

Lecture 21

Lecturer: Madhu Sudan

Scribe: Pritish Kamath

1 Introduction

In this lecture, we will see that the Ideal Membership problem is EXPSPACE-complete, which was shown by Mayr and Meyer [1]. Next, we will see weak and strong statements of the Hilbert's Nullstellensatz.

2 Ideal Membership

The ideal membership question is defined as follows,

Problem 1 (IDEAL-MEMBERSHIP). *Given polynomials $f, f_1, \dots, f_m \in \mathbb{K}[\mathbf{x}]$, decide whether $f \in \langle f_1, \dots, f_m \rangle$, or in other words, does there exist polynomials $g_1, \dots, g_m \in \mathbb{K}[\mathbf{x}]$ such that, $f = \sum_i f_i g_i$*

It turns out (due to [1]) that IDEAL-MEMBERSHIP is EXPSPACE-complete! This is contrast with RADICAL-IDEAL-MEMBERSHIP that we saw in last lecture to be in PSPACE.

2.1 EXPSPACE-hardness of IDEAL-MEMBERSHIP

We show that IDEAL-MEMBERSHIP is EXPSPACE-hard by obtaining a reduction from Commutative Word Equivalence Problem (CWEP), which is known to be EXPSPACE-complete. It is formulated as follows:

Problem 2. *We have an alphabet Σ (assume $|\Sigma| = n$) along with an implicit equivalence rule,*

$$\forall \sigma, \tau \in \Sigma \quad : \quad \sigma\tau \equiv \tau\sigma$$

and a set of m equivalence rules of the type,

$$\alpha_i \equiv \beta_i \quad \text{where } i \in [m] \text{ and } \alpha_i, \beta_i \in \Sigma^* \tag{1}$$

Given two strings $\alpha, \beta \in \Sigma^$, we need to decide if $\alpha \equiv \beta$.*

Informally, the problem is to start with the string $\alpha \in \Sigma^*$, and we can do a series of operations which include either swapping two consecutive symbols or substituting a substring α_i by β_i or vice-versa for some i . Due to commutativity, the order of the symbols in α don't matter, and thus α is completely determined by $\mathbf{d} = (d_1, \dots, d_n)$, where the i -th symbol in Σ appears d_i times in α , that is, we can think of α as $\sigma_1^{d_1} \sigma_2^{d_2} \dots \sigma_n^{d_n}$. The relationship between the CWEP and the ideal membership problem becomes clear once we interpret the substitution rules in Equation 1 as relations that generate an ideal.

Hard instance of IDEAL-MEMBERSHIP

We get a reduction from CWEP as follows. Consider a CWEP instance, where α_i 's (resp. β_i 's) correspond to the vectors \mathbf{d}_i (resp. \mathbf{e}_i 's), and α (resp. β) corresponds to the vector \mathbf{d} (resp. \mathbf{e}).

Let the polynomials f_1, \dots, f_m be given by $f_i = \mathbf{x}^{\mathbf{d}_i} - \mathbf{x}^{\mathbf{e}_i}$ and let $f = \mathbf{x}^{\mathbf{d}} - \mathbf{x}^{\mathbf{e}}$. It is easy to see that $f \in \langle f_1, \dots, f_m \rangle$ if and only if $\alpha \equiv \beta$ under the equivalence rules of $\alpha_i \equiv \beta_i$. And thus, we conclude that IDEAL-MEMBERSHIP is EXPSPACE-hard.

2.2 EXPSPACE algorithm for IDEAL-MEMBERSHIP

To show that IDEAL-MEMBERSHIP is in EXPSPACE, we will prove the following theorem (originally due to Hermann [2]) as follows,

Theorem 1 (Degree bound in IDEAL-MEMBERSHIP [2]). *Consider an instance of IDEAL-MEMBERSHIP as defined in Problem 1. Suppose that $\deg(f_i) \leq d$ for all i and $\deg(f) \leq d$. Then for any $f \in \langle f_1, \dots, f_m \rangle$, it is possible to write $f = \sum_i g_i f_i$ where $\deg(g_i) \leq (md)^{2^{O(n)}}$.*

Assuming the above theorem, it is easy to see that IDEAL-MEMBERSHIP is in EXPSPACE. Namely, since we know that $\deg(g_i) \leq \deg(f) + (md)^{2^{O(n)}} \stackrel{\text{def}}{=} D$, we can set up $f = \sum_i g_i f_i$ as a linear system in $m \cdot \binom{n+D}{n}$ variables. In particular, if $f = \sum_{\beta} f^{[\beta]} \mathbf{x}^{\beta}$, and $f_i = \sum_{\beta} f_i^{[\beta]} \mathbf{x}^{\beta}$. We want to know if there exist $g_i = \sum_{\alpha} g_i^{[\alpha]} \mathbf{x}^{\alpha}$ such that the following is true,

$$\forall \beta \text{ s.t. } |\beta| \leq D + d \quad : \quad f_{\beta} = \sum_{i=1}^m \sum_{\alpha \preceq \beta} g_i^{[\alpha]} f_i^{[\beta-\alpha]}$$

This linear system can be solved in EXPSPACE. Note that we cannot do this by explicitly computing the entries because the linear system is doubly-exponentially large in n . However, we can still solve the system in EXPSPACE, by only implicitly dealing with the values involved in the linear system.

If we were allowed to formulate linear equations over a ring, instead of a field, then we can express the ideal membership as a single linear equation over the ring $R = \mathbb{K}[\mathbf{x}]$, namely,

$$f = \sum g_i f_i \text{ where } g_i \in R$$

However, in a ring, this problem is hard since we cannot do inversions like we could in a field. We wish to bridge the gap between the two views, namely the *huge* linear system over \mathbb{K} and the single linear equation over $R = \mathbb{K}[\mathbf{x}]$. We will do this by a hybrid-type inductive argument over the number of variables n .

Define $\Pi(j)$ to be the problem obtained by looking at f , f_i 's and g_i 's as polynomials in $R_j[x_{j+1}, \dots, x_n]$, where $R_j = (\mathbb{K}[x_1, \dots, x_j])$. Note that $\Pi(n)$ is the single linear equation over $R_n = \mathbb{K}[\mathbf{x}]$, whereas $\Pi(0)$ is the original linear system over \mathbb{K} .

Our inductive claim is: If $\Pi(j+1)$ has M equations with each variable of degree D then, $\Pi(j)$ has $\text{poly}(M, D)$ equations with constants of degree $\text{poly}(M, D)$. To this end, we prove the following lemma,

Lemma 2. *Suppose $A\mathbf{x} = \mathbf{b}$ is a $M \times M$ linear system, where the entries in A and \mathbf{b} are univariate polynomials in $R[z]$, and each entry in A has degree $\leq D$, and A has full rank minor with monic determinant¹. Then if $A\mathbf{x} = \mathbf{b}$ has a solution, then it has a solution \mathbf{x} where for all i , $\deg(x_i) \leq \text{poly}(MD)$.*

Proof. Without the loss of generality we write

$$A = \begin{bmatrix} \tilde{A} & B \\ C & D \end{bmatrix}$$

where \tilde{A} is full rank and $\det(\tilde{A})$ is monic. Suppose the solution looks like

$$\mathbf{x} = \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{bmatrix} \quad \text{and} \quad \mathbf{b} = \begin{bmatrix} \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix}$$

¹here, we mean that A has a minor \tilde{A} such that $\text{rank}(A) = \text{rank}(\tilde{A})$ and $\text{Det}(\tilde{A})$ is a monic polynomial in z

Note, since the rows of $[C \ D]$ are contained in the linear span of the rows of $[\tilde{A} \ B]$, we have that if a solution to $A\mathbf{x} = \mathbf{b}$ exists, then in fact

$$[\tilde{A} \ B] \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{bmatrix} = [\mathbf{b}_1] \implies [C \ D] \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{bmatrix} = [\mathbf{b}_2]$$

Therefore we can ignore the second constraint of $[C \ D] \mathbf{x} = [\mathbf{b}_2]$, and only focus on the first constraint. Thus, we want to show that if a solution to $[\tilde{A} \ B] \mathbf{x} = [\mathbf{b}_1]$ exists, then in fact there exists a solution \mathbf{x} such that $\deg(\mathbf{x}) \leq \text{poly}(M, D)$.

We start with any solution to $[\tilde{A} \ B] \mathbf{x} = [\mathbf{b}_1]$. Since \tilde{A} has non-trivial determinant, we can write,

$$\mathbf{x}_1 = \frac{\text{Adj}(\tilde{A})}{\text{Det}(\tilde{A})} (\mathbf{b}_1 - B\mathbf{x}_2)$$

so $\deg(\mathbf{x}_i) \leq [\deg(\text{Adj}(\tilde{A})) + \deg(\mathbf{b}_1) + \deg(B) + \deg(\mathbf{x}_2)]$. So it suffices to show that we can obtain a solution where $\deg(\mathbf{x}_2)$ is bounded by $\text{poly}(M, D)$.

Now we use the observation that if $[\mathbf{x}_1 \ \mathbf{x}_2]^T$ is a solution to the linear system then $[(\mathbf{x}_1 + \text{Adj}(\tilde{A})B\mathbf{y}) \ (\mathbf{x}_2 - \text{Det}(\tilde{A})\mathbf{y})]^T$ is also a solution. Therefore by the division algorithm, we can make $\deg(\mathbf{x}_2) \leq \deg(\text{Det}(\tilde{A})) \leq MD$. Thus, we can obtain a solution \mathbf{x} where $\deg(\mathbf{x}) \leq \text{poly}(MD)$. \square

To show that our original problem satisfies the condition of having a full rank minor with monic determinant, we use the technique of applying a generic/random invertible linear transform. It allows us to use Lemma 2 and to ensure $\text{Det}(\tilde{A})$ is monic.

Lemma 3. *Given $A\mathbf{x} = \mathbf{b}$ with $A, \mathbf{b} \in \mathbb{K}[x_1, \dots, x_j]$, let $T : \mathbb{K}^j \rightarrow \mathbb{K}^j$ be an invertible affine transform. Then*

1. \mathbf{x} is a solution to $A\mathbf{x} = \mathbf{b}$ if and only if $\mathbf{x}(T)$ is a solution to $A(T)\mathbf{x}(T) = \mathbf{b}(T)$ and $\deg(\mathbf{x}(T)) = \deg(\mathbf{x})$.
2. With high probability over choices of T , $\text{Det}(\tilde{A}(T))$ is monic in x_j .

Proof of Theorem 1: We start by writing a linear system in $\Pi(n)$, with a single equation $f = \sum_{i=1}^m g_i f_i$. We successively apply the inductive step to convert the linear system in $\Pi(j+1)$ to a linear system in $\Pi(j)$. Lemma 2, in addition to Lemma 3 guarantees that if the degrees of polynomials in number of equations in $\Pi(j+1)$ in M_{j+1} , then the degrees of the solution in $\Pi(j)$ can be made to be less than $\text{poly}(M_{j+1}, d)$ (since the entries in the linear system have degree at most $d = \max_i \deg(f_i)$). Also, going from $\Pi(j+1)$ to $\Pi(j)$ increases the number of linear equations to $M_j = \text{poly}(M_{j+1}, d)$ (with degree at least 2 in M_{j+1}). Thus finally when we get to $\Pi(0)$, the degrees of the solution can be brought down to $(md)^{2^{O(n)}}$. \square

3 Hilbert's Nullstellensatz

Hilbert's Nullstellensatz deals with the problem of finding common roots to a given set of polynomials.

Problem 3. *Given polynomials $f_1, \dots, f_m \in \mathbb{K}[\mathbf{x}]$ (where \mathbb{K} is algebraically closed), decide whether there exists $(\alpha_1, \dots, \alpha_n) = \alpha \in \mathbb{K}^n$ such that $f_j(\alpha) = 0$ for all $j \in [m]$.*

A more generalized version of this problem is as follows,

Problem 4. *Given polynomials $f_1, \dots, f_m, f'_1, \dots, f'_{m'} \in \mathbb{K}[\mathbf{x}]$ (where \mathbb{K} is algebraically closed), decide whether there exists $(\alpha_1, \dots, \alpha_n) = \alpha \in \mathbb{K}^n$ such that $f_j(\alpha) = 0$ for all $j \in [m]$ and $f'_j(\alpha) \neq 0$ for all $j \in [m']$.*

We note that Problem 4 in fact reduces to Problem 3. Firstly, observe that $f'_j(\alpha) \neq 0$ for all $j \in [m']$ if and only if $F(\alpha) \stackrel{\text{def}}{=} \prod_{j \in [m']} f'_j(\alpha) \neq 0$. Next we can reduce this to Problem 3 by adding an extra variable y and noting that the polynomials $f_1, \dots, f_m, (1 - yF(\mathbf{x})) \in \mathbb{K}[\mathbf{x}, y]$ have a common root if and only if there exists $\alpha \in \mathbb{K}^n$ such that $f_j(\alpha) = 0$ for all $j \in [m]$ and $F(\alpha) \neq 0$.

The statement of Hilbert's Weak Nullstellensatz is as follows,

Theorem 4 (Weak Hilbert Nullstellensatz (WHN)). *For any ideal I in $\mathbb{K}[\mathbf{x}]$,*

$$V(I) = \emptyset \quad \Leftrightarrow \quad 1 \in I$$

(Note that $1 \in I \Leftrightarrow I = \mathbb{K}[x_1, \dots, x_n]$.)

In other words, polynomials f_1, \dots, f_m do not have a common zero iff there exist $g_1 \cdots g_m$ such that $1 = \sum_i f_i g_i$.

The statement of the Strong Nullstellensatz is defined in terms of the Radical Ideal, which is defined as follows,

Definition 5 (Radical Ideal). *For any ideal $I \subseteq \mathbb{K}[\mathbf{x}]$, the radical ideal of I is $\text{Rad}(I) = \{f : \exists d \ f^d \in I\}$.*

Theorem 6 (Strong Hilbert Nullstellensatz (SHN)). *For any ideal I in $\mathbb{K}[x_1, \dots, x_n]$,*

$$I(V(I)) = \text{Rad}(I)$$

In other words, the following are equivalent,

- polynomials $f_1, \dots, f_m, F \in \mathbb{K}[\mathbf{x}]$ are such that for every $\alpha \in \mathbb{K}^n$, if $f_i(\alpha) = 0$ for all $i \in [m]$, then $F(\alpha) = 0$
- there exists $d \geq 1$ such that $F^d \in \langle f_1, \dots, f_m \rangle$

Lemma 7. *SHN and WHN are equivalent.*

Proof. Both the SHN and the WHN have trivial directions (namely, $I(V(I)) \supseteq \text{Rad}(I)$ and $V(I) = \emptyset \Leftrightarrow 1 \in I$ respectively). So we only need to prove the equivalence of the non-trivial directions of the SHN and the WHN (namely, $I(V(I)) \subseteq \text{Rad}(I)$ and $V(I) = \emptyset \Rightarrow 1 \in I$ respectively).

[SHN \implies WHN] So suppose that $V(I) = \emptyset$. Then, by the SHN, $\text{Rad}(I) = I(\emptyset) = \mathbb{K}[\mathbf{x}]$. Hence, $1 \in \text{Rad}(I)$ and thus $1 \in I$, as claimed in the WHN.

[WHN \implies SHN] Let $F \in I(V(I))$; we need to show that $F \in \text{Rad}(I)$. If F is identically 0, we are done; so assume that F is not identically 0. Consider the ideal J in $\mathbb{K}[x_1, \dots, x_n, y]$, where y is an auxiliary variable, defined by $J = \langle I, 1 - yF \rangle$.

Notice that $V(J) = \emptyset$. Indeed, suppose by way of contradiction that there is $(a_1, \dots, a_n, b) \in V(J)$; then $(a_1, \dots, a_n) \in V(I)$ and thus $f(a_1, \dots, a_n) = 0$, and thus $1 - bF(a_1, \dots, a_n) = 1 - 0 = 1 \neq 0$; we conclude that $V(J)$ must indeed be empty.

By the WHN, since $V(J) = \emptyset$, we know that $1 \in J$, so that there must exist $p \in \mathbb{K}[x_1, \dots, x_n, y]$ and $q_1, \dots, q_d \in I$ such that $1 = p(1 - yF) + \sum_{i=0}^d y^i q_i$. This polynomial identity holds in $\mathbb{K}[\mathbf{x}, y]$, and thus also in $\mathbb{K}(\mathbf{x})[y]$; furthermore, since F is not identically 0, $1/F$ is a well defined element in $\mathbb{K}(x_1, \dots, x_n)$. By setting $y = 1/F$, we deduce that $1 = \sum_{i=0}^d F^{-i} q_i$, and thus $F^d = \sum_{i=0}^d F^{d-i} q_i$, which means that $F^d \in I$, and thus $F \in \text{Rad}(I)$, as we wanted to show. \square

3.1 Remarks on the Nullstellensatz

Brownawell [3] showed that in the statement of Weak Nullstellensatz [Theorem 4] we can have $\deg(g_i) \leq \prod_i \deg(f_i)$. Note that one can try to invoke Theorem 1 (due to Hermann) here, since we are trying to solve

an ideal membership problem here of writing $1 = \sum_i g_i f_i$. However, the bound we get is doubly-exponential in n , whereas Brownawell's result gives a much stronger bound.

This suggests that perhaps finding witnesses g_i 's such that $1 = \sum_i g_i f_i$ should not be a very hard problem. In particular, it is clear that it is in PSPACE. More strongly though, Koiran showed that assuming the Generalized Riemann Hypothesis, Hilbert Nullstellensatz is in RP^{NP} [4].

References

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