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TO:

CTSS USERS

FROM:

PROGRAMMING STAFF

SUBJECT:

CTSS LIBRARY SUBPROGRAMS NOT INCLUDED IN THE CTSS

PROGRAMMER'S GUIDE

DATE:

JULY, 1967

Introduction

The following is an index by entry names of subprograms included in this memo. A user should refer to CC-174 for the usage of XSIMEQ and XDETRM. After the index are write-ups about the subprograms.

It is suggested that this annotated itemization be inserted in the CTSS Programmer's Guide after section AG. 13.00.

	ENTRY NAME	SYNOPSIS
1	ACØS, ASIN	Arccosine, arcsine functions. Floating-point argument.
2	ATAN, ATN	Arctangent function. Floating point.
3	DETCS	Simulates a FORTRAN function call to XDETRM.
4	DFAD, DFSB, DFMP, DFDP, SFDP, DCEXIT	Performs double precision floating-point operations on numbers stored in consecutive storage locations.
5	DIM	Positive difference function.
6	EXP	Exponential function. Floating point (1).
7	EXP(1	Computes i**J. Fixed point (1).
8	EXP(2	Computes X**K。 Floating-point number to a fixed-point power (1)。
9	EXP(3	Computes X**Y。 Floating arguments (1)。
10	FINT MINT	Converts MAD integer to FORTRAN integer. Converts FORTRAN integer to MAD integer.
11	FLIP	Interchanges rows and columns in a MAD two-dimensional array.
12	INDV, DPNV	Integration of differential equations.
13	INT	Truncation。 Floating point。
14	IØSET, IØPAR, IØEND, IØSCP, IØITR	Compiled into MAD routines during translations of FORTRAN statements involving iterated input-output.
15	LØG	Logarithm (base e) function.
16	0XAM	Maximum, fixed-point argument, floating-point function.
17	MAX1, XMAX0	Maximum, floating-floating, fixed-fixed.
18	м100	Minimum, fixed-point argument, floating-point function.
19	MIN1, XMINO	Minimum, floating-floating, fixed-fixed.

	ENTRY NAME	SYNOPSIS
20	MØD	Remaindering, Floating point,
21	RANNØ, SETU	Random number generator.
22	SINCS	Simulates a FORTRAN call to XSIMEQ.
23	SIN, CØS	Sine and cosine functions. Floating point.
24	(SLI)	Short list input。 Used by FORTRAN routines。
25	(SLØ)	Short list output. Used by FORTRAN routines.
26	SQRT, SQR	Square root function. Floating point.
27	TAN, CØT	Tangent and cotangent functions. Floating point.
28	TANH	Hyperbolic tangent function.
29	XDIM	Finds the absolute difference between the two arguments. Fixed point.
30	XDTRH	Called by MAD and MADTRN programs instead of XDETRM.
31	XINT, XFIX	Truncation. Changes floating-point numbers to fixed-point numbers.
32	XLØC	Finds the location where a variable is stored.
33	XMAX1	Finds the maximum values of a set of floating-point numbers. Result is fixed-point.
34	XMIN1	Minimum floating arguments, fixed result.
35	XM Ø D	Remaindering. Fixed point.
36	XSIGN, SIGN	Transfers the sign of the second argument to the first.

en-dendrica,	ENTRY NAME	SYNOPSIS		
37	XSMEQ	Called by MAD and MADTRN programs instead of XSIMEQ.		
38	。01300	Computes Y**Z。 Floating point。 Used by MAD routines。		
39	。01301	Computes X**K。 X floating point, K fixed point。 Used by MAD routines。		
40	。01311	Computes I**J. Fixed point. Used by MAD routines.		
41	.03310, .03311	Computes linear subscripts for two-dimensional MAD arrays.		

⁽¹⁾ See corresponding entries that are used by MAD routines, nos. 38-41.

Entry Name:

ASIN, ACØS

Purpose:

Computes the principal value of arcsine X or arccosine X for a single precision

floating-point argument.

Length:

250 octal locations

Transfer Vector:

ERRØR, LDUMP

Error Procedure:

The error condition is met and ERRØR subprogram called, if the absolute value of the argument is greater than 1.0. The ERRØR subprogram may also be called in case of machine failure. Upon return from ERRØR, the ASIN and ACØS functions send control to the LDUMP subprogram.

Calling Sequence:

FORTRAN	MAD	FAP
Y = ASINF(X)	Y = ASIN.(X)	CLA X TSX \$ASIN, 4 STØ Y

where:

- Y is an angle in floating-point radians in the first and second quadrants for ACØS and the first and fourth quadrants for ASIN.
- X is a floating-point number between -1 and +1.

Reference:

SHARE Distribution No. 670, 1B ANS2 and 1B ACS2

Entry Name:

ATAN, ATN

Purpose:

Computes the principal value of arc tangent X for any single precision floating-point argument with either

entry.

Length:

127 octal locations

Transfer Vector:

None

Error Procedure:

None

Calling Sequence:

FORTRAN

MAD

EAP

ANGLE = ATANF(TANG)

ANGLE = ATAN (TANG)

CLA

TANG \$ATAN, 4

TSX \$ATAN STØ ANGLE

where:

ANGLE is an angle in floating-point radians in the

first or fourth quadrant.

TANG

is the tangent of an angle in floating-point.

Reference:

SHARE Distribution No. 507, IB ATN 1

Entry Name:

DETCS

Purpose:

Simulates a FORTRAN function call to

XDETRM.

This routine is used by the library

program XDTRM.

Length:

26 octal locations

Transfer Vector:

XDETRM

Calling Sequence:

MADTRN:

CALL DETCS (NFØR, NØFØR, A, D, MFØR)

MAD:

EXECUTE DETCS. (NFØR, NØFØR, A, D, MFØR)

where:

NFØR

is a FORTRAN (decrement) integer giving the maximum number of rows or columns which the

matrix A may have.

NOFOR

is a FORTRAN (decrement) integer giving the number of rows or columns in the matrix A

at the time XDTRM is called.

A

is an unsubscripted floating-point variable referring to the matrix.

D

is a floating-point variable by whose value the value of the determinant will be modified.

Upon return, D=Det(A).

MFØR

upon return will contain a FORTRAN (decrement)

integer which will be

1 If the solution was successful

2 if an overflow occurred

or 3 if the matrix A is singular. Execution:

Given the above calling sequence, DETCS reforms it in such a way as to simulate a FORTRAN function call. XDETRM is called by this routine. Upon return from XDETRM, the resulting integer value is stored in MFØR.

A programmer may call this routine instead of XDTRM if he will alter his integers in the call so they are FORTRAN integers (by multiplying each of them by 2.P.18, shifting the integers left 18 places, or calling FINT) and upon return changing the resulting FORTRAN integer MFØR to a MAD integer (by dividing it by 2.P.18, shifting the integer right 18 places, or calling MINT).

Restrictions:

All Integers are FORTRAN (decrement) integers.

The matrix A must be a square matrix with the base element set at 1, that is, A(1,1)=A(1). However, in the call, A must not be subscripted.

Reference:

CC-174

Entry Names:

DFAD, DFSB, DFMP, DCEXIT, DFDP, SFDP

Purpose:

To perform double-precision floatingpoint operations on numbers stored in

consecutive storage locations.

Length:

153 octal locations

Transfer Vector:

ENDJØB

Error Procedure:

If division by zero is attempted and DCEXIT has not been called, ENDJØB will be called. Floating-point operations may result in a floating-point trap.

Calling Sequences:

FORTRAN:

CALL DFAD (ADDEND, AUGEND, SUM)
CALL DFSB (SUBTRA, MINUND, DIFF)
CALL DFMP (MLTPND, MLTIER, PRODCT)
CALL DFDP (DVDND, DVSOR, QTNT)
CALL SFDP (DVDND, SPDVSR, QTNT)
CALL DCEXIT(ERRLOC)

MAD:

EXECUTE DFAD. (ADDEND, AUGEND, SUM)
EXECUTE DFSB. (SUBTRA, MINUND, DIFF)
EXECUTE DFMP. (MLTPND, MLTIER, PRODCT)
EXECUTE DFDP. (DVDND, DVSOR, QTNT)
EXECUTE SFDP. (DVDND, SPDVSR, QTNT)
EXECUTE DCEXIT. (ERRLOC)

FAP:

TSX \$DFAD,4
OPN ADDEND,TAG1
OPN AUGEND,TAG2
OPN SUM,TAG3

TSX \$DFSB,4
OPN SUBTRA,TAG4
OPN MINUND,TAG5
OPN DIFF,TAG6

TSX \$DFMP,4
OPN MLTPND,TAG7
OPN MLTIER,TAG8
OPN PRODCT,TAG9

SDFDP,4 TSX DVDHD, TAG10 OPN DVSOR, TAG11 OPN QTNT, TAG12 OPN \$SFDP,4 TSX DVDND, TAG13 OPN SPDVSR, TAG14 OPN QTNT, TAG15 OPN TSX SDCEXIT, 4 ERRLOC OPN

where:

OPN is any operation code which allows an address (and tag, if the tag position is used).

TAGI is any index register to modify the operand, except index register 4.

ADDEND Is the location of the high-order part of the addend. The low-order part is at ADDEND+1(FAP), or if the high-order part is at ADDEND(2), then the low-order part is at ADDEND(1).

AUGEND is the location of the high-order part of the augend.

SUM is the location of the high-order part of the sum of the addend and the augend.

SUBTRA is the location of the high-order part of the subtrahend.

MINUND is the location of the high-order part of the minuend.

DIFF is the location of the high-order part of the subtrahend minus the minuend.

MLTPND is the location of the high-order part of the multiplicand.

MLTIER is the location of the high-order part of the multiplier.

PRODCT is the location of the high-order part of the product of the multiplicand times the multiplier.

DVDND is the location of the high-order part of the dividend.

DVSOR is the location of the high-order part of the divisor.

QTNT is the location of the high-order part of the quotient of the dividend divided by the divisor.

SPDVSR is the location of the single-precision divisor.

ERRLOC is the location to which control is to return if the divisor is zero. This should be set by an ASSIGN statement in FORTRAN and MADTRAN programs.

Restrictions:

The tag of an operand may not be 4.

The operands may not be indirectly addressed.

Execution:

DFAD causes the double-precision numbers to be added together. The result is double-precision.

DFSB causes one double-precision number to be subtracted from the other. The result is double-precision.

DFMP multiplies two double-precision numbers together. The result is double-precision.

DFDP divides one double-precision number by another. The result is double-precision.

SFDP divides a double-precision number by a single-precision number. The result is double-precision.

DCEXIT allows the user to specify the location to which control is to go if division by zero is attempted.

Entry Name:

DIH

Purpose:

To duplicate the FAP coding for the FORTRAN built-in function, DIMF, for use with MAD-coded subprograms.

Length:

7 octal locations

Transfer Vector:

None

Calling Sequence:

MAD

EAP

 $X = DIM_{\circ}(Y,Z)$

CALL DIM, Y, Z

STØ

where:

the arguments and functions are floating-point.

Usage:

positive routine finds the The difference between the two arguments,

loeo, Arga -HIN (Arga, Arga).

Identification:

MDDIM appears in columns 73-77 of the binary deck and the symbolic deck.

Entry Name:

EXP Version II

Purpose:

Computes e * for a single floating-

point argument.

Length:

124 octal locations plus four

temporary erasable locations.

Transfer Vector:

None -

Error Procedure:

If the argument is greater than 88.028, the subprogram ERRØR is called. If the argument is less than -88.028, a result

of zero is returned.

Calling Sequences:

EORTRAN

MAD

EAP

EX = EXPF(X)

 $EX = EXP_{\circ}(X)$

CLA X

TSX \$EXP,4

STØ EX

where:

X is a floating-point number between -88.028 and +88.028.

References:

SHARE Distribution Nos. 507

and 571 IB FXP

Purpose:

CTSS SUBPROGRAM

Entry Name:

To compute $I^{\mathbf{J}}$, where I and J are

fixed-point variables.

Length: 45 octal locations plus two temporary

locations

EXP(1

Transfer Vector: None

Error Procedure: None

Calling Sequences:

FAP FORTRAN

CLA I ITØJ = I**J

LDQ J

TSX \$EXP(1,4

STØ ITØJ

where:

is a fixed-point variable, stored in the decrement.

J is a fixed-point variable, stored in the decrement.

ITØJ is the fixed-point result, stored in the decrement.

Entry Name:

EXP(2 Version II

Purpose:

To compute X^{K} , where X is a floating-point variable and K is a fixed-point

variable.

Length:

131 octal locations plus two temporary

erasable locations

Transfer Vector:

ERRØR, LDUMP

Error Procedure:

If there is a large negative exponent and small base, the divide check light is turned on and the subprograms ERRØR

and LDUMP are called.

Calling Sequences:

E	<u>)R</u>		777		EAP	
Y	33 k	X	**	K	CLA	X
					LDQ	K
					TSX	\$EXP(2,4
					STØ	Ÿ

where:

- is a floating-point variable and X
- K is a fixed-point variable, stored in the decrement in FAP.

Entry Name:

EXP(3 Version II

Purpose:

To compute Y**Z, where Y and Z are

floating-point variables.

Length:

236 octal locations plus four temporary

erasable locations

Transfer Vector:

ERRØR, LDUMP

Error Procedure:

If there is a negative base and

non-integral exponent, the subprograms

ERROR and LDUMP are called.

Calling Sequences:

FORTRAN
W = Y ** Z

EAP

CLA Y

LDQ Z

TSX EXP(3,4

STØ W

where:

W, Y and Z are floating-point variables.

Entry Names:

FINT, MINT

Purpose:

To convert FORTRAN Integers to MAD integers, or MAD integers to FORTRAN

integers.

Length:

33 octal locations

Transfer Vector:

WRFLX

Error Procedure:

If a MAD integer is too large to be converted into a FORTRAN integer,

following message is printed:

MAD INTEGER EXCEEDS 32767

and the MAD Integer module 32768 is taken as the argument.

Calling Sequences:

FORTRAN:

EQUIVALENCE (A,J)

A= FINT (1)

I = MINT (J)

MAD:

 $J = FINT_{o}(1)$

INTEGER J, FINT., I

I = MINT.(J)INTEGER LAMINT., J

\$MINT,4

FAP:

TSX \$FINT,4 PZE 1

TSX

PZE J ı

STØ J STØ

where:

refers to a MAD (full word) integer. 1

refers to a FORTRAN (decrement) integer.

is equivalent to J. Α

Execution:

FINT converts a MAD integer If the MAD integer is FORTRAN integer. than 32767, a message is larger printed, and then the integer modulo 32768 is taken as the argument.

MINT converts a FORTRAN integer into a MAD integer.

Entry Name:

FLIP

Purpose:

To transpose a matrix.

Length:

132 octal locations

Transfer Vector:

.03311, EXIT

Calling Sequence:

MAD:

EXECUTE FLIP (NAME, M, N)

where:

NAME

is a two-dimensional array dimensioned

as

(MAX(M,N), MAX(M,N))

M

is an integer variable corresponding

to the number of rows in the array NAME.

N

is an integer variable corresponding to

the number of columns in the array NAME.

Entry Names:

INDV, DPNV

Purpose:

To obtain in floating-point arithmetic the numerical solution of a system of Nth order, non-linear, simultaneous ordinary differential equations, essentially by writing the initial conditions and differential equations in any desired FORTRAN or FAP language.

Length:

626 octal locations

Transfer Vector:

ERRØR, LDUMP

Error Procedure:

If sense light 1 is not on for the first entry to INDV or if there are more than 50 dependent variable statements, the subprogram ERRØR is called. Upon return to INDV, the subprogram LDUMP is called.

Calling Sequences:

FOR'	TRAN	EAP	
χ ==	INDVF(X,H)	CLA	X
	•	LDQ	J
		TSX	\$INDV,4
		STØ	X

where:

X is the independent variable and

H is the increment.

FORTRAN	EAP	
Y = DPNVF(Y,DY)	CLA	Y
	LDQ	DΥ
	TSX	\$DPNV,4
•	STØ	Ý

where:

Y is the dependent variable and

DY is the increment using Adams four point formula.

Reference:

SHARE Distribution Nos. 413 and 827, GL AIDE1

Entry Name:

INT

Purpose:

To duplicate the FAP coding for the FORTRAN built-in function, INTF, for

use with MAD-coded subprograms.

Length:

7 locations

Transfer Vector:

None

Calling Sequence:

MAD

FAP

 $X = INT_{\circ}(Y)$

CALL INT, Y

STØ X

where:

the argument and function are floating-point.

Usage:

The routine truncates the argument (sign of argument times largest integer less than or equal to absolute

value of the argument).

Identification:

MDINT appears in columns 73-77 of the

binary and symbolic decks.

Entry Names:

IØSET, IØPAR, IØEND, IØSCP, IØITR

Purpose:

Calls to these programs are compiled into the MAD program during MADTRAN translation of FORTRAN I/O statements

involving iterations.

Length:

71 octal locations

Transfer Vector:

None

TIA to supervisor:

None .

COMMON:

None

Error Procedure:

None

Calling Sequence:

FORTRAN:

PRINT 1, (A(1), 1 = J,K,L)

where:

PRINT could be also READ, WRITE OUTPUT TAPE, READ INPUT TAPE.

1 is the format statement number.

A is the name of an array where the ith element, i+Lth element, ... (until J+(N*L) is greater than K) will be printed.

MAD:

PRINT FØRMAT ALPHA, L1, IØSET.(LØC1)

EXECUTE IPPAR. (L2) EXECUTE IPEND. (LPC2)

EXECUTE IDITR (V, M1, M2, M3)

EXECUTE ISSCP.

where:

PRINT FORMAT could also be READ FORMAT, WRITE BCD TAPE or READ BCD TAPE.

ALPHA is the format name.

L1 and L2 are normal 1/0 lists.

LØC1 is the location where the MAD sequence begins.

LØC2 is the location where the program will go after completing the list. If omitted, control will return to the statement following EXECUTE IØEND.

V is an iteration variable (usually used for indexing).

M1 is the initial value of the iterative variable $V_{\rm o}$

M2 is the last value of V.

M3 is the increment to be used on V.

Execution:

Executing IØSET will cause the program to leave the I/O list without terminating the format, transferring control to LØC1.

Executing IØPAR will cause the list L2 to be written (or read) as though part of the original I/O list. The format will be continued exactly as though the list were part of the original I/O list.

Executing IØEND terminates the I/O list and returns as indicated above.

Executing IØITR causes V to be set to its initial value, M1, and the values of M2 and M3 to be saved for use of IØSCP.

Executing IØSCP causes the value of V to be compared with M2, and, if less than M2, causes it to be incremented by M3 and then returns control to the beginning of the corresponding iteration; otherwise, control goes to the statement following the EXECUTE IØSCP.

Restrictions:

When used in the list for IMPAR, multiply subscripted arrays must appear with multiple subscripts or with a variable single subscript (i.e., if BB is a multiply subscripted array, then either BB or BB(5) is illegal). IMITR and IMSCP may be nested three deep, but there must be an 'EXECUTE IMSCP.' corresponding to each use of IMITR for proper nesting.

Entry Name:

LØG

Purpose:

Computes the floating-point natural

logarithm.

Length:

127 octal locations

Transfer Vector:

ERRØR, LDUMP

Error Procedure:

if the argument is less than or equal to zero, then control is transferred to the subprogram ERRØR. The subprogram

LØG then transfers to LDUMP.

Calling Sequence:

EOR RAN

MAD

EAP

ELNX = LØGF(X)

ELNX = LØG.(X)

CLA X

TSX \$LØG,4 STØ ELNX

where:

X is a floating-point number greater than zero.

ELNX

is equal to log, X, in floating-point.

Reference:

SHARE Distribution No. 665, 1B LØG 3

Examples:

1) FORTRAN: PRINT 2, (A(1), 1 = 1,20)

MAD: PRINT ØNLINEFØRMAT QQ0002, IØSET. (QQ0003)

QQ0003 EXECUTE | Ø|TR. (1, 1,20,1)

EXECUTE IPPAR (A(1))

EXECUTE IØSCP. EXECUTE IØEND.

2) FORTRAN: PRINT2, ((B(1,J), 1 = 1,3), J = 1,3)

MAD: PRINT ØNLINEFØRMAT QQ0002, IØSET. (QQ0005)

QQ0005 EXECUTE |Ø|TR. (1, 1,3,1) EXECUTE |Ø|TR. (J, 1,3,1)

EXECUTE IPITE. (3, 1,3,1) EXECUTE IPPAR. (B(1,J))

EXECUTE IØSCP. EXECUTE IØSCP.

EXECUTE IPEND.

Entry Name:

MAXO

Purpose:

To duplicate the FAP coding of the FORTRAN built-in function, MAXOF, for

use with MAD-coded subprograms.

Length:

25 octal locations

Transfer Vector:

None

Calling Sequence:

MAD

EAP

 $J = MAXO_{\bullet}(I_{X}, \dots, I_{n})$

MAXO, Izocoolm CALL STØ

where:

the arguments (any number of arguments greater one) are fixed-point and the function İs floating-point.

Usage:

The routine finds the maximum value

of the arguments.

identification:

MDMAXO appears in columns 73-78

the binary and symbolic decks.

Entry Names:

MAXI, XHAXO

Purpose:

To duplicate the FAP coding of the FORTRAN built-in function, MAXIF and XMAXOF, for use with MAD-coded

subprograms.

Length:

22 octal locations

Transfer Vector:

None

Calling Sequence:

MAD	FAP
$J = MAX1.(Y_1,, Y_n)$	CALL MAX1,Y ₄ ,,Y _n
J = XMAX0.(1,,In)	CALL XMAXO, Iz,, In

where:

the arguments and function of MAX1 are floating-point, the arguments and function of XMAXO are fixed-point, and there can be any number (greater than one) of arguments.

Usage:

The routine finds the maximum value of the arguments.

Identification:

MDMAX1 appears in columns the binary and symbolic decks.

Entry Name:

MINO

Purpose:

To duplicate the FAP coding of the FORTRAN built-in function, MINOF, for

use with MAD-coded subprograms.

Length:

26 octal locations

Transfer Vector:

None

Calling Sequence:

MAD

FAP

 $X = MINO.(I_1, \dots, I_n)$

CALL MINO, 1, ..., In STØ X

where:

the arguments are fixed-point

and the function is floating-point.

Usage:

The function is used to find the smallest value of the set, $I_{2},...,I_{n}$

Identification:

MDMINO appears in columns 73-78 of

the binary and symbolic decks.

Entry Names:

MINI, XMINO

Purpose:

To duplicate the FAP coding of the FORTRAN built-in functions, MIN1F and XMIN0F, for use with MAD-coded subprograms.

Length:

23 octal locations

Transfer Vector:

None

Calling Sequence:

MAD	<u>EAP</u>	
$X = MIN1.(Y_1,, Y_n)$	CALL STØ	MIN1,Y ₁ ,,Y _n
$X = XMINO.(I_{x},, I_{n})$	CALL STØ	XMINO, Iz,, In

where:

the arguments of MIN1 are floating-point and the mode of the function is floating-point,

the arguments of XMINO are fixed-point and the mode of the function is floating-point,

and for either entry the number of arguments is greater than 1.

Usage:

The routines find the minimum value of at least two or more arguments.

Identification:

MDMIN1 appears in columns 73-78 of the binary and symbolic decks.

Entry Name:

MØD

Purpose:

To duplicate the FAP coding of FORTRAN built-in function, MØDF, for

use with MAD-coded subprograms.

Length:

14 octal locations

Transfer Vector:

None

Calling Sequence:

MAD

FAP

Z = MØD.(X,Y)

CALL MØD, X, Y STØ

where:

the arguments and function are floating-point.

Usage:

The function is defined as

 $ARG_1-(ARG_1-ARG_2)*ARG_2$, where (X) = integral part of X.

Identification:

MDMØD appears in columns 73-77 of the

binary and symbolic decks.

Entry Name:

RANNO, SETU

Purpose:

Generates a floating-point number between 0 and 1.0 with rectangular distribution. The cycle time for each value of SETU is 2.35.

Length:

42 octal locations

Transfer Vector:

None

Error Procedure:

None

Calling Sequence: for RANNØ-

FORTRAN

MAD

FAP

A=RANNØF(X)

A=RANNØ。(X)

TSX \$RANNØ,4

STØ A

where:

X is a dummy argument.

A is a floating-point random number generated by the formula

$$R_{n} = R_{n-1}(2^{27} + 3) (MØD2^{35})$$

R_o =1 unless the subprogram SETU is used to change it.

for SETU-

FORTRAN

MAD

EAP

B=SETUF(1)

B=SETU.(1)

CLA I

TSX \$SETU,4

0

PÆE ,,5

where:

- is a fixed-point variable used to change the starting value of R $_{\rm o}$.
- B is a dummy argument.

Entry Name:

SIMCS

Purpose:

Simulates a FORTRAN function call to XSIMEQ. This routine is used by the

library subprogram XSMEQ.

Length:

42 octal locations

Transfer Vector:

XSIMEQ

Common:

77775

Calling Sequence:

MADTRN:

CALL SIMCS (MXFR, NFR, LFR, A, B, D, ARY, MFR)

MAD:

EXECUTE SIMCS (MXFR, NFR, LFR, A, B, D, ARY, MFR)

where:

MXFR is a FORTRAN (decrement) integer giving the maximum number of rows the matrix A may have.

NFR is a FORTRAN (decrement) integer giving the number of rows or columns in the matrix A at the time XSMEQ is called.

LFR is a FORTRAN (decrement) integer giving the number of columns in matrix B.

A is an unsubscripted floating-point variable referring to the square matrix A. Upon return, the answers (the X matrix) will replace the A matrix.

B is an unsubscripted floating-point variable referring to the matrix B.

is a floating-point variable by whose value the value of the determinant of the matrix A will be scaled. Upon return, D = D*Det(A).

ARY refers to a one-dimensional array whose length is greater than or equal to NFR.

MFR upon return will contain a FORTRAN (decrement) integer which will be

1 If the solution was successful

2 If an overflow occurred

or 3 If the matrix A is singular.

Execution:

Given the above calling sequence, SIMCS reforms it in such a way as to simulate a FORTRAN function call. XSIMEQ is called by this routine. Upon return from XSIMEQ, the resulting integer value is stored in MFR.

A programmer may call this routine instead of XSIMEQ if he first

- alters his integers to make them FORTRAN (decrement) integers (by multiplying each of them by 2.P.18, or shifting the integers left 18 places, or calling FINT)
- and 2. Interchanges rows and columns in the A and B matrices so they appear as FORTRAN two-dimensional arrays.

and if upon return he

- 1. alters the resulting FORTRAN (decrement) integer to transform it into a MAD (address) integer (by dividing it by 2.P.18, or shifting the integer right 18 places, or calling MINT)
- and 2. Interchanges rows and columns of the X (or A) matrix so it appears as a MAD two-dimensional array.

Restrictions:

All integers are FORTRAN (decrement) integers.

The matrix A must be a square matrix.

The matrices A and B must not be subscripted in the call. Further, their base elements must be set to 1, that is, A(1) is the same as A(1,1).

Reference:

CC-174

Entry Name:

SIN, CØS

Purpose:

Computes the sine or cosine of a

floating-point radian argument.

Length:

172 octal locations

Transfer Vector:

None

Error Procedure:

None

Calling Sequence:

FORTRAN

MAD

FAP

SINX = SINF(X)

SIiIX = SIN.(X)

CLA X

TSX \$SIN,4 STØ SINX

where:

X is the angle in floating-point radians.

SINX is the computed sine of X in floating-point.

Reference:

SHARE Distribution No. 510, IB SIN 1

Entry Name:

(SLI) Version II

Purpose:

To provide list indexing for the

input of nonsubscripted arrays.

Length:

17 octal locations

Transfer Vector:

None

Error Procedure:

None

Calling Sequence:

FORTRAN	EAP	
DIMENSIAN SYMBOL (10) READ 1, SYMBOL	PZE SYMBUL +	
	PZE 100	
	8\$ \$ 99	
	SYMBUL BSS 1	

where:

SYMBØL is the first location in the array to be indexed.

100 Is the number of variables in the array SYMBØL to be transmitted.

Entry Name:

(SLØ) Version II

Purpose:

To provide list indexing for the

output of nonsubscripted arrays.

Length:

17 octal locations

Transfer Vector:

None

Error Procedure:

None

Calling Sequence:

FORTRAN		EAP		
DIMENSION SYMBOL (100) PRINT 1, SYMBOL		TSX PZE PZE	\$(SLØ),4 SYMBØL + 100	1
		•		
		BSS	99	
	SYMBØL	BSS	1	

where:

SYMBØL is the first location in the array to be indexed.

100 is the number of variables in the array SYMBØL to be transmitted.

Entry Name:

SQRT, SQR

Purpose:

Computes the square root of a floatingpoint argument with either entry.

Length:

110 octal locations

Transfer Vector:

ERRUR, LDUMP

Error Procedure:

If the argument is negative, control transfers to the subprogram ERRØR and

then SQRT transfers to LDUMP.

Calling Sequence:

FORTRAN

HAD

EAP

SQX = SQRTF(X)

 $SQX = SQRT_{\bullet}(X)$

CLA X

TSX \$SQRT, 4

STØ SQX

where:

X is a floating-point variable whose square root is to be calculated.

SQX is the square root of X in floating-point.

Reference:

SHARE Distribution No. 703, CS SQT4

Entry Name:

TAN, CUT

Purpose:

Computes the tangent X or cotangent X for any single precision floating-point argument given in

radians.

Length:

244 octal locations

Transfer Vector:

ERRUR, LDUMP

Error Procedure:

If the argument for TAN is greater than 2°-1 or if the argument for CØT is less than 2'2', then control is transferred to the ERRØR subprogram. The subprogram TAN, CØT then calls LDUMP.

Calling Sequence:

FORTRAN

HAD

EAP

TANGX=TANF(X)

TANGX=TAN.(X)

CLA

TSX \$TAN,4 STØ TANGX

where:

X is any single precision floating-point argument given in radians whose tangent is to be computed.

TANGX is the floating-point result of the tangent X.

Reference:

SHARE Distribution No. 507, IB TAN1

CTSS SUBPRUGRAH

Entry Name:

TANH

Purpose:

Computes the hyperbolic tangent of X for any single precision given in argument

floating-point

radians.

Length:

143 octal locations

Transfer Vector:

None

Error Procedure:

Hone

Calling Sequence:

FORTRAN

MAD

EAP

ANS = TANHF (ARG)

ANS = $TANH_{\circ}(ARG)$

CLA

ARG

TSX STANII, 4

STØ ANS

where:

ARG is a floating-point radian argument whose

hyperbolic tangent is to be completed.

is the floating-point result of the AIIS

hyperbolic tangent of ARG.

Reference:

SHARE Distribution No. 507, IB TANN

Entry Name:

XDIA

Purpose:

To duplicate the FAP coding of the FORTRAM built-in function, XDIMF, for

use with MAD-coded subprograms.

Length:

7 locations

Transfer Vector:

Hone

Calling Sequence:

MAD

EΔP

X = XDIM.(1,J)

CALL XDIM, I, J STØ X

where:

the arguments and function are fixed-point numbers.

Usage:

The routine finds the positive difference between the two arguments, i.e., $ARG_{\mathcal{I}} - AIR(ARG_{\mathcal{I}}, ARG_{\mathcal{I}})$.

Identification:

ADXD14 appears in columns 73-78 of

Entry Name:

XDTRM

Purpose:

To allow MAD and MADTRN routines to call XDETRM, a program to compute the value of a determinant. This value is then modified by a scale factor.

Length:

53 octal locations

Transfer Vector:

DETCS, FINT, MINT

Calling Sequence:

AADTRN: A = XDTRMF(A,NØ,A,D)

HAD:

 $M = XDTRM_{\bullet}(N_{\bullet}N\emptyset_{\bullet}A_{\bullet}D)$ INTEGER M.N. HØ, XDTRM.

where:

И refers to an integer whose value is equal to the parameter N in the MADTRN statement DIMENSION A(N,N) or is the third element in the MAD dimension vector describing the matrix A.

NØ refers to an integer giving the number of rows or columns in the matrix A at the time XDTRN is called.

Α unsubscripted floating-point variable referring to the matrix. In a MAD program, base element of this array must be 1. Upon return, this matrix may be altered.

D is a floating-point variable by whose value the value of the Jeterminant will be modified. return, D = D*Det(A).

М upon return will be

- 1 if the solution was successful
- if an overflow occurred
- 3 if the matrix A is singular. or

Restrictions:

This program must not be used by FORTRAN routines.

All integers are expected to be normal MAD address integers.

The matrix A must be a square matrix with the 'base element' in the dimension vector defined as 1.

A in the calling sequence must not be subscripted.

NOTE: XDTRM. must appear in an integer declaration in a MAD program.

Reference:

CC-174

Entry Names:

XINT, XFIX

Purpose:

To duplicate the FAP coding of the FORTRAII built-in function, XINTF and XFIXF, for use with MAD-coded

subprograms.

Length:

12 octal locations

Transfer Vector:

None

Calling Sequence:

MAD			EAL	
J	•	XINT.(Y)	CALL STØ	XINT, Y J
J	332	XFIX.(Y)	CALL STØ	XFIX,Y

where:

the argument is a floating-point number and, the function is fixed-point.

Usage:

The routine truncates the argument (sign of argument times largest integer less than or equal to absolute value of the argument).

Identification:

MDXINT appears in columns 73-78 of the binary and symbolic decks.

Entry Name: XLVC Version II

Purpose: Finds the location where a variable

is stored.

Length: 26 octal locations

Transfer Vector: None

Error Procedure: None

Calling Sequence:

<u>FORTRAN</u> <u>FAP</u>

L = XLØCF(N) CLA N

TSX \$XLØC,4

STØ

where:

N is the variable whose location is to be found.

L is the location of N.

Entry Name:

XHAX1

Purpose:

To duplicate the FAP coding of the FORTRAN built-in function, XMAX1F, for use with MAD-coded subprograms.

Length:

27 octal locations

Transfer Vector:

None

Calling Sequence:

HAD

EAP

 $J = XMAXI_{n}(Y_{1},...,Y_{n})$

XIIAX1, Yy, ..., Yn CALL STØ

where:

the arguments (any number of arguments greater than one) are floating-point and

the function is fixed-point.

Usage:

The routine finds the maximum value of the arguments.

Identification:

MDHX1 appears in columns 73-77 of

Entry Name:

Xella1

Purpose:

To duplicate the FAP coding of the FORTRAN built-in function, XMINIF, for use with MAD-coded subprograms.

Length:

31 octal locations

Transfer Vector:

None

Calling Sequence:

MAD

EAP

 $J = XIIIN1.(Y_1,...,Y_n)$

CALL XIIIN1, Yy Yn

where:

the arguments are floating-point and

the function is fixed-point.

Usage:

The routines find the minimum value of

the arguments.

Identification:

MDXMM1 appears in columns 73-78 of

Entry Name:

XHIDD

Purpose:

To Juplicate the FAP coling of the FORTRAM built-in function, XMODF, for

use with MAD-coded subprograms.

Length:

7 locations

Transfer Vector:

None

Calling Sequence:

HAD

<u>EAP</u>

 $K = XMDD_{\bullet}(I,J)$

CALL L.I. GOMX

STU

where:

the arguments and functions are fixed-point.

Usage:

function defined İs $ARG_{\mathcal{I}}$ -($ARG_{\mathcal{I}}/ARG_{\mathcal{I}}$), where (X) = integral

part of X.

Identification:

PIDXHIDD appears in columns 73-78 of

Entry Names:

XSIGN, SIGN

Purpose:

To duplicate the FAP coding of the FORTRAN built-in functions, XSIGNF and SIGNE, for use with MAD-coded subprograms.

Length:

6 locations

Transfer Vector:

None

Calling Sequence:

MAD

EAP

 $Z = SIGN_{\bullet}(X,Y)$

CALL SIGH, X, Y

STØ

 $K = XSIGN_{\bullet}(1,J)$

CALL XSIGN, I, J

STØ

where:

the argument and function of SIGN are floating-point and the argument and function of XSIGN are fixed-point.

Usage:

The routine does a transfer of sign

(Sign of Arg, times Arg₁).

Identification:

MDSIGN appears in columns 73-78 of

Entry Name:

XSMEQ

Purpose:

To allow MAD and MADTRN routines to call XSIMEQ, a program to solve the matrix equation AX=B for the unknown matrix X.

Length:

116 octal locations

Transfer Vector:

FINT, MINT, SIMCS, FLIP

Calling Sequence:

MADTRN:

M = XSHEQF (HXRØH, N, L, A, B, SCALE, ARRAY)

MAD:

M = XSMEQ. (MXRØW, N, L, A, B, SCALE, ARRAY)

INTEGER M. MXROW, N. L. XSMEQ.

where:

MXRØW

refers to an integer whose value is equal to the parameter MXRØW of the MADTRN statement *DIMENSIØN A(MXRØW_J)*.

Н

is an integer giving the number of rows or columns in the matrix A at the time XSMEQ is called.

L

is an integer variable whose value is equal to the number of columns in matrix B.

A

is an unsubscripted floating-point variable referring to the matrix A. In a MAD program, the base element of this array must be 1. Upon return, the answers (the X matrix) will replace the A matrix.

В

is an unsubscripted floating-point variable referring to the matrix B. In a MAD program, the base element of this array must be 1. This matrix must be dimensioned in MADTRN as 'B(I,J)' where I and J are integer constants each greater than or equal to N.

SCALE

is a floating-point variable by whose value the value of the determinant of the matrix A will be scaled. Upon return, SCALE = SCALE + Det(A).

ARRAY refers to a one-dimensional array whose length is greater than or equal to it.

M upon return will be

- 1 If the solution was successful
- 2 If an overflow occurred
- or 3 if the matrix A is singular.

Restrictions:

This program must not be called by FORTRAN routines.

All integers are expected to be normal MAD address integers.

The matrices A and B must not be subscripted in the call to XSAEQ. Their base elements in their respective dimension vectors must be set to 1.

The matrix A must be a square matrix.

Each maximum subscript of matrix B must be greater than or equal to II, the number of rows of matrix A.

NOTE: XSMEQ. must appear in an integer declaration in a MAD program.

Reference:

CC-174

Entry Name:

.01300

Purpose:

Computes Y where Y and Z are

floating-point variables.

Length:

106 octal locations

Transfer Vector:

SQRT, LØG, EXP, ERRØR, LDUMP

Error Procedure:

The subprogram ERRØR is called if Y < 0 and the Z is not an integer.

Calling Sequence:

MAD

EAP

X = Y.P.Z

CLA Y

LDQ Z

TSX \$.01300,4

STU X

where:

X, Y, and Z are floating-point variables.

Entry Name:

.01301

Purpose:

Computes X^K where X is a floating-point variable and K is a fixel-point

variable.

Length:

43 octal locations

Transfer Vector:

None

Error Procedure:

None

Calling Sequence:

DAM

FAP

 $Y = X_o P_o K$

CLA X

LDQ K

TSX \$,01301,4

STØ Y

where:

X is a floating-point variable.

K is a fixed-point variable stored in the address

in FAP.

Y is a floating-point variable equal to X^{K} .

Entry Name:

.01311

Purpose:

To compute I J where I and J are fixed-point variables.

Length:

42 octal locations

Transfer Vector:

ilone

Error Procedure:

None

Calling Sequence:

MAD

FAP

ITUJ = 1.P.J

CLA

LDQ

TSX \$.01311,4

STØ ITØJ

where:

1, J, and ITØJ

are fixed-point variables stored in the address in FAP.

Entry Name:

.03310, .03311

Purpose:

Computes the linear subscripts for

arrays of two subscripts.

Length:

17 octal locations

Transfer Vector:

None

Error Procedure:

None

Calling Sequence:

MAD

EAP

A(I,J) = ...

CLA

LDQ

TSX \$.03310,4 or .03311 HXT A. ADIN

SUBSCR STØ

where:

Α is the name of the array.

AD Int

is the location of the dimension vector.

I and J

are subscripts.

SUBSCR

is the linear subscript which is returned to the

address of the AC.