

Lecture 3: Approximation Algorithms III

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# 1 Approximation schemes (Continued)

## 2 Bin packing (Continued)

During the last lecture, the bin packing problem was tackled first by FIRSTFIT, which we showed to be a 2-approximation algorithm. We also described  $\mathcal{A}_\epsilon$ , an exact algorithm which solves bin packing under two assumptions:

1. All items have at least size  $\epsilon$
2. There are only  $k$  different possible sizes (for some constant  $k$ ).

Towards the end, we worked towards removing these two assumptions.

**Definition 1** (Bin packing problem). *Given a set  $\mathcal{S}$  with  $n$  items where each item  $i$  has  $size(i) \in (0, 1]$ , find the minimum number of unit-sized (size 1) bins that can hold all  $n$  items.*

For any problem instance  $I$ , let  $OPT(I)$  be an optimum bin assignment and  $|OPT(I)|$  be the corresponding minimum number of bins required. One can see that  $\sum_{i=1}^n size(i) \leq |OPT(I)|$ .

### 2.1 Special case where items have sizes larger than $\epsilon$ , for some $\epsilon > 0$

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**Algorithm 1** PTAS-BINPACKING( $I = \mathcal{S}, \epsilon$ )

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$k \leftarrow \lceil \frac{1}{\epsilon^2} \rceil$

$Q \leftarrow \lceil n\epsilon^2 \rceil$

Partition  $n$  items into  $k$  non-overlapping groups, each with  $Q$  items

▷ See Figure 1

**for**  $i \in \{1, \dots, k\}$  **do**

$k_{max} \leftarrow \max_{\text{item } j \text{ in group } i} size(j)$

**for** item  $j$  in group  $i$  **do**

$size(j) \leftarrow k_{max}$

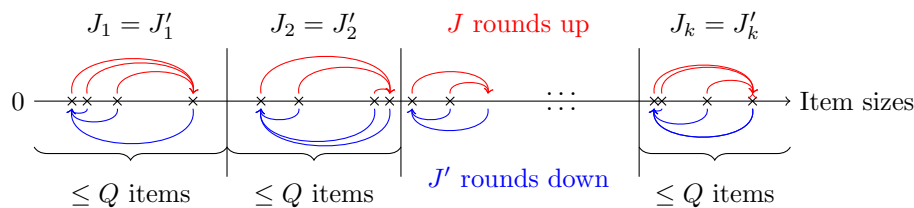
**end for**

**end for**

Denote the modified instance as  $J$

**return**  $\mathcal{A}_\epsilon(J)$

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**Figure 1:** Partition items into  $k$  groups, each with at most  $Q$  items. Label groups in ascending size ordering.  $J$  rounds up item sizes,  $J'$  rounds down item sizes.

Algorithm 1 pre-processes the sizes of a given input instance, then calls the exact algorithm  $\mathcal{A}_\epsilon$  to solve the modified instance. Since  $J$  only rounds up sizes,  $\mathcal{A}_\epsilon(J)$  will yield a satisfying bin assignment for instance  $I$ , with possibly “spare slack”. For analysis, let us define another modified instance  $J'$  as rounding down item sizes. Since we rounded down item sizes in  $J'$ ,  $|OPT(J')| \leq |OPT(I)|$ .

**Lemma 2.**  $|OPT(J)| \leq |OPT(J')| + Q$

*Proof.* Label the  $k$  groups in  $J$  by  $J_1, \dots, J_k$  where the items in  $J_i$  have smaller sizes than the items in  $J_{i+1}$ . Label the  $k$  groups in  $J'$  similarly. See Figure 1. For  $i = \{1, \dots, k-1\}$ , since the smallest item in  $J'_{i+1}$  has size larger to the largest item in  $J_i$ , any valid packing for  $J'_i$  serves as a valid packing for the  $J_{i-1}$ . For  $J_k$  (the largest group of  $Q$  items), let us use separate bins (hence the additive  $Q$  term).  $\square$

**Lemma 3.**  $|OPT(J)| \leq |OPT(I)| + Q$

*Proof.* By Lemma 2 and the fact that  $|OPT(J')| \leq |OPT(I)|$ .  $\square$

**Theorem 4.** Algorithm 1 is an  $(1 + \epsilon)$ -approximation algorithm.

*Proof.* Assumption (1) tells us that all items have at least size  $\epsilon$ , so  $|OPT(I)| \geq n\epsilon$ . Then,  $Q = \lfloor n\epsilon^2 \rfloor \leq n\epsilon^2 \leq \epsilon \cdot |OPT(I)|$ . By Lemma 2,  $|OPT(J)| \leq (1 + \epsilon) \cdot |OPT(I)|$ .  $\square$

## 2.2 Full PTAS for bin packing without assumptions

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**Algorithm 2** FULL-PTAS-BINPACKING( $I = \mathcal{S}, \epsilon$ )

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$\epsilon' \leftarrow \min\{\frac{1}{2}, \frac{\epsilon}{2}\}$	$\triangleright$ See analysis why we chose such an $\epsilon'$
$X \leftarrow$ Items with size $< \epsilon'$	$\triangleright$ Ignore small items to fulfill assumption of sizes $\geq \epsilon'$
$P \leftarrow$ PTAS-BINPACKING( $\mathcal{S} \setminus X, \epsilon'$ )	$\triangleright$ By theorem 4, $ P  = (1 + \epsilon') \cdot  OPT(\mathcal{S} \setminus X) $
$P' \leftarrow$ Using FIRSTFIT, add items in $X$ to $P$	$\triangleright$ Handle small items
<b>return</b> Resultant packing $P'$	

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**Theorem 5.** Algorithm 2 uses at most  $(1 + \epsilon)|OPT(I)| + 1$  bins

*Proof.* If FIRSTFIT does not open a new bin, the theorem trivially holds. Suppose FIRSTFIT opens a new bin (using  $m$  bins in total), then we know that at least  $(m - 1)$  bins are strictly more than  $(1 - \epsilon')$ -full.

$$\begin{aligned} |OPT(I)| &\geq \sum_{i=1}^n size(i) && \text{Lower bound on } |OPT(I)| \\ &> (m - 1)(1 - \epsilon') && \text{From above observation} \end{aligned}$$

Hence,

$$\begin{aligned} m &< \frac{|OPT(I)|}{1 - \epsilon'} + 1 && \text{Rearranging} \\ &< |OPT(I)| \cdot (1 + 2\epsilon') + 1 && \text{Since } \frac{1}{1 - \epsilon'} \leq 1 + 2\epsilon', \text{ for } \epsilon' \leq \frac{1}{2} \\ &\leq (1 + \epsilon) \cdot |OPT(I)| + 1 && \text{By choice of } \epsilon' = \min\{\frac{1}{2}, \frac{\epsilon}{2}\} \end{aligned}$$

$\square$

## 3 Minimum makespan scheduling

**Definition 6** (Minimum makespan scheduling problem). Given  $n$  jobs  $I = \{p_1, \dots, p_n\}$ , find an assignment of jobs to  $m$  identical machines such that the completion time (called the makespan) is minimized.

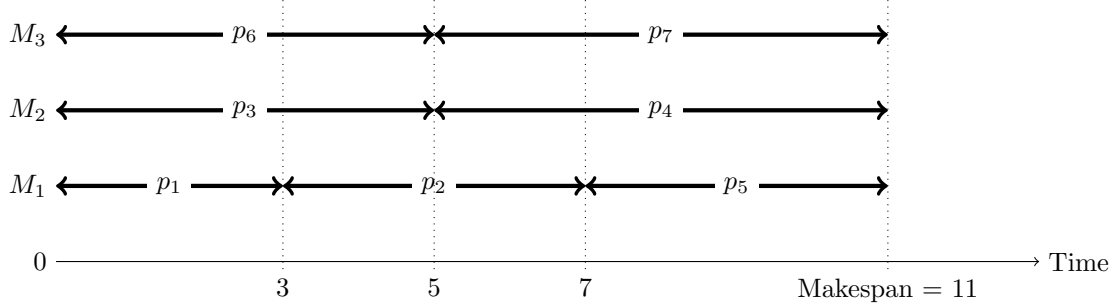
For any problem instance  $I$ , let  $OPT(I)$  be an optimum job assignment and  $|OPT(I)|$  be the corresponding makespan. One can see that:

- $p_{max} = \max_{i \in \{1, \dots, n\}} p_i \leq |OPT(I)|$
- $\frac{1}{m} \sum_{i=1}^n p_i \leq |OPT(I)|$

Denote  $L(I) = \max\{p_{max}, \frac{1}{m} \sum_{i=1}^n p_i\}$ . We see that  $L(I) \leq |OPT(I)| \leq p_{max} + \frac{1}{m} \sum_{i=1}^n p_i \leq 2L(I)$ .

**Remark** To prove approximation factors, it is often useful to relate to lower bounds of  $|OPT(I)|$ .

**Example** Suppose we have 7 jobs  $I = \{p_1 = 3, p_2 = 4, p_3 = 5, p_4 = 6, p_5 = 4, p_6 = 5, p_7 = 6\}$  and  $m = 3$  machines. Then, the lower bound on the makespan is  $L(I) = \max\{6, 11\} = 11$ . This is achievable via  $M_1 = \{p_1, p_2, p_5\}, M_2 = \{p_3, p_4\}, M_3 = \{p_6, p_7\}$ .



We now describe a simple greedy algorithm (Algorithm 3) due to Graham [Gra66] and show that it is a 2-approximation algorithm. With slight modifications, we improve it to a  $\frac{4}{3}$ -approximation algorithm (Algorithm 4). Finally, we end off the section with a PTAS for minimum makespan scheduling.

### 3.1 Greedy approximation algorithms

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**Algorithm 3** GRAHAM( $I = \{p_1, \dots, p_n\}, m$ )

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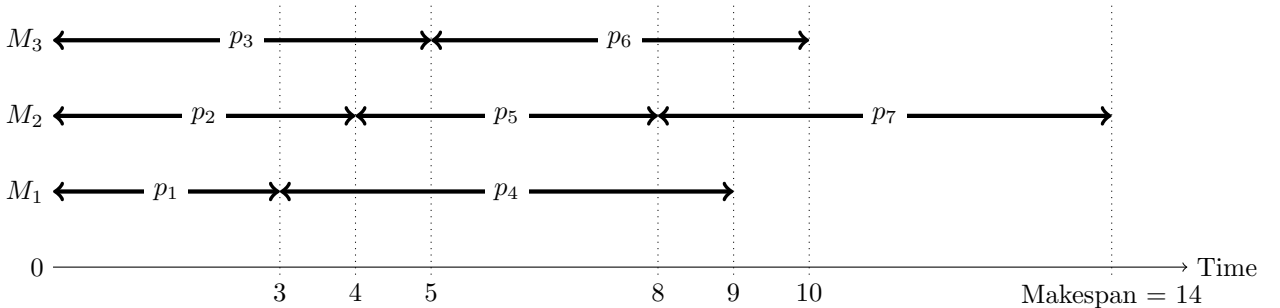
$M_1, \dots, M_m \leftarrow \emptyset$	▷ All machines are initially free
<b>for</b> $i \in \{1, \dots, n\}$ <b>do</b>	
$j \leftarrow \operatorname{argmin}_{j \in \{1, \dots, m\}} \sum_{p \in M_j} p$	▷ Pick the least loaded machine
$M_j \leftarrow M_j \cup \{p_i\}$	▷ Add job $i$ to this machine
<b>end for</b>	
<b>return</b> $M_1, \dots, M_m$	

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**Theorem 7.** GRAHAM (Algorithm 3) is a 2-approximation to minimum makespan scheduling.

*Proof.* Consider the last job that finishes running. Suppose it takes time  $p_{last}$  and it was assigned to machine  $j$  whereby  $\sum_{p \in M_j} p = t$ . Then,  $|\text{GRAHAM}(I)| = t + p_{last}$ . As GRAHAM assigns greedily to the least loaded machine, all machines take at least  $t$  time, so  $t \cdot m \leq \sum_{i=1}^n p_i \leq m \cdot |\text{OPT}(I)|$ . Since  $p_{last} \leq p_{max} \leq |\text{OPT}(I)|$ ,  $|\text{GRAHAM}(I)| = t + p_{last} \leq 2 \cdot |\text{OPT}(I)|$ .  $\square$

Recall the example where  $I = \{p_1 = 3, p_2 = 4, p_3 = 5, p_4 = 6, p_5 = 4, p_6 = 5, p_7 = 6\}$  and  $m = 3$ . GRAHAM will schedule  $M_1 = \{p_1, p_4\}, M_2 = \{p_2, p_5, p_7\}, M_3 = \{p_3, p_6\}$ , yielding a makespan of 14. As expected,  $14 = |\text{GRAHAM}(I)| \leq 2 \cdot |\text{OPT}(I)| = 22$ .



**Remark** The approximation for GRAHAM is loose because we have no guarantees on  $p_{last}$  beyond  $p_{last} \leq p_{max}$ . This motivates us to order the job timings in descending order (see Algorithm 4).

**Lemma 8.** Let  $p_{last}$  be the last job that finishes running. If  $p_{last} > \frac{1}{3} \cdot |\text{OPT}(I)|$ , then  $|\text{MODIFIEDGRAHAM}(I)| = |\text{OPT}(I)|$ .

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**Algorithm 4** MODIFIEDGRAHAM( $I = \{p_1, \dots, p_n\}, m$ )

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$I' \leftarrow I$  in descending order  
**return** GRAHAM( $I', m$ )

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*Proof.* For  $m \geq n$ ,  $|\text{MODIFIEDGRAHAM}(I)| = |\text{OPT}(I)|$  by trivially putting one job on each machine. For  $m < n$ , we may assume that every machine has a job<sup>1</sup>.

Suppose, for a contradiction, that  $|\text{MODIFIEDGRAHAM}(I)| > |\text{OPT}(I)|$ . Then, there exists<sup>2</sup> a sequence of jobs with descending sizes  $I = \{p_1, \dots, p_n\}$  such that the last smallest job  $p_n$  causes  $\text{MODIFIEDGRAHAM}(I)$  to have a makespan larger than  $\text{OPT}(I)$ . That is,  $p_{\text{last}} = p_n$  and  $|\text{MODIFIEDGRAHAM}(I \setminus \{p_n\})| \leq |\text{OPT}(I)|$ . Let  $\mathcal{C}$  be the configuration of machines after  $\text{MODIFIEDGRAHAM}$  assigned  $\{p_1, \dots, p_{n-1}\}$ .

**Observation 1** In  $\mathcal{C}$ , each machine has either 1 or 2 jobs.

If there exists machine  $M_i$  with  $\geq 3$  jobs,  $M_i$  will take  $> |\text{OPT}(I)|$  time because all jobs take  $> \frac{1}{3} \cdot |\text{OPT}(I)|$  time. This contradicts the assumption  $|\text{MODIFIEDGRAHAM}(I \setminus \{p_n\})| \leq |\text{OPT}(I)|$ .

Let us denote the jobs that are alone in  $\mathcal{C}$  as *heavy jobs*, and the machines they are on as *heavy machines*.

**Observation 2** In  $\text{OPT}(I)$ , all heavy jobs are alone.

Assigning  $p_n$  to any machine (in particular, the heavy machines) in  $\mathcal{C}$  causes the makespan to exceed  $|\text{OPT}(I)|$ . Since  $p_n$  is the smallest job, no other job can be assigned to the heavy machines otherwise  $|\text{OPT}(I)|$  cannot be attained by  $\text{OPT}(I)$ .

Suppose there are  $k$  heavy jobs occupying a machine each in  $\text{OPT}(I)$ . Then, there are  $2(m - k) + 1$  jobs (two non-heavy jobs per machine in  $\mathcal{C}$ , and  $p_n$ ) to be distributed across  $m - k$  machines. By pigeonhole principle, at least one machine  $M^*$  will get  $\geq 3$  jobs in  $\text{OPT}(I)$ . However, since the smallest job  $p_n$  takes  $> \frac{1}{3} \cdot |\text{OPT}(I)|$  time,  $M^*$  will spend  $> |\text{OPT}(I)|$  time. Contradiction.  $\square$

**Theorem 9.** MODIFIEDGRAHAM (Algorithm 4) is a  $\frac{4}{3}$ -approximation to minimum makespan scheduling.

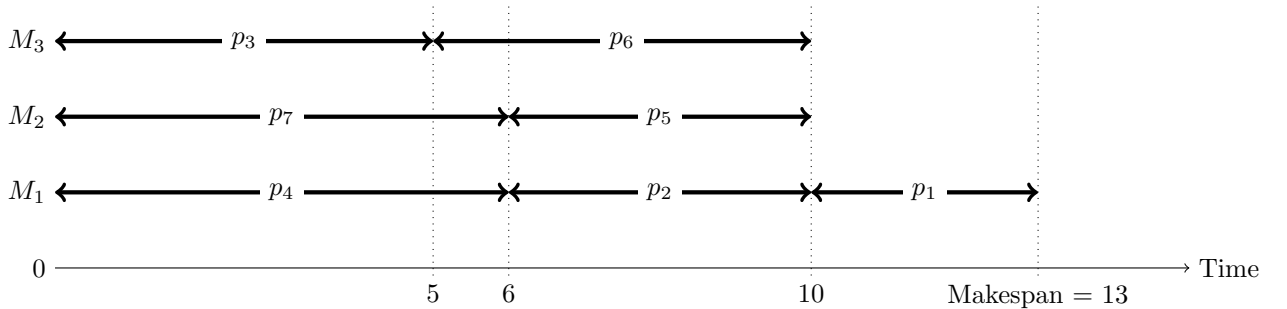
*Proof.* Case 1:  $p_{\text{last}} \leq \frac{1}{3} \cdot |\text{OPT}(I)|$

By similar arguments as per Theorem 7,  $|\text{MODIFIEDGRAHAM}(I)| = t + p_{\text{last}} \leq \frac{4}{3} \cdot |\text{OPT}(I)|$

Case 2:  $p_{\text{last}} > \frac{1}{3} \cdot |\text{OPT}(I)|$

By Lemma 8,  $|\text{MODIFIEDGRAHAM}(I)| = |\text{OPT}(I)|$ .  $\square$

Recall the example where  $I = \{p_1 = 3, p_2 = 4, p_3 = 5, p_4 = 6, p_5 = 4, p_6 = 5, p_7 = 6\}$  and  $m = 3$ .  $I' = \{p_4 = 6, p_7 = 6, p_3 = 5, p_6 = 5, p_2 = 4, p_5 = 4, p_1 = 3\}$  and  $\text{MODIFIEDGRAHAM}$  will schedule  $M_1 = \{p_4, p_2, p_1\}, M_2 = \{p_7, p_5\}, M_3 = \{p_3, p_6\}$ , yielding a makespan of 13. As expected,  $13 = |\text{MODIFIEDGRAHAM}(I)| \leq \frac{4}{3} \cdot |\text{OPT}(I)| = 14.666\dots$



<sup>1</sup>Suppose there is a machine  $M_i$  without a job, then there must be another machine  $M_j$  with more than 1 job (by pigeonhole principle). Shifting one of the jobs from  $M_j$  to  $M_i$  will not increase the makespan.

<sup>2</sup>If adding  $p_j$  for some  $j < n$  already causes  $|\text{MODIFIEDGRAHAM}(\{p_1, \dots, p_j\})| > |\text{OPT}(I)|$ , we can truncate  $I$  to  $\{p_1, \dots, p_j\}$  so that  $p_{\text{last}} = p_j$ . Since  $p_j \geq p_n > \frac{1}{3} \cdot |\text{OPT}(I)|$ , the antecedent still holds.

### 3.2 PTAS for minimum makespan scheduling

Recall that any makespan scheduling instance  $(I, m)$  has a lower bound  $L(I) = \max\{p_{max}, \frac{1}{m} \sum_{i=1}^n p_i\}$ . We know that  $|OPT(I)| \in [L(I), 2L(I)]$ . Let  $Bin(I, t)$  be the minimum number of bins of size  $t$  that can hold all jobs. By associating job times with sizes, and scaling bin sizes up by a factor of  $t$ , we can relate  $Bin(I, t)$  to the bin packing problem. One can see that  $|OPT(I)| = \min_t \{Bin(I, t) = m\}$ , and that  $Bin(I, t)$  is monotonically decreasing. To get a  $(1 + \epsilon)$ -approximate schedule, it suffices to find a  $t \leq (1 + \epsilon) \cdot |OPT(I)|$  such that  $Bin(I, t) \leq m$ .

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**Algorithm 5** PTAS-MAKESPAN( $I = \{p_1, \dots, p_n\}, m$ )

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 $L = \max\{p_{max}, \frac{1}{m} \sum_{i=1}^n p_i\}$ 
for  $t \in \{L, L + \epsilon, L + 2\epsilon, \dots, 2L\}$  do           ▷ Binary search on  $t$  also works, but it is still poly-time
     $X \leftarrow$  Jobs with sizes  $\leq \epsilon t$                  ▷ Remaining jobs have sizes  $\in (\epsilon t, t]$ 
     $I' \leftarrow I \setminus X$                              ▷ Ignore small jobs
     $h \leftarrow \lceil \log_{1+\epsilon}(\frac{1}{\epsilon}) \rceil$            ▷ Partition  $(\epsilon t, t]$  into powers of  $(1 + \epsilon)$ :  $t\epsilon \cdot (1, (1 + \epsilon), \dots, (1 + \epsilon)^h = \epsilon^{-1}]$ 
    for  $p_i \in I'$  do
         $k \leftarrow \min_{j \in \{0, \dots, h\}} \{p_i \geq t\epsilon(1 + \epsilon)^j\}$    ▷ Find lowest power of  $(1 + \epsilon)$  for rounding down
         $p_i \leftarrow t\epsilon(1 + \epsilon)^j$                                ▷ Round down job sizes
    end for
     $P \leftarrow \mathcal{A}_\epsilon(I')$                                ▷ See Section 3.2.1 in Lecture 2 notes for  $\mathcal{A}_\epsilon$ , but with size  $t$  bins
     $\alpha(I, t, \epsilon) \leftarrow$  Use bins of size  $t(1 + \epsilon)$  to emulate  $P$            ▷ Use extra  $(1 + \epsilon)$  buffer
     $\alpha(I, t, \epsilon) \leftarrow$  Using FIRSTFIT, add items in  $X$  to  $\alpha(I, t, \epsilon)$        ▷ Handle small items
    if  $\alpha(I, t, \epsilon)$  uses  $\leq m$  bins then           ▷ Since  $|OPT(I)| \in [L, 2L]$ , this will occur at some point
        return Assign jobs to machines according to bin assignment  $\alpha(I, t, \epsilon)$ 
    end if
end for

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Given  $t$ , Algorithm 5 transforms a makespan scheduling instance into a bin packing instance, then solves for an approximate bin packing to yield an approximate scheduling. Let  $\alpha(I, t, \epsilon)$  as the number of bins used by Algorithm 5.

**Lemma 10.** For any  $t > 0$ ,  $\alpha(I, t, \epsilon) \leq Bin(I, t)$ .

*Proof.* If FIRSTFIT does not open a new bin, then  $\alpha(I, t, \epsilon) \leq Bin(I, t)$  since  $\alpha(I, t, \epsilon)$  uses additional  $(1 + \epsilon)$  buffer. If FIRSTFIT opens a new bin (say, totaling  $b$  bins), then there are at least  $(b - 1)$  produced bins from  $\mathcal{A}_\epsilon$  (exact solving on rounded down non-small items) that are more than  $(t(1 + \epsilon) - \epsilon t) = t$ -full. Hence, any bin packing algorithm must use strictly more than  $\frac{(b-1)t}{t} = b - 1$  bins.  $\square$

**Theorem 11.** PTAS-MAKESPAN is a  $(1 + \epsilon)$ -approximation for minimum makespan scheduling.

*Proof.* Let  $\min_t \{Bin(I, t) = m\} = t^*$ . By Lemma 10,  $\min_t \{\alpha(I, t, \epsilon) = m\} \leq \min_t \{Bin(I, t) = m\} = |OPT(I)|$ . But since PTAS-MAKESPAN checks for values of  $t$  that differ by  $\epsilon$ , it may terminate with  $t^* + \epsilon L$  instead. Since  $L \leq |OPT(I)|$ ,  $|PTAS-MAKESPAN(I)| \leq t^* + \epsilon L \leq (1 + \epsilon) \cdot |OPT(I)|$ .  $\square$

**Theorem 12.** PTAS-MAKESPAN is runs in  $poly(I, m)$ .

*Proof.* There are at most  $\frac{L}{\epsilon} = \max\{\frac{p_{max}}{\epsilon}, \frac{1}{m\epsilon} \sum_{i=1}^n p_i\}$  values of  $t$  to try. Filtering small jobs and rounding remaining jobs take  $\mathcal{O}(n)$ . From previous lecture,  $\mathcal{A}_\epsilon$  runs in  $\mathcal{O}(\frac{1}{\epsilon} \cdot n^{\frac{h+1}{\epsilon}})$  and FIRSTFIT runs in  $\mathcal{O}(nm)$ .  $\square$

## References

[Gra66] Ronald L Graham. Bounds for certain multiprocessing anomalies. *Bell System Technical Journal*, 45(9):1563–1581, 1966.