

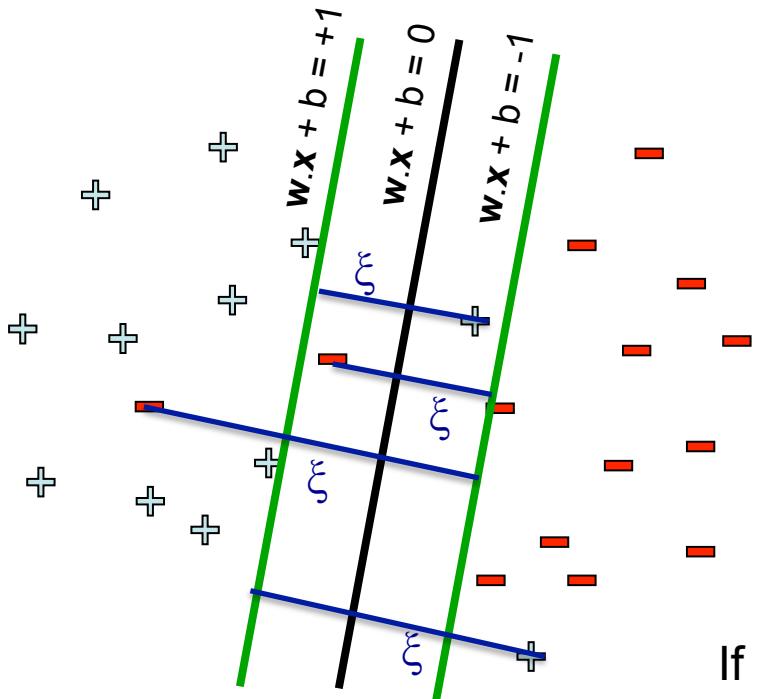
Support vector machines

Lecture 4

David Sontag
New York University

Slides adapted from Luke Zettlemoyer, Vibhav Gogate,
and Carlos Guestrin

Allowing for slack: “Soft margin” SVM



$$\begin{aligned} & \text{minimize}_{\mathbf{w}, b} \quad \mathbf{w} \cdot \mathbf{w} + C \sum_j \xi_j \\ & (\mathbf{w} \cdot \mathbf{x}_j + b) y_j \geq 1 - \xi_j, \forall j \quad \xi_j \geq 0 \end{aligned}$$

↑
“slack variables”

What is the (optimal) value of ξ_j as a function of \mathbf{w} and b ?

If $(\mathbf{w} \cdot \mathbf{x}_j + b) y_j \geq 1$, then $\xi_j = 0$

If $(\mathbf{w} \cdot \mathbf{x}_j + b) y_j < 1$, then $\xi_j = 1 - (\mathbf{w} \cdot \mathbf{x}_j + b) y_j$

Sometimes written as

$$(1 - (\mathbf{w} \cdot \mathbf{x}_j + b) y_j)_+$$

$\leftarrow \xi_j = \max(0, 1 - (\mathbf{w} \cdot \mathbf{x}_j + b) y_j)$

Equivalent hinge loss formulation

$$\begin{aligned} & \text{minimize}_{\mathbf{w}, b} \quad \mathbf{w} \cdot \mathbf{w} + C \sum_j \xi_j \\ & (\mathbf{w} \cdot \mathbf{x}_j + b) y_j \geq 1 - \xi_j, \forall j \quad \xi_j \geq 0 \end{aligned}$$

Substituting $\xi_j = \max(0, 1 - (\mathbf{w} \cdot \mathbf{x}_j + b) y_j)$ into the objective, we get:

$$\min ||\mathbf{w}||^2 + C \sum_j \max(0, 1 - (\mathbf{w} \cdot \mathbf{x}_j + b) y_j)$$

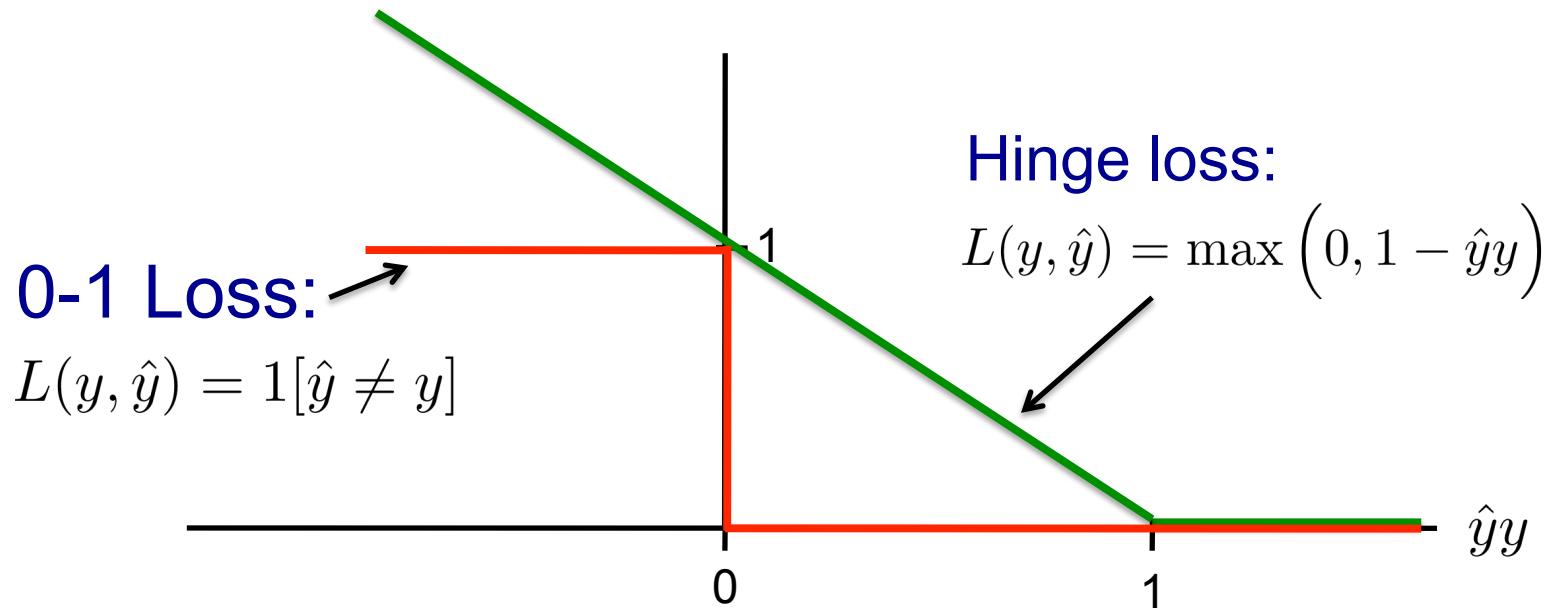
The **hinge loss** is defined as $L(y, \hat{y}) = \max(0, 1 - \hat{y}y)$

$$\min_{w,b} ||w||_2^2 + C \sum_j L(y_j, \mathbf{w} \cdot \mathbf{x}_j + b)$$

This is called **regularization**;
used to prevent overfitting!

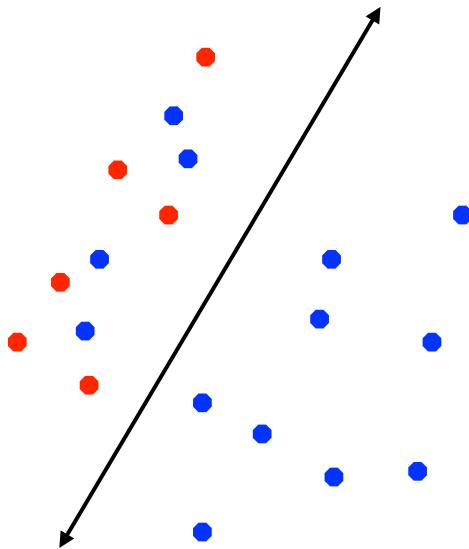
This part is empirical risk minimization,
using the hinge loss

Hinge loss vs. 0/1 loss



Hinge loss upper bounds 0/1 loss!

How to deal with imbalanced data?

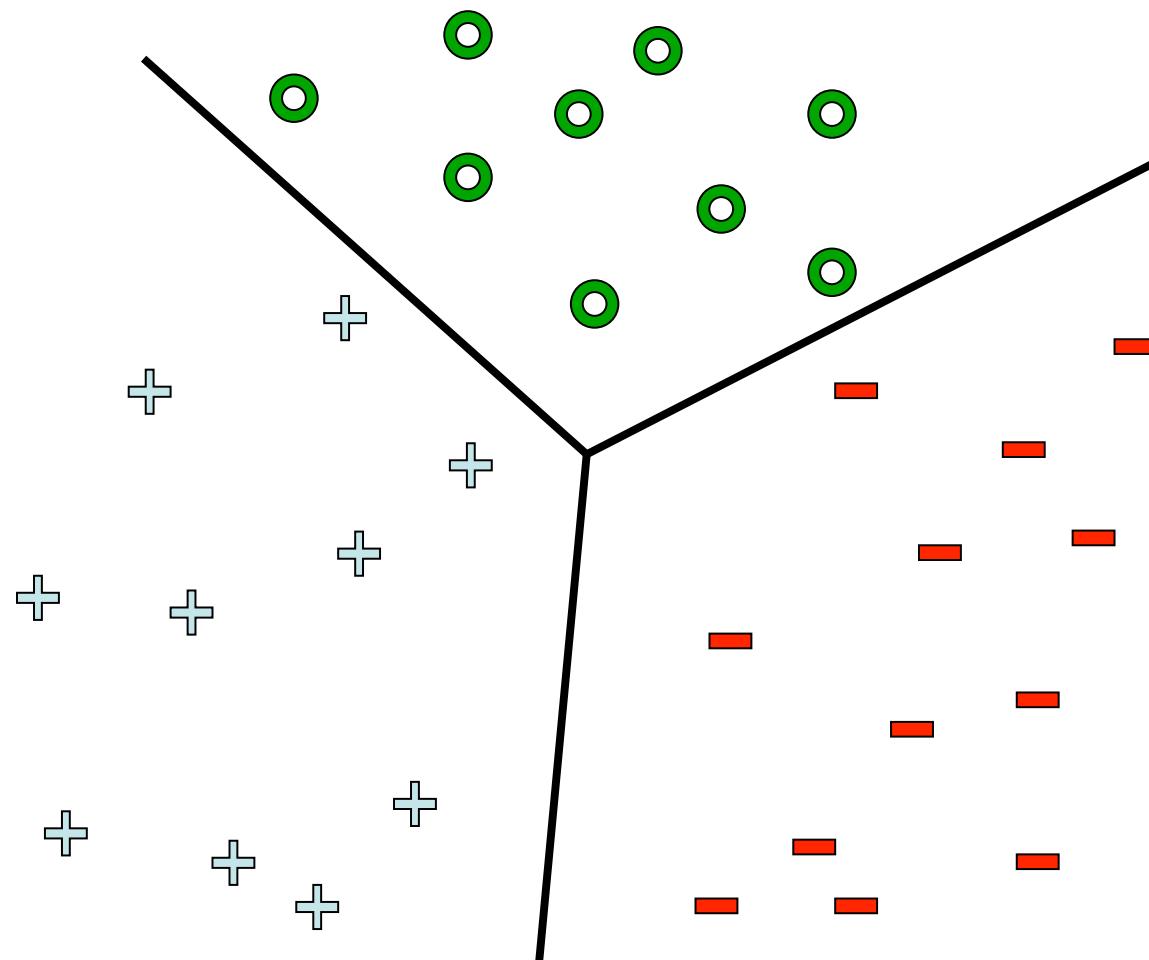


- In many practical applications we may have **imbalanced** data sets
- We may want errors to be equally distributed between the positive and negative classes
- A slight modification to the SVM objective does the trick!

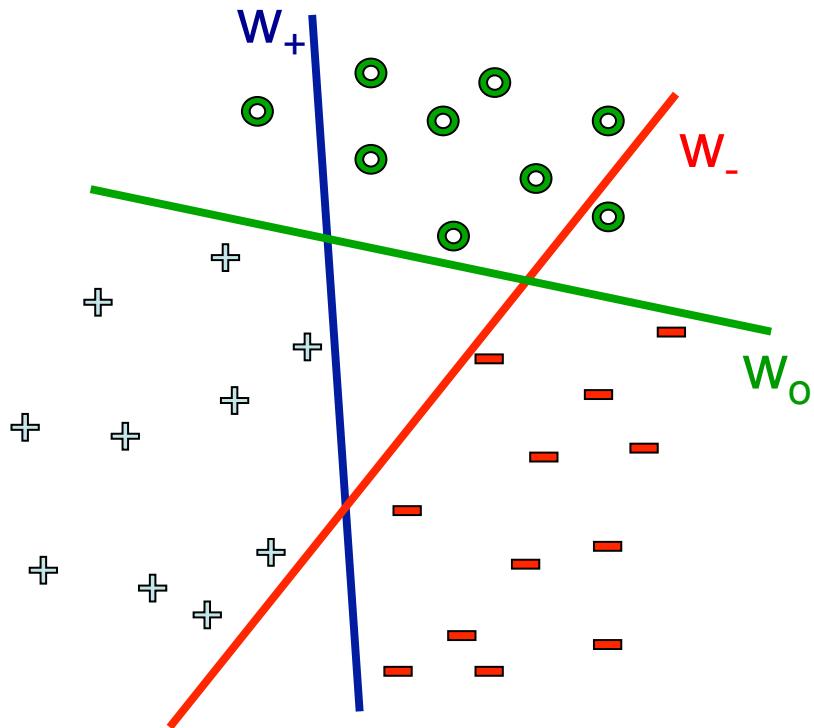
$$\min_{w,b} \frac{1}{2} \|w\|_2^2 + \frac{C}{N_+} \sum_{j : y_j = +1} \xi_j + \frac{C}{N_-} \sum_{j : y_j = -1} \xi_j$$

Class-specific weighting of the slack variables

How do we do multi-class classification?



One versus all classification



Learn 3 classifiers:

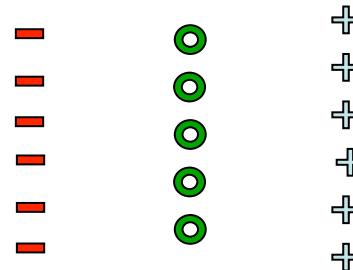
- - vs {o,+}, weights w_-
 - + vs {o,-}, weights w_+
 - o vs {+,-}, weights w_o

Predict label using:

$$\hat{y} \leftarrow \arg \max_k w_k \cdot x + b_k$$

Any problems?

Could we learn this dataset? →

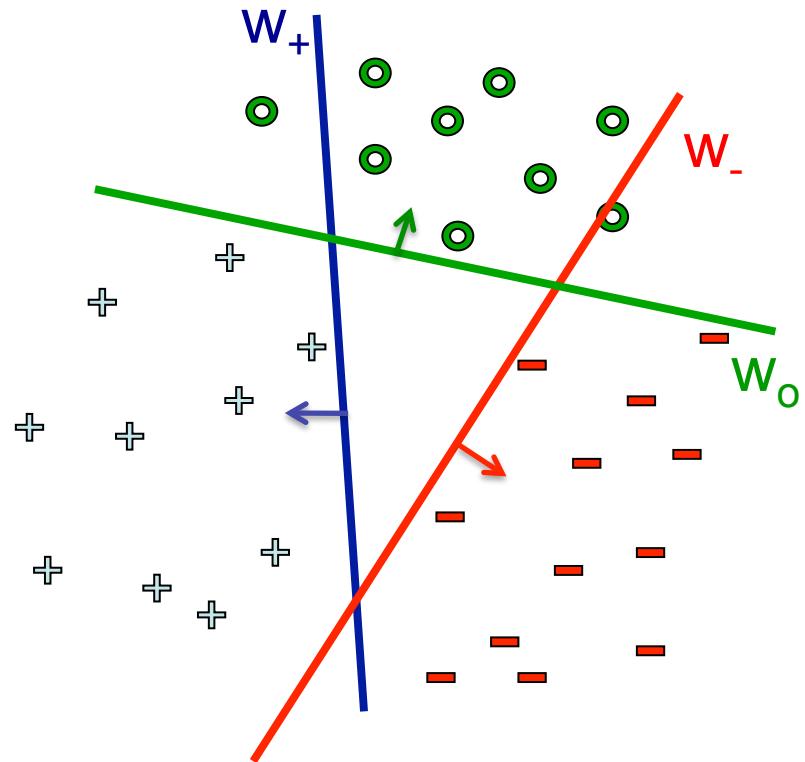


Multi-class SVM

Simultaneously learn 3 sets of weights:

- How do we guarantee the correct labels?
- Need new constraints!

The “score” of the correct class must be better than the “score” of wrong classes:



$$w^{(y_j)} \cdot x_j + b^{(y_j)} > w^{(y)} \cdot x_j + b^{(y)} \quad \forall j, y \neq y_j$$

Multi-class SVM

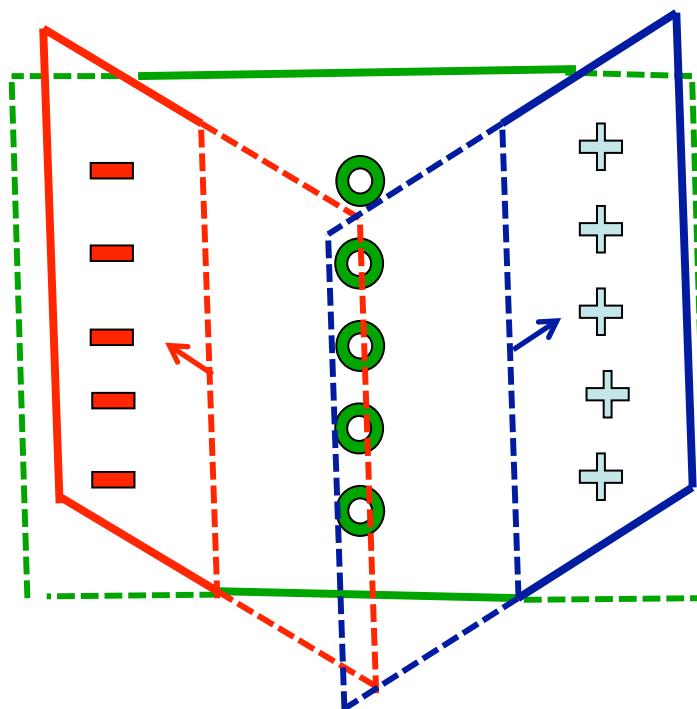
As for the SVM, we introduce slack variables and maximize margin:

$$\begin{aligned} & \text{minimize}_{\mathbf{w}, b} \sum_y \mathbf{w}^{(y)} \cdot \mathbf{w}^{(y)} + C \sum_j \xi_j \\ & \mathbf{w}^{(y_j)} \cdot \mathbf{x}_j + b^{(y_j)} \geq \mathbf{w}^{(y')} \cdot \mathbf{x}_j + b^{(y')} + 1 - \xi_j, \quad \forall y' \neq y_j, \quad \forall j \\ & \xi_j \geq 0, \quad \forall j \end{aligned}$$

To predict, we use:

$$\hat{y} \leftarrow \arg \max_k w_k \cdot x + b_k$$

Now can we learn it? →



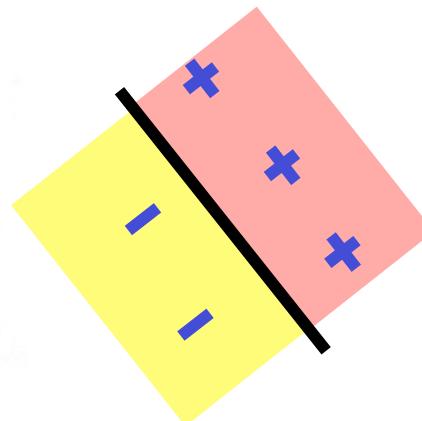
Software

- $\text{SVM}^{\text{light}}$: one of the most widely used SVM packages. Fast optimization, can handle very large datasets, C++ code.
- LIBSVM (used within Python's scikit-learn)
- Both of these handle multi-class, weighted SVM for imbalanced data, etc.
- There are several new approaches to solving the SVM objective that can be much faster:
 - Stochastic subgradient method (up next!)
 - Distributed computation
- See <http://mloss.org>, “machine learning open source software”

PEGASOS

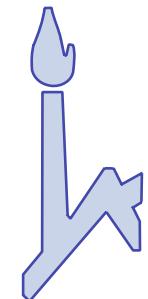
[ICML 2007]

Primal Efficient sub-GrAdient SOlver for SVM



Shai Shalev-Shwartz

The Hebrew University
Jerusalem, Israel



Yoram Singer

Google™

Nati Srebro



Support Vector Machines

QP form:

$$\begin{aligned} & \underset{\mathbf{w}, \xi_i \geq 0}{\operatorname{argmin}} \quad \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^m \xi_i \\ & \text{s.t. } \forall i, y_i \langle \mathbf{w}, \mathbf{x}_i \rangle \geq 1 - \xi_i \end{aligned}$$

More “natural” form:

$$\underset{\mathbf{w}}{\operatorname{argmin}} f(\mathbf{w}) \quad \text{where:}$$

$$f(\mathbf{w}) \stackrel{\text{def}}{=} \frac{\lambda}{2} \|\mathbf{w}\|^2 + \frac{1}{m} \sum_{i=1}^m \max\{0, 1 - y_i \langle \mathbf{w}, \mathbf{x}_i \rangle\}$$

Regularization
term

Empirical loss

PFGASOS

$A_t = S$

Subgradient method

$|A_t| = 1$

Stochastic gradient

Number of iterations T

INITIALIZE. Choose \mathbf{w}_1 s.t. $\|\mathbf{w}_1\| \leq 1/\sqrt{\lambda}$

FOR $t = 1, 2, \dots, T$

Subgradient {

- Choose $A_t \subseteq S$
- $A_t^+ = \{(\mathbf{x}, y) \in A_t : y \langle \mathbf{w}_t, \mathbf{x} \rangle < 1\}$
- $\nabla_t = \lambda \mathbf{w}_t - \frac{1}{|A_t|} \sum_{(\mathbf{x}, y) \in A_t^+} y \mathbf{x}$
- $\eta_t = \frac{1}{t \lambda}$
- $\mathbf{w}'_t = \mathbf{w}_t - \eta_t \nabla_t$

Projection $\Leftarrow \mathbf{w}_{t+1} = \min \left\{ 1, \frac{1/\sqrt{\lambda}}{\|\mathbf{w}'_t\|} \right\} \mathbf{w}'_t$

OUTPUT: \mathbf{w}_{T+1}

Run-Time of Pegasos

- Choosing $|A_t|=1$
→ Run-time required for Pegasos to find ϵ accurate solution w.p. $\geq 1-\delta$

$$\tilde{O} \left(\frac{n}{\delta \lambda \epsilon} \right)$$

- Run-time does not depend on #examples
- Depends on “difficulty” of problem (λ and ϵ)

Experiments

- **3 datasets** (provided by Joachims)
 - Reuters CCAT (800K examples, 47k features)
 - Physics ArXiv (62k examples, 100k features)
 - Covertype (581k examples, 54 features)

	Pegasos	SVM-Perf	SVM-Light
Training Time (in seconds):			
Reuters	2	77	20,075
Covertype	6	85	25,514
Astro-Physics	2	5	80

What's Next!

- Learn one of the most interesting and exciting recent advancements in machine learning
 - The “kernel trick”
 - High dimensional feature spaces at no extra cost!
- But first, a detour
 - Constrained optimization!