

Applications



SIGGRAPH2007

Frédo Durand

MIT CSAIL

Overview

- Denoising
- Tone mapping
- Relighting & texture editing



Overview

- **Denoising**

Not most powerful application

Not best denoising, but good & simple



- Tone mapping



- Relighting & texture editing



Basic denoising

Noisy input



Bilateral filter 7x7 window



Basic denoising

Bilateral filter



Median 3x3



Basic denoising

Bilateral filter



Median 5x5

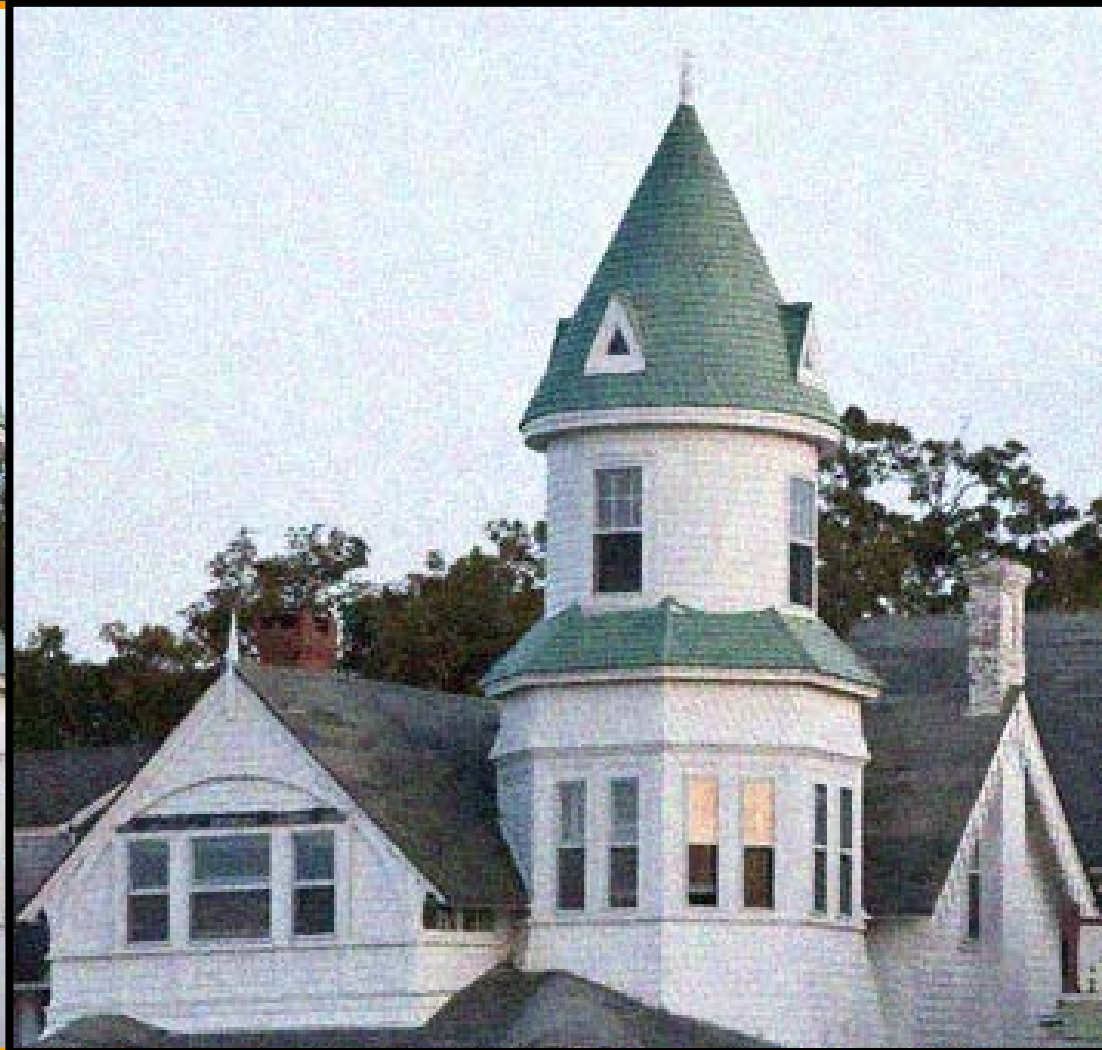


Basic denoising

Bilateral filter



Bilateral filter – lower sigma



Basic denoising

Bilateral filter



Bilateral filter – higher sigma



Denoising

- Small spatial sigma (e.g. 7x7 window)
- Adapt range sigma to noise level
- Maybe not best denoising method, but best simplicity/quality tradeoff
 - No need for acceleration (small kernel)
 - But the denoising feature in e.g. Photoshop is better



Overview

- Denoising



- **Tone mapping**



- Relighting & texture editing



Real world dynamic range

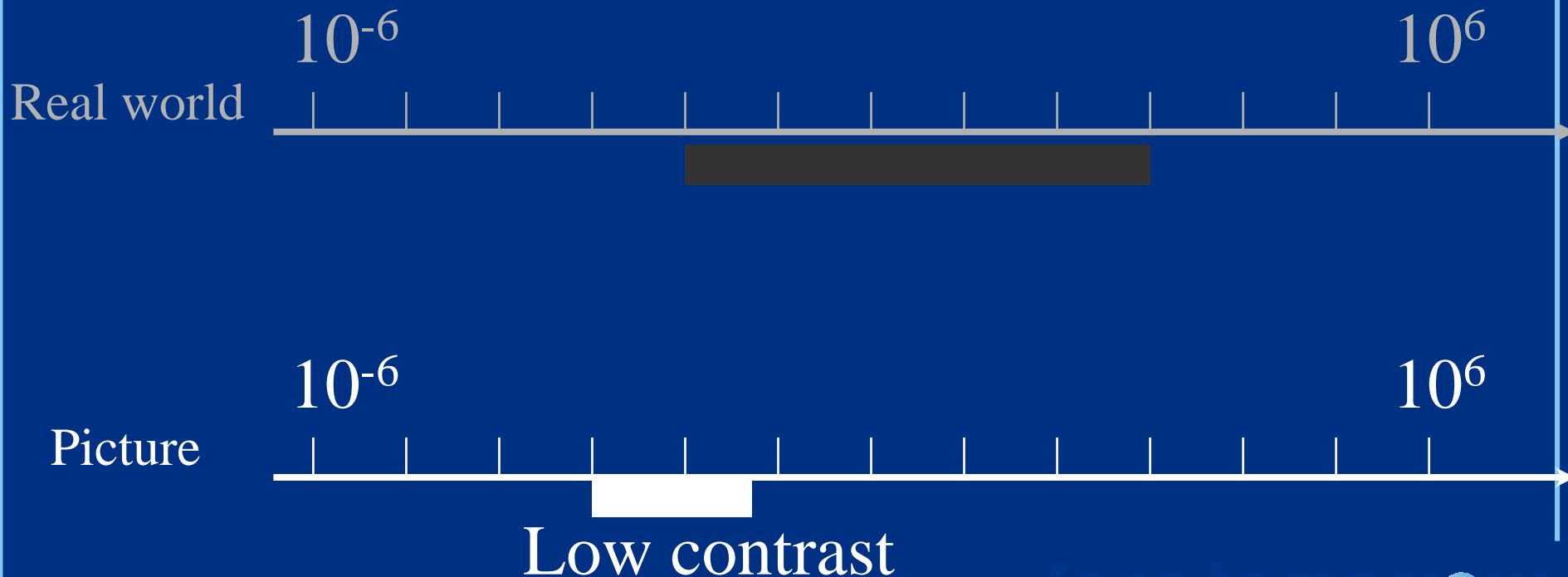
- Eye can adapt from $\sim 10^{-6}$ to 10^6 cd/m²
- Often 1 : 10,000 in a scene



Picture dynamic range

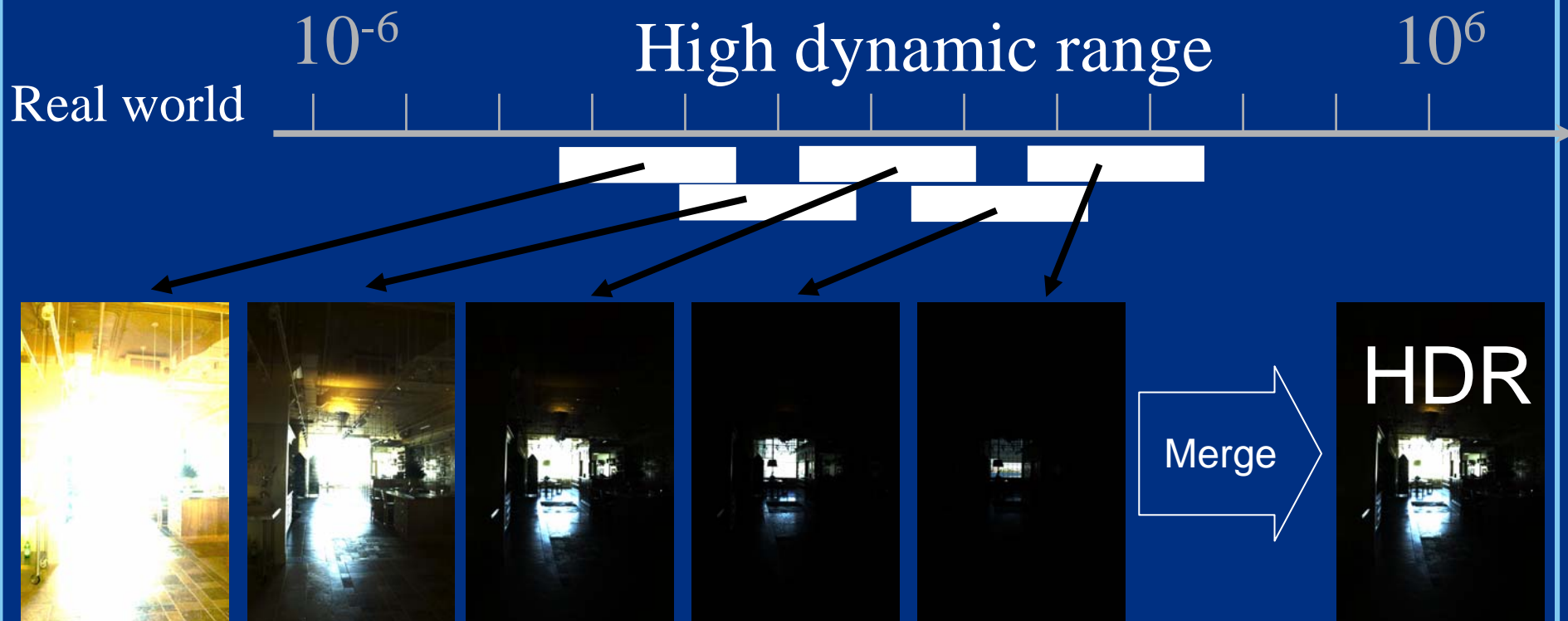
- Typically 1: 20 or 1:50

– Black  is ~ 50x darker than white 



Multiple exposure photography

- Merge multiple exposure to cover full range



- We obtain one single image with floats per pixel
 - But we still can't display it



The future: HDR Cameras

- HDR sensors using CMOS

- Use a log response curve
- e.g. SMaL,



- Assorted pixels

- Fuji
- Nayar et al.

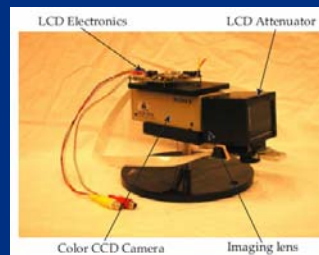


Fuji SuperCCD



- Per-pixel exposure

- Filter
- Integration time



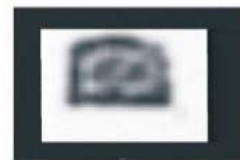
Conventional Camera
(without ADR)



Camera with Adaptive
Dynamic Range (ADR)



Transmittance Function
(LCD Input)

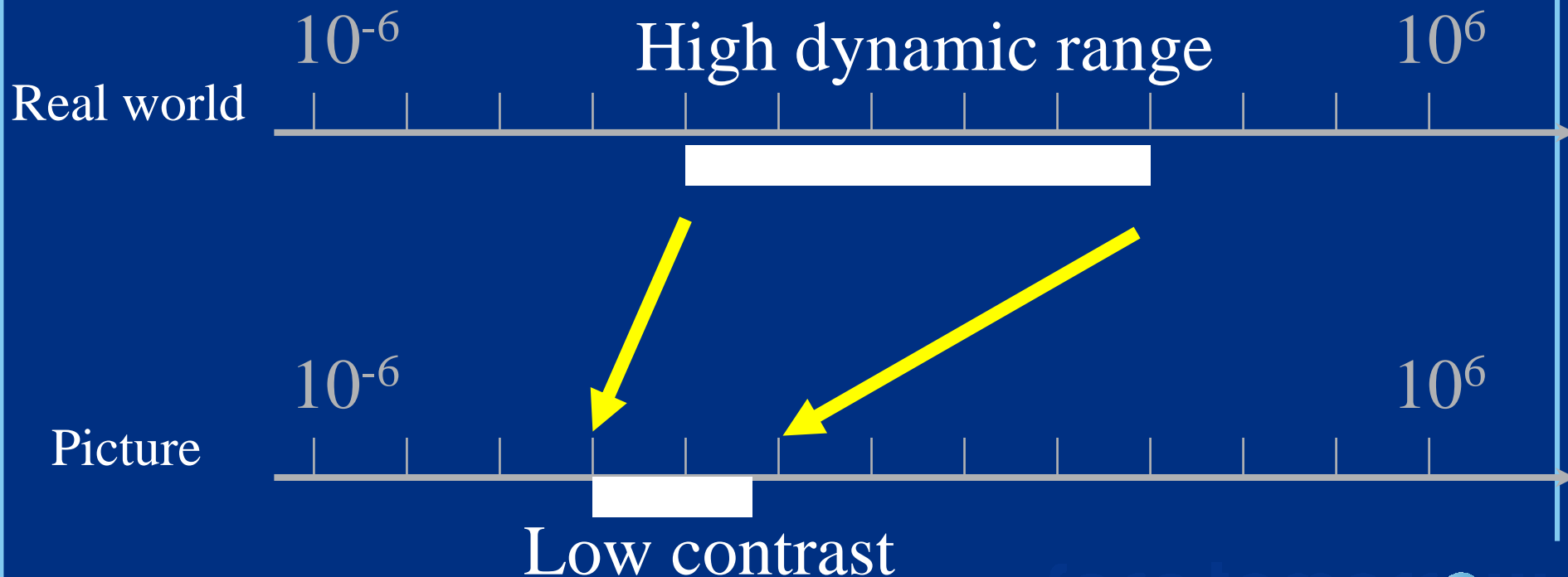


- Multiple cameras using beam splitters



Problem: Contrast reduction

- Match limited contrast of the medium
- Preserve details



Tone mapping

- Input: high-dynamic-range image
 - (floating point per pixel)



Naïve technique

- Scene has $1:10,000$ contrast, display has $1:100$
- Simplest contrast reduction?



Naïve: Gamma compression

- $X \rightarrow X^\gamma$ (where $\gamma=0.5$ in our case)
- But... colors are washed-out. Why?

Input



Gamma



Gamma compression on intensity

- Colors are OK,
but details (intensity high-frequency) are blurred

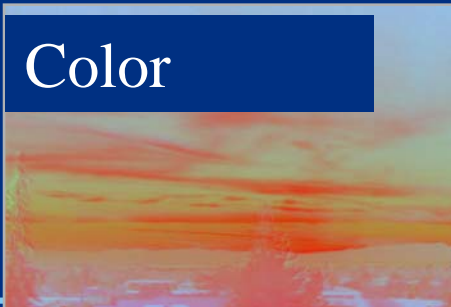
Intensity



Gamma on intensity



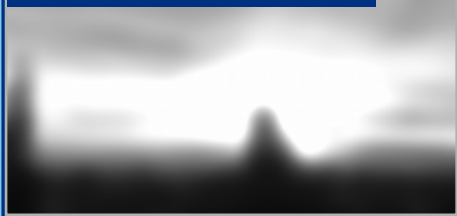
Color



Oppenheim 1968, Chiu et al. 1993

- Reduce contrast of low-frequencies (log domain)
- Keep high frequencies

Low-freq.



High-freq.



Color



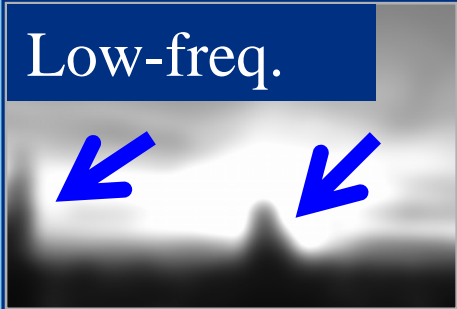
Reduce low frequency



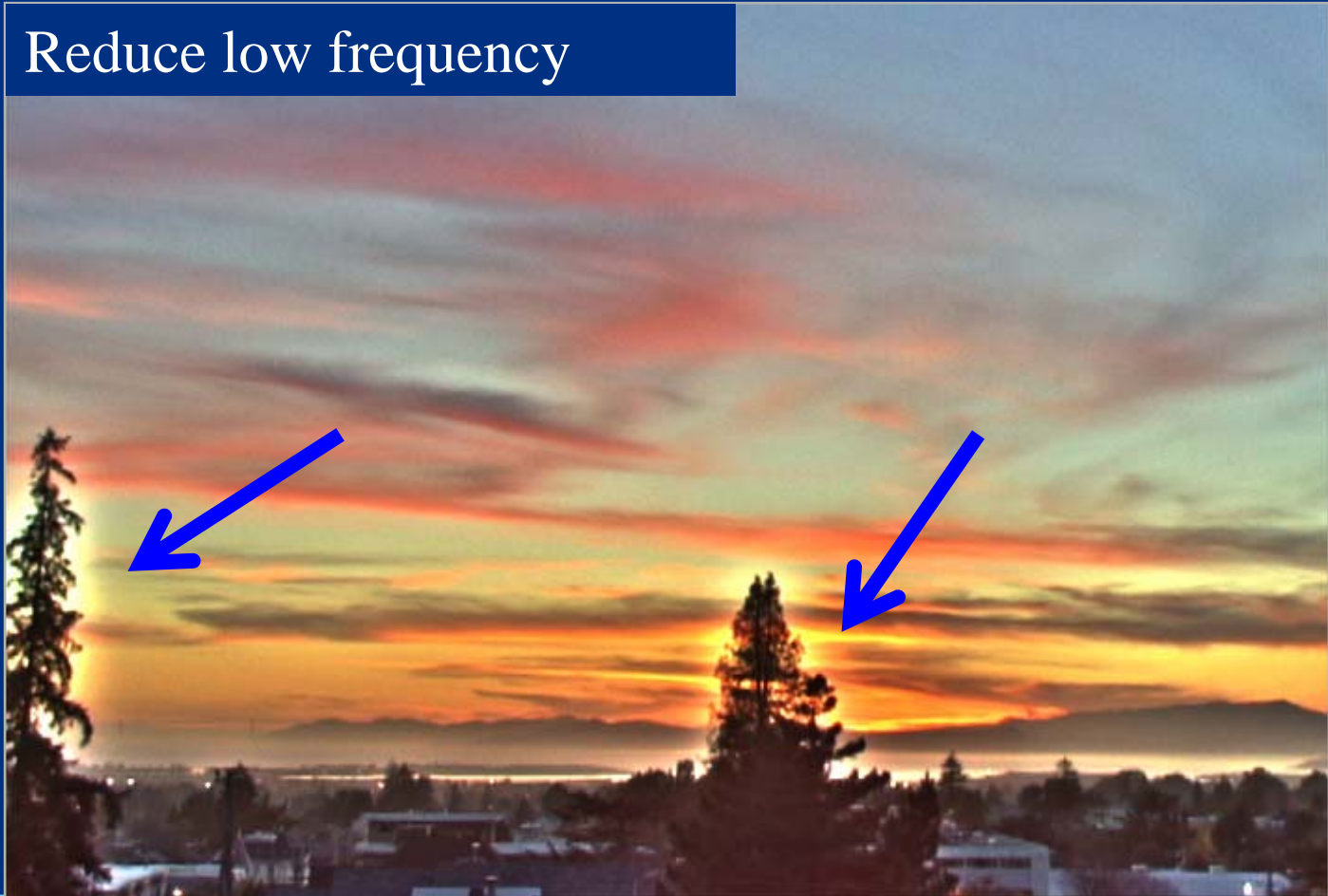
The halo nightmare

- For strong edges
- Because they contain high frequency

Low-freq.



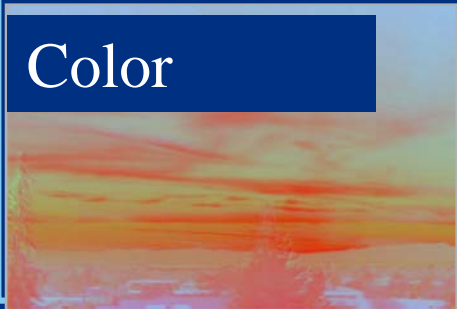
Reduce low frequency



High-freq.



Color



Bilateral filtering to the rescue

- Large scale = bilateral (log intensity)
- Detail = residual

[Durand & Dorsey 2002]

Large-scale



Detail



Color



Output



Contrast reduction

Input HDR image



Contrast
too high!

Contrast reduction

Input HDR image



Intensity



Color

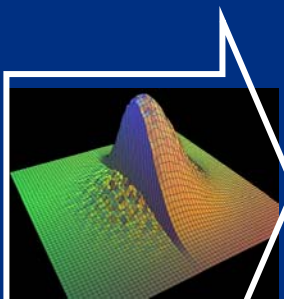


Contrast reduction

Input HDR image



Intensity



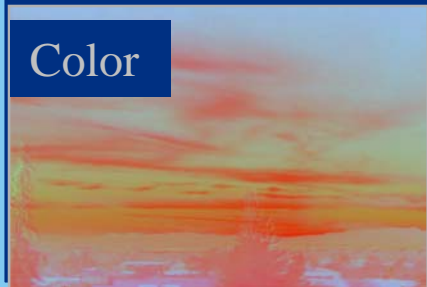
Large scale



Bilateral
Filter
(in log domain!)

Spatial sigma: 2% image size
Range sigma: 0.4 (in log 10)

Color

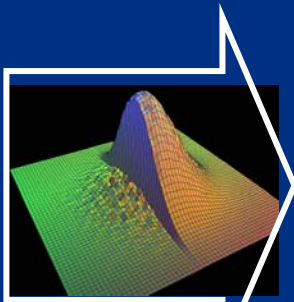


Contrast reduction

Input HDR image



Intensity



Bilateral
Filter

Large scale



Detail



Color



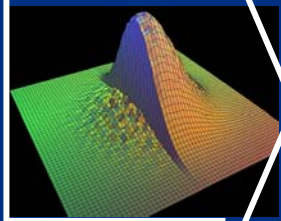
Detail = log intensity – large scale
(residual)

Contrast reduction

Input HDR image



Intensity



Bilateral
Filter

Large scale



Detail

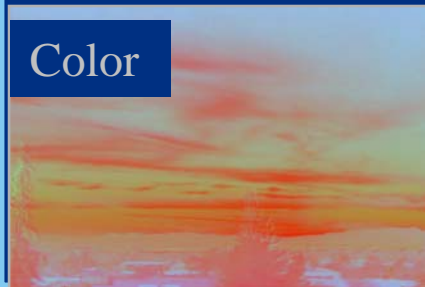


Reduce
contrast

Large scale



Color

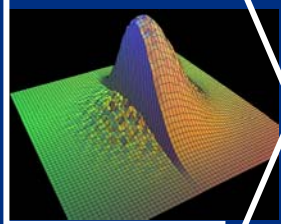


Contrast reduction

Input HDR image



Intensity



Bilateral
Filter

Large scale



Detail



Reduce
contrast

Preserve!

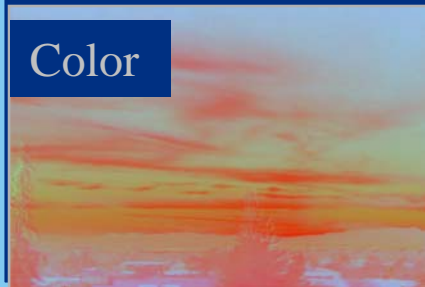
Large scale



Detail



Color

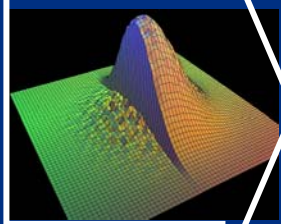


Contrast reduction

Input HDR image



Intensity



Bilateral
Filter

Large scale



Detail



Reduce
contrast

Preserve!

Output



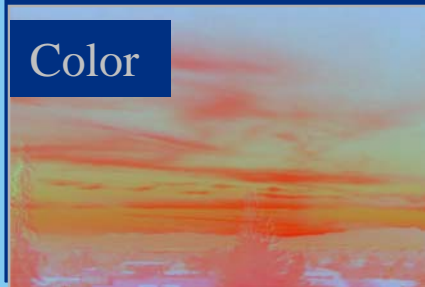
Large scale



Detail



Color



Color



Contrast reduction in log domain

- Set target large-scale contrast (e.g. $\log_{10} 10$)
 - In **linear** output, we want 1:10 contrast for large scale
- Compute range of input large scale layer:
 - $\text{largeRange} = \max(\text{inLogLarge}) - \min(\text{inLogLarge})$
- Scale factor $k = \log_{10}(10) / \text{largeRange}$
- Normalize so that the biggest value is 0 in log

$$\text{outLog} = \text{inLogDetail} + \text{inLogLarge} * k - \max(\text{inLogLarge})$$



Alternative explanation

- Explanation 1 (previous slides):
 - $\text{outLog} = k \text{ inLogLarge} + \text{inLogDetail}$ (ignoring offset)
- Explanation 2
 - $\text{outLog} = k \text{ inLogIntensity} + (1-k) \text{ detail}$
 - Reduce contrast of full intensity layer
 - Add back some detail
- Same final effect since
 - $\text{inLogDetail} + \text{inLogLarge scale} = \text{inLogIntensity}$
 - But different philosophy:
decomposition vs. add back detail

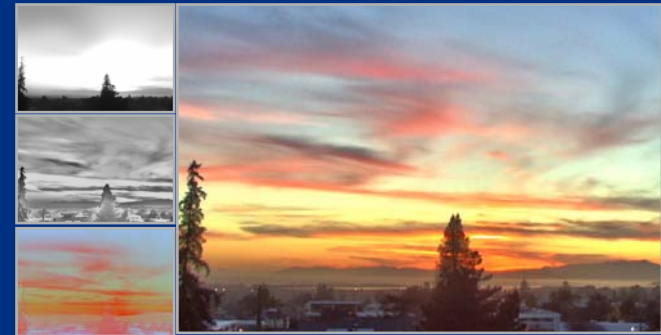
Demo

- Don't try at home without FAST bilateral filtering



Denoising vs. tone mapping

- Denoising:
 - decompose into noise+signal
 - Throw away noise, keep signal
 - Small kernel
- Tone mapping
 - Decompose into large scale + detail
 - Preserve detail, reduce large scale
 - Large kernel
 - because detail=high+medium frequency
 - →computation challenge



Crossing lines

- The bilateral filter is influenced by pixels across thin line
- Good for tone mapping



What matters

- Spatial sigma: not very important
- Range sigma: quite important
- Use of the log domain for range: **critical**
 - Because HDR and because perception sensitive to multiplicative contrast
 - CIE Lab might be better for other applications
- Luminance computation
 - Not critical, but has influence
 - see our Flash/no-flash paper [Eisemann 2004] for smarter function

Tone mapping evaluation

- Recent user experiments to evaluate competing tone mapping

- Ledda et al. 2005

- <http://www.cs.bris.ac.uk/Publications/Papers/2000255.pdf>

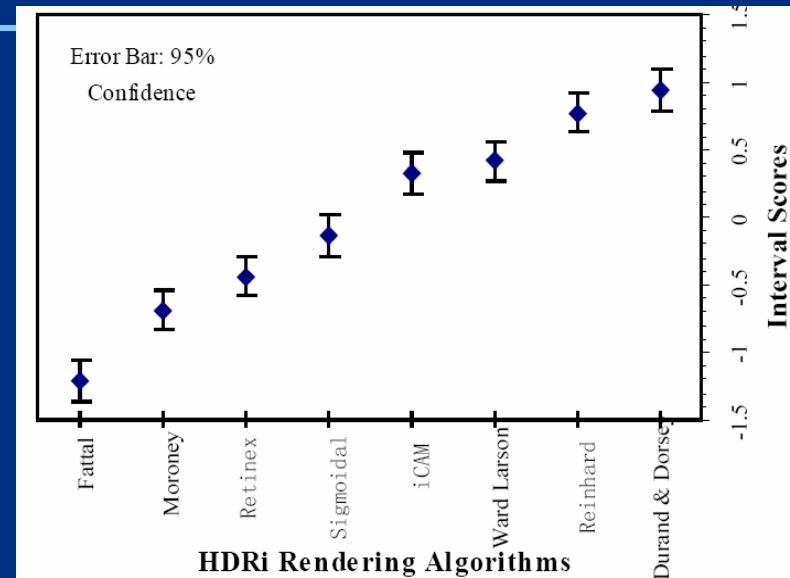
- Kuang et al. 2004

- <http://www.cis.rit.edu/fairchild/PDFs/PRO22.pdf>

- Interestingly, the former concludes bilateral is the worst, the latter that it is the best!

- They choose to test a different criterion: fidelity vs. preference

- More importantly, they focus on algorithm and ignore parameters



From Kuang et al.

	1st	2nd	3rd	4th	5th	6th
Scene 1	P	B	A	H	I	L
Scene 2	I	P	H	A	B	L
Scene 3	P	I	A	H	L	B
Scene 4	P	L	I	A	H	B
Scene 5	I	H	A	P	L	B
Scene 6	I	H	A	P	L	B
Scene 7	I	A	P	H	B	L
Scene 8	I	P	A	H	L	B
Scene 9	P	A	L	H	B	I

Adapted from Ledda et al.

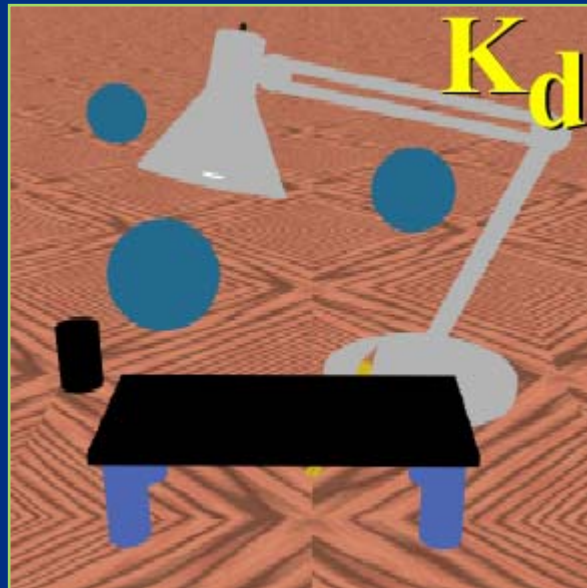


Alternative explanation

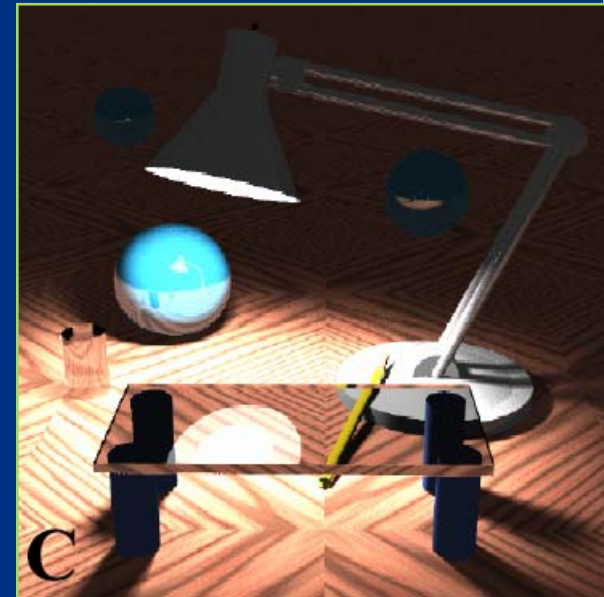
- Contrast reduction w/ intrinsic layers [Tumblin et al. 1999]
- For 3D scenes: Reduce only illumination layer



Illumination layer
Compressed



Reflectance layer



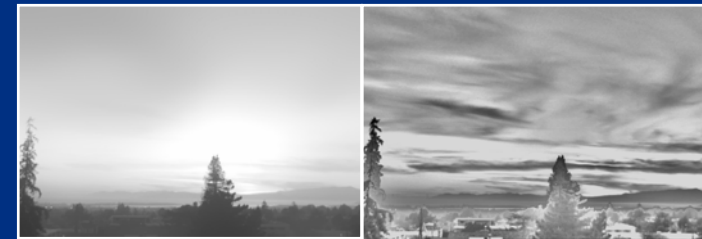
Output



Dirty vision for cool graphics

Three wrongs make one right

- Analyze image
 - Intrinsic image: albedo & illumination
 - Simple bilateral filter
- Modify
 - In our case, reduce contrast of large-scale (illumination)
- Recombine
 - Get final image



Overview

- Denoising
- Tone mapping
- **Relighting & texture editing**



Discounting Existing Lighting

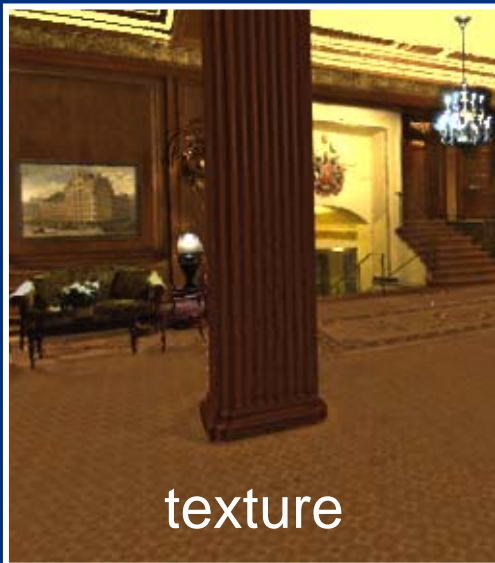
- Motivation
 - Relighting
 - Image manipulation (e.g. clone brush, texture synthesis)
- Context:
 - The following slides are from a project dealing with images +depth



Inverse Lighting Simulation

- Physically-based approaches

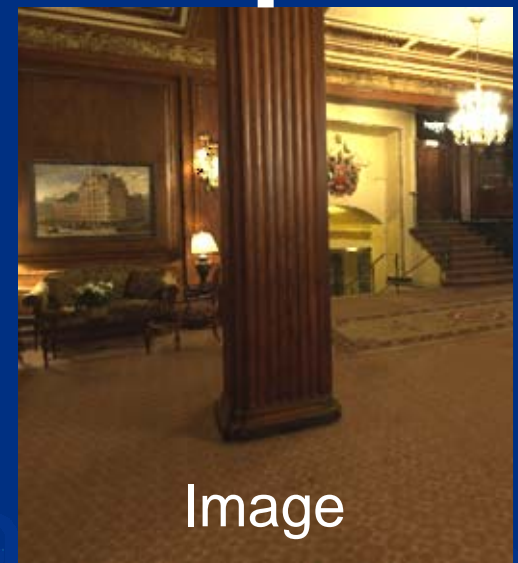
e.g. [Fournier et al.93, Drettakis et al.97, Debevec.98, Yu et al.99, Loscos et al. 99, Loscos et al.00]



×

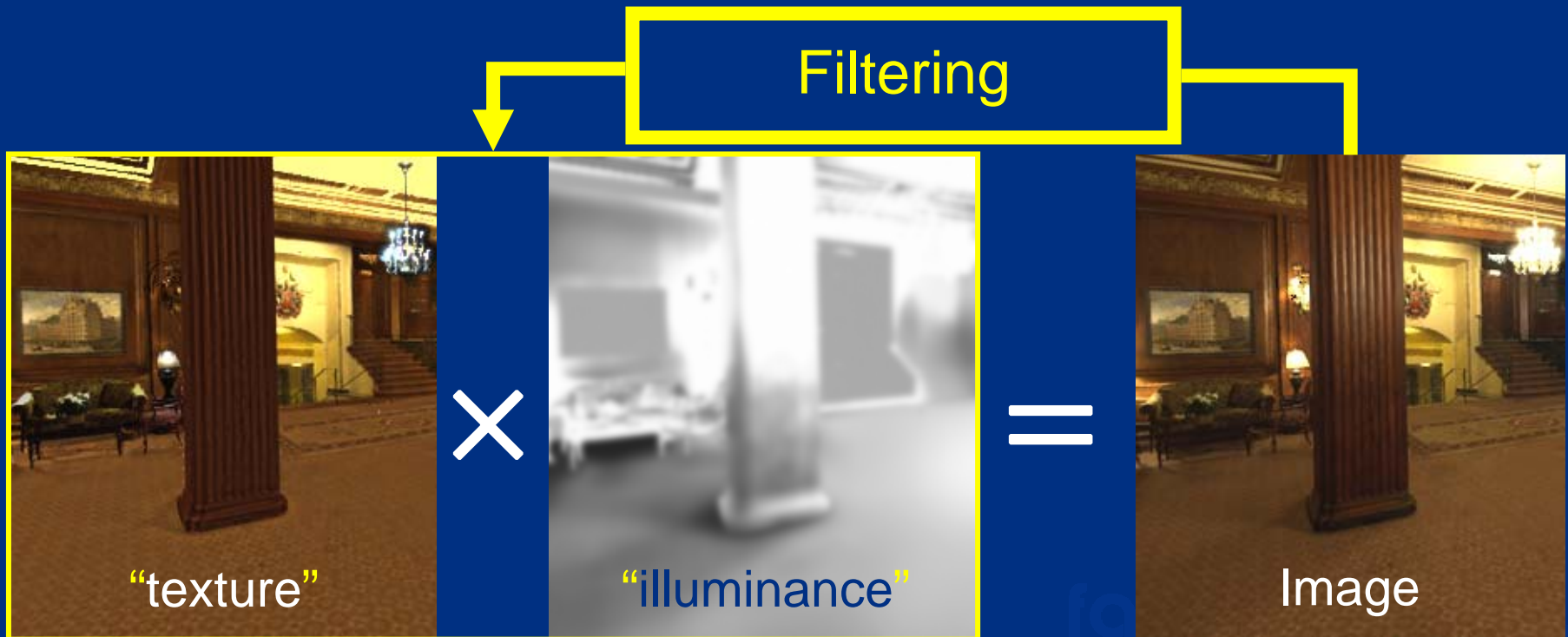


=



Texture-Illuminance Decoupling

- Not physically based
 - Our “texture” and “illuminance” are reasonable estimates



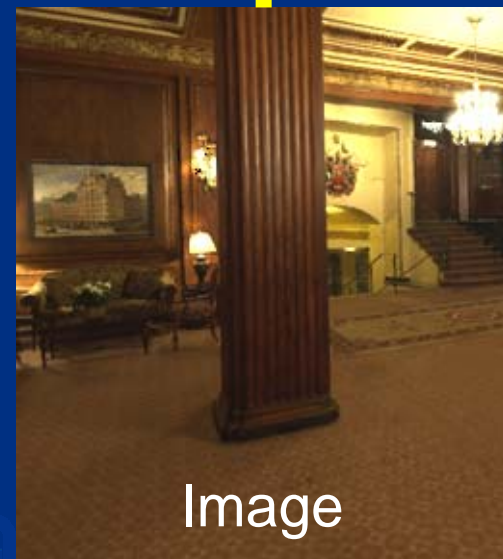
Texture-Illuminance Decoupling

- Not physically based: Filtering
- Assumptions:
 - Small-scale features → “texture”
 - Large-scale features → “illuminance”



General Idea: A Naïve Approach

- Large-scale features using low-pass filter
 - Color is assumed to be from texture

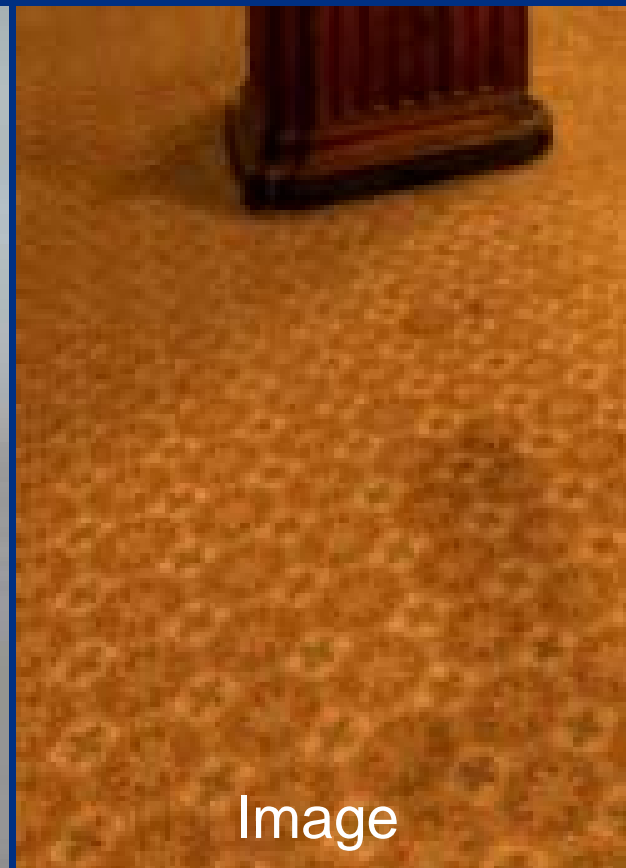
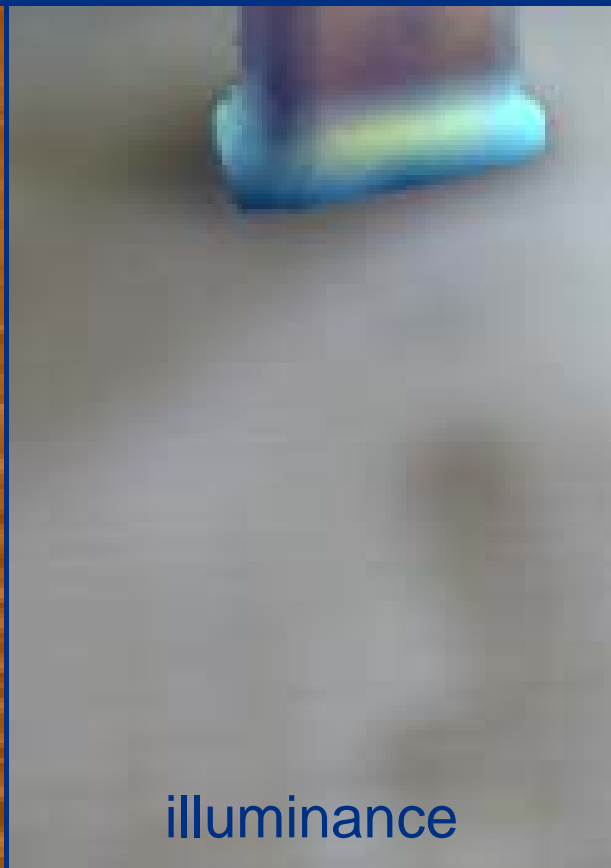


General Idea: A Naïve Approach

- Extract texture from illuminance and input image



Problems with the Naïve Approach



Problems with the Naïve Approach



Problems with the Naïve Approach

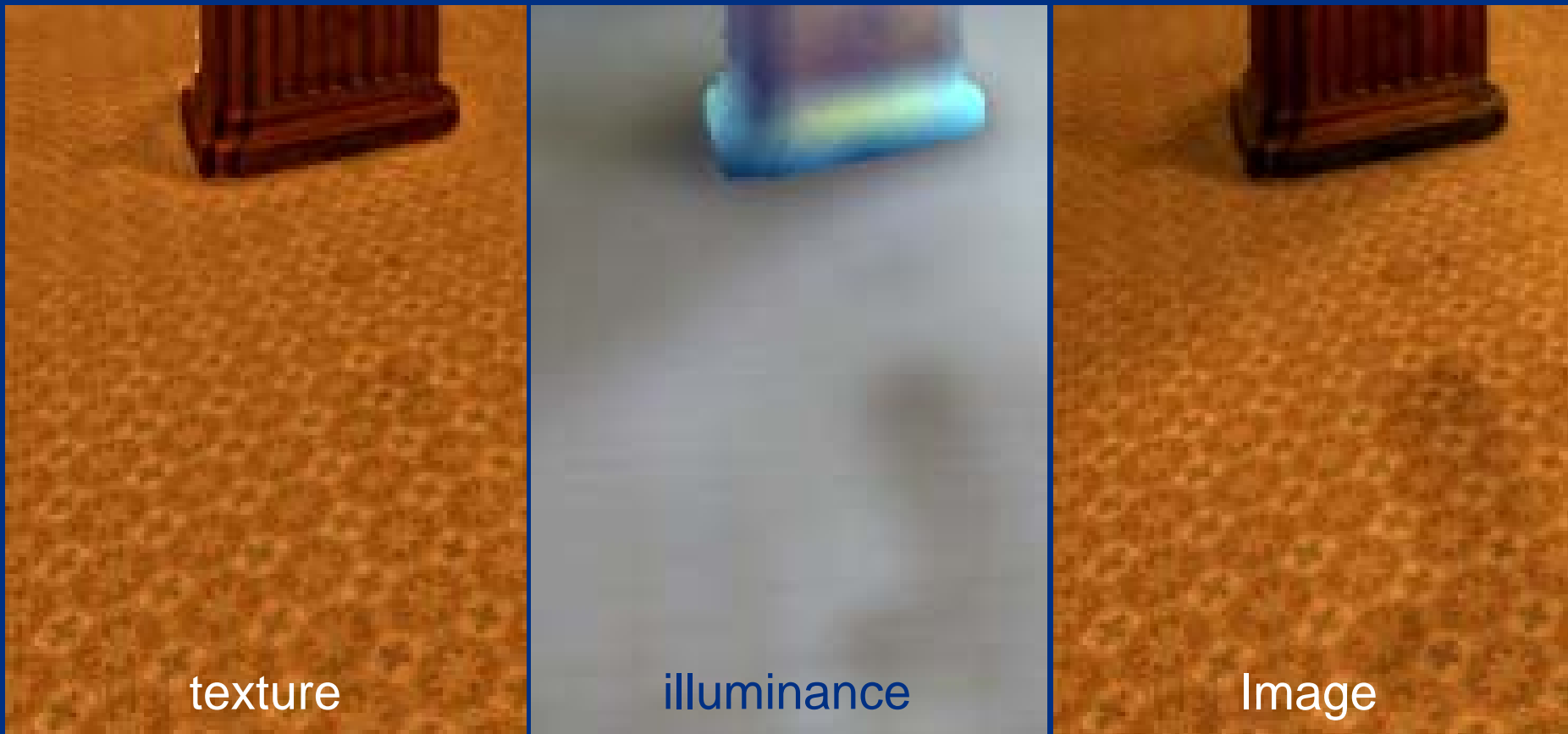


Problems with the Naïve Approach



Problems with the Naïve Approach

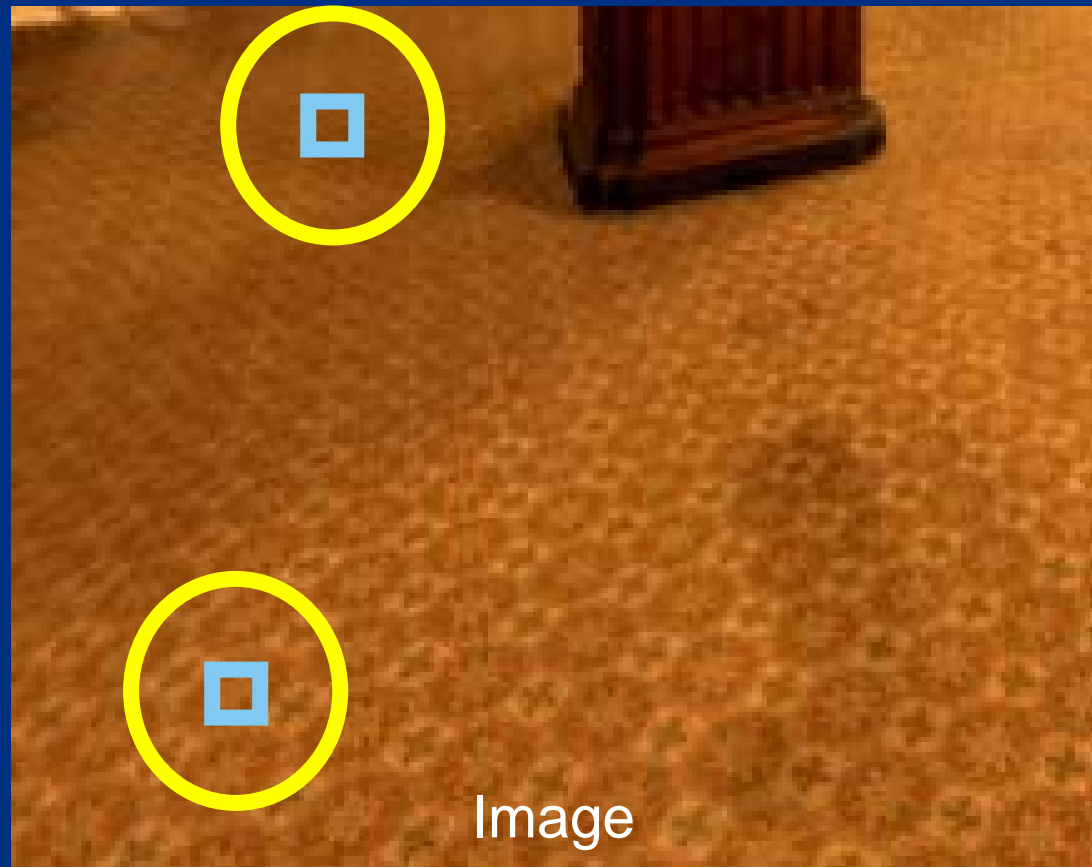
- Failure due to texture foreshortening
- Artifacts at shadow boundaries



Treatment of Foreshortening

□ pixel

○ kernel size

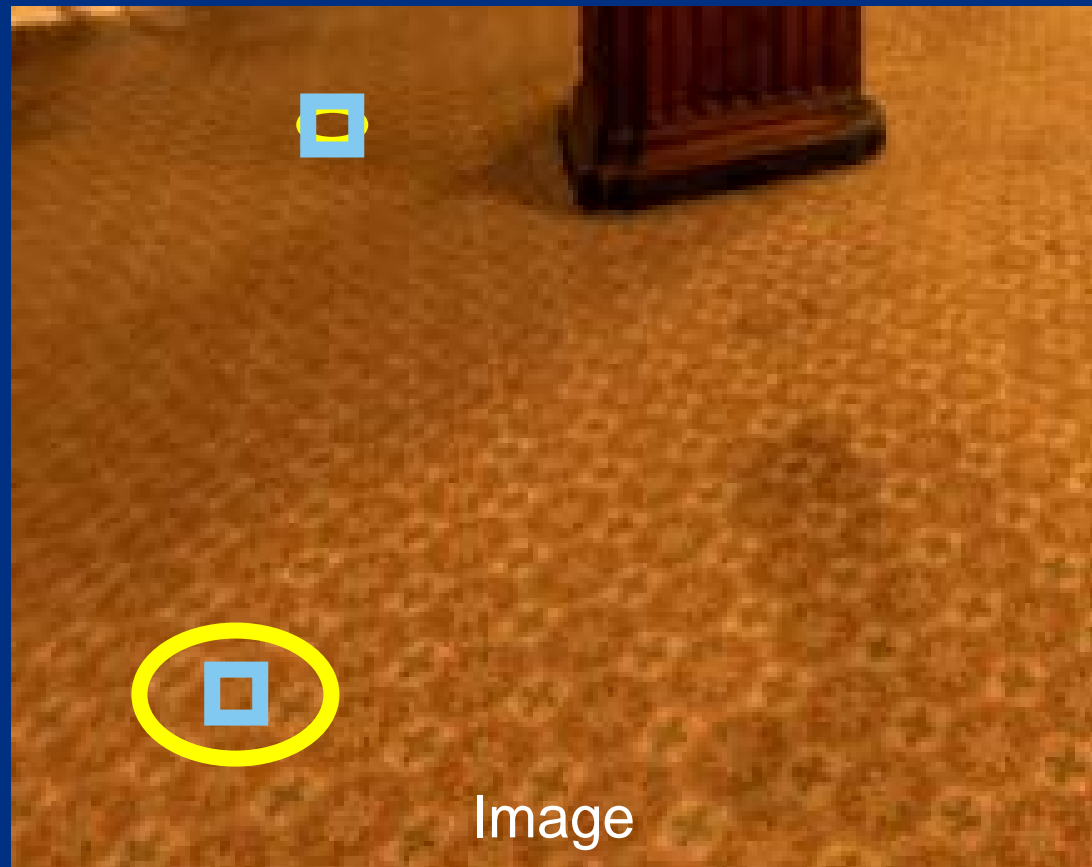


Treatment of Foreshortening

- Blurring depends on distance and orientation

□ pixel

○ kernel size



Edge-Preserving Filter

texture

illuminance

Naïve



Bilateral +
foreshortening



A Simple Relighting Example

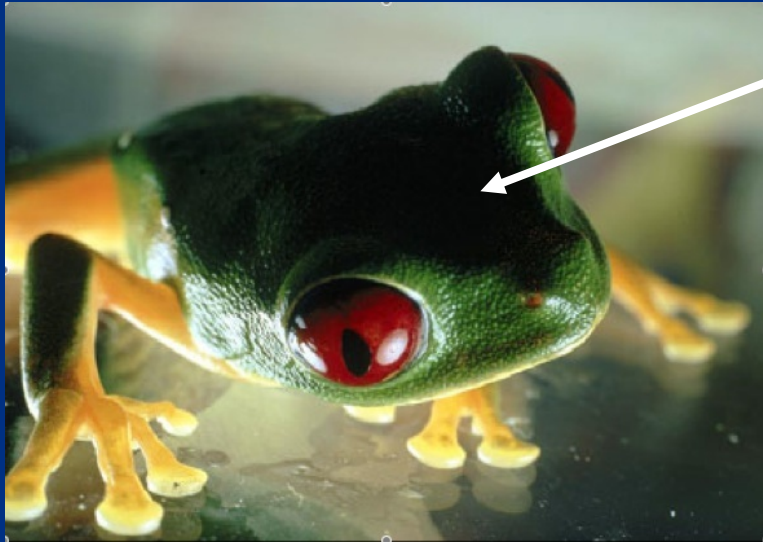


Examples



HDR hallucination

- *[Lvdi Wang, Liyi Wei, Kun Zhou, Baining Guo, Heung-Yeung Shum, EGSR 2007]*
- Low-dynamic-range images have under- and over-exposed parts
 - Information missing



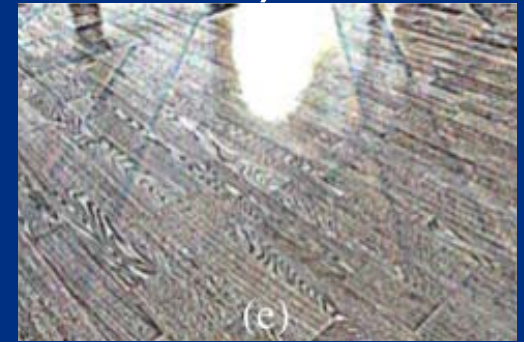
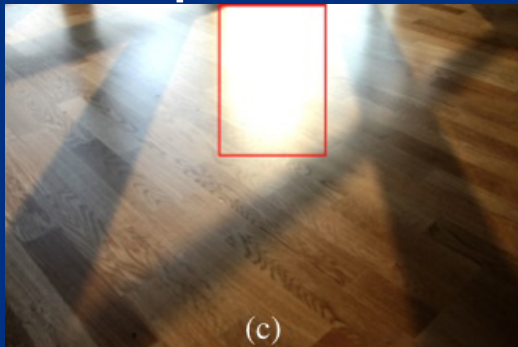
Under-
exposed



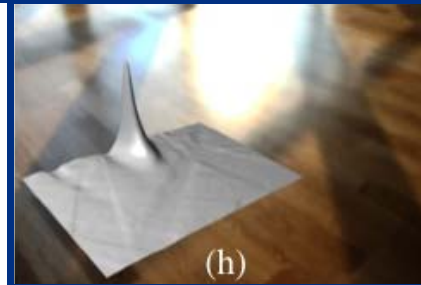
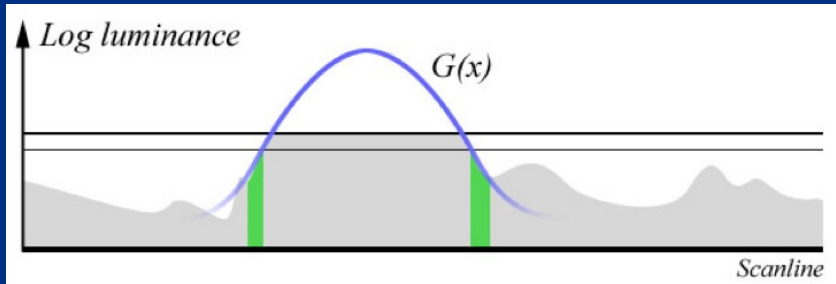
Over-
exposed

HDR hallucination

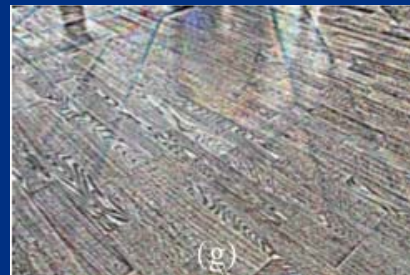
- Separate illumination and texture (Bilateral!)



- Fit smooth function to illumination



- Use texture synthesis



HDR hallucination



input



output



HDR hallucination



input



output

Recap

- Decompose into
 - Large scale (with bilateral filter)
 - Detail (residual: medium+high frequencies)
 - Use big kernels
- Use appropriate domain (log for HDR)
- Manipulate/process independently
- Tone mapping
- Relighting, HDR hallucination
- HDR hallucination



SIGGRAPH2007

Denoising with the BF

Input



output

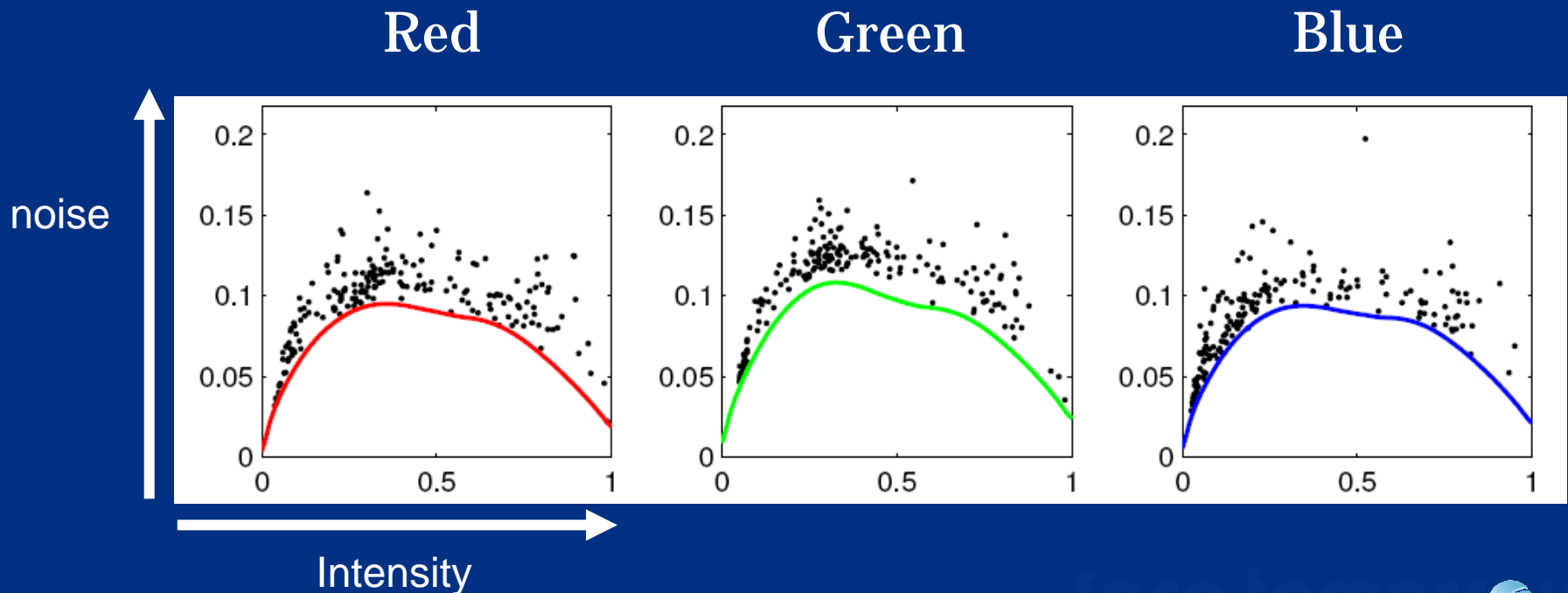


Images courtesy of Ce Liu



Noise level adaptation [Liu et al. 06]

- The noise of digital cameras varies with intensity
- Adapt sigma range to noise level
- Main topic of the paper: noise level inference



Adaptive bilateral filter

- Adapt sigma range to intensity

Input

Bilateral

Adaptive bilateral



Other tone mapping references

- J. DiCarlo and B. Wandell, Rendering High Dynamic Range Images http://www-isl.stanford.edu/%7Eabbas/group/papers_and_pub/spie00_jeff.pdf
- Choudhury, P., Tumblin, J., "The Trilateral Filter for High Contrast Images and Meshes". <http://www.cs.northwestern.edu/~jet/publications.html>
- Tumblin, J., Turk, G., "Low Curvature Image Simplifiers (LCIS): A Boundary Hierarchy for Detail-Preserving Contrast Reduction." <http://www.cs.northwestern.edu/~jet/publications.html>
- Tumblin, J., "Three Methods For Detail-Preserving Contrast Reduction For Displayed Images" <http://www.cs.northwestern.edu/~jet/publications.html>
- Photographic Tone Reproduction for Digital Images
Erik Reinhard, Mike Stark, Peter Shirley and Jim Ferwerda
<http://www.cs.utah.edu/%7Ereinhard/cdrom/>
- Ashikhmin, M. "A Tone Mapping Algorithm for High Contrast Images" <http://www.cs.sunysb.edu/~ash/tm.pdf>
- Retinex at Nasa <http://dragon.larc.nasa.gov/retinex/background/retpubs.html>
- Gradient Domain High Dynamic Range Compression Raanan Fattal, Dani Lischinski, Michael Werman <http://www.cs.huji.ac.il/~danix/hdr/>
- Li et al. : Wavelets and activity maps http://web.mit.edu/yzli/www/hdr_companding.htm



Tone mapping code

- <http://www.mpi-sb.mpg.de/resources/pfstools/>
- <http://scanline.ca/exrtools/>
- <http://www.cs.utah.edu/~reinhard/cdrom/source.html>
- <http://www.cis.rit.edu/mcsl/icom/hdr/>
- <http://people.csail.mit.edu/sparis/bf/#code>