

# Inflating the Cube by Shrinking

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## ABSTRACT

We present a continuous submetric deformation of the surface of the cube which increases the enclosed volume by about 25.67%.

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**General Terms:** Theory

**Keywords:** Submetric embeddings, surface deformation

## 1. INTRODUCTION

Every polyhedral surface in  $\mathbb{R}^3$  has a volume-increasing isometric deformation [7]. However little is known about isometric embeddings maximizing the volume. For the polyhedra typically studied, i.e., platonic solids and doubly covered two-dimensional shapes, there is a large gap between the lower and upper bound for the maximum enclosed volume. We address the problem of how large the volume of a body with a surface isometric to that of a cube can be.

An embedding  $h : S \rightarrow \mathbb{R}^3$  of a surface  $S$  in  $\mathbb{R}^3$  is *isometric* (resp. *submetric*) if the length of any rectifiable curve in  $S$  is constant (resp. non-increasing) under  $h$ . An isometric (resp. submetric) deformation is a continuous map  $H : S \times [0, \varepsilon_0] \rightarrow \mathbb{R}^3$  such that  $h_\varepsilon(\cdot) := H(\cdot, \varepsilon)$  is an isometric (resp. submetric) embedding for all  $0 \leq \varepsilon \leq \varepsilon_0$ . Instead of isometric embeddings, submetric embeddings can be used since every submetric embedding of a polyhedral surface has an isometric embedding arbitrary close to it [4, 7].

The idea of considering volume-increasing isometric embeddings is due to Bleecker [2]. He proves that a volume-increasing continuous isometric deformation exists for every simplicial convex surface in  $\mathbb{R}^3$ . By Alexandrov's uniqueness theorem [1] a body resulting from such a deformation must be non-convex. By Bellows conjecture (proved in [5]) the deformation does not preserve the faces of the polytope.

Recently, Pak [8] gave an easy construction for increasing the volume of the unit cube to about 1.1812 based on the work of Milka [6]. A more involved construction of Bleecker [2] yields a volume of about 1.2187. A simple upper bound of about 1.3820 can be obtained by the volume of the sphere which has the same surface area as the cube.

In this paper, we present a *shrinking*, i.e., a continuous, submetric deformation of the unit cube for which the resulting volume is at least 1.2567. We first present a simple construction which we then refine. This also improves the

lower bound on the volume of a surface isometric to that of a unit cube. Detailed calculations for the constructions in this paper can be found in [3]. The idea of looking at shrinkings in order to get isometric embeddings is due to Pak [7].

## 2. FIRST CONSTRUCTION

We present volume-increasing submetric embeddings of the cube. The embeddings are parametrized by  $\varepsilon \in [0, 0.5]$ . Increasing  $\varepsilon$  from 0 yields a continuous deformation. We first present a construction with volume about 1.2444, which we improve in the next section.

Our approach is a refinement of Igor Pak's work [7, 8]. The original cube is given as the convex hull of the set  $\{0, 1\}^3$ . We denote vertices on the surface of the cube by  $p_i$ . The same vertex in the deformed cube is denoted as  $v_i$ .

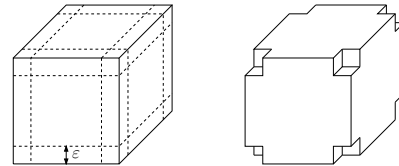


Figure 1: Cutting off  $\varepsilon$  cubes.

First we cut off  $\varepsilon$ -cubes at every corner of the cube (see Figure 1). Next we deform the remaining part of the cube. We place one vertex in the middle of every  $\varepsilon$  segment (see Figure 2.a). The segments between  $p_1, p_{5/4}, p_{3/2}, p_{7/4}, p_2$  have the length  $\varepsilon/2$ . Let the framework induced by this chain be  $C$ . We move the vertices of  $C$  such that  $v_1, \dots, v_2$  lie on a quarter-circle (see Figure 2.b). We apply the deformation for all corresponding pairs of  $\varepsilon$  segments. This leads to a body that we divide into a *corpus* and 12 bars. The 8

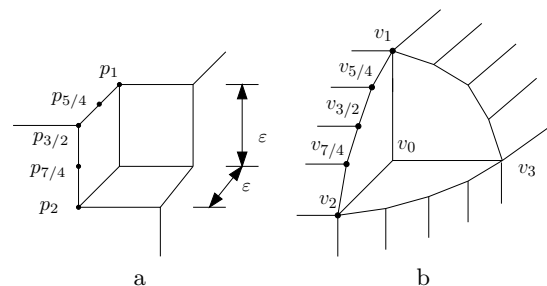


Figure 2: Bending the chains induced by a pair of  $\varepsilon$  segments.

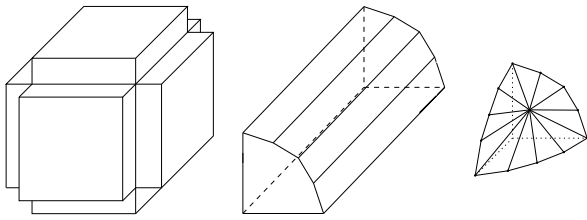


Figure 3: Corpus and bar and star.

cut off parts are called *stars*. Figure 3 shows the deformed parts. After the deformation a bar is a prism with a 6-gon as base area. The 6-gon is inscribed in quarter circle. Its shorter edges have the length  $\varepsilon/2$ . The radius of the quarter circle is denoted by  $\delta$ . The volume of one bar is given by

$$V_{bar} = 2(1 - 2\varepsilon)\delta^2 \sin(\pi/8).$$

The corpus is the remaining part after cutting off the bars. Its volume is given by

$$V_{corpus} = (1 - 2\varepsilon)^3 + 6\delta(1 - 2\varepsilon)^2.$$

It remains to place the deformed stars at the corners of the body. We have to deform the  $\varepsilon$ -cubes, such that they fit into the open 12-gons formed by three chains  $C$  of the body. Consider the open part depicted in Figure 2.b. The deformed star is the convex hull of the vertices on the chains between  $v_1, v_2, v_3$  together with  $v_0$  and a vertex  $v_*$ . The coordinate of  $v_*$  is chosen in such a way, that the embedding is submetric. We place  $v_*$  on a line given by  $x = y = z$ . This yields coordinates  $v_* = (0.9764\varepsilon, 0.9764\varepsilon, 0.9764\varepsilon)$ .

Finally, we have to evaluate the volume of the stars. Each star is divided into tetrahedra. There are two types of tetrahedra, one is given by the convex hull of  $v_0, v_1, v_{5/4}, v_*$  and the other by the convex hull of  $v_0, v_{5/4}, v_{3/2}, v_*$ . Both tetrahedra appear 6 times in every star. That leads to a volume of a star of

$$V_{star} = 1.227259706\varepsilon^3.$$

Now we can evaluate the volume of the complete body which is

$$V = V_{corpus} + 12V_{bar} + 8V_{star}.$$

See Figure 4 for the graph of  $V(\varepsilon)$  for feasible values of  $\varepsilon$ .

The volume  $V(\varepsilon)$  is maximized at about  $\varepsilon_0 = 0.351311$ , which yields a volume  $V(\varepsilon_0) = 1.2444$ . This improves the bound of Bleecker [2]. The deformed cube for this value of  $\varepsilon$  is shown in Figure 5. Each star has 3 concave edges depicted as dashed lines.

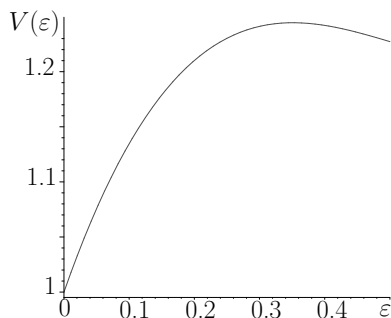


Figure 4: The volume of the deformed cube.

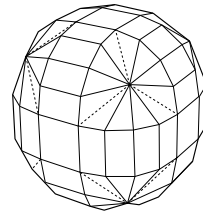


Figure 5: Deformed cube.

### 3. A REFINED CONSTRUCTION

We refine the construction to increase the volume of the cube. A crucial part of the construction was to take two adjacent edges of length  $\varepsilon$  and turn them into a chain of 4 edges of length  $\varepsilon/2$ . The deformation puts all vertices of the chain on a quarter circle with radius  $\delta$ . In the previous section the chain  $C$  contained 5 vertices. If we increase the number of vertices on  $C$  the deformed cube becomes more “spherish”, promising a larger volume. In the limit  $C$  is a spherical arc. In the following, we consider this situation.

The value of  $\delta$  is the radius of a circle with perimeter  $8\pi$ , thus  $\delta = 4\varepsilon\pi$ . The volume of the corpus is the same as calculated in Section 2. Every bar is a prism with a quarter circle of radius  $\delta$  as base area. This leads to

$$V_{bar} = (1 - 2\varepsilon)\pi\delta^2/4.$$

The stars consist of three equally sized quarter cones. The base area coincides with the base area of the bars. The height of the quarter cones is given by  $a$ . The value of  $a$  has to be chosen in such a way that the embedding is submetric.

As feasible height we get  $a = 0.9772\varepsilon$ . We get

$$V_{star} = 0.9772\varepsilon\delta^2\pi/4.$$

Maximizing the volume of the whole body (1 corpus, 12 bars, 8 stars) over  $\varepsilon \in [0, 0.5]$  leads to a volume of 1.2567 obtained at about  $\varepsilon = 0.37712$ .

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