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### Identification

The Active Process Table

Robert L. Rappaport, Michael J. Spier, A. Evans

### Purpose

The Active Process Table (APT) is a systemwide data base in segment <tc\_data>; the Traffic Controller maintains an APT entry for every active (see BJ.0 and BJ.6.00) process in the system. A process' APT entry contains all the information about that process that needs be publicly known within the Traffic Controller.

The Traffic Controller also maintains a number of lists threaded through the APT, namely the empty-list, the running-list, the ready-list, the loaded-list and the various event-lists.

### The APT entry

Following is an itemized description of an APT entry, preceded by the entry's EPL declaration.

```
declare 1 apt_entry based (p),
        2 thread,
          3 forward bit (18),
          3 backward bit (18),
        2 level fixed bin (17),
        2 state fixed bin (17),
        2 timer_residue fixed bin (35),
        2 time_last_run fixed bin (71),
        2 process_id bit (36),
        2 load_state fixed bin (17),
        2 wakeup_waiting bit (1),
        2 stop_pending bit (1),
```

2 processor\_required fixed bin (17),  
2 dsbr\_value bit (36),  
2 pstep bit (18),  
2 class fixed bin (17),  
2 event\_thread,  
    3 itt bit (18),  
    3 dst bit (18),  
2 ips\_signal char (4);

thread        an APT entry is always threaded into some list;  
              the threads are pointers relative to the base of  
              <tc\_data>. Unused pointers are reset to zero.

level        this number specifies the ready-list queue  
              into which this process belongs (see ready-list  
              below.)

state        is the process' execution state and can assume  
              one of the following values:  
  
              0 = empty entry  
              1 = process running  
              2 = process ready  
              3 = process waiting  
              4 = process blocked  
              5 = process stopped

time\_residue    whenever the processor is given away, the timer  
                  register gets stored in this item, to be restored  
                  when the process is run again.

time\_last\_run    is a clock reading taken whenever the process  
                  gives its processor away.

process\_id     the process ID

**load\_state** this variable reflects the process' loading state as follows:

- 0 = empty entry
- 1 = process is unloaded
- 2 = intermediate state, process being loaded/unloaded
- 3 = process is loaded, may be unloaded
- 4 = process is eligible

**wakeup\_waiting** is the process' wakeup-waiting switch (see BJ.3)

**stop\_pending** is the process' stop-pending switch (see BJ.4)

**processor\_required** certain processes can execute on specific processors only; if this item is non-zero, the process will be run only on the processor specified.

**dsbr\_value** this is the value loaded into the DBR by subroutine `swap_dbr` (see BJ.7)

**pstep** relative pointer to the process PST entry, needed for process loading/unloading.

**class** is the process' class as follows:

- 0 = empty entry
- 1 = user process
- 2 = system process
- 3 = hardcore process
- 4 = wired-down process
- 5 = idle process

**event\_thread** relative pointer to head of event\_queue (see BJ.3)

**filler** to make the entry an even 16 words long

### The APT lists

As mentioned above, the traffic controller maintains a number of lists threaded through the APT, and every APT entry is always threaded into one of these lists. The APT lists (except event lists) must each satisfy one or more of the following requirements:

1. It must be possible to thread an entry into either the head or tail of the list.
2. It must be possible to thread an entry into either the head or tail of a subset of the list (queue)
3. A queue within a list must be directly accessible (without having to follow the list's thread)

In order to implement these requirements, the APT contains a number of dummy entries, named "sentinels", which consist of only two items as declared

```
declare 1 sentinel based (p)
        2 thread,
          3 forward bit (18),
          3 backward bit (18),
        2 dummy_level fixed; /*level=-1*/
```

and which the APT primitives recognize by their negative level number. These sentinels are threaded into the lists as if they were normal APT entries, yet may be directly accessed.

### The empty list

This is a threaded list of all unused APT entries. It is initially set up by subroutine `tc_data_init`. It is flanked by two sentinels which constitute its first and last entries and which can be accessed by referencing `<tc_data>|[empty_q]` and `<tc_data>|[empty_q]+2` respectively.

### The ready list

The ready-list is the list of all processes which would be running, had a processor been available to them. Whenever a process gives its processor away, it selects the next process to run off the top of the ready list. The ready list

is broken up into a number of sublists (queues) which are separated from one another by sentinels. These queues are used by the scheduler (see BJ.5) to thread different processes into different, pre-determined, relative locations within the ready list. There is a sentinel in front of each queue (and therefore in the back of each queue as well), and in addition there is one at the end of the ready list (for  $n$  queues there are  $n+1$  sentinels.)

Sentinel  $i$  can be accessed by referencing `<tc_data>| [ready_q]+2*(i-1)`. Putting an entry onto the ready list at the head of the third queue means threading it into the list directly following the third sentinel. Similarly, putting it at the tail of the third queue means putting it in front of the fourth sentinel. Searching the ready-list for the highest-priority process means finding the first non-sentinel entry on the list. Primitives are provided in procedure `<pxu>` to do all the threading and unthreading of the above-mentioned lists. (see BJ.8)

### The running list

This is a list of all currently running processes. It is an array of entries, each one consisting of a relative pointer to an APT entry and a pre-emption flag (to be discussed below); each entry is associated with one processor and is accessed by using the processor number as an index into the running list. The size of the array is the maximum number of processors possible (8).

Whenever a process is given a processor to run on, it is unthreaded from the ready list and put on the running list; the relative pointer to that process' APT entry is put in the running-list slot corresponding to the processor, and the associated pre-emption flag is reset to "off".

Whenever a running process is pre-empted, its pre-emption flag is set to "on" to prevent possible recursive pre-emption. This is necessary because it is possible for more than one high-priority process to be made ready while an equal number of low-priority processes is running. Without this flag all the high-priority processes may choose one and the same target-process for pre-emption even though all of the low-priority processes should have been pre-empted.

### The loaded list

This is a list of all loaded processes. It is an array of relative pointers into the APT entries of all loaded processes. This array is dynamically allocated and initialized by `tc_data_init`, to a size corresponding to `tc_data$max_loaded` (consequently, the maximum number of loaded processes in the system must not be dynamically increased). Whenever a process gets loaded, it is entered into this list; it is out of this list that candidates for unloading are selected.

### The event lists

Waiting processes are threaded into event lists, the heads of which are in the PWT. Each event list is associated with a certain event name; all the processes waiting for event 'A' thread themselves into the list associated with event 'A'. A process that detects the occurrence of event 'A' notifies all the processes which are threaded on event list 'A'. The association between event-name and event-list is made in the PWT. (See BJ.2)