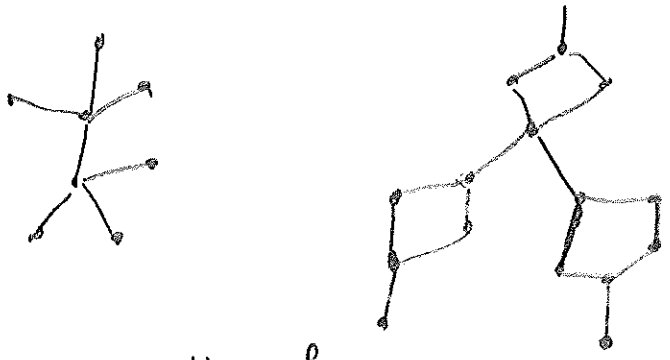


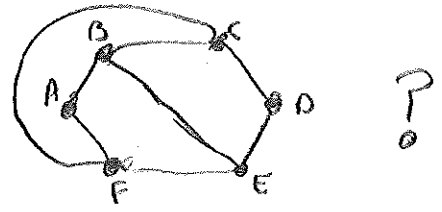
Recalls, width of induced graph is # nodes in largest clique - 1

Treewidth, or "minimal induced width," of graph  $G$  is  $\min_{\lambda} w_{G, \lambda}$ , where  $w_{G, \lambda}$  is width of graph induced by applying elimination ordering  $\lambda$  to  $G$ .

What is the treewidth of  $K_{1,4}$ ?



(Affects running time of elimination alg - exponential in treewidth)



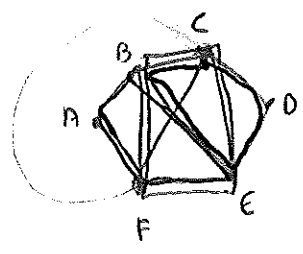
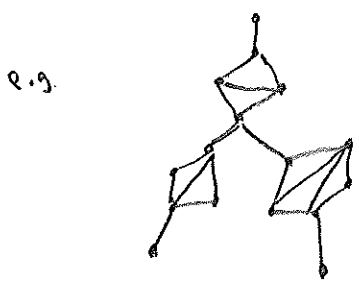
(Eliminate A + D, gives clique on B, C, E, F. Any other ordering clearly worse.)

Graph is chordal, or triangulated, if every cycle of length  $\geq 3$  has a shortcut (called a "chord")

Thm: Every induced graph is chordal

Thm: Every chordal graph has an elimination ordering which does not introduce any fill edges

→ found by Max Cardinality algorithm, (see book), Sec. 9.4



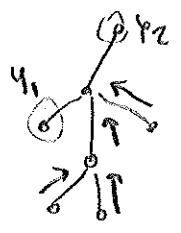
conclusion  
Finding a good elim. ordering is equivalent to making graph chordal with minimal width.

Ordering is unique...

What if you want to compute marginals for many variables?

i.e.  $pr(y_i | \bar{x}) \quad \forall i \in Y$ ?

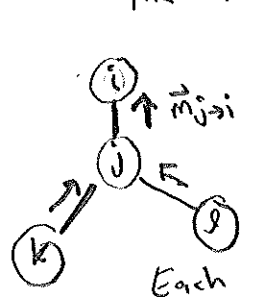
Can re-run variable elimination, once for each  $i \in Y$ , but this duplicates much of the effort, e.g.  $pr(x_1, \dots, x_n) \propto \prod_{i \in Y} \phi_i \prod_{j \in E} \phi_{ij}$



Consider the case of trees. The sum-product belief propagation algorithm computes all marginals with just double the computation and using linear space.

Based on message-passing of "messages" (tables of partial summations) between neighboring vertices of the graph.

The message sent from variable  $j$  to  $i \in N(j)$  is:

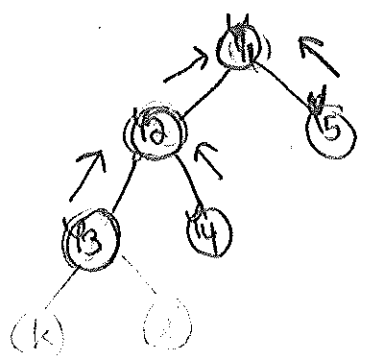


$$m_{j \rightarrow i}(x_i) = \sum_{x_j} \left( \phi_j(x_j) \phi_{ij}(x_i, x_j) \prod_{k \in N(j) \setminus i} m_{k \rightarrow j}(x_j) \right)$$

Each message  $\vec{m}_{j \rightarrow i}$  is a vector with one value for each state of  $x_i$ .

→ In order to compute  $\vec{m}_{j \rightarrow i}$ , must already have  $\vec{m}_{k \rightarrow j}$  for  $k \in N(j) \setminus i$ . Thus, there must be a specific ordering to the messages.

Suppose we want to compute  $pr(y_1)$ . Root tree at  $y_1$  and send messages from leaves to root.



Root =  $y_1$

$$m_{5 \rightarrow 1}(y_1) = \sum_{y_5} \phi_5(y_5) \phi_{15}(y_1, y_5)$$

$$m'_{3 \rightarrow 2}(y_2) = \sum_{y_3} \phi_3(y_3) \phi_{23}(y_2, y_3)$$

$$m_{4 \rightarrow 2}(y_2) = \sum_{y_4} \phi_4(y_4) \phi_{24}(y_2, y_4)$$

$$m'_{2 \rightarrow 1}(y_1) = C_3 \sum_{y_2} \phi_2(y_2) \phi_{12}(y_1, y_2) m_{3 \rightarrow 2}(y_2) m_{4 \rightarrow 2}(y_2) \quad 3,$$

Finally,  $p(y_1) \propto C_3 \phi_1(y_1) m_{2 \rightarrow 1}(y_1) m_{5 \rightarrow 1}(y_1)$ .

Elimination algorithm on trees is equivalent to message passing!

What about computing  $pr(Y_5)$ ? Could re-run algorithm, rooted at  $Y_5$ . Or...

### Belief Propagation (BP)

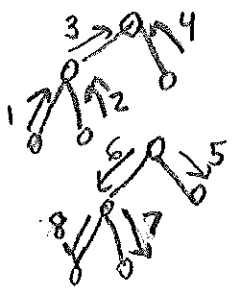
Input: Tree  $T$  with potentials  $\phi_i(x_i)$ ,  $\phi_{ij}(x_i, x_j) \forall i, j \in T$ .

Choose root  $r$ . (arbitrary)

Pass messages from leaves to  $r$ . (\*)

Pass messages from  $r$  to leaves.

Compute  $p(y_i) \propto \phi_i(y_i) \prod_{j \in N(i)} m_{j \rightarrow i}(y_i) \quad \forall i$



Running time =  $2 \times$  cost of one var. elimination =  $\Theta(nk^2)$ ,  
 where  $n = \#$  nodes and  $k = \#$  states per node.

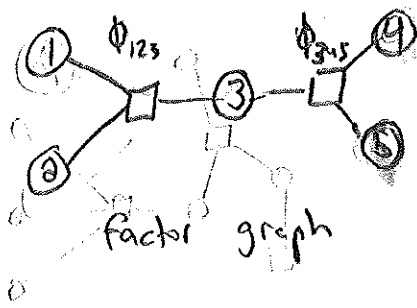
Possible numerical difficulties if multiplying many small factors.

Notice that constants passed on from message to messages then canceled during normalization.

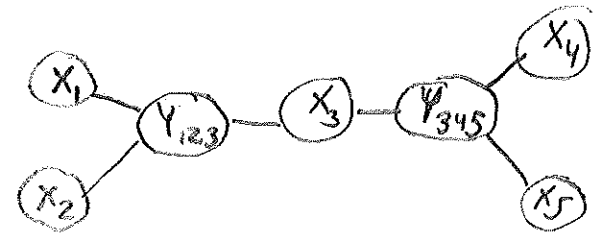
Alternative update:

$$m_{j \rightarrow i}^{\text{new}}(x_i) = \frac{m_{j \rightarrow i}^{\text{orig}}(x_i)}{\sum_{x_i} m_{j \rightarrow i}^{\text{orig}}(x_i)} \quad \left. \vphantom{\sum_{x_i}} \right\} \text{constant.}$$

This applies to any tree-structured pairwise MRF. What about a tree-structured factor graph?



Use transfr. from homework



pairwise MRF

$\phi_{123}(y_{123}), \phi_{345}(y_{345})$  single node potentials  
 $\phi(x_i, y_{123}) = 0$  if  $x_i$  inconsistent w/  $y_{123}$  pairwise node potentials

Messages can be computed slightly more efficiently:

$$m_{f \rightarrow i}(y_f) = \sum_{x_i} \phi_i(x_i) \phi_{i,f}(x_i, y_f) \prod_{f' \in N(i)} m_{f' \rightarrow i}(x_i)$$

$$= \phi_i(x_i(y_f)) \prod_{f' \in N(i) \setminus f} m_{f' \rightarrow i}(x_i(y_f))$$

one value for each  $x_i$ . Just store  $m_{i \rightarrow f}(x_i) \forall x_i$ .

$$m_{f \rightarrow i}(x_i) = \sum_{y_f} \phi_f(y_f) \phi_{i,f}(x_i, y_f) \prod_{j \in N(f) \setminus i} m_{j \rightarrow f}(y_f)$$

$$= \sum_{y_f} \phi_f(y_f) \prod_{j \in N(f) \setminus i} m_{j \rightarrow f}(y_f)$$

$$x_i = x_i(y_f)$$

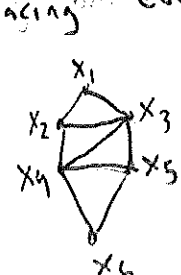
$$= \sum_{\vec{x}_{f \setminus i}} \phi_f(x_i, \vec{x}_{f \setminus i}) \prod_{j \in f \setminus i} m_{j \rightarrow f}(x_j)$$

What about graphs that aren't trees? e.g.,

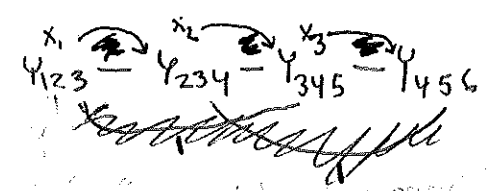


Junction tree algorithm (also called "clique trees")

Turn graph into tree by triangulating (making chordal) and replacing every maximal clique with a variable



elim. ordering  $x_1, x_2, x_3$



Elim. ordering found by max-cardinality search algorithm.  $\rightarrow$  increasing variables.

Again, messages can be computed slightly more efficiently using the structure.