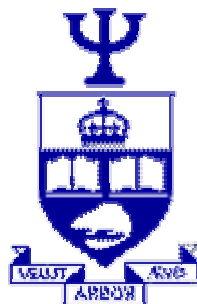


# Learning to Cluster using Local Neighborhood Structure

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# Overview

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## ■ Introduction

- A different clustering concept/properties

## ■ Motivation

- Using local neighborhood structure
- Learning to cluster

## ■ Clustering

- Probability model
- Learning to cluster

## ■ Experiments-applications

- Discovering noisy, sampled manifolds
- Learning to find spatial patterns
- Predicting gene function from gene expression

## ■ Summary

# Basic Clustering Problem

## ■ Dataset

- A finite set  $\mathcal{Z} = \{\mathbf{z}_1, \dots, \mathbf{z}_N\}$
- A measure or similarity between pairs of elements

## ■ Class labels

- A finite set of size  $M$ , e.g.,  $\mathcal{C} = \{1, \dots, M\}$

## ■ Clustering/classification

- Find labels  $C = (c_1, \dots, c_N) \in \mathcal{C}^N$  that optimize a certain function of the data points, measure, and labels.

# Clustering Problem in This Work

## ■ Dataset

- A finite set  $\mathcal{Z} = \{\mathbf{z}_1, \dots, \mathbf{z}_N\}$
- No measure or similarity assumed beforehand

## ■ Class labels

- A finite set of size  $M$ , e.g.,  $\mathcal{C} = \{1, \dots, M\}$

## ■ Clustering/classification

- Find a posterior probability distribution over class labels given the dataset:  $p(c_i | \mathcal{Z})$

- Learn to cluster from previously labeled data (labeled datasets are becoming increasingly popular)
- Neighborhood structure assumed relevant ...

# Main Conceptual Differences

## ■ Classical clustering notions

- Clusters should have **high intra-cluster and low-inter cluster** similarity
- Clustering is defined based on pair-wise similarities between data points
- Global measure

## ■ Clustering using local structure

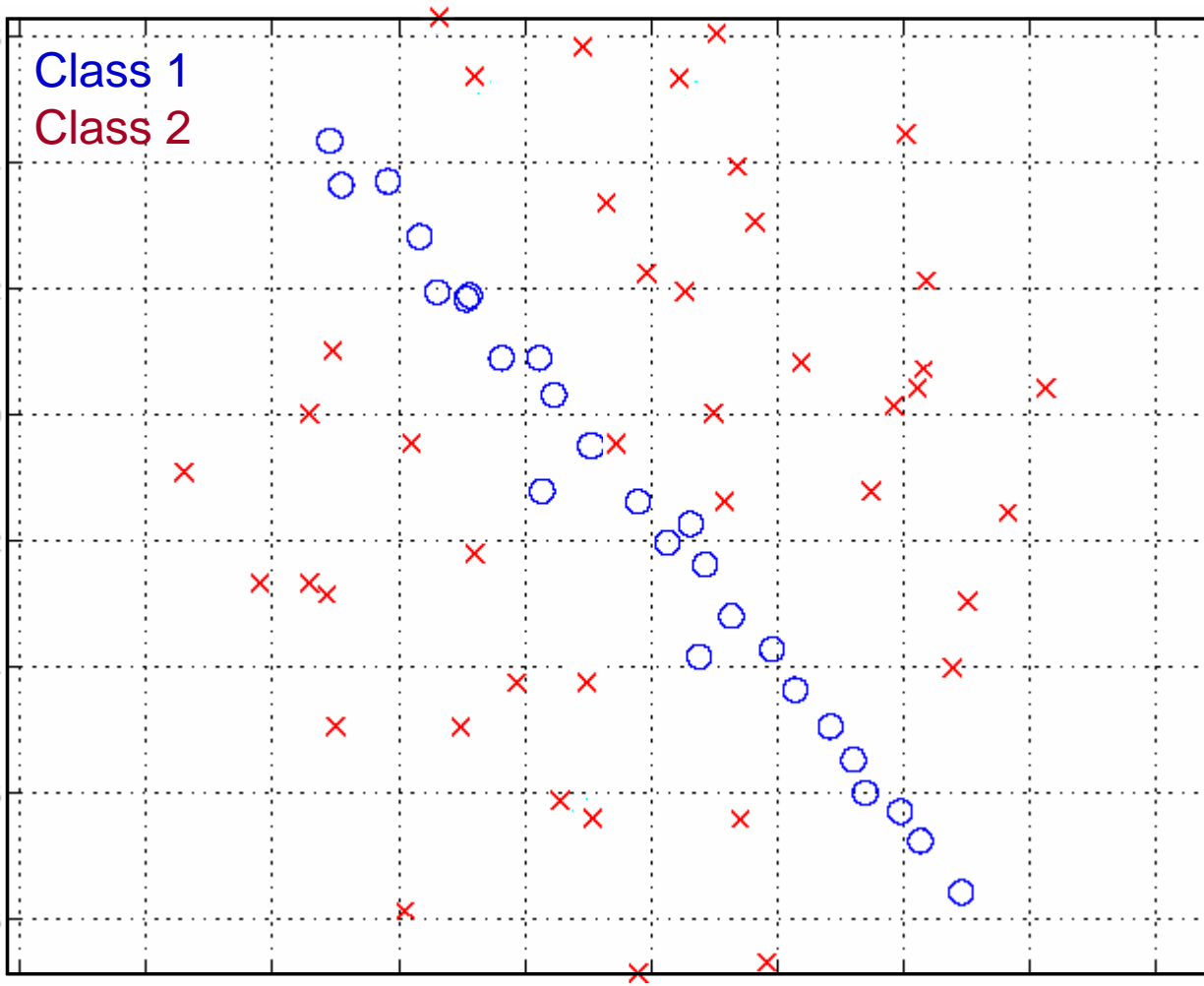
- A cluster should be **structurally** similar *everywhere* (locally)
- Clustering is defined based on the additional properties of the **local structure of the data** (in this work represented by the high-order neighborhood structure)
- Class conditioned measure

# Motivation I (Local Structure)

## ■ Local structure

- Commonly, affinities between pairs of data points are *enough* for classification
- However, in some problems, the **high-order local structure** of the data is more relevant for classification

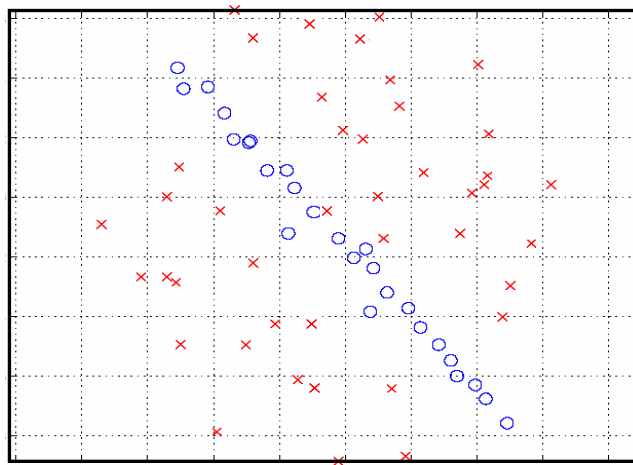
# Motivation | Example



# Motivation I

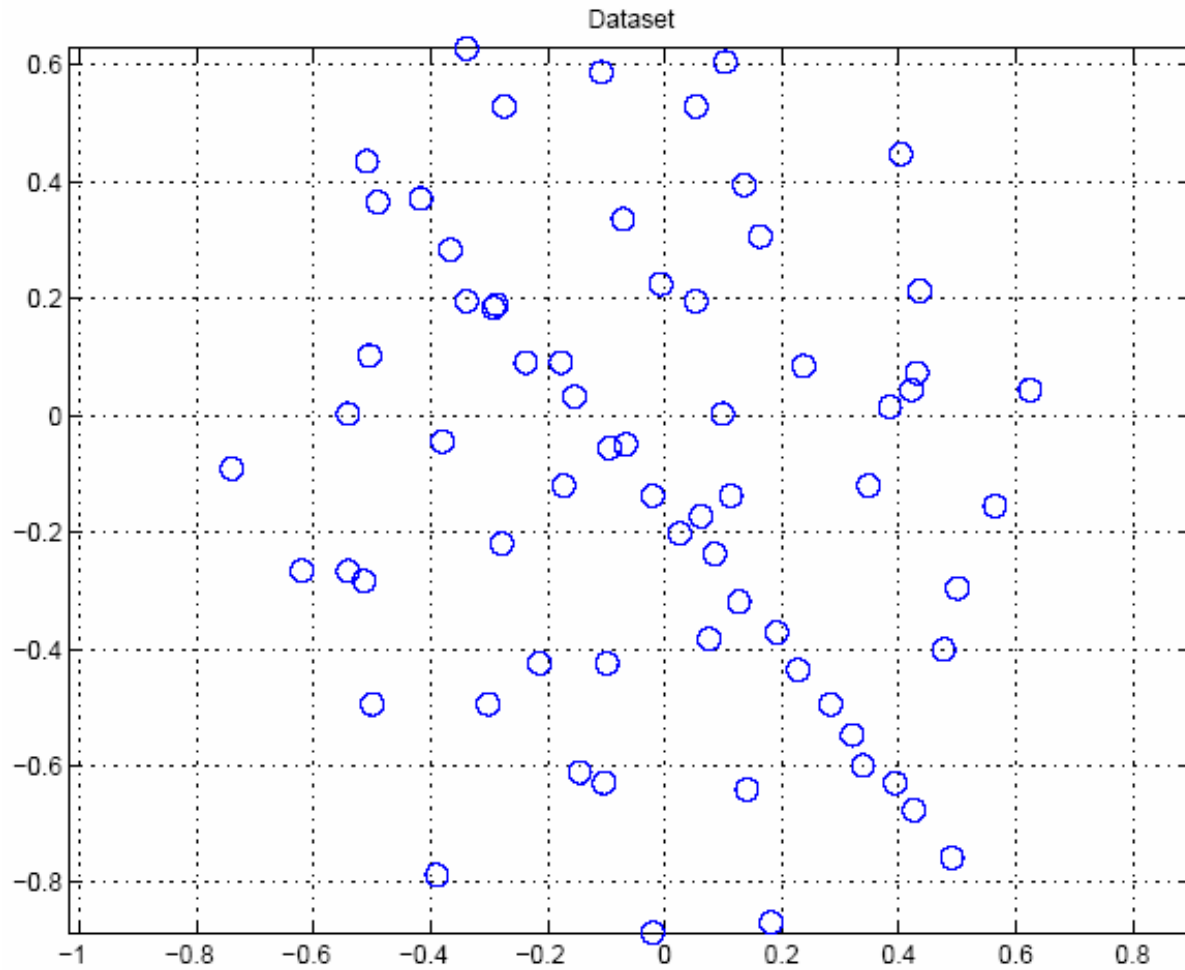
## ■ Local structure

- Commonly, affinities between pairs of data points are *enough* for classification
- However, in some problems, the **high-order local structure** of the data is more relevant for classification
- Concept allows to think of the notion of **class-conditioned structure**

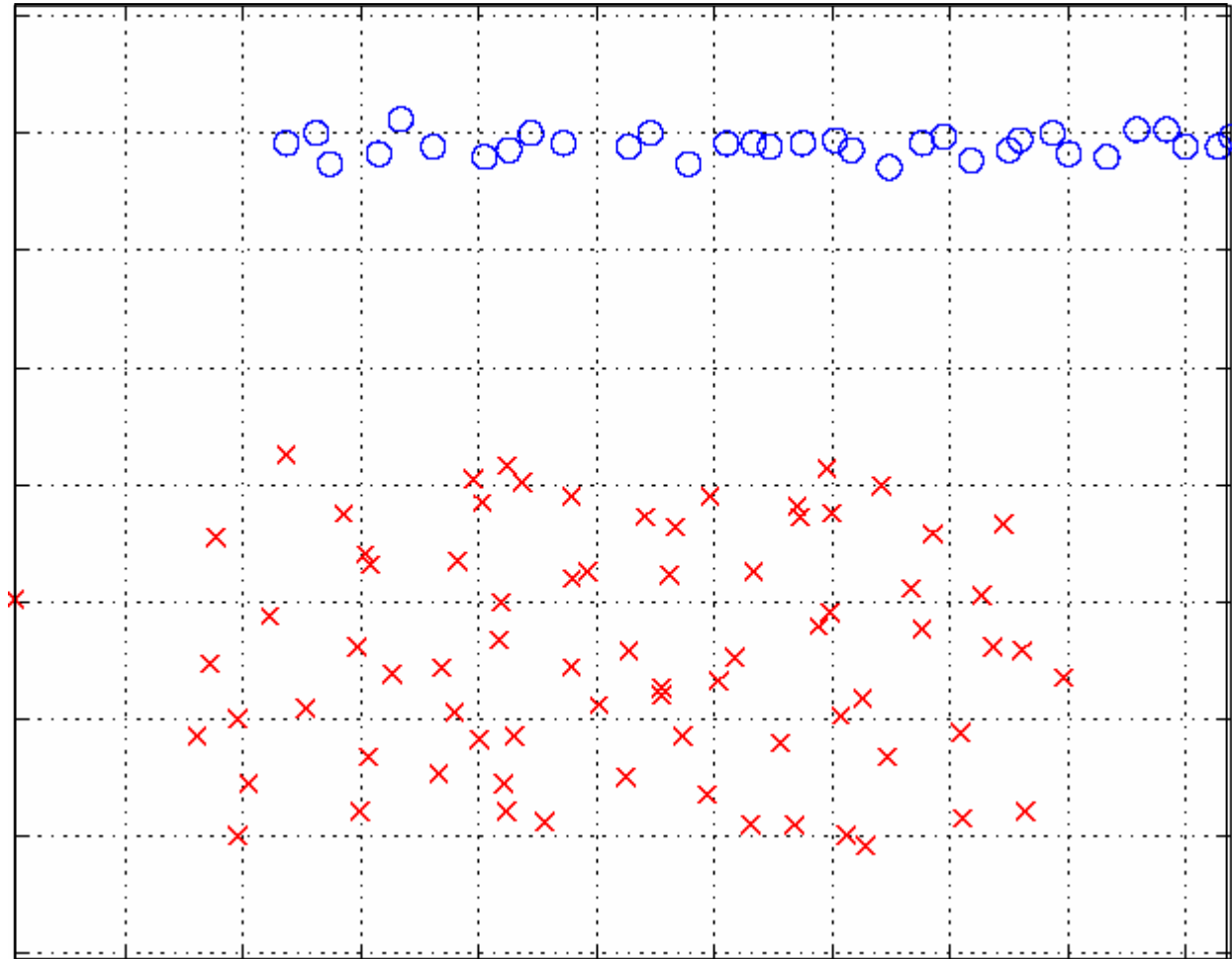




# Motivation II



# Motivation II Example



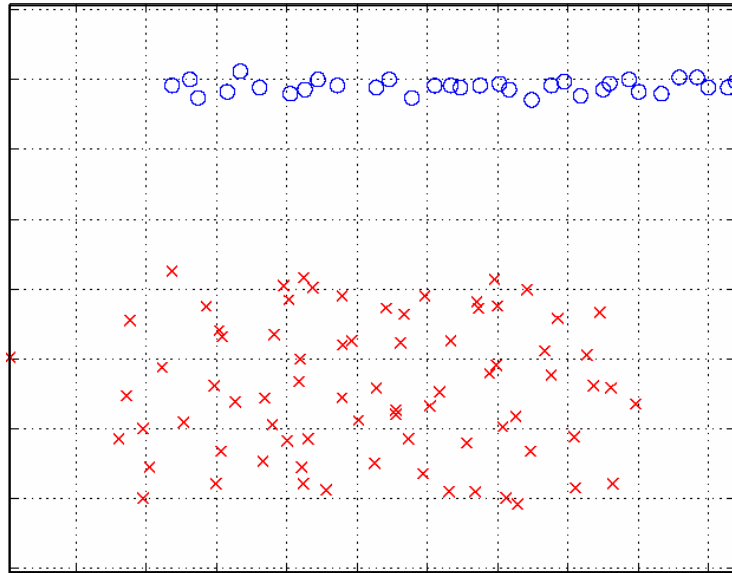
# Motivation II (Learning to Cluster)

## ■ Learning to cluster

- A measure of similarity is rarely given
  - Hand-picked
  - Obtained after feature selection
- Ideally, a way to *measure* likeness should be **obtained directly from relevant labeled data**

# Motivation II

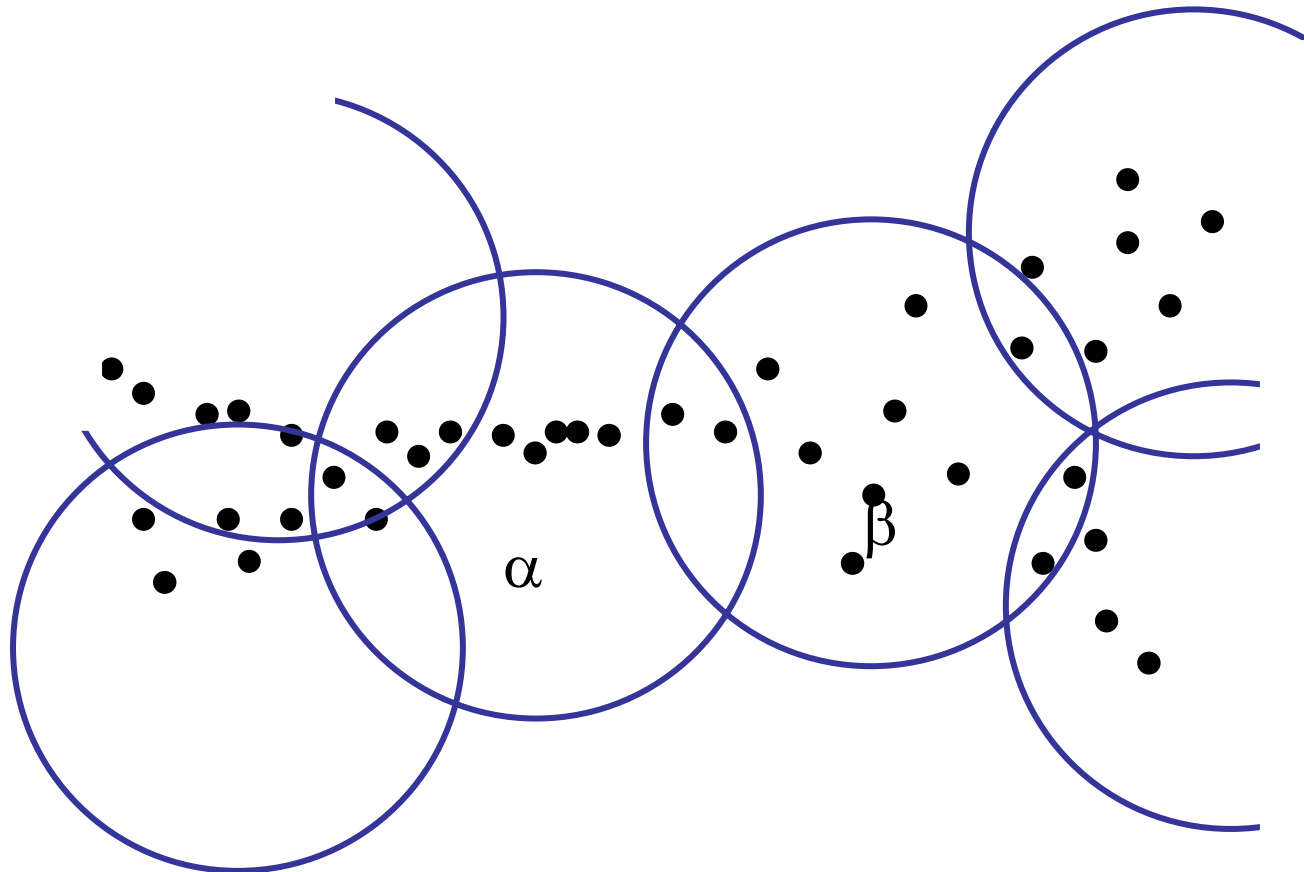
## ■ Learning to cluster



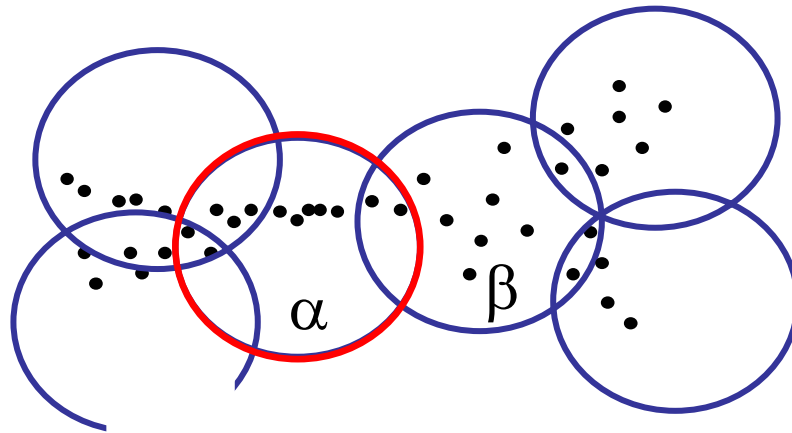
## ■ Encoding prior knowledge

- **Use examples** (e.g., instead of analytical expression)
  - Example based clustering: simple/general
  - Labeled examples are becoming more readily available

# Neighborhoods



# Neighborhoods



- Element set  $\eta_\alpha$  composed of  $K$  elements
  - E.g., randomly pick reference points and find its K-NN
- Structure representation

$$\underline{y_\alpha} = f(\{\mathbf{z}_i\}_{i \in \eta_\alpha})$$

We will look  $y_\alpha$  (structure) as a random variable

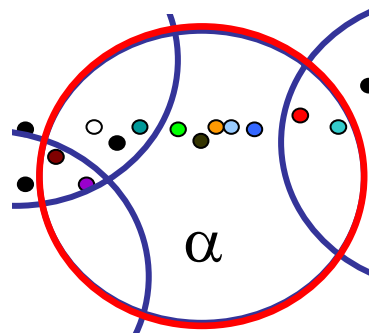
# Probability Models of Local Structure

- Main idea: conditioning structure on class label

$$p(\mathbf{y}_\alpha | \mathbf{x}_\alpha)$$

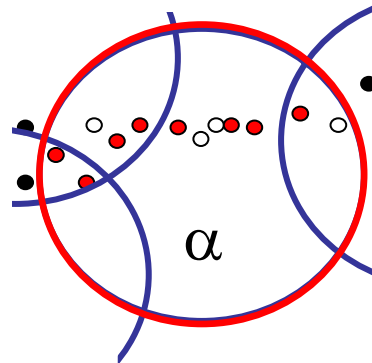
- Domain  $\mathcal{S}$  of  $\mathbf{x}$ :

- Worst case



$$|\mathcal{S}| = |\mathcal{C}|^K$$

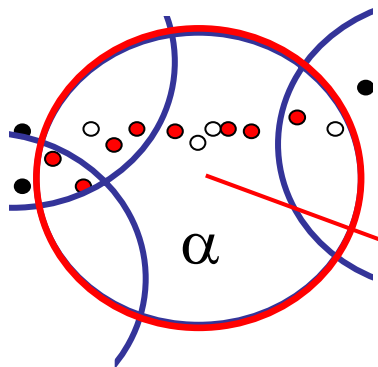
- A more structured representation



$$|\mathcal{S}| = |\mathcal{C}| \binom{K}{K_{out}}$$

# Efficient Representation of Class Labels

## ■ A more economical representation



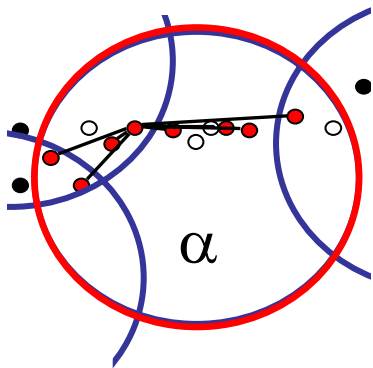
$$\mathbf{x}_\alpha = (\underline{\ell}_\alpha, \underline{s}_\alpha)$$

Class label Binary indicator

$$\mathbf{x}_\alpha = (c; 1, 1, 0, 1, 1, 1, 0, 0, 1, 1, 1, 0)$$

$$|\mathcal{S}| : \mathcal{O}(MK^{\min(K_{in}, K_{out})})$$

## ■ Conditional probability distribution



$$p(\mathbf{y}_\alpha | \mathbf{x}_\alpha) = p(\mathbf{d} | \ell_\alpha)$$

$$\mathbf{d} = \{d_{ij} | \underline{s}_i = 1, \underline{s}_j = 1\}$$

(In-class points only)



# Representing Local Structure

## ■ High order relationships

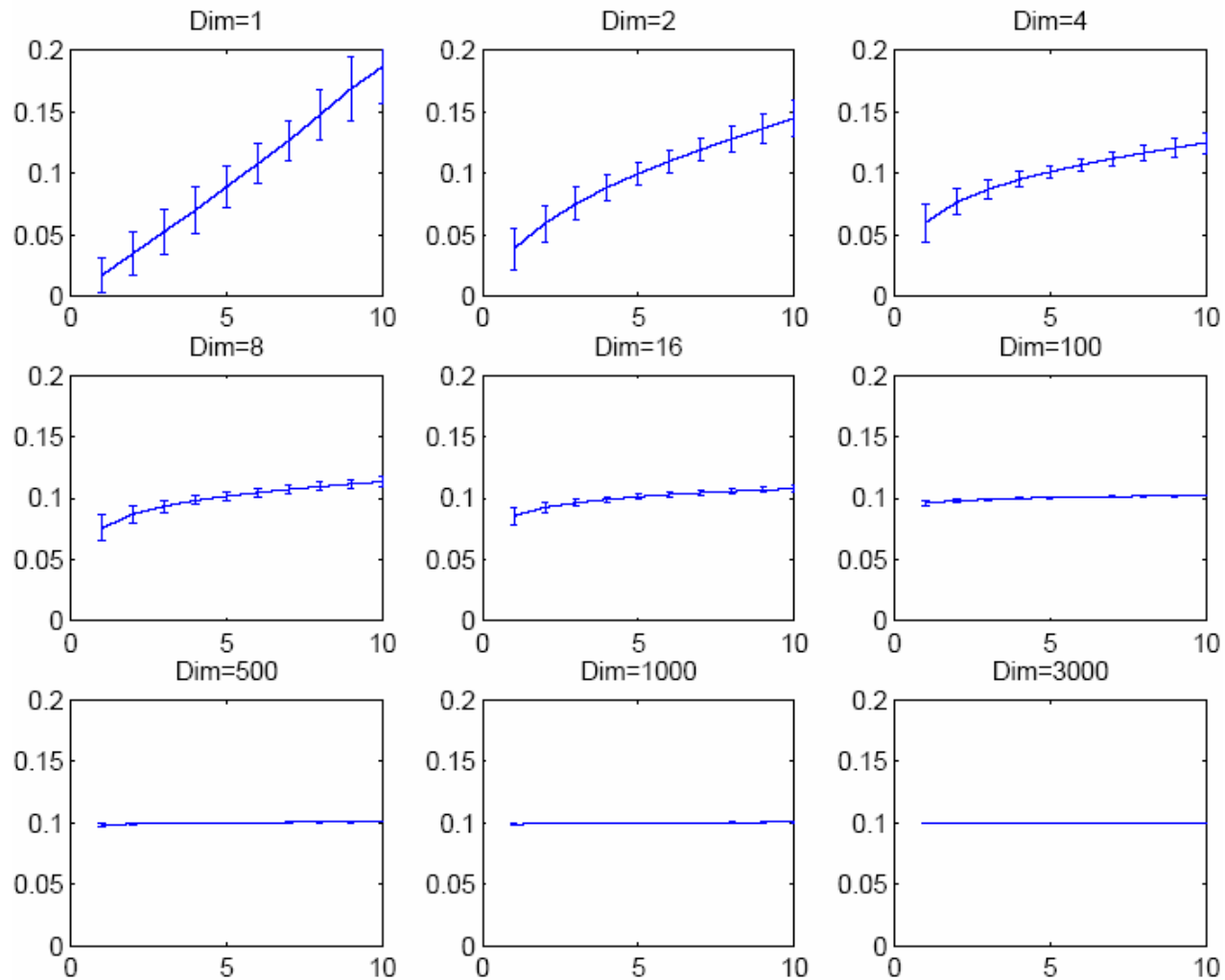
- Collection of pair-wise relationships is appropriate to describe local structure

$$f(\{\mathbf{z}_k\})_k = \{f(\mathbf{z}_i, \mathbf{z}_j)\}_{(i,j)} \sim \begin{array}{c} \text{---} d_{ij} \text{---} \\ \text{---} d'_{ik} \text{---} \\ \text{---} d_{jk} \text{---} \end{array}$$

- Clustering is a function of structure relationships between neighborhoods

Other representations possible

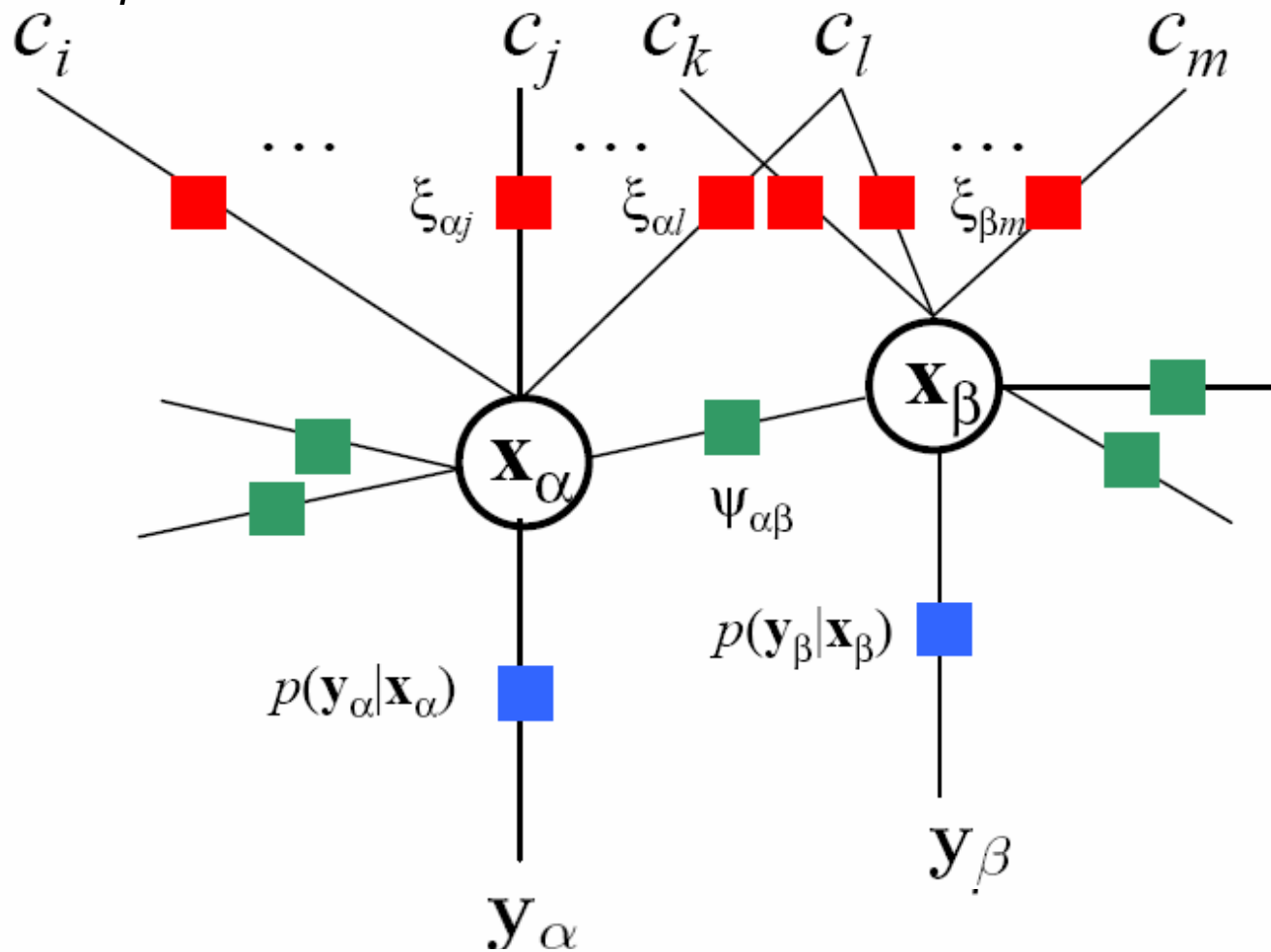
# Local Structure Example



Mean distance to  $K=[1 \dots 10]$  nearest neighbors  
(normalized) for planar surfaces of various dimensions

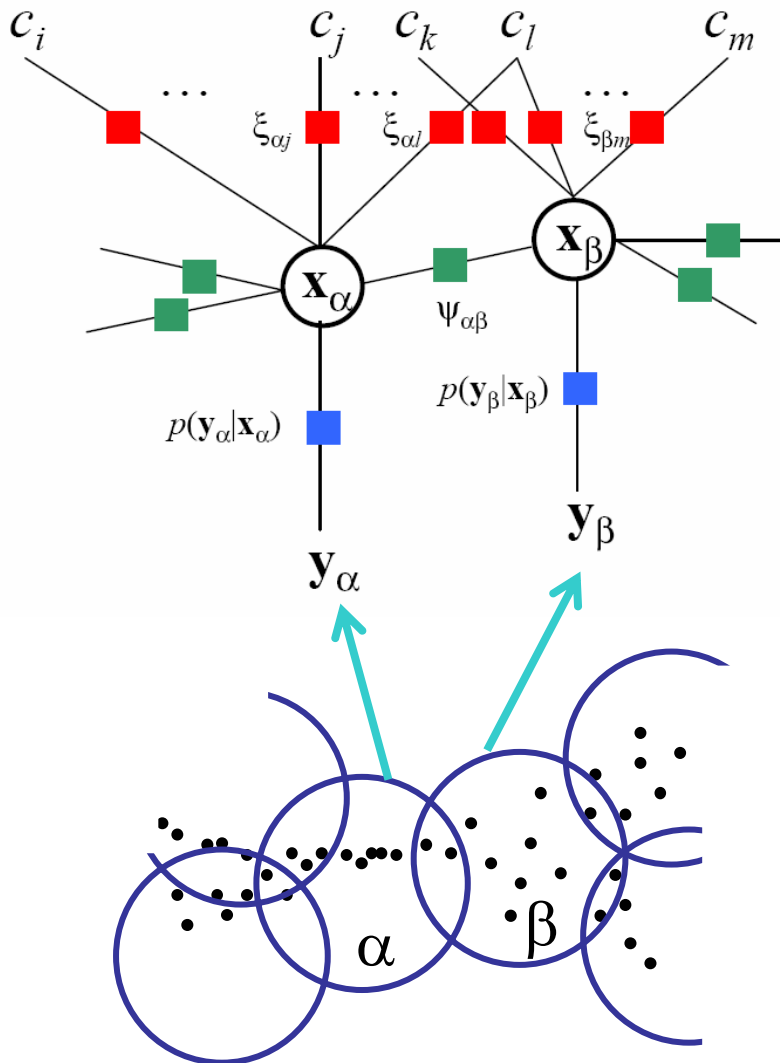
# From Neighborhoods to Labels

Factor graph for  $p$



$$P(\mathbf{y}, \mathbf{x}, C) = \frac{1}{Z} \prod_{\alpha} p(\mathbf{y}_\alpha | \mathbf{x}_\alpha) \prod_{(\alpha, \beta) \in \text{proxim.}} \psi(\mathbf{x}_\alpha, \mathbf{x}_\beta) \prod_{(\alpha, i)} \xi(c_i, \mathbf{x}_\alpha)$$

# From Neighborhoods to Labels



Individual Labels

Neighborhood assignments and labels

$$P(\mathbf{y}, \mathbf{x}, C) = \frac{1}{Z} \prod_{\alpha} p(\mathbf{y}_{\alpha} | \mathbf{x}_{\alpha}) \prod_{(\alpha, \beta) \in \text{proxim.}} \psi(\mathbf{x}_{\alpha}, \mathbf{x}_{\beta})$$

Structure conditioned on Class+ N. assignment

Neighborhood compatibility

$$\prod_{(\alpha, i)} \xi(c_i, \mathbf{x}_{\alpha})$$

Individual point class constraint

# Additional Model Description

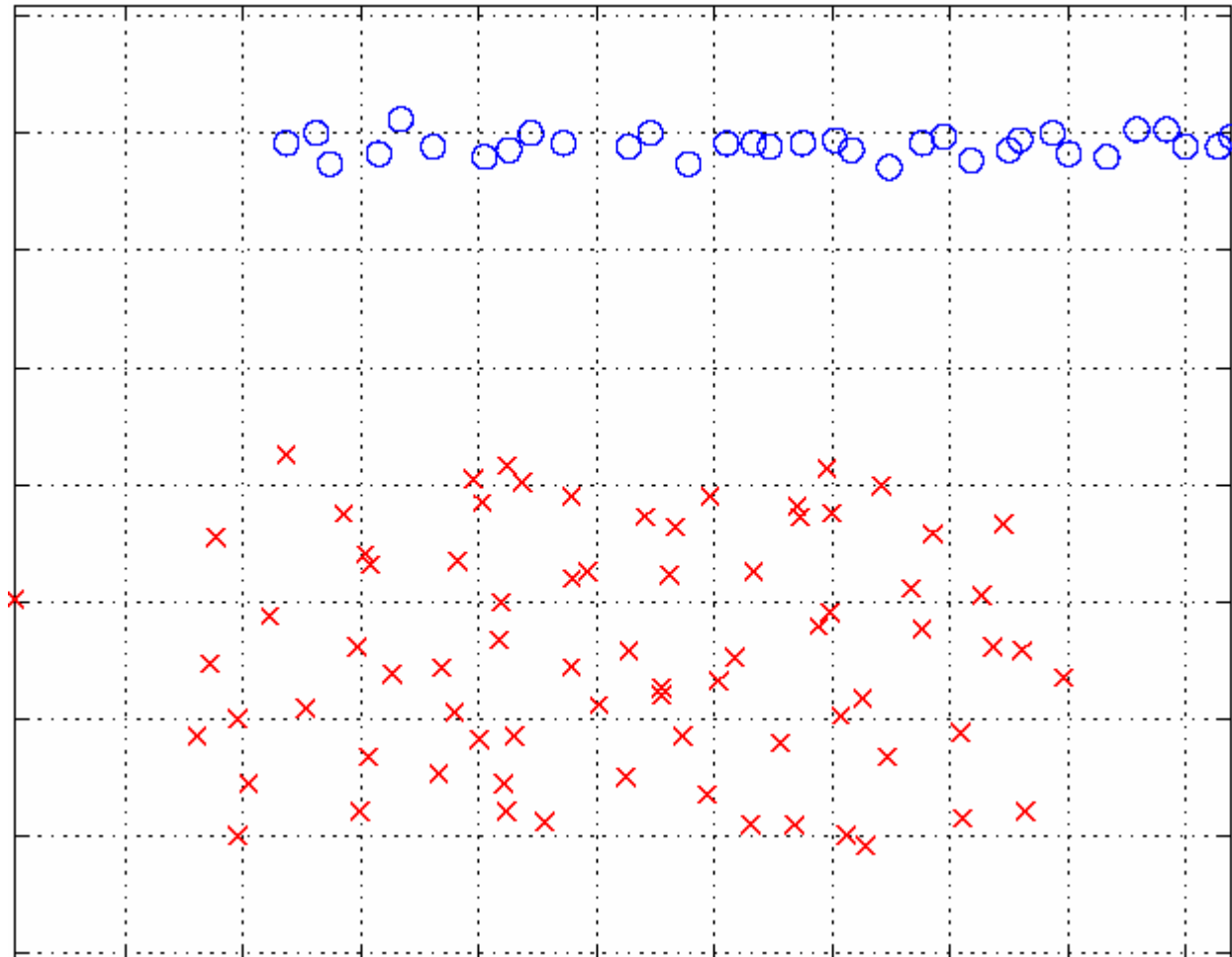
- The compatibility of two neighborhoods is inversely proportional to the number of **common** elements that *disagree*

$$\psi(\mathbf{x}_\alpha, \mathbf{x}_\beta) \propto \exp\left\{-\sum_{(i,j) \in \mathcal{P}_{\alpha\beta}} \phi(s_{\alpha i}, s_{\beta j})\right\}^{\delta(\ell_\alpha \neq \ell_\beta)}$$

- Each point class label **must agree** with its neighborhood(s) label(s)
  - Care about in-class points
  - **Do not care about out-of-class points** (wildcards)

$$\xi(c_i, \mathbf{x}_\alpha) = \delta(c_i - \ell_\alpha)[1 - \delta(s_i)]$$

# Learning to Cluster



# Learning to Cluster

## ■ Conceptual differences

- Familiar clustering concepts
  - Learn a similarity measure between pairs of points (e.g., affinity matrix)
- Clustering using local structure
  - Learn the local structure of clusters

## ■ Learning local structure

- Learning local structure from labeled (or partially labeled) datasets
- Learning is equivalent to estimating  $p(\mathbf{y}_\alpha | \mathbf{x}_\alpha)$  !
  - Well defined task
  - Because labels are given, this can be done easily for a number of distributions (in contrast to other popular clustering models)

# Extension to Unsupervised Clustering

## ■ Familiar clustering methods

- Changes in class label should occur in areas of low data density

## ■ Clustering using local structure

- Changes in class label should occur in areas where there is a change in local structure of the data (e.g., where the observed structure has low probability)



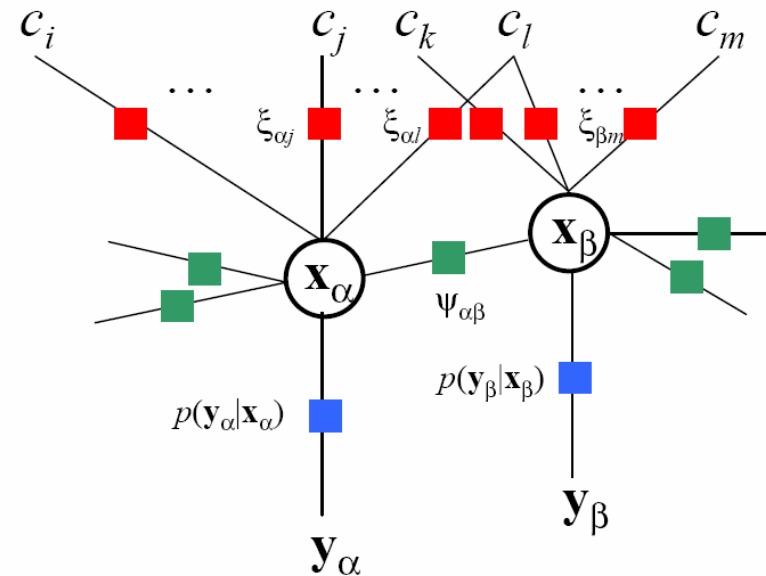
# Inference Problem

## ■ Given the neighborhoods:

- Infer class labels  $c_i$
- Infer neighborhood labels and point ownership  $\mathbf{x}_\alpha = (\ell_\alpha, s_\alpha)$

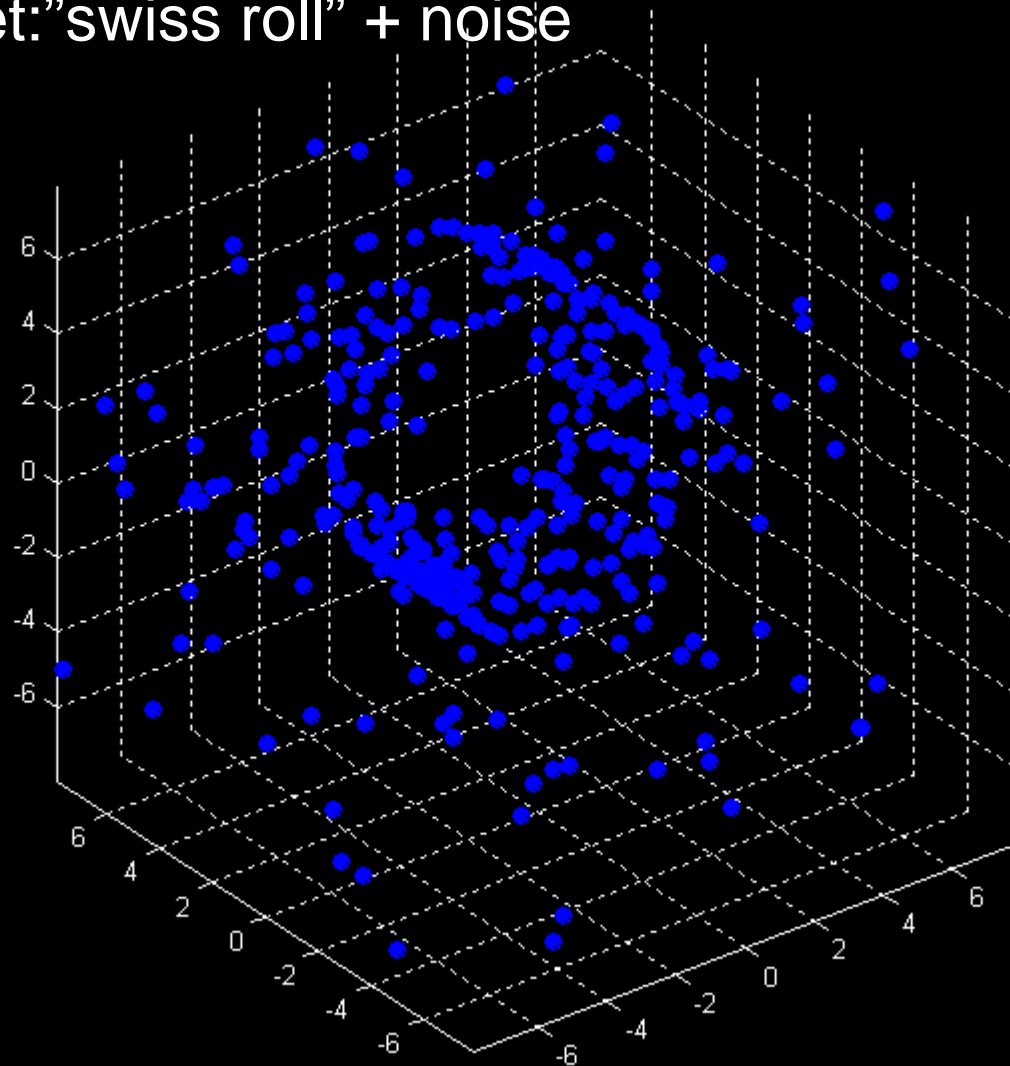
## ■ In our experiments:

- Approximate solution by using the sum-product algorithm



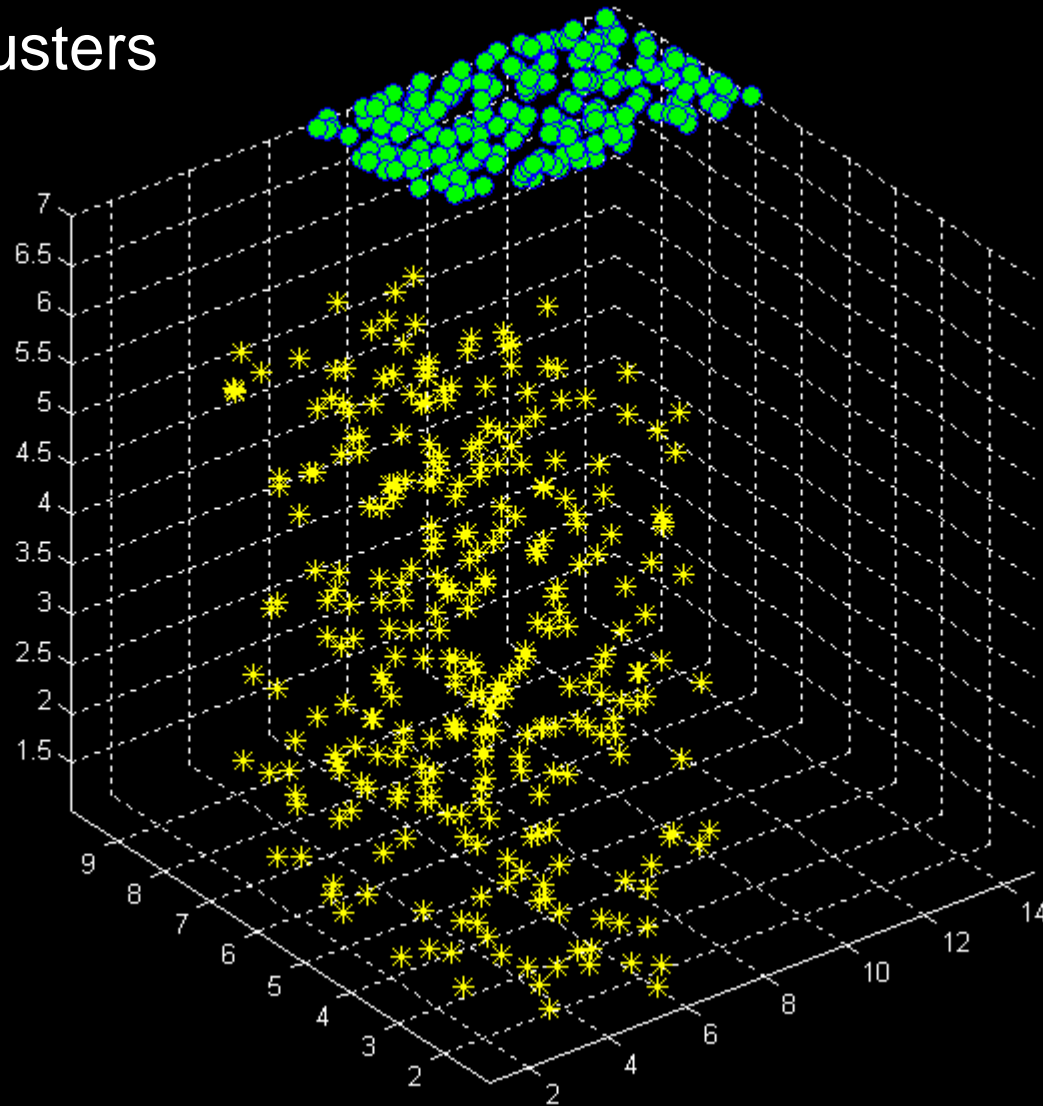
# Experiments (Manifold Discovery)

Test dataset: "swiss roll" + noise



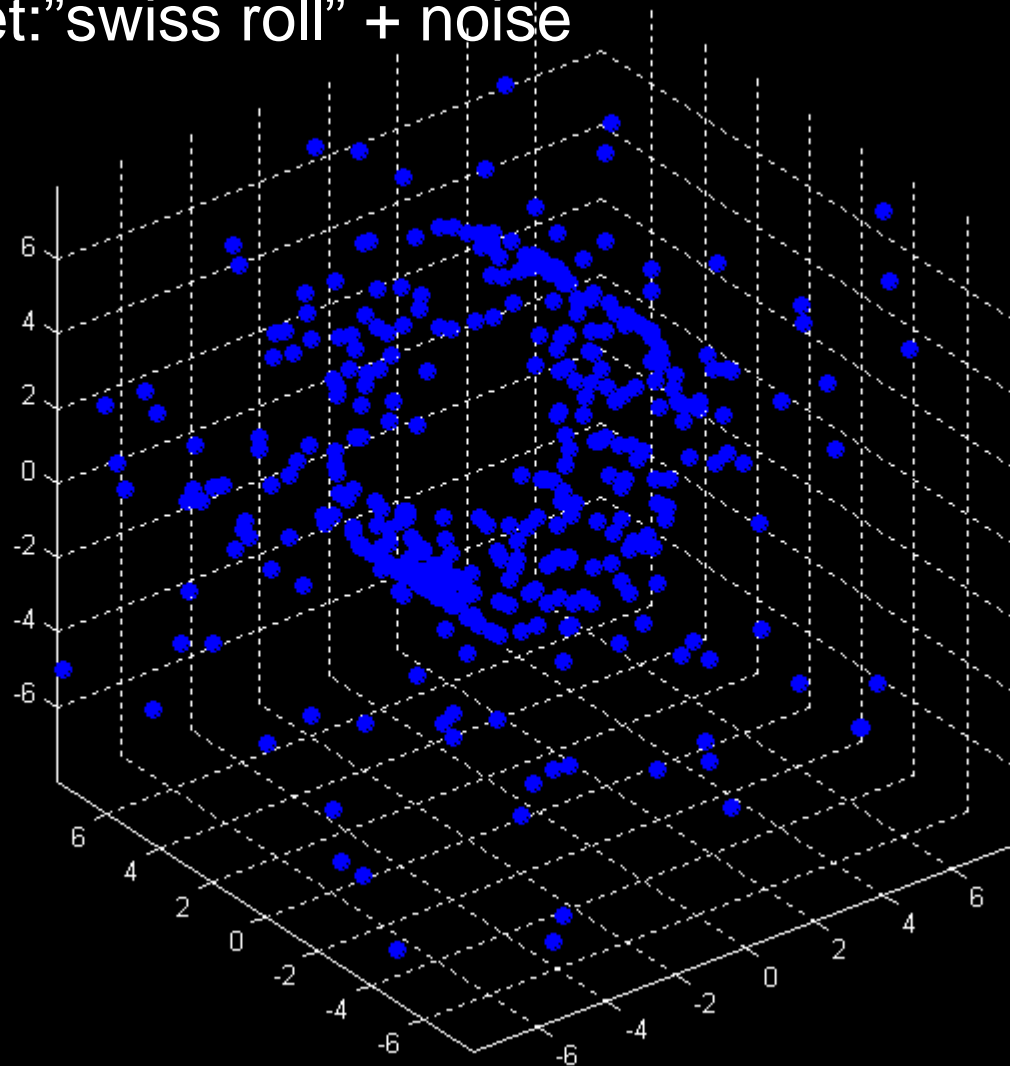
# Experiments (Manifold Discovery)

Training clusters



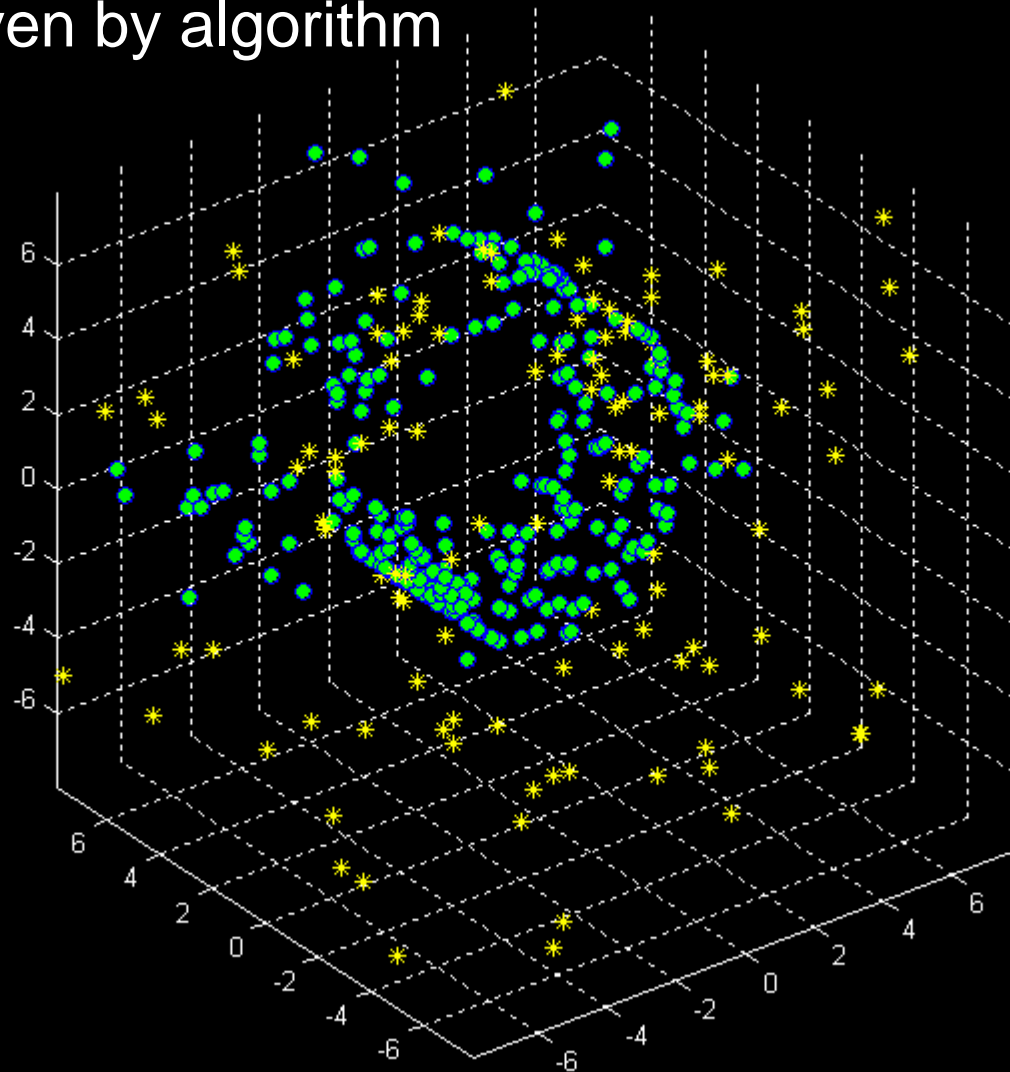
# Experiments (Manifold Discovery)

Test dataset: "swiss roll" + noise



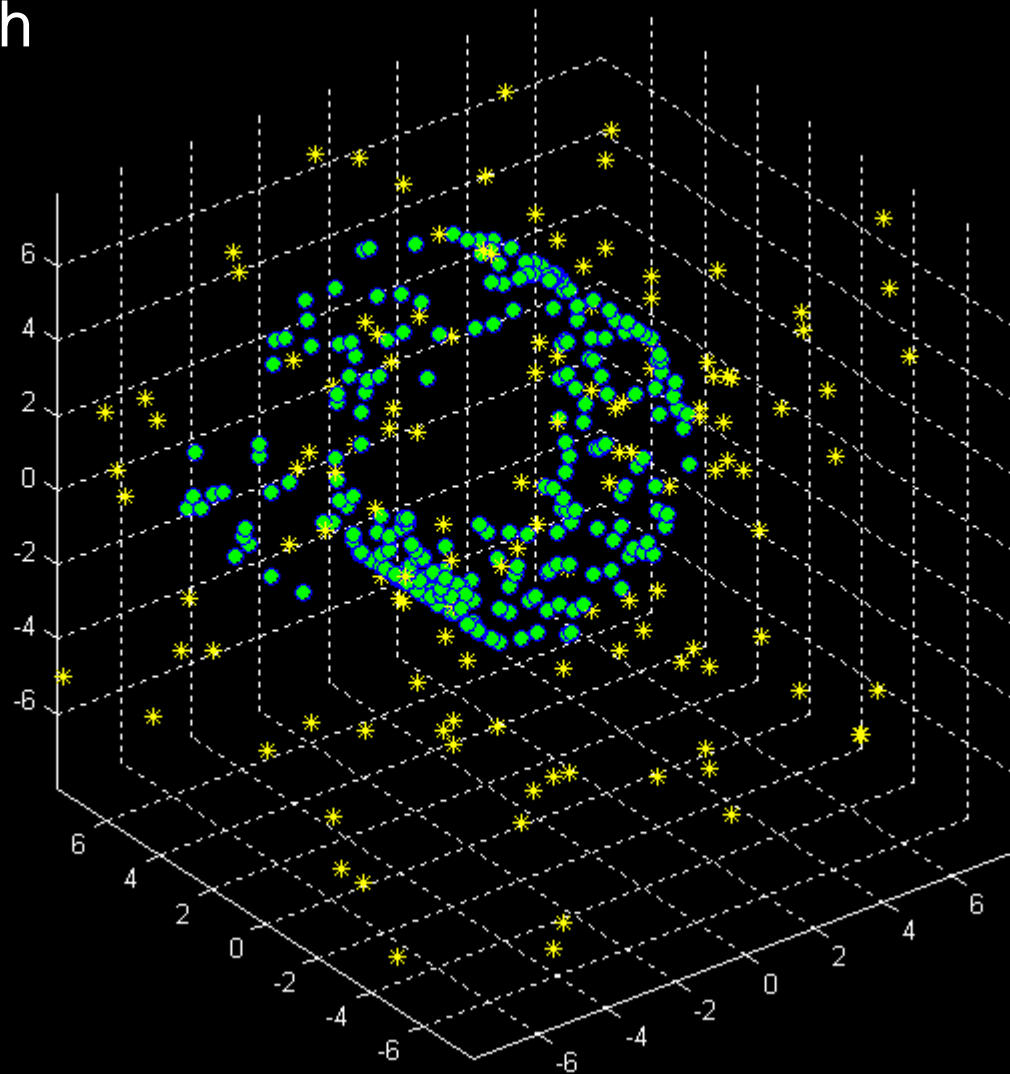
# Experiments (Manifold Discovery)

Solution given by algorithm

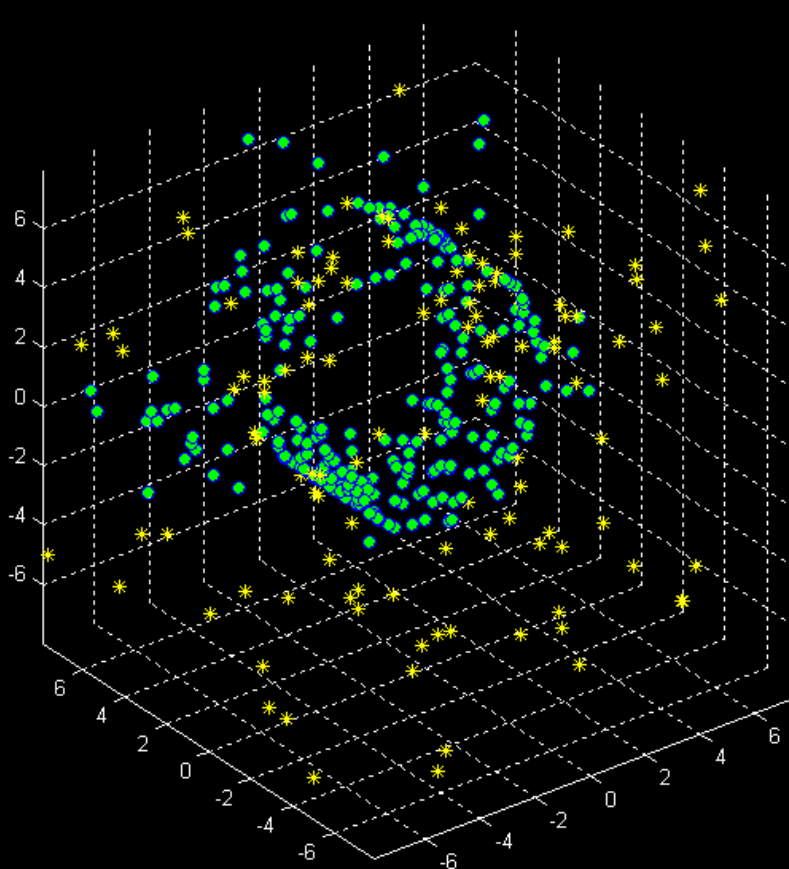
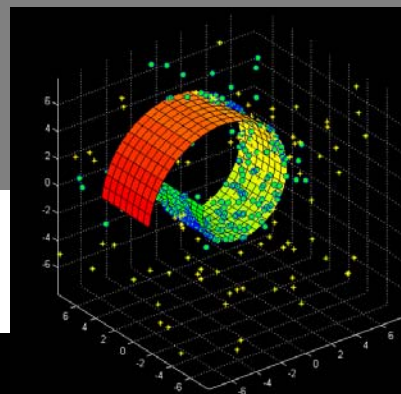


# Experiments (Manifold Discovery)

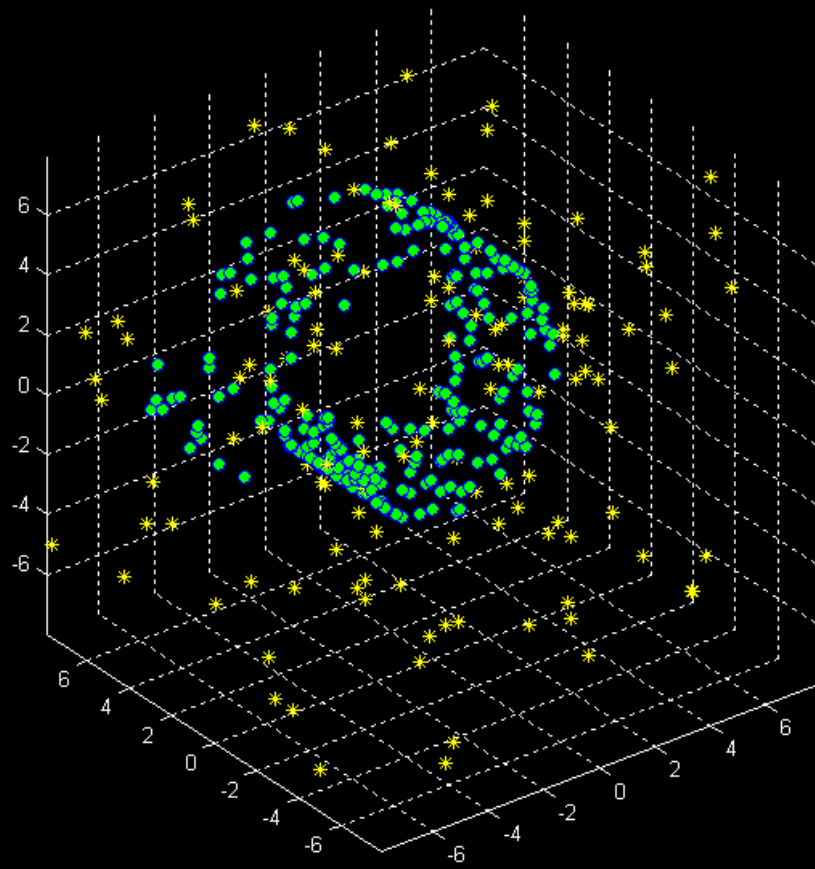
Ground truth



# Experiments (M. Discovery)

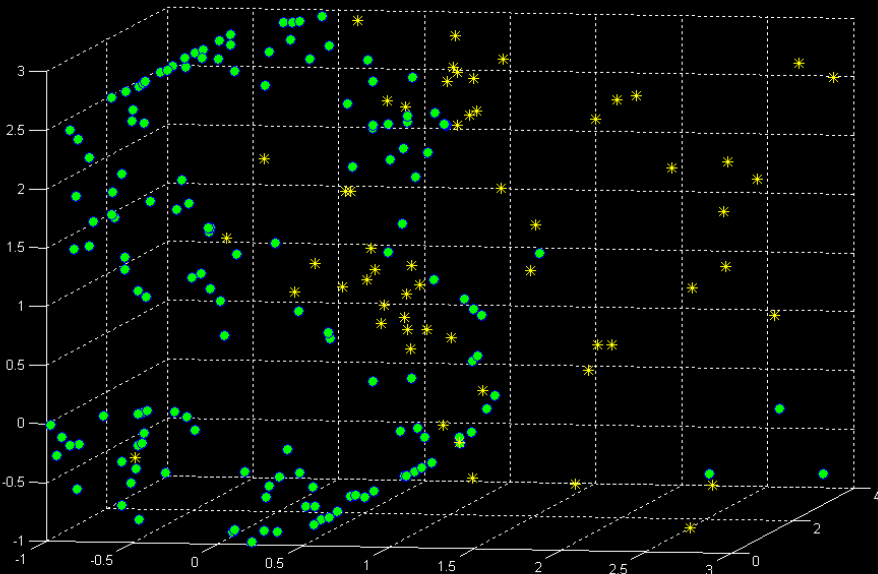


Solution given by algorithm

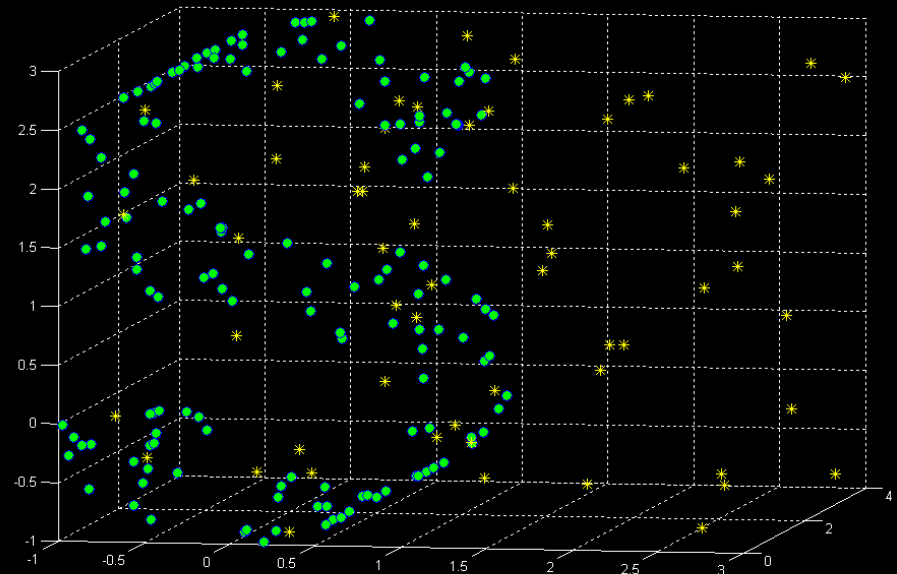


Ground truth

# Experiments (Manifold Discovery)



Solution given by algorithm

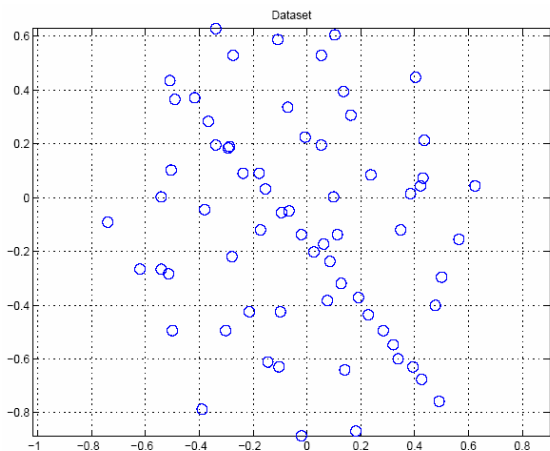


Ground truth

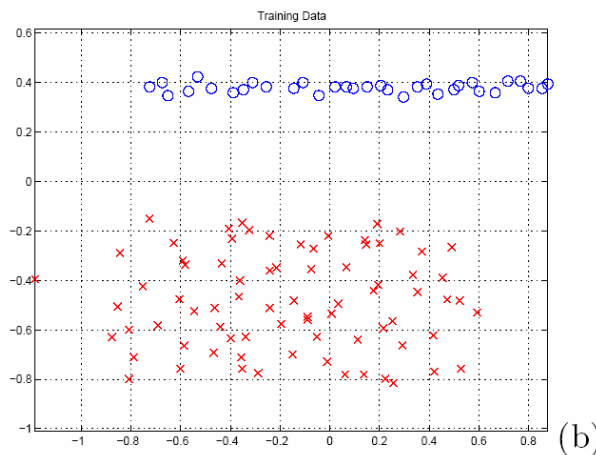


# Experiments (Learning Spatial Patterns)

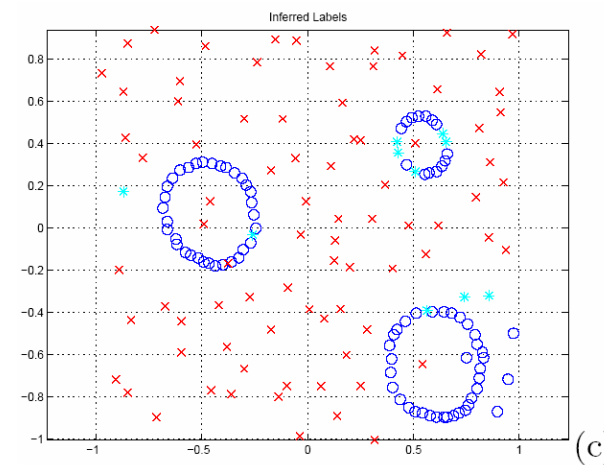
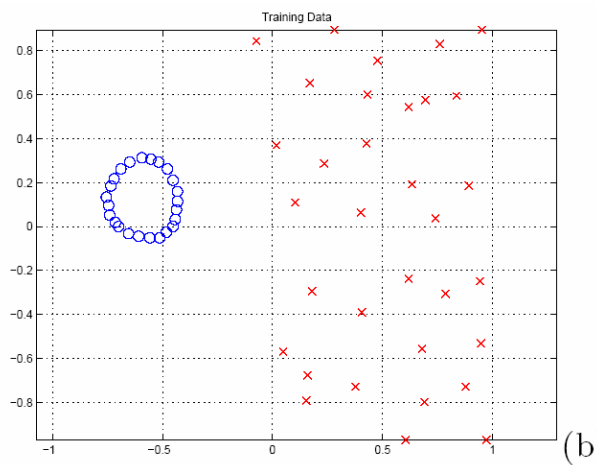
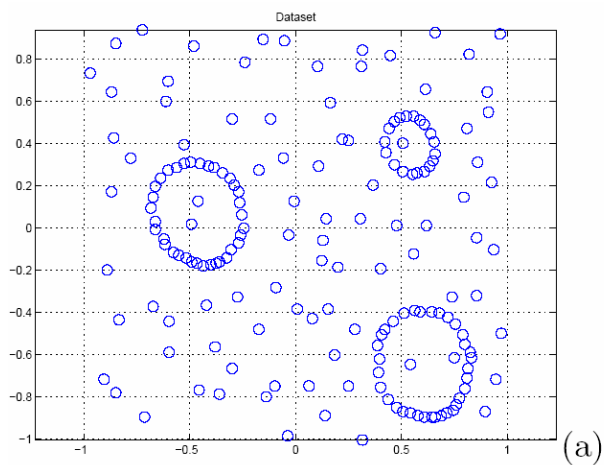
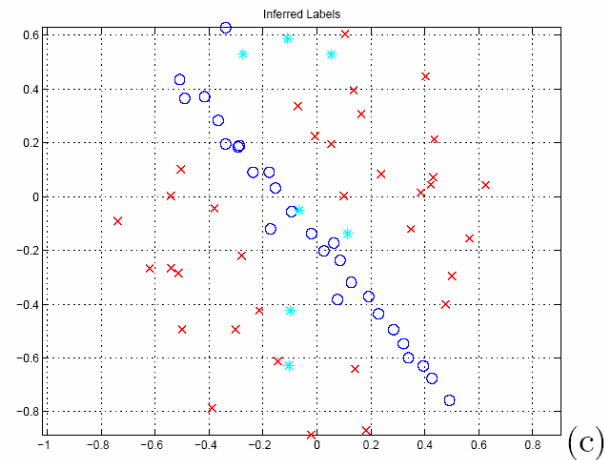
Input



Training Set



Result



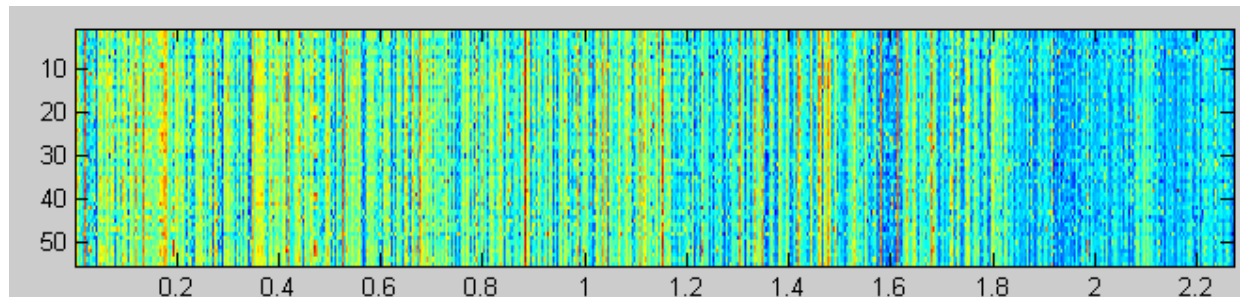
# Experiments (Functional Gene Classification)

## ■ Functional categories (GO-BP) [Ashburner et. al. 2000]

### • E.g.:

- cell homeostasis [GO:0019725] Total genes:111
- anti-apoptosis [GO:0006916] Total genes:112
- secretory pathway [GO:0045045] Total genes:112
- hemopoiesis [GO:0030097] Total genes:113
- humoral defense mechanism (sensu Vertebrata) [GO:0016064] Total genes:114
- translational initiation [GO:0006413] Total genes:119
- amino acid biosynthesis [GO:0008652] Total genes:124
- muscle development [GO:0007517] Total genes:126

## ■ Mouse gene expression data\*



Genes

\* [Hughes Lab,  
Banting and Best Institute  
University of Toronto]

# Experiments (Functional Gene Classification)

## ■ Underlying assumptions

- It might be possible to predict gene function based on the **pattern of gene expression in which they are involved**
- This pattern might be shared by same function genes
- Thus, **different classes could be distinguished by their collective pattern** of gene expression

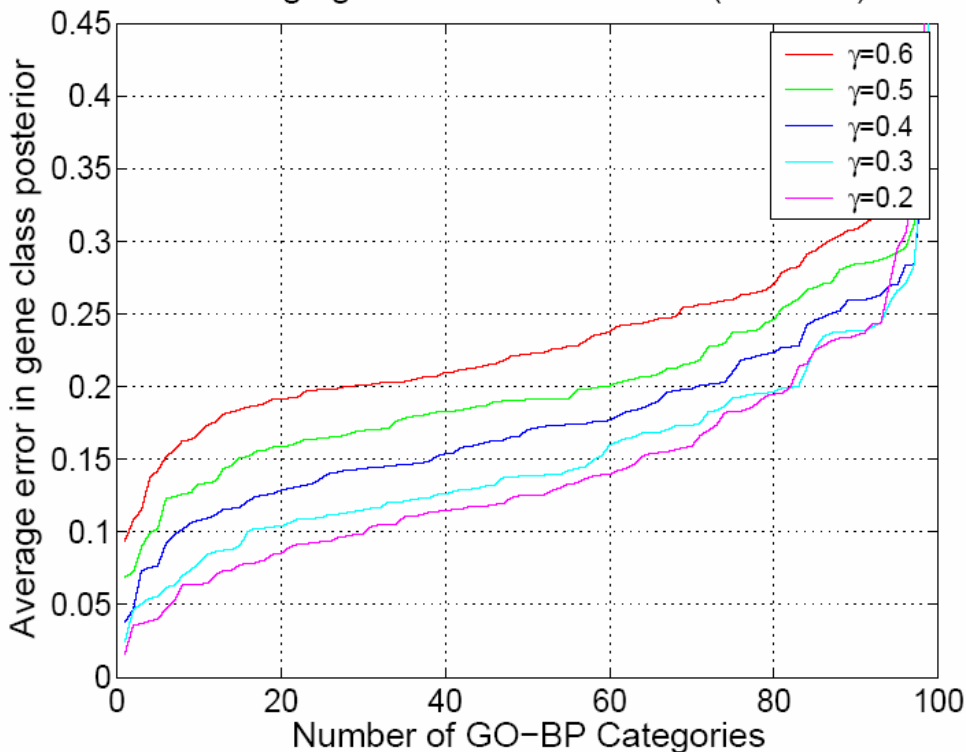
# Experiments (Functional Gene Classification)

## ■ Experimental set-up

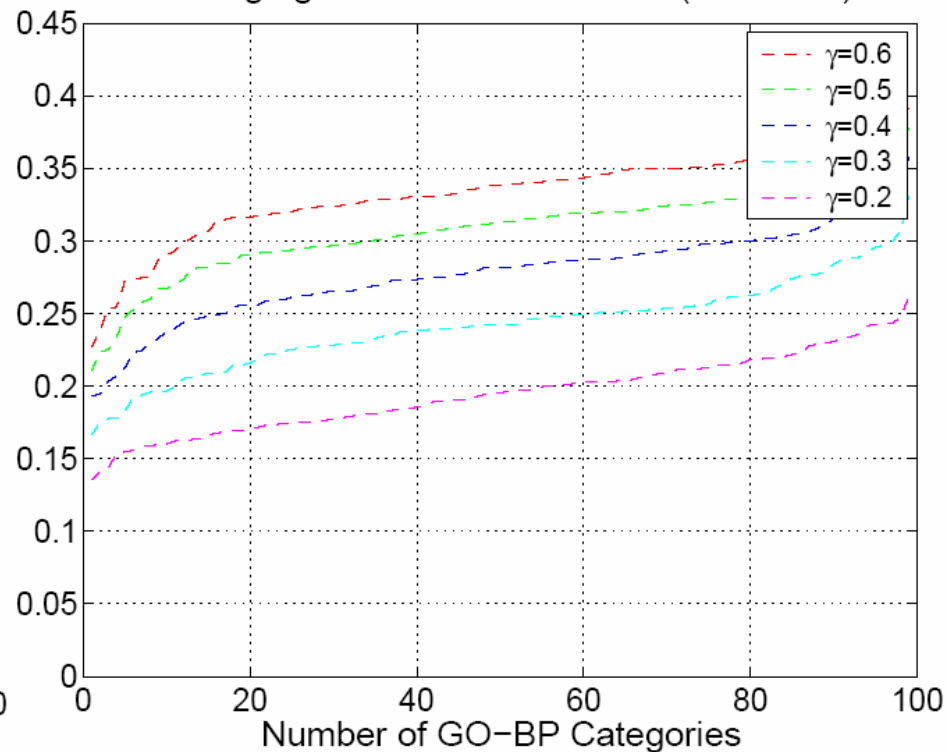
- Considered the 99 GO-BP categories with over 80 labeled genes
- Partition data: train 80% - test 20%
- Absolute error curves based on  $\gamma$  = proportion of genes that **should** be classified

# Experiments (Functional Gene Classification)

Average gene classification error (LC-LNS)



Average gene classification error (K-means)



# Summary

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- Clustering/classification based on **alternative concept**
  - Higher order properties of local structure of the data are more relevant for certain tasks
  - Class dependent cluster structure
- Probabilistic formulation yielded **well defined concepts** regarding
  - Learning to cluster
  - Inferring clusters
  - Extension to unsupervised clustering
- Concept can be related to more standard clustering ideas
- Negative aspect: Inference algorithm does not in general converge to *good* solutions (the correct posteriors)
- Demonstrated on several applications
  - Learning and finding coherent spatial patterns
  - Separating low dimensional (sampled) manifolds from higher dimensional noise
  - Predicting gene function via collective pattern of expression