



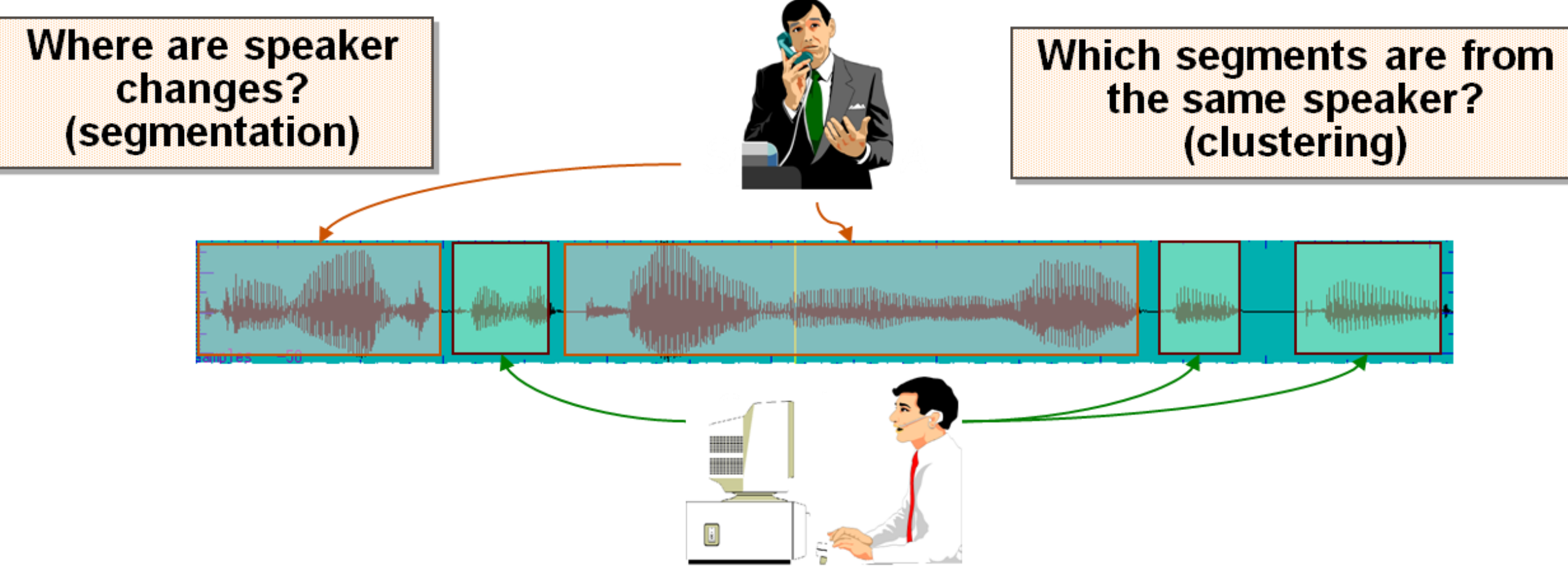
Unsupervised Methods for Speaker Diarization

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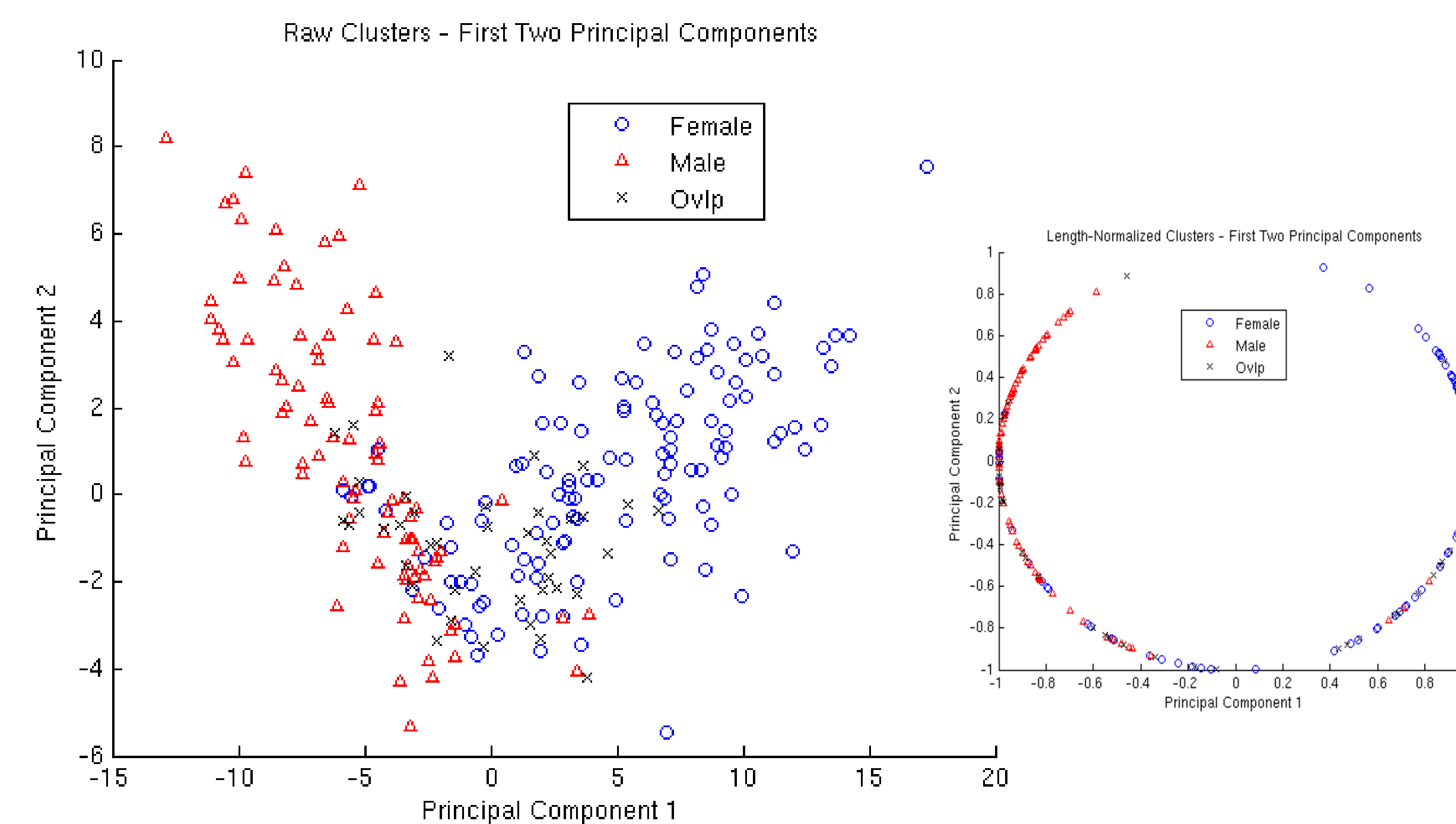
Introduction

- Audio Diarization
 - ✓ The task of marking and categorizing the different audio sources within an unmarked audio sequence [1].
 - ✓ Originally built for desktop and tablet interfaces.
- Speaker Diarization
 - ✓ “Who is speaking when?”
 - ✓ Segmentation + Clustering
- Applications
 - ✓ Annotate transcripts with speaker changes and labels
 - ✓ Provide an overview of speaker activity
 - ✓ Adapt a speech recognition system
 - ✓ Do speaker detection on multi-speaker speech



Intra-Conversation Variability

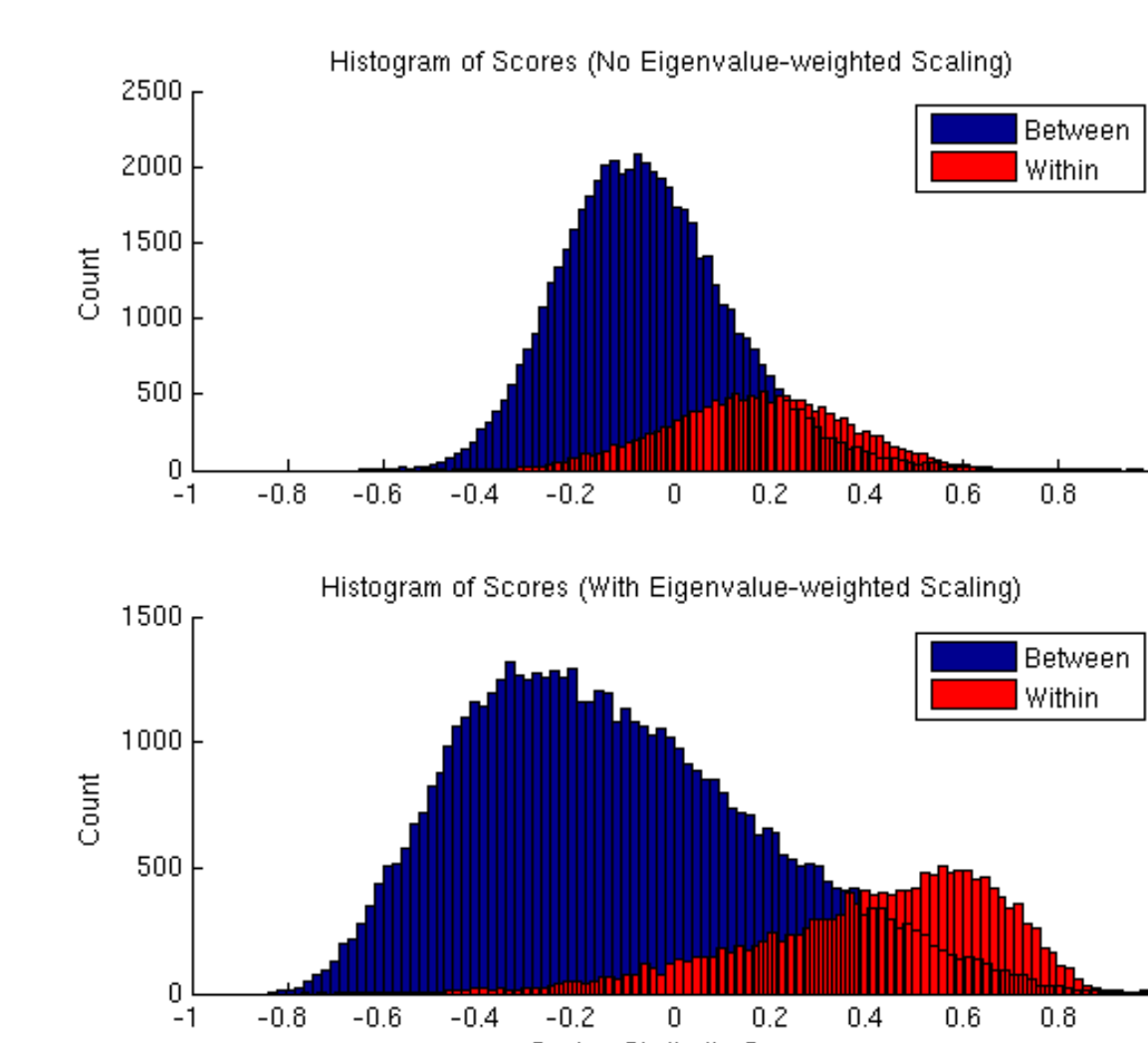
- Use PCA to find prominent directions of intra-conversation variability



- Further emphasize principal directions
 - ✓ i.e. the most principal components have largest eigenvalues

$$score(w'_1, w'_2) = \frac{(w'_1)' \Lambda (w'_2)}{\| \Lambda^{1/2} w'_1 \| \cdot \| \Lambda^{1/2} w'_2 \|}$$

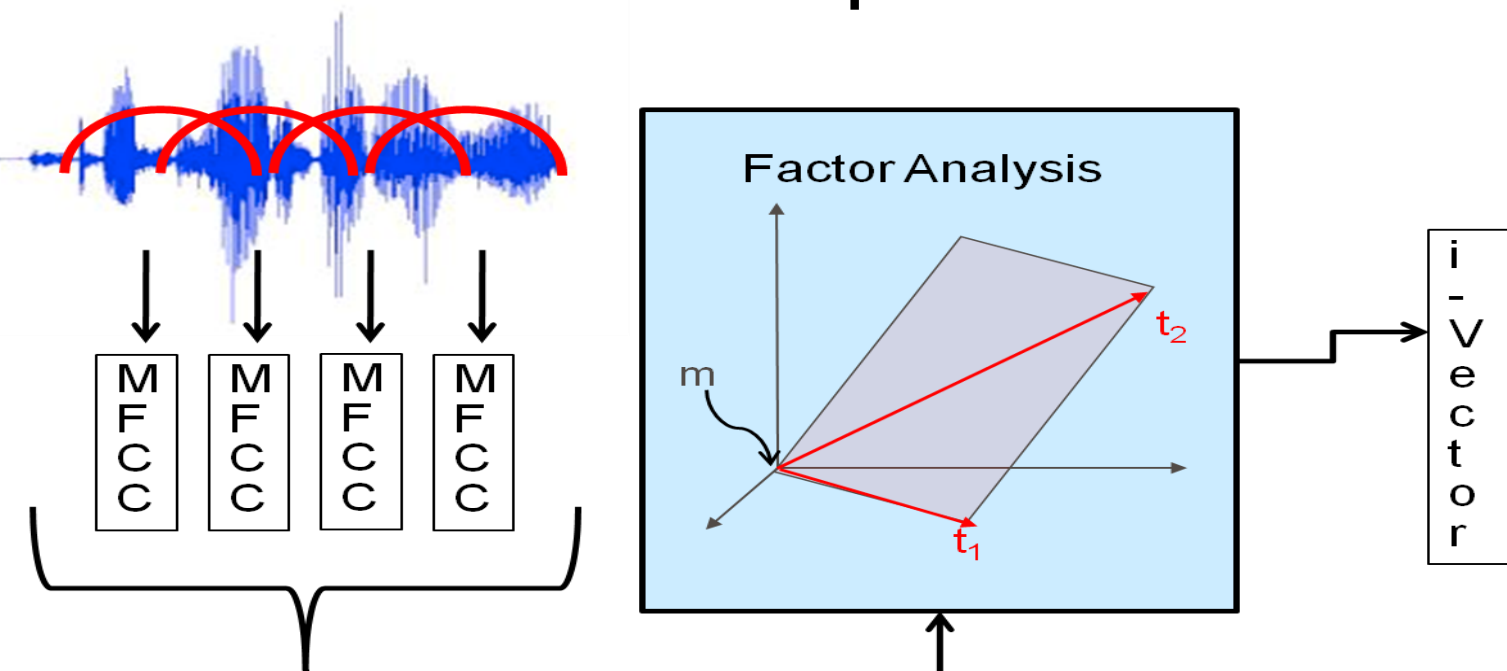
w'_i : PCA-projected i-vector
 Λ : Diagonal matrix of eigenvalues



Speaker Representation

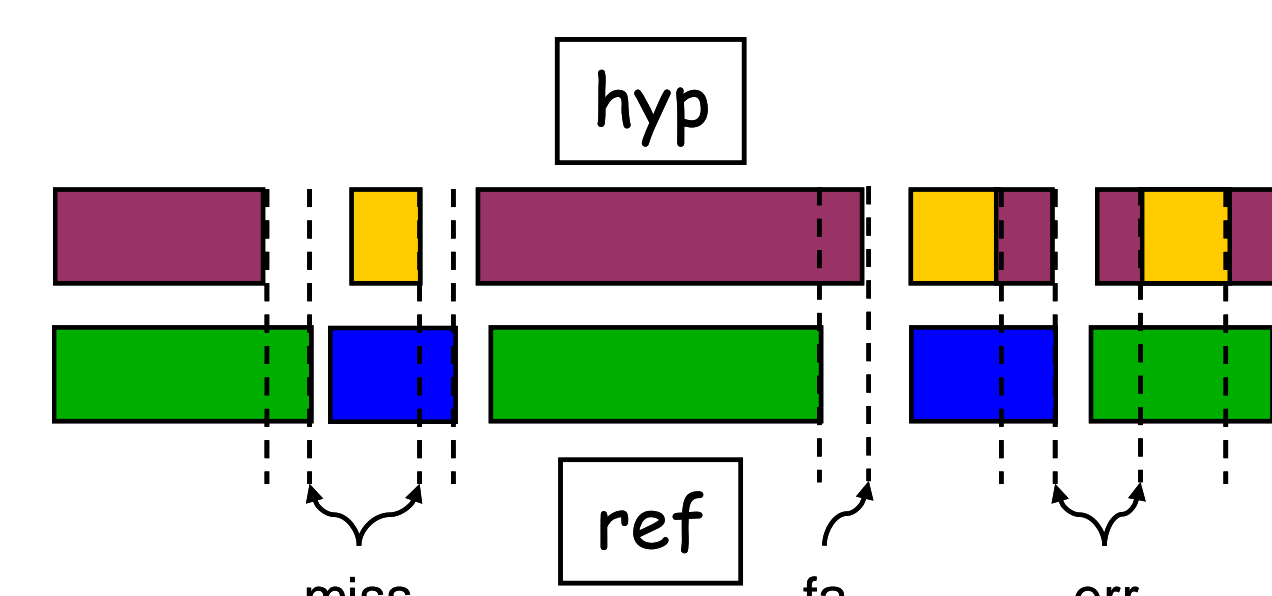
- From GMMs to Factor Analysis
 - ✓ Associated with each speaker is a distribution of acoustic features (AF) that can be modeled by a Gaussian Mixture Model (GMM).
 - ✓ A speaker **supervector** is created by concatenating all mixture mean components in a GMM.
 - 20 dim (AF) x 1024 mix (GMM) \approx 20,000 dim
 - ✓ Assume all pertinent speaker variabilities lie in some low-dimensional subspace T of the supervector space
 - Rank(T) set between 100 and 600
- Total Variability Subspace [2]

$$M = m + Tw$$
 - ✓ w is vector of total factors (Identity Vector, i-vector)
 - ✓ Use cosine distance to compare two i-vectors

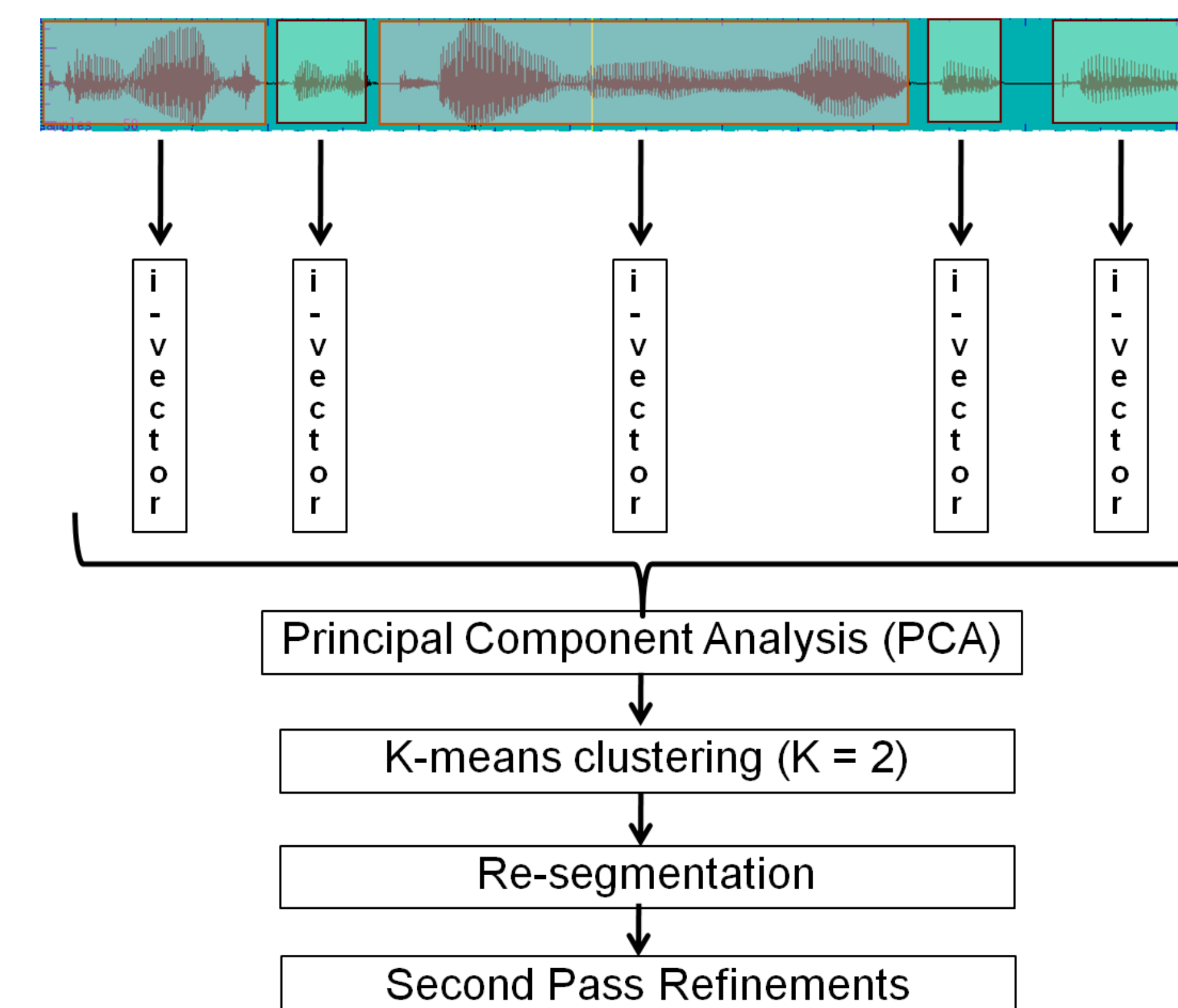


Experimental Framework

- Summed-channel Telephone Speech
 - ✓ 2008 NIST Speaker Recognition Evaluation Test Data
 - ✓ 2215 two-speaker conversations (~5min each)
 - ✓ Obtain a reference diarization by applying Automatic Speech Recognition (ASR) or Voice Activity Detection (VAD) on each channel separately.
 - ✓ Scoring ignores overlapped speech.
- Diarization Error Rate (DER)
 - ✓ Miss – speaker in reference but not in hypothesis
 - ✓ False Alarm – speaker in hyp but not in ref
 - ✓ Speaker Confusion – saying one’s speech is another’s



System Summary



- First Pass K-means (K=2) Clustering
- Viterbi Re-segmentation
 - ✓ Apply the Viterbi algorithm at the acoustic feature level to re-formulate segment boundaries and re-assign frames to each cluster (Speaker A, Speaker B, Non-speech N).
- Second Pass Refinements
 - ✓ Extract a single i-vector for each respective speaker based on the re-segmentation assignments.
 - ✓ Re-assign each segment i-vector to the speaker whose i-vector is closer in cosine distance
 - ✓ Essentially another pass of K-means, where the “means” are computed via i-vector estimation.

Experiment Results

- Using our own segmentation

	Error Breakdown			DER (%)	σ (%)
	Miss	False Alarm	Confusion		
First Pass	7.7	2.0	2.8	12.5	8.2
Re-segmentation	0.3	2.3	2.6	5.2	8.2
Second Pass	0.3	2.3	1.1	3.7	6.4

- Using reference segmentation

- ✓ Removes all errors attributed to Miss & False Alarm
- ✓ Can then focus solely on Speaker Confusion error
- ✓ Allows for direct comparison with other systems [3].

	Speaker Confusion (%)	σ_C (%)
BIC-based Baseline	3.5	8.0
VB-based FA	1.0	3.5
Ref VAD + TV100	0.9	3.2
Own VAD + TV100	1.1	3.3

Towards K-speaker Diarization

- Speech with more than two speakers
 - ✓ How well does our system generalize when given the number of speakers K?
 - ✓ Evaluate on 500 CallHome telephone conversations
 - Each call contains 2-7 speakers, length of 1-5min
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- Estimating the Number of Speakers (K)
 - ✓ Exploring Variational Bayesian GMMs
 - ✓ But because data lies on the unit hypersphere, ought to consider a more suitable distribution.
 - E.g. Mixtures of von Mises-Fisher Distributions [4]

Future Work

- Processing of overlapped speech
 - ✓ Segments containing overlapped speech potentially corrupt our PCA and subsequent speaker modeling.
- Clustering on sparse data
 - ✓ Some speakers speak relatively little in a conversation
 - ✓ Want to be able to handle these sorts of imbalance.
- Temporal modeling of conversation

References

[1] S. Tranter and D. Reynolds, “An Overview of Automatic Speaker Diarisation Systems,” *IEEE Transactions on Audio, Speech, and Language Processing*, September 2006.

[2] N. Dehak, P. Kenny, R. Dehak, P. Dumouchel, and P. Ouellet, “Front-end Factor Analysis for Speaker Verification,” *IEEE Transactions on Audio, Speech, and Language Processing*, July 2010.

[3] P. Kenny, D. Reynolds, and F. Castaldo, “Diarization of Telephone Conversations Using Factor Analysis,” *IEEE Journal of Selected Topics in Signal Processing*, December 2010.

[4] A. Banerjee, I. Dhillon, J. Ghosh, and S. Sra, “Clustering on the Unit Hypersphere using von Mises-Fisher Distributions,” *Journal of Machine Learning Research*, September 2005.