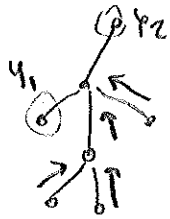
What if you want to compute marginals for many variables?

i.e. $pr(y_i \mid \vec{x}) \quad \forall i \in Y$?

Can re-run variable elimination, once for each $i \in Y$, but this duplicates much of the effort, e.g.

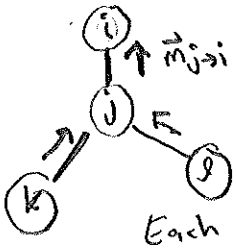
i.e. $p(x_1, \ldots, x_n) \propto \prod_i \phi_i \prod_{ij \in E} \phi_{ij}$



Consider the case of trees. The sum-product belief propagation algorithm computes all marginals with just double the computation and using linear space.

Based on message-passing of "messages" (tables of partial summations) between neighboring vertices of the graph.

The message sent from variable j to $i \in N(j)$ is:



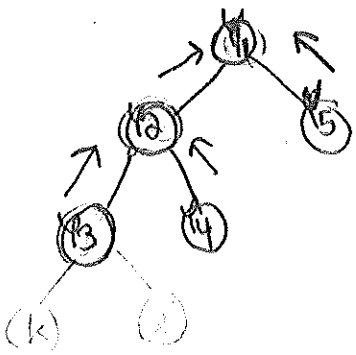
$$\text{Sum-product messages} \quad m_{j \to i}(x_i) = \sum_{x_j} \left(\phi_j(x_j)\, \phi_{ij}(x_i, x_j) \prod_{k \in N(j) \setminus i} m_{k \to j}(x_j) \right)$$

Each message $\vec{m}_{j \to i}$ is a vector with one value for each state of X_i.

→ In order to compute $\vec{m}_{j \to i}$, must already have $\vec{m}_{k \to j}$ for $k \in N(j) \setminus i$.

Thus, there must be a specific ordering to the messages.

Suppose we want to compute $pr(y_1)$. $\propto \sum_{y_2 \ldots y_5} \prod \phi \ldots$ Root tree at Y_1 and send messages from leafs to root:



Root = Y_1

$$m_{5 \to 1}(y_1) = \sum_{y_5} \phi_5(y_5)\, \phi_{15}(y_1, y_5)$$

$$m'_{3 \to 2}(y_2) = \sum_{y_3} \phi_3(y_3)\, \phi_{23}(y_2, y_3)$$

$$m_{4 \to 2}(y_2) = \sum_{y_4} \phi_4(y_4)\, \phi_{24}(y_2, y_4)$$

$$m'_{2\to 1}(y_1) = C_3 \sum_{y_2} \phi_2(y_2)\,\phi_{12}(y_1, y_2)\, m_{3\to 2}(y_2)\, m_{4\to 2}(y_2)$$

Finally, $p(y_1) \propto C_3 \phi_1(y_1)\, m_{2\to 1}(y_1)\, m_{5\to 1}(y_1)$.

Elimination algorithm on trees is <u>equivalent</u> to message passing!

What about computing $p(y_5)$? Could re-run algorithm, rooted at y_5. Or...

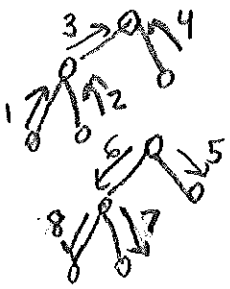
Belief Propagation (BP)

Input: Tree T with potentials $\phi_i(x_i)$, $\phi_{ij}(x_i, x_j)$ $\forall i,j \in T$.

Choose root r. (arbitrary)

Pass messages from leafs to r.

Pass messages from r to leafs.



Compute $p(y_i) \propto \phi_i(y_i) \prod_{j \in N(i)} m_{j\to i}(y_i)$. $\forall i$

Running time = 2 · cost of one var. elimination = $\Theta(nk^2)$,

where n = # nodes and k = # states per node.

Possible numerical difficulties if multiplying many small factors.

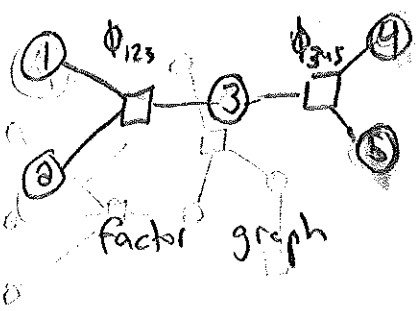
Notice that constants passed on from message to messages then canceled during normalization.

Note: normalizing messages helps, but over/underflow can still happen. Working in log-space is preferred (see slides).

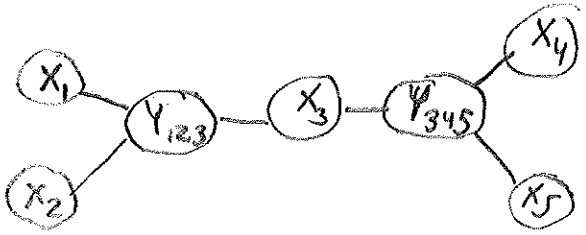
Alternative update:

$$m^{new}_{j\to i}(x_i) = \frac{m^{orig}_{j\to i}(x_i)}{\sum_{\hat{x}_i} m^{orig}_{j\to i}(\hat{x}_i)} \quad \text{constant.}$$

This applies to any tree-structured pairwise MRF. What about a tree-structured <u>factor graph</u>?



Use transf. from homework →



pairwise MRF

$\phi_{123}(y_{123})$, $\phi_{345}(y_{345})$ single node potentials

$\phi(x_i, y_{123}) = 0$ if x_i inconsistent w/ y_{123} | o.w. pairwise node potentials

Messages can be computed slightly more efficiently:

$$m_{i\to f}(y_f) = \sum_{x_i} \phi_i(x_i)\,\phi_{i,f}(x_i, y_f) \prod_{f' \in N(i)} m_{f'\to i}(x_i)$$

$$= \phi_i(x_i(y_f)) \prod_{f' \in N(i)\setminus f} m_{f'\to i}(x_i(y_f))$$

} one value for each x_i. Just store $m_{i\to f}(x_i)\ \forall x_i$.

$$m_{f\to i}(x_i) = \sum_{y_f} \phi_f(y_f)\,\phi_{i,f}(x_i, y_f) \prod_{j \in N(f)\setminus i} m_{j\to f}(y_f)$$

$$= \sum_{y_f :} \phi_f(y_f) \prod_{j \in N(f)\setminus i} m_{j\to f}(y_f)$$

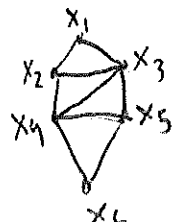
$x_i = \hat{x}_i(y_f)$

$$= \sum_{\vec{x}_{f\setminus i}} \phi_f(x_i, \vec{x}_{f\setminus i}) \prod_{j \in f\setminus i} m_{j\to f}(x_j)$$

What about graphs that aren't trees? e.g.) 

<u>Junction tree algorithm</u> (also called "clique trees")

Turn graph into <u>tree</u> by <u>triangulating</u> (making chordal) and replacing every maximal clique with a variable



elim. ordering x_1, x_2, x_3 →

$Y_{123} - Y_{234} - Y_{345} - Y_{456}$

Elim. ordering found by max-cardinality algorithm.

Again, messages can be computed slightly more efficiently using the structure.