

Dimensionality Reduction

Lecture 24

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Slides adapted from Carlos Guestrin and Luke Zettlemoyer

Dimensionality reduction

- Input data may have thousands or millions of dimensions!
 - e.g., text data has ???, images have ???
- **Dimensionality reduction**: represent data with fewer dimensions
 - easier learning – fewer parameters
 - visualization – show high dimensional data in 2D
 - discover “intrinsic dimensionality” of data
 - high dimensional data that is truly lower dimensional
 - noise reduction

Feature selection

- Want to learn $f:\mathbf{X}\rightarrow Y$
 - $\mathbf{X}=\langle X_1,\dots,X_n\rangle$
 - but some features are more important than others
- **Approach:** select subset of features to be used by learning algorithm
 - **Score** each feature (or sets of features)
 - **Select** set of features with best score

Greedy **forward** feature selection algorithm

- Pick a dictionary of features
 - e.g., polynomials for linear regression
- **Greedy**: Start from empty (or simple) set of features $F_0 = \emptyset$
 - Run learning algorithm for current set of features F_t
 - Obtain h_t
 - Select **next best feature X_j**
 - e.g., X_j that results in lowest held out error when learning with $F_t \cup \{X_j\}$
 - $F_{t+1} \leftarrow F_t \cup \{X_j\}$
 - Repeat

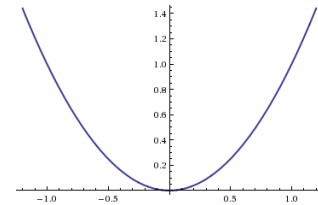
Greedy **backward** feature selection algorithm

- Pick a dictionary of features
 - e.g., polynomials for linear regression
- **Greedy:** Start with all features $F_0 = F$
 - Run learning algorithm for current set of features F_t
 - Obtain h_t
 - Select **next worst feature X_j**
 - e.g., X_j that results in lowest held out error learner when learning with $F_t - \{X_j\}$
 - $F_{t+1} \leftarrow F_t - \{X_j\}$
 - Repeat

Feature selection through regularization

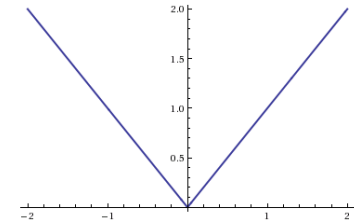
- Previously, we discussed regularization with a squared norm:

$$\hat{\theta} = \arg \min_{\theta} Loss(\theta; \mathcal{D}) + \lambda \sum_i \theta_i^2$$



- We motivated the L2 norm using the idea of **margin**
- What if we have reason to believe that there are only a few relevant features?
- In this case, we should regularize using the L1 norm!

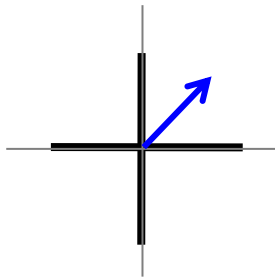
$$\hat{\theta} = \arg \min_{\theta} Loss(\theta; \mathcal{D}) + \lambda \sum_i |\theta_i|$$



- Big area of machine learning called “sparse recovery”

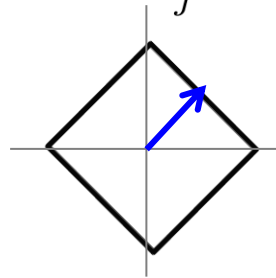
Feature selection through regularization

$$\|W\|_0 = \#\{W_j > 0\}$$



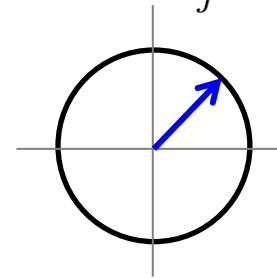
Minimizes # features
chosen

$$\|W\|_1 = \sum_j |W_j|$$



Convex
compromise

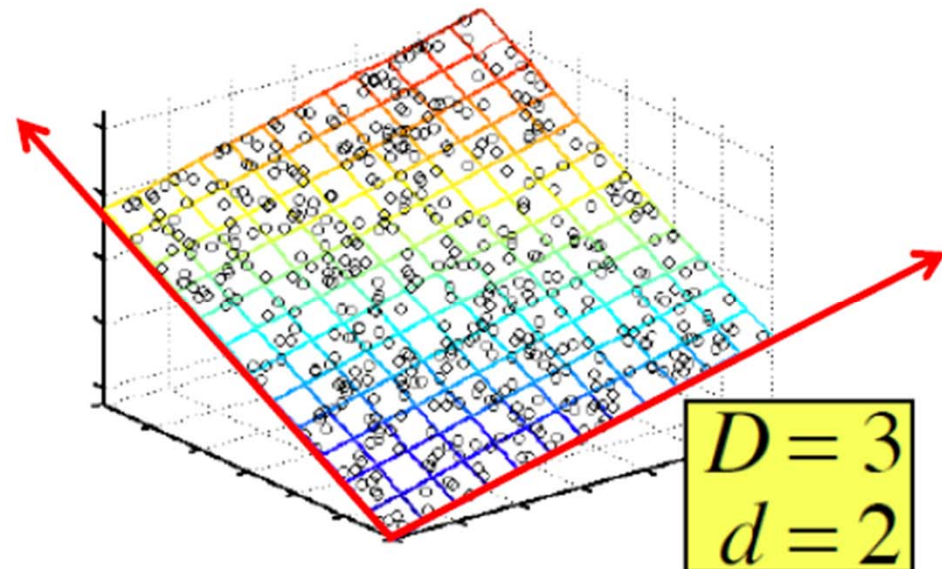
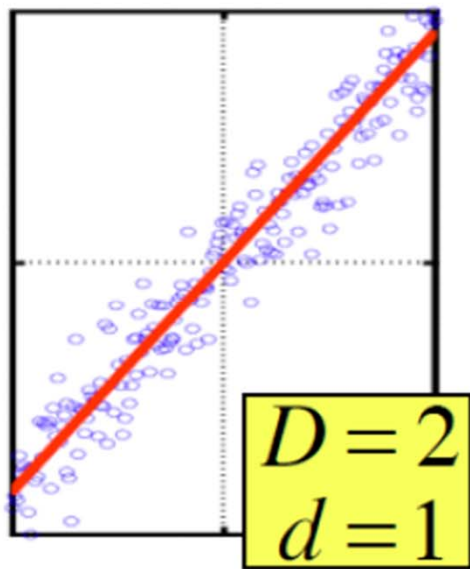
$$\|W\|_2 = \sqrt{\sum_j W_j^2}$$



Small weights of
features chosen

Dimension reduction

- Assumption: data (approximately) lies on a lower dimensional space
- Examples:



Slide from Yi Zhang

Lower dimensional projections

- Rather than picking a subset of the features, we can obtain new ones by combining existing features $x_1 \dots x_n$

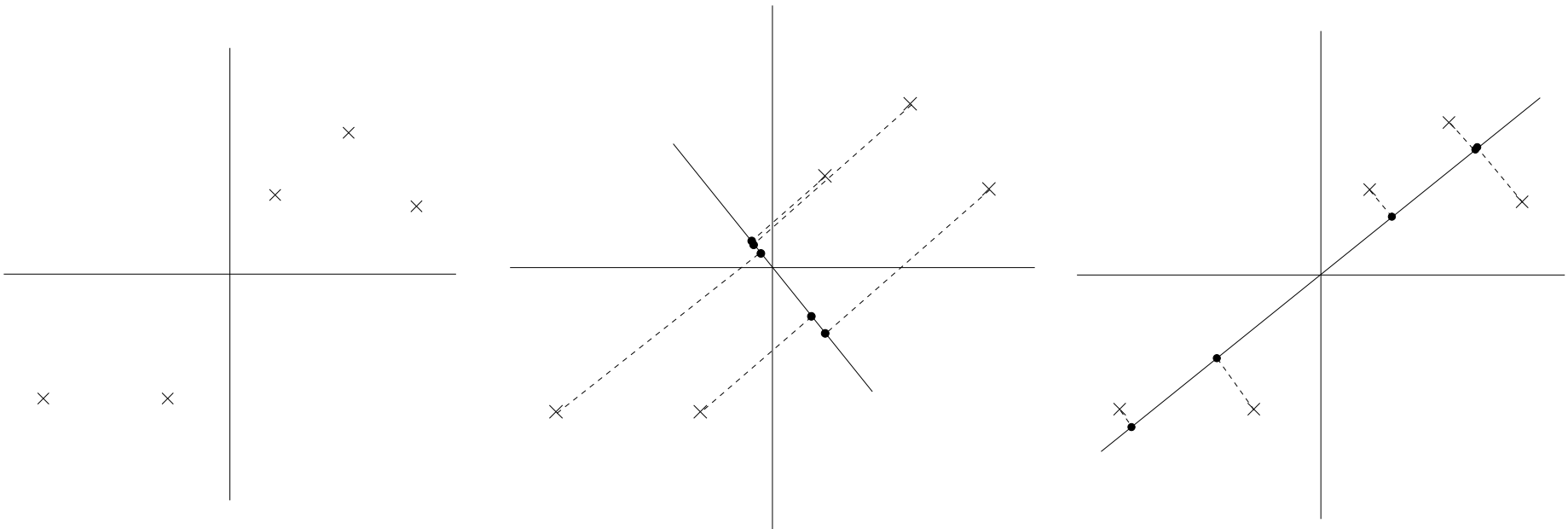
$$z_1 = w_0^{(1)} + \sum_i w_i^{(1)} x_i$$

...

$$z_k = w_0^{(k)} + \sum_i w_i^{(k)} x_i$$

- New features are linear combinations of old ones
- Reduces dimension when $k < n$
- Let's consider how to do this in the **unsupervised setting**
 - just \mathbf{X} , but no Y

Which projection is better?



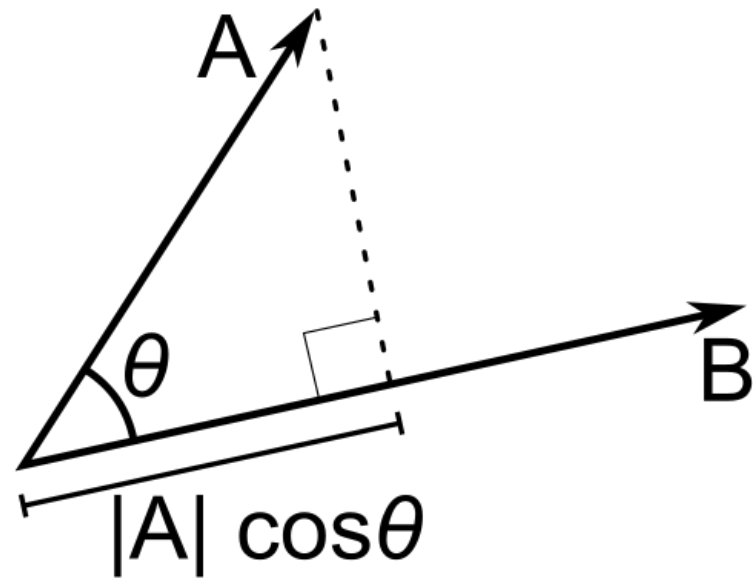
From notes by Andrew Ng

Reminder: Vector Projections

- Basic definitions:

- $A \cdot B = |A| |B| \cos \theta$

- $\cos \theta = |\text{adj}| / |\text{hyp}|$



- Assume $|B|=1$ (unit vector)

- $A \cdot B = |A| \cos \theta$

- So, dot product is length of projection!!!

Maximize variance of projection

Let $x^{(i)}$ be the i^{th} data point minus the mean.

Choose unit-length u to maximize:

$$\begin{aligned}\frac{1}{m} \sum_{i=1}^m (x^{(i)T} u)^2 &= \frac{1}{m} \sum_{i=1}^m u^T x^{(i)} x^{(i)T} u \\ &= u^T \left(\frac{1}{m} \sum_{i=1}^m x^{(i)} x^{(i)T} \right) u.\end{aligned}$$

Let $\|u\|=1$ and maximize. Using the method of Lagrange multipliers, can show that the solution is given by the principal eigenvector of the covariance matrix! (**shown on board**)

Basic PCA algorithm

- Start from m by n data matrix \mathbf{X}
- **Recenter:** subtract mean from each row of \mathbf{X}
 - $\mathbf{X}_c \leftarrow \mathbf{X} - \bar{\mathbf{X}}$
- **Compute covariance** matrix:
 - $\Sigma \leftarrow 1/m \mathbf{X}_c^T \mathbf{X}_c$
- Find **eigen vectors and values** of Σ
- **Principal components:** k eigen vectors with highest eigen values