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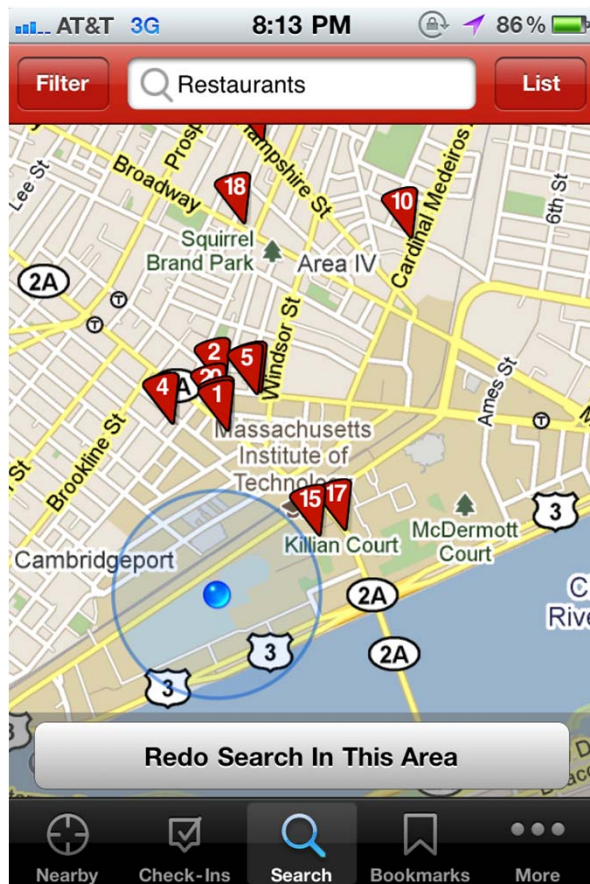
Implications of Device Diversity for Organic Localization

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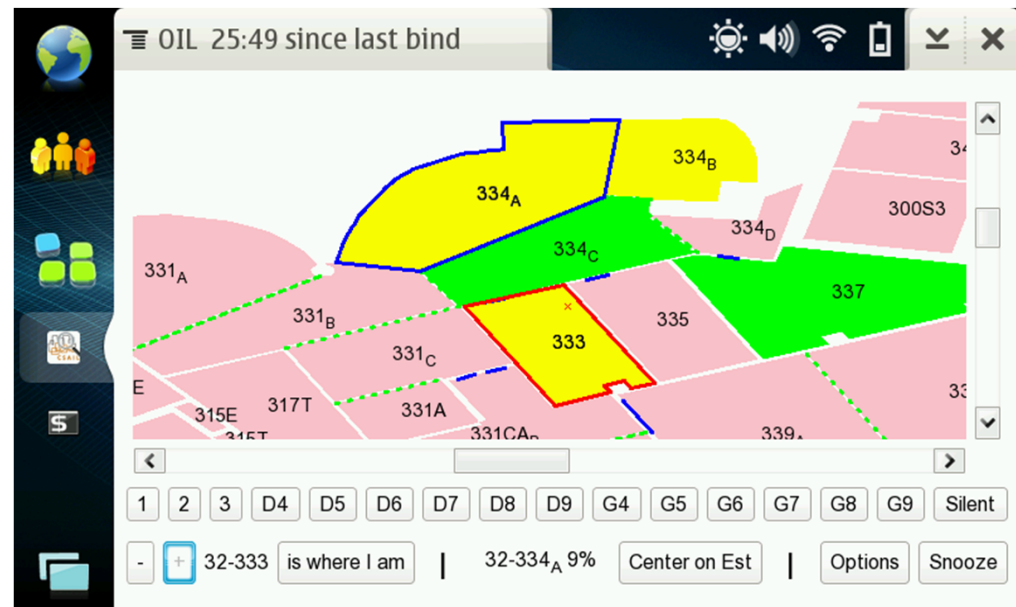
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Motivation: Location Determination for Mobile Applications



yelp (www.yelp.com)



Teller et al., "Organic Indoor Location Discovery", 2008

Wi-Fi Localization

- Objective: Learn a map $f : S \rightarrow P$ from signal space S to physical space P
 - Signal features: signal strength (RSSI)/detection/... for each wireless access point (WAP)
 - Physical location: (x,y) coordinates/location labels
- Employ a learning algorithm with training (calibration) examples $\{(s_i, p_i)\}$ “fingerprint”
- Limiting assumptions
 - Need training data for each location
 - Localization samples are drawn from the same distribution as the training samples

Organic Localization*

- Pros
 - Mitigates the need for training data by crowdsourcing
 - The system facilitates sharing fingerprints among users
- Challenge
 - Device diversity due to multiple producers/consumers
 - Different antennas, chipsets, drivers, OS's

* Teller et al, Organic Indoor Location Discovery, MIT-CSAIL-TR, 2008

* Park et al, Growing an Organic Indoor Location System, MobiSys, 2010

Overview

We present an experimental analysis and design considerations for organic localization with heterogeneous devices

- Heterogeneous WiFi Signal Strength Characteristics
- Feature Design of Localization Algorithms for Heterogeneous Devices

Data Collection

- 6 different devices including 5 distinct models
- Data collected at 18 locations in a building
- Data available at <http://rvsn.csail.mit.edu/location>

Device	WiFi Chipset	OS	Kernel
Clevo D901C laptop	Intel 5300AGN (802.11a/b/g/n)	Linux Ubuntu 10.04	Linux 2.6.32
Asus EEE900A netbook	Atheros AR5001 (802.11b/g)	Linux Ubuntu 10.04	Linux 2.6.32
Lenovo Thinkpad X61 laptop	Intel 4965AGN (802.11a/b/g/n)	Linux Ubuntu 10.04	Linux 2.6.32
Nokia N810 tablet (x2)	Conexant CX3110X (802.11b/g)	Maemo OS2008	Linux 2.6.21
Nokia N95 cellphone	TI OMAP2420 (802.11b/g)	Symbian S60 FP1	EKA2

Algorithm (Signal-Strength-Based)

- Bayes classifier

$$p_{L|O}(l|o) = \frac{p_{O|L}(o|l) p_L(l)}{p_O(o)} \quad \begin{array}{l} L : \text{Location} \\ O : \text{Signal observation} \end{array}$$

$$\hat{l} = l_{MAP} = \operatorname{argmax}_{l \in L} [p_{O|L}(o|l)]$$

- Signal-strength feature, independence between APs

$$\hat{l} = \operatorname{argmax}_{l \in L} \left[\prod_{i \in M} p_{S_i|L}(s_i|l) \right] \quad \begin{array}{l} S_i : \text{Signal strength} \\ \text{from AP } i \end{array}$$

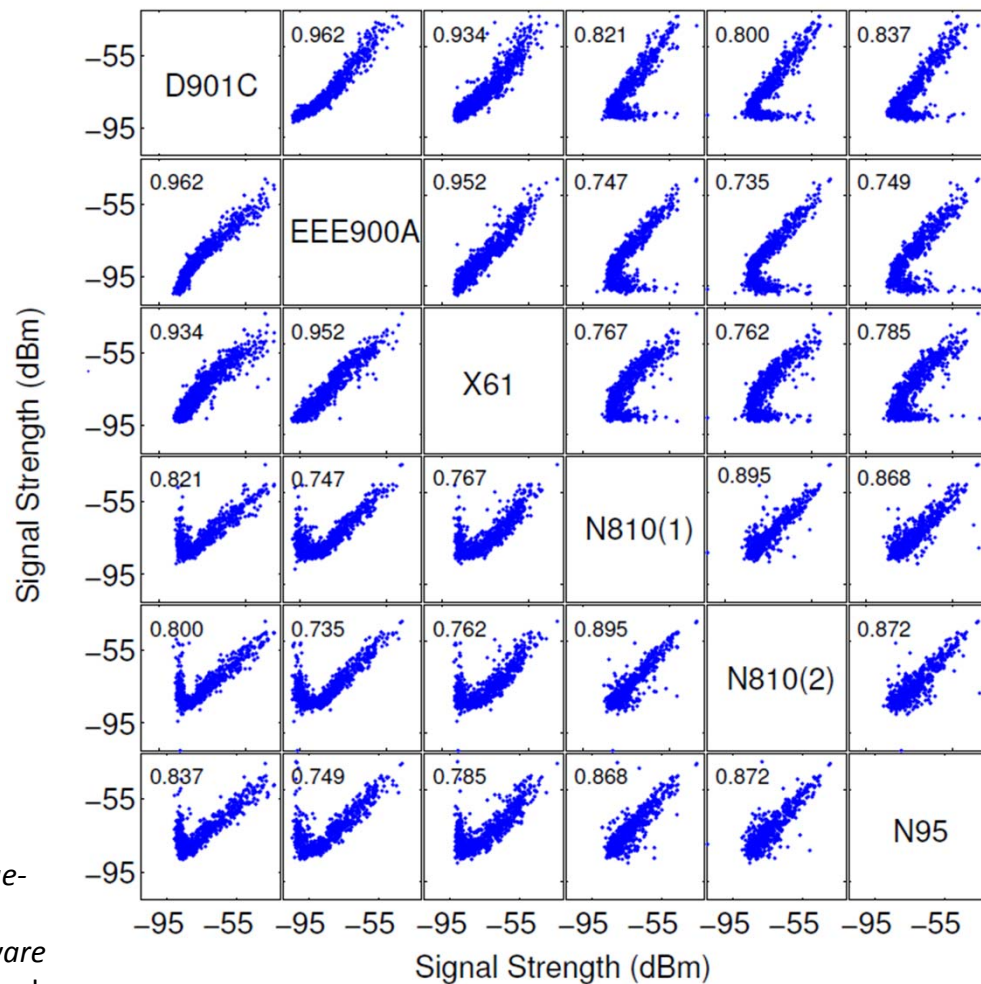
- Training: learning $p_{S_i|L}$ for each WAP i , Location l

Cross-Device Positioning with Signal Strength Features

- Training data from device A
 - $p_{S_i|L}$ was estimated with data from device A
- Localization on device B
 - $p_{S_i|L}$ is different for data from device B
 - Prediction performance degrades

Linear Transformation for Calibration?

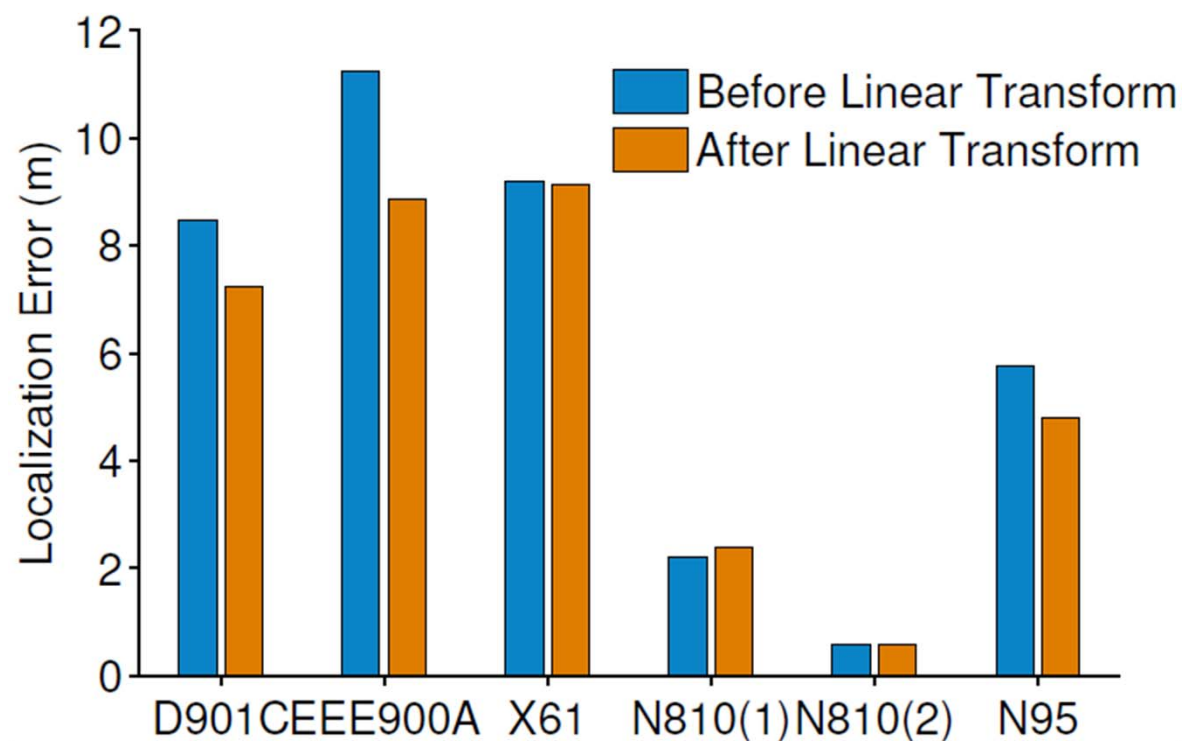
- Scatterplot matrix of signal strengths from different devices
- High linear correlations exist
- Previous work* suggested linear transformation would be sufficient



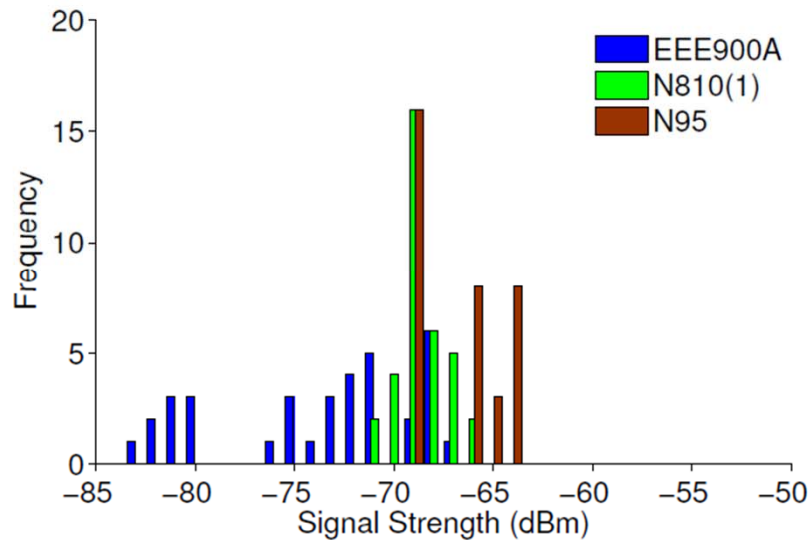
* Haeberlen et al., *Practical Robust Localization over Large-Scale 802.11 Wireless Networks*, MobiCom, 2004,
Tsui et al., *Unsupervised Learning for Solving RSS Hardware Variance Problem in WiFi Localization*, Mobile Networks and Applications, 2009

Linear Transformation for Calibration?

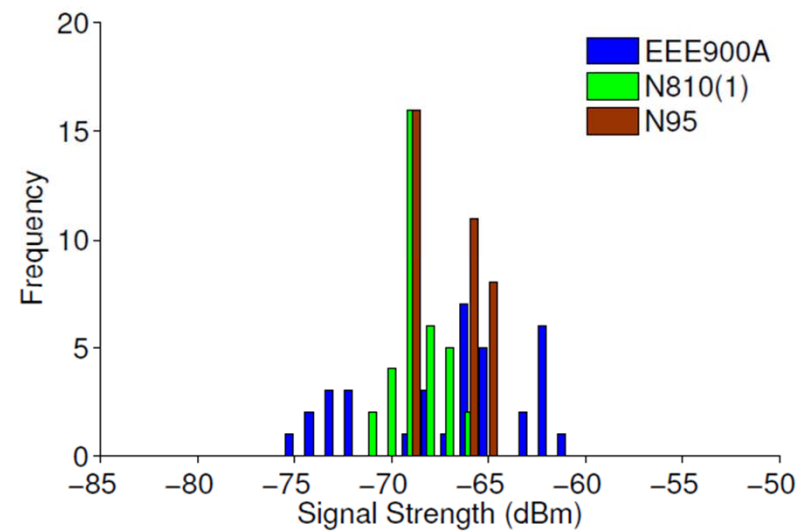
- Linear transformation alone does not solve the problem
- When N810(2) is used for training:



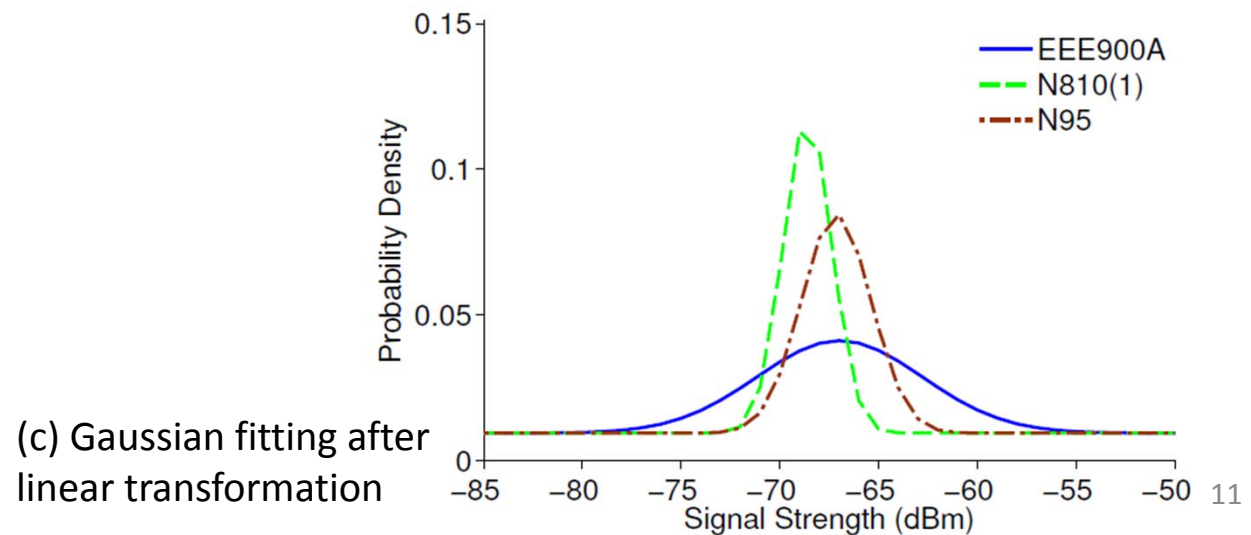
Linear Transformation for Calibration?



(a) Histograms before linear transformation



(b) After linear transformation



(c) Gaussian fitting after linear transformation

“Smoothing” by Kernel Density Estimation

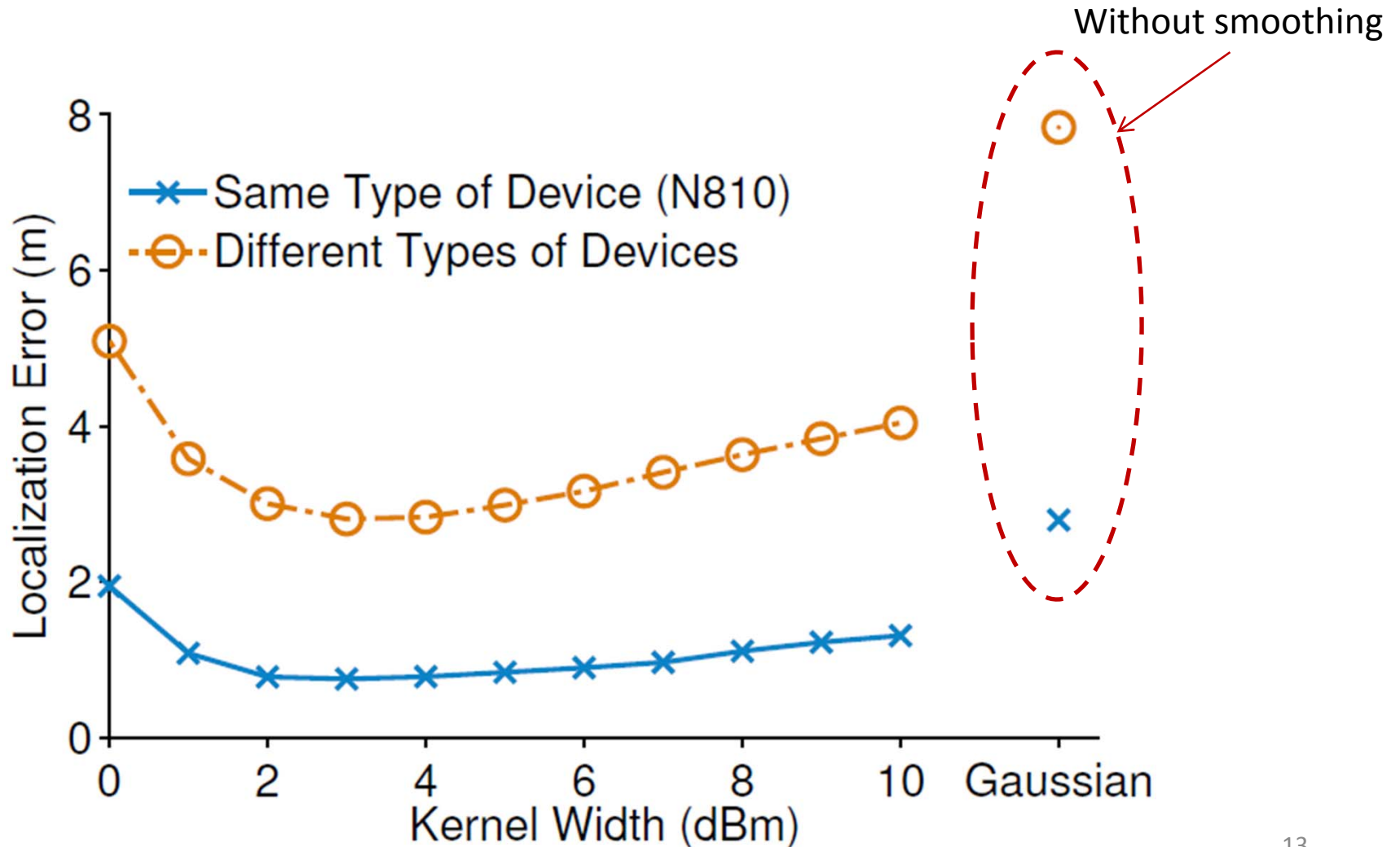
- We need to take into account the variation in individual samples from different devices
- Kernel density estimator

$$\hat{p}_X^k(x) = \frac{1}{nh} \sum_{i=1}^n K\left(\frac{x - x_i}{h}\right) \quad \begin{array}{l} K(x, x_i) : \text{kernel function} \\ h : \text{kernel width} \end{array}$$

- M-estimator on kernel density estimate

$$p_X(x) = \frac{N\hat{p}_X(x) + \Phi\bar{p}_X(x)}{N + \Phi}$$

Kernel Density Estimator Improves Cross-Device Localization



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To Use or Not To Use AP Detection Feature?

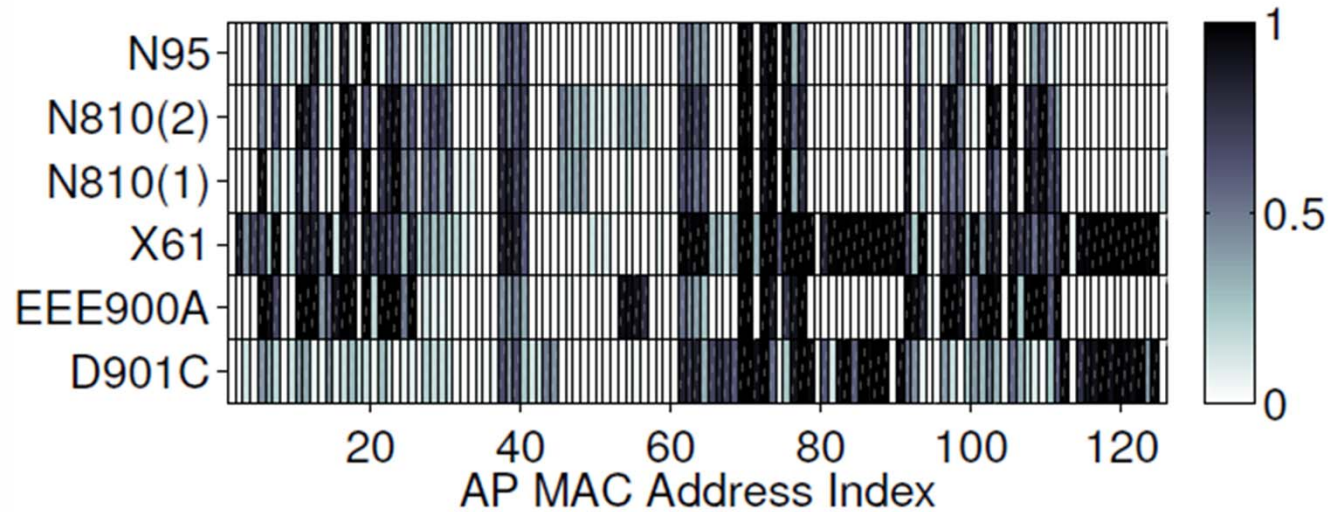
- $J_i = \begin{cases} 1 & \text{if } AP_i \text{ detected} \\ 0 & \text{otherwise} \end{cases}$
- Multivariate Bernoulli model ($J_i, 1 \leq i \leq k, k$ WAPs)

$$\hat{l} = \operatorname{argmax}_{l \in L} \left[\prod_{1 \leq i \leq k} \{p_{J_i|L}(1|l)\}^{J_i} \{1 - p_{J_i|L}(1|l)\}^{1-J_i} \right]$$

- Combine with signal strength (hybrid)

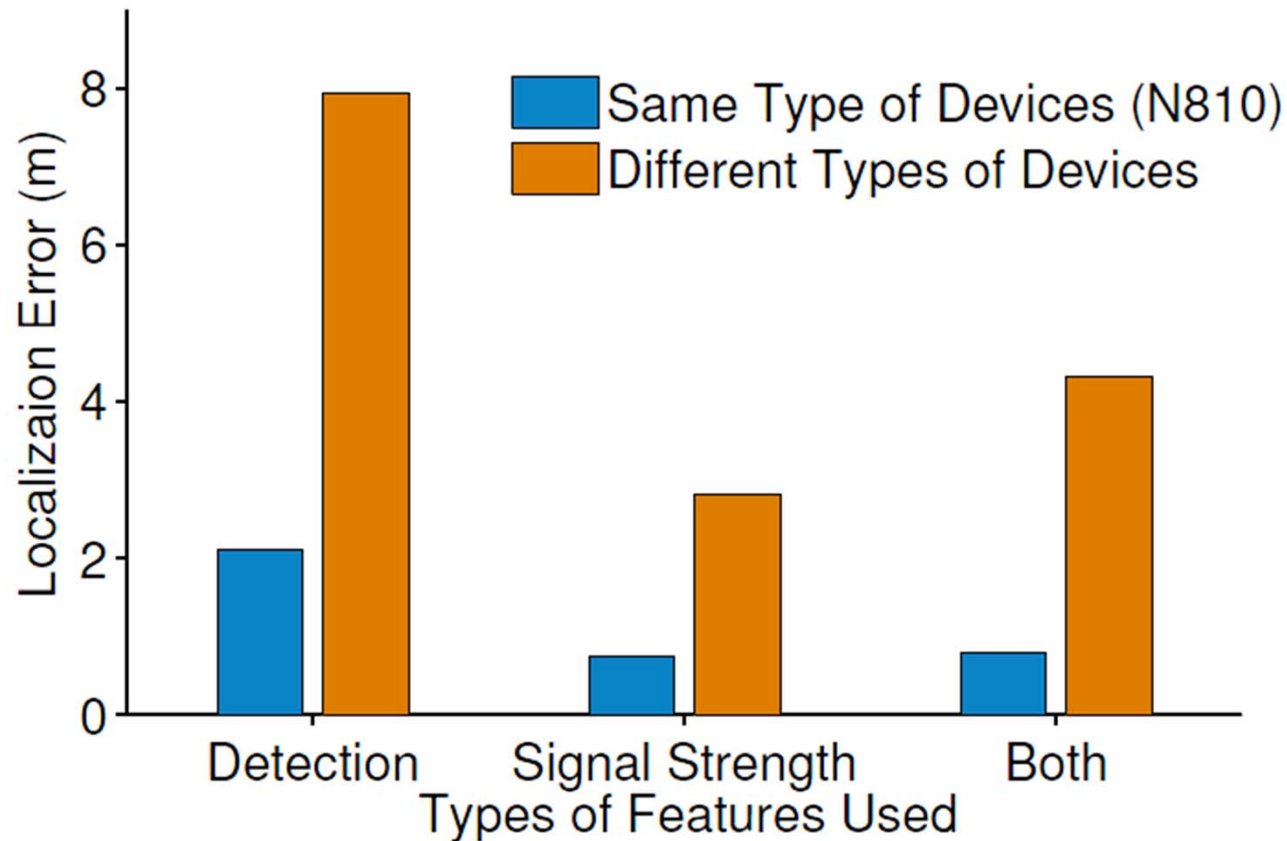
$$\hat{l} = \operatorname{argmax}_{l \in L} \left[\prod_{1 \leq i \leq k} \{p_{J_i|L}(1|l) p_{S_i|J_i,L}(s_i|1, l)\}^{J_i} \{1 - p_{J_i|L}(1|l)\}^{\alpha(1-J_i)} \right]$$

Detection Frequency Varies Across Devices



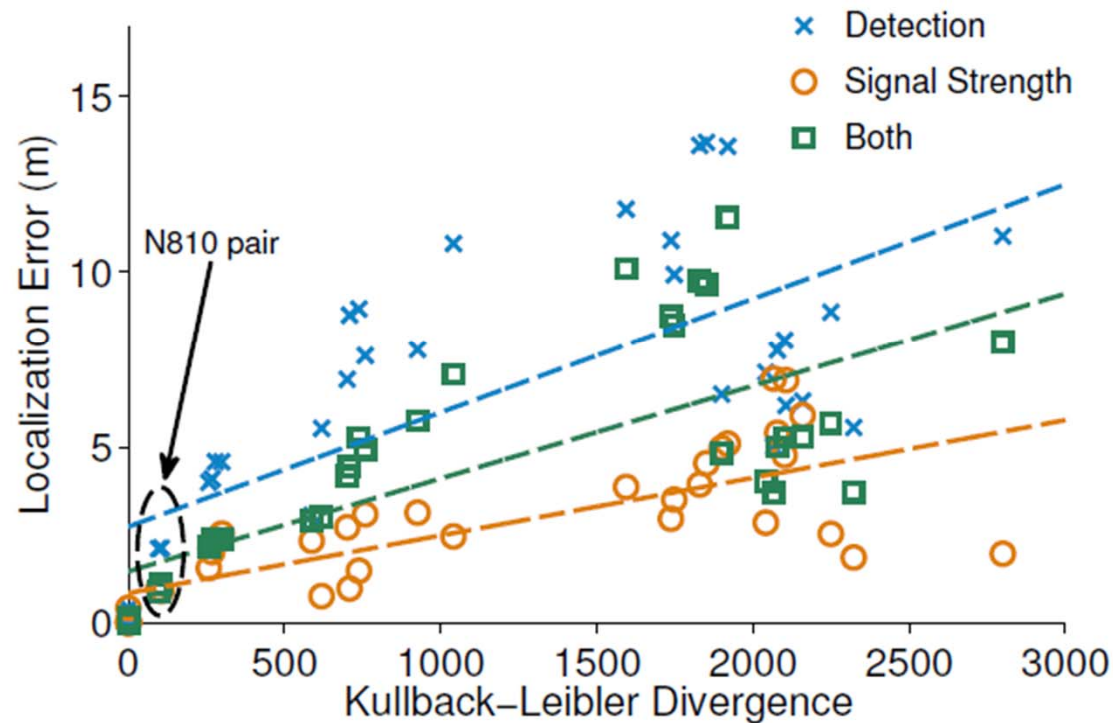
Localization Performance with Different Sets of Features

- Detection feature does not help cross-device localization



Empirical Characterization

- Quantified difference in AP detection by Kullback-Leibler divergence of detection rate probabilities J_i between different devices



Discussion

- Detection frequency feature does not give much extra information
- Detection frequency feature is largely incompatible across devices
- Signal-strength-only construction does not explicitly model detection process
- Other non-Bayesian algorithms (k-NN, SVM, ...) are also affected because missing entries need to be filled in

Concluding Remarks

- Localization algorithms for cross-device positioning need to account for different dispersions in signal strengths
 - Smoothing by kernel density estimation is an easy way to improve cross-device localization
- Localization algorithms should use only “transferrable” information across different devices
 - AP detection frequency feature may be harmful because it varies widely across different 802.11 devices.

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- Organic indoor localization
 - Teller et al., *Organic Indoor Location Discovery*, MIT-CSAIL-TR-2008-075, 2008
 - Park et al., *Growing an Organic Indoor Location System*, MobiSys 2010
 - Ledlie et al., *Molé: a Large-Scale, User-Generated Positioning Engine*, IPIN 2011, submitted
 - <http://rvsn.csail.mit.edu/location>

Detection Frequency Varies Across Devices

