

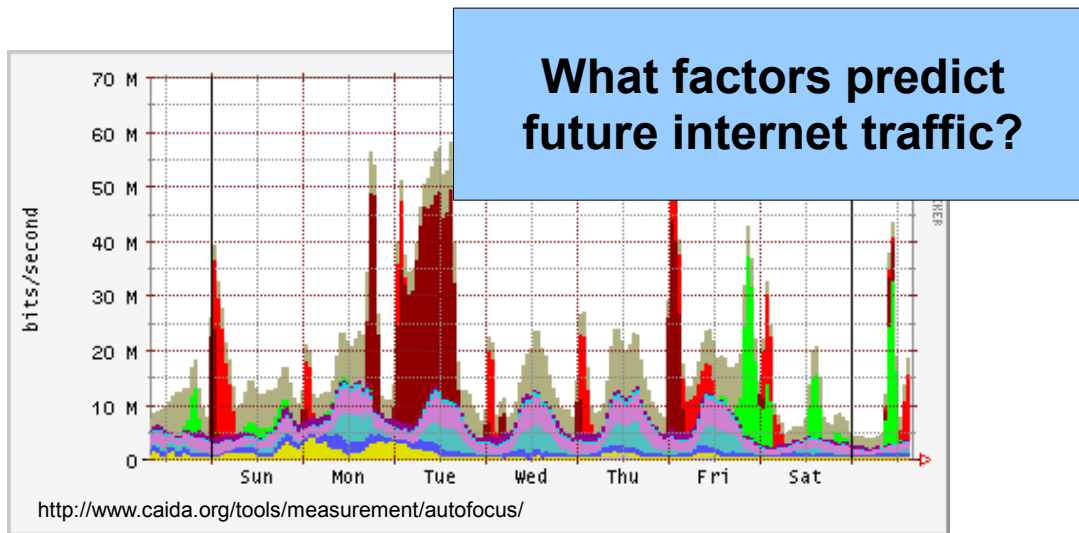
# Infinite Dynamic Bayesian Networks

Finale Doshi-Velez  
David Wingate  
Joshua Tenenbaum  
Nicholas Roy

ICML 2011

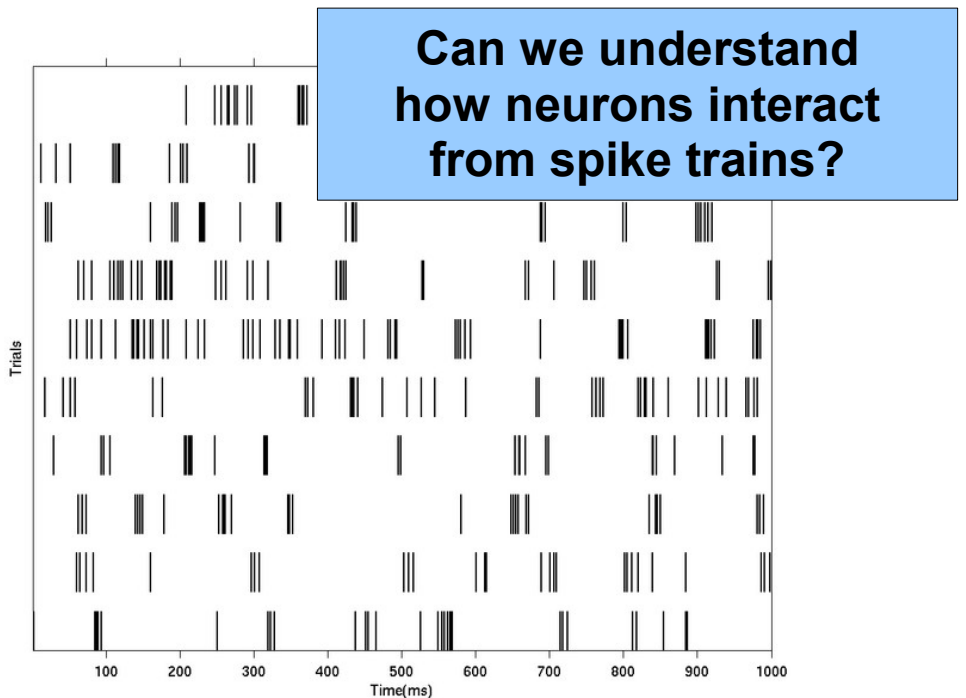
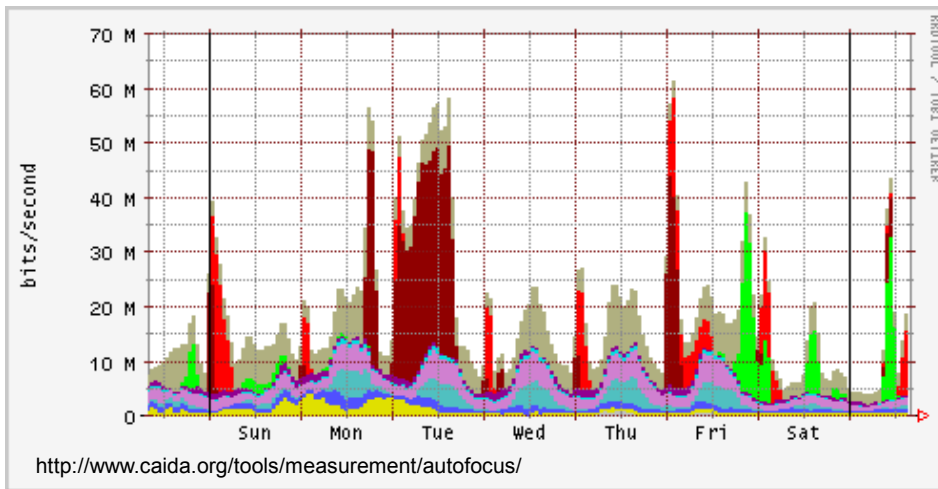
# Learning Time-Series Models

Time series data often has complex structure we wish to understand...



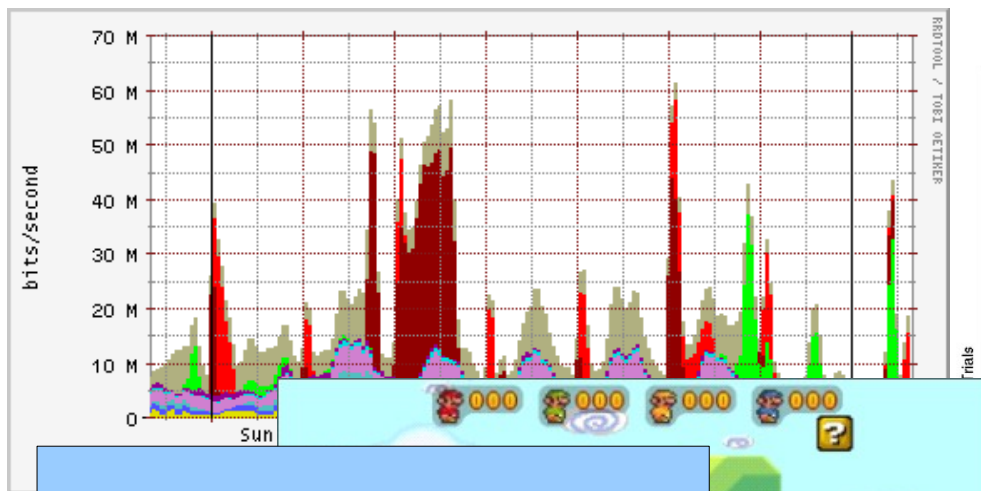
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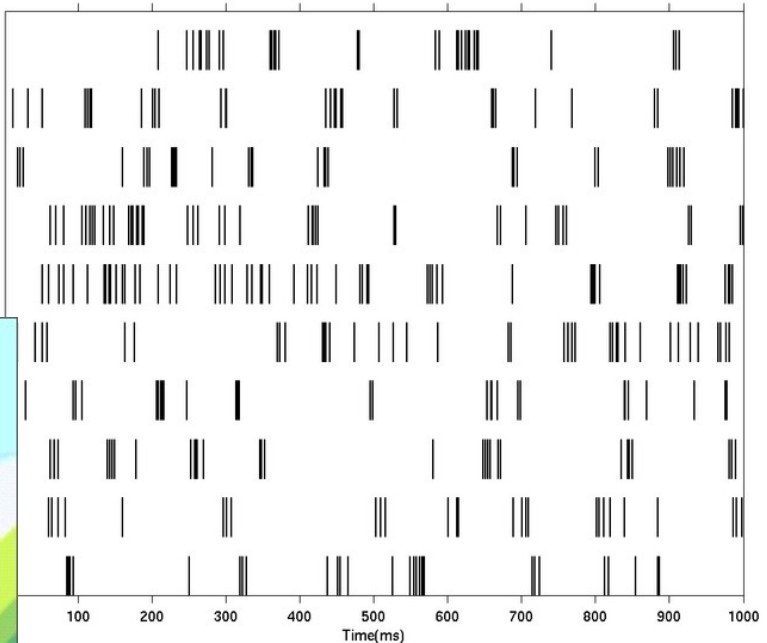


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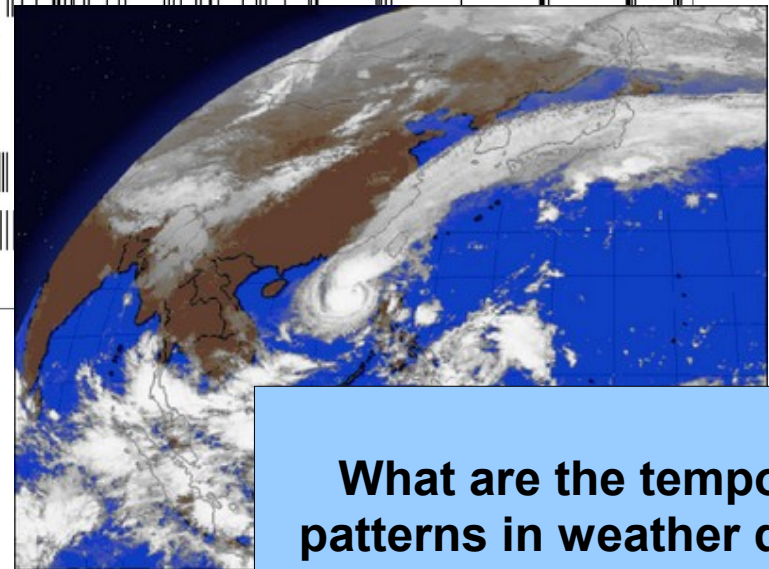
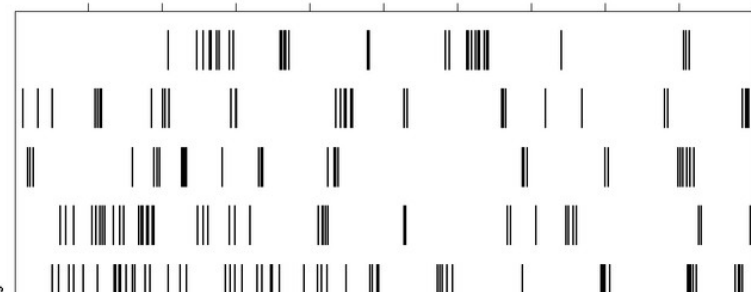
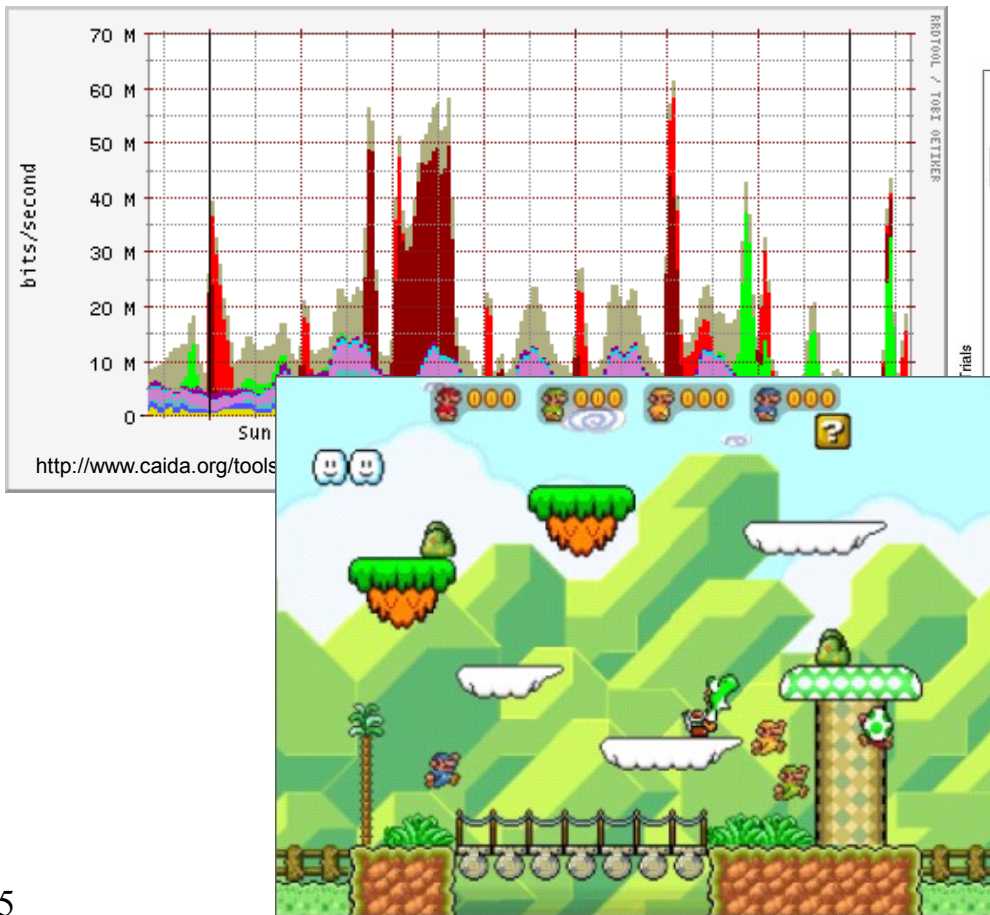


**Are there simple models to explain what happens when sprites interact?**



# Learning Time-Series Models

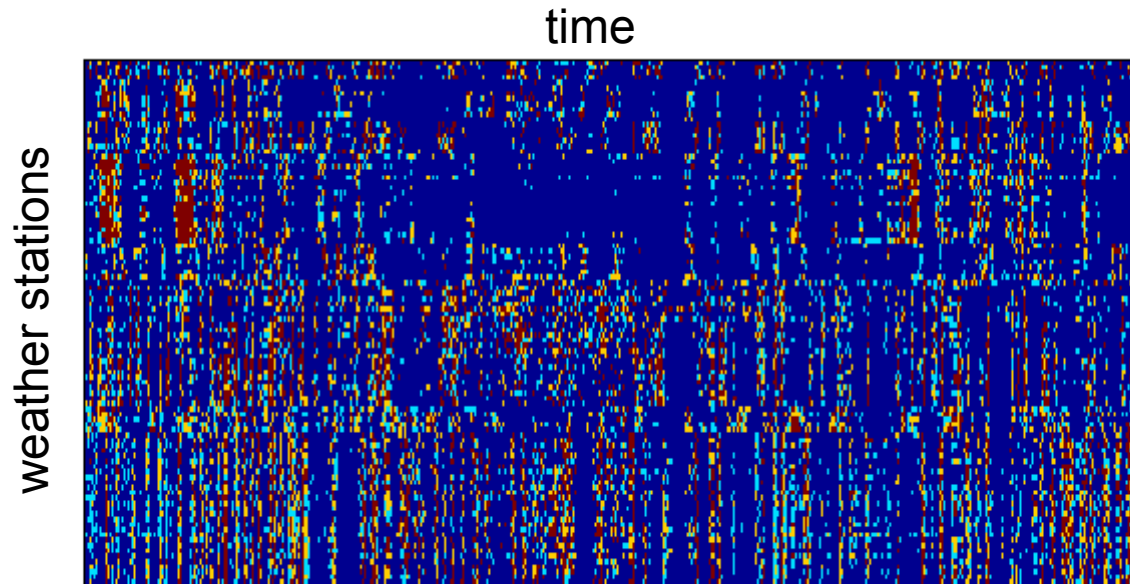
Time series data often has complex structure we wish to understand...



**What are the temporal patterns in weather data?**

# Example: Rainfall Data

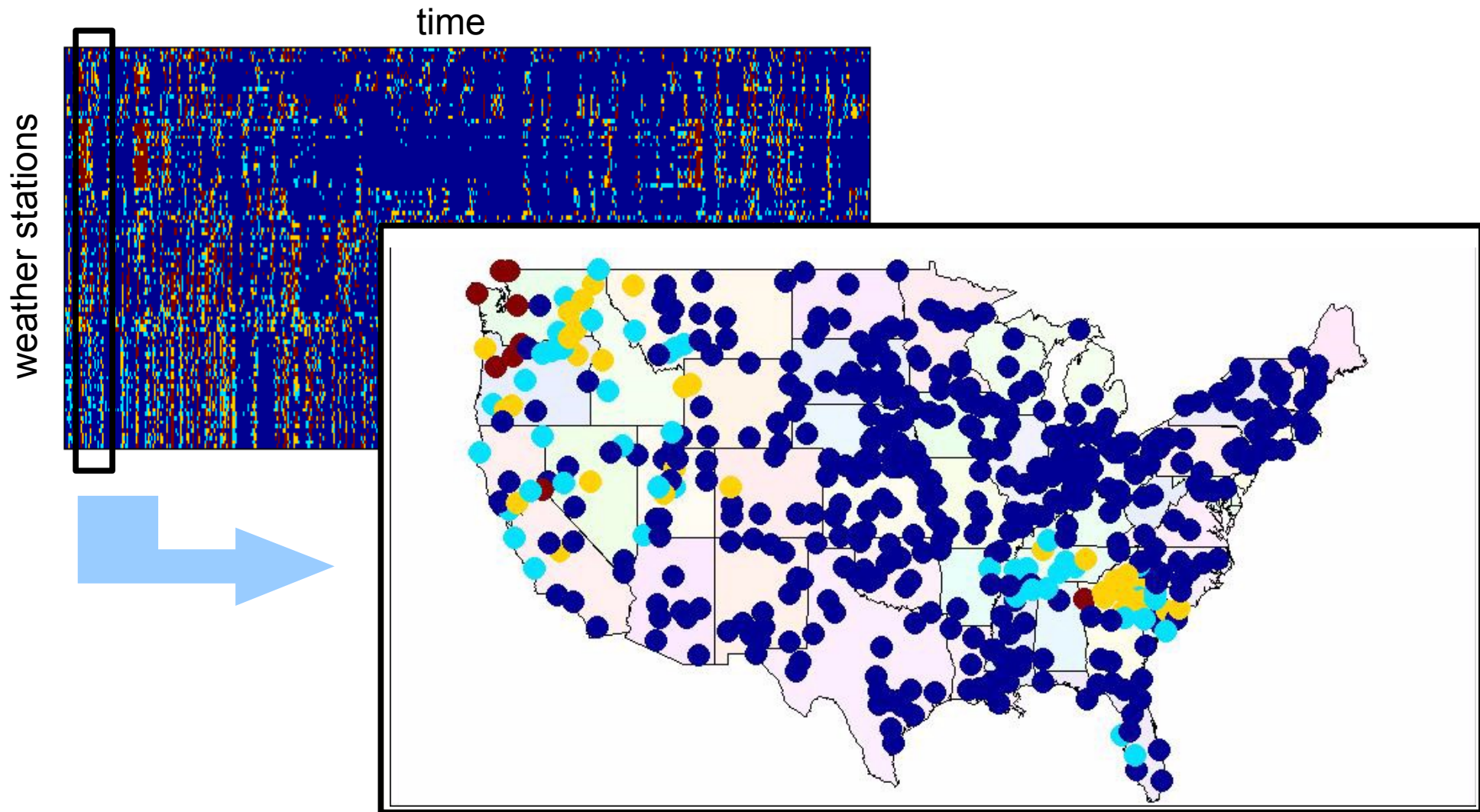
But finding that structure isn't always obvious...





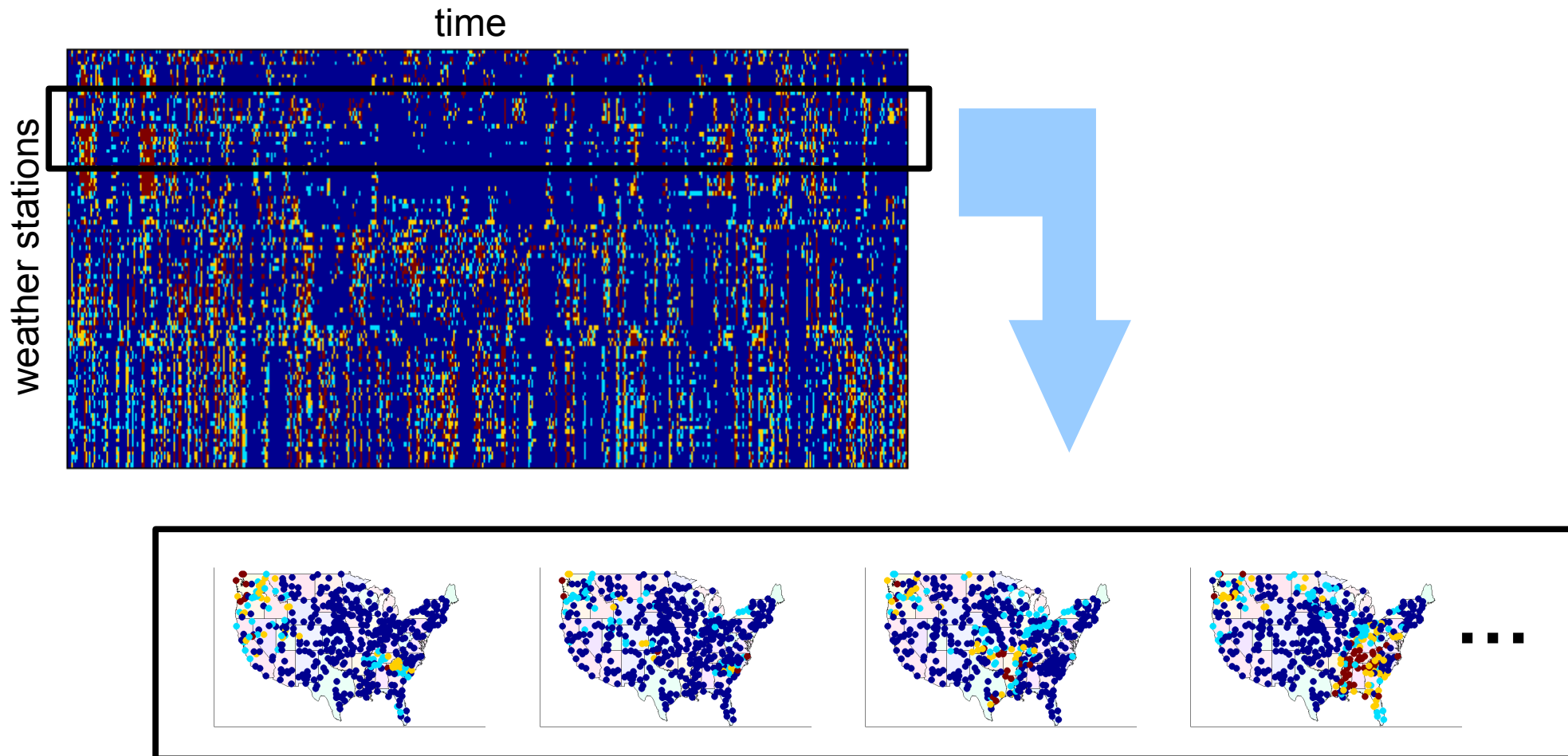
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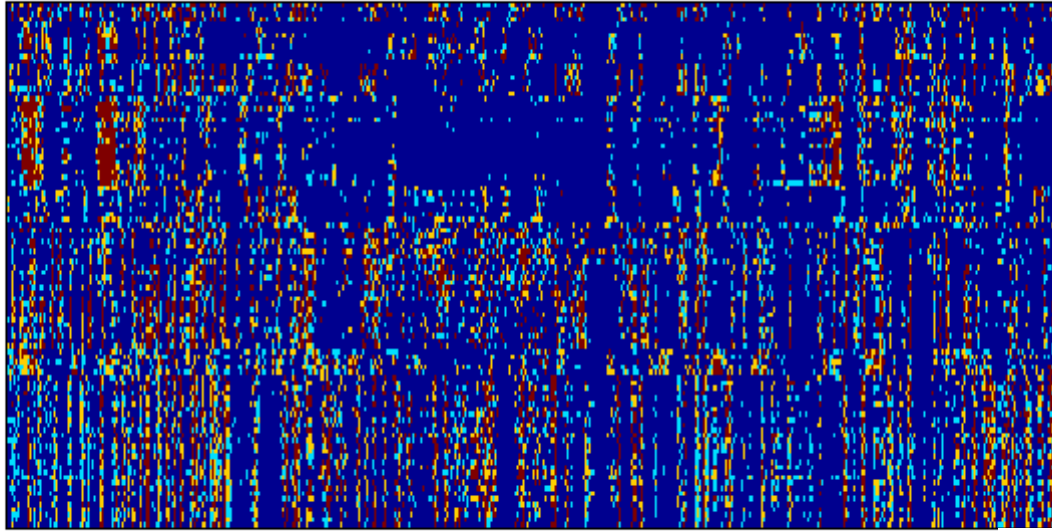




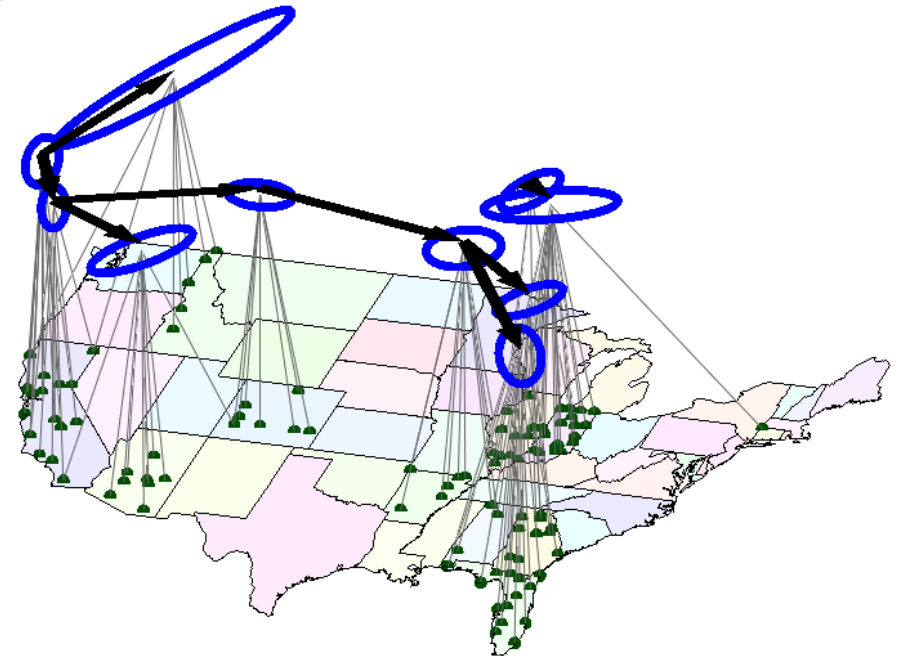
# Example: Rainfall Data

time

weather stations



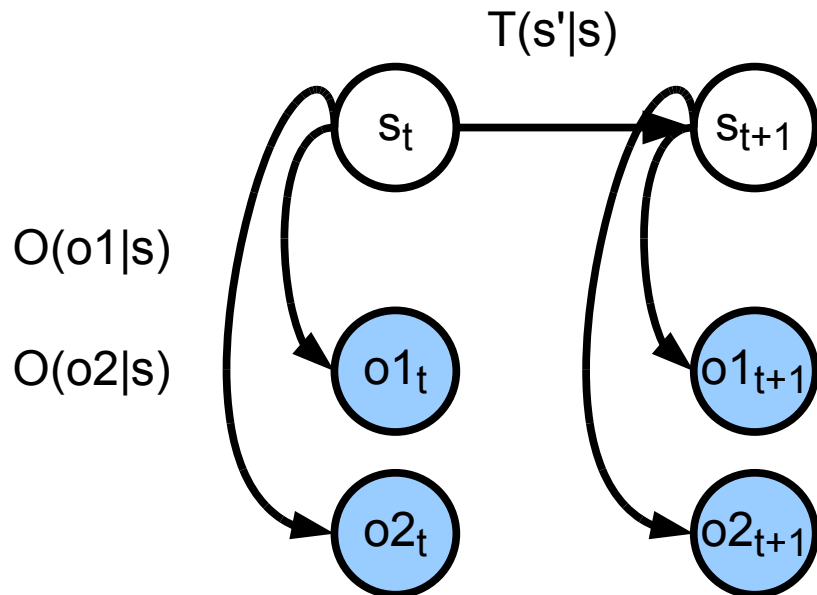
How can we go from  
**no structural information**  
to **discovering**  
**causal patterns?**



# Current Approaches

There are several ways we might try to encode the structure:

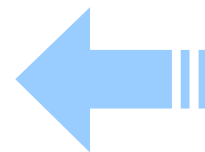
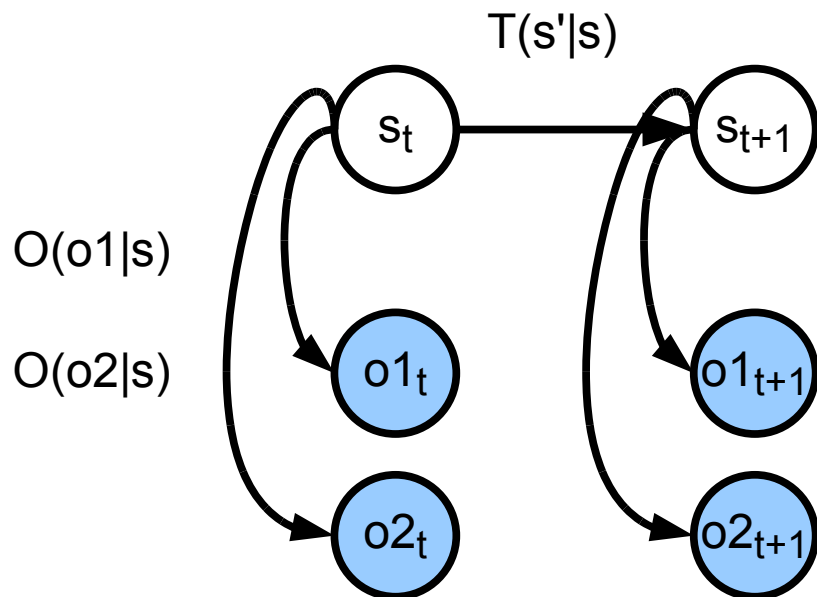
- Hidden Markov Models (HMMs): one latent factor



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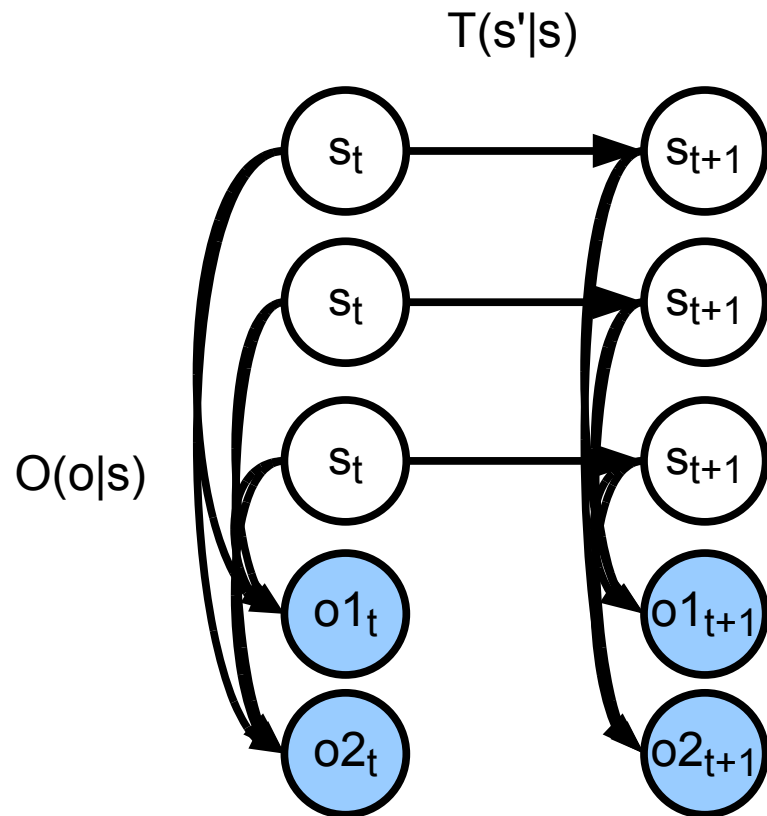


Infinite HMMs  
(Beal et al., 2002)  
infer number of  
visited states

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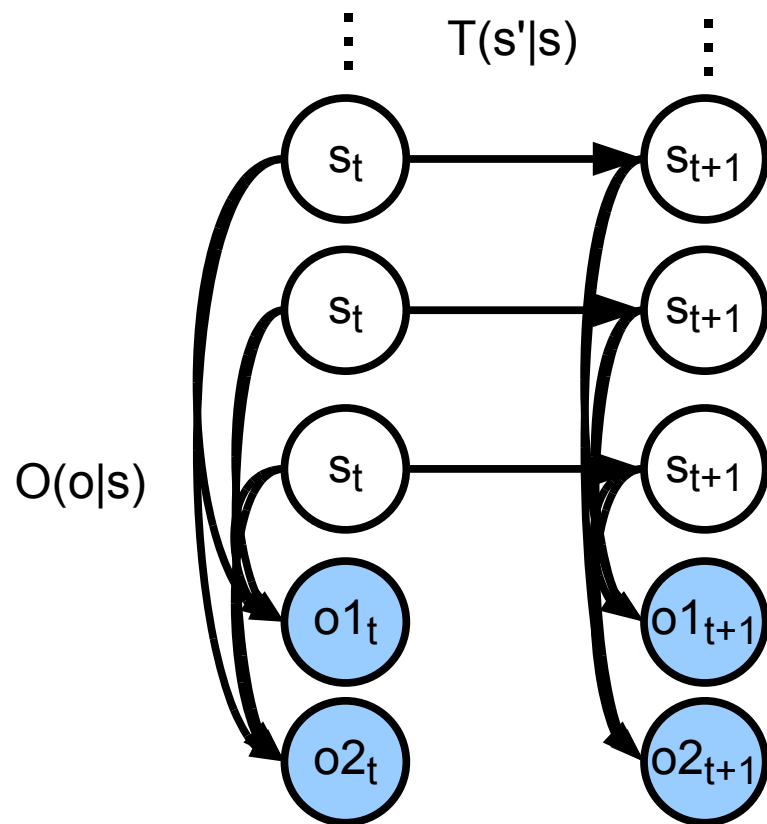
- Hidden Markov Models (HMMs): one latent factor
- Factorial HMMs: many latent factors, special structure



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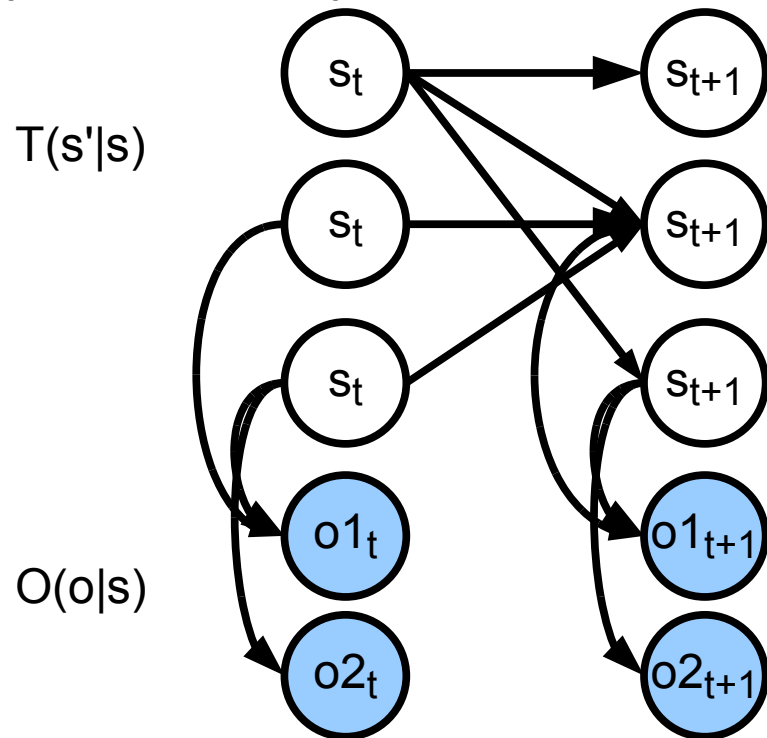


Infinite Factorial  
HMMs (Van Gael  
et al., 2002)  
infer number of  
used factors

# Current Approaches

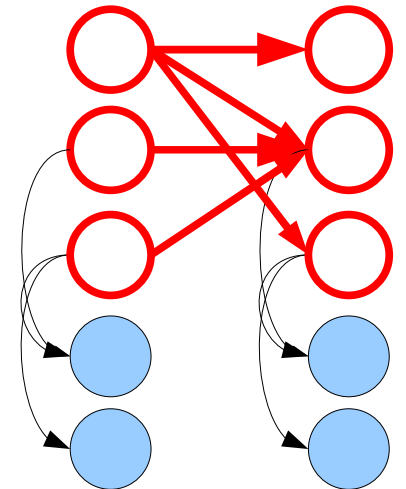
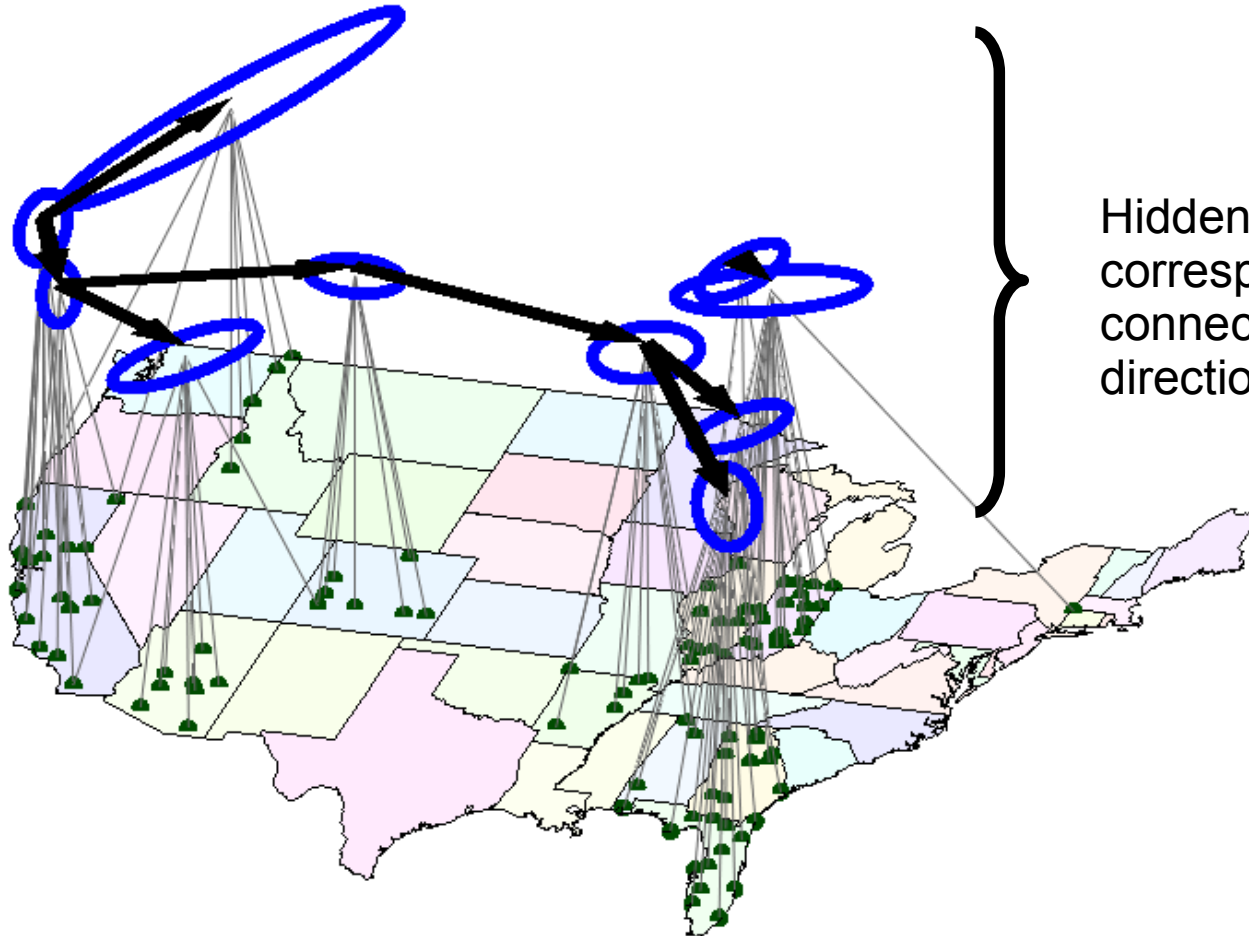
There are several ways we might try to encode the structure:

- Hidden Markov Models (HMMs): one latent factor
- Factorial HMMs: many latent factors, special structure
- Dynamic Bayes Nets: many factors, general structure

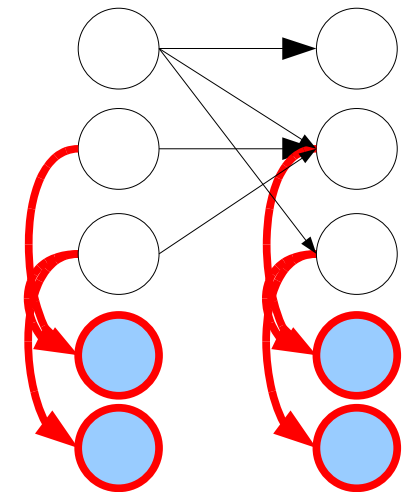
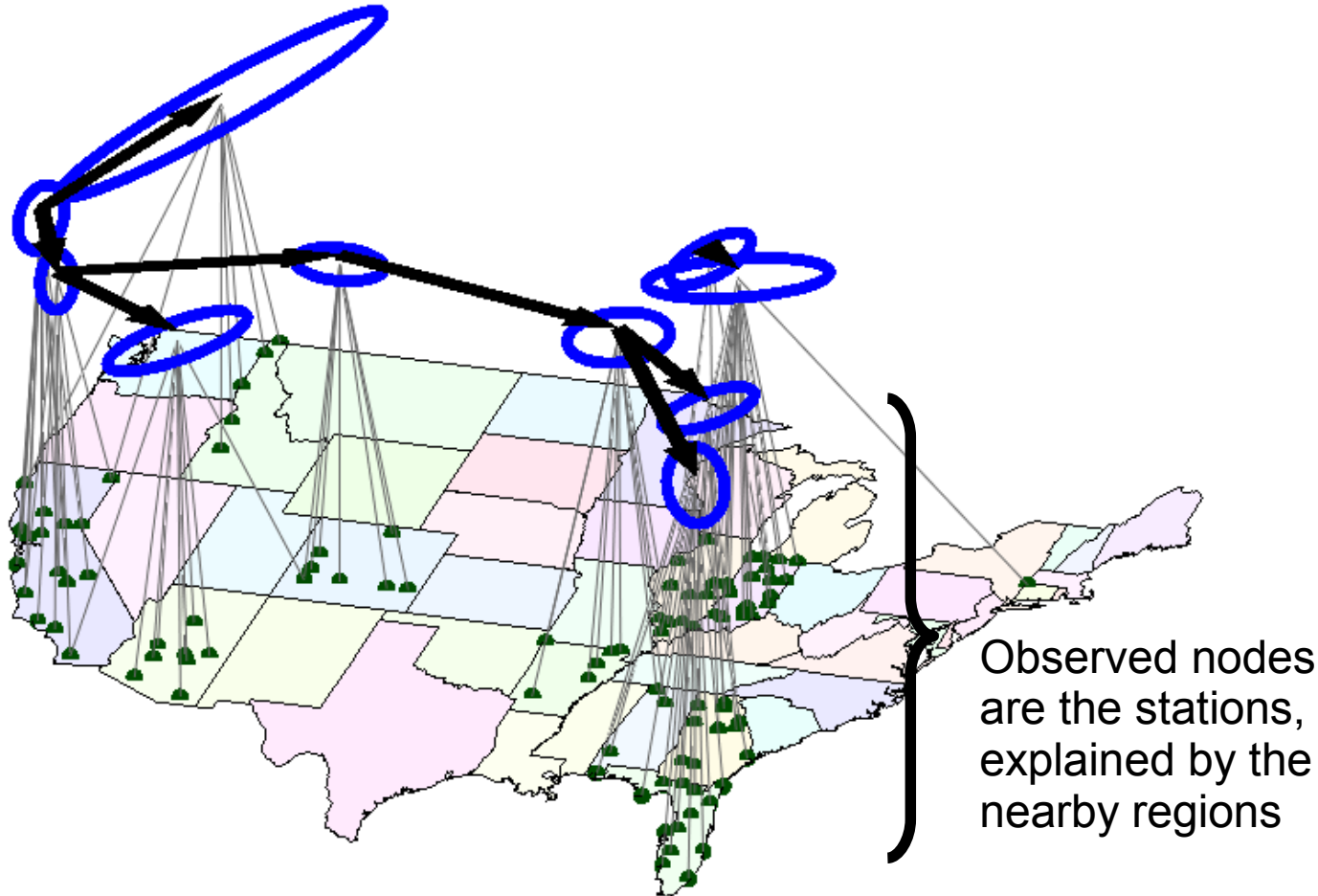




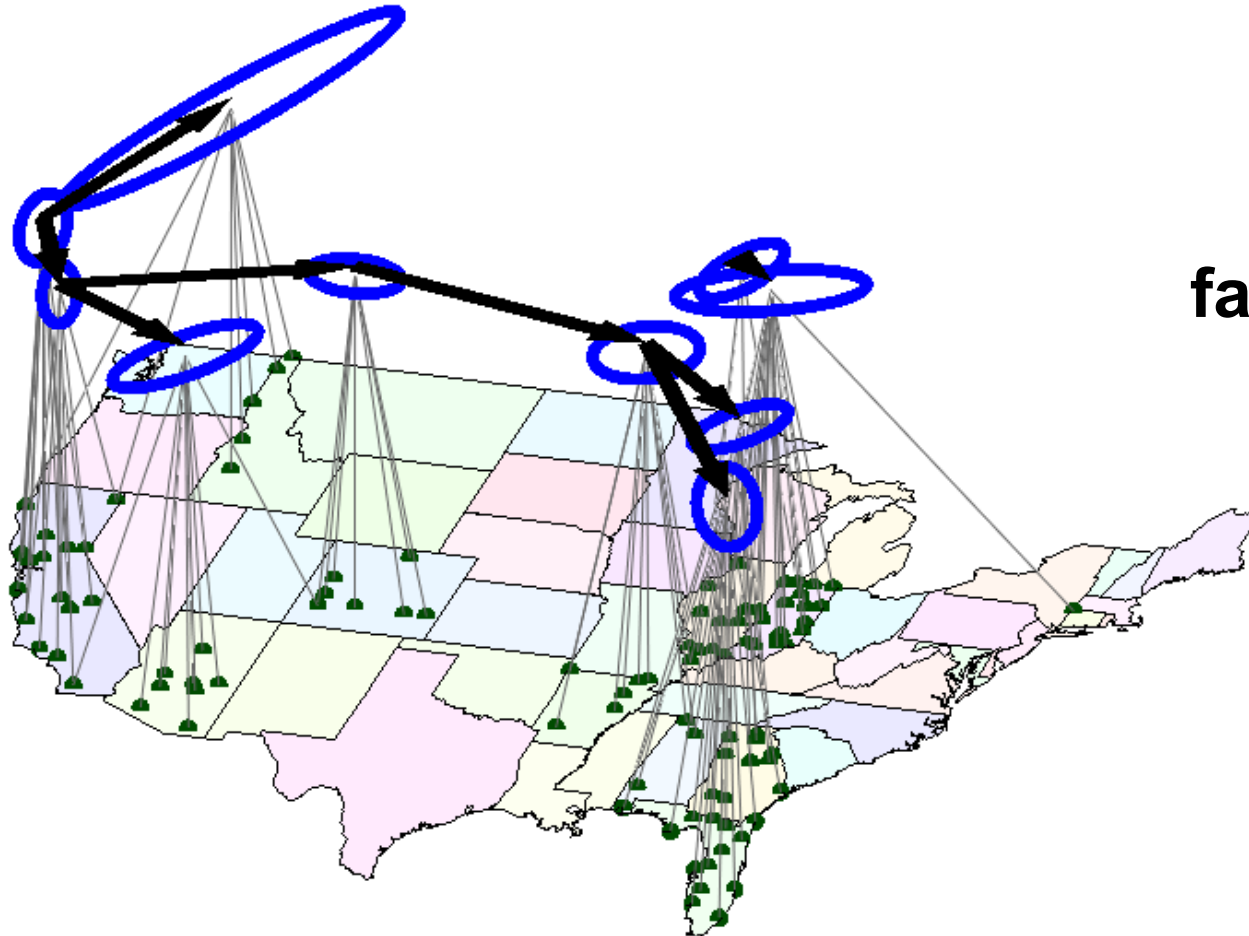
# Example: Rainfall Data



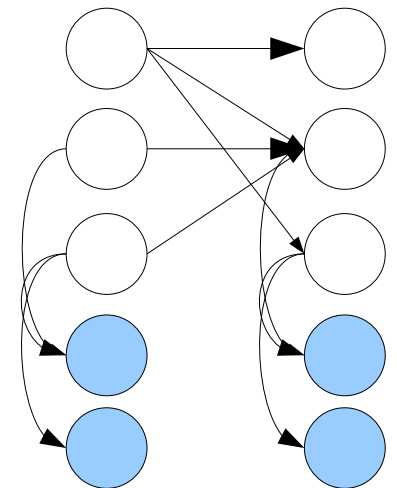
# Example: Rainfall Data



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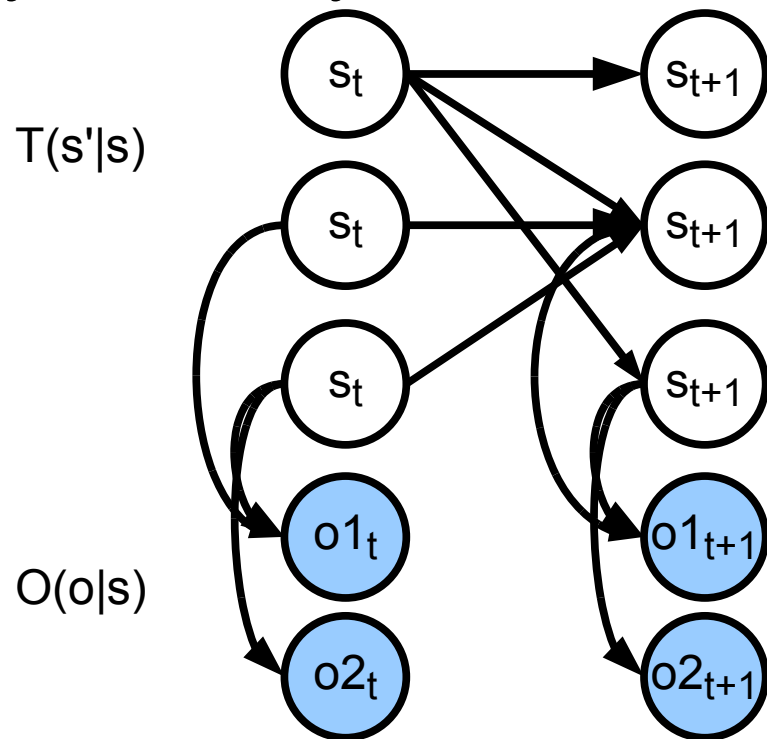
**Key Question:**  
how many  
factors do we need?



# Current Approaches

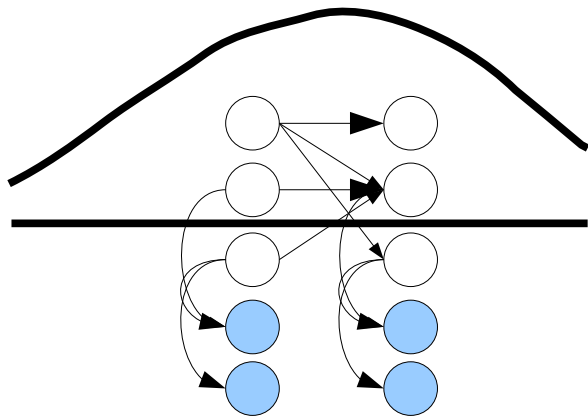
There are several ways we might try to encode the structure:

- Hidden Markov Models (HMMs): one latent factor
- Factorial HMMs: many latent factors, special structure
- Dynamic Bayes Nets: many factors, general structure

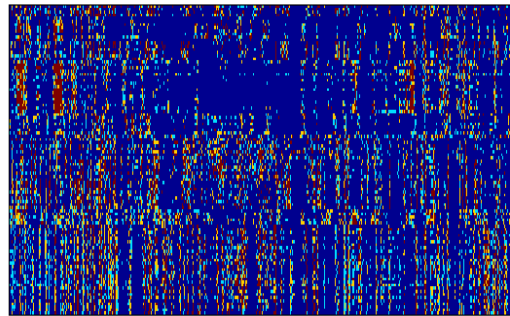


**Our contribution:**  
Infinite DBNs to  
infer number of used  
factors for a general  
DBN structure

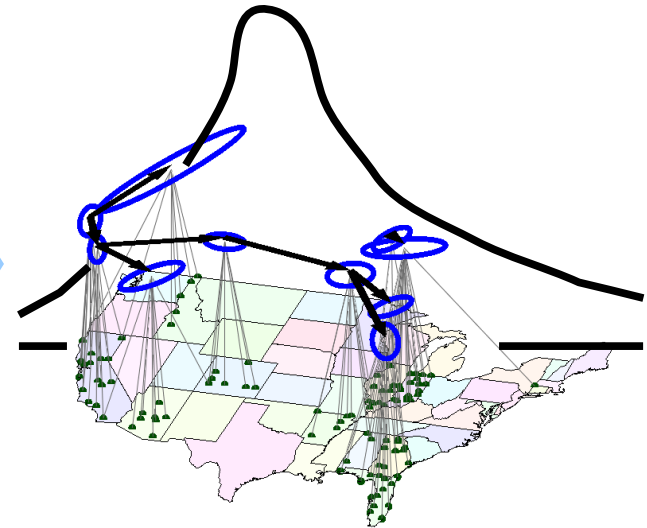
# Using Nonparametric Bayes: Distributions over Infinite DBNs



Infinite DBN prior over  
DBNs with an **infinite**  
**number of factors**

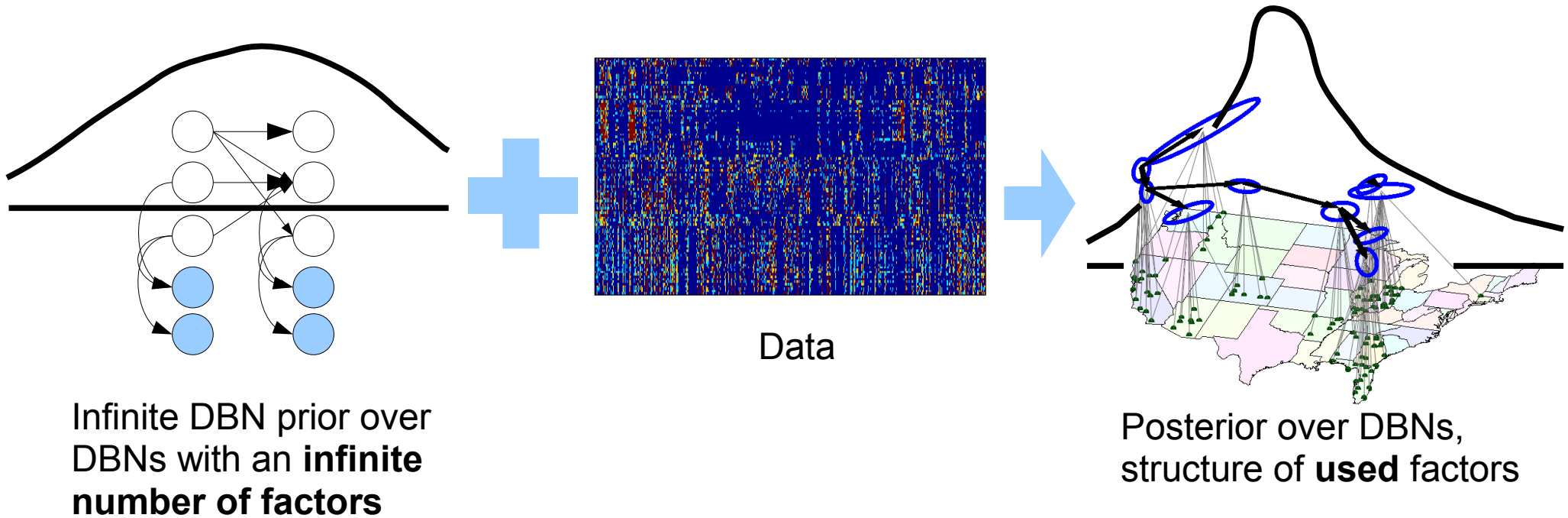


Data



Posterior over DBNs,  
structure of **used** factors

# Using Nonparametric Bayes: Distributions over Infinite DBNs



Infer:

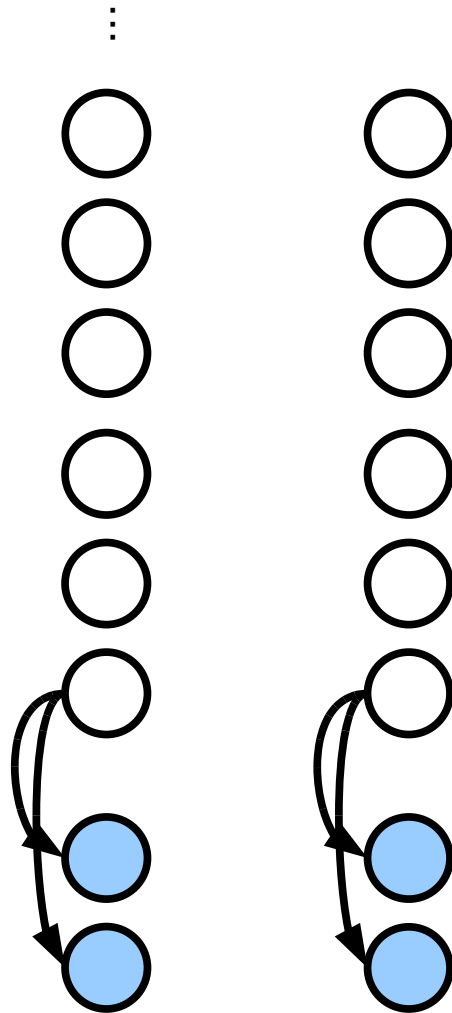
- Number of latent factors used
- State of each factor at each time
- Causal structure for transitions and emissions

Parameters adjust bias towards fewer factors/more states or more factors/fewer states.



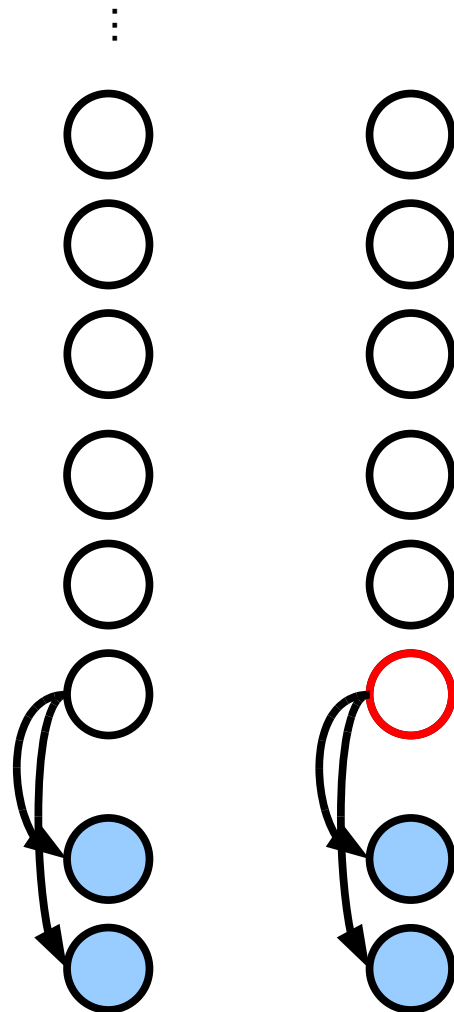
# Why this is tricky...

A finite amount of data must be explained by a finite number of parameters – easy to run into trouble!



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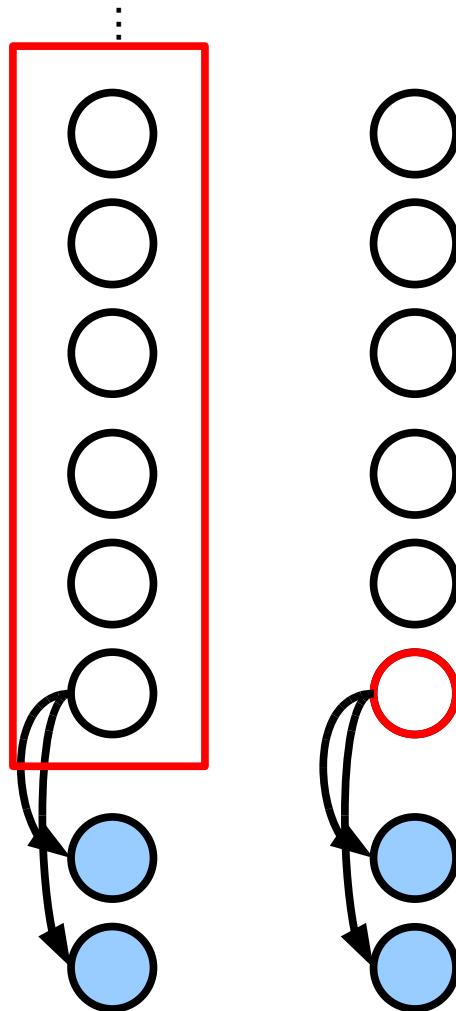


Suppose the apriori probability of a factor choosing being a parent of factor  $k$  was  $p_k$

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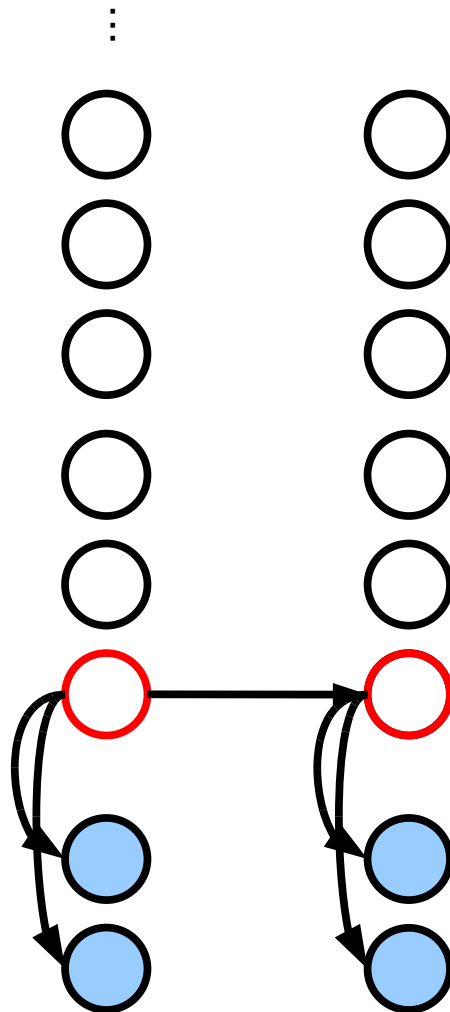
Then the generative process would choose child  $k$  with  $p_k$



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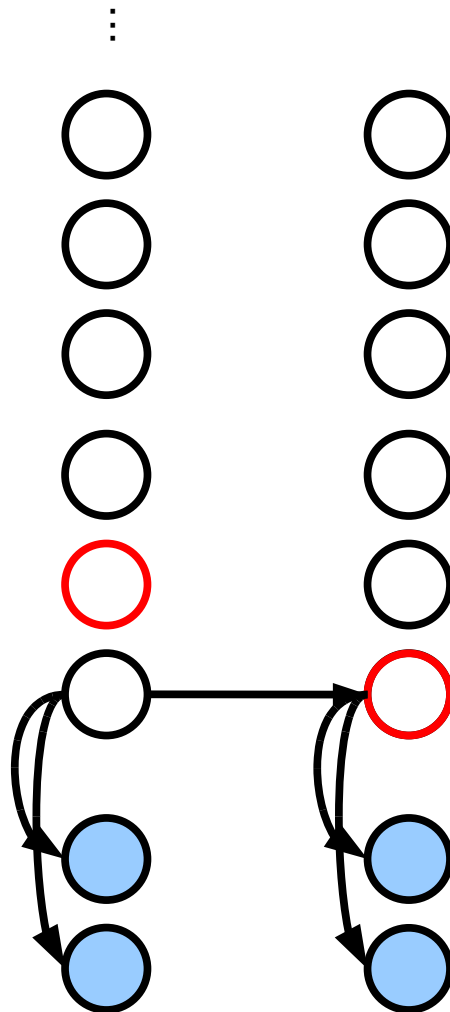
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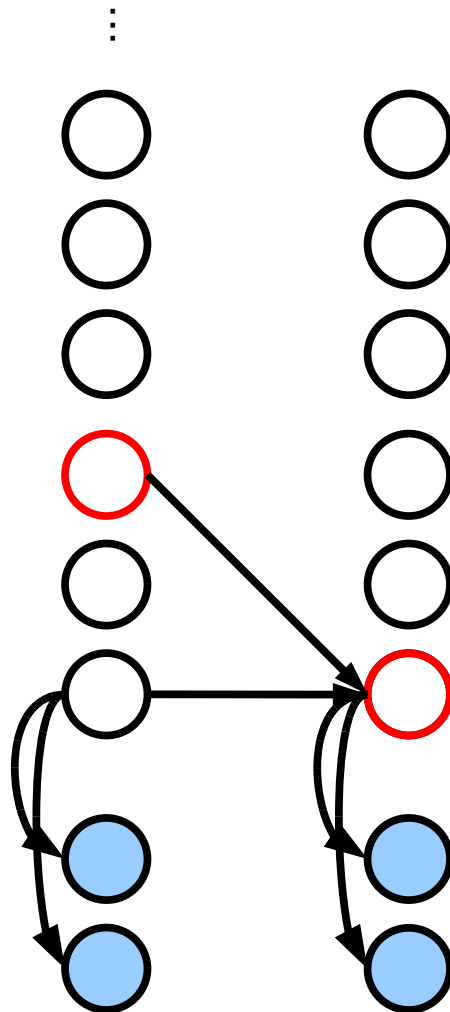
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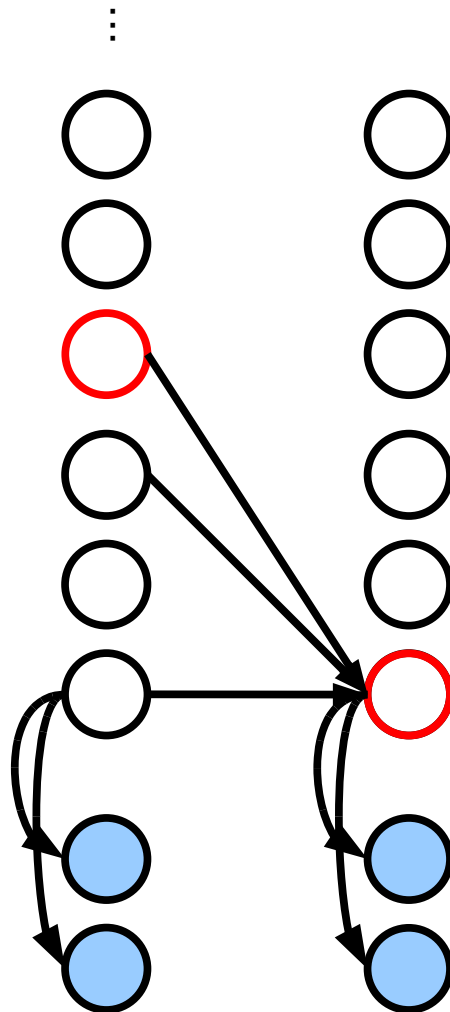




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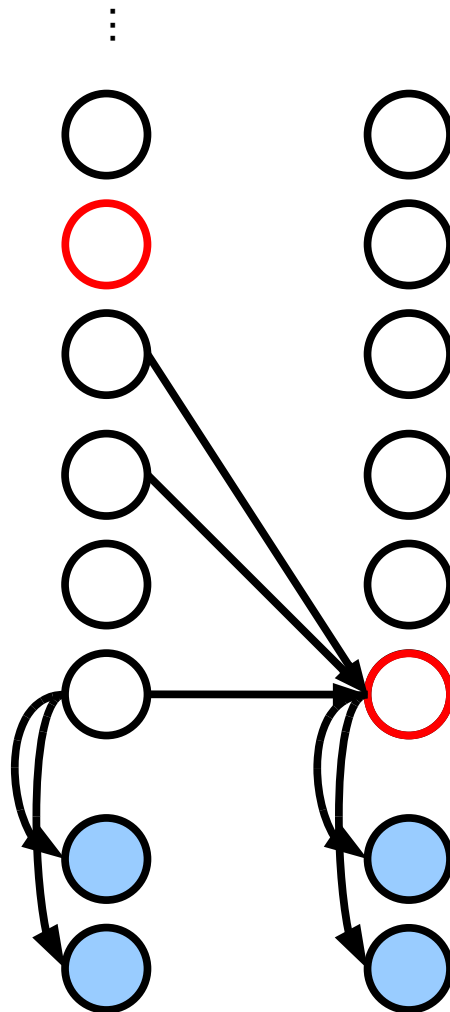
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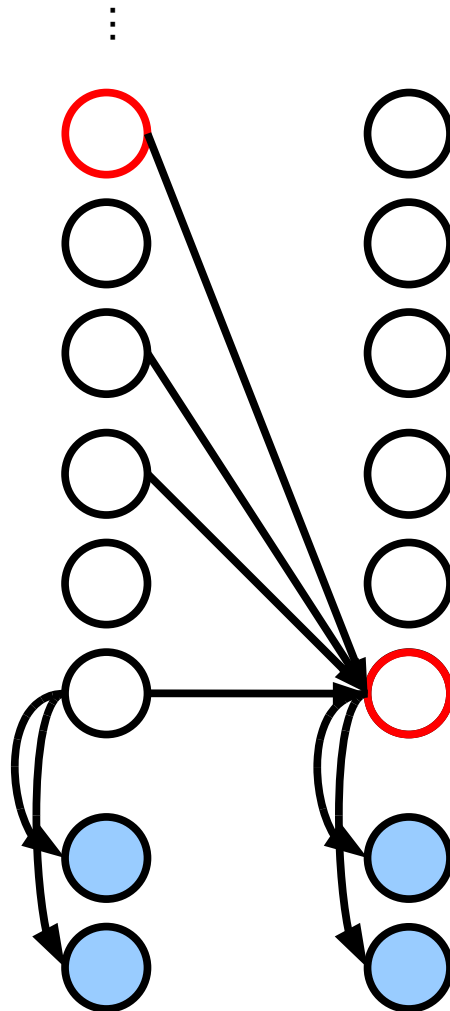
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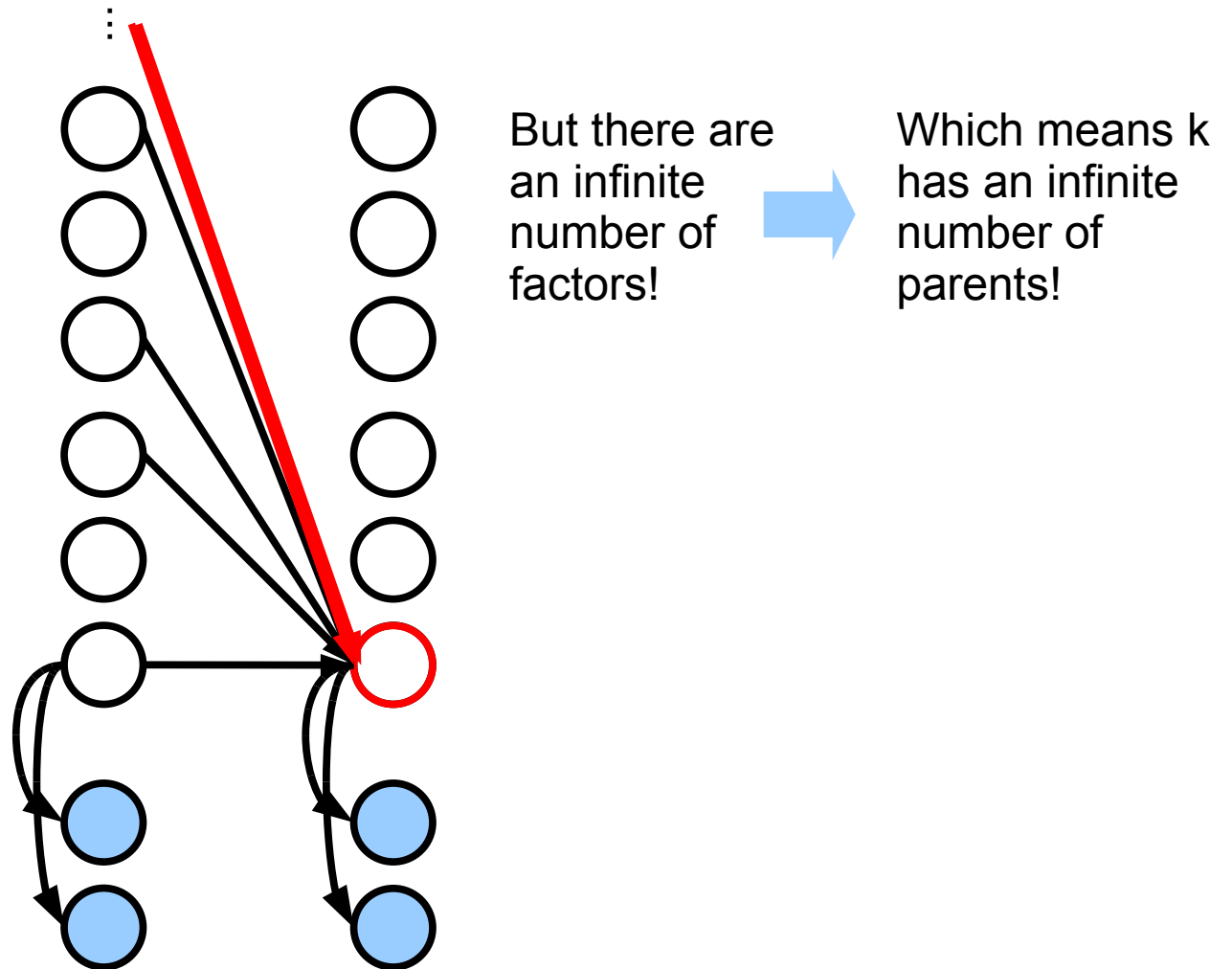
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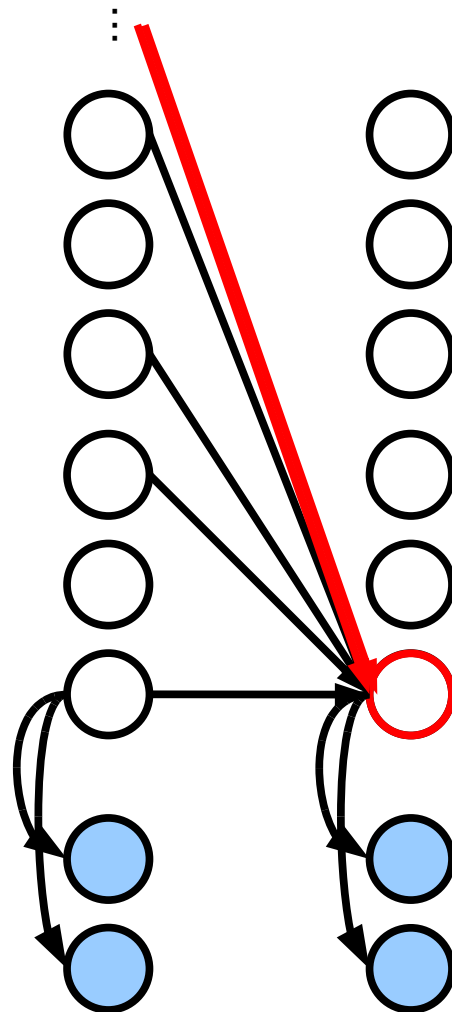
# Why this is tricky...

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But there are an infinite number of factors!

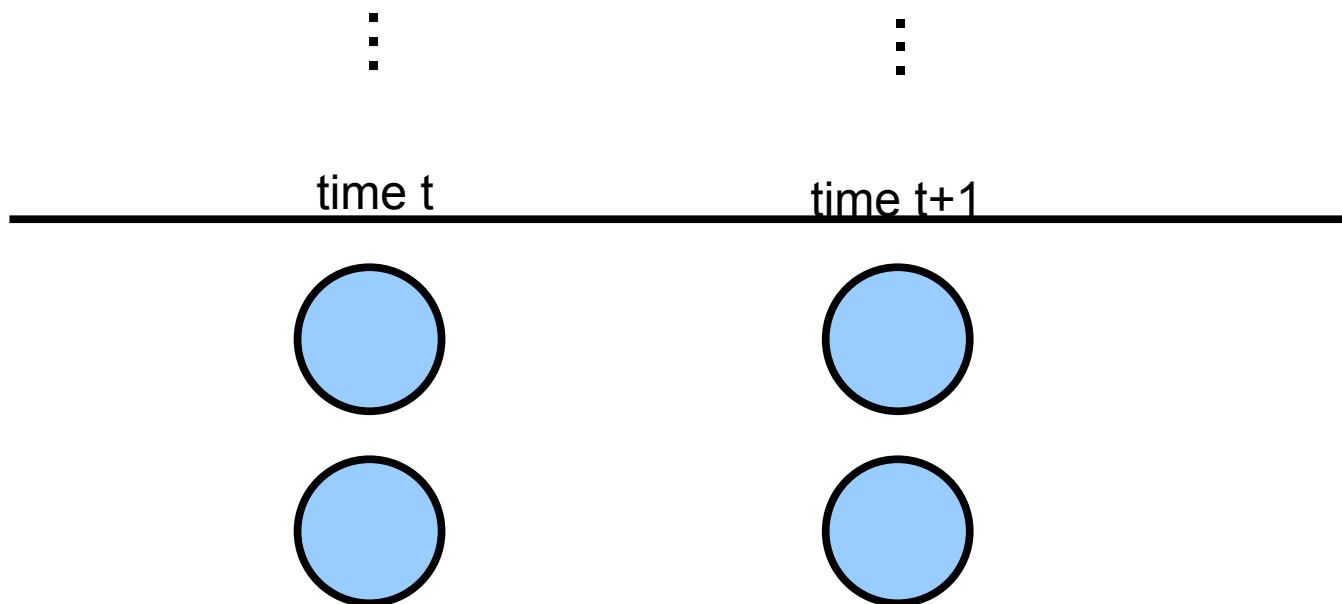


Which means  $k$  has an infinite number of parents!

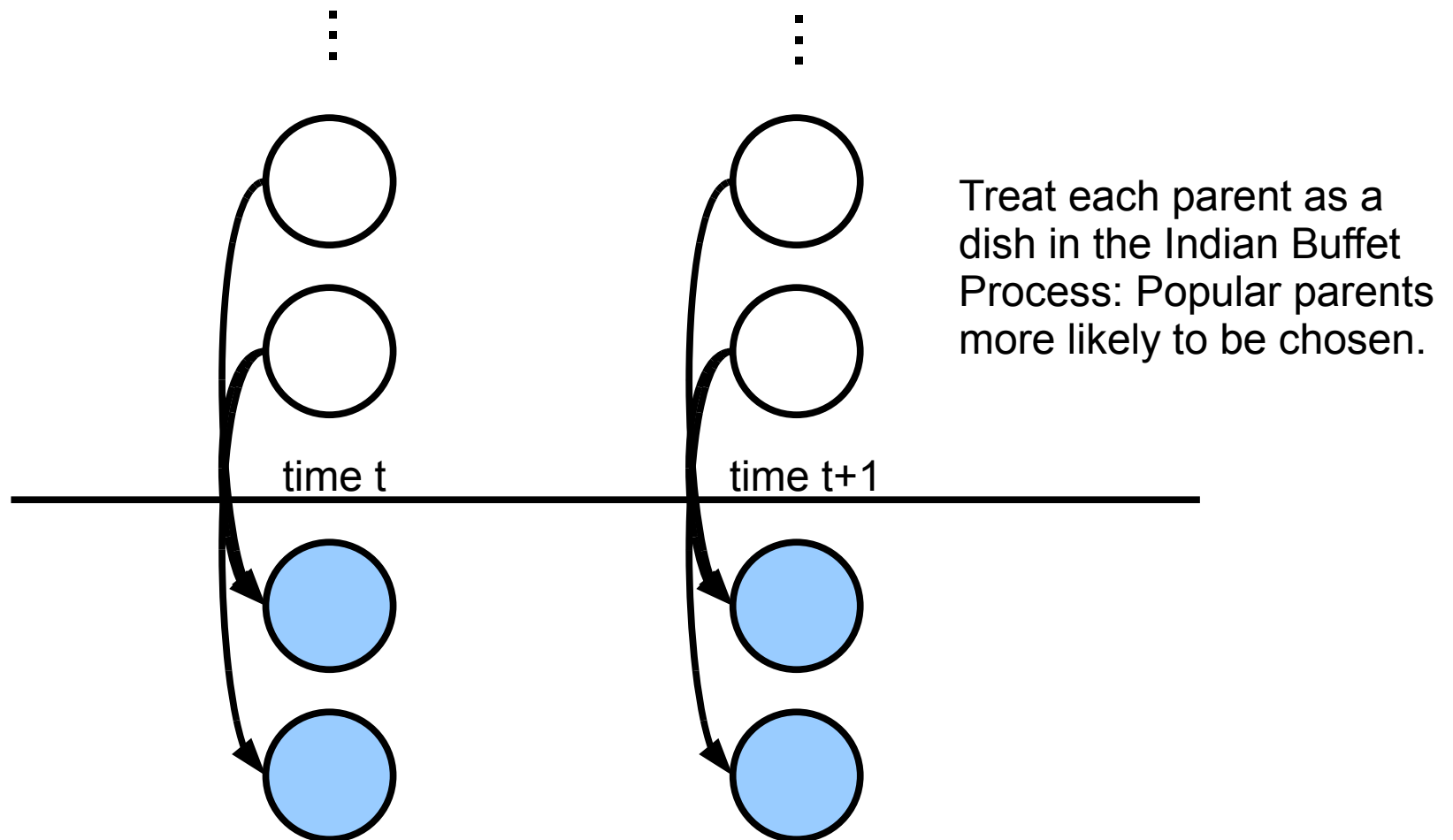
Our Approach: let **children pick parents**

- Will imply parents have infinite children
- But only factors affecting observed nodes matter

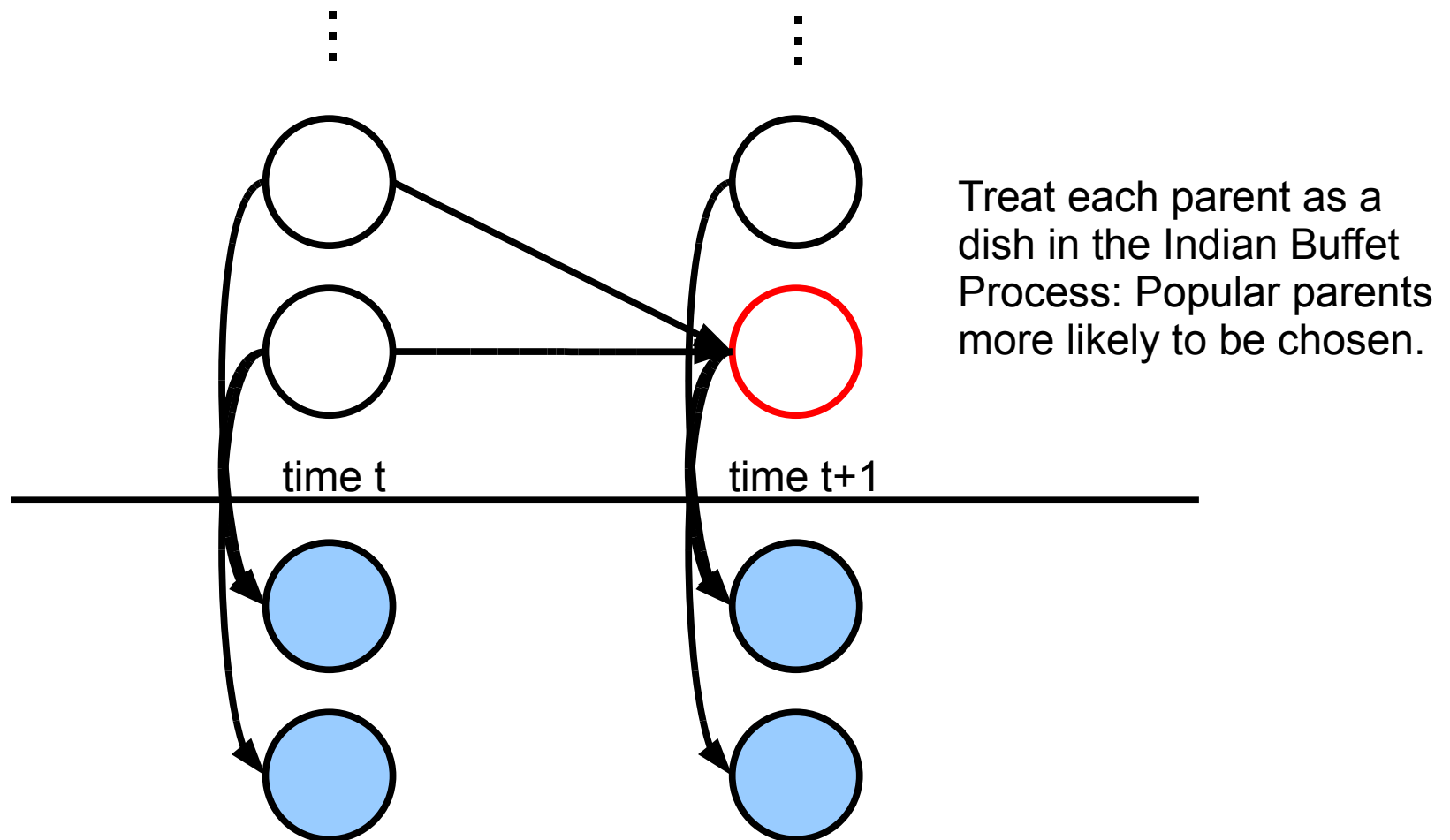
# The iDBN Generative Process



# Observed Nodes Choose Parents

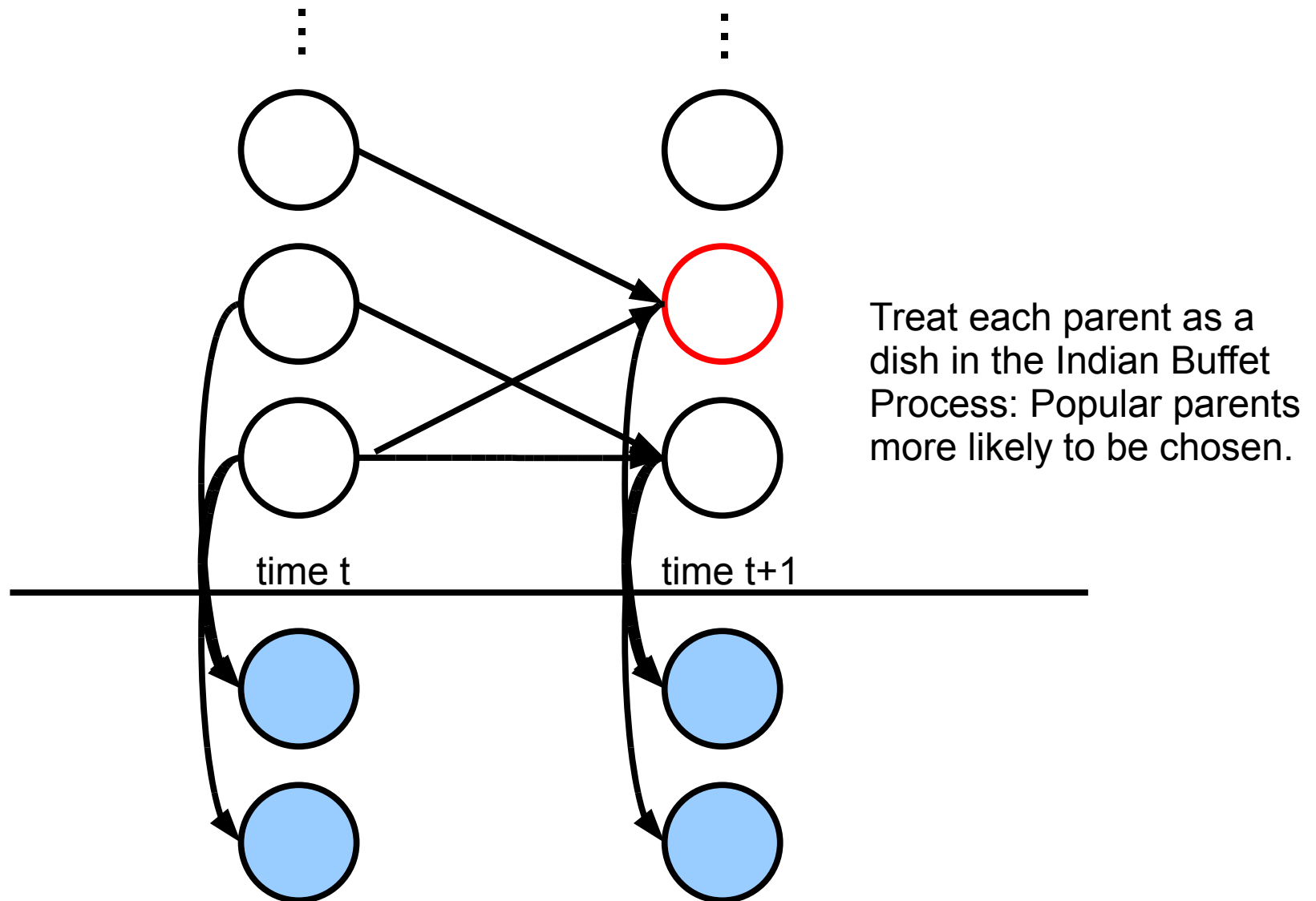


# Hidden Nodes Choose Parents

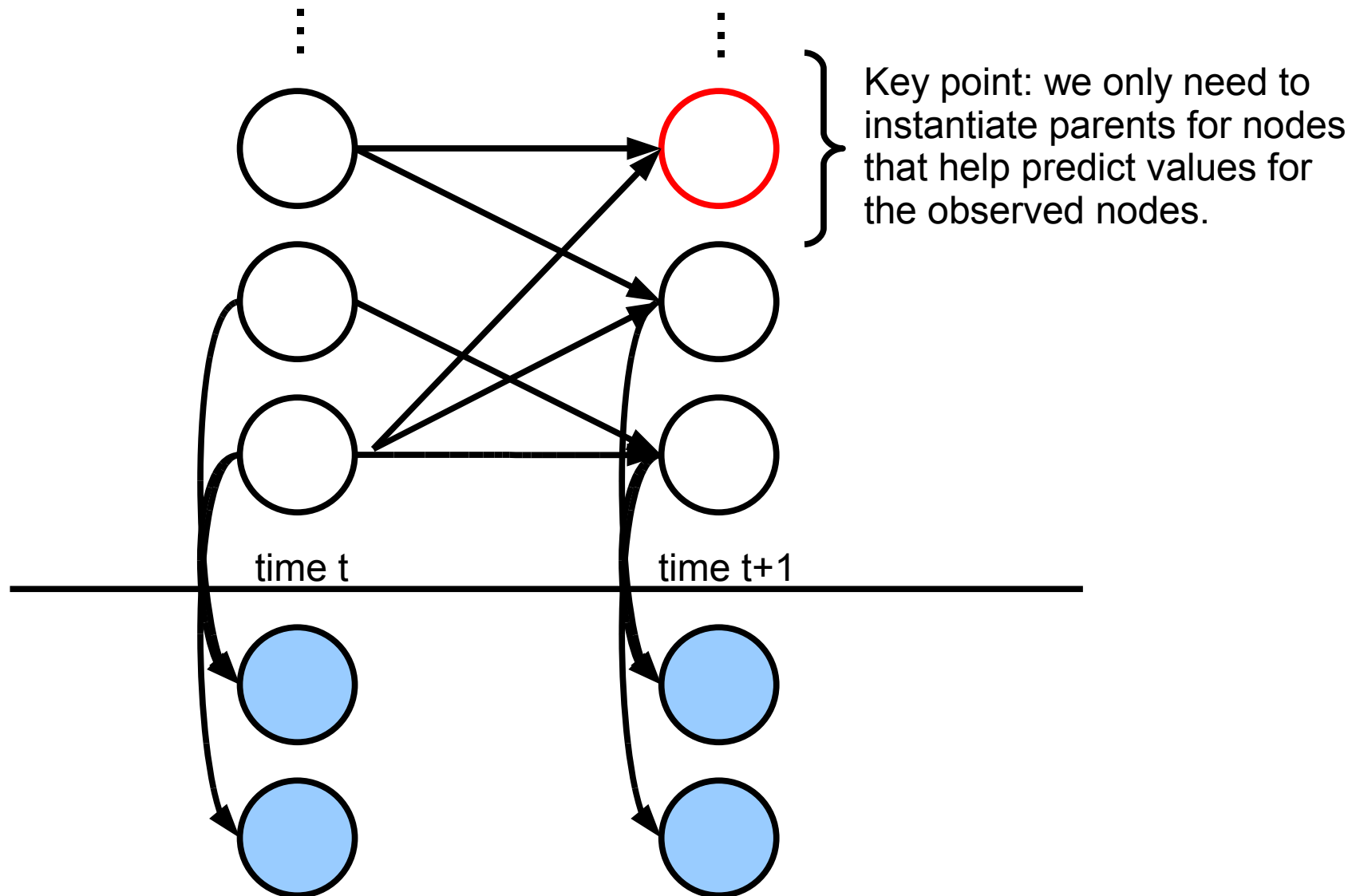


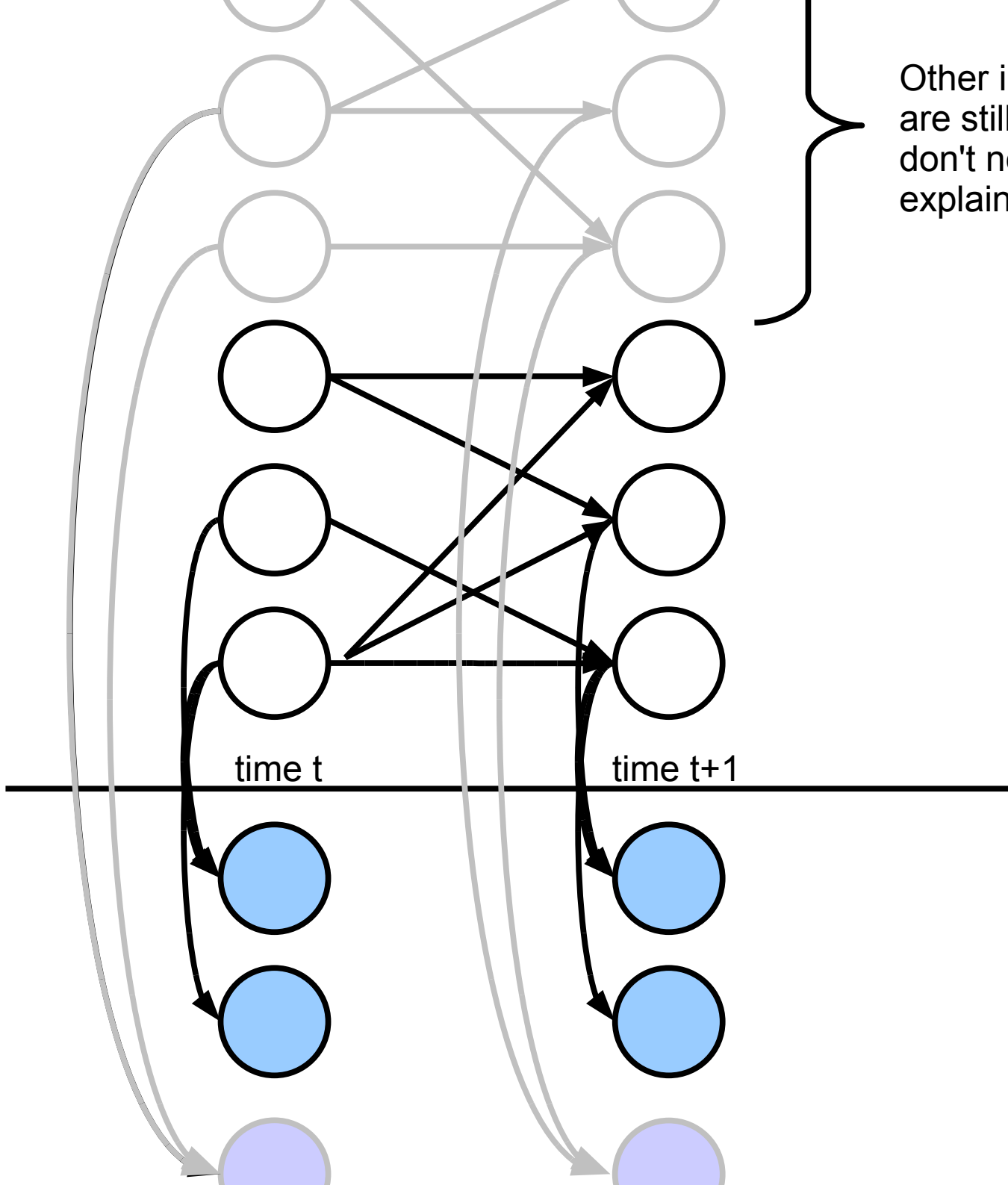


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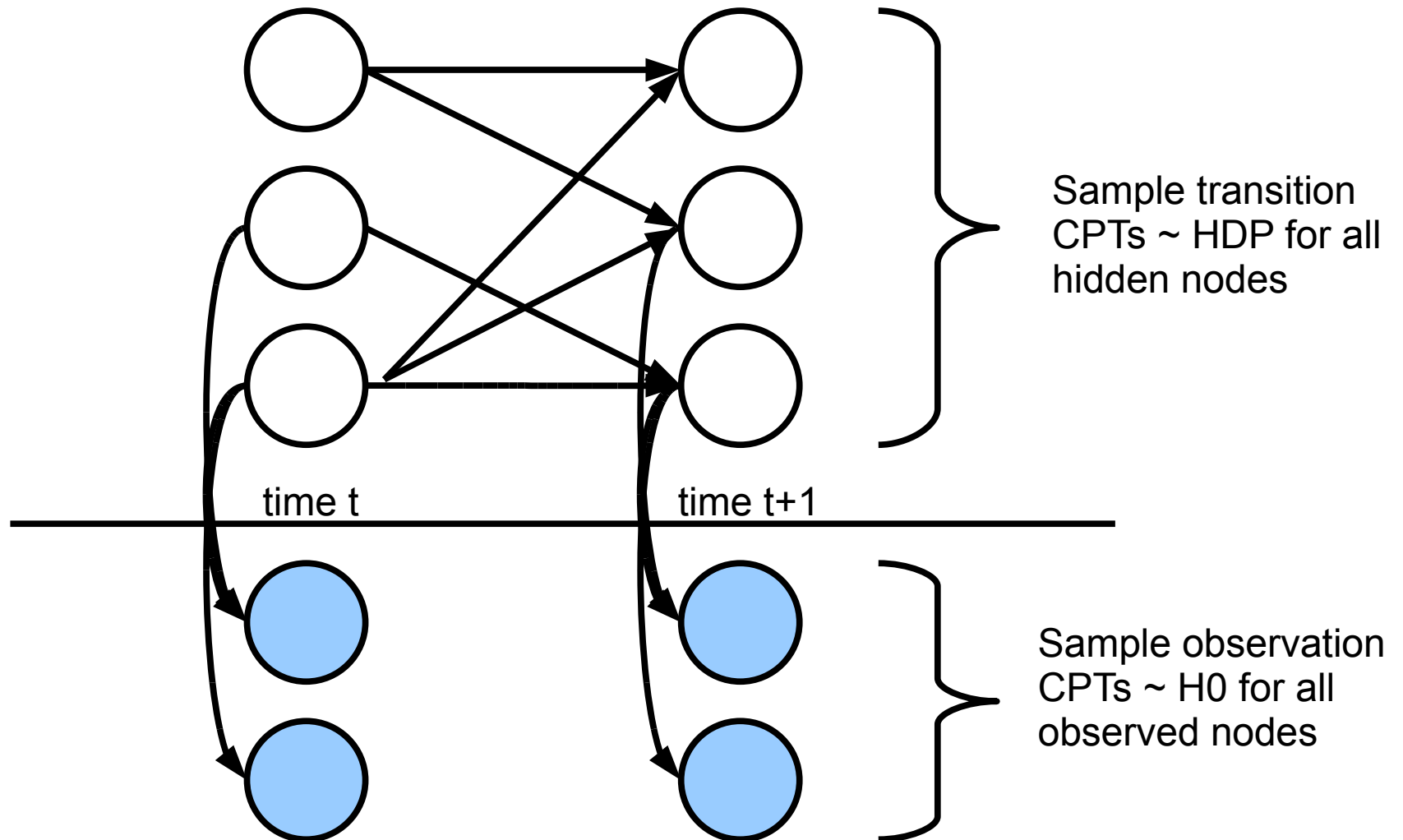


# Hidden Nodes Choose Parents

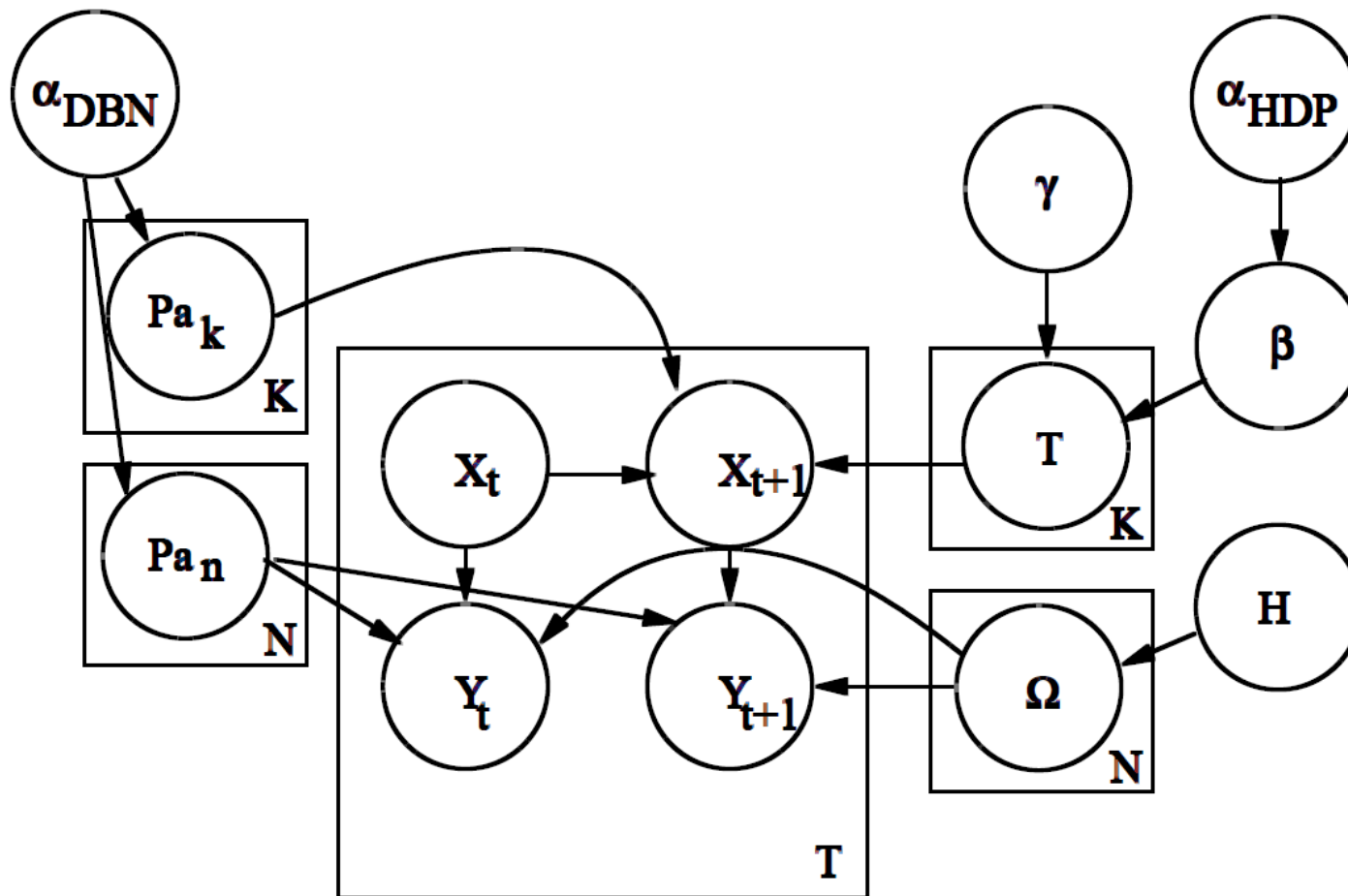




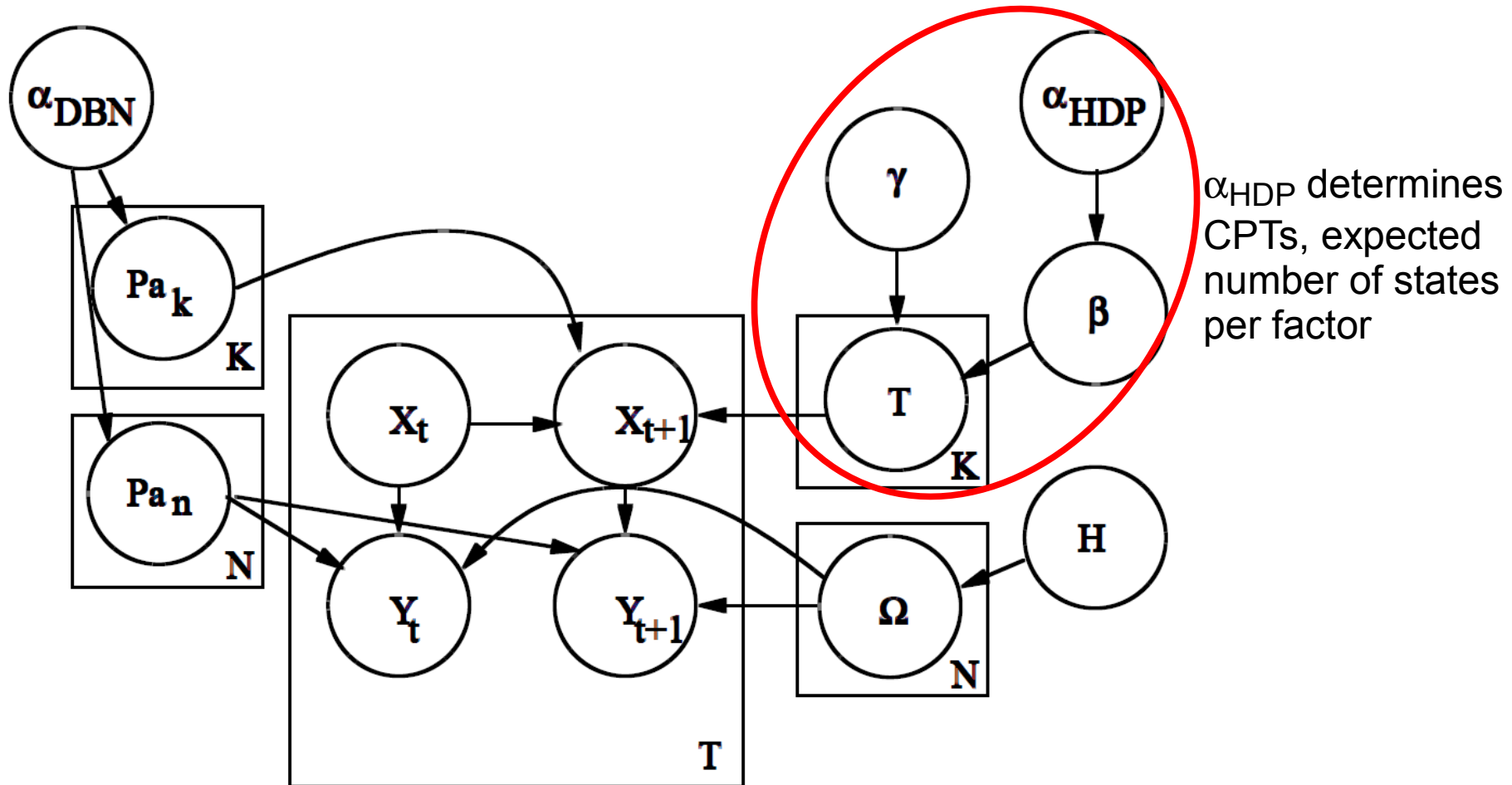
# Instantiate Parameters



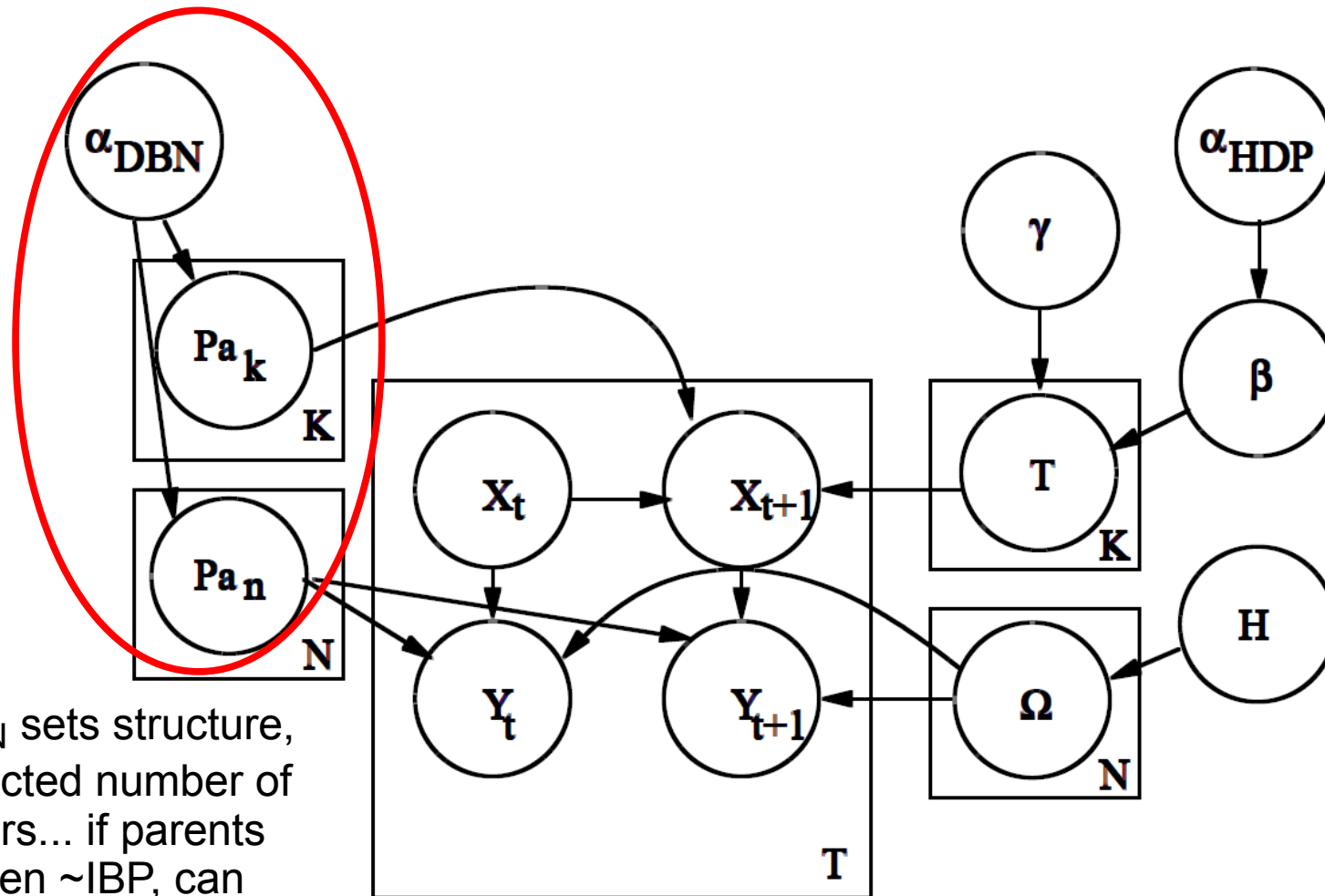
# Summary of the Prior



# Summary of the Prior



# Summary of the Prior



$\alpha_{\text{DBN}}$  sets structure, expected number of factors... if parents chosen  $\sim$ IBP, can guarantee finite factors to explain finite data

# Inference

General Approach: Blocked Gibbs sampling with the usual tricks (tempering, sequential initialization, etc.)

Resample factor-factor connections

$$p(P_{a_n} | P_{a_k}, X, \beta)$$

Gibbs sampling

Resample factor-observation connections

$$p(P_{a_k} | P_{a_n}, X, \beta)$$

Gibbs sampling

Resample transitions

$$p(T | P_{a_k}, X, \beta)$$

Dirichlet-multinomial

Resample observations

$$p(\Omega | P_{a_n}, X, \beta, Y)$$

Dirichlet-multinomial

Resample state sequence  $p(X | P_{a_n}, P_{a_k}, \beta, T, \Omega, Y)$  Factored frontier – Loopy BP

Add / delete factors

$$p(P_{a_n} | P_{a_k}, X, \beta)$$

Metropolis-Hastings birth/death



# Inference

General Approach: Blocked Gibbs sampling with  
(tempering, sequential initialization, etc.)

Common to all  
DBN inference

Resample factor-factor connections	$p(P_{a_n}   P_{a_k}, X, \beta)$	Gibbs sampling
Resample factor-observation connections	$p(P_{a_k}   P_{a_n}, X, \beta)$	Gibbs sampling
Resample transitions	$p(T   P_{a_k}, X, \beta)$	Dirichlet-multinomial
Resample observations	$p(\Omega   P_{a_n}, X, \beta, Y)$	Dirichlet-multinomial
Resample state sequence	$p(X   P_{a_n}, P_{a_k}, \beta, T, \Omega, Y)$	Factored frontier – Loopy BP
Add / delete factors	$p(P_{a_n}   P_{a_k}, X, \beta)$	Metropolis-Hastings birth/death

# Inference

General Approach: Blocked Gibbs sampling with  
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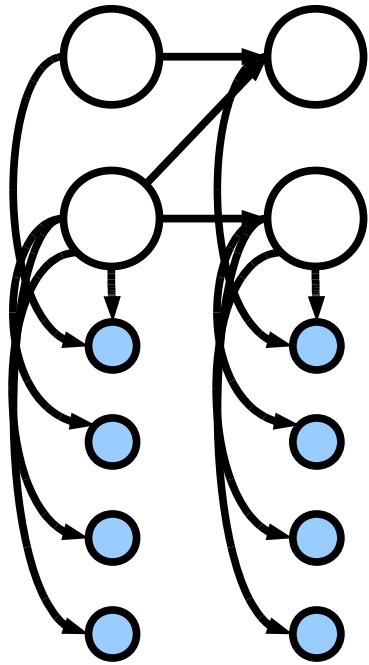
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Resample state sequence	$p(X   P_{a_n}, P_{a_k}, \beta, T, \Omega, Y)$	Factored frontier – Loopy BP

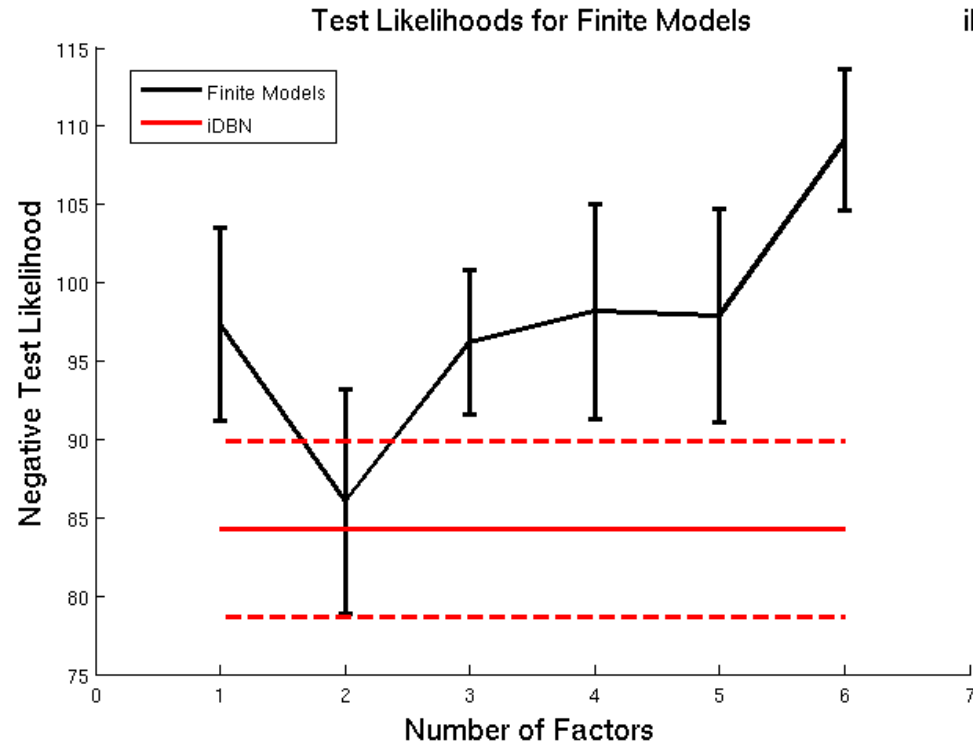
Add / delete factors	$p(P_{a_n}   P_{a_k}, X, \beta)$	Metropolis-Hastings birth/death
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Specific to iDBN  
**only 5% computational overhead!**

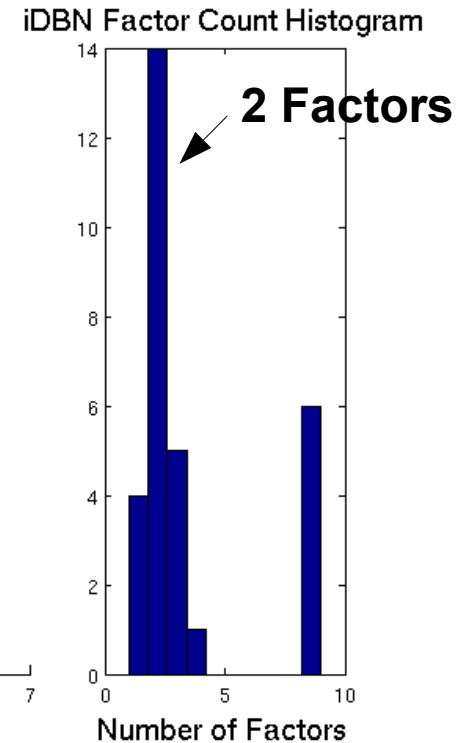
# Results: Toy Example



True Model



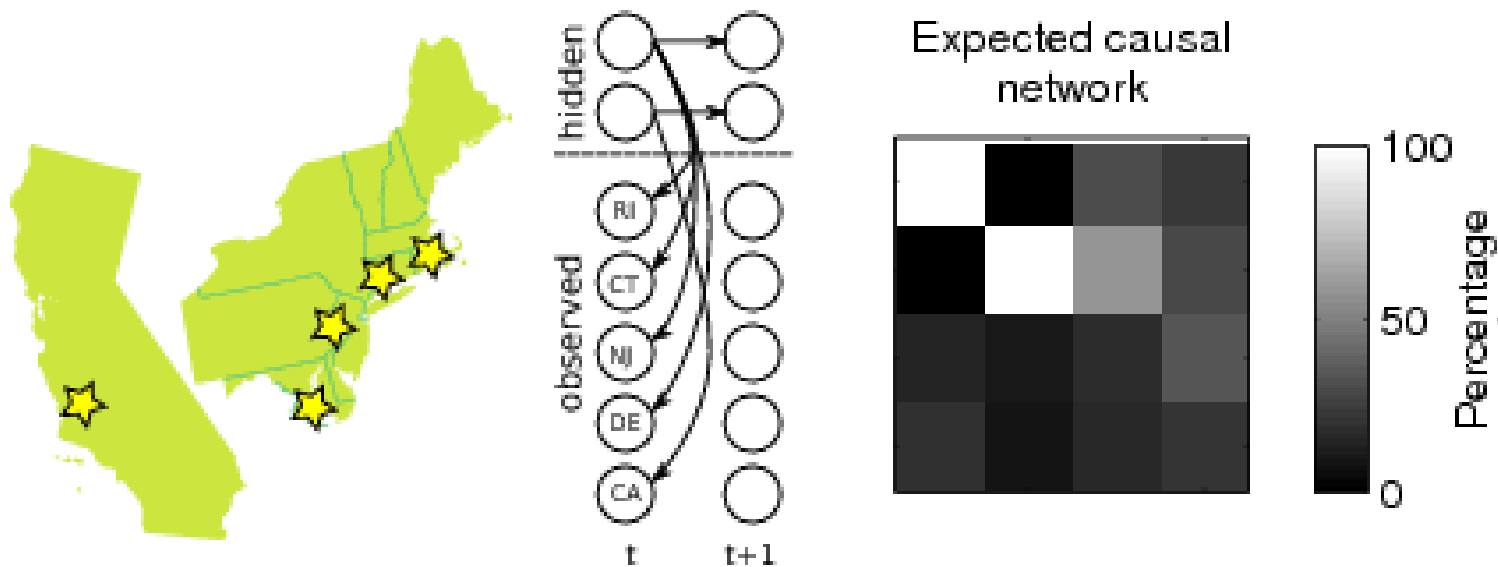
Likelihoods on Held-out Data



Factor Count

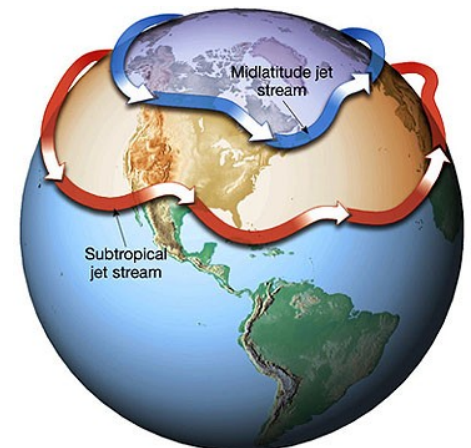
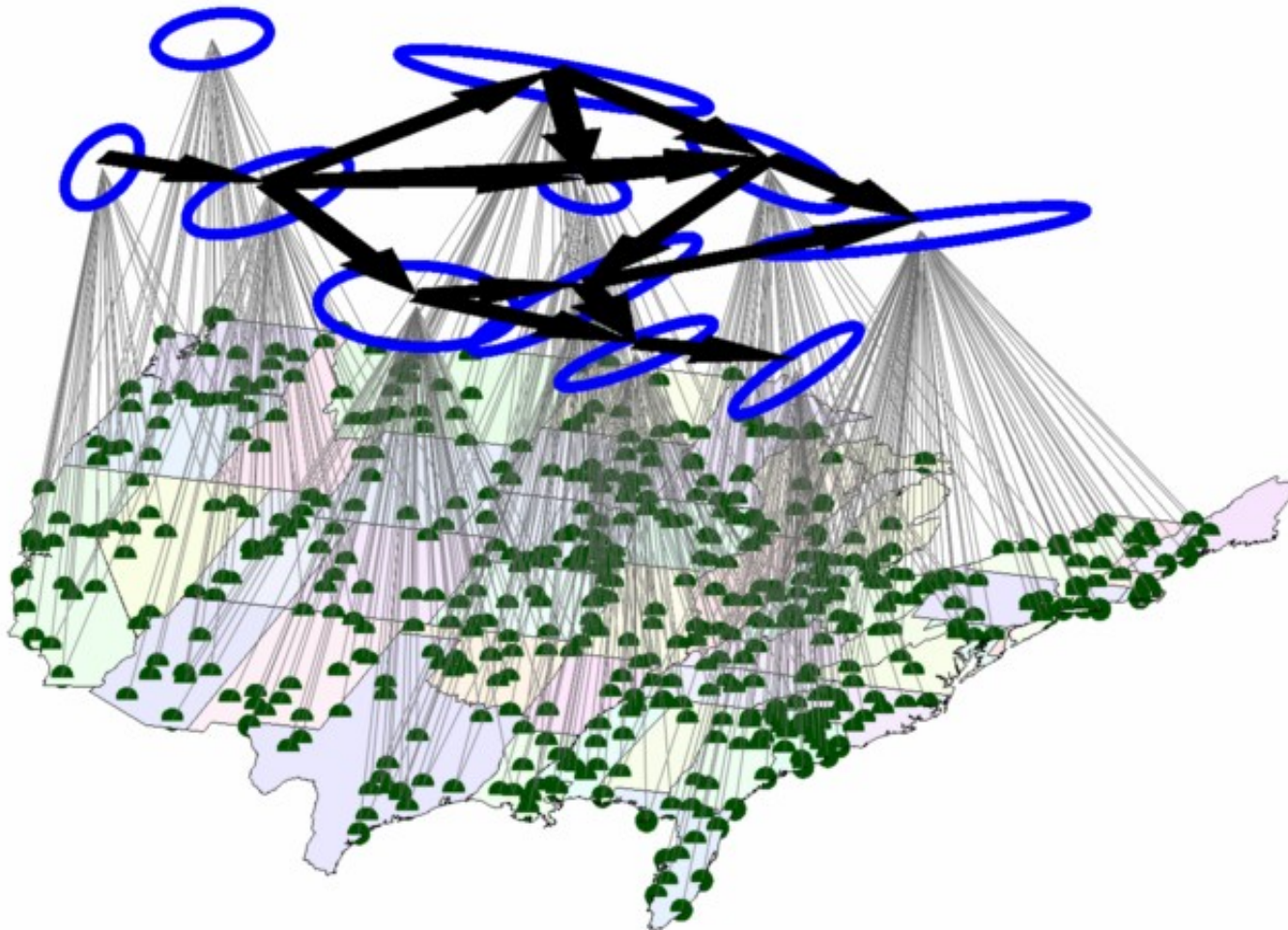
# Returning to Weather Example: Small Dataset

A model with just five locations quickly separates the east coast and the west coast data points.



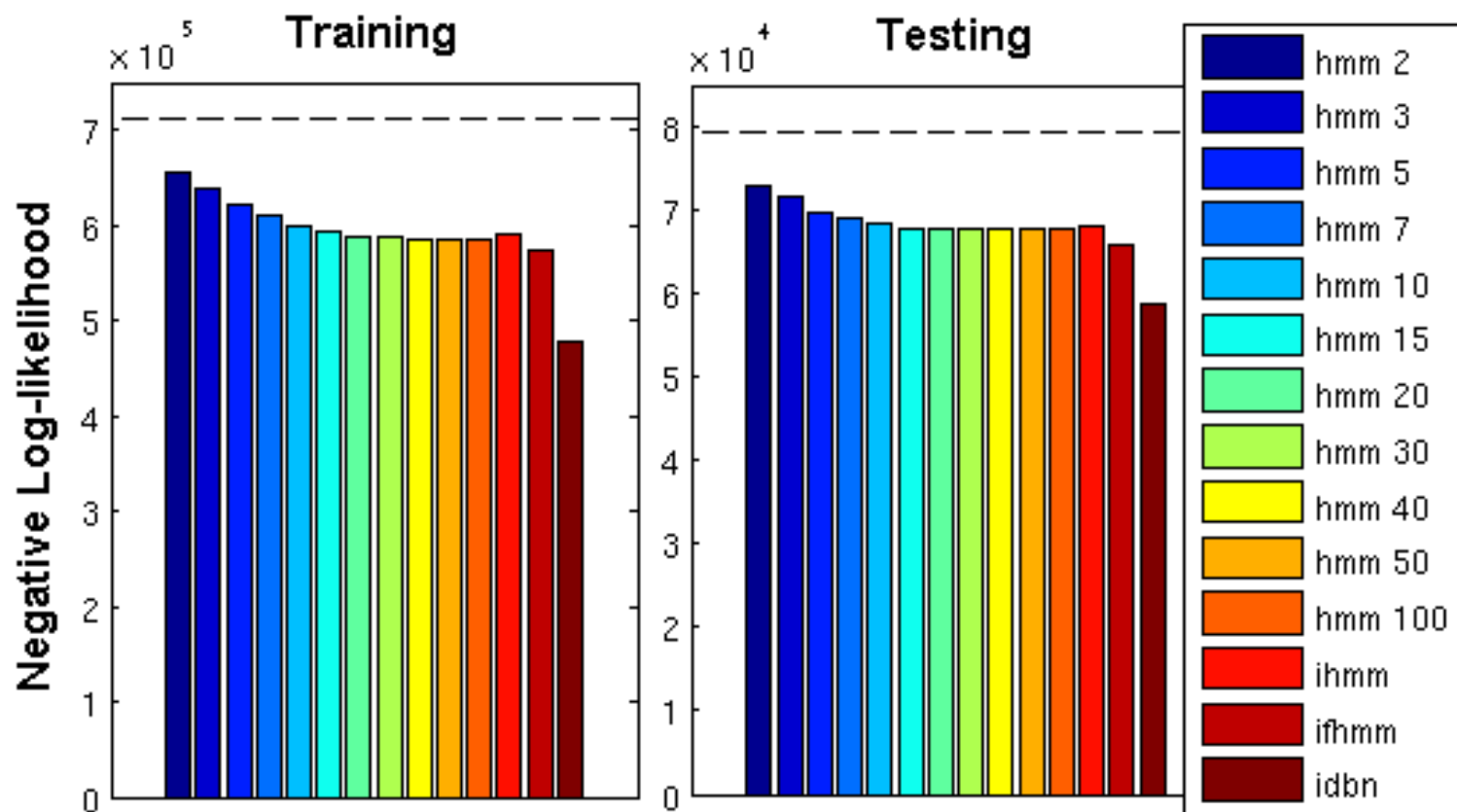
# Weather Example: Full Dataset

On the full dataset, we get regional factors with a general west-to-east pattern (the jet-stream).



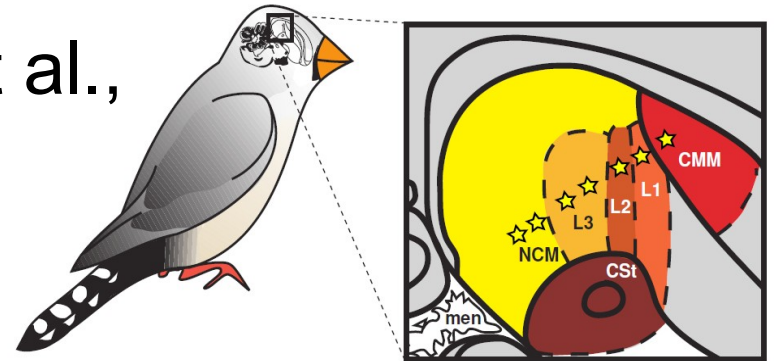
# Weather example: Full Dataset

Training and test performance (lower is better)

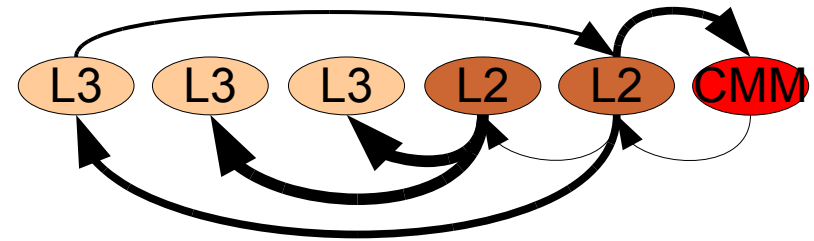
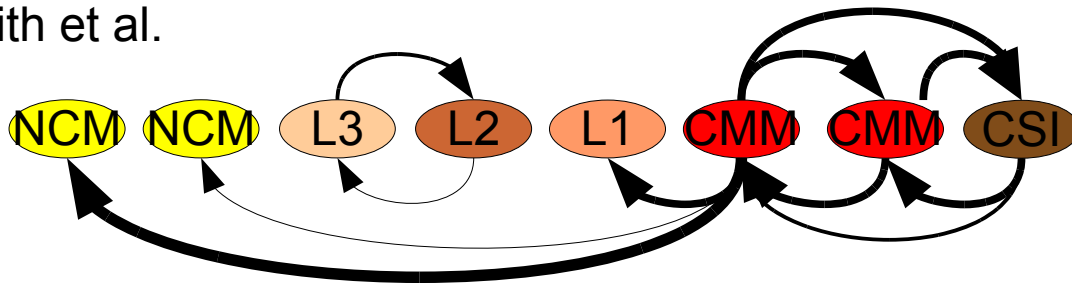


# Zebra Finch Example

Given electrode readings (Smith et al., 2006), infer functional connectivity.

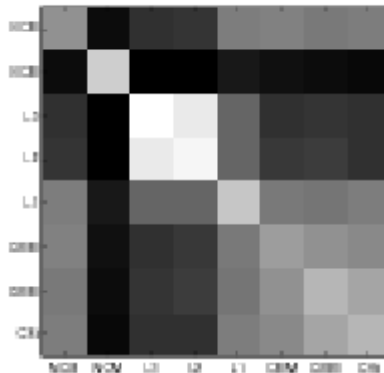


Results from Smith et al.

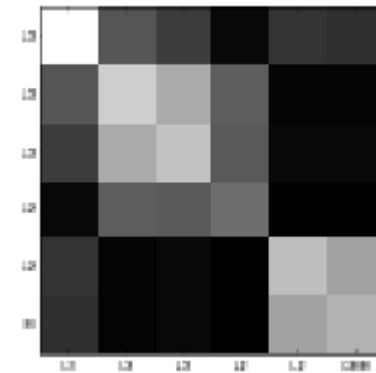


iDBN shared factors

Observation Clusterings  
LIG1841



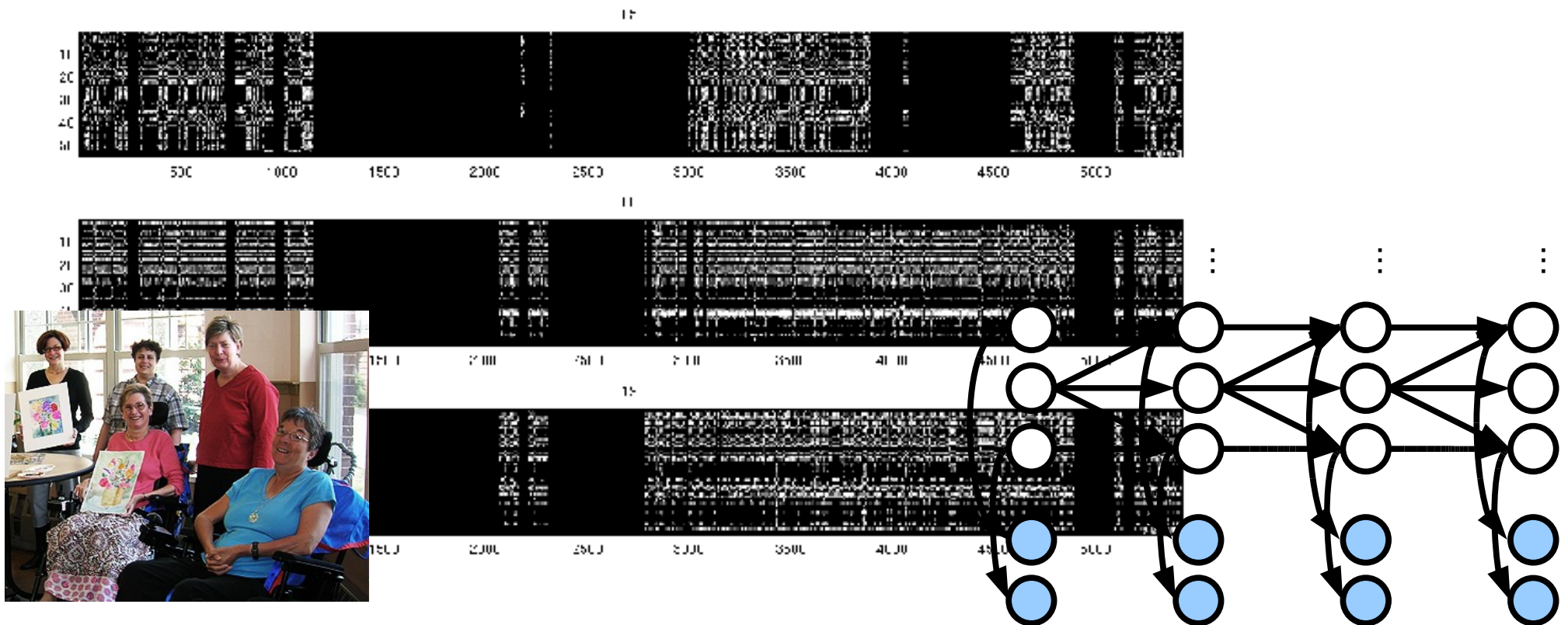
Observation Clusterings  
Black747





# Summary and Future Work

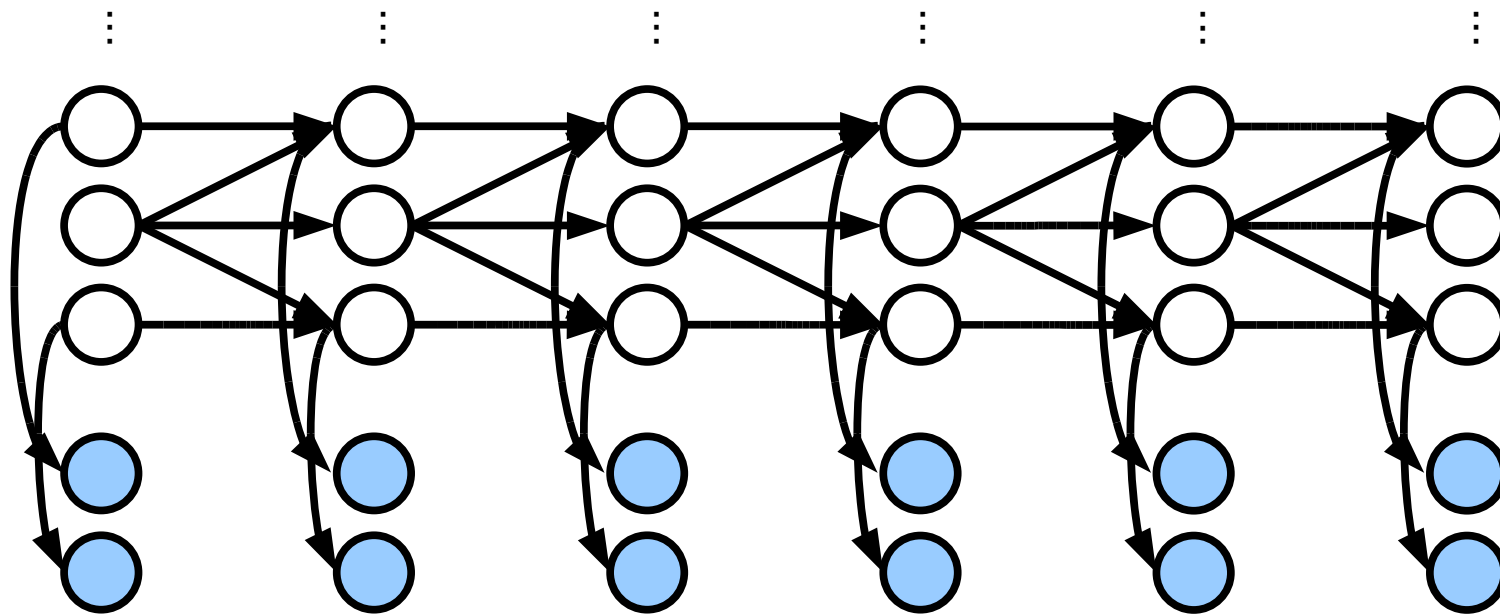
- Summary: We presented the iDBN prior, which allows us to infer the structure of general time-series models, showed it found interesting structure in weather, zebra-finch data.
- What's next: improving inference/model knobs, application to patient monitoring in an eldercare setting.





# Summary and Future Work

- Summary: We presented the iDBN prior, which allows us to infer the structure of general time-series models, showed it found interesting structure in weather, zebra-finch data.
- Future work: more control in the priors, improving inference, and adding control (e.g. for use in reinforcement learning).



# Results on Other Domains

	Negative Test Likelihood			Factors Discovered		
	DBN	iFHMM	iDBN	DBN	iFHMM	iDBN
NW Star	174.0 ± 8.2	165.2 ± 3.0	156.2 ± 3.0	5	12.8 ± 0.2	2.4 ± 0.2
NW Tree	255.6 ± 7.1	286.5 ± 2.9	216.2 ± 10.0	7	12.0 ± 0.0	4.0 ± 0.4
NW Ring	181.7 ± 16.0	154.3 ± 1.6	151.4 ± 2.8	4	9.0 ± 1.2	4.2 ± 1.0
Spike Train	142.4 ± 2.7	133.1 ± 2.1	136.0 ± 2.8	1	15.9 ± 0.1	18.1 ± 6.2
Jungle	14.8 ± 1.4	13.9 ± 1.5	14.2 ± 1.6	6	3.1 ± 0.1	29.5 ± 3.6

# Growth of Hidden Factors and Observed Nodes

