

LECTURE 17

Note Title

4/11/2012
4/10/2012

Today:

- Hilbert's Nullstellensatz

- Quantifier Elimination

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Hilbert's Nullstellensatz

- key ingredient in algebraic geometry

- Viewing system of polynomials

$$f_1(x_1 - x_n), \dots, f_m(x_1 - x_n)$$

as constraints ($f_i = 0$)

Algebraic view: $I(f_1 \dots f_m)$

Geometric view: $V(f_1 \dots f_m) = \{(a_1, \dots, a_n) \mid f_j(a) = 0 \forall j\}$

Ideal \leftrightarrow Variety Maps

- $\text{Var}(\mathcal{I}) = \left\{ \bar{a} \in \mathbb{K}^n \mid f(\bar{a}) = 0 \ \forall f \in \mathcal{I} \right\}$
- $\text{Ideal}(V) = \left\{ f \in \mathbb{K}[x_1..x_n] \mid f(\bar{a}) = 0 \ \forall \bar{a} \in V \right\}$

• If we keep taking $\text{Ideal}(\text{Var}(\text{Ideal}(\dots)))$
do we converge?

• Clearly $\text{Ideal}(\text{Var}(\mathcal{I})) \supseteq \mathcal{I}$

Actually $\text{Ideal}(\text{Var}(\mathcal{I})) \supseteq \text{Rad}(\mathcal{I})$

$$\text{Rad}(\mathcal{I}) = \left\{ f \mid \exists d \text{ s.t. } f^d \in \mathcal{I} \right\}$$

Claim: $\text{Rad}(\mathcal{I})$ is an ideal

Proof: Sufficient to prove $f, g \in \text{Rad}(\mathcal{I})$
 $\Rightarrow f+g \in \text{Rad}(\mathcal{I})$

Suppose $f^d, g^e \in I$

then $(f+g)^{d+e} \in I$



Hilbert's (strong) Nullstellensatz

Theorem: if K algebraically closed, then for

all ideals I ,

$$\underline{\text{Ideal}(\text{Variety}(I))} = \underline{\text{Rad}(I)}.$$

$$\text{In particular, } \text{Ideal}(\text{Var}(\text{Rad}(I))) = \text{Rad}(I).$$

and so process converges.

Hilbert's Weak Nullstellensatz

Theorem: If ideals $I \subseteq K[x_1 \dots x_n]$, K algebraically closed,

$$\text{Var}(I) = \emptyset \Leftrightarrow 1 \in I$$

Strong HN \Rightarrow Weak HN

• Wish to show

$$\text{Var}(I) = \emptyset \quad \& \quad \text{Ideal}(\text{Var}(I)) = \text{Rad}(I)$$

$$\Rightarrow 1 \in I$$

• Easy since $\text{Ideal}(\text{Var}(I)) = \text{Ideal}(\emptyset) \ni 1$

$$\Rightarrow 1 \in \text{Rad}(I) \Rightarrow 1^d \in I$$

$$\Rightarrow 1 \in I$$

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Weak HN \Rightarrow Strong HN

Wish to show

$$\forall J \quad \text{Var}(J) = \emptyset \Rightarrow 1 \in J$$

$$\Rightarrow f \in \text{Ideal}(\text{Var}(I)) \Rightarrow \exists d \quad f^d \in I.$$

How should we create the ideal with empty variety?

- $I \subseteq K[x_1 \dots x_n]$
- $J \subseteq K[x_1 \dots x_n, y]$
- $J = \text{Ideal}(I, 1 - y \cdot f)$
- Claim: $\text{Var}(J) = \emptyset$

$$(a_1 \dots a_n, b) \in \text{Var}(J)$$

$$\Rightarrow f(a_1 \dots a_n) = 0 \Rightarrow 1 - b \cdot 0 = 1 \neq 0$$

$$\Rightarrow (1 - y \cdot f)(a_1 \dots a_n, b) \neq 0$$

$$1 \in J \Rightarrow \exists p \in K[x_1 \dots x_n, y], q \in I$$

s.t. $1 = p \cdot (1 - y \cdot f) + q(x_1 \dots x_n, y)$

$$q = \sum_{i=0}^d y^i \cdot q_i(\bar{x}) \quad q_i \in I$$

[Rubinovich's] "trick": $y = \frac{1}{f(x_1 \dots x_n)}$

$$\Rightarrow 1 = p \cdot \left(1 - \frac{1}{f} \cdot f\right) + \sum_{i=0}^d \frac{1}{f^i} q_i(\bar{x})$$

$$\Rightarrow f^d = \sum_{i=0}^d f^{d-i} \cdot g_i(x)$$

$\in I!$

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So ... Strong & weak H-N are equivalent. Will now prove weak H.N.

Key ingredient:

Extension Lemma:

Given $I \subseteq K[x_1 \dots \underline{x_n}]$,

let $J = I \cap K[x_1 \dots \underline{x_{n-1}}]$.

If $(a_1 \dots a_{n-1}) \in \text{Variety}(J)$

$\exists a_n \in K$ st. $(a_1 \dots a_n) \in \text{Variety}(I)$

Proof of Weak H-N assuming Extension Lemma

Will show $1 \notin I \Rightarrow \exists (a_1 \dots a_n) \in \text{Var}(I)$

• Let $J = I \cap K[x_1 \dots x_{n-1}]$

- $1 \notin I \Rightarrow 1 \notin J$
- By induction $\exists (a_1 \dots a_{n-1}) \in \text{Var}(J)$
- By Extension Lemma $\exists (a_1 \dots a_n) \in \text{Var}(I)$



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Proof of Extension Lemma

Special Case: $I = I(f_1, f_2)$

$$\det R(x_1 \dots x_{n-1}) = \text{Resultant}_{x_n}(f_1, f_2)$$

Recall $R \in I$

$$\Rightarrow R \in J$$

Since $(a_1 \dots a_{n-1}) \in \text{Variety}(J)$

$$\text{we have } R(a_1 \dots a_{n-1}) = 0$$

$$\text{Now let } h_i(x_n) = f_i(a_1 \dots a_{n-1}, x_n)$$

Recalling "determinantal defn." of resultant

we have

$$\text{Res}_{x_n}(h_1, h_2) = \left. \text{Res}_{x_n}(f_1, f_2) \right|_{a_1 \dots a_{n-1}} = R(a_1 \dots a_{n-1}) = 0$$

$$\Rightarrow \exists g(x_n) \text{ s.t. } \begin{cases} g(x_n) \mid h_1(x_n) \\ g(x_n) \mid h_2(x_n) \end{cases}$$

Since \mathbb{K} is algebraically closed

$$\exists a_n \text{ s.t. } g(a_n) = 0$$

$$\Rightarrow f_1(a_1 \dots a_n) = f_2(a_1 \dots a_n) = 0$$

⊗ (Special Case)

General Case : By reduction to special case.

Let $I = I(f_1 \dots f_m) \subseteq \mathbb{K}[x_1 \dots x_n]$
 $\bar{I} = I \cap \mathbb{K}[x_1 \dots x_{n-1}] ; (a_1 \dots a_{n-1}) \in \text{Var}(\bar{I})$

Consider

$$\tilde{I} = I(f_1, F) \subseteq \mathbb{K}[x_1 \dots x_n, y_2 \dots y_m]$$

where

$$F(x_1 \dots x_n, y_2 \dots y_m) = \sum_{i=2}^m f_i(\bar{x}) \cdot y_i$$

Let $R(x_1 \dots x_{n-1}, y_2 \dots y_m) = \text{Res}_{x_n}(f_1, F)$

Claim: $R(a_1 \dots a_{n-1}, y_2 \dots y_m) = 0$

Proof: $\forall b_2 \dots b_m \in K$

$$R(x_1 \dots x_{n-1}, b_2 \dots b_m) \in \text{Jel}(f_1, F(x_1 \dots x_n, b_2 \dots b_m))$$

$$\in \text{Ideal}(f_1 \dots f_m) = I$$

$$\Rightarrow R(x_1 \dots x_{n-1}, b_2 \dots b_m) \in J$$

$$\Rightarrow R(a_1 \dots a_{n-1}, b_2 \dots b_m) = 0$$

$$\Rightarrow R(a_1 \dots a_{n-1}, y_2 \dots y_m) = 0$$

◻ (Claim)

Now, viewing $f_1, F \in L[x_1 \dots x_n]$

where $L = \overline{K(y_2 \dots y_m)}$ (algebraic closure
of $K(y_2 \dots y_m)$)

we have

$$f_i(a_1 \dots a_{n-1}, x_n) \in F(a_1 \dots a_{n-1}, x_n)$$

share a common root $a_n \in L$

But all roots of f_i are in K

so $a_n \in K$

$$(x_n - a_n) \mid f_i(a_1 \dots a_{n-1}, x_n)$$

$$\Delta (x_n - a_n) \mid \sum y_i f_i(a_1 \dots a_{n-1}, x_n)$$

$$\Rightarrow (x_n - a_n) \mid f_i(a_1 \dots a_{n-1}, x_n) \quad \forall i$$

$$(a_1 \dots a_n) \in \text{Var}(\mathcal{I})$$



Comments on degree bounds

if $f_1 \dots f_m$ have $\deg \leq d$,

& $\exists q_1 \dots q_m$ s.t. $1 = \sum f_i q_i$

then what is degree bound on q_i ?

[Hermann]: $\deg(q_i) \leq (mdn)^{O(n)}$

[Brownawell '87]: $\deg(q_i) \leq (md)^n$

using complex analysis

[Kollar '88] " using cohomology

[Dube '92] " elementary commutative algebra

Quantifier Elimination

Example: $\forall x_1 \dots x_n \exists y_1 \dots y_n$ s.t.

[2nd Level]

$$\phi_1(x_1 \dots x_n, y_1 \dots y_n) = 0$$

$$\phi_2(\quad) = 0$$

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$$\phi_m(\quad) = 0 ?$$

Main Result of area

Such problems can also be solved ...
("efficiently")

Insight

Fix $x_1 \dots x_n$ to $a_1 \dots a_n$

- Now, we have standard HN.
- Can ask, if $q_1 \dots q_m$ exist
- Can find them if they exist by solving big linear system.
- Entries of matrix are polynomials in $x_1 \dots x_n$.
- Solution exists if some determinants are non-zero & others are zero.
- Solution exists if some system of poly constraints always has a zero!
- But these are equations only in $x_1 \dots x_n$!
- We have eliminated one quantifier.

