

Single Image Haze Removal Using Dark Channel Prior

Kaiming He

The Chinese University of Hong Kong

Jian Sun

Microsoft Research Asia

Xiaoou Tang

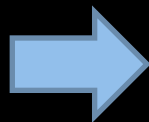
The Chinese University of Hong Kong

Hazy Images



- Low visibility
- Faint colors

Goals of Haze Removal



depth

- Scene restoration
- Depth estimation

Haze Imaging Model



Atmospheric light

$$\mathbf{I} = \mathbf{J} \cdot t + \mathbf{A} \cdot (1 - t)$$



Hazy image



Scene radiance



Transmission

Haze Imaging Model

$$\mathbf{I} = \mathbf{J} \cdot t + \mathbf{A} \cdot (1 - t)$$



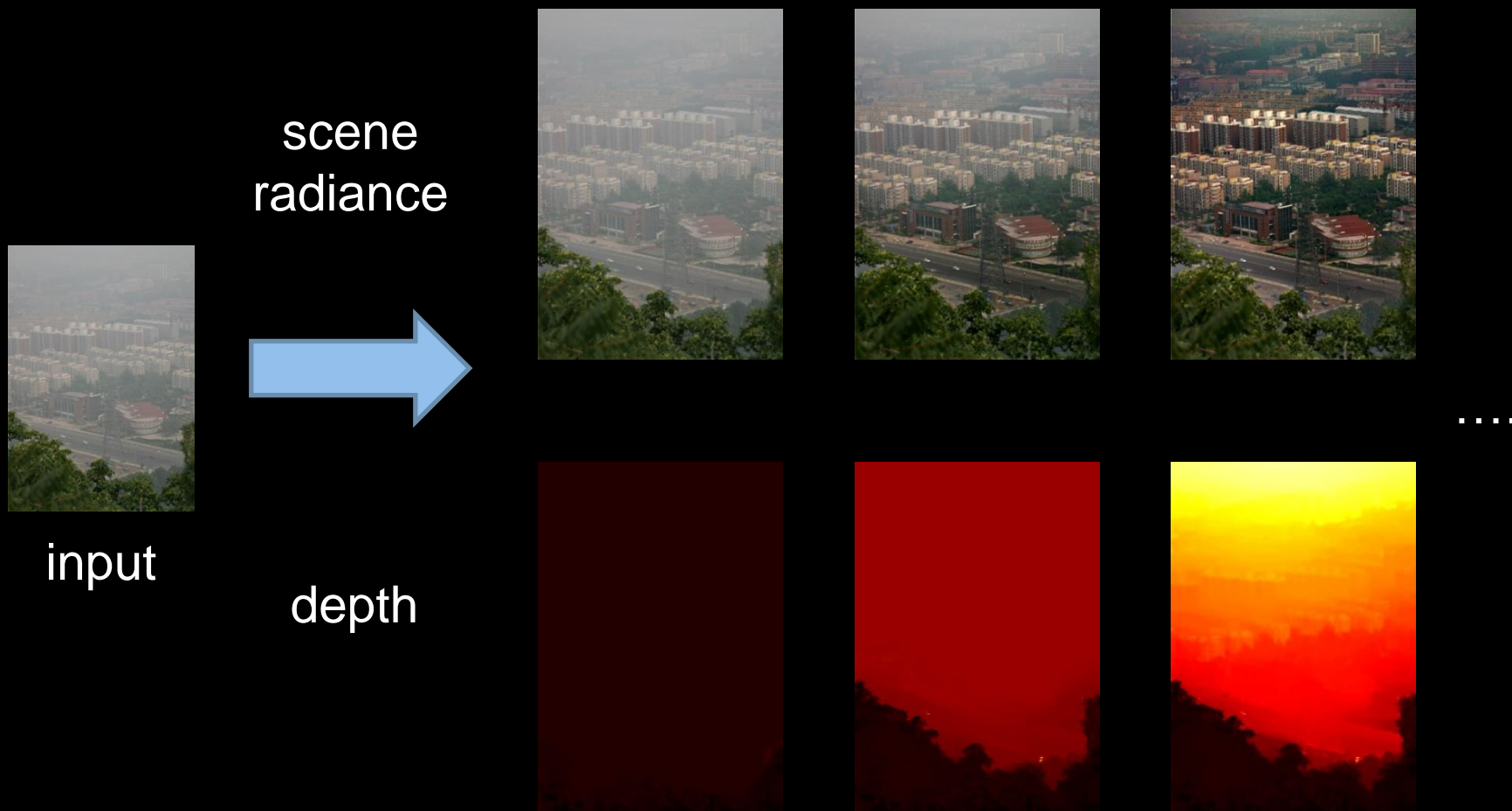
Depth

$$d = -\beta \ln t$$



Transmission

Ambiguity in Haze Removal

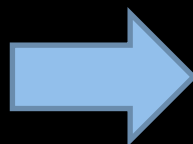


Previous Works

- Using additional information
 - Polarization filter [Shwartz et al., CVPR'06]
 - Multiple images [Narasimhan & Nayar, CVPR'00]
 - Known 3D model [Kopf et al., Siggraph Asia'08]
 - User-assistance [Narasimhan & Nayar, CPMCV'03]

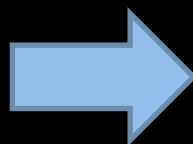
Previous Works

- Single image
 - Maximize local contrast [Tan, CVPR 08]



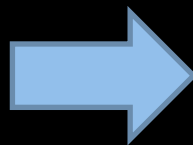
Previous Works

- Single image
 - Maximize local contrast [Tan, CVPR 08]



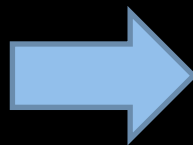
Previous Works

- Single image
 - Maximize local contrast [Tan, CVPR 08]
 - Independent Component Analysis [Fattal, Siggraph 08]

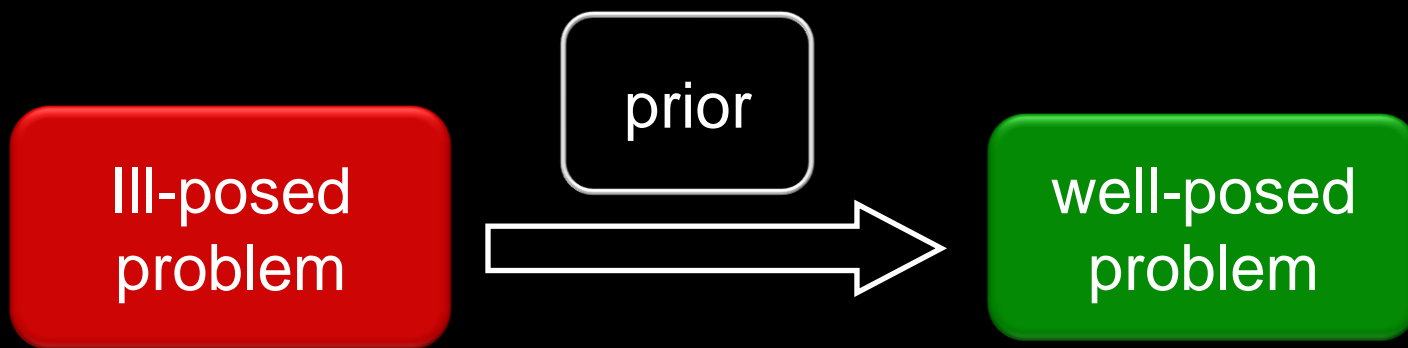


Previous Works

- Single image
 - Maximize local contrast [Tan, CVPR 08]
 - Independent Component Analysis [Fattal, Siggraph 08]



Priors in Computer Vision



- Smoothness prior
- Sparseness prior
- Exemplar-based prior

Dark Channel Prior

Dark Channel

- $\min(\text{rgb}, \text{local patch})$

Dark Channel

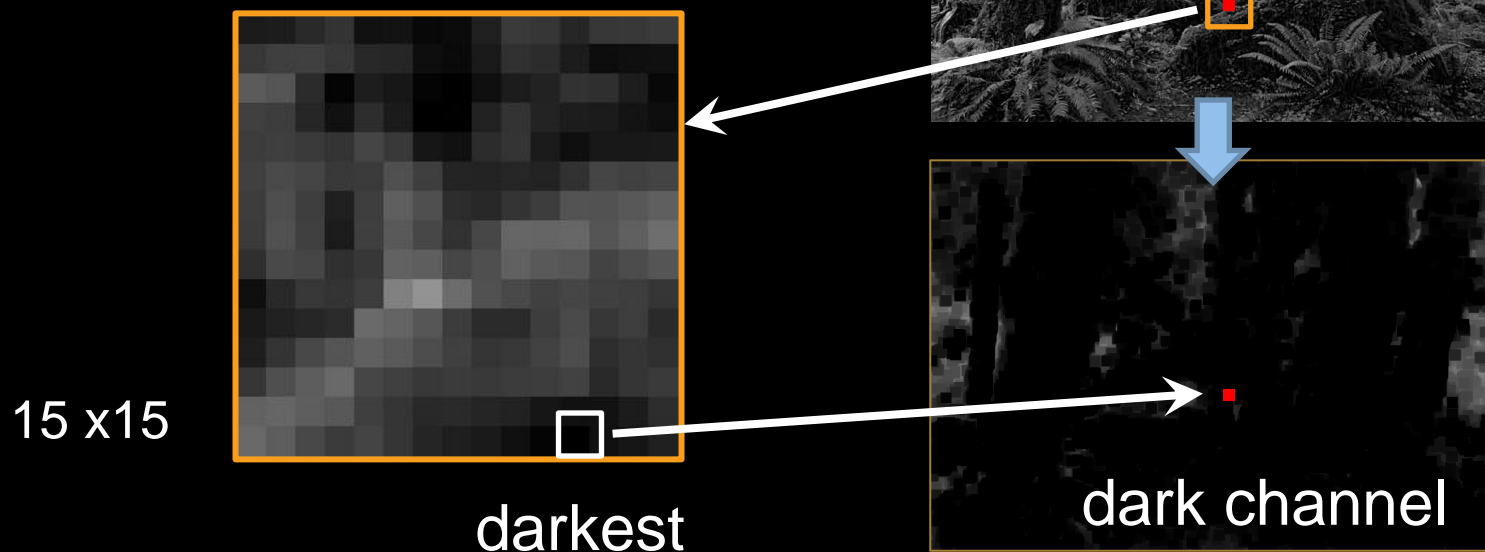
- $\min(\text{rgb}, \text{local patch})$
 - $\min(r, g, b)$



$\min(r, g, b)$

Dark Channel

- $\min(\text{rgb}, \text{local patch})$
 - $\min(r, g, b)$
 - $\min(\text{local patch}) = \text{min filter}$

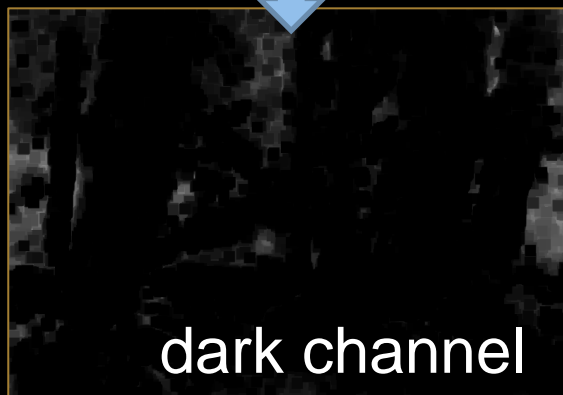
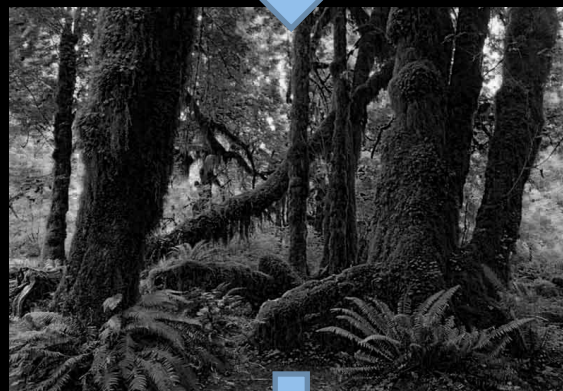


Dark Channel

- min (rgb, local patch)
 - min (r, g, b)
 - min (local patch) = min filter

$$J^{dark}(\mathbf{x}) = \min_{y \in \Omega(\mathbf{x})} \left(\min_{c \in \{r, g, b\}} J^c(\mathbf{y}) \right)$$

- J^c : color channel of \mathbf{J}
- J^{dark} : dark channel of \mathbf{J}

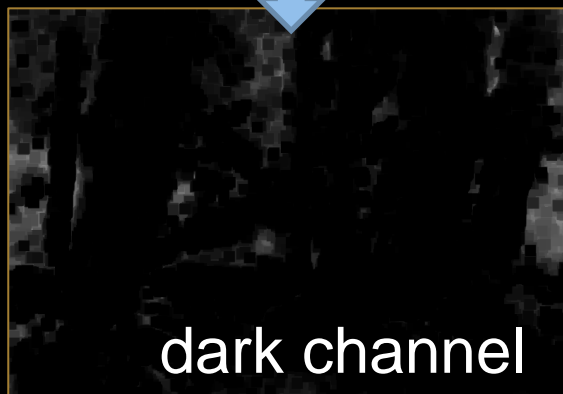
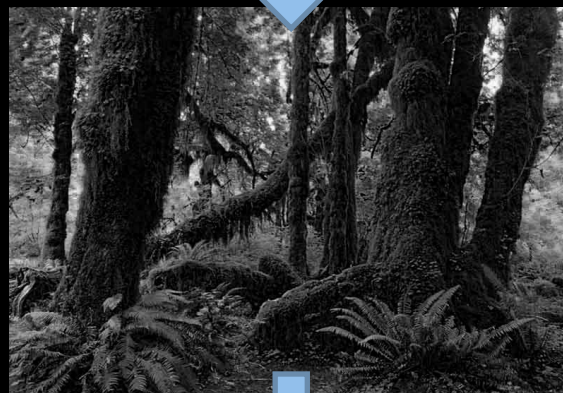


Dark Channel

- min (rgb, local patch)
 - min (r, g, b)
 - min (local patch) = min filter

$$\mathbf{J}^{dark} = \min_{\Omega} (\min_c \mathbf{J}^c)$$

- \mathbf{J}^c : color channel of \mathbf{J}
- \mathbf{J}^{dark} : dark channel of \mathbf{J}



A Surprising Observation

Haze-free



A Surprising Observation

Haze-free



A Surprising Observation

Haze-free



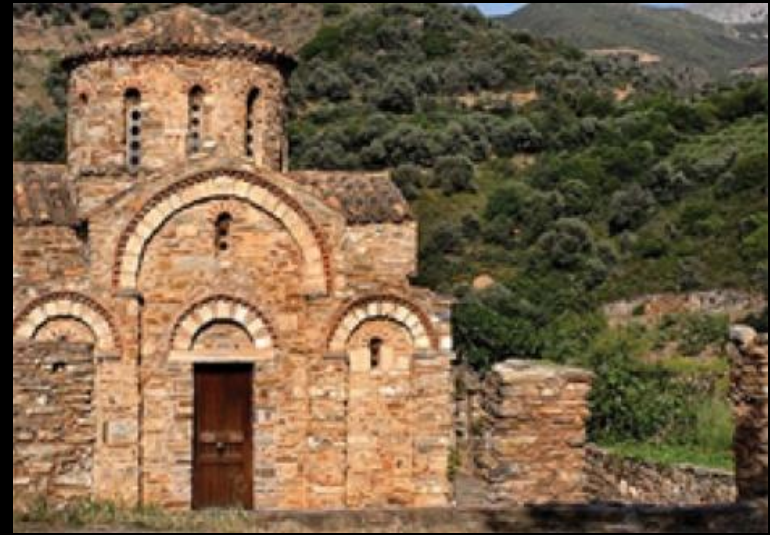
A Surprising Observation

Haze-free



A Surprising Observation

Haze-free

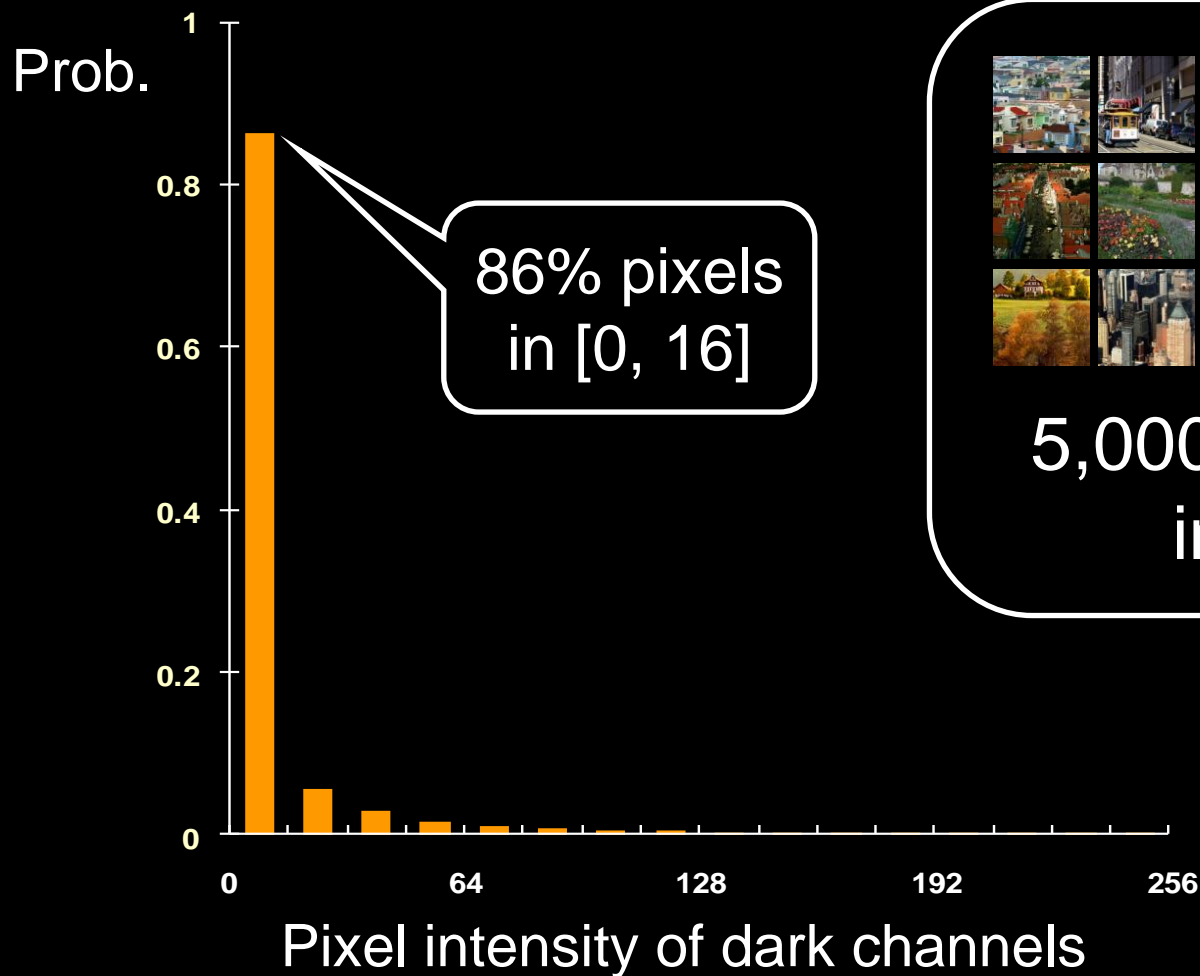


A Surprising Observation

Haze-free



A Surprising Observation



Dark Channel Prior

- For outdoor haze-free images

$$\min_{\Omega} (\min_c J^c) \rightarrow 0$$

What makes it dark?

- Shadow



- Colorful object



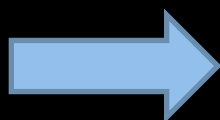
- Black object



Dark Channel of Hazy Image



hazy image



dark channel

- The dark channel is no longer dark.

Transmission Estimation

Haze imaging model $\mathbf{I} = \mathbf{J} \cdot t + \mathbf{A} \cdot (1 - t)$

Normalize $\frac{I^c}{A^c} = \frac{J^c}{A^c} t + 1 - t$

Compute dark channel

$$\min_{\Omega} \left(\min_c \frac{I^c}{A^c} \right) = \left\{ \min_{\Omega} \left(\min_c \frac{J^c}{A^c} \right) \right\} t + 1 - t$$

Transmission Estimation

Dark Channel Prior

$$\min_{\Omega} (\min_c J^c) \rightarrow 0$$

Compute dark channel

$$\min_{\Omega} (\min_c \frac{I^c}{A^c}) = \left\{ \min_{\Omega} (\min_c \frac{J^c}{A^c}) \right\}^t + 1 - t \rightarrow 0$$

Transmission Estimation

Estimate transmission

$$t = 1 - \min_{\Omega} \left(\min_c \frac{I^c}{A^c} \right)$$



Compute dark channel

$$\min_{\Omega} \left(\min_c \frac{I^c}{A^c} \right) = \left\{ \min_{\Omega} \left(\min_c \frac{J^c}{A^c} \right) \right\} t + 1 - t$$

Transmission Estimation

Estimate transmission

$$t = 1 - \min_{\Omega} \left(\min_c \frac{I^c}{A^c} \right)$$



input I



estimated t

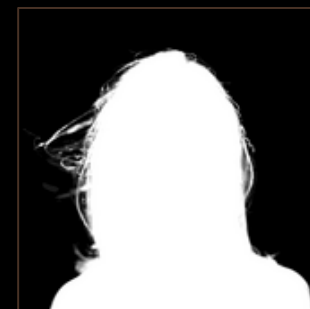
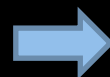
Transmission Optimization

Haze imaging model $\mathbf{I} = \mathbf{J} \cdot t + \mathbf{A} \cdot (1 - t)$

Matting model $\mathbf{I} = \mathbf{F} \cdot \alpha + \mathbf{B} \cdot (1 - \alpha)$



+

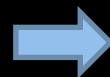


α

tri-map



+



Refined
transmission

Transmission Optimization

$$E(\mathbf{t}) = \lambda \underbrace{\|\mathbf{t} - \tilde{\mathbf{t}}\|^2}_{\text{Data term}} + \underbrace{\mathbf{t}^T \mathbf{L} \mathbf{t}}_{\text{Smoothness term}}$$

Data term

Smoothness term

- \mathbf{L} - matting Laplacian [Levin et al., CVPR '06]
- Constraint - soft, dense (matting - hard, sparse)

Transmission Optimization



before optimization

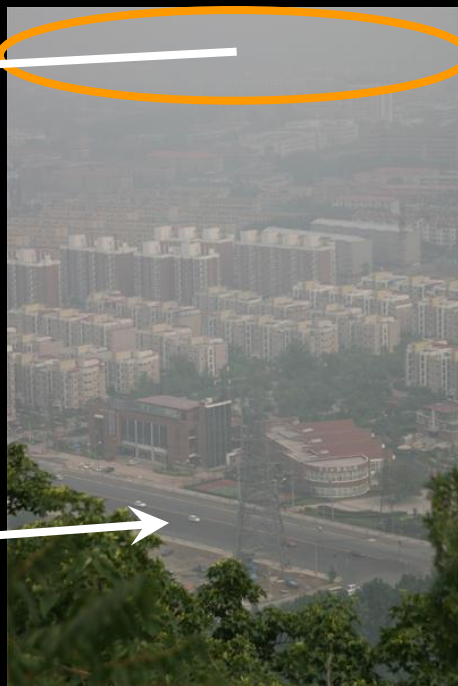
Transmission Optimization



after optimization

Atmospheric Light Estimation

A : most hazy

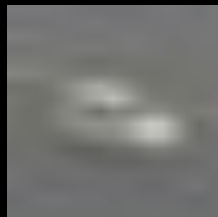


hazy image

brightest pixels



dark channel



brightest pixel

Scene Radiance Restoration

 Atmospheric light

$$\mathbf{I} = \mathbf{J} \cdot t + \mathbf{A} \cdot (1 - t)$$



Hazy image



Scene radiance



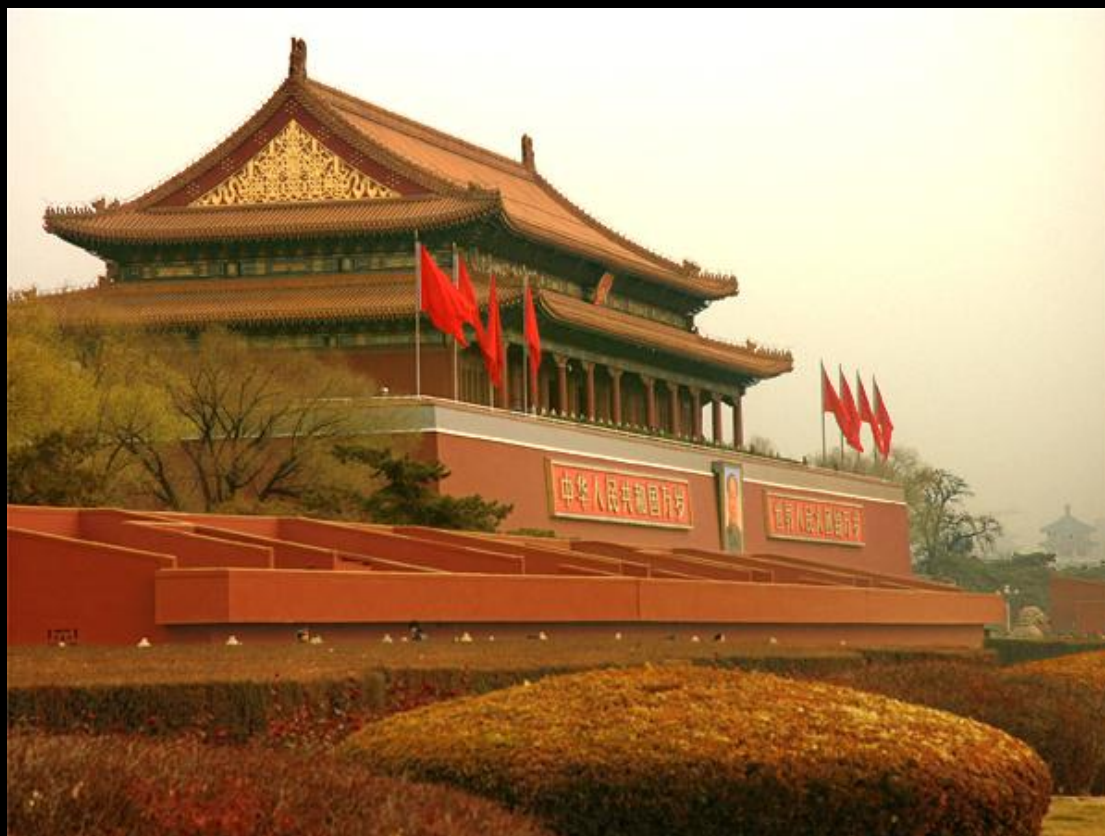
Transmission

Results



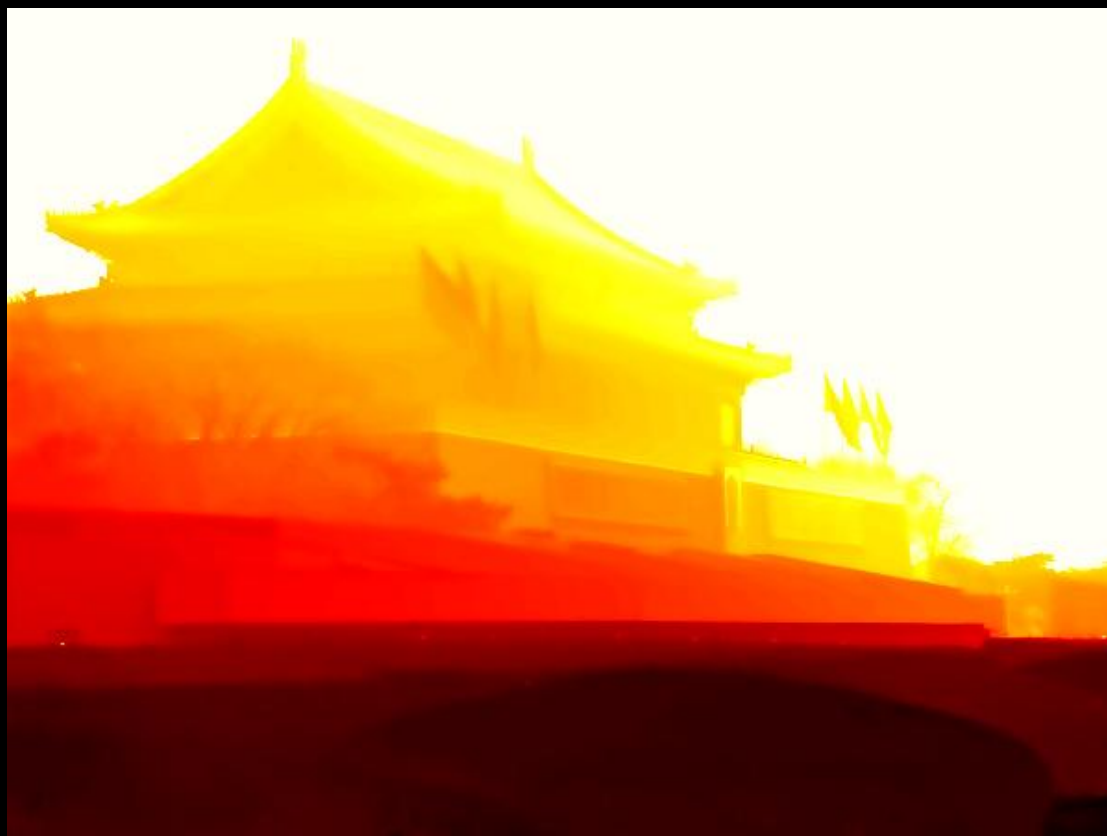
input

Results



recovered image

Results



depth

Results



input

Results



recovered image

Results



depth

Results



input

Results



recovered image

Results



depth

Comparisons



input



[Fattal Siggraph 08]

Comparisons



input



our result

Comparisons



input



[Tan, CVPR 08]

Comparisons



input



our result

Comparisons



input



[Kopf et al, Siggraph Asia 08]



our result

Results: De-focus



recovered scene radiance



input



depth

Results: De-focus



de-focus



input



depth

Results: Video

output

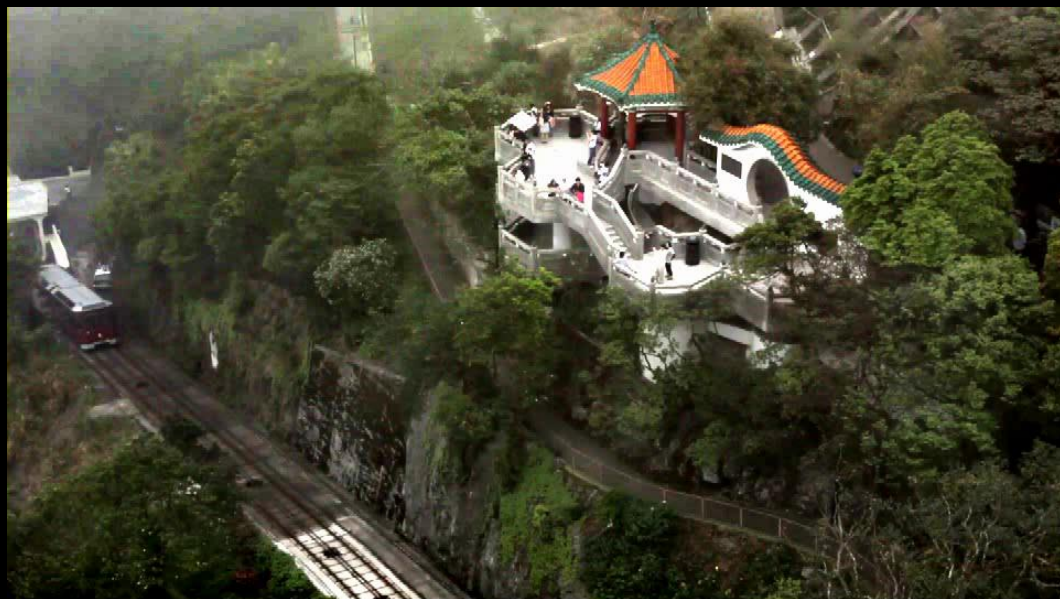


input



Results: Video

output



input



Limitations

- Inherently white or grayish objects



input



our result



transmission

Limitations

- Haze imaging model is invalid
 - e.g. non-constant A



input



our result

Summary

- Dark channel prior
 - A natural phenomenon
 - Very simple but effective
 - Put a bad image to good use

Thank you