Estimating Lp Norms

Piotr Indyk MIT

Lecture 3

Recap/Today

- Two algorithms for estimating L_2 norm of a stream
 - A stream of updates (i,1) interpreted as

```
x_i = x_i + 1
```

(fractional and negative updates also OK)

- Algorithms maintain a linear sketch Rx, where R is a k*m (pseudo)-random matrix
- Use $||\mathbf{R}\mathbf{x}||_2^2$ to estimate $||\mathbf{x}||_2^2$
- Polylogarithmic space
- Today:
 - Yet another algorithm for L_2 estimation
 - Generalizes to any L_p , $p \in (0,2]$
 - Polylogarithmic space
 - An algorithm for L_k estimation, $k \ge 2$
 - Works only for positive updates
 - Uses sampling, not sketches
 - Space: $O(k m^{1-1/k}/\epsilon^2)$ for $(1\pm\epsilon)$ -approximation with const. probability

Median Estimator

- Again we use a linear sketch $Rx=[Z_1...Z_k]$, where each entry of R has distribution N(0,1), $k=O(1/\epsilon^2)$
 - Therefore, each of Z_i has N(0,1) distribution with variance $\sum_i x_i^2 = ||x||_2^2$
 - Alternatively, $Z_i = ||\mathbf{x}||_2 G_i$, where G_i drawn from N(0,1)
- How to estimate $||\mathbf{x}||_2$ from $Z_1...Z_k$?
- In Algorithms I, II, we used $Y = [Z_1^2 + ... + Z_k^2]/k$ to estimate $||x||_2^2$
- But there are many other estimators out there...
- E.g., we could instead use

Y=median[|Z₁|, ..., |Z_k|]/ median[|G|]

to estimate $||\mathbf{x}||_2$ (G drawn from N(0,1))

- The rationale:
 - median $[|Z_1|, ..., |Z_k|] = ||x||_2$ median $[|G_1|, ..., |G_k|]$
 - For "large enough" k , median [|G₁|, ..., |G_k |] is "close to" median[|G|] (next two slides)

* median of an <u>array</u> A of numbers is the usual number in the middle of the sorted A ** M is the median of a <u>random variable</u> U if $Pr[U \le M] = \frac{1}{2}$

Closeness in probability

- Lemma 1: Let $U_1 \dots U_k$ be i.i.d. real random variables chosen from any distribution having continuous c.d.f. F and median M
 - I.e., $F(t)=Pr[U_i < t]$ and F(M)=1/2

Define U=median $[U_1, ..., U_k]$. Then, for some absolute const. C>0

 $Pr[F(U)∈(1/2-ε,1/2+ε)]≥1-e^{-Cε^2k}$ (*)

- Proof:
 - Assume k odd (so that median well defined)
 - Consider events E_i : $F(U_i) < 1/2 \epsilon$
 - We have $p=Pr[E_i]=1/2-\epsilon$
 - $F(U) < 1/2 \epsilon$ iff at least k/2 of these events hold
 - By Chernoff bound, the probability that at least k/2 of the events hold is at most e^{-Cε2k}
 - Therefore, $\Pr[F(U) < 1/2 \varepsilon]$ is at most $e^{-C\varepsilon^2 k}$
 - The other case can be dealt with in an analogous manner



Closeness in value

• Lemma 2: Let F be c.d.f of a random variable |G|, G drawn from N(0,1). For There exists a C'>0 s.t. if for some z we have $F(z) \in (1/2-\epsilon, 1/2+\epsilon)$ then

 $z = median(g) \pm C' \epsilon$

• Proof: Calculus.



Altogether

Theorem: If we use median estimator
 Y=median[|Z₁|, ..., |Z_k]] / median[|g|]

(where $Z_j = \sum_i r_{ij} x_i$, r_{ij} chosen i.i.d. from N(0,1)), then we have

- $Y = ||x||_2 [median(g) \pm C' \epsilon] / median[|g|] = ||x||_2 (1 \pm C'' \epsilon)$ with probability 1-e^{-C\epsilon²k}
- How to extend this to $\|\mathbf{x}\|_{p}$?

Other norms

- Key property of normal distribution:
 - If U₁ ... U_k indep., U normal
 - Then $x_1U_1 + \dots + x_mU_m$ is distributed as $(x_1^{p} + \dots + x_m^{p})^{1/p}U$, p=2
- Such distributions are called "p-stable"
- Good news: p-stable distributions exist for any p∈(0,2]
- For example, for p=1, we have Cauchy distribution:
 - Density function: $f(x)=1/[\pi(1+x^2)]$
 - C.d.f.: $F(z)=\arctan(z)/\pi+1/2$
 - 1-stability: $x_1U_1 + ... + x_mU_m$ is distributed as $(|x_1|+...+|x_m|)U$



Cauchy (from Wiki)



Cauchy density functions



- The median estimator arguments go through
- Can generate random Cauchy by choosing a random u∈[0,1] and computing F⁻¹(u)

p-stability for $p\neq 1, 2, 1/2$

- Basically, it is a mess
 - No closed form formula for density/c.d.f.
 - Not clear where the median is
 - Not clear what the derivative of c.d.f. around the median is
- Nevertheless
 - Can generate random variables
 - Moments are known (more or less)
 - Given samples of a*|g|, g p-stable, can estimate a up to 1±ε [Indyk, JACM'06; Ping Li, SODA'08]
 - (using various hacks and/or moments)
- For more info on p-stable distributions, see:

V.V. Uchaikin, V.M. Zolotarev,

Chance and Stability. Stable Distributions and their Applications. <u>http://staff.ulsu.ru/uchaikin/uchzol.pdf</u>

Summary

- Maintaining L_p norm of x under updates
 - Polylogarithmic space for $p\leq 2$
- Issues ignored:
 - Randomness
 - Discretization (but everything can be done using O(log (m+n)) bit numbers)

L_k norm, k≥2

Lecture 3

L_k norm

- Algorithm for estimating L_k norm of a stream
 - A stream of elements $i_1 \dots i_n$
 - Each i can be interpreted as x_i=x_i+1 (only positive updates)
 - Space: O(m^{1-1/k}/ε²) for (1±ε)-approximation with const. probability
 - Sampling, not sketching

L_k Norm Estimation: AMS'96

- Useful notion: $F_k = \sum_{i=1}^{m} x_i^k = ||x||_k^k$ (frequency moment of the stream $i_1 \dots i_n$)
- Algorithm A: two passes
 - Pass 1: Pick a stream element i=i_j uniformly at random
 - Pass 2: Compute x_i
 - Return Y=n x_i^{k-1}
- Alternative view:
 - Little birdy that samples i and returns x_i (Sublinear-Time Algorithms class)



Analysis

- Estimator Y=n x_i^{k-1}
- Expectation

$$E[Y] = \sum_{i} x_{i}/n * nx_{i}^{k-1} = \sum_{i} x_{i}^{k} = F_{k}$$

- Second moment (≥variance)
 E[Y²]= ∑_i x_i/n * n²x_i^{2k-2} = n ∑_i x_i^{2k-1} = n F_{2k-1}
- Claim:

 $n F_{2k-1} \le m^{1-1/k} (F_k)^2$

Therefore, averaging over O(m^{1-1/k} /ε²) samples
 + Chebyshev does the job (Lecture 2)

Claim

- Claim: $n F_{2k-1} \le m^{1-1/k} (F_k)^2$
- Proof:

n F_{2k-1}

- $= n ||x||_{2k-1}^{2k-1}$
- $\leq n ||x||_{k}^{2k-1}$
- $= ||\mathbf{x}||_1 ||\mathbf{x}||_k^{2k-1}$
- $\leq m^{1-1/k} ||x||_k ||x||_k^{2k-1}$
- $= m^{1-1/k} ||\mathbf{x}||_{k}^{2k}$
- $= m^{1-1/k} F_k^2$

One Pass

- Cannot compute x_i exactly
- Instead:
 - Pick i=i, uniformly at random from the stream
 - Compute r=#occurrences of i in i_j...i_n
 - Use r instead of x_i
 - Clearly r≤x_i
 - ..but E[r]=(x_i+1)/2, so things should work out up to constant factor (depending on k)
- Even better idea: use estimator

 $Y' = n (r^k - (r-1)^k)$

Analysis

- Expectation:
 - $$\begin{split} \mathsf{E}[\mathsf{Y}'] &= n \; \mathsf{E}[(\mathsf{r}^k (\mathsf{r}\text{-}1)^k)] \\ &= n \;^* \; 1/n \; \sum_i \sum_{j=1}^{x_i} \, [j^k (j\text{-}1)^k] \\ &= \sum_i x_i^{k} \end{split}$$
- Second moment:
 - Observe that Y' = n $(r^k (r-1)^k) \le n k r^{k-1} \le k Y$
 - Therefore Var[Y'] $\leq E[Y']^2 \leq k^2 E[Y]^2 \leq k^2 m^{1-1/k} F_k^2$ (can improve to k m^{1-1/k} F_k^2 for integer k)
- Altogether:
 - One pass algorithm for F_k (positive updates)
 - Space: $O(km^{1-1/k}/\epsilon^2)$ for $(1\pm\epsilon)$ -approximation

Notes

- The analysis in AMS'96, as is, works only for integer k
 (but is easy to adapt to any k>1)
- The analysis^{*} in these notes is somewhat simpler (but yields k² m^{1-1/k} space)

^{*} Contributed by David Woodruff

Summary

- Can (1±ε)-approximate L_k norm of a stream (insertions-only) in O(m^{1-1/k} /ε²) space
- Sampling quite general
 - Entropy, i.e., ∑_i x_i /n log(x_i /n) in polylog n space
 - Other stuff