

# Inference and Representation

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# Today: learning undirected graphical models

- ① Learning MRFs
  - a. Feature-based (log-linear) representation of MRFs
  - b. Maximum likelihood estimation
  - c. Maximum entropy view
- ② Getting around complexity of inference
  - a. Using approximate inference (e.g., TRW) within learning
  - b. Pseudo-likelihood

# Recall: ML estimation in Bayesian networks

- Maximum likelihood estimation:  $\max_{\theta} \ell(\theta; \mathcal{D})$ , where

$$\begin{aligned}\ell(\theta; \mathcal{D}) = \log p(\mathcal{D}; \theta) &= \sum_{\mathbf{x} \in \mathcal{D}} \log p(\mathbf{x}; \theta) \\ &= \sum_i \sum_{\hat{\mathbf{x}}_{pa(i)}} \sum_{\substack{\mathbf{x} \in \mathcal{D}: \\ \mathbf{x}_{pa(i)} = \hat{\mathbf{x}}_{pa(i)}}} \log p(x_i \mid \hat{\mathbf{x}}_{pa(i)})\end{aligned}$$

- In Bayesian networks, we have the closed form ML solution:

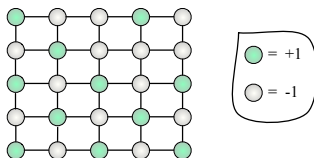
$$\theta_{x_i \mid \mathbf{x}_{pa(i)}}^{ML} = \frac{N_{x_i, \mathbf{x}_{pa(i)}}}{\sum_{\hat{x}_i} N_{\hat{x}_i, \mathbf{x}_{pa(i)}}}$$

where  $N_{x_i, \mathbf{x}_{pa(i)}}$  is the number of times that the (partial) assignment  $x_i, \mathbf{x}_{pa(i)}$  is observed in the training data

- We were able to estimate each CPD independently because the objective **decomposes** by variable and parent assignment

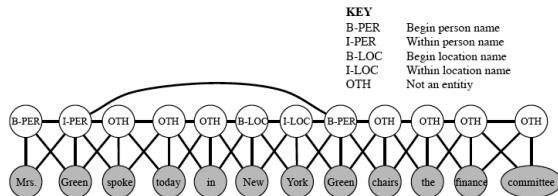
# Parameter estimation in Markov networks

- How do we learn the parameters of an Ising model?



$$p(x_1, \dots, x_n) = \frac{1}{Z} \exp \left( \sum_{i < j} w_{i,j} x_i x_j - \sum_i u_i x_i \right)$$

- What about for a skip-chain CRF?



- The global normalization constant  $Z(\theta)$  kills decomposability:

$$\begin{aligned}\theta^{ML} &= \arg \max_{\theta} \log \prod_{\mathbf{x} \in \mathcal{D}} p(\mathbf{x}; \theta) \\ &= \arg \max_{\theta} \sum_{\mathbf{x} \in \mathcal{D}} \left( \sum_c \log \phi_c(\mathbf{x}_c; \theta) - \log Z(\theta) \right) \\ &= \arg \max_{\theta} \left( \sum_{\mathbf{x} \in \mathcal{D}} \sum_c \log \phi_c(\mathbf{x}_c; \theta) \right) - |\mathcal{D}| \log Z(\theta)\end{aligned}$$

- The log-partition function prevents us from decomposing the objective into a sum over terms for each potential
- Solving for the parameters becomes much more complicated

# What are the parameters?

- Parameterize  $\phi_c(\mathbf{x}_c; \theta)$  using a log-linear parameterization:
  - Single weight vector  $\mathbf{w} \in \mathbb{R}^d$  that is used globally
  - For each potential  $c$ , a vector-valued **feature function**  $\mathbf{f}_c(\mathbf{x}_c) \in \mathbb{R}^d$
  - Then,  $\phi_c(\mathbf{x}_c; \mathbf{w}) = \exp(\mathbf{w} \cdot \mathbf{f}_c(\mathbf{x}_c))$
- Example: discrete-valued MRF with only edge potentials, where each variable takes  $k$  states
  - Let  $d = k^2|E|$ , and let  $w_{i,j,x_i,x_j} = \log \phi_{ij}(x_i, x_j)$
  - Let  $f_{i,j}(x_i, x_j)$  have a 1 in the dimension corresponding to  $(i, j, x_i, x_j)$  and 0 elsewhere
- The joint distribution is in the *exponential family*!

$$p(\mathbf{x}; \mathbf{w}) = \exp\{\mathbf{w} \cdot \mathbf{f}(\mathbf{x}) - \log Z(\mathbf{w})\},$$

where  $f(\mathbf{x}) = \sum_c \mathbf{f}_c(\mathbf{x}_c)$  and  $Z(\mathbf{w}) = \sum_{\mathbf{x}} \exp\{\sum_c \mathbf{w} \cdot \mathbf{f}_c(\mathbf{x}_c)\}$

- This formulation allows for parameter sharing

# Log-likelihood for log-linear models

$$\begin{aligned}\theta^{ML} &= \arg \max_{\theta} \left( \sum_{\mathbf{x} \in \mathcal{D}} \sum_c \log \phi_c(\mathbf{x}_c; \theta) \right) - |\mathcal{D}| \log Z(\theta) \\ &= \arg \max_{\mathbf{w}} \left( \sum_{\mathbf{x} \in \mathcal{D}} \sum_c \mathbf{w} \cdot \mathbf{f}_c(\mathbf{x}_c) \right) - |\mathcal{D}| \log Z(\mathbf{w}) \\ &= \arg \max_{\mathbf{w}} \mathbf{w} \cdot \left( \sum_{\mathbf{x} \in \mathcal{D}} \sum_c \mathbf{f}_c(\mathbf{x}_c) \right) - |\mathcal{D}| \log Z(\mathbf{w})\end{aligned}$$

- The first term is linear in  $\mathbf{w}$
- The second term is also a function of  $\mathbf{w}$ :

$$\log Z(\mathbf{w}) = \log \sum_{\mathbf{x}} \exp \left( \mathbf{w} \cdot \sum_c \mathbf{f}_c(\mathbf{x}_c) \right)$$

# Log-likelihood for log-linear models

$$\log Z(\mathbf{w}) = \log \sum_{\mathbf{x}} \exp \left( \mathbf{w} \cdot \sum_c \mathbf{f}_c(\mathbf{x}_c) \right)$$

- $\log Z(\mathbf{w})$  does not decompose
  - No closed form solution; even *computing* likelihood requires inference
- Letting  $\mathbf{f}(\mathbf{x}) = \sum_c \mathbf{f}_c(\mathbf{x}_c)$ , we showed in Lecture 7 that:

$$\nabla_{\mathbf{w}} \log Z(\mathbf{w}) = \mathbb{E}_{p(\mathbf{x}; \mathbf{w})}[\mathbf{f}(\mathbf{x})] = \sum_c \mathbb{E}_{p(\mathbf{x}_c; \mathbf{w})}[\mathbf{f}_c(\mathbf{x}_c)]$$

- Thus, the gradient of the log-partition function can be computed by *inference*, computing marginals with respect to the current parameters  $\mathbf{w}$
- Similarly, you can show that 2nd derivative of the log-partition function gives the second-order moments, i.e.

$$\nabla^2 \log Z(\mathbf{w}) = \left( \mathbb{E}_{p(\mathbf{x}; \mathbf{w})}[f^i(\mathbf{x})f^j(\mathbf{x})] \right)_{ij} = \text{cov}[\mathbf{f}(\mathbf{x})]$$

- Since covariance matrices are always positive semi-definite, this proves that  $\log Z(\mathbf{w})$  is convex (so  $-\log Z(\mathbf{w})$  is concave)



# Solving the maximum likelihood problem in MRFs

$$\ell(\mathbf{w}; \mathcal{D}) = \frac{1}{|\mathcal{D}|} \mathbf{w} \cdot \left( \sum_{\mathbf{x} \in \mathcal{D}} \sum_c \mathbf{f}_c(\mathbf{x}_c) \right) - \log Z(\mathbf{w})$$

- First, note that the weights  $\mathbf{w}$  are unconstrained, i.e.  $\mathbf{w} \in \mathbb{R}^d$
- The objective function is jointly concave. Apply any **convex optimization** method to learn!
- Can use gradient ascent, **stochastic gradient ascent**, quasi-Newton methods such as limited memory BFGS (L-BFGS)
- Let's study some properties of the ML solution!

$$\begin{aligned} \frac{d}{dw_k} \ell(\mathbf{w}; \mathcal{D}) &= \frac{1}{|\mathcal{D}|} \sum_{\mathbf{x} \in \mathcal{D}} \sum_c (\mathbf{f}_c(\mathbf{x}_c))_k - \sum_c \mathbb{E}_{p(\mathbf{x}_c; \mathbf{w})}[(\mathbf{f}_c(\mathbf{x}_c))_k] \\ &= \sum_c \frac{1}{|\mathcal{D}|} \sum_{\mathbf{x} \in \mathcal{D}} (\mathbf{f}_c(\mathbf{x}_c))_k - \sum_c \mathbb{E}_{p(\mathbf{x}_c; \mathbf{w})}[(\mathbf{f}_c(\mathbf{x}_c))_k] \end{aligned}$$

# The gradient of the log-likelihood

$$\frac{\partial}{\partial w_k} \ell(\mathbf{w}; \mathcal{D}) = \sum_c \frac{1}{|\mathcal{D}|} \sum_{\mathbf{x} \in \mathcal{D}} (\mathbf{f}_c(\mathbf{x}_c))_k - \sum_c \mathbb{E}_{p(\mathbf{x}_c; \mathbf{w})} [(\mathbf{f}_c(\mathbf{x}_c))_k]$$

- Difference of expectations!
- Consider the earlier pairwise MRF example. This then reduces to:

$$\frac{\partial}{\partial w_{i,j,\hat{x}_i,\hat{x}_j}} \ell(\mathbf{w}; \mathcal{D}) = \left( \frac{1}{|\mathcal{D}|} \sum_{\mathbf{x} \in \mathcal{D}} 1[x_i = \hat{x}_i, x_j = \hat{x}_j] \right) - p(\hat{x}_i, \hat{x}_j; \mathbf{w})$$

- Setting derivative to zero, we see that for the maximum likelihood parameters  $\mathbf{w}^{ML}$ , we have

$$p(\hat{x}_i, \hat{x}_j; \mathbf{w}^{ML}) = \frac{1}{|\mathcal{D}|} \sum_{\mathbf{x} \in \mathcal{D}} 1[x_i = \hat{x}_i, x_j = \hat{x}_j]$$

for all edges  $ij \in E$  and states  $\hat{x}_i, \hat{x}_j$

- Model marginals for ML solution equal the empirical marginals!
- Called **moment matching**, and is a property of maximum likelihood learning in exponential families

Gradient ascent requires repeated marginal inference,  
which in many models is **hard!**

We will return to this shortly.

# Maximum entropy (MaxEnt)

- We can approach the modeling task from an entirely different point of view
- Suppose we know some expectations with respect to a (fully general) distribution  $p(\mathbf{x})$ :

$$\text{(true)} \sum_{\mathbf{x}} p(\mathbf{x}) f_i(\mathbf{x}), \quad \text{(empirical)} \frac{1}{|\mathcal{D}|} \sum_{\mathbf{x} \in \mathcal{D}} f_i(\mathbf{x}) = \alpha_i$$

- Assuming that the expectations are consistent with one another, there may exist **many** distributions which satisfy them. Which one should we select?

The most uncertain or flexible one, i.e., the one with maximum entropy.

- This yields a new optimization problem:

$$\begin{aligned} \max_p H(p(\mathbf{x})) &= - \sum_{\mathbf{x}} p(\mathbf{x}) \log p(\mathbf{x}) \\ \text{s.t.} \quad \sum_{\mathbf{x}} p(\mathbf{x}) f_i(\mathbf{x}) &= \alpha_i \\ \sum_{\mathbf{x}} p(\mathbf{x}) &= 1 \quad (\text{strictly concave w.r.t. } p(\mathbf{x})) \end{aligned}$$

# What does the MaxEnt solution look like? (c.f. Lec. 9)

- To solve the MaxEnt problem, we form the Lagrangian:

$$L = - \sum_{\mathbf{x}} p(\mathbf{x}) \log p(\mathbf{x}) - \sum_i \lambda_i \left( \sum_{\mathbf{x}} p(\mathbf{x}) f_i(\mathbf{x}) - \alpha_i \right) - \mu \left( \sum_{\mathbf{x}} p(\mathbf{x}) - 1 \right)$$

- Then, taking the derivative of the Lagrangian,

$$\frac{\partial L}{\partial p(\mathbf{x})} = -1 - \log p(\mathbf{x}) - \sum_i \lambda_i f_i(\mathbf{x}) - \mu$$

- And setting to zero, we obtain:

$$p^*(\mathbf{x}) = \exp \left( -1 - \mu - \sum_i \lambda_i f_i(\mathbf{x}) \right) = e^{-1-\mu} e^{-\sum_i \lambda_i f_i(\mathbf{x})}$$

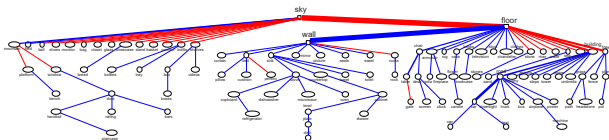
- From the constraint  $\sum_{\mathbf{x}} p(\mathbf{x}) = 1$  we obtain  $e^{1+\mu} = \sum_{\mathbf{x}} e^{-\sum_i \lambda_i f_i(\mathbf{x})} = Z(\lambda)$
- We conclude that the maximum entropy distribution has the form (substituting  $w_i = -\lambda_i$ )

$$p^*(\mathbf{x}) = \frac{1}{Z(\mathbf{w})} \exp \left( \sum_i w_i f_i(\mathbf{x}) \right)$$

# Equivalence of maximum likelihood and maximum entropy

- Feature constraints + MaxEnt  $\Rightarrow$  exponential family!
- We have seen a case of convex duality:
  - In one case, we assume exponential family and show that ML implies model expectations must match empirical expectations
  - In the other case, we assume model expectations must match empirical feature counts and show that MaxEnt implies exponential family distribution
- Can show that one is the dual of the other, and thus both obtain the same value of the objective at optimality (no duality gap)
- Besides providing insight into the ML solution, this also gives an alternative way to (approximately) solve the learning problem

# Chow-Liu algorithm for MRF structure learning



- Recall the PS 3 problem on structure learning of tree-structured MRFs:

$$\max_T \max_{\theta_T} \sum_{\mathbf{x} \in \mathcal{D}} \log p_T(\mathbf{x}; \theta_T).$$

- You used the fact that, for a fixed tree  $T$ , the maximum likelihood parameters, i.e.

$$\theta_T^{ML} = \arg \max_{\theta_T} \sum_{\mathbf{x} \in \mathcal{D}} \log p_T(\mathbf{x}; \theta_T).$$

have  $p_T(x_i, x_j; \theta_T^{ML}) = \hat{p}(x_i, x_j)$ , the latter computed from the data  $\mathcal{D}$

- For the special case of trees, the mapping  $\mu \rightarrow \theta$  has a simple closed-form solution:

$$p_T(\mathbf{x}) = \prod_{(i,j) \in T} \frac{p_T(x_i, x_j)}{p_T(x_i)p_T(x_j)} \prod_{j \in V} p_T(x_j)$$

# Chow-Liu algorithm for MRF structure learning

- This then gave the following optimization problem

$$\max_T \sum_{\mathbf{x} \in \mathcal{D}} \log \left[ \prod_{(i,j) \in T} \frac{\hat{p}(x_i, x_j)}{\hat{p}(x_i) \hat{p}(x_j)} \prod_{j \in V} \hat{p}(x_j) \right]$$

which you solved using a maximum spanning tree algorithm

- For general graphs, solving the maximum entropy problem is itself intractable



How can we get around the complexity of inference during learning?

- Recall the original learning objective

$$\ell(\mathbf{w}; \mathcal{D}) = \frac{1}{|\mathcal{D}|} \mathbf{w} \cdot \left( \sum_{\mathbf{x} \in \mathcal{D}} \sum_c \mathbf{f}_c(\mathbf{x}_c) \right) - \log Z(\mathbf{w})$$

- Use any of the sampling approaches (e.g., Gibbs sampling) that we discussed in Lecture 9
- All we need for learning (i.e., to compute the derivative of  $\ell(\mathbf{w}, \mathcal{D})$ ) are **marginals** of the distribution
- No need to ever estimate  $\log Z(\mathbf{w})$

# Using approximations of the log-partition function

- We can substitute the original learning objective

$$\ell(\mathbf{w}; \mathcal{D}) = \frac{1}{|\mathcal{D}|} \mathbf{w} \cdot \left( \sum_{\mathbf{x} \in \mathcal{D}} \sum_c \mathbf{f}_c(\mathbf{x}_c) \right) - \log Z(\mathbf{w})$$

with one that uses a tractable approximation of the log-partition function:

$$\tilde{\ell}(\mathbf{w}; \mathcal{D}) = \frac{1}{|\mathcal{D}|} \mathbf{w} \cdot \left( \sum_{\mathbf{x} \in \mathcal{D}} \sum_c \mathbf{f}_c(\mathbf{x}_c) \right) - \log \tilde{Z}(\mathbf{w})$$

- Recall from Lecture 9 that we came up with a *convex relaxation* that provided an upper bound on the log-partition function,

$$\log Z(\mathbf{w}) \leq \log \tilde{Z}(\mathbf{w})$$

(e.g., tree-reweighted belief propagation, log-determinant relaxation)

- Using this, we obtain a *lower bound* on the learning objective

$$\ell(\mathbf{w}; \mathcal{D}) \geq \tilde{\ell}(\mathbf{w}; \mathcal{D})$$

- Again, to compute the derivatives we only need *pseudo-marginals* from the variational inference algorithm

# Pseudo-likelihood

- Alternatively, can we come up with a *different* objective function (i.e., a different *estimator*) which succeeds at learning while avoiding inference altogether?
- Pseudo-likelihood method (Besag 1971) yields an exact solution if the data is generated by a model in our model family  $p(\mathbf{x}; \theta^*)$  and  $|\mathcal{D}| \rightarrow \infty$  (i.e., it is **consistent**)
- Note that, via the chain rule,

$$p(\mathbf{x}; \mathbf{w}) = \prod_i p(x_i | x_1, \dots, x_{i-1}; \mathbf{w})$$

- We consider the following approximation:

$$p(\mathbf{x}; \mathbf{w}) \approx \prod_i p(x_i | x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_n; \mathbf{w}) = \prod_i p(x_i | x_{-i}; \mathbf{w})$$

where we have added conditioning over additional variables

# Pseudo-likelihood

- The pseudo-likelihood method replaces the likelihood,

$$\ell(\theta; \mathcal{D}) = \frac{1}{|\mathcal{D}|} \log p(\mathcal{D}; \theta) = \frac{1}{|\mathcal{D}|} \sum_{m=1}^{|\mathcal{D}|} \log p(\mathbf{x}^m; \theta)$$

with the following approximation:

$$\ell_{PL}(\mathbf{w}; \mathcal{D}) = \frac{1}{|\mathcal{D}|} \sum_{m=1}^{|\mathcal{D}|} \sum_{i=1}^n \log p(x_i^m | x_{N(i)}^m; \mathbf{w})$$

(we replaced  $x_{-i}$  with  $x_{N(i)}$ ,  $i$ 's Markov blanket)

- For example, suppose we have a pairwise MRF. Then,

$$p(x_i^m | x_{N(i)}^m; \mathbf{w}) = \frac{1}{Z(x_{N(i)}^m; \mathbf{w})} e^{\sum_{j \in N(i)} \theta_{ij}(x_i^m, x_j^m)}, \quad Z(x_{N(i)}^m; \mathbf{w}) = \sum_{\hat{x}_i} e^{\sum_{j \in N(i)} \theta_{ij}(\hat{x}_i, x_j^m)}$$

- More generally, and using the log-linear parameterization, we have:

$$\log p(x_i^m | x_{N(i)}^m; \mathbf{w}) = \mathbf{w} \cdot \sum_{c:i \in c} f_c(x_c^m) - \log Z(x_{N(i)}^m; \mathbf{w})$$

- This objective only involves summation over  $x_i$  and is tractable
- Has many small partition functions (one for each variable and each setting of its neighbors) instead of one big one
- It is still concave in  $\mathbf{w}$  and thus has no local maxima
- Assuming the data is drawn from a MRF with parameters  $\mathbf{w}^*$ , can show that as the number of data points gets large,  $\mathbf{w}^{PL} \rightarrow \mathbf{w}^*$