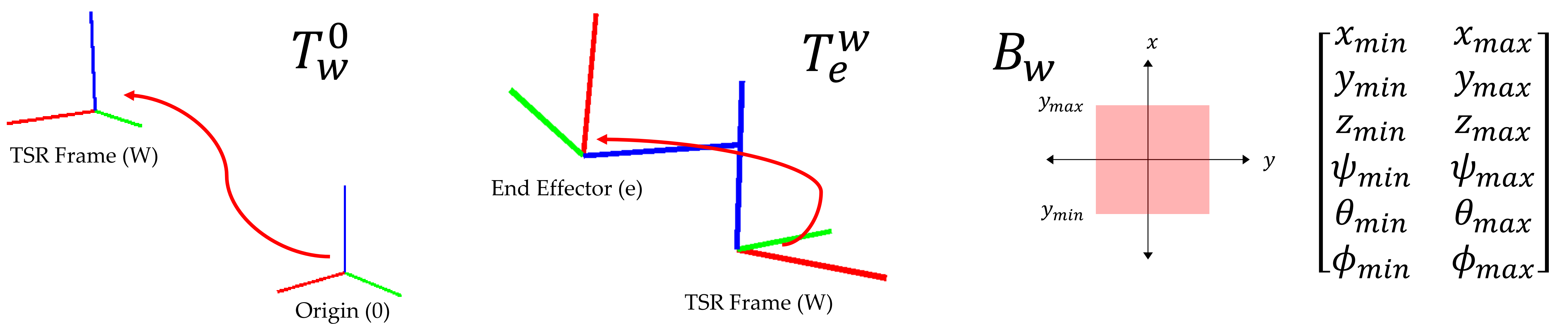


Gestures as a Communication Modality

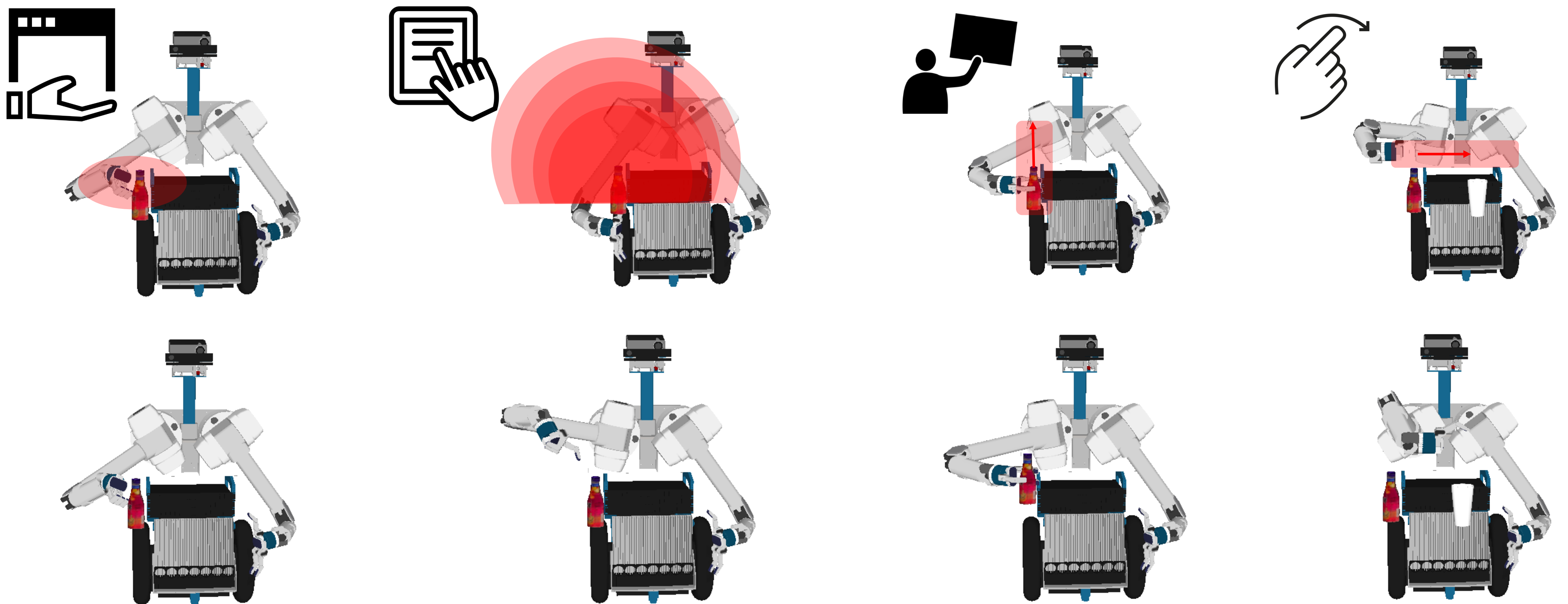


Key Insight: Generalize gestures as *task-space constraints* on the trajectory and goal.

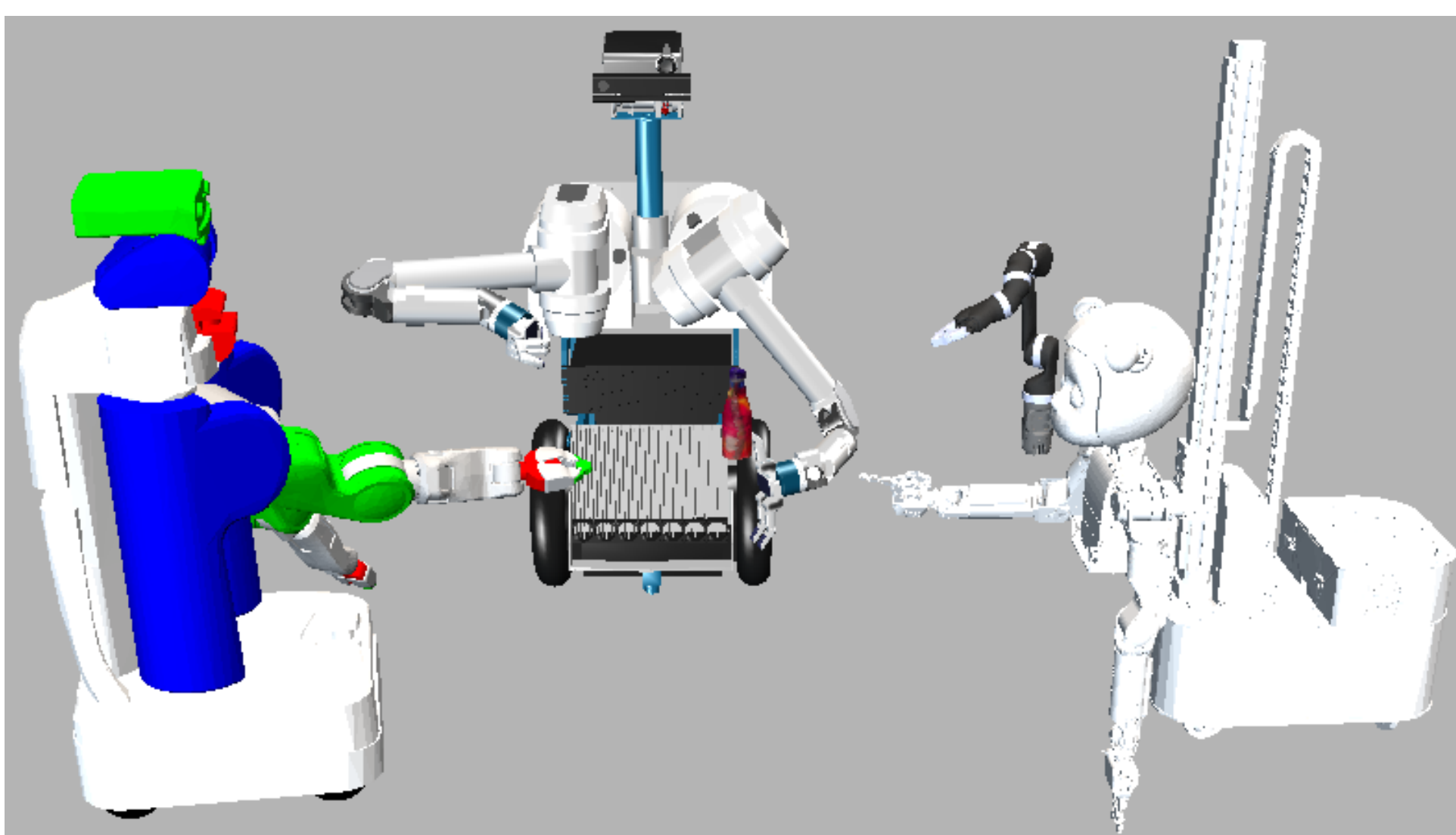
Task Space Regions



Deictic Gestures



Generalization Across Robots



Generalization Across Scenes

