

Machine Learning and Computational Statistics, Fall 2014

Problem Set 2: Support vector machines

Due: Friday, February 14, 2014 at 5pm (as a PDF document – scanning hand written solutions is acceptable – sent to akshaykumar@nyu.edu)

Important: See problem set policy on the course web site.

1. (5 points) Consider a (hard margin) support vector machine and the following training data from two classes:

$$\begin{array}{ll} +1 : & (2, 2) \quad (4, 4) \quad (4, 0) \\ -1 : & (0, 0) \quad (2, 0) \quad (0, 2) \end{array}$$

- (a) Plot these six training points, and construct by inspection the weight vector for the optimal hyperplane. In your solution, specify the hyperplane in terms of $\vec{w}$ and b such that $w_1x_1 + w_2x_2 + b = 0$. Calculate what the margin is (i.e., 2γ , where γ is the distance from the hyperplane to its closest data point), showing all of your work.
- (b) What are the support vectors? Explain why.
2. (5 points) Show that, irrespective of the dimensionality of the data space, a data set consisting of just two data points (call them $\vec{x}_1$ and $\vec{x}_2$), one from each class, is sufficient to determine the maximum-margin hyperplane. Fully explain your answer, including *giving an explicit formula* for the solution to the hard margin SVM (i.e., $\vec{w}$) as a function of $\vec{x}_1$ and $\vec{x}_2$.
3. (5 points) The primal SVM always has a unique solution because of the strict convexity of the optimization objective. By contrast, the dual SVM solution may not be unique. This question will explore the dual hard-margin SVM optimization problem to explain the non-uniqueness of the solution.

The setting we consider is the following. There are three data points in the training data: $\{(x_1, +1), (x_2, -1), (x_2 - 1)\}$, i.e. one data point of class +1, and two *identical* data points of class -1. We assume that $x_1 \neq x_2$. For this question you should use the Gaussian kernel, $K(\mathbf{x}_i, \mathbf{x}_j) = e^{\frac{-\|\mathbf{x}_i - \mathbf{x}_j\|^2}{2\sigma^2}}$. This will simplify the dual objective, although any other valid kernel would also show the non-uniqueness of the dual solution.

- (a) Write down the dual optimization problem for the setting considered. It will have three dual variables $\alpha_1, \alpha_2, \alpha_3$ for each of the three data points. Do not forget the constraints!
- (b) Simplify the dual objective so that it is a function of only one of the three dual variables. Solve the (now 1-dimensional) optimization problem, and then find the optimal $\alpha_1^*, \alpha_2^*, \alpha_3^*$ associated with the three data points. Use this to explain why the dual solution is non-unique.
- (c) Recall that the optimal primal solution can be obtained from the optimal dual solution using $w^* = \sum_j \alpha_j^* y_j x_j$. Using this, show that the non-unique dual solution still describes a unique weight vector (primal solution).

4. (10 points) Kernels

- (a) For any two documents x and z , define $k(x, z)$ to equal the number of unique words that occur in both x and z (i.e., the size of the intersection of the sets of words in the two documents). Is this function a kernel? Justify your answer. (Hint: $k(x, z)$ is a kernel if there exists $\phi(x)$ such that $k(x, z) = \phi(x)^T \phi(z)$).
- (b) Assuming that $\vec{x} = [x_1, x_2]$, $\vec{z} = [z_1, z_2]$ (i.e., both vectors are two-dimensional) and $\beta > 0$, show that the following is a kernel:

$$k_\beta(\vec{x}, \vec{z}) = (1 + \beta \vec{x} \cdot \vec{z})^2 - 1$$

Do so by demonstrating a feature mapping $\Phi(\vec{x})$ such that $k_\beta(\vec{x}, \vec{z}) = \Phi(\vec{x}) \cdot \Phi(\vec{z})$.

- (c) One way to construct kernels is to build them from simpler ones. Assuming $k_1(x, z)$ and $k_2(x, z)$ are kernels, then one can show that so are these:
- (scaling) $f(x)f(z)k_1(x, z)$ for any function $f(x) \in \mathcal{R}$,
 - (sum) $k(x, z) = k_1(x, z) + k_2(x, z)$,
 - (product) $k(x, z) = k_1(x, z)k_2(x, z)$.

Using the above rules and the fact that $k(x, z) = x^T z$ is a kernel, show that the following is also a kernel:

$$\left(1 + \left(\frac{x}{\|x\|_2} \right)^T \left(\frac{z}{\|z\|_2} \right) \right)^3.$$

5. (5 points) The multi-class SVM generalizes the binary SVM to multi-class classification. This involves introducing a weight vector $\vec{w}^{(k)}$ and $b^{(k)}$ for each class $k = 1, \dots, K$ (where K is the number of classes). Learning solves the following optimization problem, where there is still only one slack variable ξ_j for each data point, but now there are $K - 1$ constraints per data point:

$$\min_{\{\vec{w}^{(k)}, b^{(k)}\}} \sum_{k=1}^K \|\vec{w}^{(k)}\|_2^2 + C \sum_j \xi_j$$

subject to

$$\begin{aligned} \vec{w}^{(y_j)} \cdot \vec{x}_j + b^{(y_j)} &\geq \vec{w}^{(k)} \cdot \vec{x}_j + b^{(k)} + 1 - \xi_j & \forall j \text{ and } k \neq y_j \\ \xi_j &\geq 0 & \forall j. \end{aligned}$$

Prediction for a new data point $\vec{x}$ is performed using the rule

$$\hat{y} \leftarrow \arg \max_k \vec{w}^{(k)} \cdot \vec{x} + b^{(k)}.$$

This problem compares the binary prediction rule $\text{sign}(\vec{w} \cdot \vec{x} + b)$ to the multi-class prediction rule in the case that $K = 2$, and shows how to reduce between the two of them.

- (a) Demonstrate $\vec{w}$ and b as a function of $\vec{w}^{(1)}$, $b^{(1)}$, $\vec{w}^{(2)}$ and $b^{(2)}$ such that the predictions made for all data points $\vec{x}$ using the new binary prediction rule are the same as what would have been made using the multi-class prediction rule with $\vec{w}^{(1)}$, $b^{(1)}$, $\vec{w}^{(2)}$.
- (b) Next you should show the converse. Given $\vec{w}$ and b , demonstrate $\vec{w}^{(1)}$, $b^{(1)}$, $\vec{w}^{(2)}$ and $b^{(2)}$ (as a function of $\vec{w}$ and b) such that the predictions made for all data points $\vec{x}$ using the multi-class prediction rule are the same as what would have been made using the binary prediction rule with $\vec{w}$ and b .

As always, you must show all of your work to obtain full credit.