

# Unifying Execution of Imperative and Declarative Code



**Aleksandar  
Milicevic**



**Derek  
Rayside**



**Kuat  
Yessenov**



**Daniel  
Jackson**

Massachusetts Institute of Technology  
Cambridge, MA

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# Solving Sudoku

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**Sudoku puzzle:** fill in the empty cells s.t.:

1. all rows contain **all values** from 1 to 9
2. all columns contain **all values** from 1 to 9
3. all sub-grids contain **all values** from 1 to 9

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## Approaches:

- write a custom (heuristic-based) algorithm [imperative]
- write a set of constraints and use a constraint solver [declarative]

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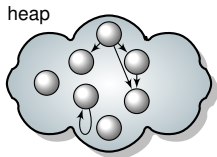
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# Sudoku with Squander

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public class Sudoku {  
    private int [][] grid = new int [9][9];  
  
    public void solve() { ??? }  
  
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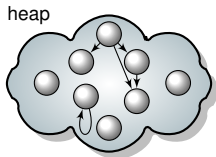
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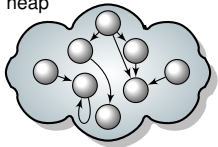


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# Sudoku with Squander

heap



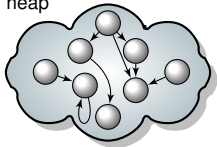
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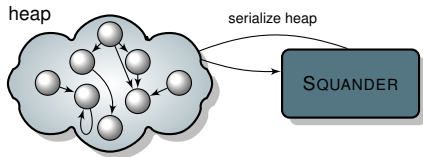
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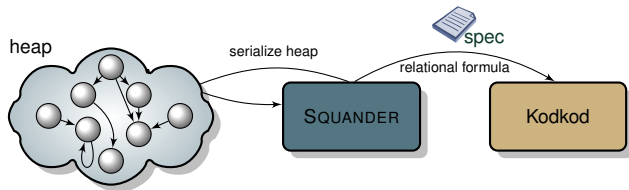
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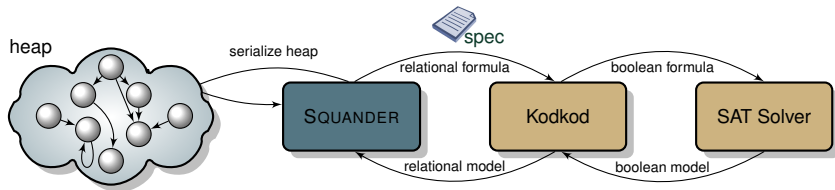
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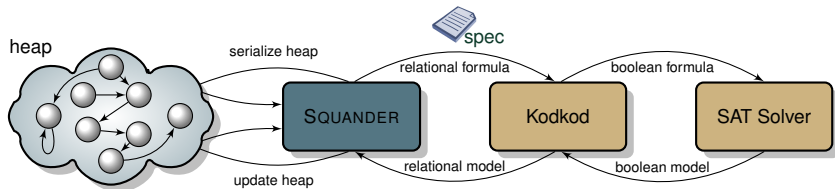
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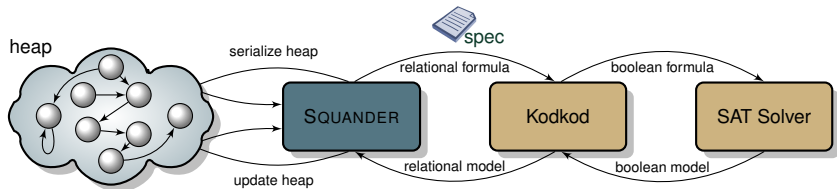
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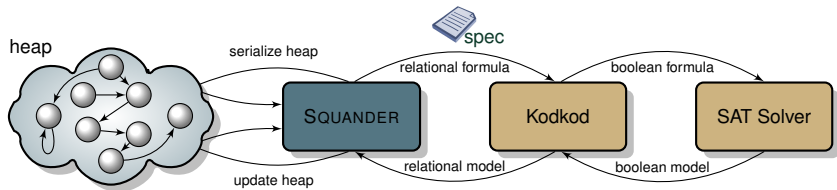
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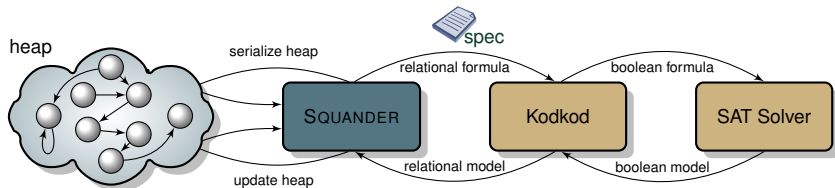


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# Sudoku with Squander



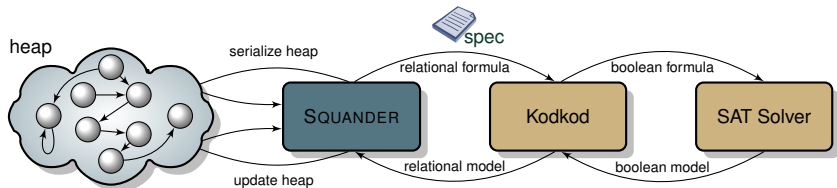
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specify and solve constraint problems in place

executable first-order relational specifications for Java



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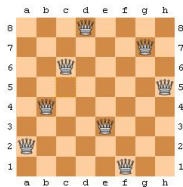
executable first-order relational specifications for Java

no manual translation to/from an external solver

# SQUANDER vs Manual Search

## N-Queens

- *place  $N$  queens on an  $N \times N$  chess board such that no two queens attack each other*

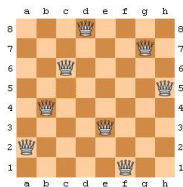


# SQUANDER vs Manual Search

## N-Queens

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## A backtracking with pruning solution



```
static boolean solveNQueens(int n, int col, int[] queenCols,
                           boolean[] bRow, boolean[] bD45, boolean[] bD135) {
    if (col >= n)
        return true;

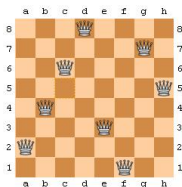
    for (int row = 0; row < n; row++) {
        if (bRow[row] || bD45[row + col] || bD135[col - row + n - 1])
            continue;
        queenCols[col] = row;
        bRow[row] = true;
        bD45[row + col] = true;
        bD135[col - row + n - 1] = true;
        if (solveNQueens(n, col+1, queenCols, bRow, bD45, bD135))
            return true;
        bRow[row] = false;
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    return false;
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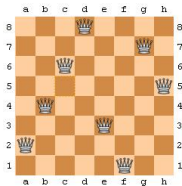
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how do you argue that it is correct?

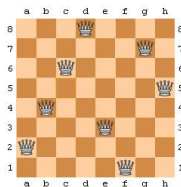
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## A solution with SQUANDER

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@Ensures({
  "all disj q, r: result.elts | " + // for every two different queens q and r ensure that they are
  "  q.i      != r.i      && " + // not in the same row
  "  q.j      != r.j      && " + // not in the same column
  "  q.i - q.j != r.i - r.j && " + // not in the same ↖ diagonal
  "  q.i + q.j != r.i + r.j" }) // not in the same ↗ diagonal
@Modifies({
  "result.elts.i from {0 ... n-1}", // modify fields i and j of all elements of
  "result.elts.j from {0 ... n-1}" }) // the result set, but only assign values from {0, ..., n-1}
static void solveNQueens(int n, Set<Queen> result) {
  Squander.exe(null, n, result);
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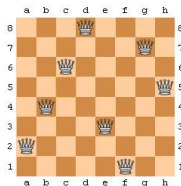
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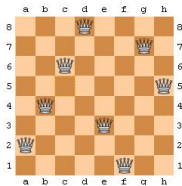
says **what**, not how



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  "  q.i + q.j != r.i + r.j" }) // not in the same ↙ diagonal

@Modifies({
  "result.elts.i from {0 ... n-1}", // modify fields i and j of all elements of
  "result.elts.j from {0 ... n-1}" }) // the result set, but only assign values from {0, ..., n-1}

static void solveNQueens(int n, Set<Queen> result) {
  Squander.exe(null, n, result);
}
```

says **what**, not **how**

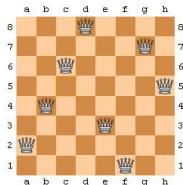
(almost) **correct by construction!**



# SQUANDER vs Manual Search

## N-Queens

- *place  $N$  queens on an  $N \times N$  chess board such that no two queens attack each other*



## A solution with SQUANDER

```
@Ensures({
  "all disj q, r: result.elts | " + // for every two different queens q and r ensure that they are
  "  q.i      != r.i      && " + // not in the same row
  "  q.j      != r.j      && " + // not in the same column
  "  q.i - q.j != r.i - r.j && " + // not in the same ↖ diagonal
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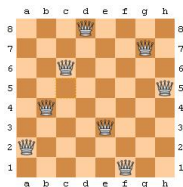
(almost) **correct by construction!**

## What about performance?

# SQUANDER vs Manual Search

## N-Queens

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## A solution with SQUANDER

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(almost) **correct by construction!**

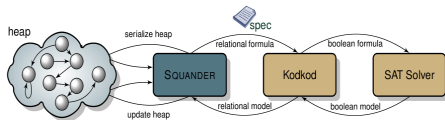
## What about performance?

- It even outperforms the backtracking algorithm in this case!

# Outline

## Framework Overview

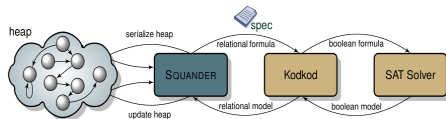
- specification language
- SQUANDER architecture



# Outline

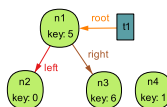
## Framework Overview

- specification language
- SQUANDER architecture



## Translation

- from Java heap + specs to Kodkod
- minimizing the universe size



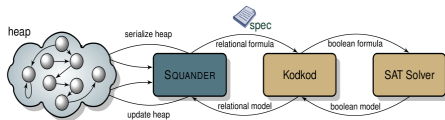
**BST1:**  $\{t_1\}$     **N3:**  $\{n_3\}$     **BST\_this:**  $\{t_1\}$   
**N1:**  $\{n_1\}$     **N4:**  $\{n_4\}$     **z:**  $\{n_4\}$   
**N2:**  $\{n_2\}$     **null:**  $\{null\}$     **ints:**  $\{0, 1, 5, 6\}$

**key\_pre:**  $\{(n_1 \rightarrow 5), (n_2 \rightarrow 0), (n_3 \rightarrow 6), (n_4 \rightarrow 1)\}$   
**root\_pre:**  $\{(t_1 \rightarrow n_1)\}$   
**left\_pre:**  $\{(n_1 \rightarrow n_2), (n_2 \rightarrow null), (n_3 \rightarrow null), (n_4 \rightarrow null)\}$   
**right\_pre:**  $\{(n_1 \rightarrow n_3), (n_2 \rightarrow null), (n_3 \rightarrow null), (n_4 \rightarrow null)\}$   
**root:**  $\{, \{t_1 \times \{n_1, n_2, n_3, n_4\}\}$   
**left:**  $\{, \{n_1, n_2, n_3, n_4\} \times \{n_1, n_2, n_3, n_4\}$   
**right:**  $\{, \{n_1, n_2, n_3, n_4\} \times \{n_1, n_2, n_3, n_4\}$

# Outline

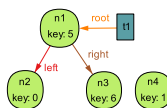
## Framework Overview

- specification language
- SQUANDER architecture



## Translation

- from Java heap + specs to Kodkod
- minimizing the universe size



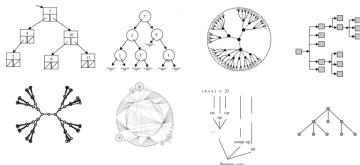
<b>BST1:</b>	{t <sub>1</sub> }	<b>N3:</b>	{n <sub>3</sub> }	<b>BST_this:</b>	{t <sub>1</sub> }
<b>N1:</b>	{n <sub>1</sub> }	<b>N4:</b>	{n <sub>4</sub> }	<b>z:</b>	{n <sub>4</sub> }
<b>N2:</b>	{n <sub>2</sub> }	<b>null:</b>	{null}	<b>ints:</b>	{0, 1, 5, 6}

→

<b>key_pre:</b>	{(n <sub>1</sub> → 5), (n <sub>2</sub> → 0), (n <sub>3</sub> → 6), (n <sub>4</sub> → 1)}
<b>root_pre:</b>	{(t <sub>1</sub> → n <sub>1</sub> )}
<b>left_pre:</b>	{(n <sub>1</sub> → n <sub>2</sub> ), (n <sub>2</sub> → null), (n <sub>3</sub> → null), (n <sub>4</sub> → null)}
<b>right_pre:</b>	{(n <sub>1</sub> → n <sub>3</sub> ), (n <sub>2</sub> → null), (n <sub>3</sub> → null), (n <sub>4</sub> → null)}
<b>root:</b>	{}, {t <sub>1</sub> } × {n <sub>1</sub> , n <sub>2</sub> , n <sub>3</sub> , n <sub>4</sub> }
<b>left:</b>	{}, {n <sub>1</sub> , n <sub>2</sub> , n <sub>3</sub> , n <sub>4</sub> } × {n <sub>1</sub> , n <sub>2</sub> , n <sub>3</sub> , n <sub>4</sub> }
<b>right:</b>	{}, {n <sub>1</sub> , n <sub>2</sub> , n <sub>3</sub> , n <sub>4</sub> } × {n <sub>1</sub> , n <sub>2</sub> , n <sub>3</sub> , n <sub>4</sub> }

## Treatment of Data Abstractions

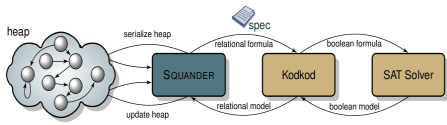
- support for third party **library classes** (e.g. Java collections)



# Outline

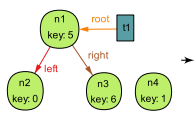
## Framework Overview

- specification language
- SQUANDER architecture



## Translation

- from Java heap + specs to Kodkod
- minimizing the universe size



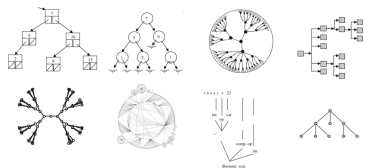
BST1:	{t1}	N3:	{n3}	BST_this:	{t1}
N1:	{n1}	N4:	{n4}	z:	{n4}
N2:	{n2}	null:	{null}	ints:	{0, 1, 5, 6}

key_pre:	{(n1 → 5), (n2 → 0), (n3 → 6), (n4 → 1)}
root_pre:	{(t1 → n1)}
left_pre:	{(n1 → n2), (n2 → null), (n3 → null), (n4 → null)}
right_pre:	{(n1 → n3), (n2 → null), (n3 → null), (n4 → null)}
root:	{}, {t1} × {n1, n2, n3, n4}
left:	{}, {n1, n2, n3, n4} × {n1, n2, n3, n4}
right:	{}, {n1, n2, n3, n4} × {n1, n2, n3, n4}

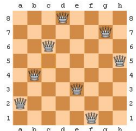
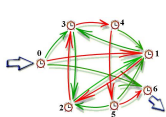
## Treatment of Data Abstractions

- support for third party library classes (e.g. Java collections)



## Evaluation/Case Study

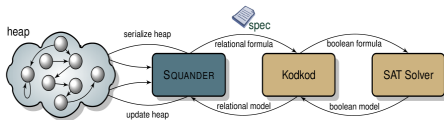
- performance advantages for some puzzles and graph algorithms
- case study: MIT course scheduler



# Framework Overview

## Framework Overview

- specification language
- SQUANDER architecture



## Translation

- from Java heap + specs to Kodkod
- minimizing the universe size



## Treatment of Data Abstractions

- support for third party library classes (e.g. Java collections)



## Evaluation/Case Study

- performance advantages for some puzzles and graph algorithms
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# Specification Language

## Example - Binary Search Tree

```
public class Tree {  
    private Node root;  
}
```

```
public class Node {  
    private Node left, right;  
    private int key;  
}
```



# Specification Language

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## Annotations

class specification field

`@SpecField` ("`<fld_decl>` | `<abs_func>`")

# Specification Language

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# Specification Language

## Example - Binary Search Tree

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class invariant                @Invariant (" $\langle$ expr $\rangle$ ")

# Specification Language

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**public class** Tree {

**class invariant**      **@Invariant** ("**<expr>**")  
**@Invariant**{  
    /\* left sorted \*/ "**all** x: **this.left.\*(left+right) - null** | x.key < **this.key**",  
    /\* right sorted \*/ "**all** x: **this.right.\*(left+right) - null** | x.key > **this.key**"}  
**public class** Node {

# Specification Language

## Example - Binary Search Tree

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public class Tree {  
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public class Node {  
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method pre-condition              **@Requires** ("**<expr>**")  
method post-condition              **@Ensures** ("**<expr>**")  
method frame condition            **@Modifies** ("**<fld>** | **<filter>** **from** **<domain>**")

# Specification Language

## Example - Binary Search Tree

```
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## Annotations

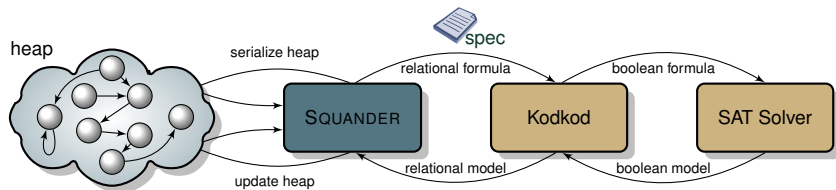
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@Requires ("**z.key !in this.nodes.key**")  
@Ensures ("**this.nodes = @old(this.nodes) + z**")  
@Modifies ("**this.root, this.nodes.left | \_<1> = null, this.nodes.right | \_<1> = null**")  
public void insertNode(Node z) { Squander.exe(**this**, z); }

# Framework Overview



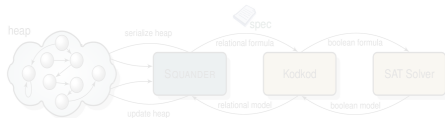
## Execution steps

- traverse the heap and assemble the relevant constraints
- translate to Kodkod
  - translate the heap to relations and bounds
  - collect all the specs and assemble a single relational formula
- if a solution is found, update the heap to reflect the solution

# Translation

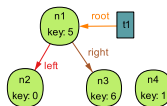
## Framework Overview

- specification language
- SQUANDER architecture



## Translation

- from **Java heap + specs** to **Kodkod**
- **minimizing** the universe size



<b>BST1:</b>	{t <sub>1</sub> }	<b>N3:</b>	{r <sub>3</sub> }	<b>BST_this:</b>	{t <sub>1</sub> }
<b>N1:</b>	{r <sub>1</sub> }	<b>N4:</b>	{r <sub>4</sub> }	<b>z:</b>	{r <sub>4</sub> }
<b>N2:</b>	{r <sub>2</sub> }	<b>null:</b>	{null}	<b>ints:</b>	{0, 1, 5, 6}

<b>key_pre:</b>	{(r <sub>1</sub> → 5), (r <sub>2</sub> → 0), (r <sub>3</sub> → 6), (r <sub>4</sub> → 1)}
<b>root_pre:</b>	{(t <sub>1</sub> → n <sub>1</sub> )}
<b>left_pre:</b>	{(n <sub>1</sub> → n <sub>2</sub> ), (n <sub>2</sub> → null), (n <sub>3</sub> → null), (n <sub>4</sub> → null)}
<b>right_pre:</b>	{(n <sub>1</sub> → n <sub>3</sub> ), (n <sub>3</sub> → null), (n <sub>3</sub> → null), (n <sub>4</sub> → null)}
<b>root:</b>	{}, {t <sub>1</sub> } × {n <sub>1</sub> , n <sub>2</sub> , n <sub>3</sub> , n <sub>4</sub> }
<b>left:</b>	{}, {n <sub>1</sub> , n <sub>2</sub> , n <sub>3</sub> , n <sub>4</sub> } × {n <sub>1</sub> , n <sub>2</sub> , n <sub>3</sub> , n <sub>4</sub> }
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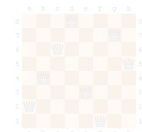
## Treatment of Data Abstractions

- support for third party library classes (e.g. Java collections)



## Evaluation/Case Study

- performance advantages for some puzzles and graph algorithms
- case study: *MIT course scheduler*





# From Objects to Relations

## The back-end solver — Kodkod

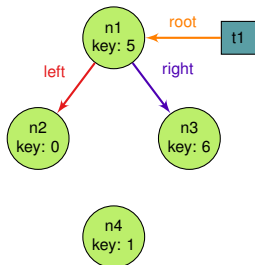
- constraint solver for **first-order logic with relations**
- SAT-based **finite** relational model finder
  - finite **bounds** must be provided for all relations
- designed to be efficient for **partial models**
  - partial instances are encoded using bounds



# From Objects to Relations

## Translation of the `BST.insert` method

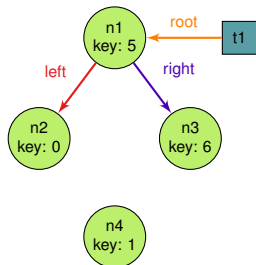
```
@Requires("z.key !in this.nodes.key")  
@Ensures("this.nodes = @old(this.nodes) + z")  
@Modifies("this.root, this.nodes.left | _<1> = null, this.nodes.right | _<1> = null")  
public void insertNode(Node z) { Squander.exe(this, z); }
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# From Objects to Relations

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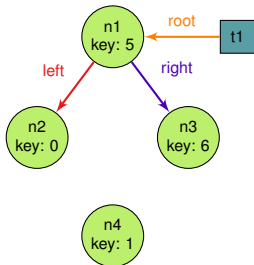
<b>BST1:</b>	{ <i>t</i> <sub>1</sub> }	<b>N3:</b>	{ <i>n</i> <sub>3</sub> }	<b>BST_this:</b>	{ <i>t</i> <sub>1</sub> }
<b>N1:</b>	{ <i>n</i> <sub>1</sub> }	<b>N4:</b>	{ <i>n</i> <sub>4</sub> }	<b>z:</b>	{ <i>n</i> <sub>4</sub> }
<b>N2:</b>	{ <i>n</i> <sub>2</sub> }	<b>null:</b>	{ <i>null</i> }	<b>ints:</b>	{0, 1, 5, 6}

— reachable  
objects

# From Objects to Relations

## Translation of the BST.insert method

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@Requires("z.key !in this.nodes.key")  
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<b>N1:</b>	{n <sub>1</sub> }	<b>N4:</b>	{n <sub>4</sub> }	<b>z:</b>	{n <sub>4</sub> }
<b>N2:</b>	{n <sub>2</sub> }	<b>null:</b>	{null}	<b>ints:</b>	{0, 1, 5, 6}

reachable  
objects

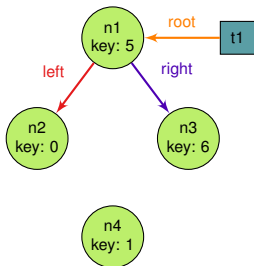
<b>key_pre:</b>	{(n <sub>1</sub> → 5), (n <sub>2</sub> → 0), (n <sub>3</sub> → 6), (n <sub>4</sub> → 1)}
<b>root_pre:</b>	{(t <sub>1</sub> → n <sub>1</sub> )}
<b>left_pre:</b>	{(n <sub>1</sub> → n <sub>2</sub> ), (n <sub>2</sub> → null), (n <sub>3</sub> → null), (n <sub>4</sub> → null)}
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pre-state

# From Objects to Relations

## Translation of the BST.insert method

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@Requires("z.key !in this.nodes.key")
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<b>BST1:</b>	$\{t_1\}$	<b>N3:</b>	$\{n_3\}$	<b>BST_this:</b>	$\{t_1\}$
<b>N1:</b>	$\{n_1\}$	<b>N4:</b>	$\{n_4\}$	<b>z:</b>	$\{n_4\}$
<b>N2:</b>	$\{n_2\}$	<b>null:</b>	$\{null\}$	<b>ints:</b>	$\{0, 1, 5, 6\}$

reachable  
objects

<b>key_pre:</b>	$\{(n_1 \rightarrow 5), (n_2 \rightarrow 0), (n_3 \rightarrow 6), (n_4 \rightarrow 1)\}$
<b>root_pre:</b>	$\{(t_1 \rightarrow n_1)\}$
<b>left_pre:</b>	$\{(n_1 \rightarrow n_2), (n_2 \rightarrow null), (n_3 \rightarrow null), (n_4 \rightarrow null)\}$
<b>right_pre:</b>	$\{(n_1 \rightarrow n_3), (n_2 \rightarrow null), (n_3 \rightarrow null), (n_4 \rightarrow null)\}$

pre-state

<b>root:</b>	$\{\}$	$\{t_1\} \times \{n_1, n_2, n_3, n_4, null\}$
<b>left:</b>	$\{n_1 \rightarrow n_2\}$	$\{n_2, n_3, n_4\} \times \{n_1, n_2, n_3, n_4, null\}$
<b>right:</b>	$\{n_1 \rightarrow n_3\}$	$\{n_2, n_3, n_4\} \times \{n_1, n_2, n_3, n_4, null\}$

post-state

lower bound

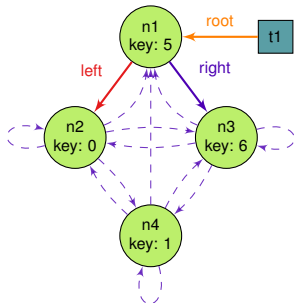
upper bound

- **lower bound:** tuples that **must** be included
- **upper bound:** tuples that **may** be included
- shrinking the bounds (instead of adding more constraints) leads to more efficient solving

# From Objects to Relations

## Translation of the BST.insert method

```
@Requires("z.key !in this.nodes.key")
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<b>BST1:</b>	$\{t_1\}$	<b>N3:</b>	$\{n_3\}$	<b>BST_this:</b>	$\{t_1\}$
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post-state

lower bound

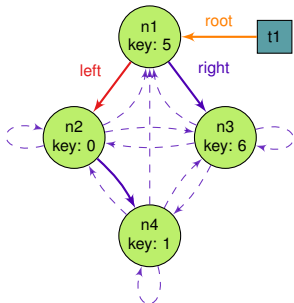
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post-state

lower bound

upper bound

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# Performance of `Tree.insertNode`

## What about performance now?

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@Requires("z.key !in this.nodes.key")
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- reason: tree insertion is **algorithmically simple**
  - imperative algorithm scales better than NP-complete SAT solving

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“Squander”: *wasting CPU cycles for programmer's cycles*

## Saving programmer's cycles

- **fast prototyping**: get a correct working solution early on
- **differential testing**: compare the results of imperative and declarative implementations
- **test input generation**: use SQUANDER to generate some binary trees

# Generating Binary Search Trees with SQUANDER

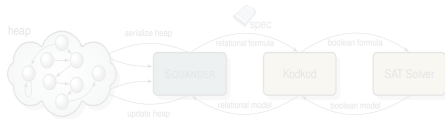
```
@Ensures("#this.nodes = size")
@Modifies("this.root, Node.left, Node.right, Node.key")
@FreshObjects(cls=Node.class, num = size),
@Options(solveAll = true)
public void gen(int size) { Squander.exe(this); }
```

- to generate many different trees
  - the caller can use the SQUANDER API to request a different solution for the same specification

# Treatment of Data Abstractions

## Framework Overview

- specification language
- SQUANDER architecture



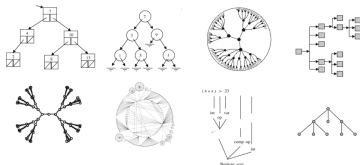
## Translation

- from Java heap + specs to Kodkod
- minimizing the universe size



## Treatment of Data Abstractions

- support for third party **library classes** (e.g. Java collections)



## Evaluation/Case Study

- performance advantages for some puzzles and graph algorithms
- case study: *MIT course scheduler*



# User-Defined Abstractions for Library Types

## Why is it important to be able to specify library types?

- library classes are ubiquitous
- specs need to be able to talk about them

```
class Graph {  
    class Node { public int key; }  
    class Edge { public Node src, dest; }  
  
    private Set<Node> nodes = new LinkedHashSet<Node>();  
    private Set<Edge> edges = new LinkedHashSet<Edge>();  
  
    // how to write a spec for the k-Coloring  
    // problem for a graph like this?  
    public Map<Node, Integer> color(int k) {  
        return Squander.exe(this, k);  
    }  
}
```

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    }  
}
```

- **solution:**

- use @SpecField to specify **abstract data types**

# User-Defined Abstractions for Library Types

## How to support a third party class?

- write a spec file

```
interface Map<K, V> {  
  @SpecField("elts: K -> V")  
  
  @SpecField("size: one int | this.size = #this.elts")  
  @SpecField("keys: set K | this.keys = this.elts.(V)")  
  @SpecField("vals: set V | this.vals = this.elts[K]")  
  
  @Invariant({"all k: K | k in this.elts.V => one this.elts[k]"})  
}
```



# User-Defined Abstractions for Library Types

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}
```

- write an **abstraction** and a **concretization** function

```
public class MapSer implements IObjSer {  
  public List<FieldValue> absFunc(JavaScene javaScene, Object obj) {  
    // return values for the field "elts": Map -> K -> V  
  }  
  
  public Object concrFunc(Object obj, FieldValue fieldValue) {  
    // update and return the given object "obj" from  
    // the given values of the given abstract field  
  }  
}
```

# Using Collections: Example

## Now we can specify the k-Coloring problem

```
class Graph {  
  class Node { public int key; }  
  class Edge { public Node src, dest; }  
  
  private Set<Node> nodes = new LinkedHashSet<Node>();  
  private Set<Edge> edges = new LinkedHashSet<Edge>();  
  
  @Ensures({  
    "return.keys = this.nodes.elts",  
    "return.vals in {1 ... k}",  
    "all e: this.edges.elts | return.elts[e.src] != return.elts[e.dst]"})  
  @Modifies("return.elts")  
  @FreshObjects(cls = Map.class, num = 1)  
  public Map<Node, Integer> color(int k) {return Squander.exe(this, k);}  
}
```

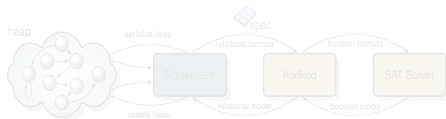
```
interface Set<K> {  
  @SpecField("elts: set K")  
  
  @SpecField("size: one int |  
    this.size=#this.elts")  
}
```

```
interface Map<K,V> {  
  @SpecField("elts: K -> V")  
  
  @SpecField("size: one int | this.size = #this.elts")  
  @SpecField("keys: set K | this.keys = this.elts.(V)")  
  @SpecField("vals: set V | this.vals = this.elts[K]")  
  
  @Invariant({"all k: K | k in this.elts.V => one this.elts[k]"}))
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# Evaluation/Case Study

## Framework Overview

- specification language
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## Translation

- from Java heap + specs to Kodkod
- minimizing the universe size



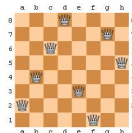
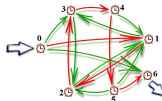
## Treatment of Data Abstractions

- support for third party library classes (e.g. Java collections)



## Evaluation/Case Study

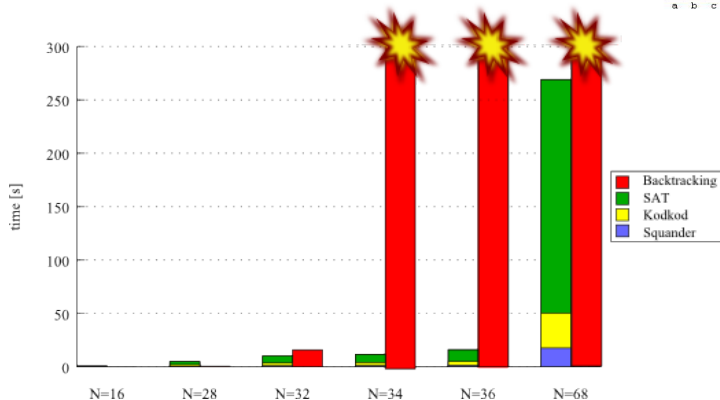
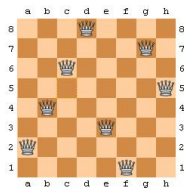
- **performance advantages** for some puzzles and graph algorithms
- case study: *MIT course scheduler*



# SQUANDER vs Manual Search

## N-Queens

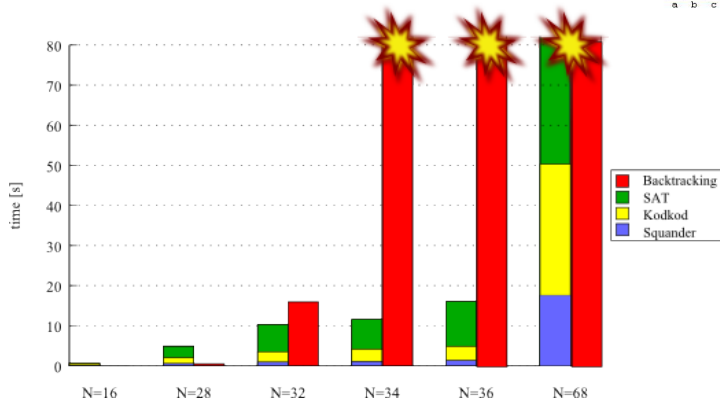
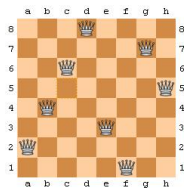
- place  $N$  queens on an  $N \times N$  chess board such that no two queens attack each other



# SQUANDER vs Manual Search

## N-Queens

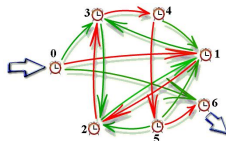
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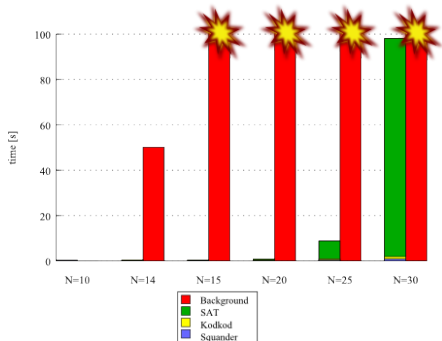
# SQUANDER vs Manual Search

## Hamiltonian Path

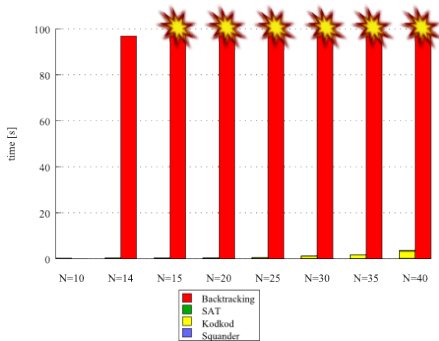
- find a path in a graph that visits all nodes exactly once



### Graphs with Hamiltonian path



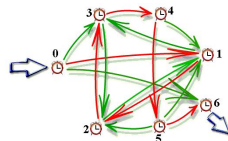
### Graphs with no Hamiltonian path



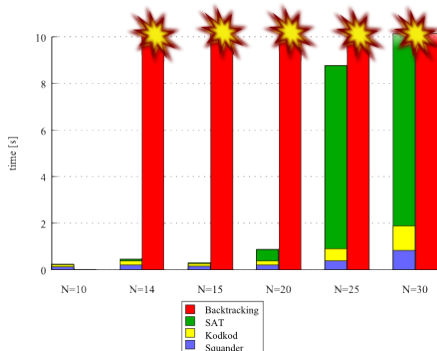
# SQUANDER vs Manual Search

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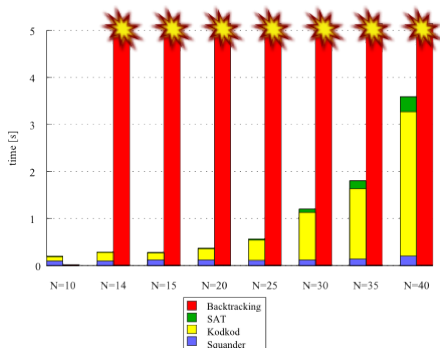
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### Graphs with Hamiltonian path



### Graphs with no Hamiltonian path



# SQUANDER vs Manual Search

**So, is SQUANDER always better than backtracking?**

- **of course not!**

**Rather, the takeaway point is**

- if the problem is easy to specify, it makes sense to do that first
  1. you'll get a correct solution faster
  2. if the problem is **algorithmically complex**, the scalability might be satisfying as well



# Other Evaluation Questions

- **usability on a real-world constraint problem**
- **annotation overhead**
- **ability to handle large program heaps**
- **efficiency**

# Case Study – Course Scheduler

Scheduler

Load Requirements Load Schedule Save Requirements Save Schedule Create Schedule

from Spring 2011 to Fall 2013

PastSemesters

Spring 2011

18.03	✖	<	>
18.440	✖	<	>
2.003	✖	<	>
8.02	✖	<	>

Fall 2011

18.02	✖	<	>
6.001	✖	<	>
6.002	✖	<	>
6.021	✖	<	>
6.UAT	✖	<	>

Spring 2012

6.004	✖	<	>
6.826	✖	<	>
6.UAP	✖	<	>

Fall 2012

6.003	✖	<	>
6.837	✖	<	>

Spring 2013

6.011	✖	<	>
6.012	✖	<	>

Fall 2013

6.170	✖	<	>
-------	---	---	---

Course Grouping Tree

- bio-lab
- core
- ee-headers
- eecs-ec
- lab
- math
- project

18.02  
18.03  
18.440  
2.003  
6.001  
6.002  
6.003  
6.004  
6.011  
6.012  
6.021  
6.170  
6.826  
6.837  
6.UAP  
6.UAT  
8.02

Additional Requirements:

Remove	18.440 BEFORE Fall 2011
Remove	6.004 BEFORE Spring 2013
Remove	6.UAP BEFORE Fall 2012
Remove	6.UAT AFTER Spring 2011

# Other Evaluation Questions

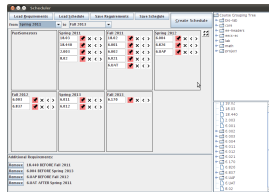
- usability on a real-world constraint problem
- annotation overhead
- ability to handle large program heaps
- efficiency

Performance	Spring 2011	Fall 2011	Spring 2011	Fall 2011	
18.41	X C S	18.41	X C S	18.41	X C S
18.42	X C S	18.41	X C S	18.41	X C S
18.43	X C S	18.41	X C S	18.41	X C S
18.44	X C S	18.41	X C S	18.41	X C S
18.45	X C S	18.41	X C S	18.41	X C S
18.46	X C S	18.41	X C S	18.41	X C S
18.47	X C S	18.41	X C S	18.41	X C S
18.48	X C S	18.41	X C S	18.41	X C S
18.49	X C S	18.41	X C S	18.41	X C S
18.50	X C S	18.41	X C S	18.41	X C S
18.51	X C S	18.41	X C S	18.41	X C S
18.52	X C S	18.41	X C S	18.41	X C S
18.53	X C S	18.41	X C S	18.41	X C S
18.54	X C S	18.41	X C S	18.41	X C S
18.55	X C S	18.41	X C S	18.41	X C S
18.56	X C S	18.41	X C S	18.41	X C S
18.57	X C S	18.41	X C S	18.41	X C S
18.58	X C S	18.41	X C S	18.41	X C S
18.59	X C S	18.41	X C S	18.41	X C S
18.60	X C S	18.41	X C S	18.41	X C S
18.61	X C S	18.41	X C S	18.41	X C S
18.62	X C S	18.41	X C S	18.41	X C S
18.63	X C S	18.41	X C S	18.41	X C S
18.64	X C S	18.41	X C S	18.41	X C S
18.65	X C S	18.41	X C S	18.41	X C S
18.66	X C S	18.41	X C S	18.41	X C S
18.67	X C S	18.41	X C S	18.41	X C S
18.68	X C S	18.41	X C S	18.41	X C S
18.69	X C S	18.41	X C S	18.41	X C S
18.70	X C S	18.41	X C S	18.41	X C S

Additional Requirements

18.41	18.41	18.41	18.41
18.42	18.41	18.41	18.41
18.43	18.41	18.41	18.41
18.44	18.41	18.41	18.41
18.45	18.41	18.41	18.41
18.46	18.41	18.41	18.41
18.47	18.41	18.41	18.41
18.48	18.41	18.41	18.41
18.49	18.41	18.41	18.41
18.50	18.41	18.41	18.41
18.51	18.41	18.41	18.41
18.52	18.41	18.41	18.41
18.53	18.41	18.41	18.41
18.54	18.41	18.41	18.41
18.55	18.41	18.41	18.41
18.56	18.41	18.41	18.41
18.57	18.41	18.41	18.41
18.58	18.41	18.41	18.41
18.59	18.41	18.41	18.41
18.60	18.41	18.41	18.41
18.61	18.41	18.41	18.41
18.62	18.41	18.41	18.41
18.63	18.41	18.41	18.41
18.64	18.41	18.41	18.41
18.65	18.41	18.41	18.41
18.66	18.41	18.41	18.41
18.67	18.41	18.41	18.41
18.68	18.41	18.41	18.41
18.69	18.41	18.41	18.41
18.70	18.41	18.41	18.41

# Other Evaluation Questions



- **usability on a real-world constraint problem**
  - an existing implementation retrofitted with SQUANDER
  - didn't have to change the local structure, just annotate classes
  - ... thanks to the **treatment of data abstractions**
- **annotation overhead**
- **ability to handle large program heaps**
- **efficiency**

# Other Evaluation Questions

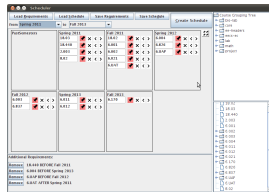
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10.48	X C S	10.48	X C S
10.49	X C S	10.49	X C S
10.50	X C S	10.50	X C S
10.51	X C S	10.51	X C S
10.52	X C S	10.52	X C S
10.53	X C S	10.53	X C S
10.54	X C S	10.54	X C S
10.55	X C S	10.55	X C S
10.56	X C S	10.56	X C S
10.57	X C S	10.57	X C S
10.58	X C S	10.58	X C S
10.59	X C S	10.59	X C S
10.60	X C S	10.60	X C S
10.61	X C S	10.61	X C S
10.62	X C S	10.62	X C S
10.63	X C S	10.63	X C S
10.64	X C S	10.64	X C S
10.65	X C S	10.65	X C S
10.66	X C S	10.66	X C S
10.67	X C S	10.67	X C S
10.68	X C S	10.68	X C S
10.69	X C S	10.69	X C S
10.70	X C S	10.70	X C S
10.71	X C S	10.71	X C S
10.72	X C S	10.72	X C S
10.73	X C S	10.73	X C S
10.74	X C S	10.74	X C S
10.75	X C S	10.75	X C S
10.76	X C S	10.76	X C S
10.77	X C S	10.77	X C S
10.78	X C S	10.78	X C S
10.79	X C S	10.79	X C S
10.80	X C S	10.80	X C S
10.81	X C S	10.81	X C S
10.82	X C S	10.82	X C S
10.83	X C S	10.83	X C S
10.84	X C S	10.84	X C S
10.85	X C S	10.85	X C S
10.86	X C S	10.86	X C S
10.87	X C S	10.87	X C S
10.88	X C S	10.88	X C S
10.89	X C S	10.89	X C S
10.90	X C S	10.90	X C S
10.91	X C S	10.91	X C S
10.92	X C S	10.92	X C S
10.93	X C S	10.93	X C S
10.94	X C S	10.94	X C S
10.95	X C S	10.95	X C S
10.96	X C S	10.96	X C S
10.97	X C S	10.97	X C S
10.98	X C S	10.98	X C S
10.99	X C S	10.99	X C S
11.00	X C S	11.00	X C S

Additional Requirements

- 10.4100 BENCH Fall 2011
- 10.4100 BENCH Spring 2011
- 10.4100 BENCH Fall 2012
- 10.4100 BENCH Spring 2012

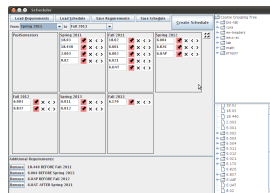
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  - only about 30 lines of specs to replace 1500 lines of code
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- **ability to handle large program heaps**
- **efficiency**

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- **efficiency**
  - about 5s as opposed to 1s of the original implementation

# Limitations

- **boundedness** – SQUANDER can't generate an arbitrary number of new objects; instead the maximum number of new objects must be explicitly specified by the user
- **integers** – integers must also be bounded to a small bitwidth
- **equality** – only referential equality can be used (except for strings)
- **no higher-order expressions** – e.g. can't specify *find the longest path in the graph*; instead must specify the minimum length  $k$ , i.e. *find a path in the graph of length at least  $k$  nodes*
- **debugging** – if a solution cannot be found, the user is not given any additional information as to why the specification wasn't satisfiable



# Future Work

- **optimize translation** to Kodkod
  - use **fewer** relations to represent the heap (short-circuit some unmodifiable ones)
- **support debugging** better
  - when no solution can be found, explain why (with the help of **unsat core**)
- **synthesize** code from specifications
  - especially for methods that only traverse the heap
- **combine different solvers** in the back end
  - SMT solvers would be better at **handling large integers**

# Summary

SQUANDER **lets you**

- **execute** first-order, relational **specifications** in Java



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## Why would you want to do that?

- conveniently **express** and **solve** algorithmically complicated problems using **declarative constraints**
- **gain performance** in certain cases (e.g. for NP-hard problems)
- during development:
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  - generate test inputs
  - runtime assertion checking



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# Thank You!

<http://people.csail.mit.edu/aleks/squander>



# Solving Sudoku with Alloy Analyzer

```
abstract sig Number {}
one sig N1,N2,N3,N4,N5,N6,N7,N8,N9 extends Number {}

one sig Global {
  data: Number -> Number -> one Number
}

pred complete [rows:set Number, cols:set Number]{
  Number = Global.data[rows][cols]
}

pred rules {
  all row: Number { complete[row,Number] }
  all col: Number { complete[Number,col] }
  let r1=N1+N2+N3, r2=N4+N5+N6, r3=N7+N8+N9 |
    complete[r1,r1] and complete[r1,r2] and complete[r1,r3] and
    complete[r2,r1] and complete[r2,r2] and complete[r2,r3] and
    complete[r3,r1] and complete[r3,r2] and complete[r3,r3]
}

pred puzzle {
  N1->N4->N1 + N1->N8->N9 +
  ...
  N9->N2->N2 + N9->N6->N1 in Global.data
}

run { rules and puzzle }
```



			1				9	
6	7	9	2				4	5
			7	3	2			
1						4	8	9
7								5
4	3	6						2
			1	7	9			
7	4			3	2	9	1	
	9					1		

# Solving Sudoku with Kodkod

```
public class Sudoku {
    private Relation Number = Relation.unary("Number");
    private Relation data = Relation.ternary("data");
    private Relation[] regions = new Relation[] {
        Relation.unary("Region1"),
        Relation.unary("Region2"),
        Relation.unary("Region3") };

    public Formula complete(Expression rows, Expression cols) {
        // Number = data[rows][cols]
        return Number.eq(cols.join(rows.join(data))); }

    public Formula rules() {
        // all x,y: Number | lone data[x][y]
        Variable x = Variable.unary("x");
        Variable y = Variable.unary("y");
        Formula f1 = y.join(x.join(data)).lone().
            forAll(x.oneOf(Number).and(y.oneOf(Number)));
        // all row: Number | complete[row, Number]
        Variable row = Variable.unary("row");
        Formula f2 = complete(row, Number).
            forAll(row.oneOf(Number));
        // all col: Number | complete[Number, col]
        Variable col = Variable.unary("col");
        Formula f3 = complete(Number, col).
            forAll(col.oneOf(Number));
        // complete[r1,r1] and complete[r1,r2] and complete[r1,r3] and
        // complete[r2,r1] and complete[r2,r2] and complete[r2,r3] and
        // complete[r3,r1] and complete[r3,r2] and complete[r3,r3]
        Formula rules = f1.and(f2).and(f3);
        for(Relation rx: regions)
            for(Relation ry: regions)
                rules = rules.and(complete(rx,ry));
        return rules;
    }

    public Bounds puzzle() {
        Set<Integer> atoms = new LinkedHashSet<Integer>(9);
        for(int i = 1; i <= 9; i++) { atoms.add(i); }
        Universe u = new Universe(atoms);
        Bounds b = new Bounds(u);
    }
}
```



			1				9	
	6	7	9	2			4	5
				7	3	2		
	1					4	8	9
	7						5	
4	3	6					2	
			1	7	9			
7	4			3	2	9	1	
	9				1			

```
TupleFactory f = u.factory();
b.boundExactly(Number, f.allOf(1));
b.boundExactly(regions[0], f.setOf(1, 2, 3));
b.boundExactly(regions[1], f.setOf(4, 5, 6));
b.boundExactly(regions[2], f.setOf(7, 8, 9));
```

```
TupleSet givens = f.noneOf(3);
givens.add(f.tuple(1, 4, 1));
givens.add(f.tuple(1, 8, 9));
...
givens.add(f.tuple(9, 6, 1));
b.bound(data, givens, f.allOf(3));
return b;
}
```

```
public static void main(String[] args) {
    Solver solver = new Solver();
    solver.options().setSolver(SATFactory.MiniSat);
    Sudoku sudoku = new Sudoku();
    Solution sol = solver.solve(sudoku.rules(), sudoku.puzzle());
    System.out.println(sol);
}
```

# Mixing Imperative and Declarative with SQUANDER

			1				9	
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static class Cell { int num = 0; } // 0 means empty
```

```
@Invariant("all v: int - 0 | lone {c: this.cells.vals | c.num = v}")
```

```
static class CellGroup {  
    Cell[] cells;  
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```
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```

```
@Modifies("Cell.num | _<1> = 0")
```

```
public void solve() { Squander.exe(this); }
```

			1					9
	6	7	9	2				4 5
				7	3	2		
	1						4 8 9	
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```
public static void main(String[] args) {  
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    ...  
    s.rows[8][1].num = 9; s.rows[8][5].num = 1;  
    s.solve();  
    System.out.println(s);  
}
```

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Write more imperative code  
to make constraints simpler

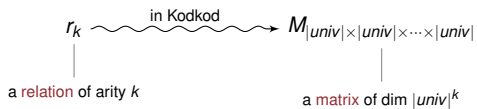
# Everything is a relation

## Everything is a relation

			relation name	relation type
classes	↔ unary relations	<b>class</b> C {}	↔ $\mathcal{R}_C$	: C
objects	↔ unary relations	<b>new</b> C();	↔ $\mathcal{R}_{C_1}$	: C
fields	↔ binary relations	<b>class</b> C { A fld ; }	↔ $\mathcal{R}_{fld}$	: C → A ∪ {null}
arrays	↔ ternary relations	T []	↔ $\mathcal{R}_{T[]\_elems}$	: T [] → int → T ∪ {null}

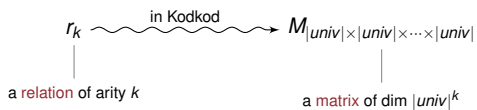
# Minimizing the Universe Size

## Relations in Kodkod



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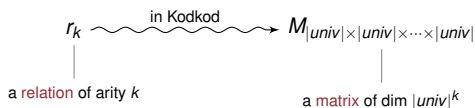


SO

if  $|univ| > 1291 \wedge (\exists r_k \mid k \geq 3)$

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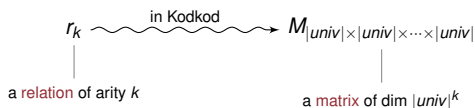
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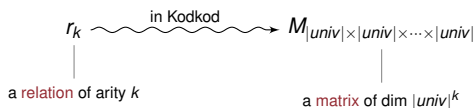
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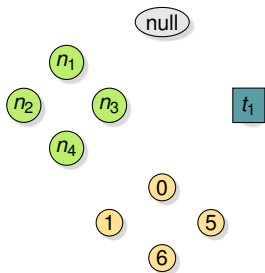
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$\implies$  can't be represented in Kodkod

- ternary relations are not uncommon in SQUANDER (e.g. arrays)
- *MIT course scheduler* case study: almost 2000 objects
- **solution:**
  - **partitioning algorithm** that allows atoms to be shared

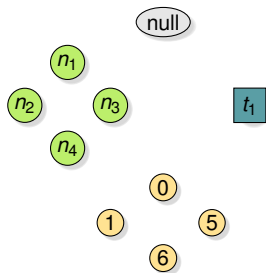
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**goal:** use fewer Kodkod atoms than heap objects



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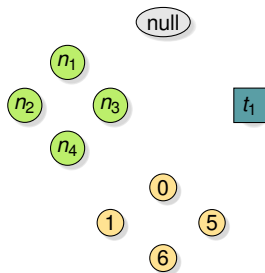
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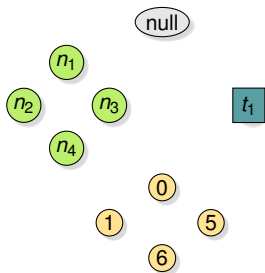
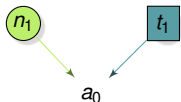
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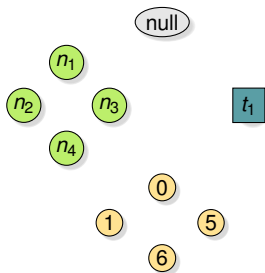
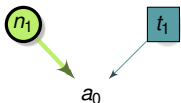
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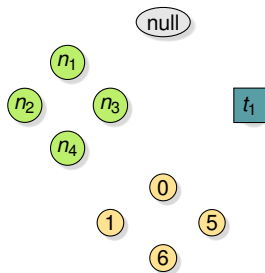
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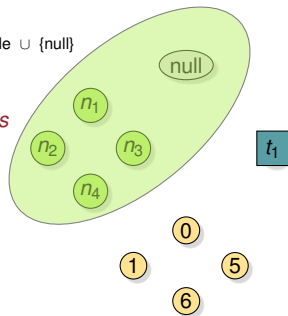
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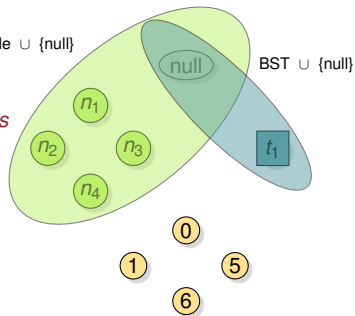
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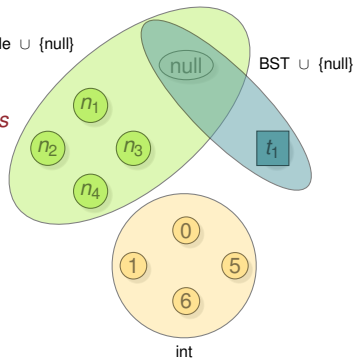
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# Minimizing the Universe

**goal:** use fewer Kodkod atoms than heap objects

→ multiple objects must map to same atoms

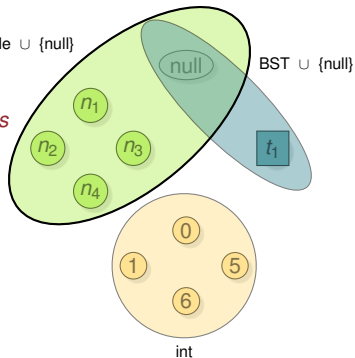
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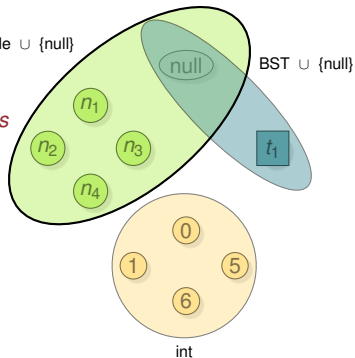
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$a_4$

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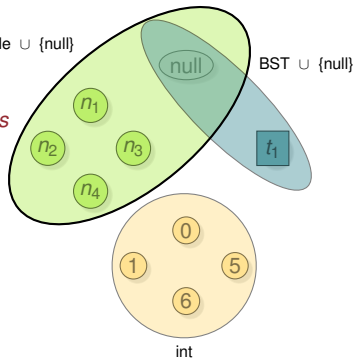
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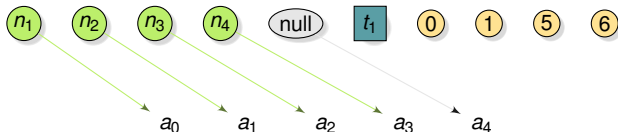
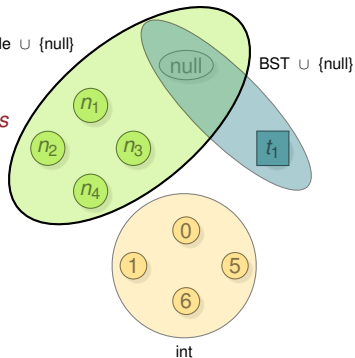
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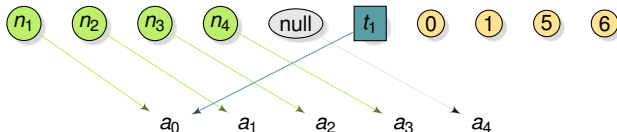
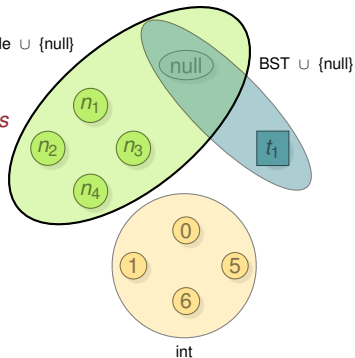
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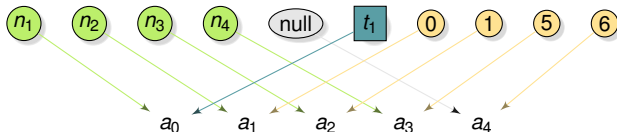
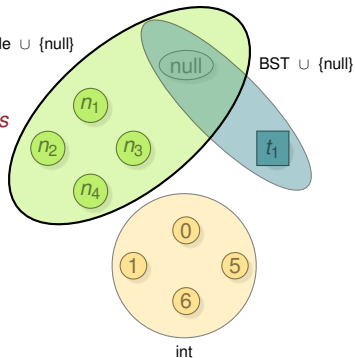
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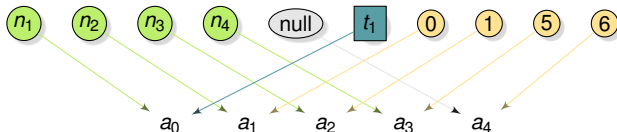
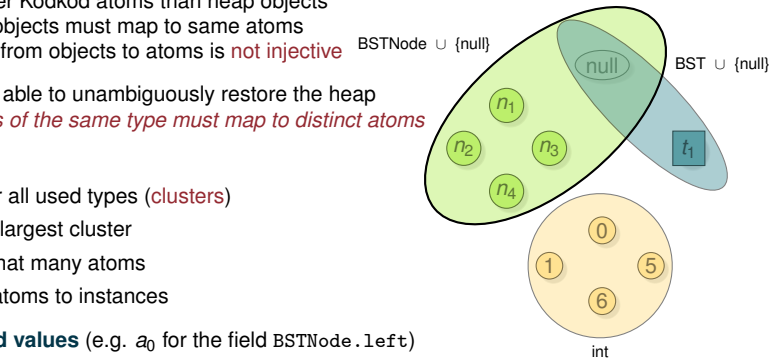
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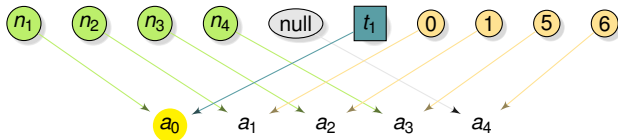
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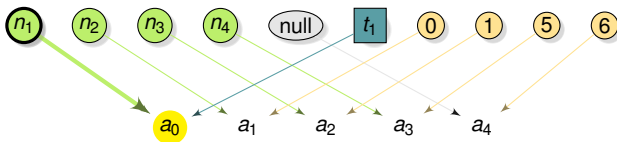
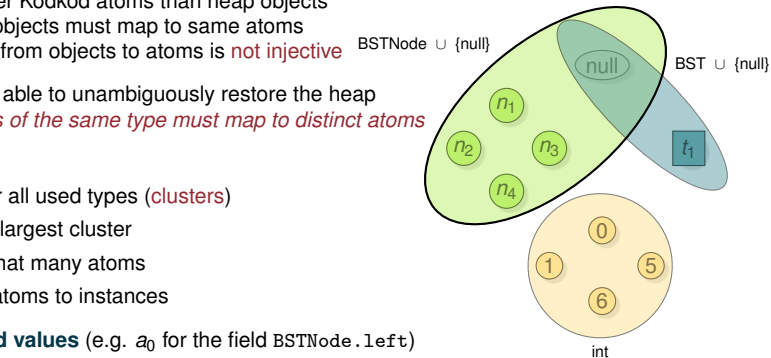
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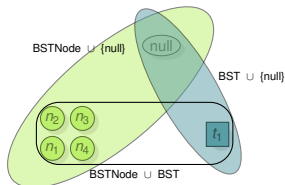
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## Why is this algorithm sufficient?

- what if we had partitions like this:

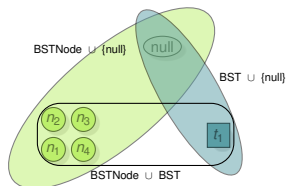


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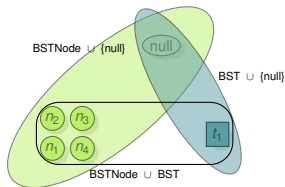
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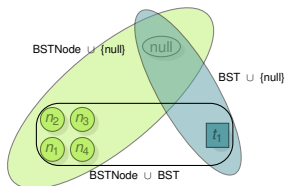
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## Limitations

- no performance gain
- if a field of type `Object` is used, this algorithm has no effect
  - everything is a subtype of `Object` so everything has to go to the same partition



## Executable Specifications:

- **An Overview of Some Formal Methods for Program Design**, C.A.R. Hoare (*IEEE Computer* 1987)
- **Specifications are not (necessarily) executable**, I. Hayes et al. (*SEJ* 1989)
- **Specifications are (preferably) executable**, N.E. Fuchs (*SEJ* 1992)
- **Programming from Specification**, C. Morgan, PrenticeHall, 1998
- **Agile Specifications**, D. Rayside et al. (*Onward!* 2009)
- **Falling Back on Executable Specifications**, H. Samimi et al. (*ECOOP* 2010)
- **Unified Execution of Imperative and Declarative Code**, A. Milicevic et al. (*ICSE* 2011)

## Specification Languages

- **JFSL: JForge Specification Language**, K. Yessenov, MIT 2009
- **Software Abstractions: Logic, Language, and Analysis**, D. Jackson, MIT Press 2006

## Programming Languages with Constraint Programming:

- **Jeeves: Programming with Delegation**, J. Yang, MIT, 2010
- **Programming with Quantifiers**, J.P. Near, MIT, 2010