

Lecture Notes for $O(\lg n)$ -Competitive BSTs

- Recap:
- Binary Search Tree (BST) model
 - consider a set S of $|S|=n$ ordered elements
let $S = \{1, \dots, n\}$ for concreteness
 - must maintain a dynamic BST with elements in S
 - ↳ can be changed thru rotations
 - only operation: $\text{search}(x)$, where $x \in S$
Cost = Running Time = #nodes touched by search
+ #rotations performed
 - Goals: → given a sequence $\bar{x} = (x_1, \dots, x_m)$, find $\text{OPT}(\bar{x}) =$
= optimal cost to run $\text{search}(x_1), \dots, \text{search}(x_m)$ in BST model/
Examples: $\text{OPT}(1, 2, \dots, n) = \Theta(n)$
 $\mathbb{E}[\text{OPT}(\bar{x})] = \Omega(m \lg n)$ for random $\bar{x} \in [n]^m$
Wanted: d -approximation algorithm
 - sequence $\bar{x}$ revealed online (x_1 , then x_2 , then $x_3, \dots$)
Wanted: d -competitive algorithm (compared to offline $\text{OPT}(\bar{x})$)

Why?

"All Pairs Shortest Paths should take $O(n^3)$, but on my company's graphs my optimized algorithm runs much faster"
"This problem is NP-complete, but this optimized backtracking solves it very well on my practical instances"

We'll pick a very simple problem where we understand the worst-case well
(BSTs)

Can we understand the "difficulty" of each particular instance?

Results:

- $O(\lg n)$ -competitive = trivial
 - Tango-trees: $O(\lg \lg n)$ competitive, $O(\lg \lg n)$ approximation (best known even offline)
 - Conjecture: splay trees $O(1)$ -competitive [Sleator Tarjan '83]
 - Conjecture: a greedy algorithm is $O(1)$ -approx [Lucas '88] [Munro '00]
- If so $\Rightarrow \exists$ online $O(1)$ -competitive [DHKP '09]

How to prove approximation / competitive ratios:

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compare upper bound with lower bound

↳ often value of linear program, etc

Here: lower bound = lower bound on computation

Wilber I

[Wilber '86]

- plot sequence $\bar{x}$ on time/value diagram
- build a tree over values $\leadsto$ "lower bound tree" (arbitrary, static)
- "interleave thru a node" = switching from left subtree $\rightarrow$ right subtree

$$\text{Lower bound} = \sum_{\text{all nodes}} (\# \text{interleaves})$$

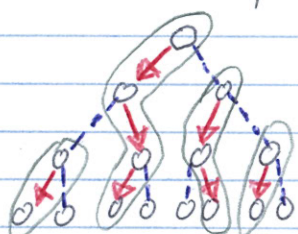
See Fig 1
next page

Proof: later

Tango trees

$$\text{Cost} = (\text{Wilber I}) \times O(\lg \lg n)$$

Each node has a preferred ~~child~~ ^{child} (where most recent access happened)



↓ = preferred child

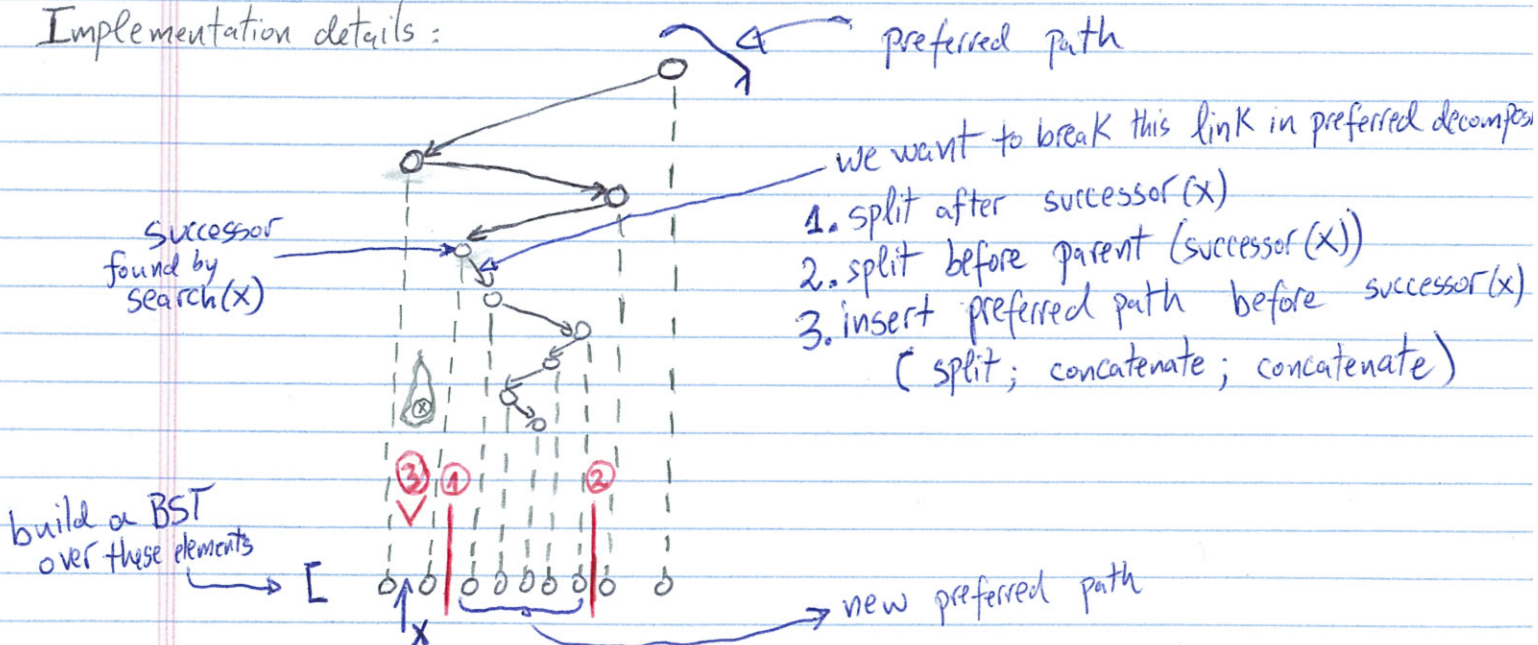
- - - = other child

↪ = preferred path

"Preferred path decomposition" of the lower bound tree

1. Lower bound tree = perfect binary tree
2. Maintain each preferred path as dynamic BST (red-black tree / AVL / splay tree / etc)
 - { Preferred path has $\leq \lg n$ nodes $\Rightarrow O(\lg \lg n)$ time / operation
 - { # preferred paths visited = Wilber I

Implementation details:



Proof of Wilber I ~ a lower bound on computation

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Conceptual shift: what are BSTs useful for?

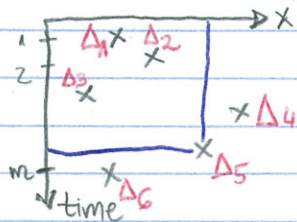
→ searching for elements? maybe, but not really optimal (think hashing, etc)

→ augmented BSTs maintain aggregates!

Partial-sums problem: given array $A[1..n]$ { • update(i, Δ): change $A[i] = \Delta$
• query(i): return $\sum_{j=1}^i A[j]$

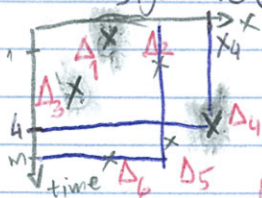
Computational model: let S = arbitrary semigroup
each $A[i] \in S$; machine memory stores $\text{Mem}[i] \in S$
Cost = # semigroup additions performed

Given $\bar{X} = (x_1, \dots, x_m)$ Execute: update(x_1, Δ_1), query(x_1); update(x_2, Δ_2), query(x_2); ...
BSTs support these $2m$ operations in $O(\text{OPT}(\bar{X}))$ cost (additions)



the answer to query(x_5) is $\Delta_1 + \Delta_2 + \Delta_3 + \Delta_5$

Signatures: Each memory location looks like $\text{Mem}[a] = \Delta_{i_1} + \Delta_{i_2} + \dots$
Signature($\text{Mem}[a]$) is $(\star, \star) = (\max\{i_1, i_2, \dots\}, \max\{\Delta_{i_1}, \Delta_{i_2}, \dots\})$



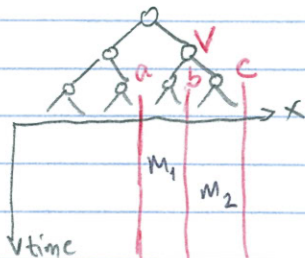
if $\text{Mem}[17] = \Delta_1 + \Delta_3 + \Delta_4 \Rightarrow \text{Signature}(\text{Mem}[17]) = (4, \Delta_4)$

better example: $\text{Mem}[13] = \Delta_1 + \Delta_6 + \Delta_2 \Rightarrow \text{Signature}(\text{Mem}[13]) = (6, \Delta_2)$

Observation: Signatures move down-right when adding elements

Wilber I: for each node $v \in$ lowerbound tree, let

$A(v) = \{ \text{all additions } "m_1 + m_2" \text{ with } \left. \begin{array}{l} \text{signature}(m_1) \in [a, b] \times [1, m] \\ \text{signature}(m_2) \in [b, c] \times [1, m] \end{array} \right\}$



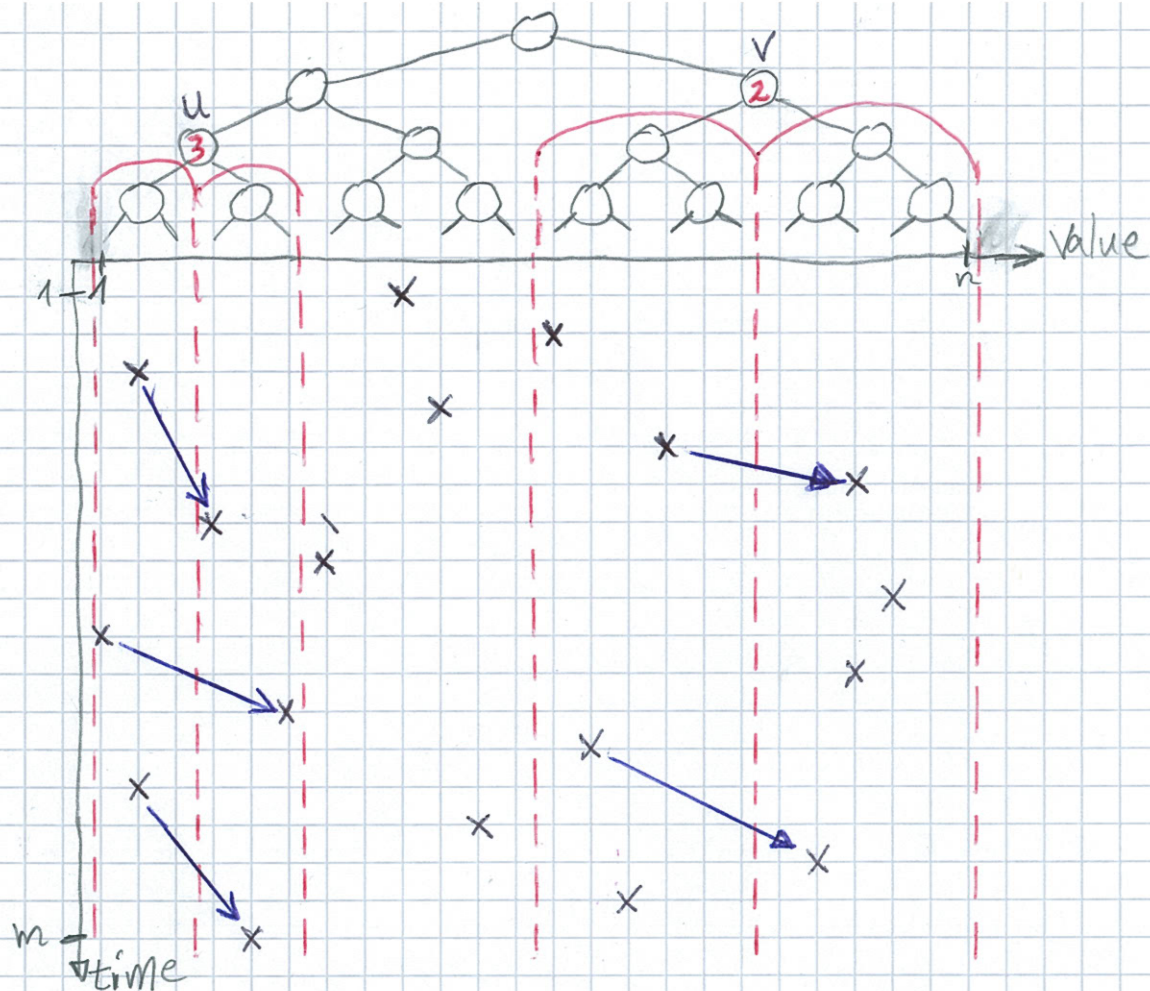
$A(v)$ for all v is a partition of all additions executed by code
 $\Rightarrow \text{cost} = \sum_v |A(v)|$ because v = lowest common ancestor

mma: $\forall v, |A(v)| \geq \# \text{interleaves through node } v$

Proof by picture: Fig 2

conclusion: $\text{Cost} \geq \sum_v \# \text{interleaves through } v$

Fig 1



"X" mark access sequence $(x_1, \dots, x_m)$

there are 3 interleaves through u ; 2 interleaves through v

Fig 2

