

# Learning theory

## Lecture 8

David Sontag  
New York University

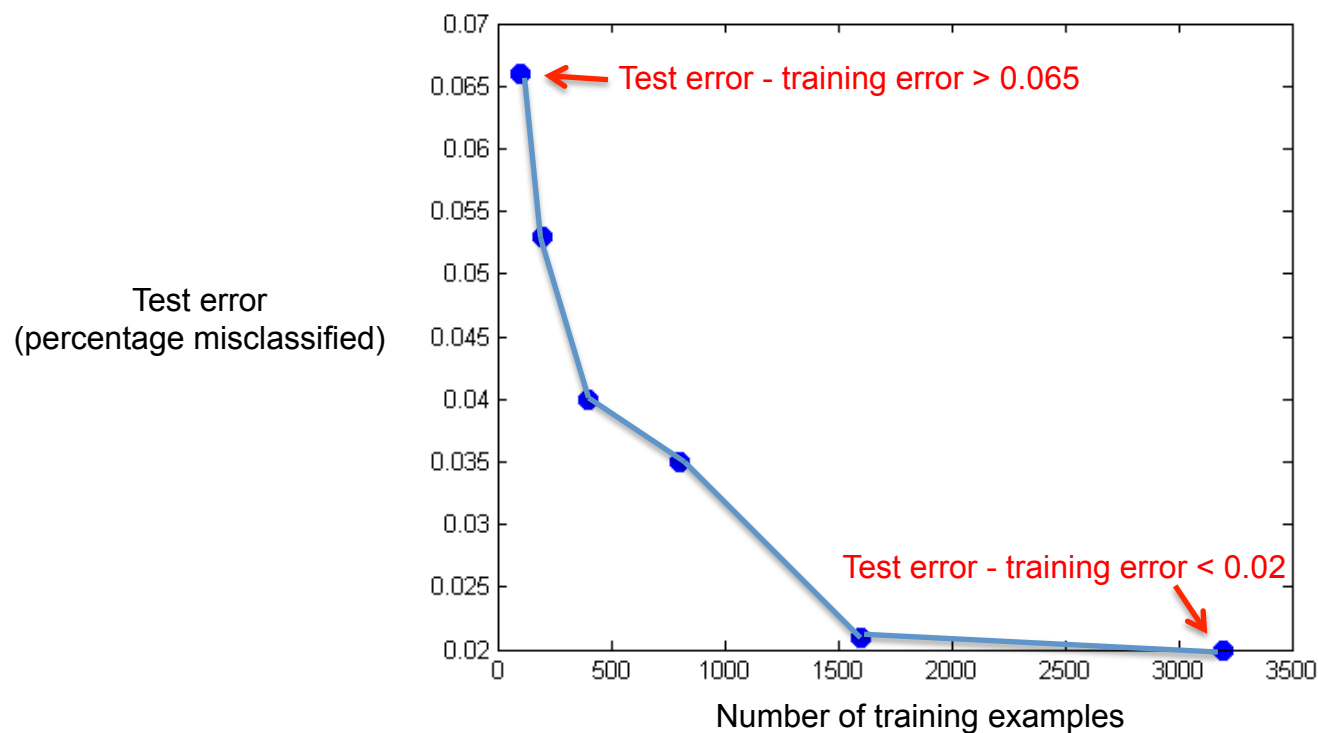
Slides adapted from Carlos Guestrin & Luke Zettlemoyer

## What's next...

- We gave several machine learning algorithms:
  - Perceptron
  - Linear support vector machine (SVM)
  - SVM with kernels, e.g. polynomial or Gaussian
- How do we guarantee that the learned classifier will perform well on test data?
- How much training data do we need?

## Example: Perceptron applied to spam classification

- In your homework 1, you trained a spam classifier using perceptron
  - The training error was always zero
  - With few data points, there was a big gap between training error and test error!



## How much training data do you need?

- Depends on what *hypothesis class* the learning algorithm considers
- For example, consider a memorization-based learning algorithm
  - Input: training data  $S = \{ (\mathbf{x}_i, y_i) \}$
  - Output: function  $f(\mathbf{x})$  which, if there exists  $(\mathbf{x}_i, y_i)$  in  $S$  such that  $\mathbf{x}=\mathbf{x}_i$ , predicts  $y_i$ , and otherwise predicts the majority label
  - This learning algorithm will always obtain zero training error
  - But, it will take a **huge** amount of training data to obtain small test error (i.e., its generalization performance is horrible)
- Linear classifiers are powerful precisely because of their simplicity
  - Generalization is easy to guarantee

# Roadmap of next two lectures

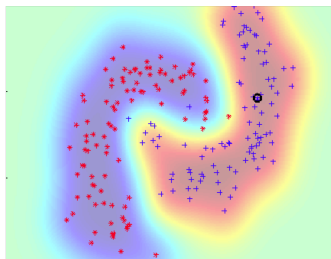
## 1. Generalization of finite hypothesis spaces

## 2. VC-dimension

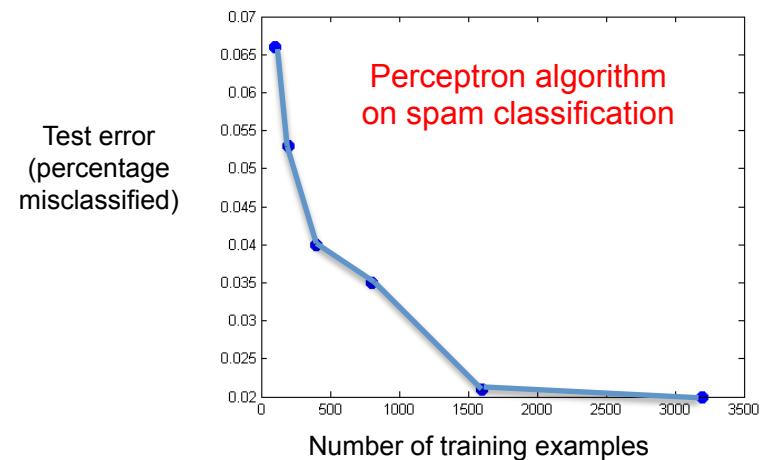
- Will show that linear classifiers need to see approximately  $d$  training points, where  $d$  is the dimension of the feature vectors
- Explains the good performance we obtained using perceptron!!!! (we had a few thousand features)

## 3. Margin based generalization

- Applies to **infinite** dimensional feature vectors (e.g., Gaussian kernel)



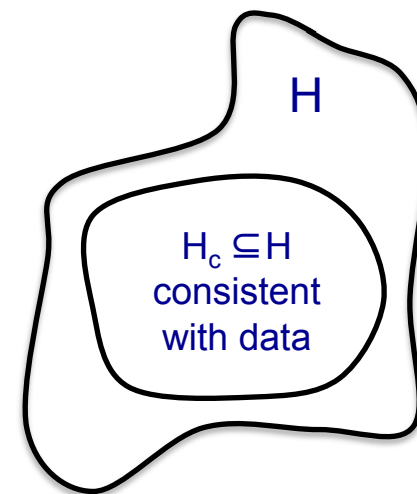
[Figure from Cynthia Rudin]



## How big should your validation set be?

- In PS1, you tried many configurations of your algorithms (avg vs. regular perceptron, max # of iterations) and chose the one that had smallest validation error
- Suppose in total you tested  $|H|=40$  different classifiers on the validation set of  $m$  held-out e-mails
- The best classifier obtains 98% accuracy on these  $m$  e-mails!!!
- But, what is the true classification accuracy?
- How large does  $m$  need to be so that we can guarantee that the best configuration (measured on validate) is truly good?

## A simple setting...






- **Classification**
  - m data points
  - **Finite** number of possible hypothesis (e.g., 40 spam classifiers)
- A learner finds a hypothesis  $h$  that is **consistent** with training data
  - Gets zero error in training:  $error_{train}(h) = 0$
  - I.e., assume for now that one of the classifiers gets 100% accuracy on the  $m$  e-mails (we'll handle the 98% case afterward)
- What is the probability that  $h$  has more than  $\epsilon$  **true** error?
  - $error_{true}(h) \geq \epsilon$

# Introduction to probability: outcomes

- An **outcome space** specifies the possible outcomes that we would like to reason about, e.g.

$$\Omega = \{ \text{ , \text{ } \quad \text{Coin toss}$$

$$\Omega = \{ \text{ , \text{ , \text{ , \text{ , \text{ , \text{ } \quad \text{Die toss}$$

- We specify a **probability**  $p(x)$  for each outcome  $x$  such that

$$p(x) \geq 0, \quad \sum_{x \in \Omega} p(x) = 1$$

E.g.,  $p(\text{}) = .6$

$p(\text{}) = .4$



# Introduction to probability: events

- An **event** is a subset of the outcome space, e.g.

$$E = \{ \text{die with 2, 4, 6} , \text{die with 1, 3, 5} , \text{die with 2, 4, 6} \} \quad \text{Even die tosses}$$

$$O = \{ \text{die with 1, 3, 5} , \text{die with 2, 4, 6} , \text{die with 1, 3, 5} \} \quad \text{Odd die tosses}$$

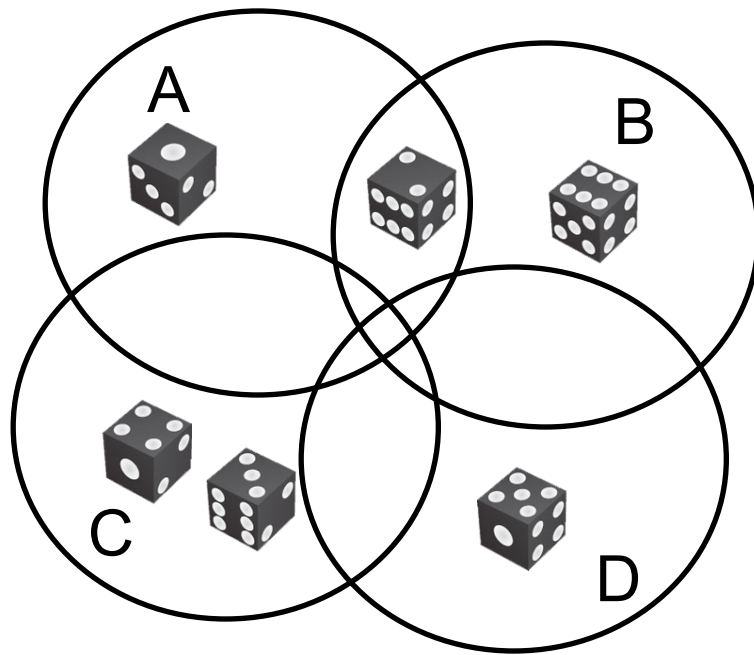
- The **probability** of an event is given by the sum of the probabilities of the outcomes it contains,

$$p(E) = \sum_{x \in E} p(x) \quad \text{E.g., } p(E) = p(\text{die with 2, 4, 6}) + p(\text{die with 1, 3, 5}) + p(\text{die with 2, 4, 6})$$

= 1/2, if fair die

# Introduction to probability: union bound

- $P(A \text{ or } B \text{ or } C \text{ or } D \text{ or } \dots)$   
 $\leq P(A) + P(B) + P(C) + P(D) + \dots$



$$p(A \cup B) = p(A) + p(B) - p(A \cap B)$$
$$\leq p(A) + p(B)$$

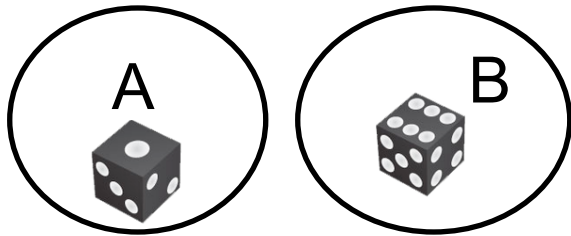
**Q: When is this a tight bound?**

**A: For disjoint events**  
(i.e., non-overlapping circles)

# Introduction to probability: independence

- Two events A and B are **independent** if

$$p(A \cap B) = p(A)p(B)$$



Are these events independent?

**No!**  $p(A \cap B) = 0$

$$p(A)p(B) = \left(\frac{1}{6}\right)^2$$

# Introduction to probability: independence

- Two events A and B are **independent** if

$$p(A \cap B) = p(A)p(B)$$

- Suppose our outcome space had two different die:

$$\Omega = \{ \text{die1, die2}, \text{die1, die2}, \text{die1, die2}, \dots, \text{die1, die2} \} \quad \text{2 die tosses}$$

$6^2 = 36$  outcomes

and the probability of each outcome is defined as

$$p(\text{die1, die2}) = a_1 b_1 \quad p(\text{die1, die2}) = a_1 b_2 \quad \dots$$

$a_1$	$a_2$	$a_3$	$a_4$	$a_5$	$a_6$
.1	.12	.18	.2	.1	.3

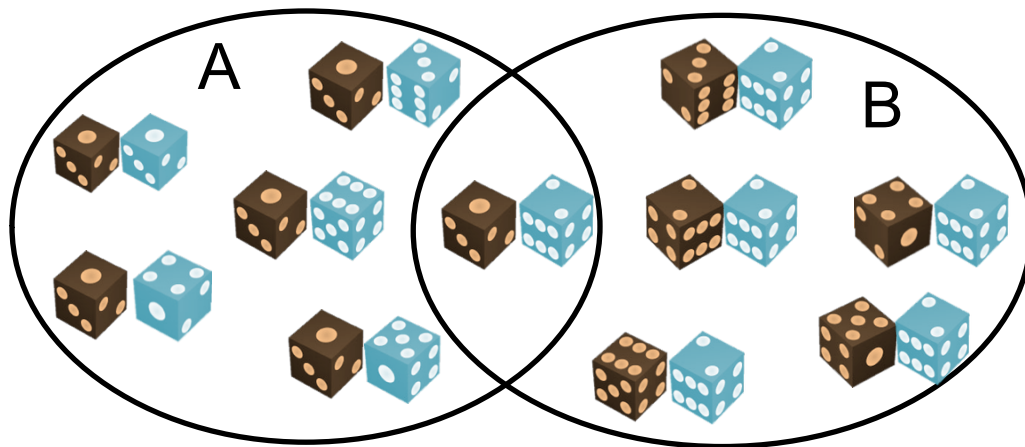
$b_1$	$b_2$	$b_3$	$b_4$	$b_5$	$b_6$
.19	.11	.1	.22	.18	.2

$$\sum_{i=1}^6 a_i = 1$$

$$\sum_{j=1}^6 b_j = 1$$

# Introduction to probability: independence

- Two events A and B are **independent** if
$$p(A \cap B) = p(A)p(B)$$
- Are these events independent?



$$p(A) = p(\text{brown die})$$

$$p(B) = p(\text{blue die}) = b_2$$

$$= \sum_{j=1}^6 a_1 b_j = a_1 \sum_{j=1}^6 b_j = a_1$$

**Yes!**  $p(A \cap B) = p(\text{brown die and blue die})$

$$p(A)p(B) = p(\text{brown die}) p(\text{blue die})$$