# Plane Embeddings of Planar Graph Metrics 

MohammadHossein Bateni<br>Sharif University of Technology<br>bateni@gmail.com

Erik D. Demaine<br>MIT CSAIL<br>edemaine@mit.edu

MohammadTaghi Hajiaghayi ${ }^{*}$<br>MIT CSAIL and CMU<br>hajiagha@mit.edu

Mohammad Moharrami<br>Sharif University of Technology<br>mmoharrami@gmail.com


#### Abstract

Embedding metrics into constant-dimensional geometric spaces, such as the Euclidean plane, is relatively poorly understood. Motivated by applications in visualization, ad-hoc networks, and molecular reconstruction, we consider the natural problem of embedding shortest-path metrics of unweighted planar graphs (planar graph metrics) into the Euclidean plane. It is known that, in the special case of shortest-path metrics of trees, embedding into the plane requires $\Theta(\sqrt{n})$ distortion in the worst case [19 1], and surprisingly, this worst-case upper bound provides the best known approximation algorithm for minimizing distortion. We answer an open question posed in this work and highlighted by Matoušek [21] by proving that some planar graph metrics require $\Omega\left(n^{2 / 3}\right)$ distortion in any embedding into the plane, proving the first separation between these two types of graph metrics. We also prove that some planar graph metrics require $\Omega(n)$ distortion in any crossingfree straight-line embedding into the plane, suggesting a separation between low-distortion plane embedding and the well-studied notion of crossing-free straight-line planar drawings. Finally, on the upper-bound side, we prove that all outerplanar graph metrics can be embedded into the plane with $O(\sqrt{n})$ distortion, generalizing the previous results on trees (both the worst-case bound and the approximation algorithm) and building techniques for handling cycles in plane embeddings of graph metrics.


## Categories and Subject Descriptors

F.2.2 [Nonnumerical Algorithms and Problems]: Geometrical problems and computations

## General Terms

Algorithms, Theory

[^0][^1]
## Keywords

Metric embedding, planar graphs, Euclidean plane

## 1. INTRODUCTION

Metric embedding is a mathematical study arising out of the classic field of multidimensional scaling, originally motivated by such applications as visualization, compression, clustering, and nearestneighbor searching [26, 27] 16, 17], and more recently finding applications in geometric reconstruction of ad-hoc wireless sensor networks [8, 25 23] and molecular structure of proteins [6, 9, 13]. Roughly speaking, the goal is to embed a given metric (matrix of pairwise distances among $n$ points) into a target space while minimizing the maximum additive or multiplicative error, called distortion, introduced in the distances ${ }^{11}$ Of particular interest in many of these applications is embedding into low-dimensional geometric spaces, typically Euclidean. For example, in visualization, the natural target spaces are 2D and 3D Euclidean space, for display on an LCD panel or a holographic display. Similarly, in ad-hoc wireless sensor networks and molecule structure of proteins, 2D and 3D Euclidean spaces are the natural spaces inhabited by these objects, so embedding into these spaces corresponds to reconstructing the original object.
Yet despite persistent efforts by many researchers leading to many recent results about embedding-see, e.g., [14| for a survey-we remain in the dark about most aspects of embedding into low-dimensional geometric spaces. Even when the target space is the one-dimensional line, little is known. For example, when the given metric is the shortest-path metric of an (unweighted) tree, the best known approximation factor for multiplicative distortion is $\tilde{O}\left(n^{1 / 3}\right)$ (improving on the $O\left(n^{1 / 2}\right)$-approximation for general graphs) [5], and it is unknown whether it is possible to achieve a factor of $n^{o(1)}$; see [3]. (On the other hand, additive distortion is less interesting in this context: there is an $O(1)$-approximation for embedding a general metric into the line [12].)
Even less is known about embedding into the two-dimensional plane. For additive distortion and the Euclidean plane, the only

[^2]$o(n)$-approximation algorithm runs in pseudo-quasipolynomial time [4]. For additive distortion and the $\ell_{1}$ plane, there is a polynomial-time $O(1)$-approximation [2]. But for the most natural case of multiplicative distortion, nothing beyond a trivial $O(n)$ approximation is known for embedding general metrics into any $\ell_{s}$ plane. Essentially the only result is by Babilon, Matoušek, Maxová, and Valtr [1]: an $O(\sqrt{n})$-approximation for embedding the shortest-path metric of an (unweighted) tree into the Euclidean plane. In fact, this approximation result comes trivially from a worst-case bound: all such metrics can be embedded into the Euclidean plane with multiplicative distortion $O(\sqrt{n})$ (improving on an earlier bound by Gupta [10]), and thus such an embedding is an $O(\sqrt{n})$-approximation on the optimal multiplicative distortion. This bound is tight in the worst case for trees (or even stars), but can we generalize beyond trees?

One of the major open questions about embedding into the Euclidean plane, posed in [21, 1] and addressed in this paper, is whether there is a worst-case bound on distortion better than $O(n)$ for shortest-path metrics of all (unweighted) planar graphs, in particular whether there is an $O(\sqrt{n})$ bound like trees. It has been known for over 15 years that the shortest-path metrics of some nonplanar graphs, such as $K_{5}$ with each edge subdivided $n / 10$ times, requires multiplicative distortion $\Omega(n)[19,14]$. But for shortestpath metrics of (unweighted) planar graphs, which we call planar graph metrics, no worst-case lower bound better than $\Omega(\sqrt{n})$ is known. One of the results of this paper is a stronger, more complicated lower bound of $\Omega\left(n^{2 / 3}\right)$ for the shortest-path metrics of a family of planar graphs called "globe graphs". Interestingly, this graph family has not been considered before (at least in the context of embedding) and the lower-bound argument uses topological graph theory, in contrast to the standard packing arguments in most embedding lower bounds.

Planar graph metrics are a natural family of metrics to embed: many structures of interest, such as communication networks and traffic networks, are planar (or nearly planar) graphs, and lowdistortion embedding of such structures is important, e.g., for visualization. There is also a wealth of knowledge about crossing-free straight-line drawings of planar graphs into the plane, originating with Tutte's embedding theorem [29] and studied more recently in the context of graph drawing (see, e.g., [28]). It is natural to consider to what extent such embeddings can preserve approximate distances as well. Another result of this paper is that, in fact, $\Omega(n)$ distortion can be required if we restrict attention to crossing-free straight-line embeddings of planar graph metrics, even when the graph has bounded treewidth.

One intriguing aspect of the problem of embedding planar graph metrics into the plane is that, in the context of embeddings, planar graphs usually behave the same as graphs excluding any fixed minor. For example, the same upper bound of $O(\sqrt{\log n})$ distortion is known for embedding into Euclidean space [24 [20], the same upper bound of $O(1)$ distortion is known for embedding into $\ell_{\infty}$ space [15], and the same upper bound of $O(1)$ distortion is conjectured for embedding into $\ell_{1}$ space [11]. (All of these bounds require a superconstant number of dimensions.) While we prove in this paper an $\Omega\left(n^{2 / 3}\right)$ lower bound on the distortion required to embed a planar graph metric into a plane, a sublinear upper bound is still quite possible. In contrast, the subdivided $K_{5}$ graph mentioned above excludes a fixed minor (e.g., $K_{3,3}$ ), yet its shortest-path metric requires $\Omega(n)$ distortion when embedded into the plane. Therefore, any sublinear upper bound on distortion for planar graph metrics will need substantially different techniques compared to previous approaches, which seem to apply equally well to planar graphs and graphs excluding a fixed minor.

Toward this goal, we develop new techniques for embedding
into the plane with sublinear distortion. Specifically, we prove an $O(\sqrt{n})$ upper bound on distortion for the shortest-path metrics of (unweighted) outerplanar graphs, i.e., graphs that can be drawn in the plane without crossings and with all vertices on the outer face. Interestingly, this result does not take the obvious approach of embedding the dual tree of an outerplanar graph; rather, it uses a breadth-first-search tree. The main challenge is in handling the cycles in the graph.

Our results. In more detail, the main results of this paper are as follows.

On the lower-bound side, we prove that some planar graph metrics require $\Omega\left(n^{2 / 3}\right)$ distortion in any embedding into the plane, and prove that some planar graph metrics require $\Omega(n)$ distortion in any crossing-free straight-line embedding into the plane. These results imply that embedding planar graph metrics into the plane with sublinear distortion is different from planar drawings of planar graphs, suggesting that we cannot apply the well-studied tools from that domain. In fact, our $\Omega\left(n^{2 / 3}\right)$ lower bound builds on the $\Omega(n)$ crossing-free lower bound, extending the structure of the underlying planar graph substantially to force a "planar-like" drawing. We use topological graph theory to reason about which vertices must be embedded "interior" to cycles in the graph, even though these cycles may embed as curves with many self-crossings and crossings of each other. To help cope with this difficulty, we use a combinatorial approach to eliminate some of the crossings.

On the upper-bound side, we prove that every outerplanar graph metric can be embedded into the plane with $O(\sqrt{n})$ distortion. In particular, this result improves the best approximation factor for minimum-distortion embedding of outerplanar graph metrics from $O(n)$ to $O(\sqrt{n})$, which is the only nontrivial such result for multiplicative distortion into the Euclidean plane other than trees. The result uses the following ideas. First, we decompose the graph into a "tree of cycles", cutting apart faces so that they do not share edges. We cannot use the dual tree itself: the main challenge is to correctly handle the cycles in the graph. Second, we perform a breadth-first search in this graph, partitioning the graph into a BFS tree and several nontree edges. Third, we use a modification of the $O(\sqrt{n})$-distortion embedding for trees so as to embed the BFS tree without stretching the nontree edges too much. We modify the input to the algorithm, augmenting the BFS tree with extra paths in key locations to force desired gaps in the output, and we modify the output of the algorithm, shifting vertices to close unwanted gaps in the output.

## 2. LOWER BOUND FOR PLANAR GRAPH EMBEDDING

In this section we prove a separation between embedding trees and embedding planar graphs into the plane. Namely, we prove that embedding some planar graphs with $n$ vertices into the plane requires distortion $\Omega\left(n^{2 / 3}\right)$, whereas trees can be embedded into the plane with distortion $O\left(n^{1 / 2}\right)$. Along the way, we prove that every crossing-free straight-line embedding of some planar graphs with $n$ vertices into the plane has distortion $\Omega(n)$.
Throughout this section, we use the odd-even notion of "inside" and "outside" of self-crossing polygons. Namely, for a point $v$ not on the boundary of a (potentially self-crossing) polygon $P$, we count the number of times that an arbitrary half-infinite ray emanating from $v$ properly crosses the polygon $P$; we do not count when the ray "grazes" the polygon (with the polygon locally on one side of the ray). If this count is odd, the point $v$ is inside the polygon $P$; otherwise, $v$ is outside $P$. Also, let $|P|$ denote the number of vertices of polygon $P$.


Figure 1. The subtended angles of an edge at a point.

LEMMA 1. For any point $v$ inside a (potentially self-crossing) polygon $P$ in the plane, if the distance from $v$ to every vertex of $P$ is at least $r$, then there is an edge of $P$ of length $\Omega(r /|P|)$.

Proof: Let $u_{1}, u_{2}, \ldots, u_{|P|}$ be the vertices of $P$ in counterclockwise order. For each edge of $P$, we consider the absolute $s u b$ tended angle of this edge at $v$, as shown in Figure 1 In any polygon, these subtended angles sum to at least $360^{\circ}$ (larger because of taking absolute values, and if the winding number of $P$ is larger than 1). Thus, at least one edge $\left(u_{i}, u_{i+1}\right)$ has subtended angle at least $360^{\circ} /|P|$ (and at most $180^{\circ}$ by definition). Considering the triangle $v, u_{i}, u_{i+1}$, because $\left\|u_{i}-v\right\|$ and $\left\|u_{i+1}-v\right\|$ are both at least $r,\left\|u_{i}-u_{i+1}\right\|$ is $\Omega(r /|P|)$.

Our result about crossing-free straight-line planar embeddings is based on graphs that inspire our main result later on.

THEOREM 2. There are planar graphs where every crossingfree straight-line embedding into the plane has distortion $\Omega(n)$.

Proof: Consider the graph $G$ obtained by starting with $K_{4}$ and attaching a path of length $n$ to each vertex of $K_{4}$. Any crossingfree straight-line embedding of $G$ in particular embeds $K_{4}$ without crossings, which implies that one vertex $v$ of $K_{4}$ is inside the cycle $C$ connecting the other three vertices of $K_{4}$. (This fact follows because all outerplanar graphs exclude $K_{4}$ as a minor.) Any crossing-free straight-line embedding of $G$ must therefore place the path attached to $v$ completely inside $C$. Let $u$ denote the endpoint of this path (other than $v$ ). The graph distance from $u$ to every vertex of $C$ is at least $n$, so in any expansive embedding of $G$, the Euclidean distance between $u$ and every vertex of $C$ is at least $n$. By Lemma 1 with $P=C$, an edge of $C$ (which is an edge of $K_{4}$ ) has length $\Omega(n /|C|)=\Omega(n)$. Therefore, the distortion of any crossing-free straight-line embedding of $G$ is $\Omega(n)$.

Our main result is based on the globe graph, defined as follows; see Figure 2 On a sphere (the globe), draw $n^{1 / 3}$ longitude and $n^{1 / 3}$ latitude lines. These lines define a preliminary graph, whose vertices are the intersections of the lines (including the two poles) and whose edges are portions of the lines. We subdivide each of these edges into a path of $n^{1 / 3}$ edges. We attach a path of length $n$ to each of the two poles $v_{N}$ and $v_{S}$, and to each of two antipodal points $v_{W}$ and $v_{E}$ on the equator. The resulting globe graph $G_{n}$ is planar and has $\Theta(n)$ vertices.

In the spherical embedding of the globe graph shown in Figure 2 , each face is called a country ${ }^{2}$ Thus each country is a cycle of length $\Theta\left(n^{1 / 3}\right)$.

The four vertices $v_{N}, v_{S}, v_{W}$, and $v_{E}$, together with the three longitudes at $0^{\circ}$ and $\pm 90^{\circ}$ and the rear half of the equator, define a subdivided $K_{4}$ as a subgraph of $G_{n}$. This subgraph is shown in

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Figure 2. The globe graph $G_{n}$.

Figure 2 with heavy edges. The distance between any two vertices in the subdivided $K_{4}$ is within a constant factor of the distance between those vertices in the globe graph $G_{n}$.

LEMMA 3. If two graph edges cross in a straight-line embedding of a graph into the plane, and the graph distance between each endpoint of the first edge and each endpoint of the second edge (four pairs) is at least $s$, then the distortion of the embedding is $\Omega(s)$.

Proof: Consider the quadrilateral formed by the endpoints of the two edges. In any expansive embedding of the graph into the plane, the Euclidean length of each side of the quadrilateral is at least $s$ (the graph distance between the two edge endpoints). By the triangle inequality, at least one diagonal of the quadrilateral (i.e., one of the two edges) also has Euclidean length at least $s$. Therefore, the distortion of any such embedding is $\Omega(s)$.

LEMMA 4. Any o( $\left.n^{2 / 3}\right)$-distortion straight-line embedding of the subdivided $K_{4}$ into the plane puts one vertex of $K_{4}$ inside the cycle (polygon) connecting the other three vertices of $K_{4}$.

Proof: Call a vertex of $K_{4}$ good if it is inside the cycle connecting the other three vertices of $K_{4}$. If the straight-line embedding of the subdivided $K_{4}$ is crossing-free, then there must be a good vertex as in the proof of Theorem 2 2 Otherwise, we modify the embedding into an embedding of $K_{4}$, drawing each edge as a curve, in such a way that eliminates all crossings while preserving the parity of the number of good vertices of $K_{4}$. Thus, if there is an odd number of good vertices in the new embedding, then there was a good vertex in the original embedding too.

Throughout the modification of the embedding, we maintain a labeling of some portions of these curves. Namely, in the original embedding, we label every edge of the subdivided $K_{4}$ whose endpoints are within distance $\frac{1}{3} n^{2 / 3}$ of vertex $v_{d}, d \in\{N, S, E, W\}$, with label $d$. (Every point has at most one label.) As we modify the embedding of $K_{4}$, every point of a curve that remains in the embedding keeps the same label that we originally assigned it.

This labeling has several properties with respect to the original straight-line embedding, and as we shall see, with respect to the modified embeddings we create. First, for any point $x$ labeled $a$ along the curve representing an edge $\left\{v_{a}, v_{b}\right\}$ of $K_{4}$, the subcurve from $v_{a}$ to $x$ is entirely labeled $a$. Second, for any three distinct vertices $v_{a}, v_{b}, v_{c}$ of $K_{4}$, the edge $\left\{v_{a}, v_{b}\right\}$ embeds to a curve that does not cross any portion of a curve labeled $c$. Third, two nonincident edges of $K_{4}$ cannot cross. Fourth, two incident edges of
$K_{4}$ sharing an endpoint $v_{a}$ can intersect only along the portions labeled $a$. The last three properties use Lemma 3. which tells us that, in the original straight-line embedding of the subdivided $K_{4}$ with distortion $o\left(n^{2 / 3}\right)$, two endpoints of two crossing edges must have graph distance $o\left(n^{2 / 3}\right)$. Because we only remove portions of curves and/or change curves locally around removed crossings, we maintain all four of these properties as invariants of the modified embedding.

Whenever an edge of $K_{4}$, say $\left\{v_{N}, v_{S}\right\}$, is embedded as a selfcrossing curve, we remove a self-crossing as follows. Consider starting from one endpoint $v_{N}$ of the curve and following the curve until reaching a point $q$ that has already been visited. Thus $q$ decomposes the curve into three pieces: a curve from $v_{N}$ to $q$, a closed curve starting and ending at $q$, and a curve from $q$ to $v_{S}$. We remove the closed curve from the embedding of $K_{4}$. This removal affects only the embedding of the edge $\left\{v_{N}, v_{S}\right\}$ of $K_{4}$, which is not involved in the definition of whether $v_{N}$ or $v_{S}$ is good, so the goodness of $v_{N}$ and $v_{S}$ is preserved. On the other hand, the nonincident edge $\left\{v_{W}, v_{E}\right\}$ of $K_{4}$ cannot cross the edge $\left\{v_{N}, v_{S}\right\}$ (before or after the removal), so $v_{W}$ is inside the removed closed curve if and only if $v_{E}$ is inside the removed closed curve. Thus, the goodness of $v_{W}$ and $v_{E}$ either both remain the same or both change as a result of the removal. Hence, the removal preserves the parity of the number of good vertices of $K_{4}$.

Whenever the edges of $K_{4}$ do not have self-intersections (i.e., the previous modification has been applied fully), yet two (incident) edges, say $\left\{v_{N}, v_{S}\right\}$ and $\left\{v_{N}, v_{W}\right\}$, embed to curves that cross each other at a point $x$, then we remove the crossing as follows; see Figure 4 The point $x$ divides the edge $\left\{v_{N}, v_{S}\right\}$ into two curves, one of which connects $v_{N}$ to $x$. Similarly, the edge $\left\{v_{N}, v_{W}\right\}$ gives us a curve from $v_{N}$ to $x$. We swap these two curves from $v_{N}$ to $x$, switching the identity of to which edge each curve belongs. This change affects the embedding of only these two edges, which are not involved in the definition of whether $v_{N}$ is good, so the goodness of $v_{N}$ is preserved. Also, because we did not remove any portions of curves connecting $v_{N}, v_{S}$, and $v_{W}$ from the embedding-we only changed how they were connected-we preserve the number of crossings with a ray emanating from $v_{E}$, and thus we preserve its parity and whether $v_{E}$ is good. Finally, we claim that the goodness of $v_{S}$ and $v_{W}$ either both change or both stay the same. By our invariants, the point $x$ is labeled $N$ on both curves from $v_{N}$ to $x$, and therefore the entire curves from $v_{N}$ to $x$ are labeled $N$. Therefore, the edge $\left\{v_{S}, v_{W}\right\}$ must embed to a curve that does not cross either of these curves, so $v_{S}$ and $v_{W}$ must both be either inside or outside of the closed curve formed by the two curves from $v_{N}$ to $x$. In the former case, the goodness of $v_{S}$ and $v_{W}$ both change, and in the latter case, they both stay the same.

By repeatedly applying each of the two rules above for removing crossings, giving preference to the removal of self-crossings, we eventually remove all crossings in the embedding of $K_{4}$. Removing a crossing between two different edges of $K_{4}$ can introduce new self-crossings, but every operation decreases the total number of crossings, so the process terminates. As we have argued, the parity of the number of good vertices of $K_{4}$ has remained the same, any crossing-free straight-line embedding has a good vertex, and thus we obtain the desired good vertex in the original embedding.

By symmetry, assume that vertex $v_{N}$ is embedded inside the cycle (polygon) $C$ in the subdivided $K_{4}$ connecting $v_{S}, v_{W}, v_{E}$. Let $u$ denote the endpoint of the path attached to $v_{N}$ (other than $v_{N}$ itself). By Lemma $3 u$ must also be inside the cycle connecting $v_{S}, v_{W}, v_{E}$ in any $o\left(n^{2 / 3}\right)$-distortion embedding, because every edge of the chain attached to $v_{N}$ has distance $\Omega\left(n^{2 / 3}\right)$ to every edge of the cycle.

(a) Before

(b) After

Figure 3. Eliminating self-intersections. Bold lines indicate a hypothetical labeling of part of the curve.

(a) Before

(b) After

Figure 4. Eliminating edge intersections. Bold lines indicate portions of the curve labeled $v_{N}$.

LEMMA 5. In any o( $\left.n^{2 / 3}\right)$-distortion embedding of the globe graph, the endpoint $u$ is embedded inside a country of the globe graph.

Proof: If we draw the globe graph on a sphere as in Figure 2 then the cycle $C$ divides the sphere into two regions: inside and outside. We define the inside region to be the region containing $v_{N}$, which is roughly three quarters of the sphere; the outside region is the other region, the back lower quarter of the sphere. We define an inside country to be a country (face) of the globe graph that is within the inside region (viewed on the sphere). An edge of an inside country is boundary if it is an edge of the cycle $C$.
By the definition of $u$ being inside $C$, a half-infinite ray emanating from $u$ properly crosses $C$ an odd number of times. Let $S$ denote the sum, over all inside countries, of the number of times that the ray properly crosses that country in the embedding. This sum decomposes into two parts: the number of crossed boundary edges of inside countries and the number of crossed nonboundary edges of inside countries. Every crossed nonboundary edge is shared by exactly two inside countries and therefore is counted exactly twice in the sum $S$. Hence, the parity of $S$ is the same as the parity of the number of crossed nonboundary edges (i.e., crossed edges of $C$ ), which we know to be odd. Thus, at least one term in the sum $S$ is odd, i.e., at least one inside country is crossed an odd number of times by the ray. Therefore, $u$ is embedded inside this country.

ThEOREM 6. Every embedding of the globe graph into the plane has distortion $\Omega\left(n^{2 / 3}\right)$.

Proof: If there were an embedding with distortion $o\left(n^{2 / 3}\right)$, then by Lemma 5 the endpoint $u$ of one of the attached paths would be embedded inside a country of the globe graph. The distance of $u$ to the vertices of the country is at least $n$, while the country is a cycle of $\Theta\left(n^{1 / 3}\right)$ vertices. By Lemma 1 the distortion of the embedding must be $\Omega\left(n^{2 / 3}\right)$, a contradiction.

The same result as Theorem6 can be proved with a mathematically more natural graph instead of the cartographically natural globe graph. Namely, take a tetrahedron and repeatedly refine each triangle into four subtriangles until each edge of the tetrahedron is refined into $\Theta\left(n^{1 / 3}\right)$ edges. Then we refine each edge further into a path of $n^{1 / 3}$ edges, and attach a path of length $n$ to each corner of the tetrahedron.

## 3. OUTERPLANAR EMBEDDING

In this section, we give an algorithm for embedding outerplanar graph metrics into the plane with $O(\sqrt{n})$ distortion. Our algorithm consists of five main steps:

1. Modify the graph so that no two face $3^{3}$ share an edge, and so that the number of vertices of every face is congruent to 1 modulo 4, at the expense of $O(1)$ distortion.
2. Build the BFS tree rooted at an arbitrary vertex $r$, conceptually removing the nontree edges.
3. Add extra "branches" (paths) in between subtrees of the tree in order to change the shape of the embedding of the BFS tree (to come in Step 4) to have a desired horizontal gap between the two subtrees.
4. Embed the resulting tree using Babilon et al.'s tree embedding algorithm.
5. Shift the upper half of the left side of each face to the right to compensate (if needed) for the nontree edges' improvements to shortest paths.

Step 1. We begin with the transformation of the graph into a "tree of cycles":

Lemma 7. Given an outerplanar graph $G$, we can compute an outerplanar graph $G^{\prime}$ such that $V\left(G^{\prime}\right) \supseteq V(G)$, no two faces of $G^{\prime}$ share an edge, the number of vertices on every face of $G^{\prime}$ is congruent to 1 modulo 4 , and any embedding of the shortest-path metric of $G^{\prime}$ into the plane induces an embedding of the shortestpath metric of $G$ with an extra multiplicative factor of $O(1)$ in distortion. Also, $G^{\prime}$ has $O(n)$ vertices.

Proof: To satisfy the distortion constraint, it suffices to construct a suitable graph $G^{\prime}$ such that, for any two vertices $u, v$ of $G$, the shortest-path distance between $u$ and $v$ in $G^{\prime}$ is within a factor of $O(1)$ of their distance in $G$. The dual of $G$ is a forest consisting of one tree for every biconnected component of $G$. It suffices to consider each biconnected component separately, and then glue the modified components together at the vertices with common labels.

The modification of a biconnected component proceeds recursively. To initialize, we set $e$ to any edge of $G$ incident to only one face, and we color the edge $e$ and its endpoints red. In general, we proceed as follows. Let $f$ be the unique face incident to $e$. For each edge $e^{\prime} \neq e$ of face $f$, we double the edge $e^{\prime}$ and duplicate one of its nonred endpoints as in Figure 5 Because $e^{\prime} \neq e$, at least one of the endpoints $u$ of $e^{\prime}$ is different from the red endpoints of $e$; we split $u$ into two vertices, one with the same label $u$, and the other with duplicate label $u^{\prime}$. We color each of the duplicated edges and their endpoints red. Afterward, we conceptually remove the face $f$, and we recurse in each component that has more than one face. Note that, inductively, each component has exactly one red edge, incident to exactly one face.

Because every duplicated vertex is immediately colored red, and no red vertices are duplicated, the number of vertices in the resulting graph $G^{\prime}$ is $O(n)$. Also, the shortest-path distance between any vertex $u$ of $G$ and its duplicate $u^{\prime}$ is exactly 2 in $G^{\prime}$. Thus, any shortest path in $G^{\prime}$ between distinct vertices in $G$ is at most a constant factor longer than the shortest path in $G$, so we obtain the desired distortion bound.
Finally, we can modify $G^{\prime}$ to guarantee that every face has length congruent to 1 modulo 4 . For each face in $G^{\prime}$ of length congruent

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Figure 5. Eliminating edge neighborings.
to $j \neq 1$ modulo $4,2 \leq j \leq 4$, we subdivide one of the edges into a path of $6-j$ edges. Now every face has length congruent to 1 modulo 4 . Each edge is subdivided $O(1)$ times, so the total length of any path, and the size of the whole graph, increases by at most a constant factor.

From now on, we work on $G^{\prime}$ instead of $G$. We fix a combinatorial outerplanar embedding of $G^{\prime}$, so that cycles correspond to faces.

Step 2. Next we compute a breadth-first search (BFS) tree of $G^{\prime}$ (in the primal). For simplicity, we assign the root of the breadthfirst search to be a degree-2 vertex of $G^{\prime}$. We view this root vertex as being at the bottom of the embedding. Define the height of a vertex to be its level in the BFS tree, i.e., its tree distance to the root. We view the $y$ coordinates of the embedding as being proportional to height; together with the combinatorial planar embedding of $G^{\prime}$, this view defines a notion of "left" and "right" between vertices at the same height. See Figure 6
The BFS tree decomposes the edges of $G^{\prime}$ into tree edges and nontree edges. Each nontree edge completes a face of the outerplanar graph $G^{\prime}$ together with only tree edges, because the faces of $G^{\prime}$ are the 2 -connected components of $G^{\prime}$. Indeed, there is exactly one nontree edge per face $f$. Because faces of $G^{\prime}$ have odd length by Lemma 7 the endpoints of the nontree edge of $f$ have equal height, namely, the maximum height among all vertices on the face $f$. In Figure 6 we draw the nontree edge as an apex at the top of each face. On the other hand, the base vertex of a face is the vertex of minimum height, which is where the breadth-first search first enters the face. The base vertex and the nontree edge divide the tree edges of the face into a left side and a right side, of equal size, each starting at the base vertex and ending at an endpoint of the nontree edge. We consider the base vertex to belong to both the left and right sides unless specified otherwise.
At the end, the endpoints of each nontree edge will need to be brought closer together. Intuitively, no vertex is pulled in two directions by two different nontree edges: every vertex is incident to at most one nontree edge, because a vertex is the base of all but at most one incident face, and the endpoints of the nontree edge of a face have strictly larger height than the base of the face.

Step 3. We now define a further modification $G^{\prime \prime}$ of the graph. The modification is based on attaching new child paths, called extra branches, of certain lengths to certain nodes of the BFS tree. Extra branches are always added in pairs, and each pair of extra branches is effectively treated as a unit. There are three types of pairs of extra branches that we add.
Extra branches of the first and second types are created as follows. For each vertex $u$ with $k \geq 2$ children in the BFS tree, we attach $k-1$ pairs of extra branches, one pair between every two consecutive children of $u$ in the BFS tree. We first try attaching the pair of branches at $u$, and embedding the branches to enter the


Figure 6. The graph $G^{\prime \prime}$ with extra branches.
region between the two children. However, if this would cause the branches to enter a face $f$ of the graph $G^{\prime}$, then we instead attach the two branches at the two endpoints of the nontree edge of $f$, one branch at each endpoint, embedded between any children of the two endpoints. Branches attached to $u$ are of the first type; branches attached to the nontree edge of $f$ are of the second type. In either case, the origin of each branch is the vertex $u$ (even though the branch may not be attached to $u$ ).

Next we define the height of the extra branches of the first and second types, i.e., the height of the top vertex of each such branch. Initially, we set all of the heights to be $n$; then we trim some of the branches in order to guarantee that the number of vertices in $G^{\prime \prime}$ is only a constant factor larger than the number of vertices in $G^{\prime}$. We also try to preserve the property that there is at least one extra vertex between any two nonextra vertices at the same height not belonging to the same face. The trimming algorithm proceeds as follows: while there are two horizontally adjacent extra vertices of the same type, but not from the same pair of extra branches, remove the extra vertex that originates from a higher vertex, breaking ties according to horizontal order with left having highest priority. Note that extra branches of the second type are given priority according to the height of their origin at the bottom of the face, not the height of the endpoints of the nontree edge.

We add pairs of extra branches of the third type wherever a vertex $u$ is on the left side of a face $f$ (excluding the base vertex) and has at least one child strictly left of $f$. In this case, we attach a pair of extra branches to $u$ in between the face $f$ and the children of $u$ strictly left of $f$. The height of these branches is defined to be the minimum of two heights: (1) the maximum height among descendants of the children of $u$ strictly left of $f$, and (2) the maximum height among vertices strictly right of $f$ that are descendants of vertices on the right half of the face $f$. One vertex may have attached to it pairs of extra branches of multiple types; in this case, we arbitrarily assign the left-to-right ordering of the pairs in the combinatorial embedding. (In fact, we could also simply remove the shorter pairs of extra branches.)

Figure 6shows an example with six faces. The extra branches after trimming are drawn as dashed lines; the dotted extensions show the original branches of the first type before trimming. For instance, there are two pairs of extra branches originating from the junction between $f_{1}$ and $f_{3}$. As drawn, the left extra branch is of the third type, and the right extra branch is of the first type (and has been trimmed).

The extra branches preserve many aspects of the graph. We never add a branch inside a face, so the faces are preserved. The extra branches do not change the distances between vertices in $G^{\prime}$. Furthermore, the resulting graph $G^{\prime \prime}$ is not much larger than $G^{\prime}$ :

## LEMMA 8. The graph $G^{\prime \prime}$ with extra branches has size $O(n)$.

Proof: We prove that the number of extra vertices is linear separately for each type. For extra branches of the first or second type separately, if we remove one branch from each pair of extra branches, then by the definition of trimming, each extra vertex is either the leftmost at its height or it has a unique nonextra vertex immediately to its left. Thus we can charge the two vertices from a pair of extra branches either to the height or to the unique nonextra vertex. For extra branches of the third type, if we remove one branch from each pair of extra branches, then we claim that each extra vertex has a unique nonextra vertex immediately to its left. This claim follows from the definition of the height of an extra branch of the third type: any potentially conflicting horizontally adjacent branches of the third type must be above one of the two heights whose minimum we take. Thus we can charge to the nonextra vertex. Because the maximum height and the number of nonextra vertices is $O(n)$, the total number of extra vertices is $O(n)$.

Step 4. We apply the Babilon et al. tree embedding algorithm [1] to the BFS tree of the graph $G^{\prime \prime}$ (i.e., the BFS tree of $G^{\prime}$ augmented with the extra branches). Intuitively, the algorithm assigns an angular wedge to each subtree proportionally according to the number of vertices in the subtree, and assigns $y$ coordinates according to the height of each node plus a complicated perturbation. In particular, the algorithm preserves the specified combinatorial embedding of the BFS tree of $G^{\prime \prime}$. Precisely, the algorithm assigns to each vertex $v$ the coordinates $\left(x^{\prime}(v), y(v)\right)$ as follows:

$$
\begin{aligned}
y(v) & =2 \sqrt{n} h(v)+[\ell(v) \bmod \sqrt{n}] \\
x^{\prime}(v) & =\frac{k(v)}{\sqrt{n}}
\end{aligned}
$$

The functions $h(v), \ell(v)$, and $k(v)$ are defined as follows. First, $h(v)$ denotes the height of $v$. Let $\pi_{v}$ denote the BFS path from the root to $v$, i.e., the path of ancestors of $v$. These paths define a partial order on the vertices: $u \prec v$ if $u \notin \pi_{v}, v \notin \pi_{u}$, and $\pi_{u}$ goes to the left of $\pi_{v}$ at the vertex at which $\pi_{u}$ and $\pi_{v}$ branch. Now $\ell(v)$ denotes the number of predecessors of $v$ in this partial order: $\ell(v)=|\{u \in V \mid u \prec v\}|$. Define $\operatorname{sgn}_{v}(u)$ to be 0 if $u \in \pi_{v}$ or $v \in \pi_{u},+1$ if $u \prec v$, and -1 if $v \prec u$. Let $a_{v}(u)$ denote the tree distance from $v$ to the nearest common ancestor of $u$ and $v$, i.e., the vertex at which $\pi_{u}$ and $\pi_{v}$ branch. Finally, $k(v)=\sum_{u \in V} \operatorname{sgn}_{v}(u) a_{v}(u)$.

ThEOREM 9. [1] Theorem 1] Babilon et al.'s tree embedding $\left(x^{\prime}(v), y(v)\right)$ embeds the BFS tree with $O(\sqrt{n})$ distortion: for a constant $c_{0}>0$, the Euclidean distance between any two vertices is between (a) $c_{0}$ times their tree distance and (b) $O(\sqrt{n})$ times their tree distance.

Before we describe our modifications to this embedding, we prove a basic fact about it:

LEMMA 10. In Babilon et al.'s tree embedding algorithm, the difference in $x$ coordinates between two vertices of the same height is no less than the difference in $x$ between their parents.
Proof: Suppose two vertices $w$ and $z$ have the same height. Assume by symmetry that $w$ is to the left of $z$. Let $p$ be $w$ 's parent and let $q$ be $z$ 's parent. Assume that $p \neq q$; otherwise,
$x^{\prime}(q)-x^{\prime}(p)=0$ and the lemma follows trivially. Thus, $p$ is to the left of $q$. Let $g(v)=\sum_{u \in V} \operatorname{sgn}_{v}(u)$ be the number of vertices to $v$ 's left minus the number of vertices to $v$ 's right. Let $c(v)=\left|\left\{u \mid v \in \pi_{u}\right\}\right|$ be the number of descendants of $v$ (including $v$ itself).

We analyze the difference in $x$ coordinates between $w$ and its parent $p$, i.e., $x^{\prime}(w)-x^{\prime}(p)=(k(w)-k(p)) / \sqrt{n}$. It suffices to consider the difference $k(w)-k(p)$, ignoring the factor of $\sqrt{n}$. By the definition of $k(v)$, there are two ways in which $k(p)$ differs from $k(w)$. First, for every vertex $u$ with $\operatorname{sgn}_{p}(u) \neq 0$, $a_{p}(u)=a_{w}(u)-1$, for an overall decrease in the summation by $g(w)$. Second, the $c(p)-c(w)$ descendants of $p$ that are not descendants of $w$ are no longer counted in the summation; each such descendant $u$ has lowest common ancestor $p$ with $w$, so $a_{w}(u)=1$, leading to a contribution of $\pm 1$ to the summation. Therefore, we have the following bound on the difference $k(w)-k(p)$ :

$$
\begin{equation*}
g(p)-c(p) \leq k(w)-k(p) \leq g(p)+c(p) \tag{1}
\end{equation*}
$$

By symmetry, we obtain the following bound on the difference $k(z)-k(q)$ :

$$
g(q)-c(q) \leq k(z)-k(q) \leq g(q)+c(q)
$$

Summing the upper bound on $k(w)-k(p)$ and the lower bound on $k(z)-k(q)$, we obtain

$$
k(q)-k(p) \leq k(z)-k(w)+g(p)-g(q)+c(p)+c(q)
$$

We claim that $g(p)-g(q)+c(p)+c(q) \leq 0$, i.e., $g(q)-g(p) \geq$ $c(p)+c(q)$, and thus this term can be discarded from the inequality. By the definition of $g$ and because $p$ is left of $q, g(q)-g(p)$ counts the number of vertices that are horizontally in between $p$ and $q$ (right of $p$ and left of $q$ ), plus the number of descendants of $p$ and of $q$. The number of these descendants is $c(p)+c(q)$.

Therefore, $x^{\prime}(q)-x^{\prime}(p)=(k(q)-k(p)) / \sqrt{n} \leq(k(z)-$ $k(w)) / \sqrt{n}=x^{\prime}(z)-x^{\prime}(w)$.

Step 5. Because of nontree edges, shortest paths in the BFS tree may be much larger than in $G^{\prime \prime}$. To compensate for the lack of nontree edges in tree embedding algorithm, we "shift" part of each face. Intuitively, the tree embedding algorithm pushes apart the two sides to match the shortest paths in the BFS tree between the vertices of the sides. On the other hand, the existence of the nontree edge between its endpoints decreases the shortest path between the vertices in the upper half of the two sides, so much that the endpoints have distance 1 from each other. Roughly speaking, if the endpoints of the nontree edge of a face are farther than $c_{1} \sqrt{n}$, for a suitable constant $c_{1}$, we shift the upper half of the left side to the right, so that the endpoints have distance $\Theta(\sqrt{n})$ at the end.

More precisely, we put a shift value $s(u)$ on any vertex $u$ in the upper half of the left side of a face $f$. Thus, the distance from $u$ to the base vertex of $f$ is at least $\lfloor|f| / 4\rfloor$ where $|f|$ is the number of vertices on face $f$. (The face $f$ is well-defined because a vertex $u$ can be in the upper left part of at most one face.) Let $v$ denote the vertex on the right side of $f$ with the same height as $u$, and let $p$ and $q$ be the parents of $u$ and $v$, respectively. Let $g$ and $t$ be the vertices midway along the left and right sides, respectively, of the face $f$ (of distance exactly $\lfloor|f| / 4\rfloor$ from the base vertex of $f$ ). If $x^{\prime}(t)-x^{\prime}(g) \leq c_{1} \sqrt{n}$, we define $s(u)=0$. Otherwise, we define
$s(u)=\left[x^{\prime}(p)-x^{\prime}(u)\right]-\left[x^{\prime}(q)-x^{\prime}(v)\right]+\frac{x^{\prime}(t)-x^{\prime}(g)-c_{1} \sqrt{n}}{\lfloor|f| / 4\rfloor}$.
where $x^{\prime}(v)$ is the $x$ coordinate assigned to $v$ by Babilon et al.'s algorithm as defined above. Note that, by Lemma $10 x^{\prime}(p)-x^{\prime}(u)+$ $x^{\prime}(v)-x^{\prime}(q) \geq 0$, and thus $s(u) \geq 0$. For any vertex $u$ that is not on the upper half of the left side of any face, we define $s(u)=0$.

The shift value $s(u)$ applies to $u$ and all of its descendants. Therefore, our formula for the embedding is as follows:

$$
\begin{aligned}
y(v) & =2 \sqrt{n} h(v)+[\ell(v) \bmod \sqrt{n}] \\
x(v) & =\frac{k(v)}{\sqrt{n}}+\sum_{u \in \pi_{v}} s(u)
\end{aligned}
$$

In other words, we first make the upper half of the left side of the face roughly parallel to the upper half of the right side of the face, and then slant the left side of the upper half of the face to the right by having a linear growth in shift amount as we proceed up the left side.

LEMMA 11. For every vertex $u, s(u)=O(\sqrt{n})$.
Proof: Applying [1] with $w=u$, we obtain that $|k(u)-k(p)|=$ $O(n)$. Thus, $x^{\prime}(p)-x^{\prime}(u)=(k(u)-k(p)) / \sqrt{n}=O(\sqrt{n})$, and similarly, $x^{\prime}(v)-x^{\prime}(q)=O(\sqrt{n})$. Because the distance in the BFS tree between $g$ and $t$ is less than $|f|$, and by Theorem 9b), we have $\left|x^{\prime}(g)-x^{\prime}(t)\right|=O(|f| \sqrt{n})$. Therefore, $\frac{\left|x^{\prime}(g)-x^{\prime}(h)\right|-c_{1} \sqrt{n}}{\lfloor|f| / 4\rfloor}=O(\sqrt{n})$, so by summing all terms, we obtain that $s(u)=O(\sqrt{n})$.

Distortion analysis. We prove that the distortion of our embedding is $O(\sqrt{n})$ in two parts: the least any distance is contracted is $\Omega(1)$, and the most any distance is expanded is $O(\sqrt{n})$.

LEMMA 12. The shifting process preserves the horizontal ordering of vertices with the same height. Furthermore, two vertices of the same height that got closer during the shifting process remain at a horizontal distance of at least $c_{1} \sqrt{n}$.

Proof: Suppose that $u$ and $v$ are at the same height and that $u$ is to the left of $v$ in the tree. Let $p$ be the nearest ancestor of $u$ with positive shift value $s(p)$, and let $f$ be the face causing the shift. Let $q$ be the ancestor of $v$ at the same height as $p$. Assume that $p \neq q$, because otherwise $u$ is not shifted relative to $p$ and any shifting of $v$ only separates $u$ and $v$, so there is nothing to prove. Thus, $p$ is strictly to the left of $q$. Let $r$ be the vertex on the right side of face $f$ with the same height as $p$ and $q$. Thus, $r$ is strictly right of $p$ and (nonstrictly) left of $q$ in the tree.
We claim that, after shifting, $p$ is to the left of $r$ by a horizontal distance of at least $c_{1} \sqrt{n}$. Let $d$ denote the graph distance between $p$ and $r$ in $G^{\prime \prime}$, and suppose that $g$ and $t$ are the vertices midway along the left and right sides, respectively, of the face $f$. Because this face was shifted, $x^{\prime}(t)-x^{\prime}(g)>c_{1} \sqrt{n}$. Thus,

$$
\begin{aligned}
x(r)- & x(p) \\
= & x^{\prime}(r)-x^{\prime}(p)-\sum_{r \in f \cap \pi_{p}} s(r) \\
= & x^{\prime}(r)-x^{\prime}(p)-\left[x^{\prime}(g)-x^{\prime}(p)\right]+\left[x^{\prime}(t)-x^{\prime}(r)\right] \\
& \quad-\sum_{r \in f \cap \pi_{p}} \frac{x^{\prime}(t)-x^{\prime}(g)-c_{1} \sqrt{n}}{\lfloor|f| / 4\rfloor} \\
= & x^{\prime}(t)-x^{\prime}(g)-(\lfloor|f| / 4\rfloor-d / 2) \frac{x^{\prime}(t)-x^{\prime}(g)-c_{1} \sqrt{n}}{\lfloor|f| / 4\rfloor} \\
= & {\left[1-\frac{\lfloor|f| / 4\rfloor-d / 2}{\lfloor|f| / 4\rfloor}\right]\left[x^{\prime}(t)-x^{\prime}(g)\right]+\frac{\lfloor|f| / 4\rfloor-d / 2}{\lfloor|f| / 4\rfloor} c_{1} \sqrt{n} } \\
= & \frac{d / 2}{\lfloor|f| / 4\rfloor}\left[x^{\prime}(t)-x^{\prime}(g)\right]+\left(1-\frac{d / 2}{\lfloor|f| / 4\rfloor}\right) c_{1} \sqrt{n} \\
\geq & \frac{d / 2}{\lfloor|f| / 4\rfloor} c_{1} \sqrt{n}+\left(1-\frac{d / 2}{\lfloor|f| / 4\rfloor}\right) c_{1} \sqrt{n} \\
= & c_{1} \sqrt{n} .
\end{aligned}
$$

Observe that $r$ either has a strictly smaller height than $u$, or it is to the right of $p=u$. Thus, we can apply induction to the vertices $r$ and $q$ to conclude that $r$ remains to the left of $q$ after shifting. Hence, $p$ remains to the left of $q$ (in addition to $r$ ) by a horizontal distance of at least $c_{1} \sqrt{n}$. By repeated application of Lemma 10 . $x^{\prime}(v)-x^{\prime}(u) \geq x^{\prime}(q)-x^{\prime}(p)$. Because $u$ is shifted the same amount as $p$ and $v$ is shifted at least as much as $q, x(v)-x(u) \geq$ $x(q)-x(p)$, which is at least $c_{1} \sqrt{n}$. Therefore, $u$ remains to the left of $v$ by a horizontal distance of at least $c_{1} \sqrt{n}$.

LEMMA 13. For sufficiently large $c_{1}$, the Euclidean distance between two nonextra vertices of the same height is at least a constant factor times their graph distance.

Proof: Consider any two nonextra vertices $u$ and $v$ of the same height, and assume by symmetry that $u$ is to the left of $v$. (By Lemma 12 the notion of "left" is the same before and after shifting.) Assume without loss of generality that $u$ got closer to $v$ during the shifting process; otherwise, the lemma follows from Theorem 9 (a).

If $u$ and $v$ are on a common face $f$, then they are in the upper half of a face that was shifted. Let $d$ denote the graph distance between $u$ and $v$ in $G^{\prime \prime}$, and suppose that $g$ and $t$ are the vertices midway along the left and right sides, respectively, of the face $f$. By Theorem 9a), the Euclidean distance between $g$ and $t$ in the tree embedding is at least $c_{0}\lfloor|f| / 2\rfloor$. Furthermore, their vertical distance $|y(g)-y(t)|$ is at most $\sqrt{n}$, and because this face was shifted, by Lemma 12 their horizontal distance $x^{\prime}(t)-x^{\prime}(g)$ is at least $c_{1} \sqrt{n}$. Therefore, $x^{\prime}(t)-x^{\prime}(g) \geq\left(c_{1}-1\right) c_{0}\lfloor|f| / 2\rfloor$. Now we can prove that $x(v)-x(u)=\Omega(d)$ and therefore that the Euclidean distance between $u$ and $v$ in our embedding is $\Omega(d)$ :

$$
\begin{aligned}
x(v)-x(u)= & x^{\prime}(v)-x^{\prime}(u)-\sum_{r \in f \cap \pi_{u}} s(r) \\
= & x^{\prime}(v)-x^{\prime}(u)-\left[x^{\prime}(g)-x^{\prime}(u)\right]+\left[x^{\prime}(t)-x^{\prime}(v)\right] \\
& -\sum_{r \in f \cap \pi_{u}} \frac{x^{\prime}(t)-x^{\prime}(g)-c_{1} \sqrt{n}}{\lfloor|f| / 4\rfloor} \\
= & x^{\prime}(t)-x^{\prime}(g)-\sum_{r \in f \cap \pi_{u}} \frac{x^{\prime}(t)-x^{\prime}(g)-c_{1} \sqrt{n}}{\lfloor|f| / 4\rfloor} \\
\geq & x^{\prime}(t)-x^{\prime}(g)-\sum_{r \in f \cap \pi_{u}} \frac{x^{\prime}(t)-x^{\prime}(g)}{\lfloor|f| / 4\rfloor} \\
& =\left[1-\frac{\lfloor|f| / 4\rfloor-d / 2}{\lfloor|f| / 4\rfloor}\right]\left[x^{\prime}(t)-x^{\prime}(g)\right] \\
& =\frac{d / 2}{\lfloor|f| / 4\rfloor}\left[x^{\prime}(t)-x^{\prime}(g)\right] \\
& \geq \frac{d / 2}{\lfloor|f| / 4\rfloor}\left(c_{1}-1\right) c_{0}\lfloor|f| / 2\rfloor \\
& =\left(c_{1}-1\right) c_{0} d,
\end{aligned}
$$

which is $\Omega(d)$ for sufficiently large $c_{1}$.
Now we prove the claim when $u$ and $v$ are not on a common face $f$. Let $p$ be the nearest common anscestor of $u$ and $v$. We distinguish two cases. In Case $1, p$ is the base vertex of a face $f$ such that the children of $p$ that are ancestors of $u$ and $v$ are precisely the two children on the left and right sides, respectively, of $f$. In Case 2, there is no such face $f$.

Case 2 is the easier case. Because the children of $p$ that are ancestors of $u$ and $v$ are not on the two sides of any face, there is a pair of extra branches of the first type attached to $p$ in between $u$ and $v$. Take the leftmost such pair of extra branches (which survives the longest). The height of these branches is at least $h(u)=h(v)$ because this pair of branches is the dominant pair (in terms of priority)
among ancestors of $p$ in between $u$ and $v$. Let $w$ be a vertex in this pair of branches at the same height as $u$ and $v$. By Theorem 9 a), in the tree embedding, the Euclidean distance between $w$ and $v$ is at least $c_{0}$ times their tree distance, which equals their graph distance (because the tree is a BFS tree and $w$ is on its own path from the nearest common ancestor $p$ ), which equals the graph distance from $u$ to $v$ (because the extra branches provide a separation between $u$ and $v$ ). Because $w$ is not shifted relative to $p$, and any shifting of $v$ relative to $p$ brings $w$ and $v$ farther apart, shifting preserves this property that the Euclidean distance between $w$ and $v$ is at least $c_{0}$ times the graph distance from $u$ to $v$. By Lemma $12, u$ is to the left of $w$ and thus the horizontal distance between $u$ and $v$ is at least the horizontal distance between $w$ and $v$. Hence the Euclidean distance between $u$ and $v$ is at least the Euclidean distance between $w$ and $v$ minus $2 \sqrt{n}$ (to account for possible vertical variations), which is at least $c_{0}$ times the graph distance from $u$ to $v$ minus $2 \sqrt{n}$. By Lemma 12, because $u$ shifted toward $v$, their horizontal distance is also at least $c_{1} \sqrt{n}$. By setting $c_{1}$ large enough, we obtain that the Euclidean distance between $u$ and $v$ is at least a constant factor times the graph distance from $u$ to $v$.

Now we consider Case 1. Let $q$ be the highest vertex (on the left side) of the face $f$ that is an ancestor of $u$. Because we are in Case $1, q \neq p$, so there is a pair of extra branches of the third type attached to $q$. By construction of the height of branches of the third type, the height of these branches is at least $h(u)=h(v)$. Let $r$ be a vertex in this pair of branches that has the same height as $u$. We distinguish two subcases according to whether the highest vertex of $f$ is strictly lower than $u$. In each subcase, we argue that $|x(r)-x(v)|=\Omega\left(\mu_{r v}\right)-O(\sqrt{n})$ where $\mu_{r v}$ denotes the graph distance between $r$ and $v$. The construction of the branches ensures that $\mu_{r v}=\mu_{u v}$. By Lemma $12 r$ is between $u$ and $v$, so $|x(u)-x(v)| \geq|x(r)-x(v)|$. Thus we can conclude that $|x(u)-x(v)|=\Omega\left(\mu_{r v}\right)-O(\sqrt{n})=\Omega\left(\mu_{u v}\right)-O(\sqrt{n})$. As argued above, $|x(u)-x(v)| \geq c_{1} \sqrt{n}$. Therefore, for sufficiently large $c_{1}$, we obtain that $|x(u)-x(v)|=\Omega\left(\mu_{u v}\right)$ as desired.

In the first subcase, the highest vertex of $f$ is not strictly lower than $u$ (intuitively, the line segment connecting $r$ and $v$ crosses the face $f$ ). Let $w$ and $z$ be the vertices on the left and right side, respectively, of $f$ with the same height as $u$ and $v$. Then we have

$$
\begin{aligned}
|x(u)-x(v)| & \geq|x(r)-x(w)|+|x(w)-x(z)|+|x(z)-x(v)| \\
& \geq \Omega\left(\mu_{r w}+\mu_{w z}+\mu_{z v}\right)-O(\sqrt{n}) \\
& \geq \Omega\left(\mu_{r v}\right)-O(\sqrt{n})
\end{aligned}
$$

The first inequality follows from the horizontal ordering given by Lemma 12 The second inequality follows from Theorem 9 a); because $r$ does not shift relative to $q$, and $w$ shifting relative to $q$ could only increase $|x(r)-x(w)|$; by the proof above for the case of two vertices on the same face; and because similarly $z$ and $v$ can shift only apart from each other. The third inequality follows from the triangle inequality.
In the second subcase, the highest vertex of $f$ is strictly lower than $u$. Consider the pair of extra branches of the second type attached to the endpoints of the nontree edge of $f$. As usual, these branches have height at least $h(u)=h(v)$ because this is a dominant pair of branches (in terms of priority) among ancestors of $p$ in between $u$ and $v$. (Thus, intuitively, the line segment connecting $r$ and $v$ crosses the extra branches attached to the nontree edge of $f$.) Let $w$ and $z$ be the vertices of the left and right branches in the pair, respectively, with the same height as $u$. Similar to the previous subcase, we have

$$
\begin{aligned}
|x(u)-x(v)| & \geq|x(r)-x(w)|+|x(z)-x(v)| \\
& \geq \Omega\left(\mu_{r w}+\mu_{z v}\right)-O(\sqrt{n}) \\
& \geq \Omega\left(\mu_{r w}+\mu_{w v}\right)-O(\sqrt{n}) \\
& \geq \Omega\left(\mu_{r v}\right)-O(\sqrt{n}) .
\end{aligned}
$$

The first, second, and fourth inequalities follow as in the previous subcase. The third inequality follows because, by the construction of extra branches, $\left|\mu_{z v}-\mu_{w v}\right| \leq 1$.

Lemma 14. For sufficiently large constants $c_{1}$ and $c_{2}$, two vertices at different heights with graph distance at least $c_{2} \sqrt{n}$ have Euclidean distance at least a constant factor times their graph distance.

Proof: Suppose that vertices $u$ and $v$ have graph distance at least $c_{2} \sqrt{n}$. If the height difference between $u$ and $v$ is $\Omega(\sqrt{n})$, then the difference in $y$ coordinates is $\Omega(n)$, which is enough for any graph distance. Therefore, we can assume that $|h(u)-h(v)| \leq \epsilon \sqrt{n}$ for any constant $\epsilon>0$. Assume by symmetry that $h(u)<h(v)$. Let $w$ be the ancestor of $v$ at the same height at $u$.
We claim that the descendants of $w$ (in particular, $v$ ) embed to lie within a cone with apex at $v$ and whose sides are within $\theta$ of vertical for a constant $\theta<90^{\circ}$. This claim is true in the original Babilon et al. embedding: the overall cone for the root node has a vertical axis and angle of at most $45^{\circ}$ from this axis, and all subtree cones are contained in the original. Now we bound the effect of the shifting process. Consider any two adjacent vertices in the graph with heights differing by 1 . Their vertical distance is $\Theta(\sqrt{n})$, so by the $45^{\circ}$ cone property of the original tree embedding, their horizontal distance in the original tree embedding is $O(\sqrt{n})$. Also, by Lemma 11 every shift value is $O(\sqrt{n})$. Thus, their horizontal distance in our embedding is $O(\sqrt{n})$, at most a constant factor times the vertical distance. Because this holds for all edges of the graph that span adjacent heights, the entire subtree of $w$ 's descendants must lie in a cone with a constant lower bound on the absolute slope of the two sides.
Because $w$ is an ancestor of $v$ in the BFS tree, the length $\mu_{v w}$ of the shortest path from $v$ to $w$ is $h(v)-h(w)$, which we assumed to be at most $\epsilon \sqrt{n}$. By the triangle inequality, $\mu_{u v} \leq \mu_{u w}+\mu_{v w}$. The left-hand side is large- $\mu_{u v} \geq c_{2} \sqrt{n}$-yet the second term on the right-hand side is small- $\mu_{v w} \leq \epsilon \sqrt{n}$. Thus, $\mu_{u w} \geq(1-\epsilon) \mu_{u v} \geq$ $(1-\epsilon) c_{2} \sqrt{n}$.
By Lemma 13 the Euclidean distance between $u$ and $w$ is $\Omega\left(\mu_{u w}\right)$, and we have just shown that $\mu_{u w} \geq(1-\epsilon) c_{2} \sqrt{n}$. By construction, the difference in $y$ coordinates between $u$ and $w$ is at most $\sqrt{n}$. Thus, by choosing $c_{2}$ large enough, we obtain that the horizontal distance between $u$ and $w$ is at least any desired constant times $\sqrt{n}$, while the vertical distance is at most $\sqrt{n}$. Hence, for $c_{2}$ sufficiently large, $u$ is outside $w$ 's cone, and furthermore, the absolute slope of the line segment from $u$ to $w$ is strictly less than the absolute slope of the sides of the cone. Therefore, the Euclidean distance from $u$ to any point in the cone is at least a constant factor times the Euclidean length of the line segment from $u$ to $w$, which we showed is $\Omega\left(\mu_{u w}\right)=\Omega\left(\mu_{u v}\right)$. In particular, $v$ is in $w$ 's cone, so the Euclidean distance from $u$ to $v$ is $\Omega\left(\mu_{u v}\right)$.

Lemma 15. The expansion in our embedding between any pair of nonextra vertices is $O(\sqrt{n})$.

Proof: First we claim that every edge of the graph $G^{\prime}$ has Euclidean length $O(\sqrt{n})$. Each graph edge is either a tree edge or a nontree edge. The tree edges had $O(\sqrt{n})$ distortion in the original tree embedding by Theorem 9 b), and by Lemma 11 the shifting process changes the Euclidean length of each edge by at most an additive $O(\sqrt{n})$. Thus, the tree edges still have Euclidean length $O(\sqrt{n})$.
Now we prove the claim for nontree edges. Let $w$ and $z$ be the left and right endpoints, respectively, of the nontree edge of face $f$. If $x^{\prime}(z)-x^{\prime}(w)>2 c_{1} \sqrt{n}$, then by concavity of the horizontal distance of the two vertices on the face $f$ at the same height in Babilon et al.'s embedding, the points $g$ and $t$ midway along the left
and right sides, respectively, of the face $f$ satisfy $x^{\prime}(t)-x^{\prime}(g)>$ $c_{1} \sqrt{n}$. Thus, in this case, the face $f$ is shifted. After shifting, we have

$$
\begin{aligned}
x(z)-x(w)= & x^{\prime}(z)-x^{\prime}(w)-\sum_{r \in f \cap \pi_{w}} s(r) \\
= & x^{\prime}(z)-x^{\prime}(w)-\left[x^{\prime}(g)-x^{\prime}(w)\right]+\left[x^{\prime}(t)-x^{\prime}(z)\right] \\
& -\sum_{r \in f \cap \pi_{w}} \frac{x^{\prime}(t)-x^{\prime}(g)-c_{1} \sqrt{n}}{\lfloor|f| / 4\rfloor} \\
= & x^{\prime}(t)-x^{\prime}(g)-(\lfloor|f| / 4\rfloor) \frac{x^{\prime}(t)-x^{\prime}(g)-c_{1} \sqrt{n}}{\lfloor|f| / 4\rfloor} \\
= & c_{1} \sqrt{n} .
\end{aligned}
$$

Hence, if the nontree edge $\{w, z\}$ is shifted, which is forced when $x^{\prime}(z)-x^{\prime}(w)>2 c_{1} \sqrt{n}$, then $x(z)-x(w)=c_{1} \sqrt{n}$. Otherwise, we have $x(z)-x(w)=x^{\prime}(z)-x^{\prime}(w) \leq 2 c_{1} \sqrt{n}$. Also, $\mid y(w)-$ $y(z) \mid \leq \sqrt{n}$. Therefore, every edge of $G^{\prime}$ has length $O(\sqrt{n})$.
By the triangle inequality, the distortion of the embedding of $G^{\prime}$ is $O(\sqrt{n})$, because the bound holds for each edge of a shortest path. By Lemma 7 the distortion of the embedding of the original graph $G$ is $O(\sqrt{n})$.

We conclude with the main result of this section:
THEOREM 16. Every outerplanar graph $G$ can be embedded into the plane with distortion $O(\sqrt{n})$.

Proof: We claim that the Euclidean distance between any two vertices $u$ and $v$ in the constructed embedding is at least a constant factor times their graph distance. If $u$ and $v$ have the same height, Lemma 13 proves the claim. Otherwise, their graph distance is either at least $c_{2} \sqrt{n}$ or smaller. In the first case, Lemma 14 proves the claim. In the second case, the Euclidean distance between $u$ and $v$ is at least their distance in $y$ coordinates, which by construction is at least $\sqrt{n}$, proving the claim.
On the other hand, Lemma 15 proves that the Euclidean distance between any two vertices $u$ and $v$ in the constructed embedding is at most $O(\sqrt{n})$ times their graph distance. Therefore, scaling the embedding by a constant multiplicative factor yields a noncontractive embedding with expansion $O(\sqrt{n})$ as desired.

## 4. OPEN PROBLEMS

The main open problem is to obtain tight worst-case bounds on the distortion required to embed planar graph metrics into the plane. To this end, it would be a natural step to consider boundedouterplanarity graphs (which generalize the notion of outerplanar graphs), series-parallel graphs (which are slightly more general than outerplanar graphs), and bounded-treewidth graphs (which generalize both of these classes). Note that the series-parallel graph known as the diamond graph, used previously in embedding lower bounds [7. 18, 22], can be embedded into the plane with $O(\sqrt{n} \log n)$ distortion.
We also emphasize the open problem from [1 19] of embedding the shortest-path metrics of weighted trees and planar graphs into the plane. Matoušek [19| conjectures an upper bound of $O(\sqrt{n})$ for trees, but no $o(n)$ upper bound is known. It may also be easier to prove an $\omega\left(n^{2 / 3}\right)$ worst-case lower bound for weighted planar graph metrics.

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[^2]:    ${ }^{1}$ More precisely, given a metric $M$ on a point set $V$ and a target space of $d$-dimensional $\ell_{s}$ space, the goal is to find a mapping $f: V \rightarrow \mathbb{R}^{d}$ to either approximately minimize additive distortion $\max _{v, w \in V}\left|\|f(v)-f(w)\|_{s}-M[v, w]\right|$, or approximately minimize multiplicative distortion $\max _{v, w \in V} \| f(v)$ $f(w) \|_{s} / M[v, w]$ subject to $\|f(v)-f(w)\|_{s} \geq M[v, w]$ (noncontractiveness). (In $d$-dimensional $\ell_{s}$ space, distances and lengths are measured according to the $\ell_{s}$ norm $\left\|\left(x_{1}, \ldots, x_{d}\right)\right\|_{s}=$ $\sqrt[s]{x_{1}^{s}+\cdots+x_{d}^{s}}$.

[^3]:    ${ }^{2}$ We use the term "country" instead of "face" in order to refer to the same cycles when considering not-necessarily-planar embeddings of the globe graph.

[^4]:    ${ }^{3}$ Throughout this section we use the term "face" to refer to bounded faces only, excluding the outside face.

