On Dynamic Range Reporting in One Dimension

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Range Reporting in 1D

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Maintain a set S, |S| = n, under:

INSERT(x): S \leftarrow S \cup \{x\}

DELETE(x): S \leftarrow S \setminus \{x\}

REPORT(a, b): return S \cap [a, b]
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Maintain a set S, |S| = n, under: INSERT(x): $S \leftarrow S \cup \{x\}$ DELETE(x): $S \leftarrow S \setminus \{x\}$ REPORT(a, b): return $S \cap [a, b]$

Model: Word RAM, *w*-bit words $S \subset \{0, \dots, 2^w - 1\}$

A (1) > A (1) > A

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Alternative query

FINDANY(a, b): return any $y \in S \cap [a, b]$, or EMPTY

Updates maintain *S* in sorted order. Then, just scan left or right starting with *y*.

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Search Problems

Exact Search MEMBER(x) : is $x \in S$?

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Predecessor Search PRED(x) : return max{ $y \in S | y \le x$ }

Exact Search MEMBER(x) : is $x \in S$?

Predecessor Search

 $\mathsf{PRED}(x): \mathsf{return} \max\{y \in \mathsf{S} \mid y \leq x\}$

 \Downarrow PRED(b)

Range Reporting in 1D

FINDANY(a, b): return any $y \in S \cap [a, b]$

 \Downarrow FINDANY(x, x)

Exact Search

 $\mathsf{MEMBER}(x):\mathsf{is}\;x\in\mathsf{S?}$

Search Problems

Range Reporting in 2D

 $\mathsf{EMPTY}([a,b]\times[c,d]):\mathsf{is}\ \mathsf{S}\cap([a,b]\times[c,d])=\emptyset?$

 \Downarrow "colored predecessor problem"

Predecessor Search

PRED(x) : return max{ $y \in S \mid y \leq x$ }

 \Downarrow PRED(b)

Range Reporting in 1D

FINDANY(a, b) : return any $y \in S \cap [a, b]$

 \Downarrow FINDANY(x, x)

Exact Search

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Predecessor search:

 $\Omega(\frac{\lg w}{\lg \lg w})$ per query, even statically $O(\lg w)$ per query/update: van Emde Boas recursion.

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Static range reporting \mathcal{MAGIC} :

- O(1) query [MNSW STOC'95]
- ... and *O*(*n*) space [ABR STOC'01]

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Dynamize these solutions \Rightarrow tradeoff:

- $O(w^{\varepsilon})$ per update, O(1) per query
- O(lg w) per update, O(lg w) per query
 Not so magical: converges to van Emde Boas.

A (1) > A (1) > A

Dynamic \mathcal{MAGIC}

We achieve:

- O(lg w) updates
- O(lg lg w) queries

• O(n) space

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exponential improvement over van Emde Boas in terms of universe size u, this is $O(\lg \lg \lg u)$

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A (10) N (10)

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- $\mathcal{MAGICAL}$ ingredients:
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 - new, subtle recursion idea
 - dynamic perfect hashing in sublinear space

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Interpret integers at different levels of detail.

- van Emde Boas examines levels of detail sequentially
- we do a binary search on the levels of detail

What are we searching for?



Interpret S as paths in trie of height $w \Rightarrow n-1$ branching nodes

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4 interesting values per branching node

What are we searching for?



findany(*a*, *b*

- compute LCA(a, b)
- find lowest branching ancestor of the LCA
- check if any extreme point is in [a, b]

(A) < (A)

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Happens only when $S \cap [a, b] = \emptyset$ \Rightarrow witness verification catches the error



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• at level *L*, must have branching immediately above



Then, *w* holds pointer to lowest branching ancestor. Nice, but can we update?

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- so ancestor in same "triangle" as w on level L



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Space: $O(\lg w)$ pointers to O(n) branching nodes But can encode as level pointers: $O(\lg w)$ bits each $\Rightarrow O(n \lg^2 w)$ bits of "real information" = o(n) words.

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Bloomier filters:

- store vector A[1..U] of r-bit values
- only $N \ll U$ nonzero positions

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$$N = O(n \lg w), U = O(2^w), r = O(\lg w)$$

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Bloomier filters:

- store vector A[1..U] of r-bit values
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Space lower bound: $\sim N(r + \lg U)$ bits $\sim N$ words.

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Allow one-sided error:

- if $A[i] \neq 0$, answer must be correct
- if A[i] = 0, answer can be wrong

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Low-Space Structures

First sublinear-space solution to dynamic Bloomier filters: $O(n(r + \lg \lg u))$ bits

Via first sublinear-space solution to dynamic perfect hashing

We prove matching lower bounds improves [CKRT – SODA'04]

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Story Time

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Story Time

THE END

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