

Scientific Computing

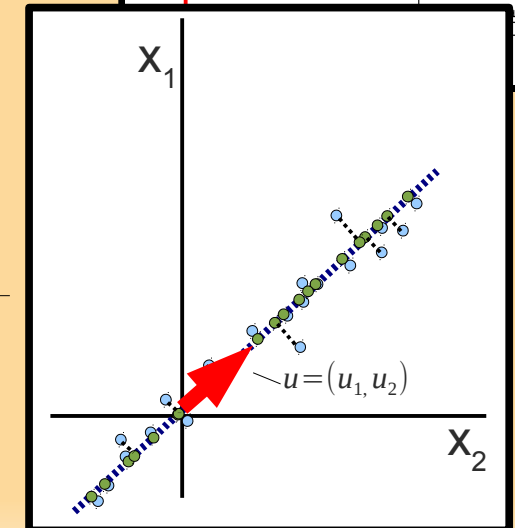
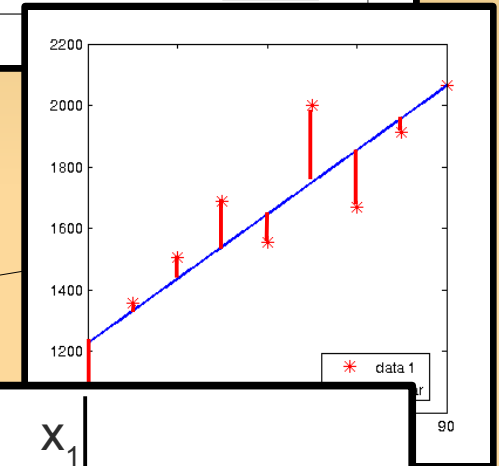
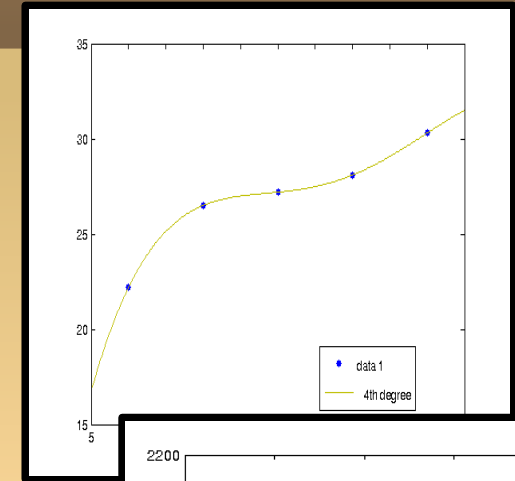
Maastricht Science Program

Week 4

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Recap

- Matlab...!
- Supervised Learning
 - find f that maps $\{x_1^{(j)}, \dots, x_D^{(j)}\} \rightarrow y^{(j)}$
 - Interpolation
 - f goes through the data points
 - linear regression
 - lossy fit, minimizes 'vertical' SSE
- Unsupervised Learning
 - PCA
 - We just have data points $\{x_1^{(j)}, \dots, x_D^{(j)}\}$



Numerical Differentiation and Integration

Numerical Differentiation and Integration

- Finding derivatives or primitives of a function f
- not always easy or possible....
 - no closed form solution exists
 - the solution is a very complex expression that is hard to evaluate
 - we may not know f (as before!)

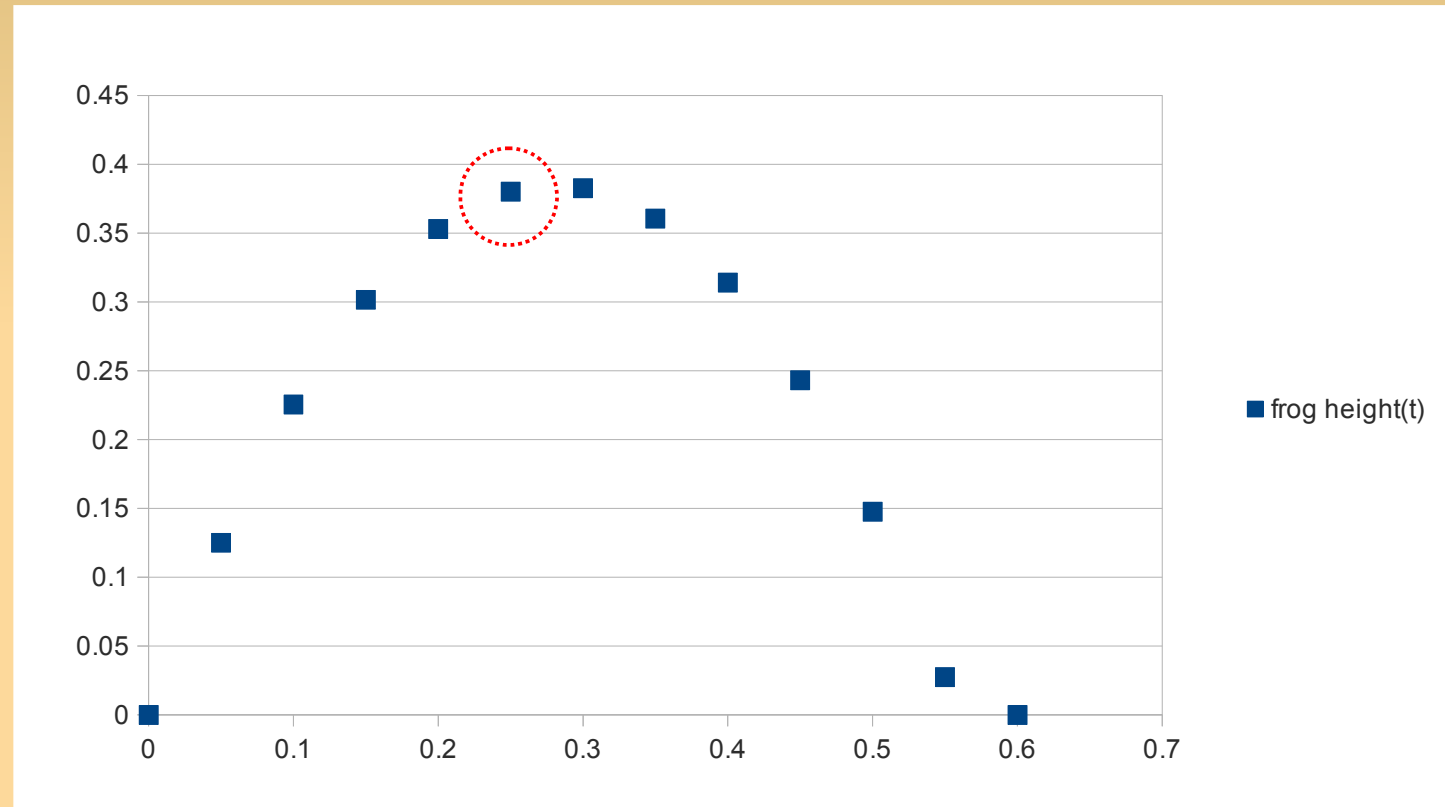
→ numerical methods

Numerical Differentiation

- If we want to know the rate of change...
- E.g.:
 - fluid in a cylinder with a hole in the bottom, measured every 5 seconds.
 - High-speed camera images of animal movements, (jumping in frogs and insects, suction feeding in fish, and the strikes of mantis shrimp)
 - determine speed
 - and acceleration

Numerical Differentiation

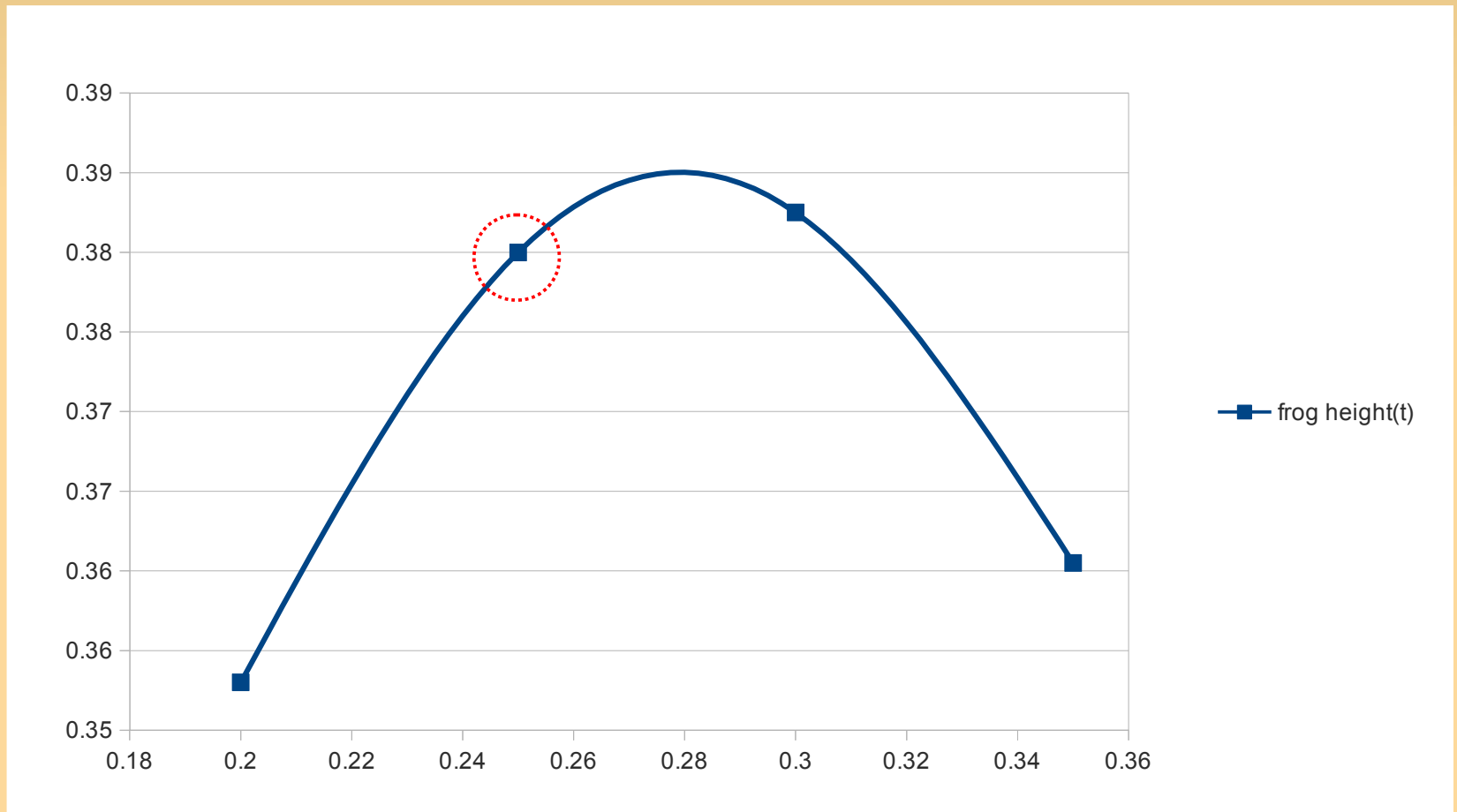
- Determine the vertical speed at $t=0.25$



- what would you do?

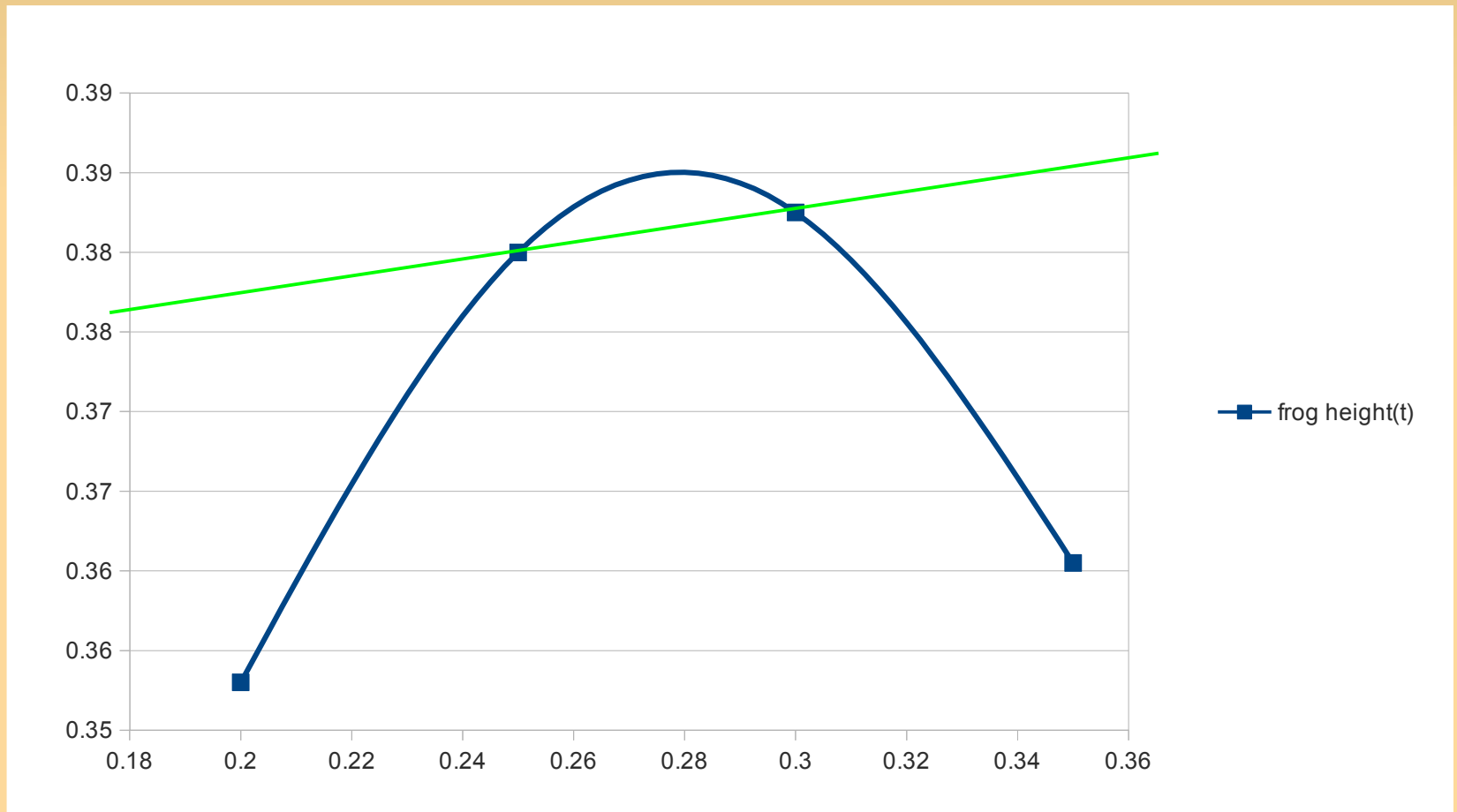
Numerical Differentiation

- Determine the vertical speed at $t=0.25$...
 - a few options...



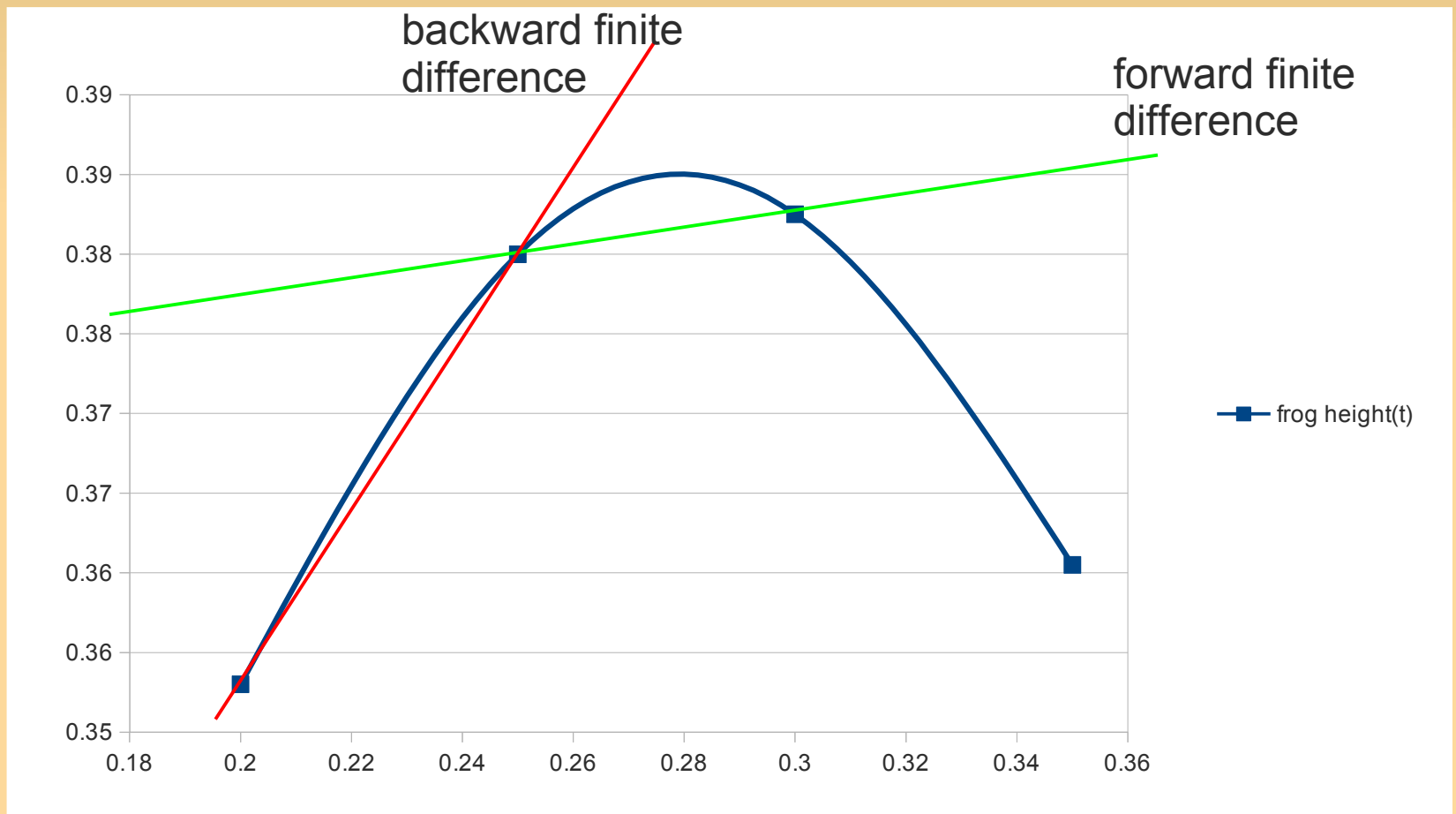
Numerical Differentiation

- Determine the vertical speed at $t=0.25$...
 - a few options...



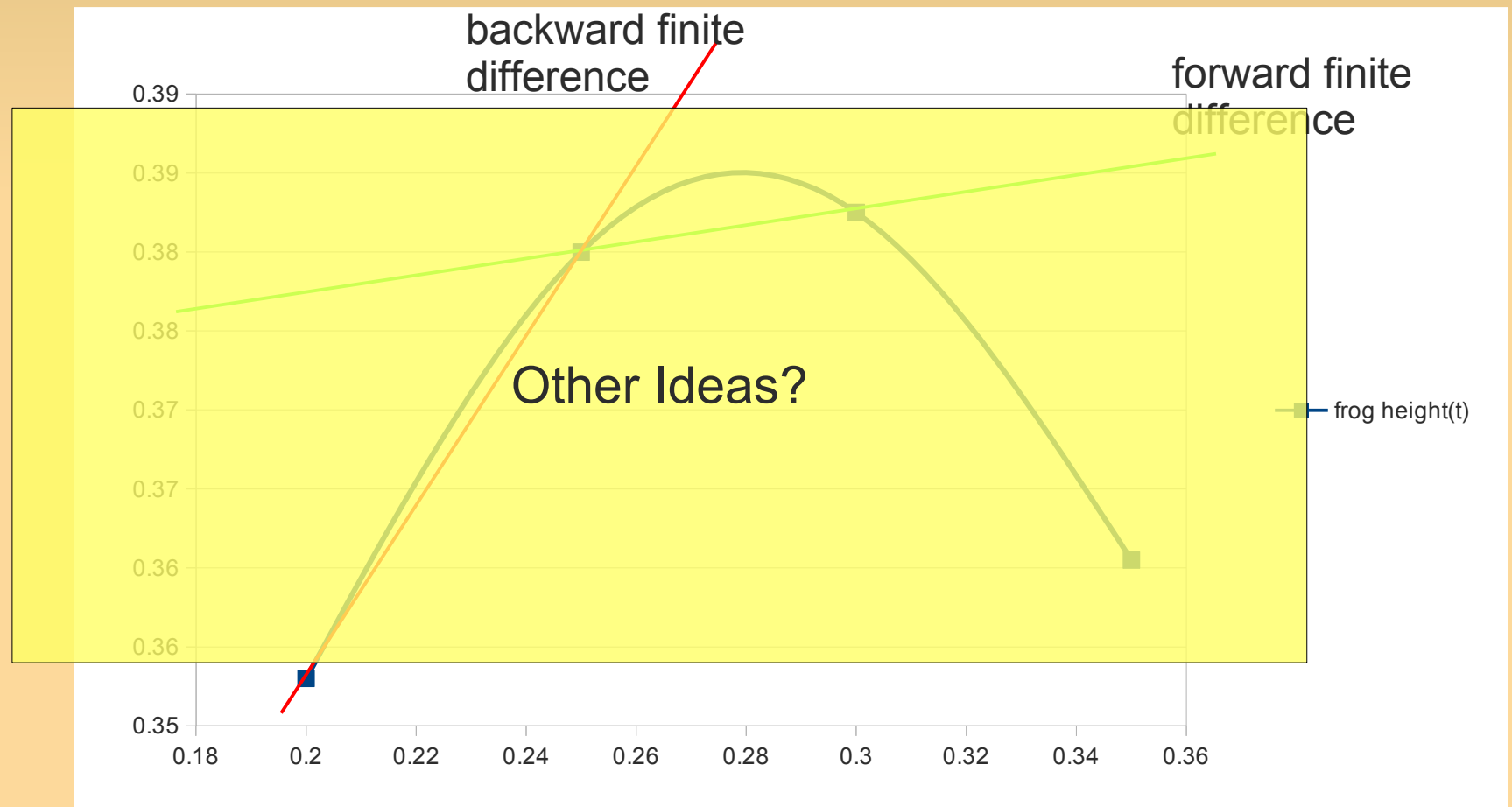
Numerical Differentiation

- Determine the vertical speed at $t=0.25$...
 - a few options...



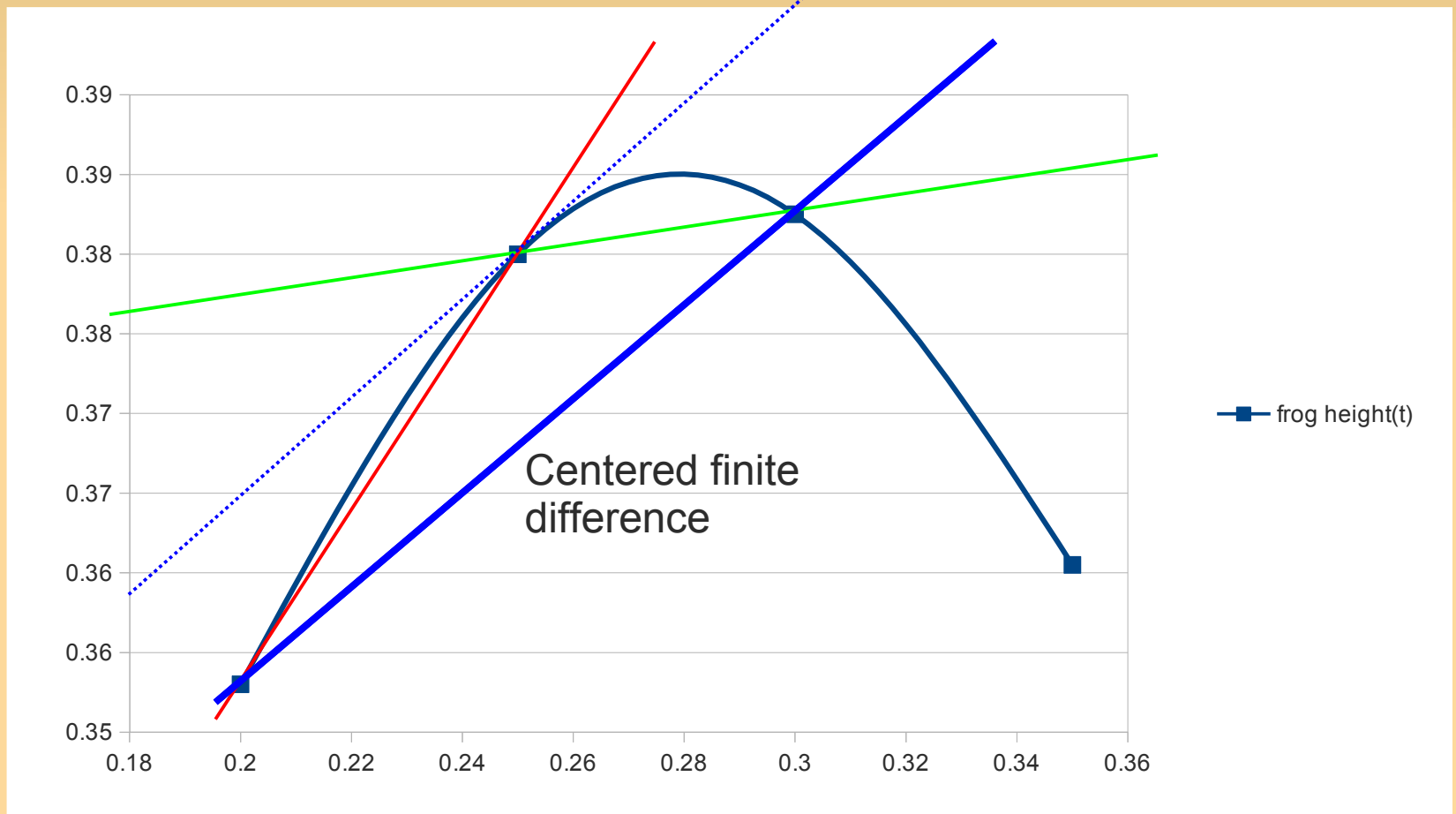
Numerical Differentiation

- Determine the vertical speed at $t=0.25$...
 - a few options...



Numerical Differentiation

- Determine the vertical speed at $t=0.25$...
 - a few options...



Numerical Integration

- Integration: the reversed problem...
- Suppose we travel in a car with a broken odometer
- Speedometer is working...



Numerical Integration

- maintain speeds, to figure out traveled distance

t	v(t) km/h
0	80
30	120
65	128
120	122
728	120
733	0
798	20
836	20
941	70
970	120
1350	123
1404	90

enter highway ramp

traffic jam

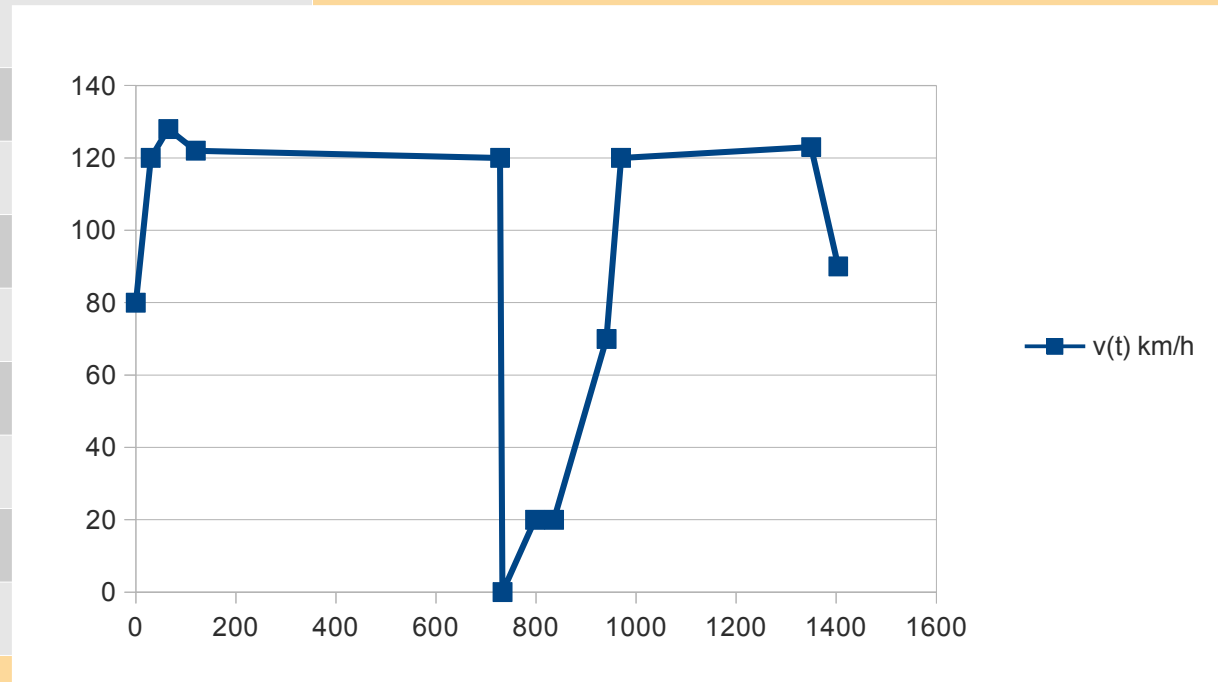
exit highway ramp

Numerical Integration

- maintain speeds, to figure out traveled distance

t	v(t) km/h
0	80
30	120
65	128
120	
728	
733	
798	
836	
941	
970	
1350	
1404	

enter highway ramp

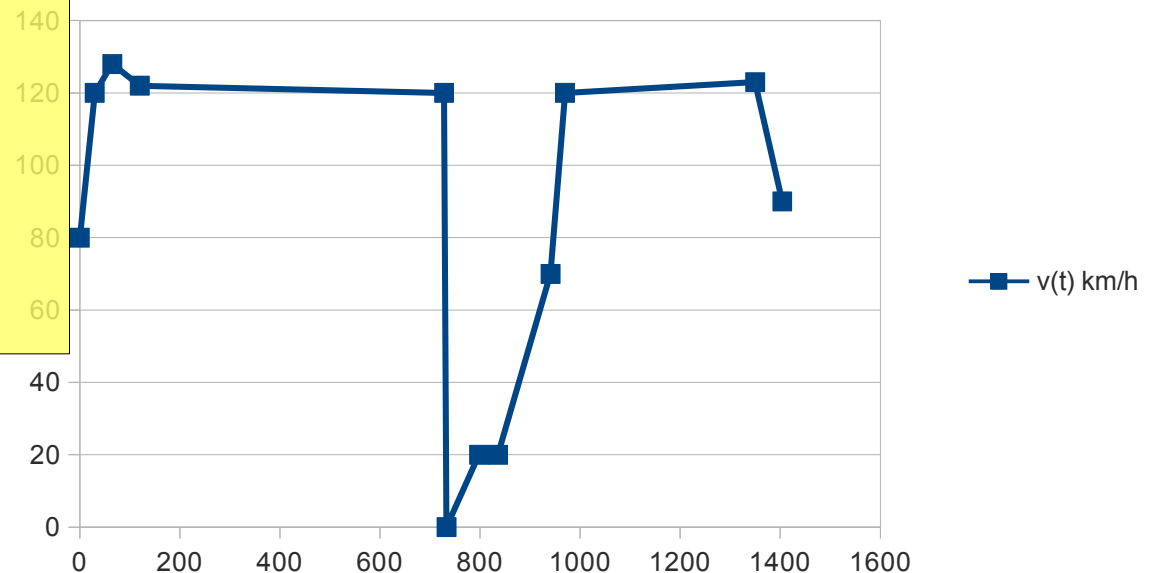


Numerical Integration

- maintain speeds, to figure out traveled distance

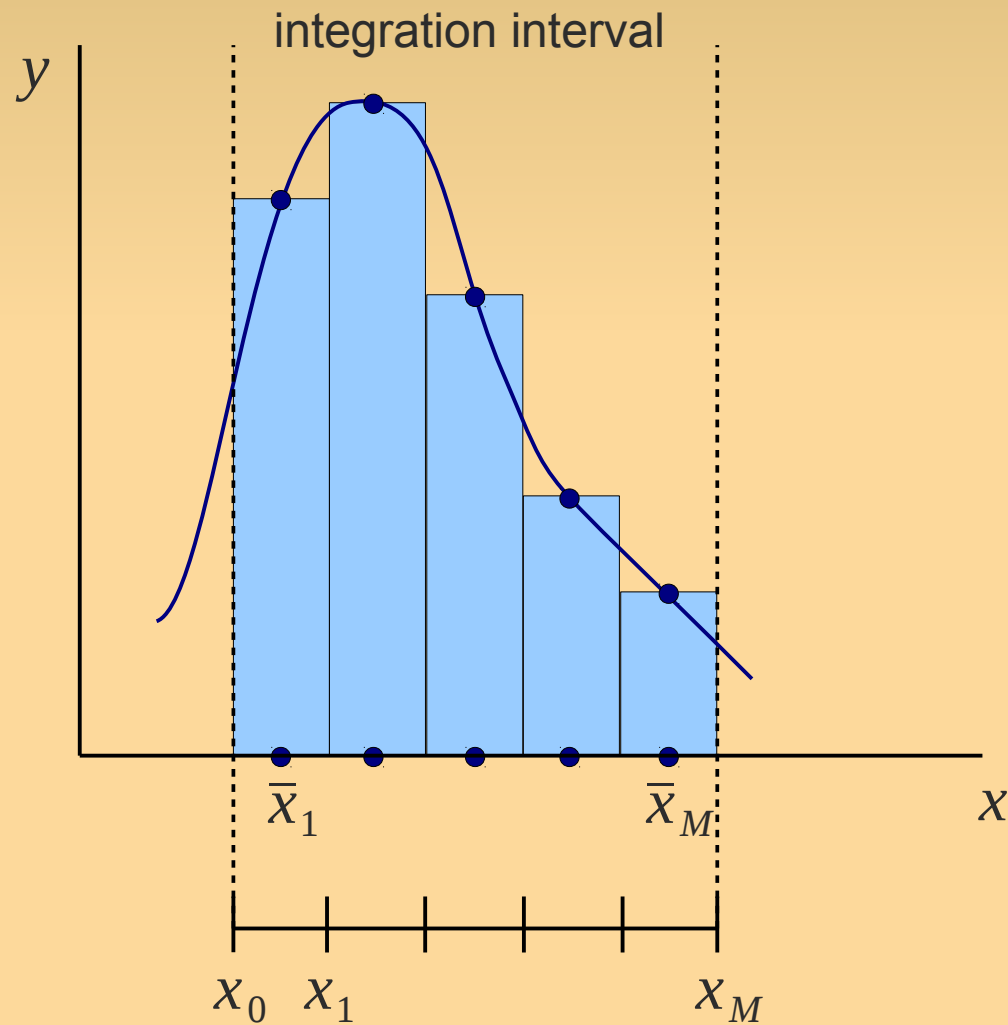
t	v(t) km/h
0	80
30	120
65	128
120	128
733	0
798	20
836	70
941	120
970	120
1350	125
1404	90

How far did we travel?

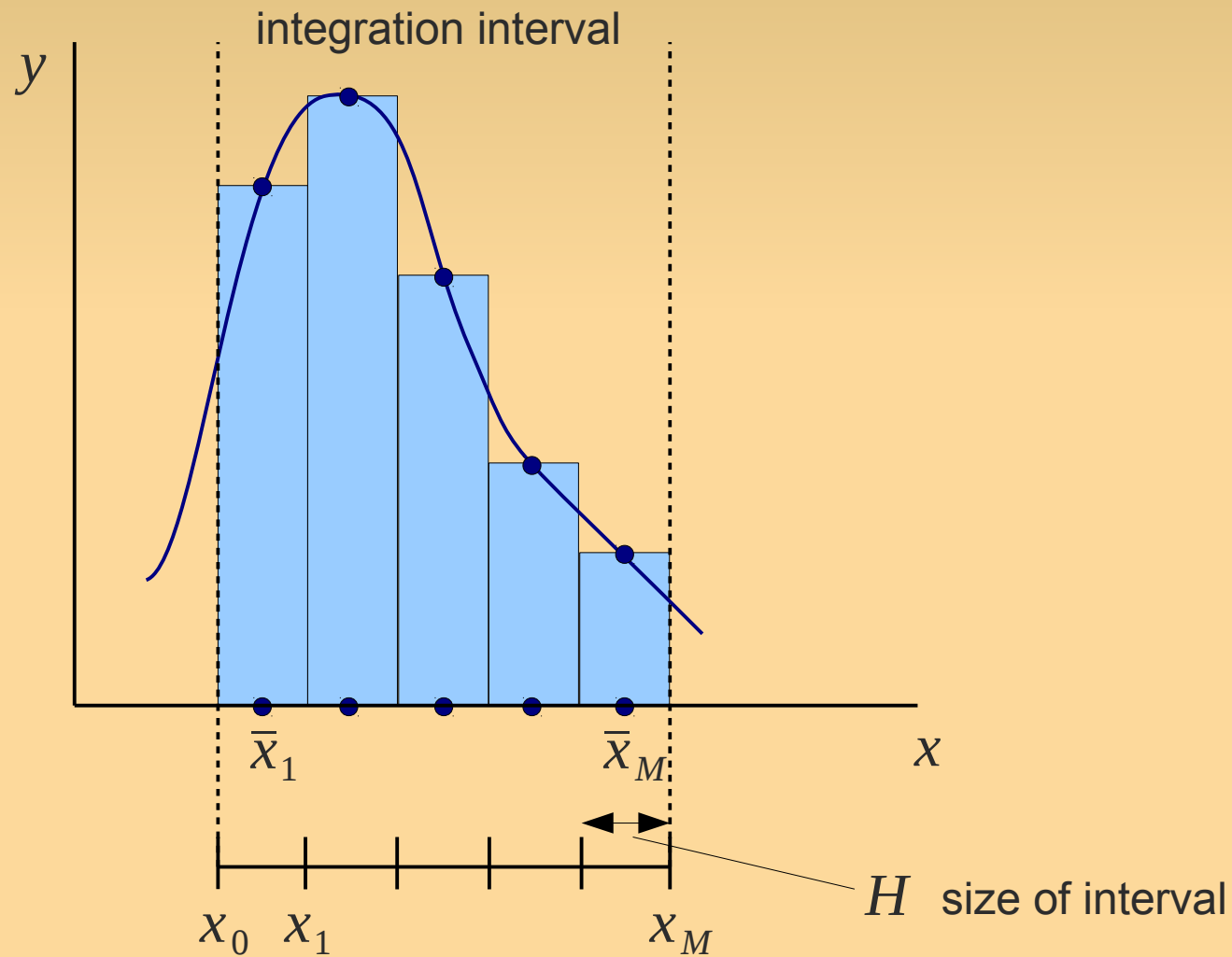


Midpoint Formula

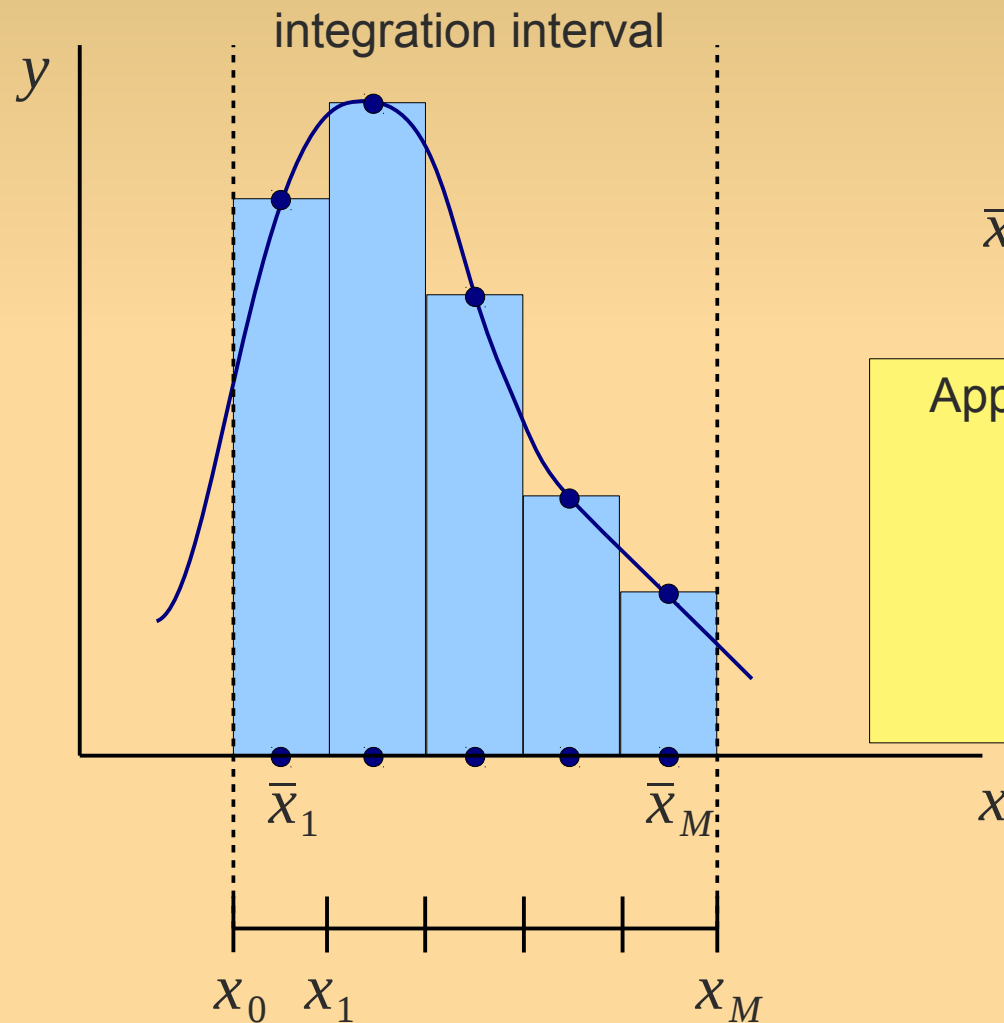
- Approximate the integral with a finite sum



Midpoint Formula



Midpoint Formula

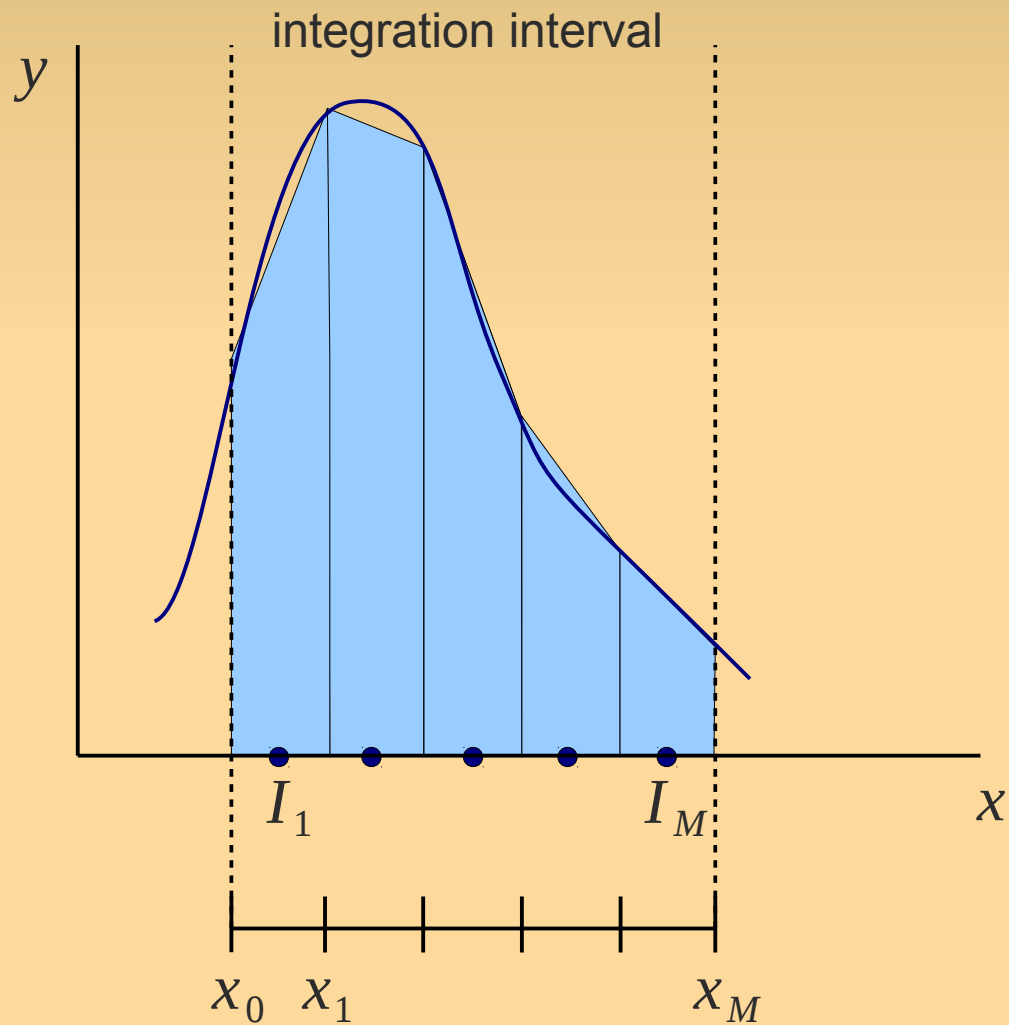


$$\bar{x}_k = \frac{x_{k-1} + x_k}{2}$$

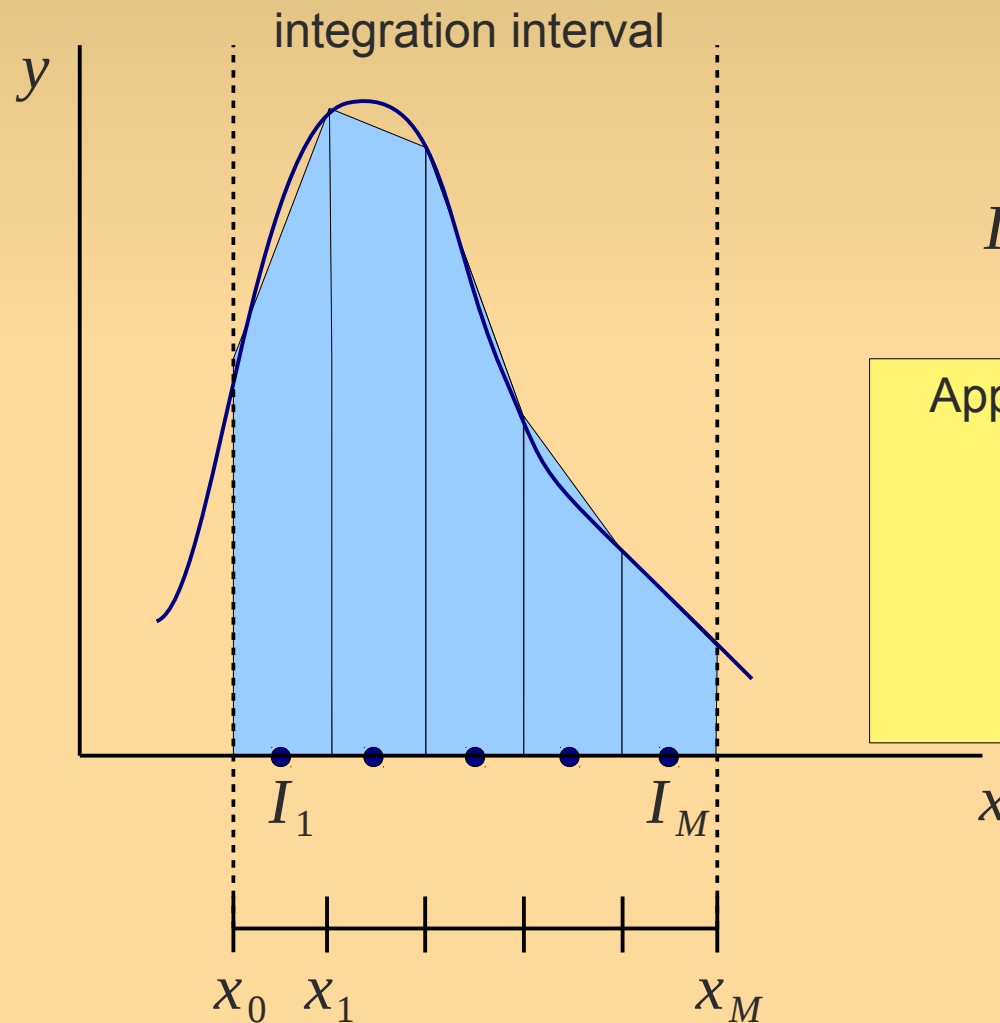
Approximation of the integral:

$$I_{MP}(f) = H \sum_{k=1}^M f(\bar{x}_k)$$

Trapezoid Formula



Trapezoid Formula



$$I_k = H \frac{f(x_{k-1}) + f(x_k)}{2}$$

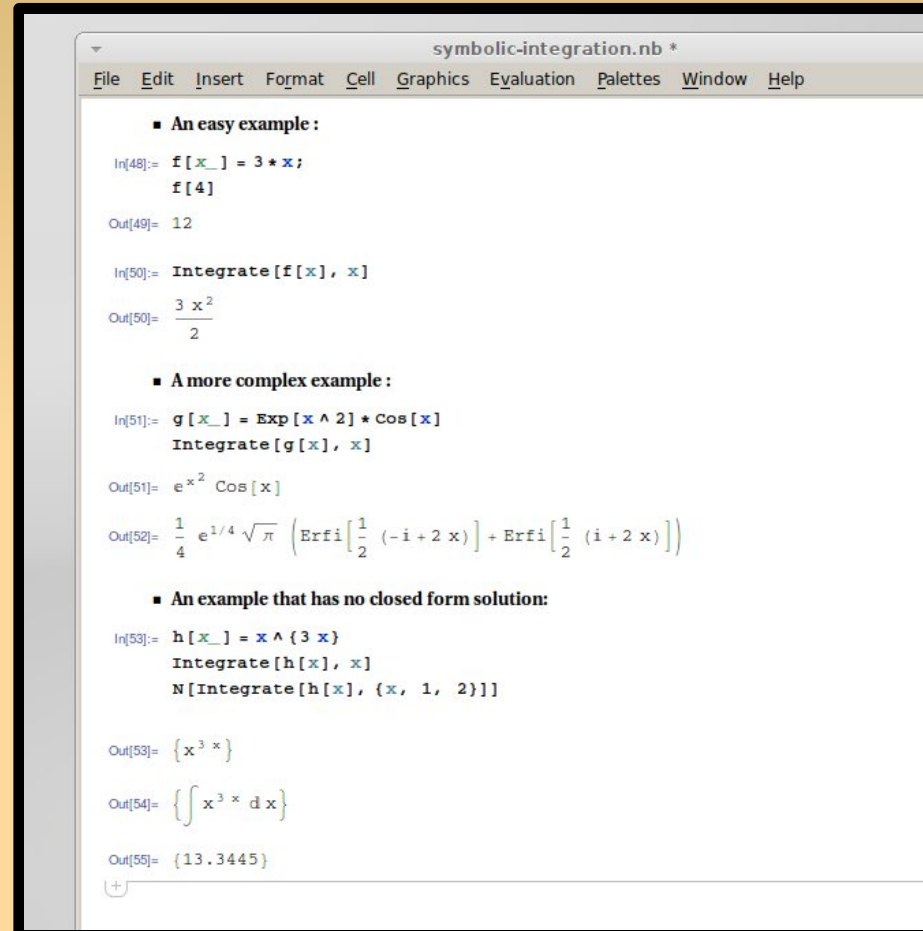
Approximation of the integral:

$$I_{MP}(f) = \sum_{k=1}^M I_k$$

Symbolic Integration

- Finally: when faced with a difficult integral...

→ try 'symbolic' packages!



```
symbolic-integration.nb *
File Edit Insert Format Cell Graphics Evaluation Palettes Window Help

■ An easy example :
In[48]:= f[x_] = 3 * x;
          f[4]
Out[49]= 12

In[50]:= Integrate[f[x], x]
Out[50]=  $\frac{3 x^2}{2}$ 

■ A more complex example :
In[51]:= g[x_] = Exp[x ^ 2] * Cos[x]
          Integrate[g[x], x]
Out[51]=  $e^{x^2} \text{Cos}[x]$ 
Out[52]=  $\frac{1}{4} e^{1/4} \sqrt{\pi} \left( \text{Erfi}\left[\frac{1}{2} (-i + 2 x)\right] + \text{Erfi}\left[\frac{1}{2} (i + 2 x)\right] \right)$ 

■ An example that has no closed form solution:
In[53]:= h[x_] = x ^ {3 x}
          Integrate[h[x], x]
          N[Integrate[h[x], {x, 1, 2}]]

Out[53]= {x3 x}
Out[54]= {∫ x3 x dx}
Out[55]= {13.3445}
```

- An easy example :

```
In[48]:= f[x_] = 3 * x;
         f[4]
```

```
Out[49]= 12
```

```
In[50]:= Integrate[f[x], x]
```

```
Out[50]=  $\frac{3 x^2}{2}$ 
```

- A more complex example :

```
In[51]:= g[x_] = Exp[x ^ 2] * Cos[x]
         Integrate[g[x], x]
```

```
Out[51]=  $e^{x^2} \cos[x]$ 
```

```
Out[52]=  $\frac{1}{4} e^{1/4} \sqrt{\pi} \left( \operatorname{Erfi}\left[\frac{1}{2}(-i + 2x)\right] + \operatorname{Erfi}\left[\frac{1}{2}(i + 2x)\right] \right)$ 
```

- An example that has no closed form solution:

```
In[53]:= h[x_] = x ^ {3 x}
         Integrate[h[x], x]
         N[Integrate[h[x], {x, 1, 2}]]
```

```
Out[53]= { $x^{3 x}$ }
```

```
Out[54]= { $\int x^{3 x} dx$ }
```

```
Out[55]= {13.3445}
```