

# Efficient Semantic Communication & Compatible Beliefs

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Based on joint works with:  
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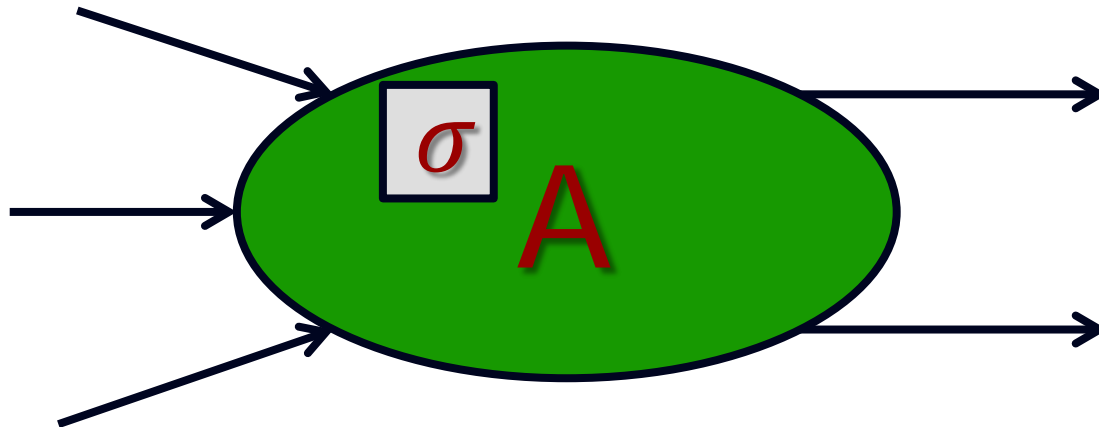
# **Part I: Background on Semantic Communication**

# Semantic Communication: Motivation

- First era of communication: Reliable Wires
  - Essentially done: wires are very reliable; performance can be enhanced (maybe) quantitatively but not qualitatively.
- Can we get endpoints to also be reliable?
  - Modern systems have "smart" endpoints.
  - Smart implies capability.
  - Smart implies diversity.
    - But diversity implies (potential) misunderstanding.
- Semantic Communication [Goldreich, Juba+S '10]
  - Detect/Correct Misunderstanding.

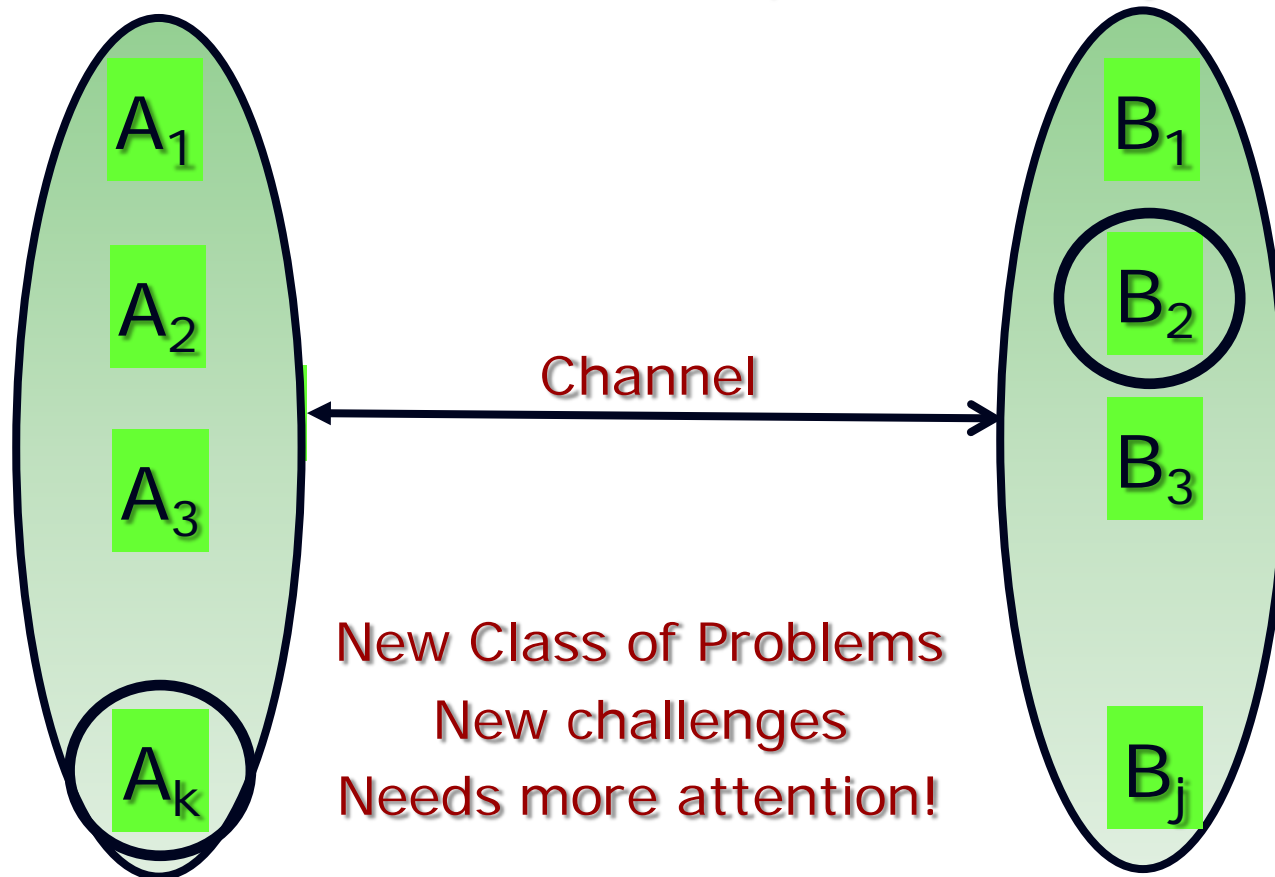
# Semantic Communication: Model - I

- General Model: Two "smart" interacting agents: User and Server; User wishes to accomplish some Goal, and Server is trying to help User.
- Interacting agents?
  - Agent: State  $\times$  Inputs  $\rightarrow$  New State  $\times$  Outputs



# Semantic Communication: Model - II

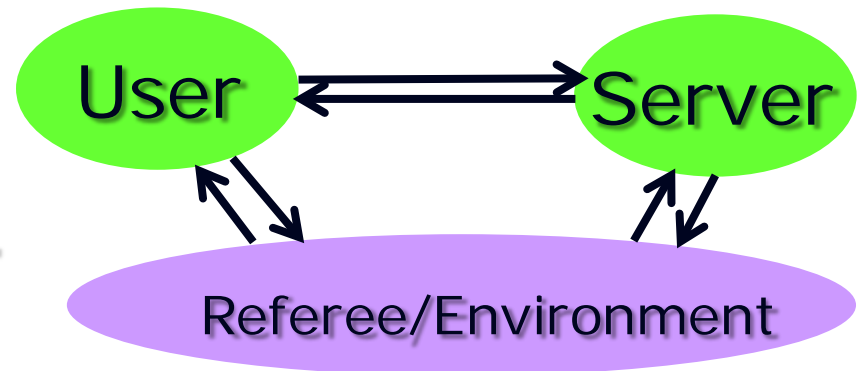
- Uncertainty about the receiver:  
(User doesn't know server; vice versa).



# Semantic Communication: Model - IIIa

- Goal-oriented communication:
  - User attempting to reach some goal.
  - How to model this?
- Classical approaches:
  - Some function of state of user, or some function of transcript of interaction etc.
  - Fails in “semantic/uncertainty” setting.
- Our [GJS] approach: Introduce a (hypothetical) third agent.

# Semantic Communication: Model - IIIb



- Referee
  - Poses tasks to user.
  - Judges success.
- Generic Goal specified by  $(R, B, \check{U}, \check{S})$ 
  - $R$  = Referee (just another agent)
  - $B$  = Boolean Function determining if the state evolution of the referee reflects successful achievement of goal.
  - $\check{U}, \check{S}$  = Class of users/servers.
  - (All finitely specified)u
- Which goals can be achieved universally?

# Basic Definitions:

## Helpfulness, Universality, Sensing

- What makes a server helpful?
  - S is G-helpful, if there exists a user who can achieve goal (efficiently) for every starting state of S.
- Universality:
  - User U is universal if it achieves G with every G-helpful server.
- Sensing?
  - Roughly, Goal G can be sensed if there exists an efficient algorithm that scan use (with their inputs) to see if Referee will accept.



# Principal Thesis and Theorem

- Thesis: Every Goal of communication captured in our model (by appropriate choice of  $(R, B, \check{U}, \check{S})$ )
- Theorem: Goal is universally achievable if and only if there exists a sensing function (for "one-shot" goals).

# Proof + Insights

- Positive results by enumeration.
- Negative? Mostly by definition.
- Insights:
  - Servers should know how to be “interrupted”.  
(How else can they function independent of complexity of their own state?)
  - Short “interrupt” signal helps.
  - Goals should be “sense”ible.

## **Part II: Beliefs & Compatibility**

# Motivation

- Why does natural (human) communication differ so much from designed communication?
  - Languages are ambiguous
  - They violate their own grammatical rules
  - They are needlessly redundant at times, and noisily compressed at other times?
- Can we use information theory to explain such phenomena (departures from information theory)?
  - Use fact that natural communication deals with uncertainty about server.

# Does Semantic Communication help?

## ■ Pros:

- Does deal with uncertainty about servers.

## ■ Cons:

- Seems quite inefficient (user is enumerating all servers?).
- Seems to throw away all "knowledge" about server (that might yield efficiency).
- Is universality really a goal? Is it not at odds with "use of knowledge"

# Beliefs in Semantic Communication

- Addition to the model, to include beliefs of user and server.
- Each server and user has associated belief.
- Belief of Server  $S = D_S =$  Distribution on Users
- Belief of User  $U = D_U =$  Distribution on Servers
- Compatibility?

# Compatibility of Beliefs

- For user  $U$ , Consider the distribution  $\bar{D}_U$  on users obtained as follows:
  - Sample Server  $S'$  from distribution  $D_U$
  - Sample user  $U'$  from distribution  $D_{S'}$
- Compatibility of user  $U$  with server  $S$ :
  - Measured by "proximity" of  $\bar{D}_U$  with  $D_S$
  - Our choice:  $U$  is  $\alpha$ -compatible with  $S$  if

$$1 - \frac{1}{2} |\bar{D}_U - D_S|_1 \geq \alpha$$

# Server Performance?

- What does it mean that server has a belief about users? How is it reflected in server's actions?
- Performance of server  $S$  (roughly) for goal  $G$   
=  $\text{Perf}_G(S)$   
= Expected time that user  $U$  chosen from distribution  $D_S$  takes to achieve goal  $G$ .
- Well-designed server should be "broad-minded" i.e., efficient against a broad distribution of users.



# Universality of Users under Beliefs

- Universal User  $U$  now has beliefs on servers.
- Can expect user to do well not only on servers in the support of its beliefs, but a potentially broader set: namely servers with compatible beliefs.
- Theorem [Juba, S '11]:  $\forall U, \exists$  a universal user  $U'$  with same beliefs as  $U$ , whose time to achieve goal  $G$  with server  $S$  is  $\frac{O(1)}{\alpha(U,S)} \text{Perf}_G(S)$ , provided the goal allows universal users.

# Consequences/Conclusions

- Universality of communication is not at odds with efficiency.
- Efficiency comes with compatibility of communicating players.
- Universality takes care of possibility of misunderstanding, at an affordable price.

**Thank You**