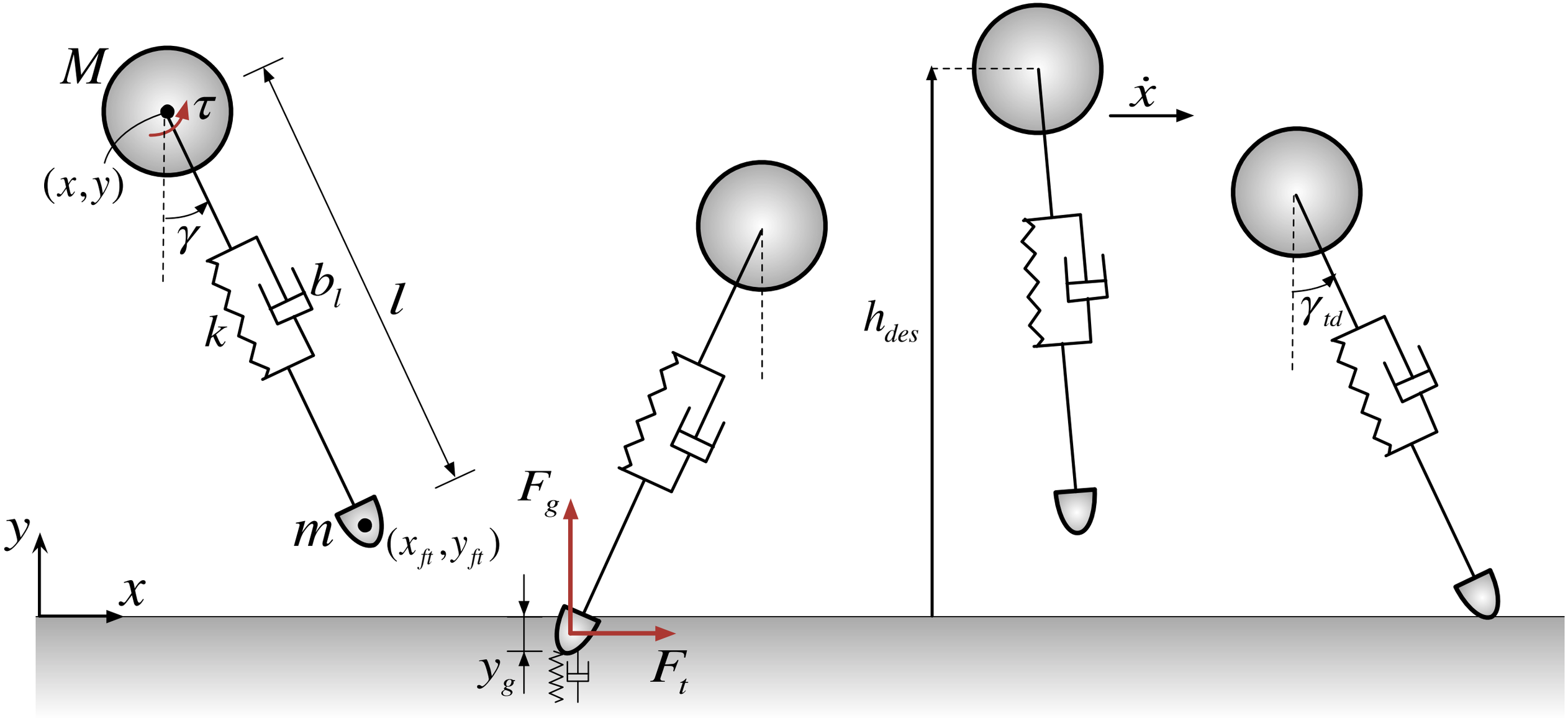
M
τ
(x,y)
γ
b_l
k
l
m
(x_ft, y_ft)
y
x
F_g
y_g
F_t
h_des
ẋ
γ_td