### **Semantic Goal-Oriented Communication**

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### Disclaimers

Work in progress (for ever) ...

Feedback welcome.

Interruptions welcome during the talk.

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... Alas, no algebra 🙁
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### The Meaning of Bits



What if Alice is trying to send instructions?

- Aka, an algorithm
- Does Bob understand the correct algorithm?
- What if Alice and Bob speak in different (programming) languages?

### Miscommunication (in practice)

- Exchanging (powerpoint) slides.
  - Don't render identically on different laptops.
- Printing on new printer.
  - User needs to "learn" the new printer, even though printer is quite "intelligent".
- Many such examples ...
  - In all cases, sending bits is insufficient.
  - Notion of meaning ... intuitively clear.
  - But can it be formalized?
    - Specifically? Generically?
    - While conforming to our intuition

### Bits vs. their meaning

- Say, User and Server know different programming languages. Server wishes to send an algorithm A to User.
  - A = sequence of bits ... (relative to prog. language)
- Bad News: Can't be done
  - For every User, there exist algorithms A and A', and Servers S and S' such that S sending A is indistinguishable (to User) from S' sending A'
- Good News: Need not be done.
  - From Bob's perspective, if A and A' are indistinguishable, then they are equally useful to him.

### What should be communicated? Why?

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### **Part I: Computational Motivation**

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### **Computational Goal for Bob**

- Why does User want to learn algorithm?

### Setup



Computes  $P(x,R,a_1,...,a_k)$ Hopefully P(x,...) = f(x)!

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### **Intelligence & Cooperation?**

- For User to have a non-trivial interaction, Server must be:
  - Intelligent: Capable of computing f(x).
  - Cooperative: Must communicate this to User.
- Formally:
  - Server S is f-<u>helpful</u> if
    - ∃ some (other) user U' s.t.

 $\forall x, \text{ starting states } \sigma \text{ of the server}$ (U'(x)  $\leftrightarrow$  S( $\sigma$ )) outputs f(x)

### Successful universal communication

- Universality: Universal User U should be able to talk to any (every) f-helpful server S to compute f.
- Formally:
  U is f-universal, if
  ∀ f-helpful S, ∀ σ, ∀ x
  (U(x) ↔ S(σ)) = f(x) (w.h.p.)
- What happens if S is not helpful?
  - Paranoid view ⇒ output "f(x)" or "?"
  - Benign view  $\Rightarrow$  Don't care (everyone is helpful)

### Main Theorems [Juba & S. '08]

- If f is PSPACE-complete, then there exists a funiversal user who runs in probabilistic polynomial time.
  - Extends to checkable ("compIP") problems
    - (NP  $\cap$  co-NP, breaking cryptosystems)
    - S not helpful ⇒ output is safe

- Conversely, if there exists a f-universal user, then f is PSPACE-computable (in "compIP")
  - Scope of computation by communication is limited by misunderstanding (alone).

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### Proofs?

### Positive result:

- $f \in PSPACE \Rightarrow$  membership is verifiable.
- User can make hypothesis about what the Server is saying, and use membership proof to be convinced answer is right, or hypothesis is wrong. <u>Enumerate</u>, till hypothesis is right.

### Negative result:

- In the absence of proofs, sufficiently rich class of users allow arbitrary initial behavior, including erroneous ones.
- (Only leads to finitely many errors ...)

### Implications

Communication is not unboundedly helpful S

- If it were, should have been able to solve every problem (not just (PSPACE) computable ones).
- But there is gain in communication:
  - Can solve more complex problems than on one's own, but not every such problem.
- Resolving misunderstanding? Learning Language?
  - Formally No! No such guarantee.
  - Functionally Yes! If not, how can user solve such hard problems?

### **Principal Criticisms**

- Solution is no good.
  - Enumerating hypotheses is too slow.
    - Approach distinguishes right/wrong; does not solve search problem.
    - Search problem <u>needs</u> new definitions to allow better efficiency.
- Problem is not the right one.
  - Computation is not the goal of communication. Who wants to talk to a PSPACE-complete server?

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### Part II: Generic Goals of Communication

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### Aside: Communication?

Classical "Theory of Computing"

$$X \longrightarrow F \longrightarrow F(X)$$

Issues: Time/Space on DFA? Turing machines?



 Issues: Reliability, Security, Privacy, Agreement?
 If communication is so problematic, then why not "Just say NO!"?

### **Communication: Example 1 (Printing)**



### **Communication: Ex. 2 (Computation)**

![](_page_17_Figure_1.jpeg)

# **Communication: Ex. 3 (Web search)** WWW Ρ $Q(WWW(P)) = \bigcirc?$

### **Communication: Ex. 4 (Intelligence?)**

![](_page_19_Picture_1.jpeg)

### **Aside: Modelling Computing**

Classically: Turing Machine/(von Neumann) RAM.

Described most computers being built?

![](_page_20_Figure_3.jpeg)

 Modern computers: more into communication than computing.

- What is the mathematical model of a communicating computer?
- What is universality?

### **Communication: Ex. 2 (Computation)**

![](_page_21_Figure_1.jpeg)

![](_page_22_Figure_0.jpeg)

### Modelling User/Interacting agents

- (standard AI model)
- User has state and input/output wires.
  - Defined by the map from current state and input signals to new state and output signals.

![](_page_23_Figure_4.jpeg)

### **Generic Goal?**

![](_page_24_Figure_1.jpeg)

### Goal = function of ?

- User? But user wishes to change actions to achieve universality!
- Server? But server also may change behaviour to be helpful!
- Transcript of interaction? How do we account for the many different languages?

### **Generic Goals**

- Key Idea: Introduce 3rd entity: Referee
  - Poses tasks to user.
  - Judges success.

![](_page_25_Figure_4.jpeg)

- Referee (just another agent)
- Boolean Function determining if the state evolution of the referee reflects successful achievement of goal.

User

Class of users/servers.

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Server

**Referee/Environment** 

### **Generic Goals**

Pure Control

![](_page_26_Picture_2.jpeg)

Pure Informational

![](_page_26_Figure_4.jpeg)

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### **Sensing & Universality**

- To achieve goal, User should be able to sense progress.
  - I.e., user should be compute a function that (possibly with some delay, errors) reflects achievement of goals.
- Generalization of positive result:
  - Generic goals (with technical conditions) universally achievable if 3 sensing function.
- Generalization of negative result:
  - Sensing is necessary (in one-shot goals)
  - (In infinite goals, If non-trivial generic goal is achieved with sufficiently rich class of helpful servers, then it is safely achieved with every server.)

### Conclusions

Is there a universal communication protocol?

- No! (All functions vs. PSPACE-computable functions).
- But can achieve "sensible" goals universally.
- But ... diversity of goals may be the barrier to universality.
- Goals of communication.
  - Should be studied more.
  - Suggests good heuristics for protocol design:
    - Server = Helpful?
    - User = Sensing?

### Language Learning

Meaning = end effect of communication.

- [Dewey 1920s, Wittgenstein 1950s]
- What would make learning more efficient?
  - What assumptions about "language"?
  - How to do encapsulate it as "class" restrictions on users/servers.
  - What learning procedures are efficient?

Time to get back to meaningful conversation!

### References

# Juba & S. ECCC TR07-084: <u>http://eccc.uni-trier.de/report/2007/084/</u>

## Goldreich, Juba & S. ECCC TR09-075: <u>http://eccc.uni-trier.de/report/2009/075/</u>

### **Thank You!**

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