

## Lecture #10

Last Time: Min Cost Flow and Goldberg-Tarjan

↑  
augment along cycle of min mean cost

remember:  
fixed part of  
Lemmas 3

Today: Introduction to Linear Programs

Many examples so far of pattern

optimization problem  $\longleftrightarrow$  certificate of optimality

max flow  $\longleftrightarrow$  min cut

min cost flow  $\longleftrightarrow$  potentials with nonnegative reduced costs

Many more examples in combinatorial optimization,  
most derived from linear programming:

Canonical form

$$(P) \quad \max c^T x$$

$$\text{s.t. } Ax \leq b$$

$$x \geq 0$$

$$(D) \quad \min y^T b$$

$$\text{s.t. } y^T A \geq c^T$$

$$y \geq 0$$

Here " $\leq$ " is a component wise constraint

We say that  $x$  is feasible if it meets constraints in (P), similarly for  $y$ .

weak duality

Lemma: If  $x$  and  $y$  are feasible then  $c^T x \leq y^T b$

Proof: Using that  $x \geq 0$  and  $y^T A \geq c^T$  we have

$$y^T A x \geq c^T x$$

Now using that  $Ax \leq b$  and  $y \geq 0$  we have

$$y^T A x \leq y^T b$$

Combining inequalities completes proof  $\square$

Let's apply this to max flow. Let  $\mathcal{P}_{s,t}$  be all  $s$ - $t$  paths in  $G$ .

$$\max \sum_{p \in \mathcal{P}_{s,t}} x_p$$

$$\text{st. } \sum_{\substack{p \in \mathcal{P}_{s,t} \\ p \ni e}} x_p \leq u(e)$$

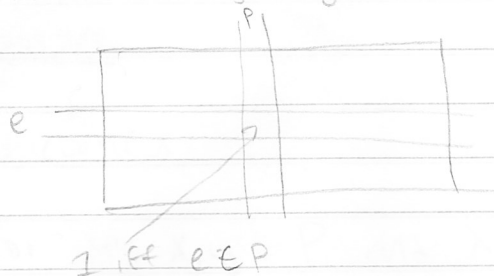
$$x_p \geq 0$$

$$\min \sum_e u(e) y(e)$$

$$\text{st. } \sum_{e \in p} y(e) \geq 1 \quad \forall p \in \mathcal{P}_{s,t}$$

$$y(e) \geq 0$$

Here  $A$  is the edge-by-path matrix



How is an  $s$ - $t$  cut a feasible solution to the dual? (let  $e = (u,v)$ )

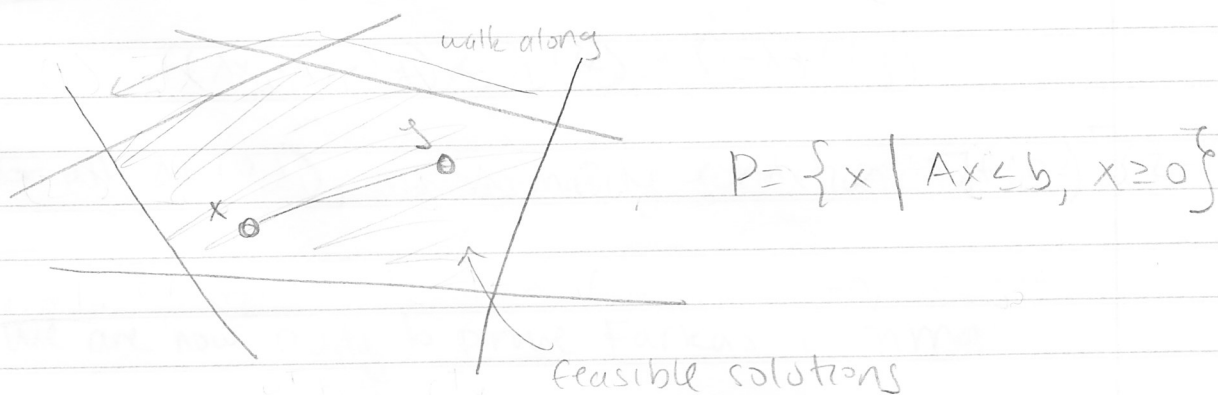
$$\text{let } y(e) = \begin{cases} 1 & \text{if } u \in S, v \in V \setminus S \\ 0 & \text{else} \end{cases}$$

Then  $\sum_{e \in P} y(e) \geq 1$   $\forall P \in \mathcal{P}_{s,t}$ , because the  $s$ - $t$  path must cross at least one  $y(e)=1$  edge

Moreover  $\sum_e y(e) u(e) = \text{cap}(S, V \setminus S)$

In fact, duality gives us a more general way to prove c.b.s. via Fractional cuts, but we do not need them here

Let's draw a picture:



We call a finite intersection of halfspaces a polyhedron

It is convex:

for any  $x, y \in P$  and  $\lambda \in [0, 1]$  we have

$$\lambda x + (1-\lambda)y \in P$$

basic feasible soln  $\equiv$  vertex  $\equiv$  extreme point

$\uparrow$  intersection of  $n$  tight constraints    
 $\uparrow$  not convex combination of  $x$  &  $y$     
 $\uparrow$  unique optimal solution in some direction

## projection thm

Thm, If  $P$  is a nonempty, closed convex set then

(1) For any  $b$ , there is a unique minimizer to

$$f(z) = \|z - b\|^2$$

over  $P$ . Call the optimal <sup>point</sup> - the projection  $p = \text{proj}_P(b)$

(2)  $p$  is the projection of  $b$  iff

$$(z - p)^T (b - p) \leq 0 \quad \forall z \in P$$

go back to picture

Idea: Follows from fact that  $f(z)$  is strictly convex:

$$f(\lambda x + (1-\lambda)y) < \lambda f(x) + (1-\lambda)f(y)$$

for all  $\lambda \in (0,1)$ , <sup>and</sup>  $x \neq y$ , and optimality condition  $\nabla f(p)^T (z - p) \geq 0$

We are now ready to prove Farkas' Lemma:

Lemma: Exactly one of the following holds

(1)  $\exists x$  s.t.  $Ax = b, x \geq 0$

(2)  $\exists y$  s.t.  $y^T A \geq 0$  and  $y^T b < 0$

↖ another duality pair "standard form"

Proof: If both (1) and (2) hold set  $c = 0$ .

Then  $y^T b < c^T x$ , but since  $x$  and  $y$  are

feasible, this violates weak duality for "standard form"

Now assume  $\nexists x$  that satisfies (1). We will construct  $y$  that satisfies (2)

Let  $P = \{Ax \text{ st. } x \geq 0\}$ , by assumption  $b \notin P$   
since  $p \in P$

Let  $p = \text{Proj}_P(b)$ ,  $p = Ax$  for  $x \geq 0$  and  $y = p - b$

claim #1  $y^T A \geq 0$

Proof: Projection thm  $\Rightarrow (z - p)^T (b - p) \leq 0 \quad \forall z \in P$

Let  $z = A(x + e_i)$ , then  
 $i^{\text{th}}$  standard basis vector

$$\begin{aligned}(z - p)^T (b - p) &= (A(x + e_i) - Ax)^T (b - p) \\ &= e_i^T A^T (b - p) \leq 0\end{aligned}$$

This is equivalent to  $e_i^T A^T y \geq 0$ , and this holds for all  $i$ .  $\square$

claim #2  $b^T y < 0$

Proof:  $b^T y = (p - y)^T y = p^T y - y^T y$

Now  $0 \in P$ , then again by projection thm

$$(z - p)^T (b - p) = \underbrace{-y^T}_{-y} (b - p) = -p^T y \leq 0$$

And since  $y^T y > 0$ , we're done  $\square$

This establishes both constraints in (2).  $\square$

There are many equivalent formulations

$$(1'') \quad [A, -A, I] \begin{bmatrix} x^+ \\ x^- \\ s \end{bmatrix} = b, \quad \begin{bmatrix} x^+ \\ x^- \\ s \end{bmatrix} \geq 0$$

This is a system of inequalities as in (1),  
equivalent to

unconstrained  
↓  
 $Ax \leq b$

Thus Farkas' Lemma yields that exactly one  
of (1') and

$$(2') \quad y^T [A \ -A \ I] \geq 0, \quad y^T b < 0$$

holds. Moreover (2') is equivalent to

$$y^T A = 0, \quad y \geq 0 \quad \text{and} \quad y^T b < 0$$

Lemma: <sup>alternate Farkas'</sup> Exactly one of the following conditions  
holds

$$(1') \quad \exists x \text{ s.t. } Ax \leq b$$

$$(2') \quad \exists y \text{ s.t. } y^T A = 0, \quad y \geq 0 \quad \text{and} \quad y^T b < 0$$