

Clock services provided by the supervisor

The supervisor, with the aid of certain hardware devices, provides

two fundamentally different types of clock services: real-time services

and process time services. ~~The difference is that the real-time services~~

process. Process time services are those connected with clocks which "tick"

only while the process is in control of a processor. Both real-time

and process time services ~~offer~~ include internal measurement and

internal event interrupt. The precise specification of these services

~~does not~~ assume ^{hardware} implementation of the proposed system of clocks.

Real-Time Services

Three real time services are provided: Calendar time, real-time interval measurement, and real-time interrupt interrupts. All real-time services utilize words of 52-bit precision and use a fundamental time unit of microseconds.

1. Calendar Clock: ^{real-time interval measurement} The calendar clock contains the number of microseconds since Jan 1, 1980. Although this value may be inaccurate by a millisecond or more, ~~the successive ticks of the calendar clock will have different times between successive ticks~~ the calendar clock will be ~~sometimes~~ accurate to one part in a million, or 10^{-6} , whichever is ~~more~~ greater. The value of the clock is read by a ~~special program instruction~~ ^{clock-read}; a ~~PL/I subroutine~~ will also be provided. A supervisor subroutine is available to reset the value of the ^{calendar} clock:
 - call Calendar-clock (I)
 - sets the 52-bit integer variable I to the current calendar clock value.

2. Real-Time Interval Interrupts. An interrupt signal may be generated will be set to a process at a specific time if the process calls a request:
- call Set-Time-interrupt (^{request}_{Calendar time})

~~which agrees~~ the process should take care to make, for some processes
~~the time~~ interrupt before it occurs.

A process may set or modify several real-time interrupt, for different times if desired.

Note that although the interrupts signal to the process will occur at the process time requested, the process may not get control for some time due to scheduling and swapping depending on system load.

To cancel a real-time interrupt request
 to get rid of a time interrupt which has been set, the call

call Delete-time-interrupt (^{request}_{Calendar time})

is provided.

A library package must be provided for PCL I
 A library package can be provided which will accept multiple standard calls several time interrupt time, and allow selection deletion of them requests, and control enabling of interrupt processes.