

Discovery of Intrinsic Primitives on Triangle Meshes

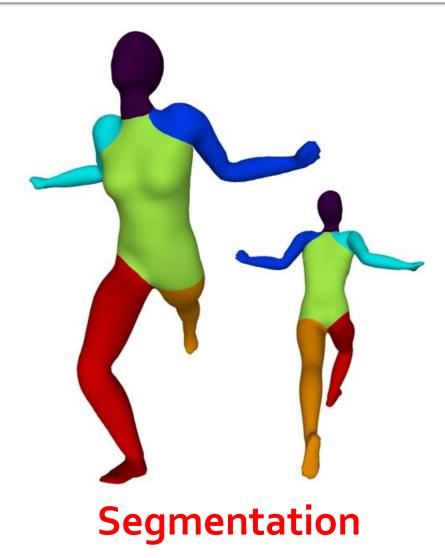


Justin Solomon, Mirela Ben-Chen, Adrian Butscher, and Leo Guibas

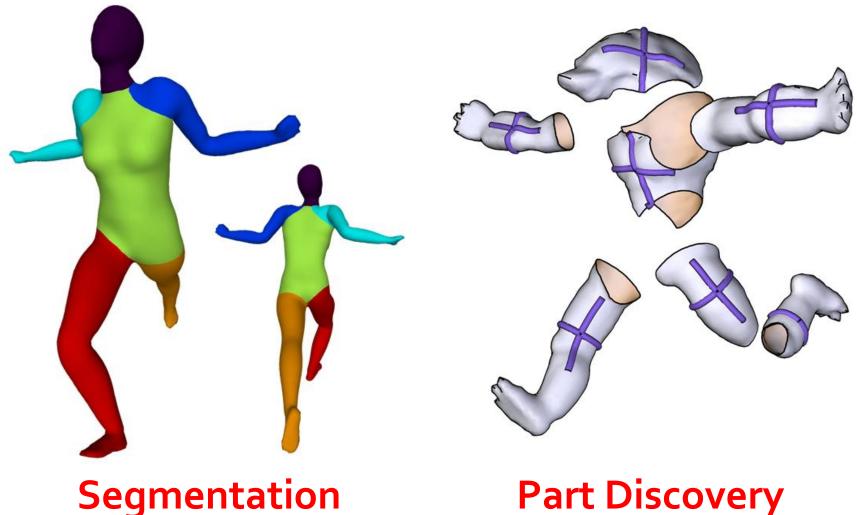
Stanford University



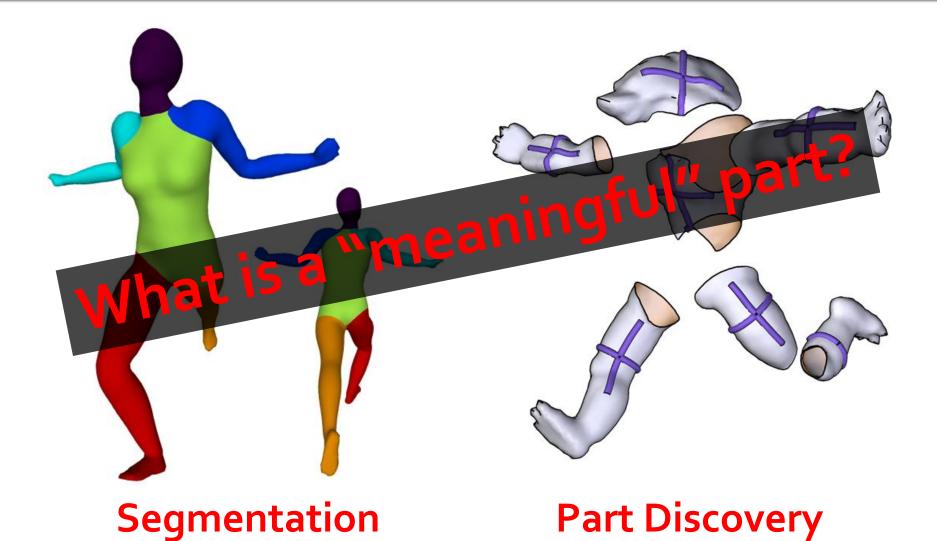
Two Related Problems



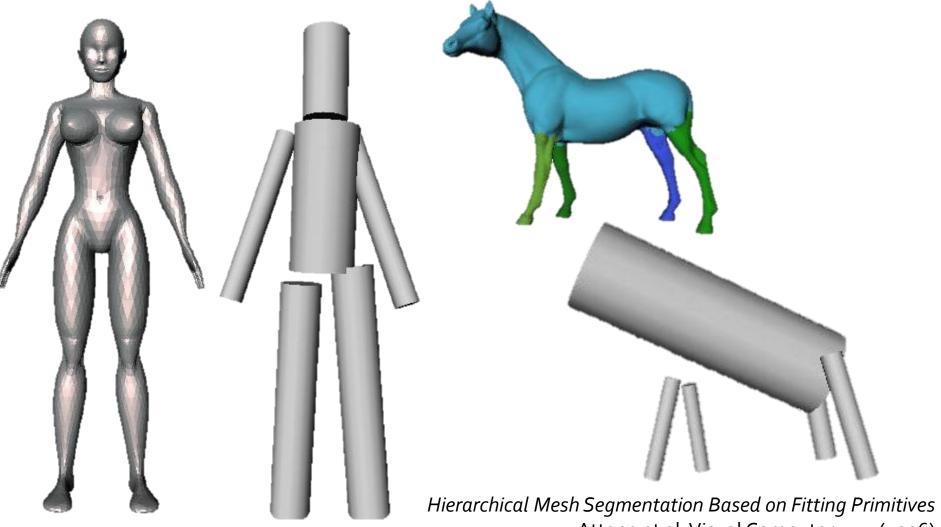
Two Related Problems



Two Related Problems

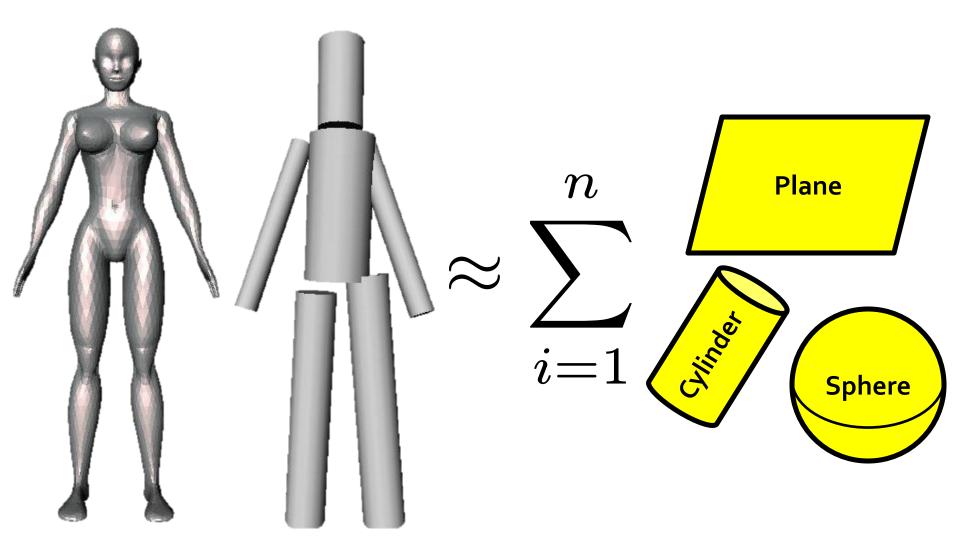


"Meaningful" Parts?

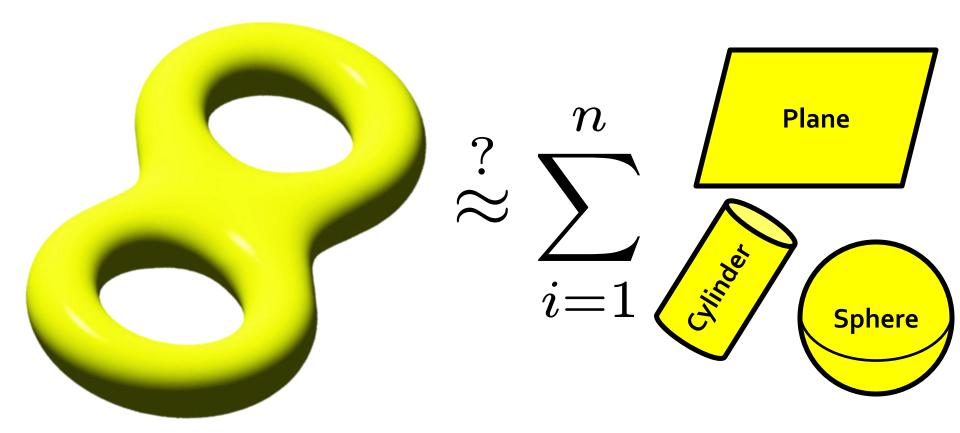


Attene et al, Visual Computer 22.3 (2006)

"Meaningful" Parts?

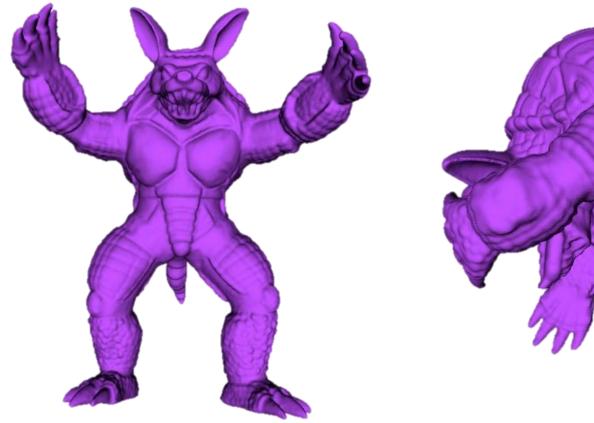


Problem



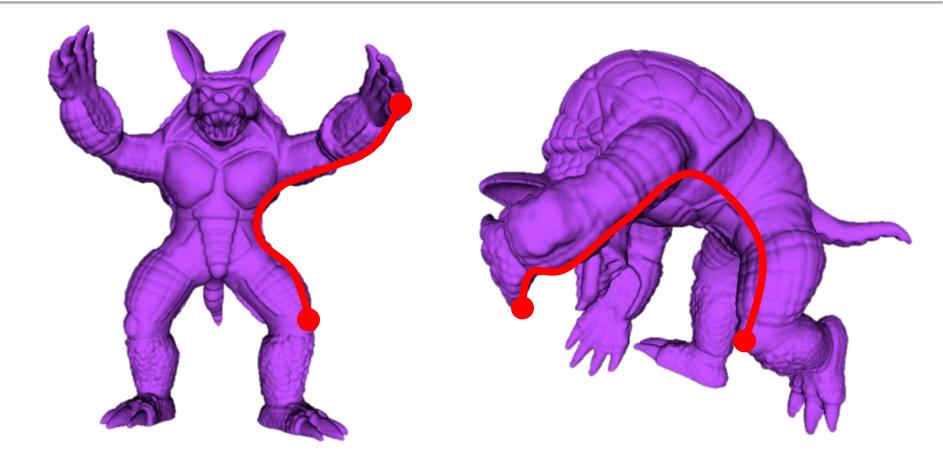
How do you choose?

Idea: Let Parts Bend





Isometric Deformation



Preserves Pairwise Distances

Near-Isometric Deformation

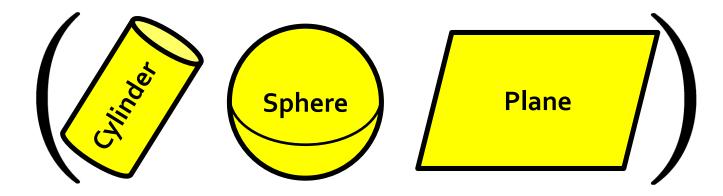




Segmentation and part-finding invariant to near-isometry



Segmentation and part-finding invariant to near-isometry



Approach

Find symmetries using approximate Killing vector fields

Compute and cluster isometry-invariant point signatures



Killing Vector Fields

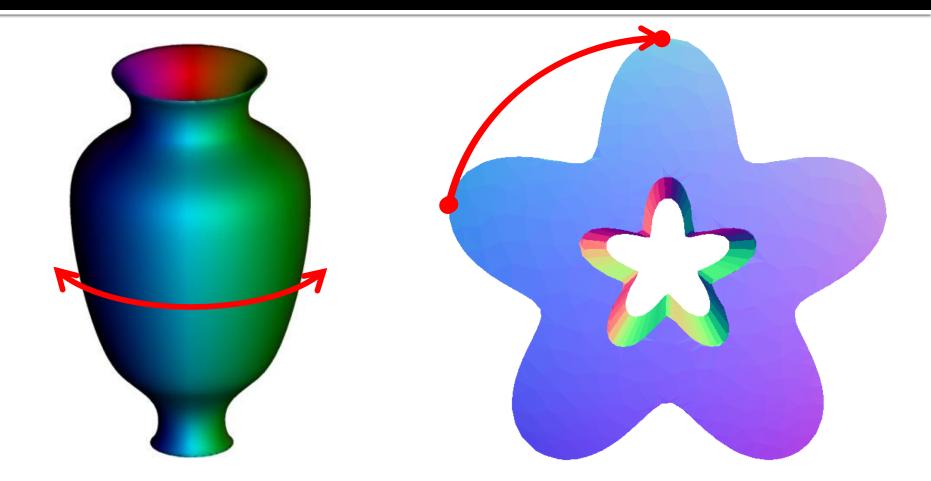


Killing Vector Fields



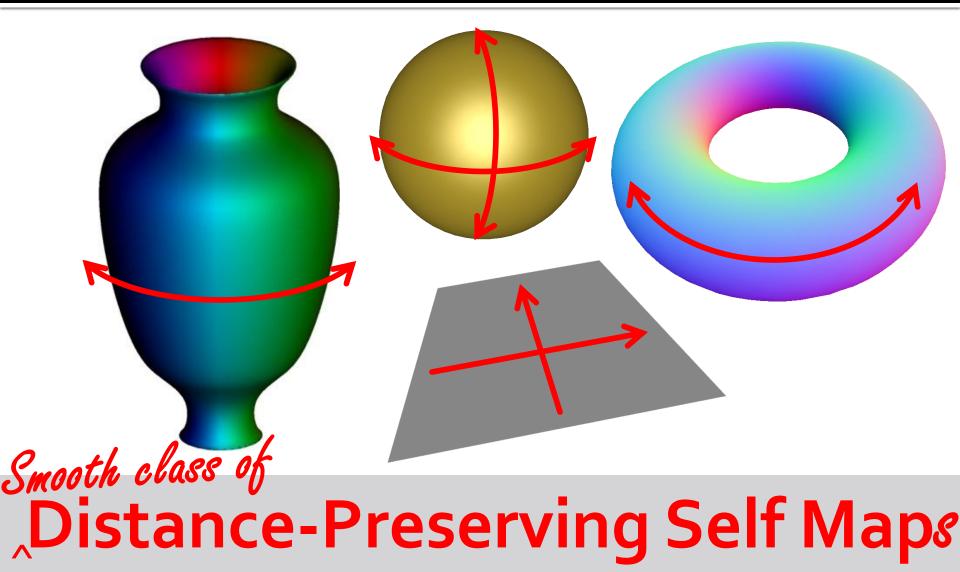
Wilhelm Killing 1847-1923

Self-Isometry



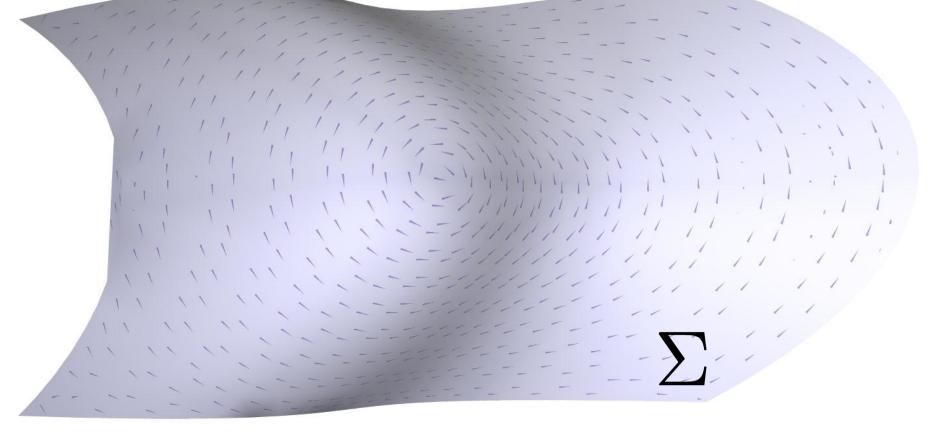
Distance-Preserving Self Map

Continuous Self-Isometry

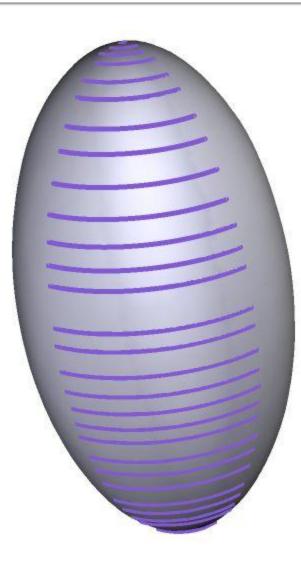


Tangent Vector Field



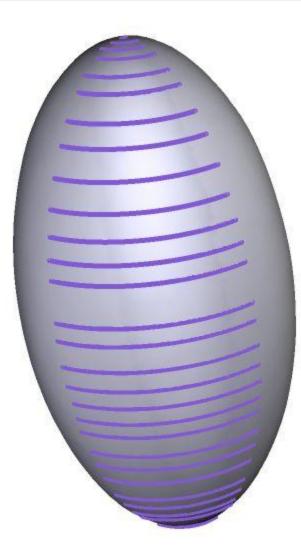


Killing Vector Fields (KVFs)



Continuous self-isometry $\phi_t: \Sigma \to \Sigma$

Killing Vector Fields (KVFs)



Continuous self-isometry $\phi_t: \Sigma \to \Sigma$ Killing vector field $\frac{d\phi_t}{dt}: \Sigma \to T\Sigma$

Discrete Approximate KVFs

Eurographics Symposium on Geometry Processing 2010 Olga Sorkine and Bruno Lévy (Guest Editors) Volume 29 (2010), Number 5

On Discrete Killing Vector Fields and Patterns on Surfaces

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Adrian Butscher Justin Solomon

Leonidas Guibas

Stanford University

Abstract

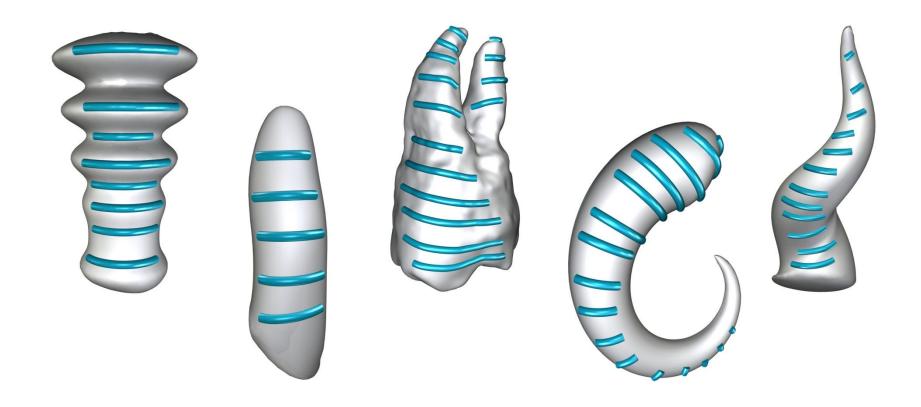
Symmetry is one of the most important properties of a shape, unifying form and function. It encodes semantic information on one hand, and affects the shape's aesthetic value on the other. Symmetry comes in many flavors, amongst the most interesting being intrinsic symmetry, which is defined only in terms of the intrinsic geometry of the shape. Continuous intrinsic symmetries can be represented using infinitesimal rigid transformations, which are given as tangent vector fields on the surface – known as Killing Vector Fields. As exact symmetries are quite rare, especially when considering noisy sampled surfaces, we propose a method for relaxing the exact symmetry constraint to allow

AKVFs: Main Idea

Vector field: $\omega \in \mathbb{R}^E$ Operator (matrix) K measuring deviation from isometry

Want to minimize $||K\omega||^2$ subject to $||\omega|| = 1$ \updownarrow Find eigenvectors ("eigenfields") of K

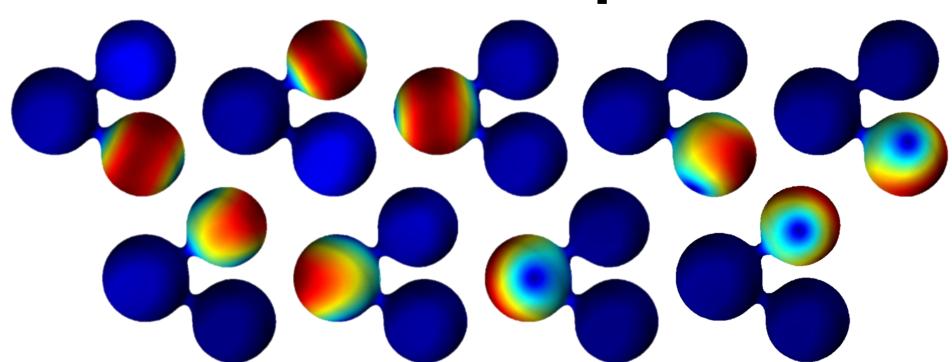
AKVF Examples



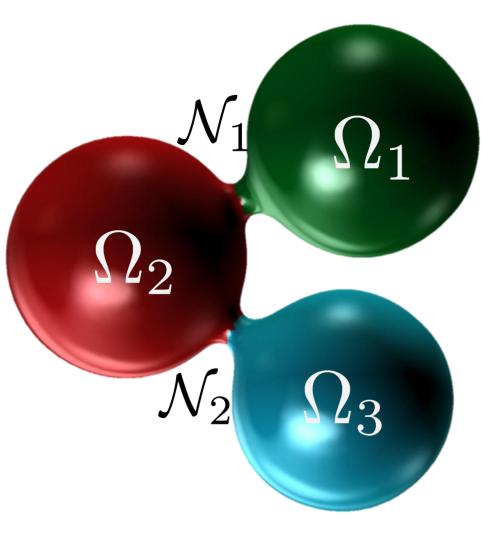




Eigenfields of *K* are localized on parts!



Composite Shape



- $_{i}$ = component i- $_{i} \subseteq$ surface Σ_{i} \mathcal{N}_{i} = neck i

Proposition 1. There exist constants $\varepsilon_0, C > 0$ depending only on the eigenvalues of Σ_1 , Σ_2 and a number $M(\varepsilon)$ with $\lim_{\varepsilon \to 0} M(\varepsilon) = \infty$ so that the spectral data of P^*P satisfies: 1. If $\varepsilon < \varepsilon_0$ then for all $n \text{ s.t. } \lambda_n < M(\varepsilon)$ we have

$$|\lambda_n - \mu_n| \leq C/|\log(\varepsilon)|.$$

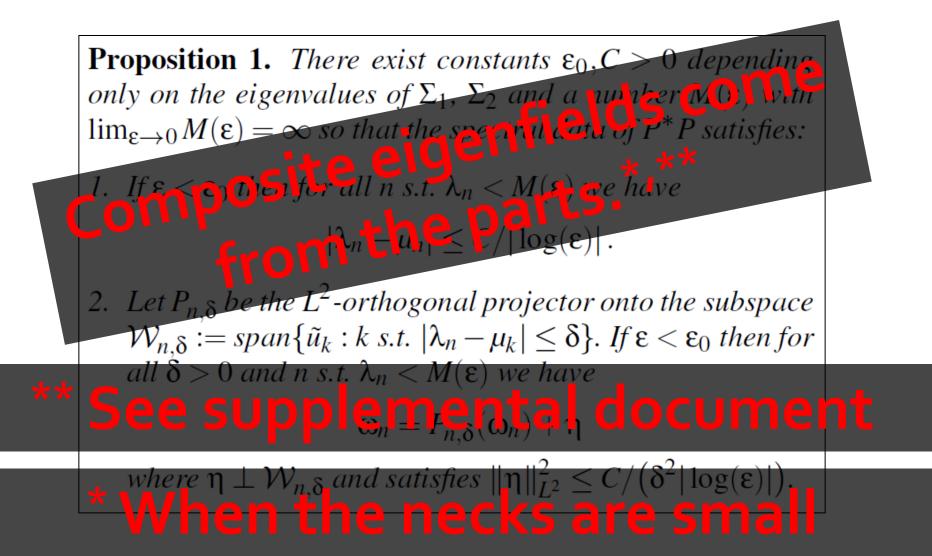
2. Let $P_{n,\delta}$ be the L^2 -orthogonal projector onto the subspace $\mathcal{W}_{n,\delta} := span\{\tilde{u}_k : k \ s.t. \ |\lambda_n - \mu_k| \le \delta\}$. If $\varepsilon < \varepsilon_0$ then for all $\delta > 0$ and $n \ s.t. \ \lambda_n < M(\varepsilon)$ we have

 $\omega_n = P_{n,\delta}(\omega_n) + \eta$

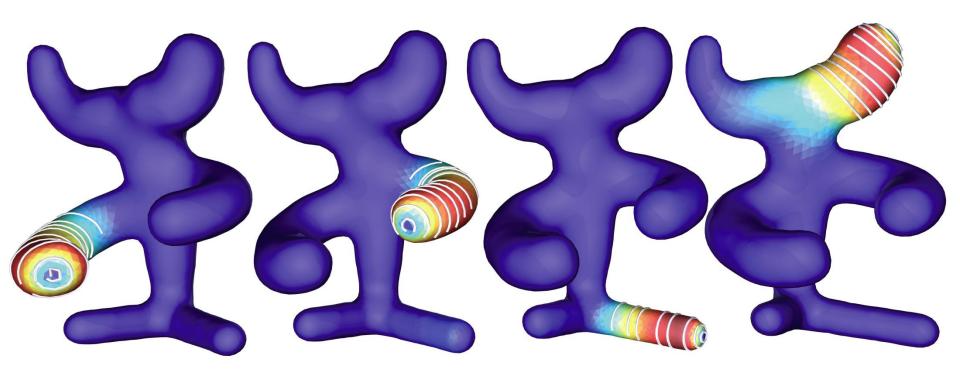
where $\eta \perp W_{n,\delta}$ and satisfies $\|\eta\|_{L^2}^2 \leq C/(\delta^2 |\log(\varepsilon)|)$.

Proposition 1. There exist constants ε_0 , C > 0 depending only on the eigenvalues of Σ_1 , Σ_2 and a number M(0) with $\lim_{\epsilon \to 0} M(\epsilon) = \infty$ so that the spectral value of P^*P satisfies: $If \varepsilon < OUS for all n s.t. \lambda$ rom < M(s) me SureDomesine (c) me Surelog(c)2. Let $P_{n,\delta}$ be the L^2 -orthogonal projector onto the subspace $\mathcal{W}_{n,\delta} := span\{\tilde{u}_k : k \text{ s.t. } |\lambda_n - \mu_k| \leq \delta\}.$ If $\varepsilon < \varepsilon_0$ then for all $\delta > 0$ and *n* s.t. $\lambda_n < M(\varepsilon)$ we have $\omega_n = P_{n,\delta}(\omega_n) + \eta$ where $\eta \perp \mathcal{W}_{n,\delta}$ and satisfies $\|\eta\|_{L^2}^2 \leq C/(\delta^2 |\log(\varepsilon)|)$.

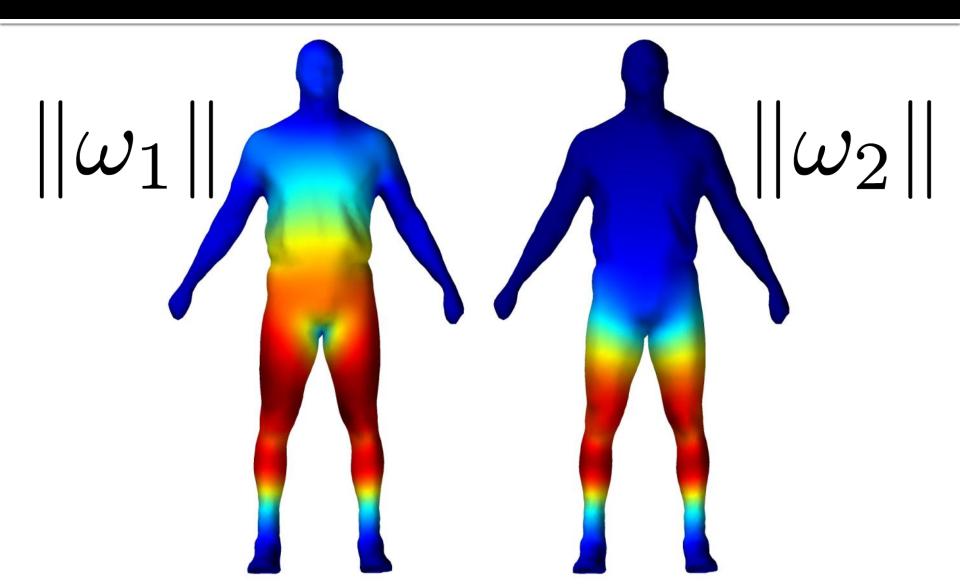
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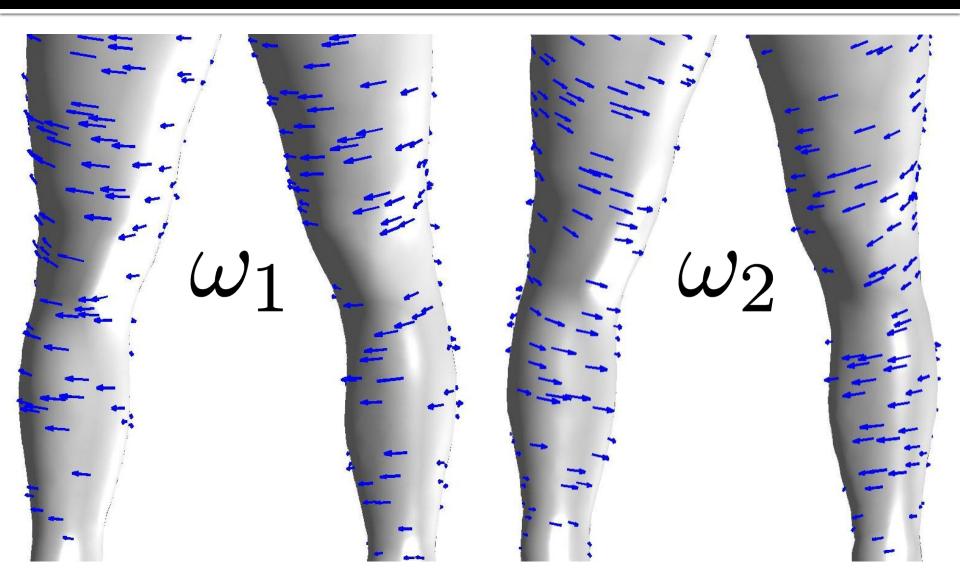
Larger Necks



Problem: Linear Combination



Problem: Linear Combination



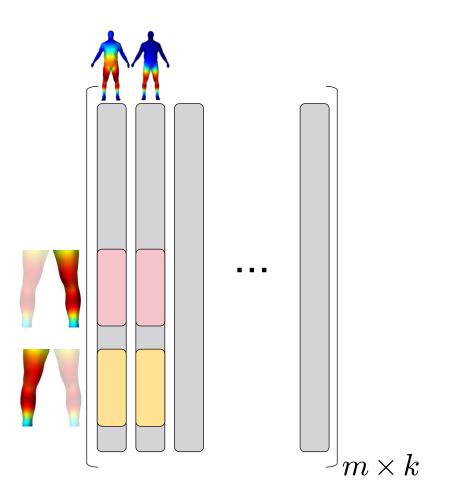
Problem: Linear Combination

 $\|\omega_1 - \omega_2\|$ $\|\omega_1 + \omega_2\|$

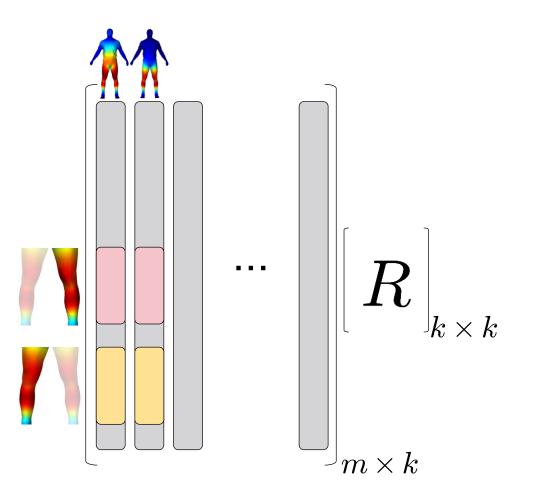
Tangling Energy

$$E(\omega_1, \omega_2) = \int_{\Sigma} \|\omega_1\|^2 \|\omega_2\|^2$$
$$\downarrow$$
$$E(\omega_1, \dots, \omega_N) = \sum_i \sum_{j>i} E(\omega_i, \omega_j)$$

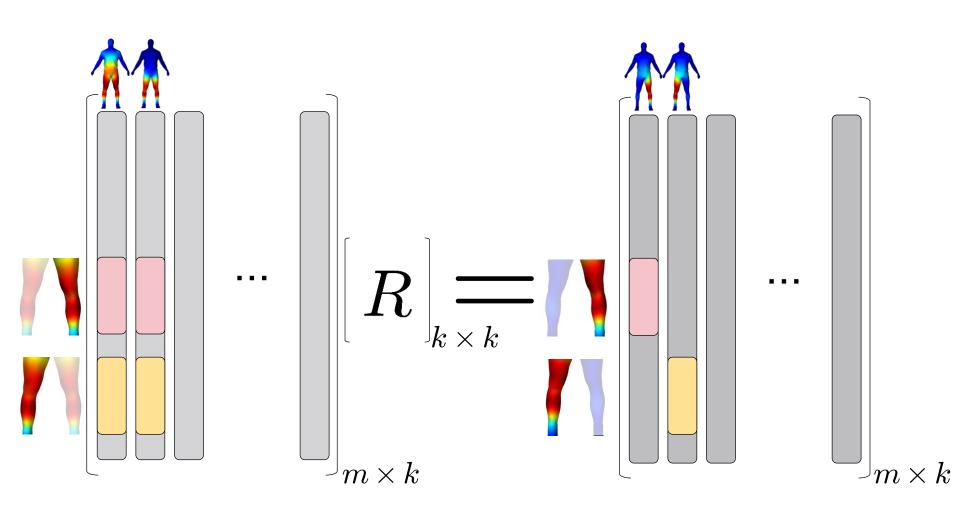
How to Untangle



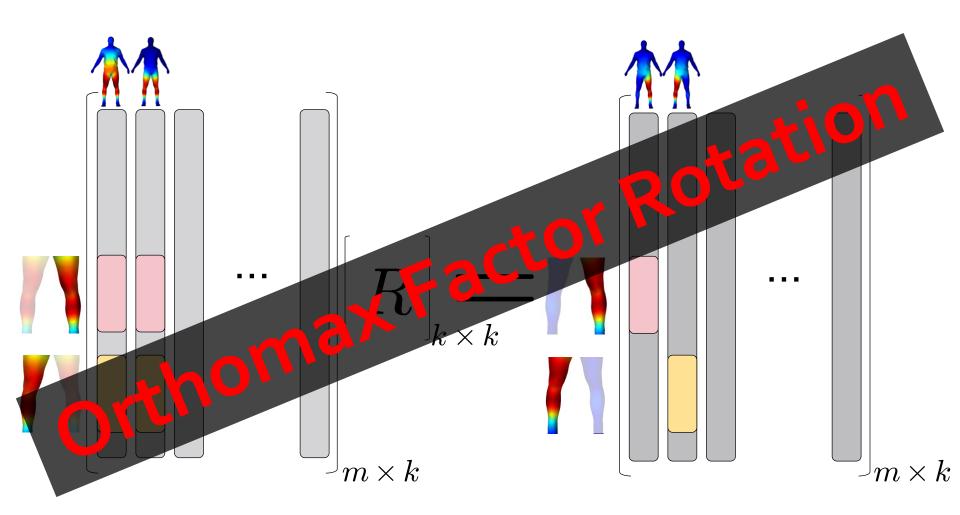
How to Untangle



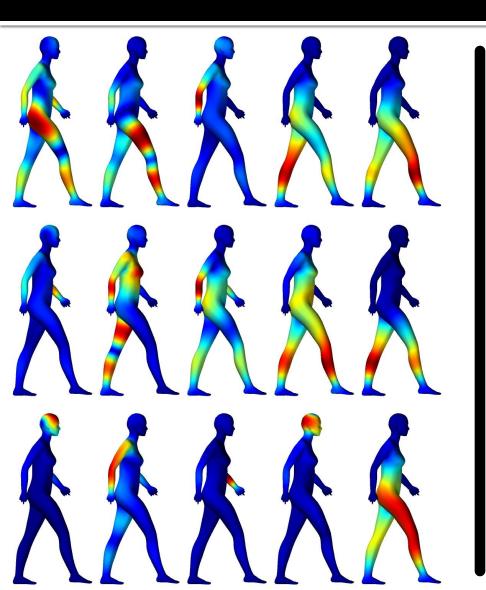
How to Untangle



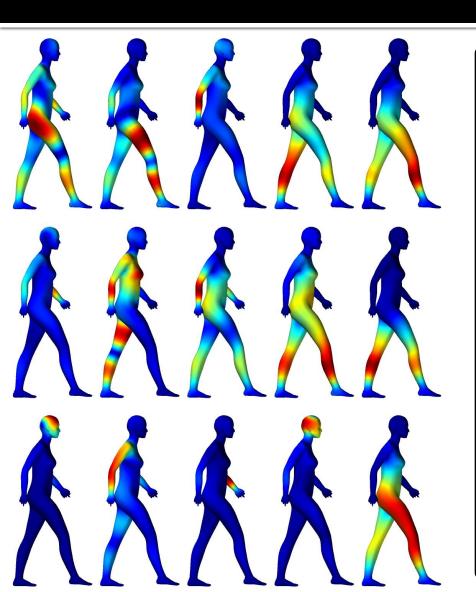
How to Untangle

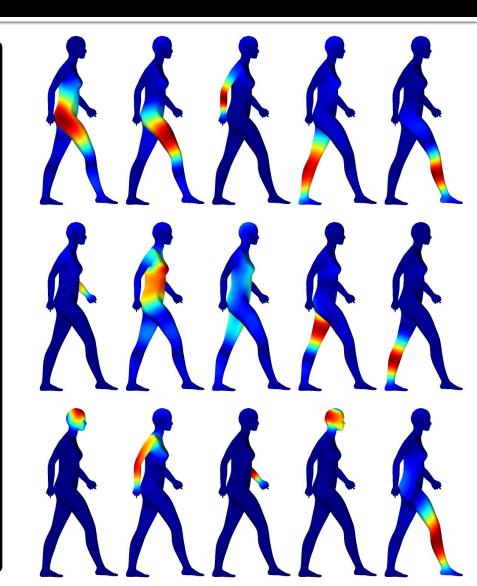


Untangling Example

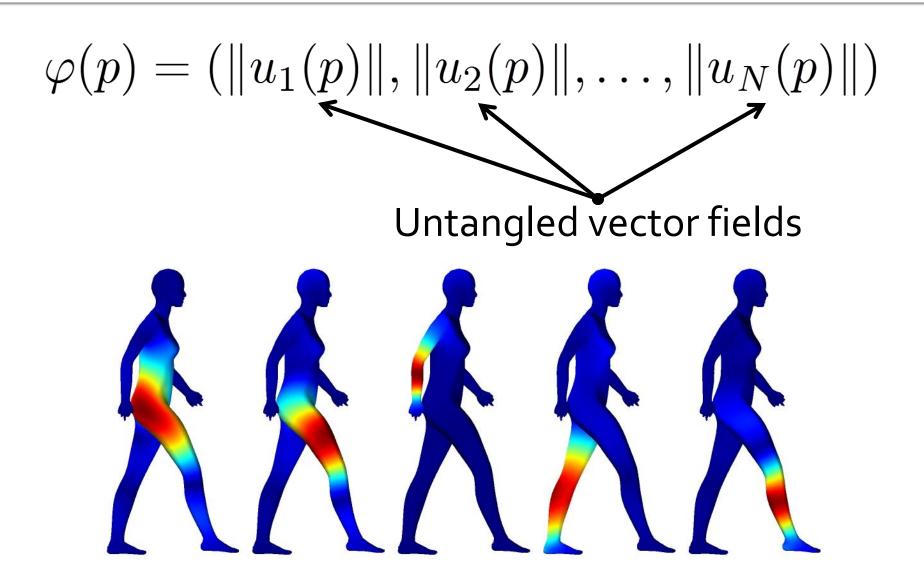


Untangling Example

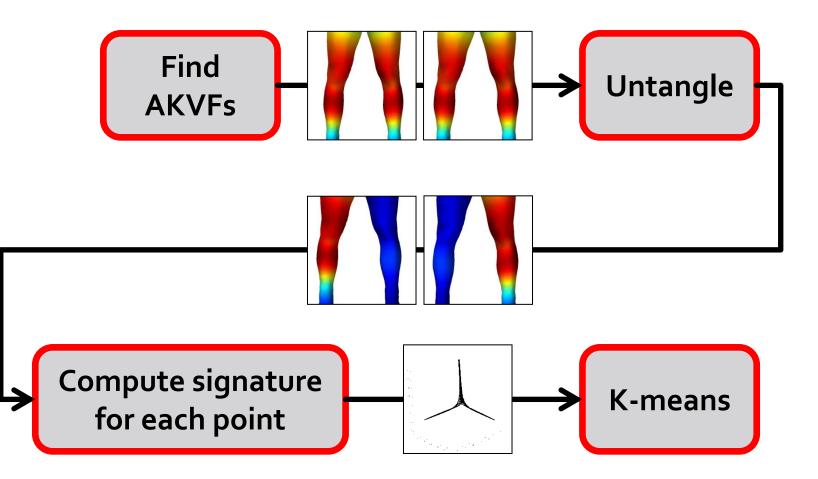




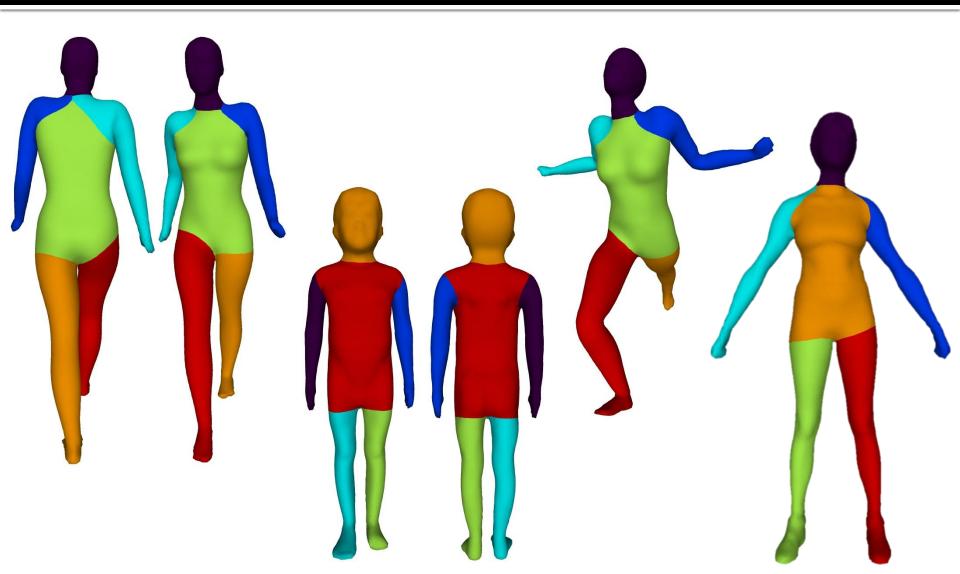
Signatures for Part Discovery



Segmentation Algorithm



Segmentation Results

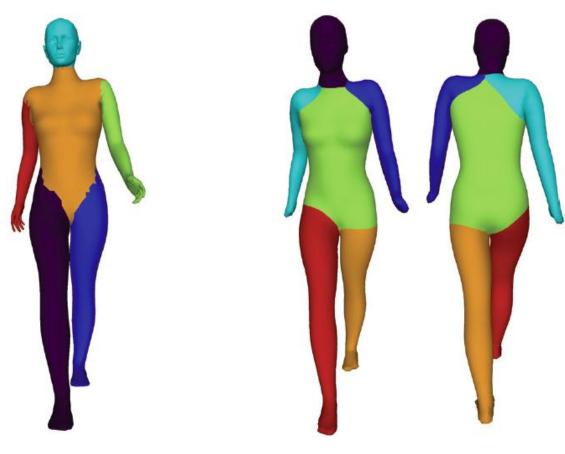


Segmentation Results



Comparison





Shape Diameter [Shapira et al. 2008] Randomized Cuts [Golovinskiy et al. 2008] **Intrinsic Primitives**

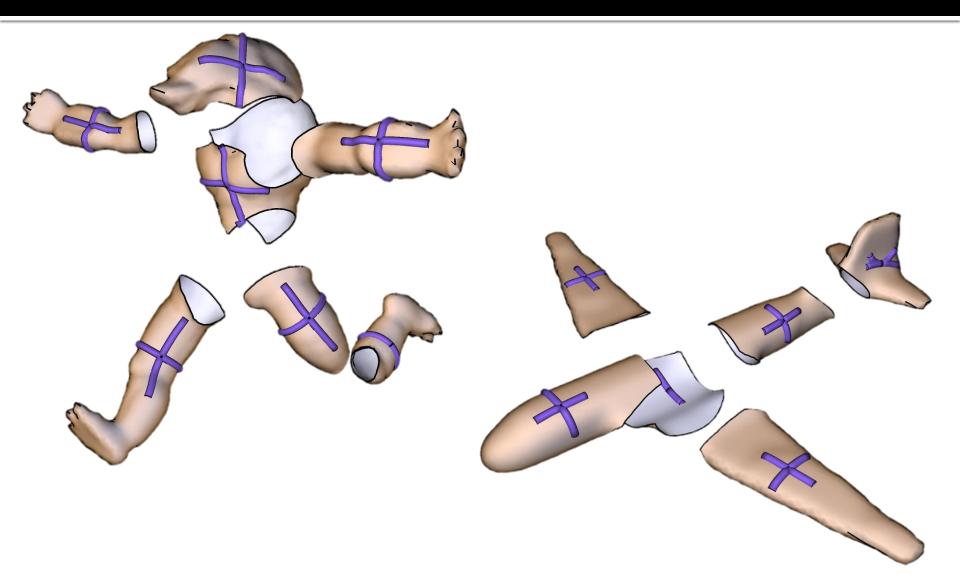
Comparison



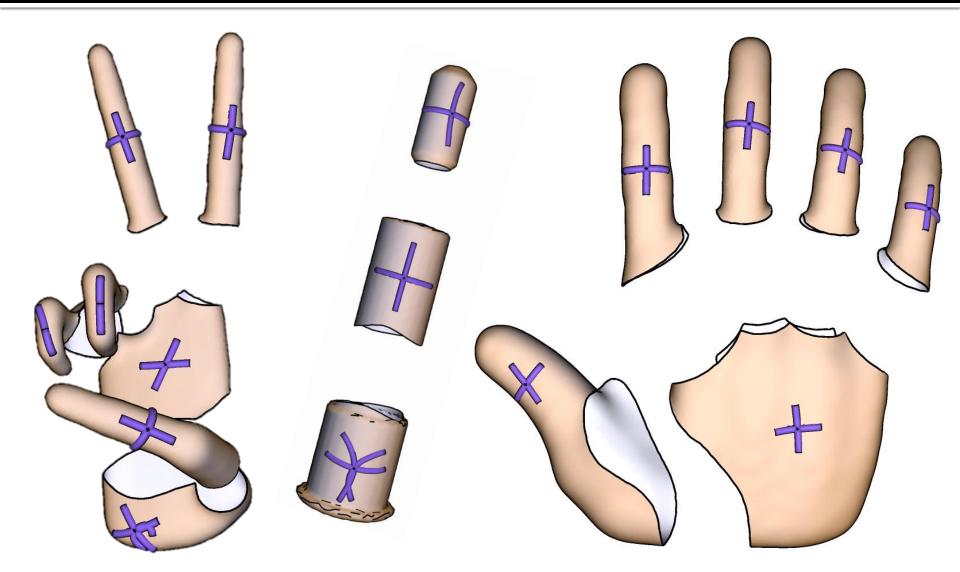
Shape Diameter [Shapira et al. 2008] Randomized Cuts [Golovinskiy et al. 2008]

Intrinsic Primitives

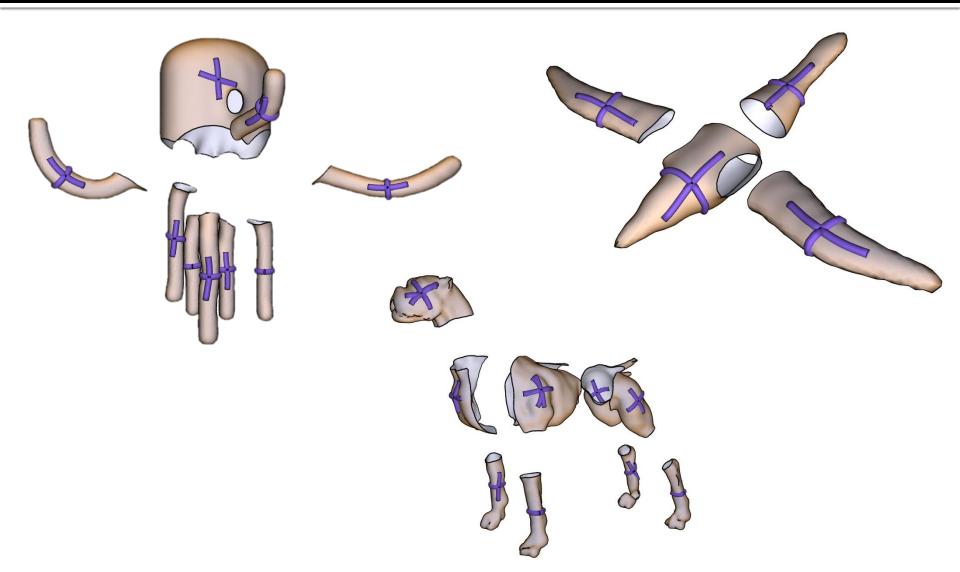
Part Discovery



Part Discovery



Part Discovery



Conclusions

- Segmentation into intrinsically symmetric parts
- KVFs of a composite come from KVFs of its parts

3. Untangle KVFs for better localization

Special Thanks





















Questions?