

2/3/73

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Memo to

Jerry

Room

Ext.

Thought you might want to hold onto this. It is a collection of documents concerning the partially implemented Dynamo compiler that Martin Jack worked on.

Vic

from

Room

Ext.

~~XXXXXXXXXXXX~~

This term I have transferred the existing 360 PL/I code to Multics.  
This necessitated:

- Coding and testing of `dynamo_operators_`.
- Rearranging `dyn_c_error_` to output messages directly to `user_output`, and elimination of the procedure `edump`.
- Transferring `dyn_trans_` nearly as-is.
- Transferring `dyn_sort_` nearly as-is.
- Transferring `dyn_sdump_` nearly as-is, but changing the method by which the equation numbers were converted.
- Transferring `dyn_ddump_` as is, and fixing a serious bug.
- Recoding `dyn_lex_` completely, incorporating `ctlproc`.
- Rearranging `dyn_codegen_`, and redesigning the object code macros.

In addition, the structure of the data bases was completely rearranged from all static external with refer-based structures to based structures overlaid on working segments.

The object code interfaces and the interfaces with the operating system had to be completely redesigned to fit in with Multics.

What needs to be done to get it working

~~There is some kind of minor bug in `dyn_sdump_` with the cross reference numbers.~~ I think what is happening is that the rightmost digit is being cut off. *fixed.*

The remaining undebugged code: `dynamo_operators_`

The plot routine is in skeleton form right now so that a raw dump of the `v_tabs` can be obtained in order to be sure that they are right before proceeding with a plot routine.

Improvements to the implementation

A macro processor needs to be added, in order to facilitate the implementation of the built-in functions `delay3` and `clip`, which use temporary variables which ought to be generated via a macro call. Also, the table facility should be added as soon as possible, since people use them widely.

It would be hard to say what could be done to the implementation. So much depends upon the reordering phase that a major change would be hard to make. It might be nice to make the symbol table into a hash table, but it has to be linearly scanned so much that that might not be such a good improvement. I think the thing is about as efficient in syntax and codegeneration as it can get. Some minor bit fiddling could be done in reordering but I don't recommend doing anything to it as it is very obscure in places and in fact there is only one person in the world who completely understands how it works, namely JRN, who wrote it.

*dyn\_sdump\_ uses fixed to char conversion  
pw1 & pw2 are currently external static.  
some modules (e.g. dyn\_trans) misdeclare labels so unwinder is invoked.*

The following modules are part of the dynamo compiler:

dynamo\_operators\_

Performs run-time services for the object program which are unwieldy when coded directly in machine language. There are currently two entries: dyninit\_, which initializes the stack frame for the object program from the run-table chains, and dynio\_ which interfaces to the data collection tables and which is called from the object program when it needs to have the data collection tables updated.

dyn\_e\_error\_

Issues diagnostics to the user's console when errors are detected during compilation.

dyn\_trans\_

Performs syntactic and semantic analysis of the source program. It generates the intermediate code chains. It is a stack-driven bounded context analysis program (operator precedence). It performs evaluation of constant expressions.

dyn\_sort\_

This phase reorders the intermediate language according to the cross-reference bits into the order in which the code must be generated.

dyn\_sdump\_

Generates a formatted listing into the listing segment of the identifiers used in the compilation with attributes and references.

dyn\_odump\_

Generates a formatted listing into the listing segment of the state of the ordering table after reordering. This program is primarily a debugging tool.

dyn\_lex\_

This is the lexical analysis routine for dynamo. It is responsible for generating a source listing if requested, parsing the input segment into tokens, returning them one at a time to syntactic analysis, and processing control statements "\$...;". There is an initializing entry setup\_, which sets up internal static variables for the main routine

dyn\_codegen\_

This is the code generator. It uses the intermediate code tree as input and produces GE645 machine code into the object segment.

dyn\_alm\_

This is an alm program used as a transfer vector to obtain external linkage from the dynamo object code. The function of this program is described more completely where the object program environment is described.

## dyn\_odump\_

This rather simple procedure simply uses the ordering table `work_segment_2.order` and the indexing variables `n_l`, `n_s`, `n_a`, `n_r`, and `n_i` to format a listing of the order in which the equations will be compiled to the listing segment.

## dyn\_sdump\_

This procedure produces a formatted listing of the symbol table. It first uses the array `deqn` as a temporary area to sort the symbol table (maintaining indexes to `sym_tab` in `deqn`) via a simple interchange sort.

It then loops over all entries in the symbol table (that is, `deqn`) to print the attribute and cross reference listing.

The first line contains the information from `sym_tab`, that is, a '\*' for `inflag`, and the `def` and `init` pointers, the ASCII name of the symbol, and the type of the symbol (translated to a character string via `sym_type`).

## dynamo

This is the command module, entered from the command processor. It is basically a dispatching module, calling the various phases of the compiler based on the options specified. It also processes the command argument list, creates and truncates the working segments, and initializes the working variables in the common data segments.

## Data Bases

In general, each program has internal automatic variables which are completely local in nature, and in general few in number. Most of the data common to all phases of the compiler is held in two working segments which are declared by the include files `dynamo_1` and `dynamo_2`, and are created by `dynamo` and the static external pointers `pw1` and `pw2` set to point to the created segments.

The first work segment contains element variables which are global in scope, and a large area in which allocation of free storage is done. The second contains an interleaved array in which all of the data which is array-structured is kept. The reason that the array was interleaved is to allow the working set of this segment to vary uniformly with the size of the input program.

Description of dynamo\_1.incl.pl1

Work\_segment\_1 is overlaid on  $\phi$  pd $\phi$  dynamo\_temp1\_.

n\_dev      Number of device interfaces to be generated by codegenerator. This number is currently fixed at 2 but may be made variable at some future time.

n\_est      Number of entries in the constant table, work\_segment\_2.c\_tab.

n\_eqn      Number of equations in the model.

n\_sym      Number of entries in the symbol table, work\_segment\_2.sym\_tab .

n\_var      Number of allocated entries in the cross reference bit arrays, work\_segment\_2.crossv and work\_segment\_2.crosse .

n\_err      Number of entries which have been made in the (new defunct) error table. This field is not currently in use.

sp         Stack pointer (used only by lex\_ and trans\_).

tsp        Stack pointer to tstack (used only by lex\_ and trans\_).

line\_no    Current source program line number.

l\_run      lex\_'s opinion of the current run number. Used for synchronization.

t\_eqn      trans\_'s opinion of the equation number.

t\_run      trans\_'s opinion of the run number.

cc\_code    Maximum severity code of an error detected so far.

n\_a  
n\_b  
n\_l  
n\_r  
n\_s

These five variables are all indexes into work\_segment\_2.order and are used to indicate what order equations are to be generated in. See the picture of the ordering table somewhere else to see what these variables are used for.

m\_comp    Extent of the ordering table, work\_segment\_2.order .

first\_run Set to indicate that the first run is in progress. This is an indicator to dynamo\_operators\_\$dyninit\_.

lhs        Set to indicate that parse is on the left side of an equation. Used only by lex\_ and trans\_.

lnext     Next available character in the listing segment.

lseg      Length (in characters) of the source segment.

psource   Pointer to the source segment.

pobject   Pointer to the object segment.

pentry    Was supposed to have been a pointer to the entry point of the object segment. Is not being used now since same as pobject.



**crossv** Reordering cross array, by variable (cross field of sym\_tab).  
**crose** Reordering cross array, by equation number (n\_eqn).  
**deqn** Used in reordering.  
**eqns** Equation table. Usage: ← ?  
**dsym** Used in reordering.  
**dzar** Used in reordering.  
**eq\_tab** Pointer to the intermediate text blocks for the ~~variable~~ equation.  
**order** Indexes in eq\_tab for the result of the reordering process. The variables n\_a, n\_i, n\_r, n\_s, n\_l give indexes in order for the different variable types. See the picture.

**DESCRIPTION of dynamo\_m.incl.pl1**

Formats of the intermediate text blocks.

**MATRIX** (A line with two arguments)

**chain** pointer to next block or null.

**op** Operation code for this line

**t1** Type of operand 1 (sym\_tab.type field)

**tp1** See 1.2.



## Description of module dynamo

First off, we output a message to the user's console indicating that we are working. Then, all of the options given are processed. We make sure that at least one argument (pathname of source program) exists and then process the 2nd through nth arguments, trying to match them against the valid options in `arg_tab`. For each one which was given, we set the corresponding bit in `arg_bit`. For options not recognizable, we call the error handler to issue diagnostics. Then, the three temporary segments are made by a call to `make_seg`.

We then process the pathname of the input program. We check for the suffix `.dyn` and add it if necessary, and then call `expand_path_` to get the full pathname. Then, we initiate the segment, and set the appropriate variables in work segment 1. The remaining variables in the two working segments are then initialized. The first `r_tab` is allocated and initialized. If any options requiring the presence of a listing segment have been given, then a listing segment is created in the working directory.

After this point, a simple set of calls are made to the appropriate modules of the compiler based on the success of compilation as measured by `cc_code`, and the option flags. When compilation and execution are complete, the code following the label `quit` terminates the source segment, sets the bit count on the listing segment and terminates it, and then truncates the working segments.

Description of module dyn\_alm

*(see description of the procedure dyn\_codegen-)*

This module is the means whereby the dynamo object program is able to make external references. The second word of the object program is initialized with a pointer obtained via make\_ptr to the entry dyn\_alm\_\$dyn\_tv\_, and the following calling sequence is used to reference an external entry:

lxl5	offset,d1	load the offset in transfer vector
stcd	sp/20	save return point
tra	2,*	transfer indirect through saved pointer to transfer vector

Within the transfer vector, the first instruction transfers to location 1 indexed by the contents of index register 5, thereby accessing either an external symbol or an alm subroutine coded in dyn\_alm\_. These ]

*← status now?*

## Description of module dyn\_trans\_

This module performs syntactic and semantic analysis. It uses an operator precedence analysis technique to parse the input stream.

The top of loop is at bca, where the equation counter is incremented, and a left pad is put on the stack. One token is lexed, and checked for identifier. If not, then a syntax error exists. The next token is check for "=". If not, then one is inserted. Then, precedence analysis is used to determine where the reducible phrases are.

Semantics for constant operator constant are to evaluate the constant expression, placing the result into the next available spot in c\_tab, and reduce the source. When a constant\_variable = constant is recognized, an rv\_tab is allocated and added to the chain off r\_tab.rvars, and initialized so that the constant variable will be initialized at run time by dyninit\_.

? → For arithmetic operators, the routine ~~is~~ iop allocates and chains a binary matrix line block and fills in the appropriate fields. If the operator is assignment, then end of statement has been reached and cleanup occurs.

Unary minus operations are accomplished by adding a unary minus matrix block or in the case of a constant placing the negative of the constant indicated into the next c\_tab location.

Exponentiation is handled as a constant evaluation if possible, or a function-call matrix is allocated, and initialized. The name of the function invoked is "\*\*\*exp". For function calls, the appropriate function call matrix line is allocated, and initialized.

When the stack is to be cleared after the end of a statement, the variables t\_run, t\_eqn, and l\_run are examined and set for synchronization with lex regarding end of statement. | ?

## Description of module dyn\_lex

Dyn\_lex has the function of returning one lexical token on the syntactic analysis stack when called at entry point dyn\_lex. It must be initialized via a call to dyn\_lex\$setup\_first. It will also process control statements in general by modifying the run table chains.

A lexical token comprises a ~~type, code, and name~~ <sup>token, type, and name</sup> cell. The following codes are used:

token	<del>type</del> = 0 **	1 *	2 /	3 +	4 -
	5 =	6 un-	7 ,	8	9 ;
	10 (	11 )	12	13 idn	

type (for token=13)

0 .j	1 .k	2 .jk	3 .kl
4 nosub	5 const	6 matr	

name (for token=13)

for type=0,1,2,3,4	- index in sym_tab
type=5	index in c_tab
type=6	matrix line number

(The token=6,8,12 and type=6 indications are set only by dyn\_trans\_.)

The internal procedure endline is called when a newline character is encountered. It increments the line counter, and outputs the line just completed to the listing if a source listing has been requested.

The internal procedure nextokn returns the next token to the caller (either lex or ctlproc) as nptr, nmod, and ntyp. The rules are as follows: if the bit eof is on, then return. Skip all blank, tab, and newline characters before the next ~~nonblank character~~ significant character. Set nptr to point to the significant character. If this character is numeric, then the token is a numeric item. If a special character, then the token is an operator. Otherwise, it is an alphabetic item.

For operators, the special cases \*\*\*, ;"=, and comments are recognized. The handling of each of these is relatively straightforward. For single character operators, nmod will have already been set to the token field above.

Numeric items are delimited on the right by a special character, blank, tab, or newline. Alphabetic tokens have the same restrictions, except that the time subscript has to be checked for and returned as nmod.

The ~~mainline~~ <sup>dyn\_trans</sup> code checks if anything has been placed on the temporary stack (trans can place tokens on this stack if it wants to insert a token for error handling.) If so, then this token is returned. If a \$run; statement has been encountered, a right pad is returned, or if physical end of data on the segment has been reached, a right pad is also returned. Otherwise, a call is made to nextokn to ~~get~~ get another token, and the processing depends upon the type (operator, numeric literal, identifier).

For operators, the flag lhs (left hand side) is set or reset if an ;"= or ;" is reached. If the \$ character occurs, then ctlproc is entered

to process the control statement which follows. If the construction "!=" occurs, this is returned as token=5,type=1, to distinguish from "=", which is returned as token=5,type=0.

For literals, the character string token is converted to floating point and stored in the next available c\_tab position, and returned as token=13, type=5, name=index in c\_tab.

For identifiers, the symbol table must be searched to determine if the identifier already was recognized. If so, then token=13, type=some function of the time subscript given by tp\_tab, and name=symtab index. If the identifier must be entered, then the symbol table entry must be initialized, and a slot allocated in the cross reordering array. The pointer n\_var is updated to indicate the allocation, and the index in crossreorder(\*) is stored in sym\_tab.cross. The cross arrays are updated to indicate usage on the right and left hand sides, and multiple declaration and initialization are checked for. The token is then added to the stack.

The routine gitproc processes all control statements. The variable ntoken will contain the verb (~~run~~ (run, dev, spec)).

For a \$run statement, a check is made to be sure that the dt and length fields are filled in for the previous r\_tab, and that some \$dev statements were supplied, and then a new r\_tab is allocated chained and initialized. The input stream is then flushed to the next semicolon.

For a \$spec dt=length; statement, the routine kw\_parse is used to obtain the parse of the keyword expression and then r\_tab.dt and r\_tab.length are filled in with the user's values.

For a \$dev unit=outper=idn= statement, a dv\_tab is allocated and added to the device chain for the run. For each identifier specified, a pv\_tab is allocated and chained to the newly allocated dv\_tab. If an identifier which has not yet been encountered is used in a \$dev statement, it is given a type of -2 so that a type conflict diagnostic will not be produced, and a contextual type can be assigned later when more information is available. The dv\_tab is not chained to the r\_tab until all parameters on the statement have been scanned so in the event of an error no effect will remain.

The routine kw\_parse uses an lr(0) parse (DeRemer's thesis PhD MIT) using an encoded finite state machine to parse the keyword control statements. Its operation is rather straightforward.

## Description of module dyn\_sort

This module uses the reordering cross arrays `crosses` and `crossv` and the `array order(*)` to produce an indication of which equations are dependent upon one another and therefore resolve the order in which the equations should be compiled. The groups are taken in the order supplementary, auxiliary, initial value, levels and rates. The operation of this module is extremely complex and it is recommended that the author, John R. Nestor, be contacted if modifications are to be made.

Description of module dynamo\_operators\_

This module performs run-time services for the dynamo program.

The entry dyninit\_ initializes the object program's stack frame.

The length cell is set to minus the number of iterations over the model so that a test can be made by the object program via aos-tnz whether enough iterations have been made. The cells variables(54) and (55) contain the values of dt and time. These values are obtained from r\_tab, for the current run.

For the first run of a group, the constant variables all have to be initialized, and the sym\_tab.init cell is set to the c\_tab index for the appropriate value. If not the first run, only the non-permanent constants are initialized from the rv\_tab.chain; the others are initialized from the sym\_tab.init field, so that permanent constants can be retained. For permanent constants, the sym\_tab.init field is reset so that subsequent reruns will obtain the new value of the constant.

Finally, the v\_tabs for each of the variables to be output are allocated and attached to the appropriate pv\_tab.

The entry dynio\_ collects the values of variables for later printing or plotting. It loops over all devices active that is dv\_tabs, and for each pv\_tab extracts the value of the associated variable (the index within variables(\*) is contained in the sym\_tab.def field) and enters in the v\_tab.

## Description of module dyn\_codegen

This module is the dynamo code generator for Multics. It generates GE645 machine language directly into the object segment. The object segment is not in the standard Multics format, but rather depends upon support code within the compiler for execution time services and its environment. The input to the code generator is the intermediate language tree constructed by the semantic translator and as reordered by the reordering phase.

Some portions of code generated by the code generator are fixed in nature, and are stored in arrays of static initial bit strings and copied into the object segment with some minor filling in of offsets, numbers, and so forth. Code which is generated for the matrix lines ~~is~~ in general more variable and is generated by encoded macros.

Storage allocation is the first task performed by the code generator. All storage for variables declared in the dynamo program is held in the stack. Some storage is obtain after the initial 32 word header for internal compiler and run-time variables, and then programmer variables are allocated beginning at offset 54 from the sp.) For level and rate type variables, two words are allocated, and for ordinary variables, one word is allocated. No particular alignment of the two word allocations is observed.

Next, the working variables lbound(\*), hbound(\*), and incr(\*) are initialized to indicate what areas of eq\_tab will be examined and in what order. The general form of the object code is shown in fig. 1.

The procedure prologue code is generated first. The variable loc contains the index within object\_bits (which is overlaid on dynamo\_object\_) which is currently the first unused location. The procedure prologue adjusts the sp (performs a standard Multics save sequence), stores the current value of sp in words 6 and 7 of the object code for dynamo\_operators\_, establishes the value of bp by loading from word 4 and 5 of the object code where a pointer to dynamo\_temp2\_ has been stored, and performs the first part of the call sequence. It then calls the 0th entry in the transfer vector, which is dynamo\_operators\_\$dyninit\_, which completes the initialization of the object programs stack frame via reference to the run table information.

Next, code is generated for the initial value equations which contain expressions. This is done in the main loops. There are two nested loops. One goes from 1 to 5 and references the lbound and hbound arrays; the other goes from lbound(i) to hbound(i). Within that loop, one simply chains from eq\_tab(\*) which the chain pointer is not null.

Following initial value equations, a short piece of code is generated to transfer around the calculations which follow and to re-enter just before auxiliary equations are generated. This branch, being forward, is fixed up after the level equations are generated. Then, auxiliaries are generated, followed by a piece of code to test for a print or plot time.



?

There is one word in the stack at offset 35 which contains flags used by the print/plot data collection interface `dynio_`. Bits 16 and 17 of this word correspond to devices 1 and 2 and when set indicate that the "outper" for this device has expired and that data should be collected on the current call to `dynio_` for all `pvars` chained from that `dv_tab`. The outper is maintained in words 36 and 37 of the stack and they are set such that an `aos` on each loop will cause decrementing to zero when the interval next expires. The code generated after rate equations does `aos` on these words, tests for zero, and if zero sets the appropriate bit in word 35. Finally, the supplementary equations are compiled, and a test is made of the device flags in word 35 to determine if either of them is on, thereby indicating that data is to be collected for some device on the current loop. If so, a call is made to `dynamo_operators_$dynio_` to collect the data. Next, the generated code in epilogue code adds `dt` to time to get the new value of time, swaps the `.j` and `.k` index registers, inverts the `jk-bit` in word 35 (this ~~mask~~ bit is used by `dynio_` to figure out if `.j` or `.k` comes first in the two-word level and rate slots), does an `aos` on word 34 which contains the negative of the number of loops over the model equations to be made, and if this word has not been incremented to zero, branches back to the level equations to begin another loop. If it is zero, then the standard Multics return is made.

The processing performed for generation of code for matrix lines is now described. First, the opcode is extracted and assigned to the variable `op`. If zero, then a function matrix line has been encountered. First, a temporary is obtained to store the result in `(rt)`. `tc(rt)` is set to indicate that temporary `rt` contains the result of the current matrix line. Then, the accumulator is stored into a temporary if `rc` is not zero, so that it can be preserved over the call. Next, the name of the function is looked up in `func_tab`, and the index is saved in `fx` for the `lxl5` instruction. Next, if the location counter is not even, a `nop 0,du` instruction is generated for alignment. Next, a loop is made over all arguments to the function. A search is made for the location of the argument in storage and an appropriate address halfword and modifier bits are constructed (description below). An `eapap` and `stpap` instruction are generated to get the address into the parameter list for each one. Following that, an `eapap` and `stpap` get the address of the result temporary into the parameter list. ~~Next~~ Next, an `eapap` instruction loads the address of the parameter list into the `ap`, and a `tra` branches around it. Following the parameter list, an `std` and `tra 2,*` get through the transfer vector to the desired function. This completes processing for function calls.

If not a function matrix line, then there is at least one operand. The first operand is located by noticing what the `t1` field of the matrix line contains. If a 6, then it is a matrix result, and is either in the `a-register` or in a temporary. The bit `op1nir` is set if `op1` is not in a register. The `op1addr` is set to the offset in the stack of the temporary where it is stored, and `op1modifier` is set to zero so that no address modification will be performed. `Op1temp` is set ~~to~~ to the number of the temporary so that it can be released at the end of generation of this matrix line (it cannot be released now; in the event another temporary is required during the generation, it would overlay the data).

If a constant (type 5), then the offset from the object-time contents of the bp is determined via the `ral` function, and `opladdr` is set. `op1modifier` is set to zeros, and `op1nir` is set to indicate not in a register. Otherwise, the operand is a programmer variable, and the field `sym_tab.def` will have been set by the storage allocator to the offset of the allocation within the stack. `Op1addr` is set to this address, and `op1modifier` is set to the appropriate address modifier (0 for an ordinary, x1 for a .j, and x2 for a .k). The array (`typ_mod`) makes this conversion.

If the matrix line is a unary minus, then the operand is loaded if not in a register, and the `fneg` instruction generated to reverse the sign.

If not a `uminus`, then the second operand is found as for the first, and the corresponding `op2...` variables set.

For an assignment matrix block, if the operand is not in a register, it is loaded, and then a store instruction is generated to store the data into the new assignment.

For arithmetic operations, the machine instruction generation depends upon whether the operands are in registers and whether the operation is a commutative one.

For neither operand in a register, a (store) load operate group is generated. The array (`arithops`) contains the opcodes for the four instructions (`fad`, `fsb`, `fmp`, `fdiv`). For one operand in a register, if the correct one, or if the operation is commutative, then the correct operation is generated. If not the correct one, then a store load operator group is generated. ~~XXX~~ The variable `rc` is set to indicate that the AC contains the result of the current matrix line, and the next line is processed.

Cleanup for the current line consists of resetting flags, and freeing temporaries where indicated by the `opxtmp` settings.

## INTERMEDIATE LANGUAGE

The intermediate language tree is a series of threaded lists, one per equation, chained from eq tab(\*). The array order(\*) indicates in what order the equations are to be compiled, as given in the diagram.

There are three formats of intermediate language line blocks. One is used when a binary operator is indicated:

```
dcl 1 matrix based,  
    2 chain ptr,  
    2 op fixed bin,  
    2 t1 fixed bin,  
    2 op1 fixed bin,  
    2 t2 fixed bin,  
    2 op2 fixed bin;
```

*explain  
rules*

~~The second is used when a unary operator is indicated:~~

A second is used when a unary operator is indicated:

```
dcl 1 matrix1 based,  
    2 chain ptr,  
    2 op fixed bin,  
    2 t1 fixed bin,  
    2 op1 fixed bin;
```

A third is used for function invocations:

```
dcl 1 fmatrix based,  
    2 chain ptr,  
    2 op fixed bin,  
    2 name fixed bin,  
    2 n_args fixed bin,  
    2 arglist (i refer (n_args)),  
    3 type fixed bin,  
    3 narg fixed bin;
```

The type and narg fields correspond to the t and op fields of the previous blocks. The name field is a unique identifier assigned to a function name, and is the index of the name in the symbol table.

The op field is as follows:

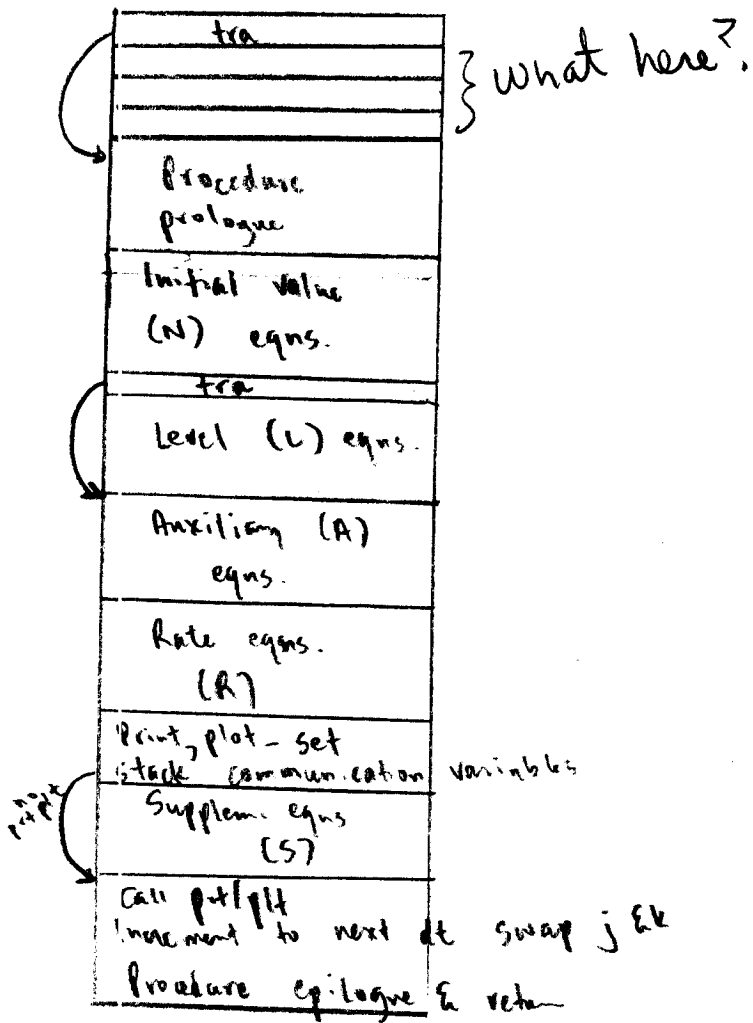
0	function
1	*
2	/
3	+
4	-
5	=
6	unary -

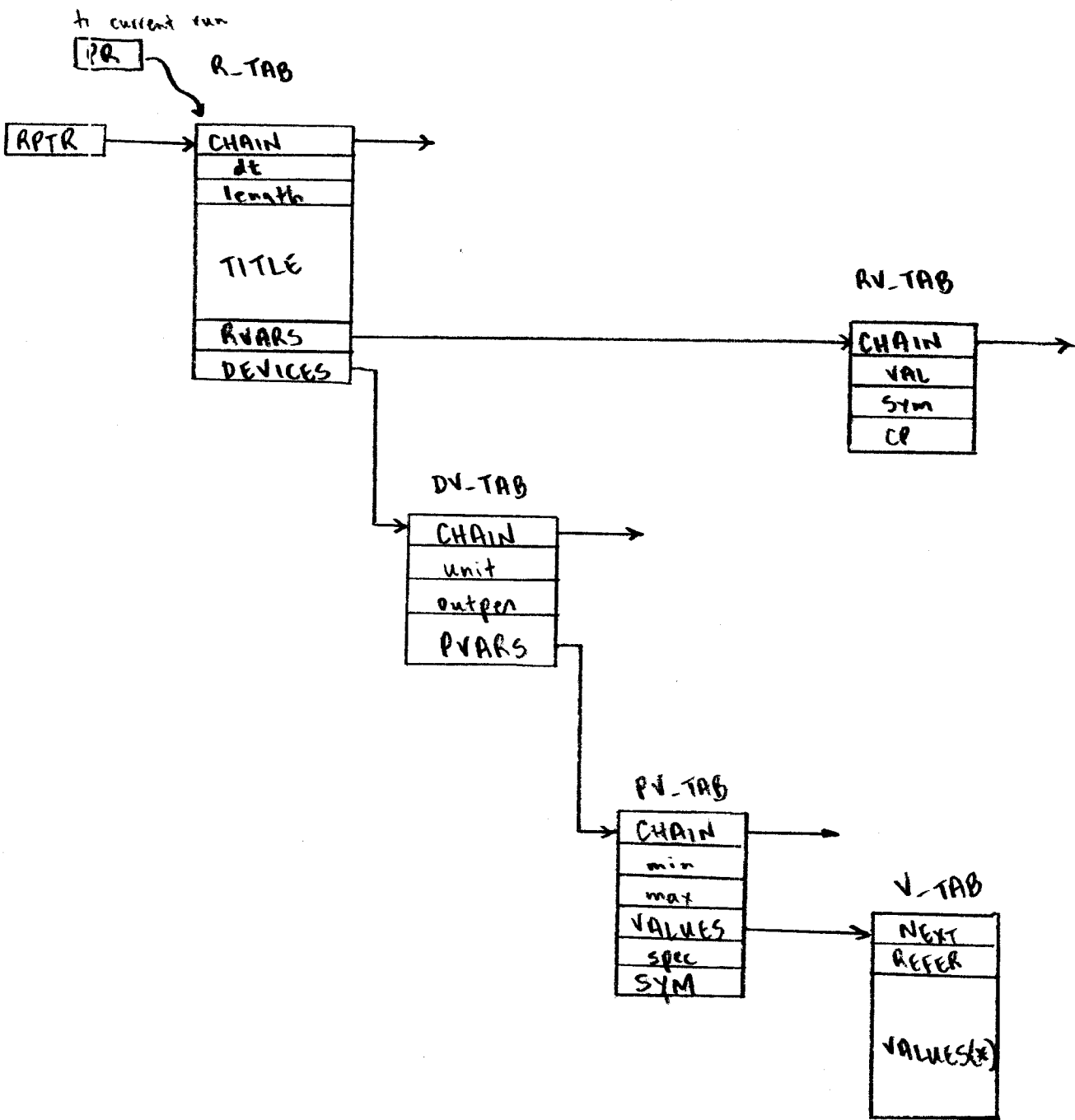
The type fields are as follows, with the operand field corresponding:

type = 0	.j	name = index in symtab
1	.k	''
2	.jk	''
3	.kl	''

4 ordinary  
5 constant (literal)  
6 matrix result

!!  
index in c\_tab  
line number in this equation.





# I Operator Codes

CODE	STACK-LEX	STACK-TRANS	MATRIX Operators
0	**	**	Function Call
1	*	*	*
2	/	/	/
3	+	+	+
4	-	-	-
5	=	=	=
6		- unary	- unary
7	,	,	
8		+ SOS	
9	;	;	
10	(	(	
11	)	)	
12	EOF	EOF	
13	NAME-NUMBER	NAME-NUMBER-MATE	

## II SYMBOL TABLE

```

DCL 1 SYM-TAB(M#SYM) CTL,
    2 NAME CHAR(32), IFLAG BIT(1),
    2 TYPE FIXED BIN(15),
    2 CROSS FIXED BIN(15),
    2 OFF FIXED BIN(15),
    2 INIT FIXED BIN(15);
  
```

INDEX → DCL #SYM FIXED BIN(15) STATIC;

CROSS - Index in CROSS

OFFSET FROM CROSS

0 - ORDINARY,	00	.00
10 -	.J	.JK
2 -	.K	.KL

DEF - EQN # defined in or 0 - undefined

INIT - EQN # initialized in or 0 - uninitialized

IFLAG - VALUE CAN BE CHANGED FOR RE RUNS ('I'B)

TYPE 0 - ORDINARY

1 - LEVEL TYPE AUXILIARIES

2 - RATE

5 in Trans → 3 - Function

4 - MACRO

5 - ~~RECORD~~

6 - ~~Supplementary~~

RA

↑

Set in Lex

LEVEL

Supplementary

↳ SET IN SORT



### III MATRIX

DCL 1 MATRIX BASED (MPTR),  
2 CHAIN PTR,  
2 OP FIXED BIN(15),  
2 T1 FIXED BIN(15),  
2 OP1 FIXED BIN(15),  
2 T2 FIXED BIN(15),  
2 OP2 FIXED BIN(15);

Unary -

DCL 1 MATRIX1 BASED (MPTR),  
2 CHAIN PTR,  
2 OP FIXED BIN(15),  
2 T1 FIXED BIN(15),  
2 OP1 FIXED BIN(15);

FUNCTIONS

DCL 1 FMATRIX BASED (MPTR),  
2 CHAIN PTR,  
2 OP FIXED BIN(15),  
2 NAME FIXED BIN(15),  
2 #ARGS FIXED BIN,  
2 ARGLIST (N REFER(#ARGS)),  
3 TYPE FIXED BIN(15),  
3 NAME FIXED BIN(15);

OCL AREA AREA (AMSIZE) CTL;

OCL C PTR BASED (CHAIN1);

OP - See PART I

NAME - Index in SYM-TAB OF FUNCTION NAME

#ARGS - NUMBER OF ARGUMENTS

STACK-TYPE TYPE, T1, T2		STACK-NAME OP1, OP2, NARG
0	.J	} INDEX IN SYM-TAB
1	.K	
2	.JK	
3	.KL	
6	MATRIX RESULT	MATRIX BLOCK#
4	ORDINARY VARIABLE	INDEX IN SYM-TAB
5	CONSTANT	INDEX IN C-TAB

## IV STACK

```
DCL 1 STACK (MAXS) CTL,  
    2 TOKEN  FIXED BIN(15),  
    2 TYPE   FIXED BIN(15),  
    2 NAME   FIXED BIN(15);
```

INDEX → DCL    SP0    FIXED BIN(15)    STATIC

TOKEN - SEE PART I

TYPE, NAME - SEE PART III