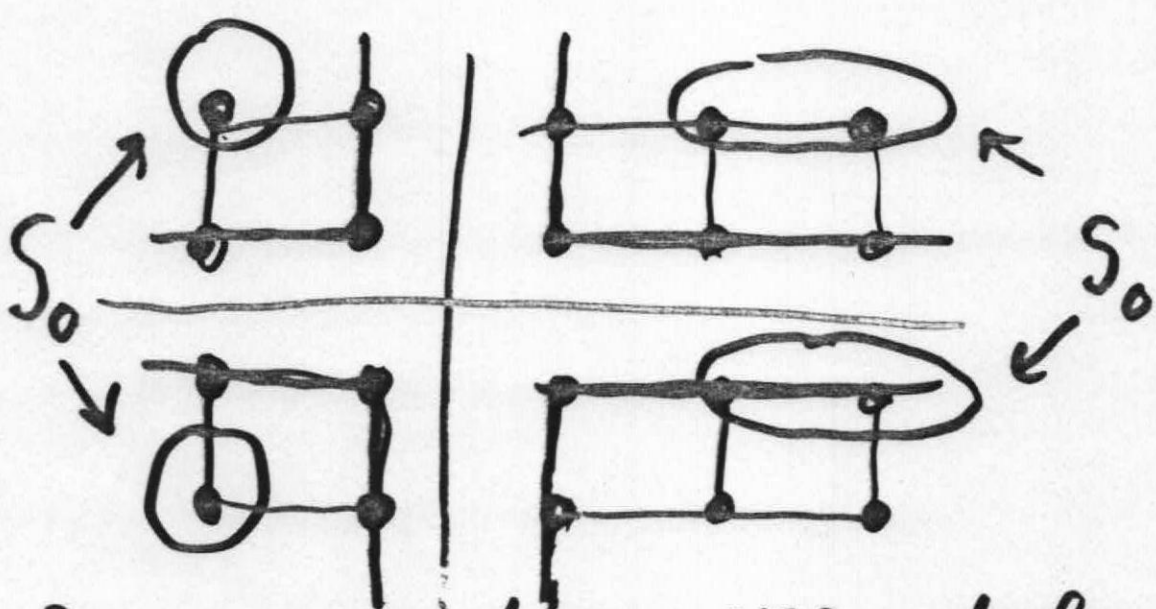
# $O(\sqrt{n})$ - SEPARATOR FOR GRAPH/MATRIX



level 2



level 1



level 0

SEPARATOR TREE HAS  $d \sim \log n$  levels

At level  $i$  it gives decomposition of Graph(A) into  $2^{d-i-1}$  subgraphs (not disjoint)



CLAIM: IF WE CHOOSE  $i$ -TH SEPARATOR FOR  $S_i$ ,<sup>-8-</sup>  
then each factor IN  $(\alpha)$  has  $O(n)$  nonzero  
elements.

MOREOVER, WE CAN FIGURE OUT their  
POSITIONS BY looking at the sep. tree.

# SEQUENTIAL NESTED DISSECTION: -9-

- CONSTRUCT SEPARATOR TREE FOR  $G(A)$
- FACTOR  $A^{-1}$  INTO PRODUCT OF  $\sim 2 \log n$  SPARSE  $n \times n$  MATRICES.
- SOLVE:  $x = A^{-1}B$

SEQ:  $O(n^{3/2})$

? PAR: SPACE/TIME  $\stackrel{?}{=} \frac{O(n)}{O(\sqrt{n})}$

## NEED PARALLEL NESTED DISSECTION

That is, WANT to factor  $A^{-1}$  in parallel

Recall: factorisation of  $A^{-1}$  is obtained by partial Gaussian elimination

# Recursive factorization of $A^{-1}$ by partial G.E.

want:  $A^{-1} = (L_1^T)^{-1} D_1^{-1} \dots (L_{d-1}^T)^{-1} D_{d-1}^{-1} L_{d-1}^{-1} \dots L_2^{-1} L_1^{-1} (\alpha)$

— Reorder variables of  $A$  so that variables in the group  $S_0$  come first.

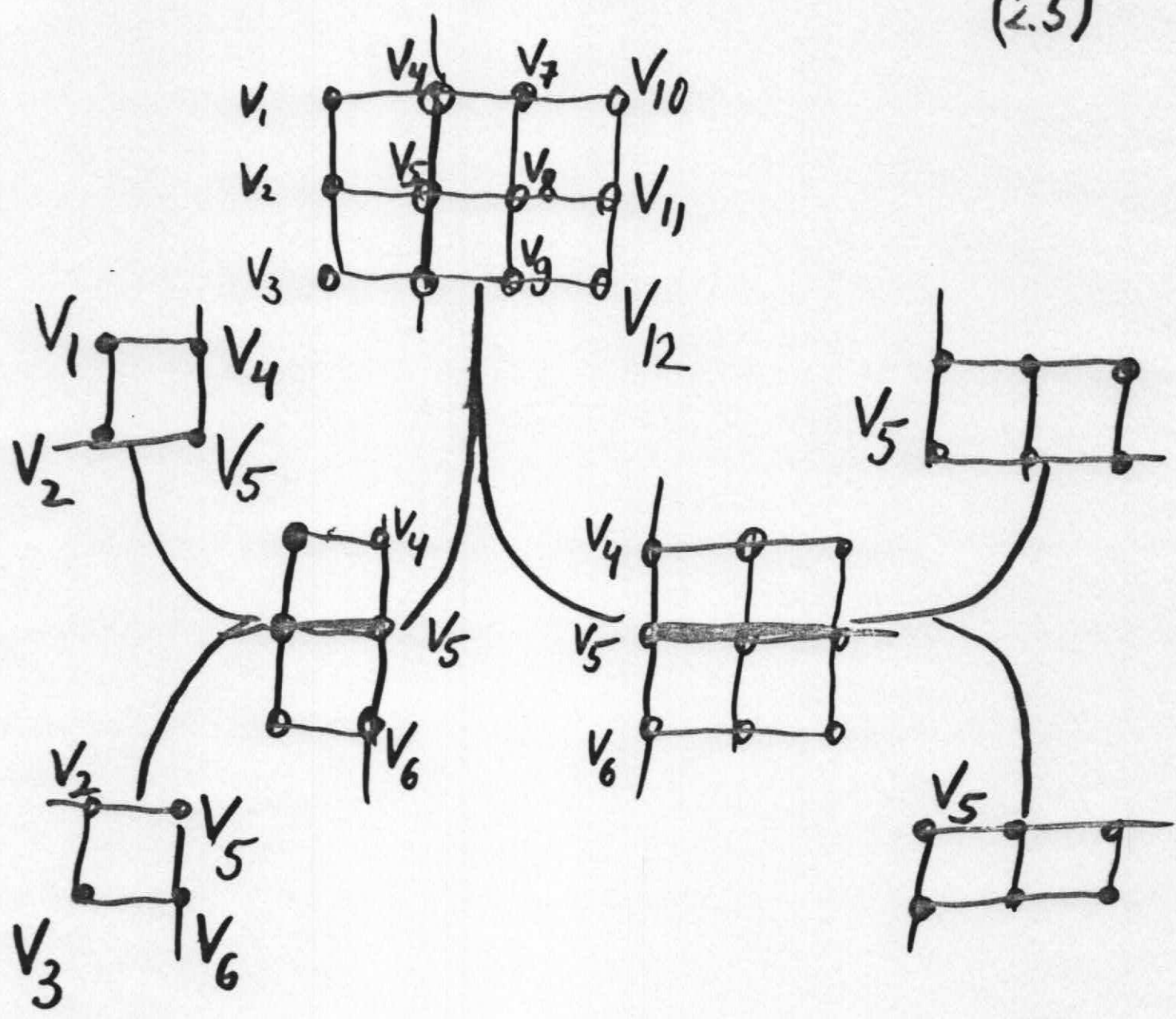
—  $A \xrightarrow[S_0]{\text{eliminate}}$

$$\left[ \begin{array}{ccc|ccc} 1 & & & & & \\ & \ddots & & & & \\ & & \ddots & & & \\ & * & & \ddots & & \\ & * & & & \ddots & \\ & & & & & \ddots \\ & & & & & & 1 \end{array} \right] L_1^{-1} \quad \left[ \begin{array}{ccc|ccc} D_1 & * & * & * & & \\ \hline 0 & & & & A_1 & \end{array} \right] (\beta)$$

—  $A_1 \xrightarrow[S_1]{\text{eliminate}} L_2, D_2, A_2,$

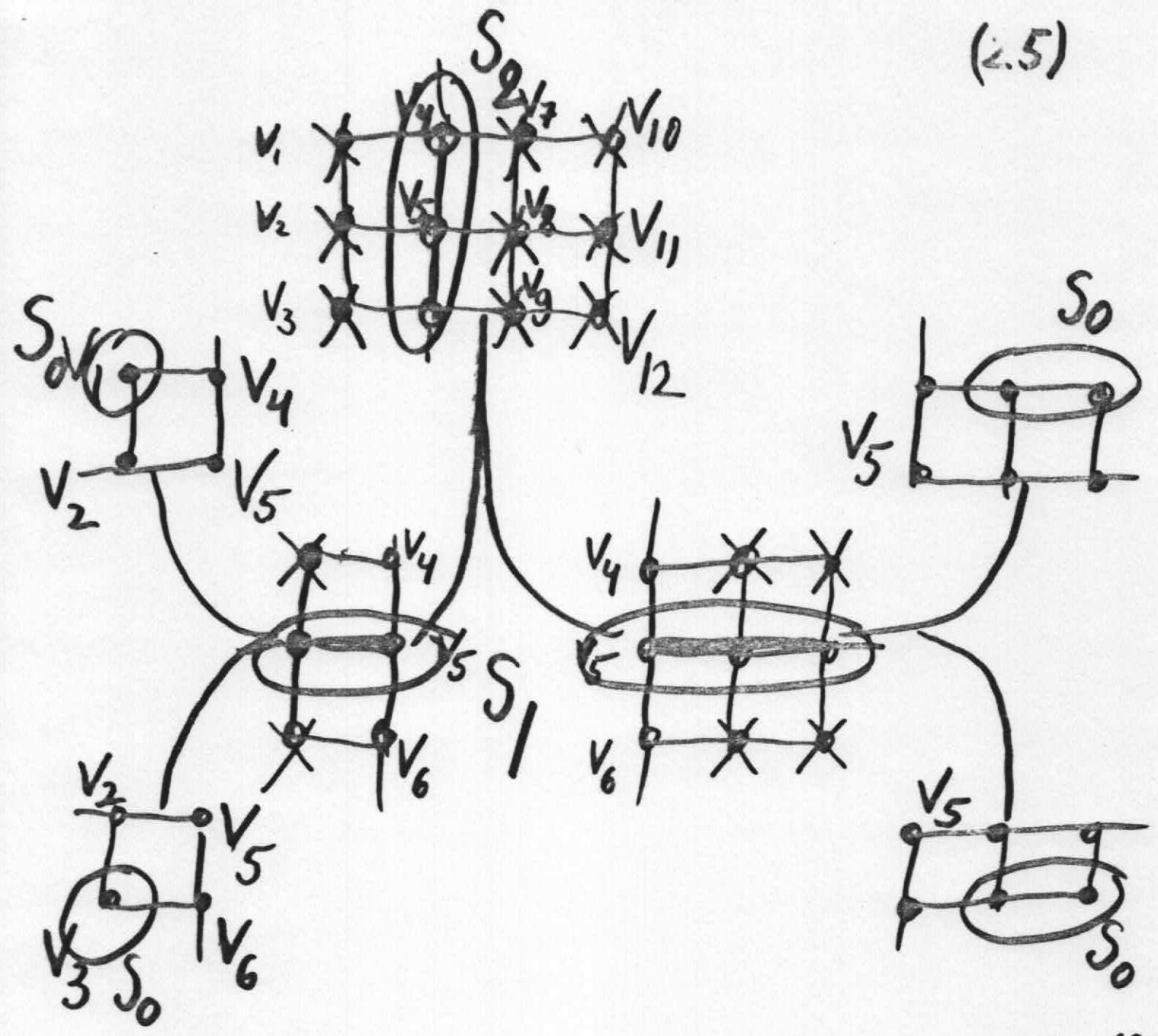
etc.

(2.5)



# $O(Vn)$ - SEPARATOR TREE FOR GRAPH - 11-

(2.5)



TREE-NODE AT LEVEL  $i$  CONTAINS:

- SOME SUBSET OF  $S_i$
- SUBSET OF  $\bigcup_{k>i} S_k$ , adjacent to  $S_i$

FACTORING  $A^{-1}$  in parallel:

- Construct the separator tree with  $d = \log n$  levels
- Split our matrix  $A$  into the direct "sum" of small matrices. Variables = vertices in corresponding tree-nodes on level  $0$ .
- Inductive step: for tree level  $i = 0, \dots, d$ :

1. For all small matrices in parallel, do partial G.E.
2. As a result, for each small matrix obtain  $L^{-1}$  and  $A_i$  (see identity (P) above).  
All  $L^{-1}$  are left on the current level; all  $A_i$  are moved to the next level.
3. Each  $A_i$  is added up to its sibling in the separator tree

Claim: After we are done, sum of all small matrices  $L^{-1}$  from level  $i$  equals to  $L_i^{-1}$  (see f).

In other words; if variables are chosen according to the sep. tree then G.E and  $\oplus$  commute with each other

Handwaving proof: (i) fill-ins in G.E. correspond to certain paths in Graph(A).  
(ii) Paths in Graph(A) "agree" with separator tree.

Rigorous proof is not very straightforward.  
I couldn't find any papers on this,  
so I wrote it down myself. Notes are available -

Lenz.

## MAIN IDEA (PAN-REIF)

-13-

- split the matrix into  $(\oplus)$  small matrices.
  - PRIMITIVE OPERATIONS REQUIRED for factoring  $A^{-1}$  will commute with  $(\oplus)$
- $\Rightarrow$  We can apply these operations to small matrices on different levels of the separator tree.
- IN THE END all factors of  $A^{-1}$  will be distributed among the tree-nodes.

### Our Implementation:

We use identity (2), with primitive operation = Gaussian elimination

They used different identity, with much more complicated primitive operation.

# SPACE REQUIREMENTS:

1 MATRIX ELEMENT PER PROCESSOR

$\log(n)$  levels of the TREE

At each level, SPACE = CONST \* N

FOR "NICE" GRID GRAPHS, CONST = 25

FOR "GENERAL" GRIDS, CONST  $\approx$  50

FOR PLANAR GRAPHS, MIGHT BE WORSE.

# TIME REQUIREMENTS:

WORST CASE: LEVEL  $d-1$  TIME =  $O(\sqrt{n})$



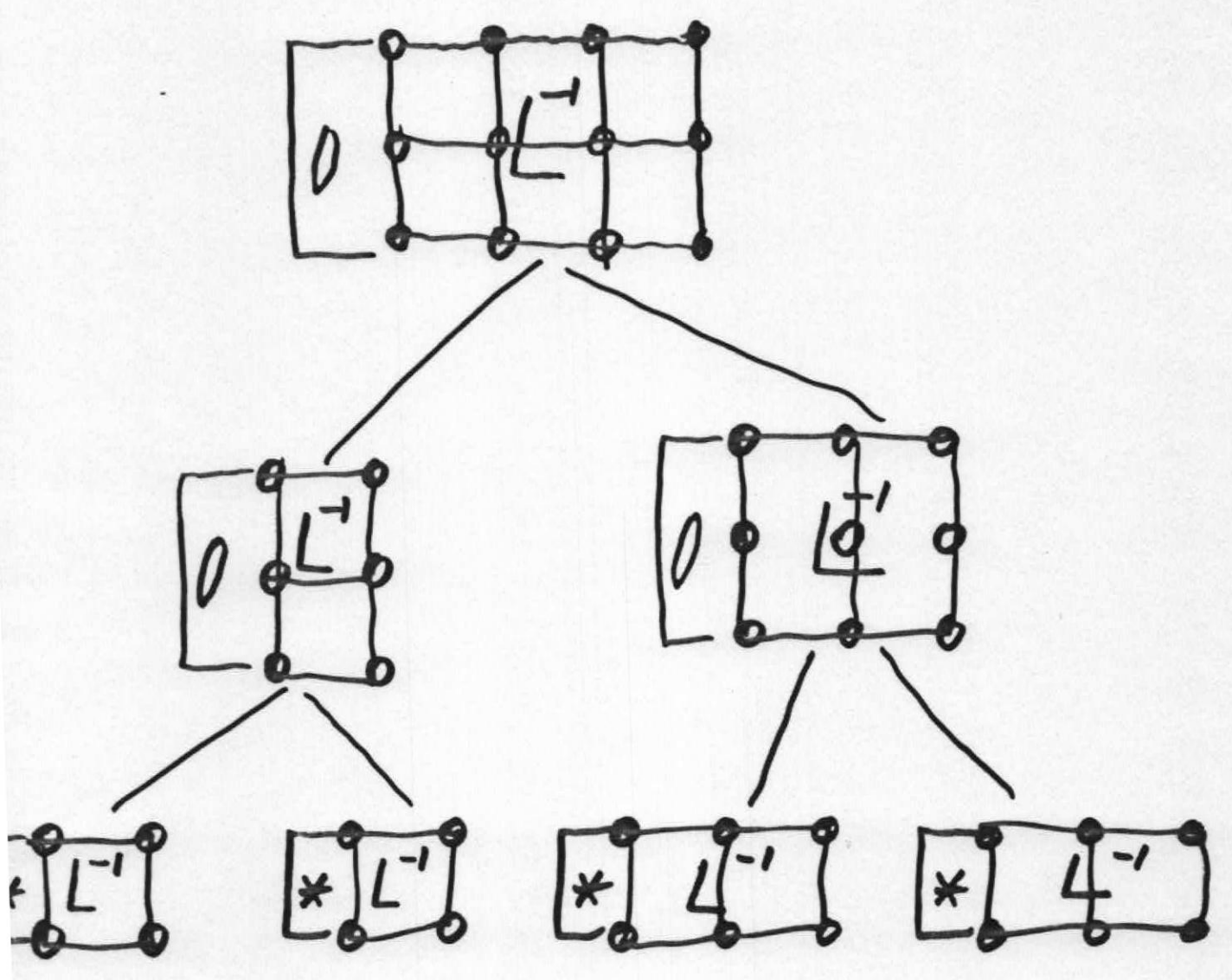
## Backsolve

ALL FACTORS OF  $A^{-1}$  ARE NOW COMPUTED AND STORED IN THE CM.

SO, GIVEN vector  $b$ , we should be able to compute  $A^{-1}b = x$ .

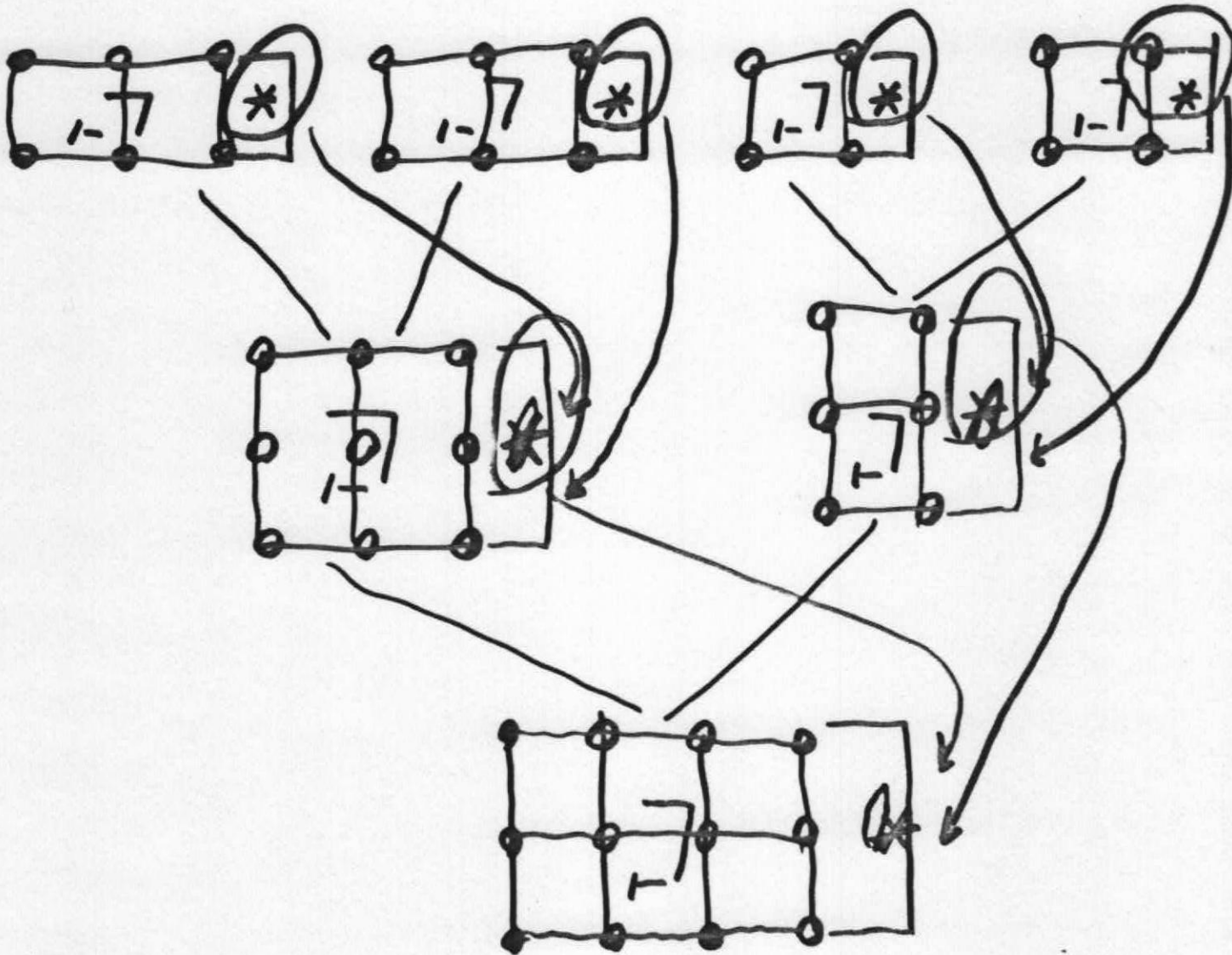
This computation is called backsolving.

# BACKSOLVE: $L^{-1}$ PART (GOING UP)



EACH MATRIX OCCUPIES A SQUARE IN CM AND CORRESPONDING PIECE OF VECTOR  $b$  OCCUPIES A COLUMN TO THE LEFT OF IT.

EACH MATRIX OCCUPIES A SQUARE IN  $Q$  AND CORRESPONDING PIECE OF VECTOR  $b$  OCCUPIES A COLUMN TO THE LEFT OF IT.



BACKSOLVE:  $L^{-1}$  PART (GOING UP)

BACKSOLVE: U<sup>-1</sup>D<sup>-1</sup> PART  
(GOING DOWN)

RUNNING TIME: BACKSOLVE:

$$\log(\sqrt{n}) + \log(\sqrt{\frac{n}{2}}) + \dots \sim \underline{\text{const} \cdot \log n}$$

DATA MAPPING

IN LISPM: Construct the separator tree for Graph(A).

- each tree-node at level  $i$  is a struct corresponding to

some small submatrix of matrix  $A_e$  (see (P)).

- slots of struct contain:

- list of variables of this submatrix

- its sublist, which we eliminate

- address of the corner of this submatrix in the CM

- a dozen of other things, later converted into

printers for the CM part of the algorithm

IN CM:

- allocate space for all submatrices

- create a structure for operating on a set of matrices.

(by now we have a standard way of doing it)

- create printers for sending matrix and vector elements

from level to level.

To do this:

• First we sequentially load data from LispM struct into lower left corners of matrices in the CM

• Then we spread data to all processors of the same matrix. This is done in parallel for all matrices.

Complete algorithm

- (1) Create the necessary structures in LispM and CM  
(= data mapping)
- (2) Initialize submatrices and pieces of vector  $b$  at 0 level of CM, so that their direct sum equals  $A$  and  $b$  correspondingly.
- (3) Factor  $A^{-1}$
- (4) Backsolve: going up and down.
- (5) Read the solution  $x$  from CM.  
(The value of  $x$  is contained in the columns to the left of submatrices, where we initially put  $b$ . Each processor knows to which variable it corresponds. Processors, corresponding to the same variables, contain the same value of  $x$ ).

Note: 2 and 5 are done sequentially.