

Exercise 11

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1 Majority

In the class, we discussed the deterministic algorithm of Boyer and Moore which has space complexity $O(\log n)$ and outputs an element such that if the stream has a majority, the output is equal to this majority. Prove that any deterministic algorithm that is able to decide whether a stream has a majority element or not needs space $\Omega(n)$ bits.

2 Frequent Elements

Extend the majority algorithm of Boyer and Moore, which we discussed in the class, to an algorithm space complexity of $O(k \log n)$ bits that outputs k elements that include those that appear in more than $1/k$ fraction of the stream.

3 Morris's Approximate Counting Algorithm

In Morris's approximate counting algorithm, which we discussed in the class, prove that

$$\mathbb{E}[2^{2X_m}] = \frac{3}{2}m^2 + \frac{3}{2}m + 1.$$

4 Pairwise Independent Hashing

Prove that given a prime number p , the random hash function $h_{a,b}(x) : \mathbb{F}_p \rightarrow \mathbb{F}_p$ defined as $f(x) = ax + b \pmod p$, where a and b are random numbers in $\{0, 1, \dots, p-1\}$ is a pairwise independent hash function, that is, for every $x, y \in \{0, 1, \dots, p-1\}$ where $x \neq y$, and every $i, j \in \{0, 1, \dots, p-1\}$, we have $\Pr[f(x) = i \text{ and } f(y) = j] = 1/p^2$.

5 Distinct Elements

Consider the Distinct Elements algorithms of Bar-Yossef et al., which we discussed in the class. We saw that the probability of undershooting by a $(1 - \varepsilon)$ factor is at most $1/6$. Prove that the probability of overshooting by a $(1 + \varepsilon)$ factor is also upper bounded by $1/6$.