

Lecture 10

(1)

Bounds to Mixing via Multicommodity Flows.

Input: Ergodic P on state space Ω , stationary distn' π

Flow Problem: (directed)

• edge $e = (z, z')$ capacity $C(e) = \pi(z) \cdot P(z, z')$

is also called the ergodic flow from z to z'

• Demands: for $(x, y) \in \Omega^2$:

$$D(x, y) = \pi(x) \cdot \pi(y)$$

different commodity for every pair (x, y)

• Flow:

$f: P \rightarrow \mathbb{R}^+ \cup \{0\}$ where $P = \cup_{x, y} P_{xy}$
 \rightarrow simple paths from x to y

$$\text{s.t. } \sum_{p \in P_{xy}} f(p) = D(x, y)$$

• Cost of flow: $\rho(f) = \max_e \frac{f(e)}{C(e)}$ $\leftarrow \sum_{p \ni e} f(p)$

• length of flow: $l(f) = \max_{p: f(p) > 0} |p|$. (length of longest flow carrying path)

Theorem: For any lazy, ergodic MC $P = \frac{1}{2}I + \frac{1}{2}\hat{P}$ (\hat{P} is ergodic) and any flow f we have:

$$\tau_{\text{mix}} \leq O(\rho(f) \cdot l(f) \cdot \ln \pi_{\min}^{-1}),$$

where $\pi_{\min} = \min_{x \in \Omega} \pi(x)$.

Remark 1: Usually above bound dominated by $\rho(f)$, since $l(f)$, $\ln \pi_{\min}^{-1}$ are typically polynomial in the problem size.

Remark 2: We'll show a stronger result, replacing π_{\min} w/ $\pi(x)$ where x is starting state.

Remark 3: Flows provide upper bound of mixing. Their dual problem of sparsest cut provides a lower bound. Any SC provides a lower bound.

The Poincaré Constant

Def: Let $\varphi: \Omega \rightarrow \mathbb{R}$ be any function. Then

$$\mathbb{E}_\pi \varphi = \sum_x \pi(x) \varphi(x)$$

$$\begin{aligned} \text{Var}_\pi \varphi &= \sum_x \pi(x) (\varphi(x) - \mathbb{E}_\pi \varphi)^2 = \sum_x \pi(x) \varphi(x)^2 - (\mathbb{E}_\pi \varphi)^2 = \\ &= \sum_x \pi(x) \varphi(x)^2 \sum_y \pi(y) - \sum_x \pi(x) \varphi(x) \cdot \sum_y \pi(y) \varphi(y) = \\ &= \sum_x \pi(x) \pi(y) (\varphi(x)^2 - \varphi(x) \varphi(y)) = \\ &= \frac{1}{2} \sum_{x,y} \pi(x) \pi(y) (\varphi(x) - \varphi(y))^2. \end{aligned}$$

Def: Local Variance:

$$\mathcal{E}_\pi(\varphi, \varphi) = \frac{1}{2} \sum_{x,y} \pi(x) P(x,y) (\varphi(x) - \varphi(y))^2$$

↳ also called the Dirichlet form (because $\varphi(x) - \varphi(y)$ is the discrete derivative of φ)

Def: The Poincaré constant is

$$\alpha := \inf_{\varphi \text{ non-constant}} \frac{\mathcal{E}_\pi(\varphi, \varphi)}{\text{Var}_\pi \varphi}$$

Theorem 1: For any lazy ergodic P and any initial state $x \in \Omega$:

$$\tau_x(\varepsilon) \leq \frac{1}{\alpha} (2 \ln \varepsilon^{-1} + \ln \pi(x)^{-1}).$$

Theorem 2: For any ergodic P and any flow f for P :

[Sinclair 92;
Diaconis, Stroock '91]

$$\alpha \geq \frac{1}{\rho(f) \cdot \ell(f)}.$$

Thm 1 + Thm 2 \Rightarrow main theorem (choose $\varepsilon = \frac{1}{2e}$)

• $P = \frac{1}{2}(I + \hat{P})$ (P & \hat{P} have same stationary π).

• $[P\varphi](x) = \sum_y P(x,y) \varphi(y)$

$[P^t\varphi](x) = \sum_y P^t(x,y) \varphi(y) \xrightarrow{t \rightarrow \infty} \sum_y \pi(y) \varphi(y) \equiv E_\pi \varphi$

hence $Var_\pi P^t \varphi \xrightarrow{t \rightarrow \infty} 0$

• We are interested in the rate of convergence of $Var_\pi P^t \varphi$

• Main Lemma: For any $\varphi: \Omega \rightarrow \mathbb{R}$

proof postponed ↙

$Var_\pi P\varphi \leq Var_\pi \varphi - E_\pi(\varphi, \varphi) \leq Var_\pi \varphi (1 - \alpha)$.

• Corollary: $Var_\pi P^t \varphi \leq (1 - \alpha)^t \cdot Var_\pi \varphi$.

• for any $A \subseteq \Omega$ define $\varphi_A(x) = \begin{cases} 1, & x \in A \\ 0, & \text{ow.} \end{cases}$

- clearly $Var_\pi \varphi_A \leq 1$, hence $Var_\pi P^t \varphi_A \leq (1 - \alpha)^t \leq e^{-\alpha t}$

$\leq \varepsilon^2 \cdot \pi(x)$ (*)

setting $t = \frac{1}{\alpha} (\ln \pi(x)^{-1} + 2 \ln \varepsilon^{-1})$

- on the other hand:

$Var_\pi P^t \varphi_A \geq \pi(x) \left(\underbrace{[P^t \varphi_A](x)}_{\text{III } \textcircled{1}} - \underbrace{E_\pi P^t \varphi_A}_{\text{III}} \right)^2$

$\geq \pi(x) (P_x^t(A) - E_\pi \varphi_A)^2$

$= \pi(x) (P_x^t(A) - \pi(A))^2$ (**)

(*) + (**) \Rightarrow for $t = \frac{1}{\alpha} (\ln \pi(x)^{-1} + 2 \ln \varepsilon^{-1})$

$|P_x^t(A) - \pi(A)| \leq \varepsilon$

$\textcircled{1} [P^t \varphi_A](x) = \sum_y P^t(x,y) \varphi_A(y)$
 $= \sum_{y \in A} P^t(x,y) = P_x^t(A)$

But A is arbitrary event $\Rightarrow \|P_x^t - \pi\|_{TV} \leq \varepsilon$, for t chosen as above.

Remains to show main lemma:

(4)

$$\begin{aligned} \circ [P\varphi](x) &= \sum_y P(x,y)\varphi(y) = \\ &= \frac{1}{2}\varphi(x) + \frac{1}{2} \sum_y \hat{P}(x,y)\varphi(y) = \\ &= \frac{1}{2} \sum_y \hat{P}(x,y)(\varphi(x) + \varphi(y)). \end{aligned}$$

◦ w.l.o.g. assume $E_{\pi}\varphi = 0$ (shifting by a constant won't change any of the variances computed below)

$$\begin{aligned} \circ \text{Var}_{\pi} P\varphi &= \sum_x \pi(x) \cdot ([P\varphi](x))^2 \\ &= \frac{1}{4} \sum_x \pi(x) \left(\sum_y \hat{P}(x,y)(\varphi(x) + \varphi(y)) \right)^2 \\ &\leq \frac{1}{4} \sum_{x,y} \pi(x) \hat{P}(x,y) (\varphi(x) + \varphi(y))^2 \quad (\text{by Cauchy-Schwartz}) \end{aligned}$$

$$\begin{aligned} \circ \text{Var}_{\pi} \varphi &= \frac{1}{2} \sum_x \pi(x) \varphi(x)^2 + \frac{1}{2} \sum_y \pi(y) \varphi(y)^2 \quad (\text{using that } E_{\pi}\varphi = 0) \\ &= \frac{1}{2} \sum_{x,y} \pi(x) \varphi(x)^2 \hat{P}(x,y) + \frac{1}{2} \sum_{x,y} \pi(x) \hat{P}(x,y) \varphi(y)^2 \\ &= \frac{1}{2} \sum_{x,y} \pi(x) \hat{P}(x,y) (\varphi(x)^2 + \varphi(y)^2). \end{aligned}$$

$$\begin{aligned} \circ \text{Hence: } \text{Var}_{\pi} \varphi - \text{Var}_{\pi} P\varphi &\geq \frac{1}{4} \sum_{x,y} \pi(x) \hat{P}(x,y) (\varphi(x) - \varphi(y))^2 \\ &= \frac{1}{2} \sum_{x,y} \pi(x) P(x,y) (\varphi(x) - \varphi(y))^2 = E_{\pi}(\varphi, \varphi). \end{aligned}$$

□
(end of proof of Thm 4)

Proof of Thm 2:

$$\begin{aligned}
 2 \operatorname{Var}_{\pi} \varphi &= \sum_{x,y} \pi(x)\pi(y) (\varphi(x) - \varphi(y))^2 \\
 &= \sum_{x,y} \sum_{p \in P_{xy}} f(p) (\varphi(x) - \varphi(y))^2 \\
 &= \sum_{x,y} \sum_{p \in P_{xy}} f(p) \left(\sum_{(u,v) \in p} (\varphi(u) - \varphi(v)) \right)^2 && \text{(massaging formula to make it up from local variances)} \\
 &\leq \sum_{x,y} \sum_{p \in P_{xy}} f(p) |p| \cdot \sum_{(u,v) \in p} (\varphi(u) - \varphi(v))^2 && \text{(Cauchy-Schwartz)} \\
 &= \sum_{e=(u,v)} (\varphi(u) - \varphi(v))^2 \sum_{p \ni e} f(p) \cdot |p| \\
 &\leq \ell(f) \sum_{e=(u,v)} (\varphi(u) - \varphi(v))^2 \sum_{p \ni e} f(p) \\
 &\leq \ell(f) \sum_{e=(u,v)} (\varphi(u) - \varphi(v))^2 C(e) \cdot p(f) && f(e) \leq p(f) \cdot C(e) \\
 &= \ell(f) \cdot p(f) \cdot \sum_{e=(u,v)} (\varphi(u) - \varphi(v))^2 \cdot \pi(u) P(u,v) \\
 &= \ell(f) \cdot p(f) \cdot 2 \cdot \mathcal{E}_{\pi}(\varphi, \varphi).
 \end{aligned}$$

$$\Rightarrow \underset{\varphi \text{ non-constant}}{\frac{\mathcal{E}_{\pi}(\varphi, \varphi)}{\operatorname{Var}_{\pi} \varphi}} \geq \frac{1}{\ell(f) p(f)} \quad \square$$

Some Further Intuition: Reversible Markov Chains and the Poincaré Constant

o **Known fact:** If P is reversible and ergodic then its eigenvalues are:

$$1 = \lambda_1 > \lambda_2 > \dots > \lambda_N > -1$$

and its spectral gap $1 - \lambda_2$ satisfies:

$$1 - \lambda_2 \equiv \inf_{\phi \text{ non-constant}} \frac{E_{\pi}(\phi, \phi)}{\text{Var}_{\pi} \phi}$$

we: the first part in lecture 2; the second part follows from the variational characterization of eigenvalues of symmetric matrices, using the symmetrization operator we constructed in lec 2 for reversible chains

o If P is also lazy, then $\lambda_N > 0$ and hence $\max_{i \geq 2} |1 - \lambda_i| \equiv 1 - \lambda_2$.

o Now suppose an arbitrary starting state $x \in \Omega$, and suppose

$$P_x^{(0)} = \sum_{i=1}^N \alpha_i e_i, \text{ where } e_i \text{ is the eigenvector corresponding to eigenvalue } \lambda_i$$

$$\text{then } P_x^t = P_x^{(0)} \cdot P^t = \alpha_1 e_1 + \underbrace{\sum_{i \geq 2} \alpha_i \lambda_i^t e_i}_{\downarrow t \rightarrow \infty}$$

0 (by the fundamental Thm of Markov Chains)

Hence:

$$\begin{aligned} \Delta_x(t) &\leq \lambda_2^t \cdot \left(\sum_{i \geq 2} \sum_y |\alpha_i| \cdot |e_i(y)| \right) \\ &\leq (1 - (1 - \lambda_2))^t \cdot (-||-) \\ &\leq e^{-(1 - \lambda_2) \cdot t} \cdot (-||-) \end{aligned}$$

Therefore, the rate of convergence is dictated by $1 - \lambda_2 \equiv$ Poincaré constant