

# idioms

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6898: Advanced Topics in Software Design

February 13, 2002

# issues

## state change

- › how do you describe change in a logic?

## mutation

- › how do you modularize the change?

## frame conditions

- › how do you control unwanted changes?

# “the relational model”

## ideas

- › view behaviour as a relation on states
- › represent as a simple formula
- › distinct variables for pre- and post-state

## example

- › a procedure that returns the index of an element in an array

```
fun Find (t: Index ->? Elt, e: Elt): Index {  
  t[result] = e  
}
```

## this procedure is

- › partial: some pre-states have no post-states
- › non-deterministic: some pre-states have >1 post-state

# preconditions

what does partiality mean?

- › **guard**  
a control: won't allow invocation in bad state
- › **precondition**  
a disclaimer: havoc if invoked in bad state

# the VDM/Larch approach

make precondition explicit

```
> op Find (t: Index ->? EIt, e: EIt): Index  
  pre  e in Index.(t.map)  
  post t[result] = e
```

do ‘implementability check’

```
> all s: State | pre(s) => some s': State | post(s,s')
```

# the Z approach

precondition is implicit

›  $\text{Find} = [ t: \text{Index} \rightarrow ? \text{Elt}, e?: \text{Elt}, i!: \text{Index} \mid t[i!] = e? ]$

compute precondition

›  $\text{Pre} (\text{Find}) = \text{some } s': \text{State} \mid \text{Find} (s,s')$

and check properties

›  $\text{Pre} (\text{Find}) = \text{true} \quad ??$

# the Alloy approach

roll your own!

- › can split pre/post into distinct functions
- › can combine in different ways
- › can interpret as guard or precondition

```
fun FindPre (t: Index ->? Elt, e: Elt) { e in Index.t }
```

```
fun FindPost (t: Index ->? Elt, e: Elt): Index { t[result] = e }
```

```
fun Find (t: Index ->? Elt, e: Elt): Index {  
  FindPre (t, e) => FindPost (t, result, e)  
}
```

# frame conditions

procedure that removes dupls

```
> fun RemoveDupls (t, t': Index ->? E!t) {  
  Index.t = Index.t'  
  #Index.t' = #t'  
}
```

procedure that sorts array without dupls

```
> fun Sort (t, t': Index ->? E!t) {  
  Index.t = Index.t'  
  all i, j: t.E!t | i->j in Index$t => t[i]->t[j] in E!t$t  
}
```

are these constrained enough?



# summary so far

declarative style is powerful

- › spec by conjunction
- › separation of concerns

declarative style is dangerous

- › implicit preconditions
- › underconstraint

frame conditions

- › subtle for non-deterministic operations
- › subtle in OO programs
- › important stylistic issue, even when not subtle

# modularizing change

## 3 approaches

- › global state machine
- › local state machines
- › object oriented

# a static model of router tables

```
module routing
sig IP {}
sig Link {from, to: Router}
sig Router {ip: IP, table: IP ->? Link, nexts: set Router}
{
  table[IP].from in this
  nexts = table[IP].to
  no table[ip]
}
fact {inj (Router$ip)}
fun Consistent () {
  all r: Router, i: IP | r.table[i].to in i.~ip.*~nexts
}
fun inj [t,t'] (r: t->t') {all x: t' | sole r.x}
```

# a dynamic model

```
sig State {}
sig IP {}
sig Link {from, to: State ->! Router}
sig Router {ip: IP, table: State -> IP ->? Link,
  nexts: State -> Router}
  {
    all s: State {
      (table[s][IP].from) [s] in this
      nexts[s] = (table[s][IP].to)[s]
      no table[s] [ip]
    }
  }
fun Consistent (s: State) {
  let nexts = {r,r': Router | r->s->r' in Router$nexts} |
  all r: Router, i: IP | (r.table[s][i].to) [s] in i.~ip.*~nexts}
```

# Propagation

```
fun Propagate (s, s': State) {  
  let nnexts = {r,r': Router | r->s->r' in Router$nnexts} |  
    all r: Router | r.table[s'] in r.table[s] + r.~nnexts.table[s] }  
assert PropagationOK {  
  all s, s': State |  
    Consistent (s) && Propagate (s,s') => Consistent (s') }  
}
```

can you write NoTopologyChange?

```
fun NoTopologyChange (s,s': State) {  
  all x: Link {  
    x.from[s] = x.from[s'] && x.to[s] = x.to[s']  
  }  
}
```

# global state version

```
sig IP {} sig Link {} sig Router {}
```

```
sig LinkState {  
  from, to: Link -> Router }  
}
```

```
sig NetworkState extends LinkState {
```

```
  ip: Router -> IP,
```

```
  table: Router -> IP ->? Link,
```

```
  nexts: Router -> Router } {
```

```
  all r: Router {
```

```
    table[r][IP].from in r
```

```
    nexts[r] = table[r][IP].to
```

```
    no table[r][r.ip] }
```

```
  inj (ip) }
```

# operations for global version

```
fun Consistent (s: NetworkState) {  
  all r: Router, i: IP |  
    s.table[r][i].to[s] in i.~(ip[s]).*~(nexts[s]) }
```

```
fun Propagate (s, s': NetworkState) {  
  all r: Router {  
    s'.table[r] in s.table[r] + r.~(nexts[s]).(table[s])  
    s.ip[r] = s'.ip[r] } }
```

can you write NoTopologyChange?

```
fun NoTopologyChange (s,s': NetworkState) {  
  s.from = s'.from  
  s.to = s'.to  
}
```

# object oriented version

```
sig IP {}
sig Link {from, to: RouterRef}
sig Router {ip: IP, table: IP ->? LinkRef, nexts: set RouterRef} {
  no table[ip] }
fact {inj (Router$ip)}
sig LinkRef {}
sig RouterRef {}

sig State {
  robj: RouterRef ->! Router,
  lobj: LinkRef ->! Link
}
```



# invariants

router invariant is now recognized as 'cross object'

```
fact {  
  all s: State, r: RouterRef {  
    r.(s.robj).table[IP].(s.lobj).from in r  
    r.(s.robj).nexts = r.(s.robj).table[IP].(s.lobj).to  
  }  
}
```

# operations in OO version

```
fun Consistent (s: State) {  
  all r: RouterRef, i: IP |  
    r.(s.robj).table[i].(s.lobj).to in  
      i.~ip.~(s.robj).*~(s.robj.nexts) }
```

```
fun Propagate (s, s': State) {  
  let nexts = {r,r': Router | r->s->r' in Router$nexts} |  
  all r: RouterRef |  
    r.(s'.robj).table in r.(s.robj).table  
      + r.~(s.robj.nexts).(s.robj).table }
```

can you write NoTopologyChange?

```
fun NoTopologyChange (s,s': State) {  
  s.lobj = s'.lobj }
```

# comparison

how do the approaches compare?

- › ease of expression
- › degree of modularity
- › how systematic
- › frame conditions

*didn't get round to discussing this*