## Learning Restricted Boltzmann Machines

## Ankur Moitra (MIT)

joint work with Guy Bresler and Frederic Koehler

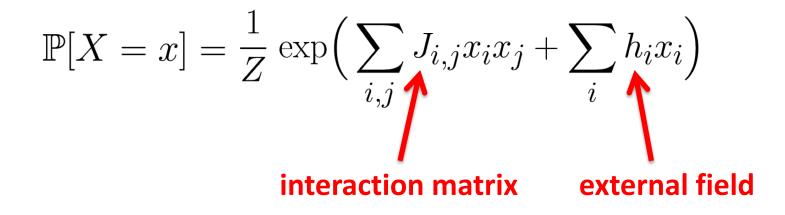
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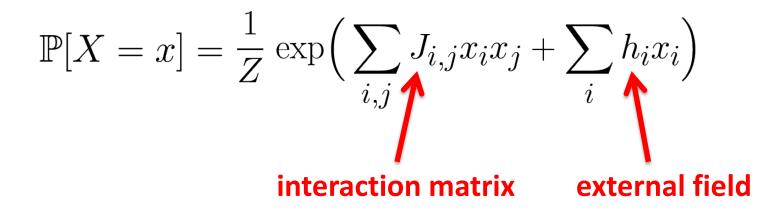


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**Generalizations:** larger alphabet (Potts model), higher-order interactions (Markov Random Field), directed (Bayesian network)

Often helpful to look at their graph structure:

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Can we learn graphical models from random samples?

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[Bresler et al. '08], [Ravikumar et al. '10]: Better algorithms when there are no long range correlations

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#### **Part I: Introduction**

- Learning Ising Models
- Latent Variables and Higher-Order Dependencies
- Our Results

#### Part II: Learning Ferromagnetic RBMs

- The Discrete Influence Function
- A Greedy Algorithm
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What if there are unobserved/latent variables?

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# Allows variables to influence each other through unobserved mechanisms

Scientific theories that explain data in a more parsimonious way can be learned/tested

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latent variables:  $Y_1, \cdots, Y_m$ 

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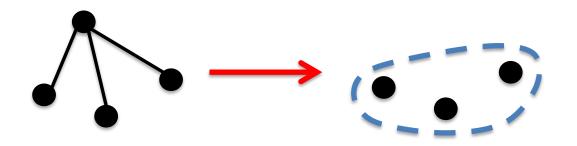
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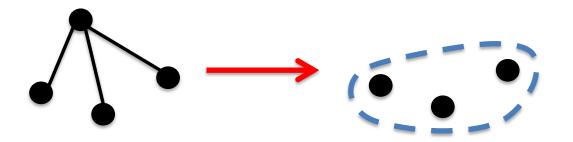
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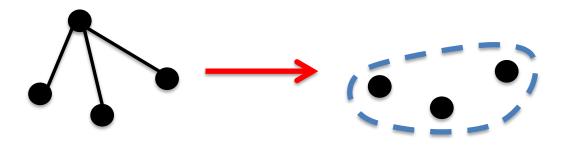
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So what type of distribution is it?

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Are there efficient algorithms for learning MRFs?

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These algorithms are close to trivial, because we can always brute-force search for the two-hop neighbors of a node in n<sup>d<sup>2</sup></sup>time

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Earlier work of [Martens et al. '13] showed that dense RBMs can represent parity (more generally, any predicate depending on # 1s)

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Earlier work of [Bogdanov et al. '08] required a large number of latent variables, one for each gate in a given circuit

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In our context, it prevents hidden nodes from cancelling out each other's lower-order interactions

Our main result:

**Theorem:** There is a greedy algorithm with running time f(d) n<sup>2</sup> and sample complexity f(d) log n for learning ferromagnetic RBMs, with upper and lower bounds on the interaction strength

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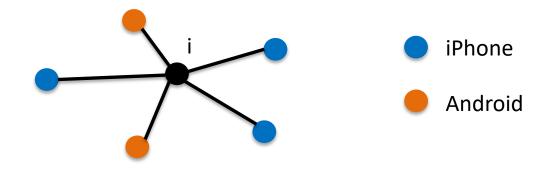
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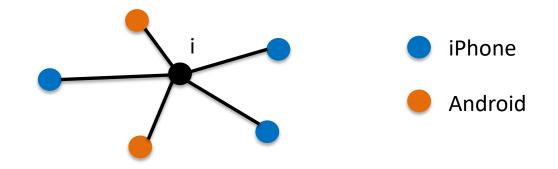
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**Everything generalizes to ferromagnetic Ising models with latent variables, under conditions on diameter of latent nodes** 

Natural scenario where interactions are positive: Modeling the adoption of technology/spread of an epidemic on a network

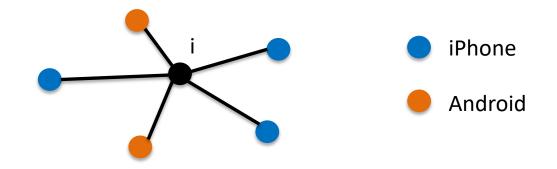


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When you know the network/interactions, natural questions like: What are the most influential nodes? How quickly does it spread?

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Many natural extensions to consider: Potts models, arbitrary external field

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## MAIN STRUCTURAL RESULT

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It turns out that the **concavity of magnetization** is analogous to properties of the **multilinear extension** 

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(2) is called **concavity of magnetization**, and follows from the famous **Griffiths-Hurst-Sherman inequality** and captures diminishing returns

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#### **KEY IDEAS**

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Idea #2: The maximizer ought to be the two hop neighbors of node i (or any set containing them)

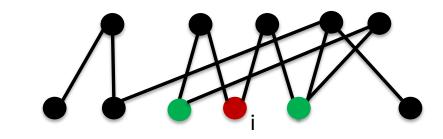
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latent nodes

e.g.



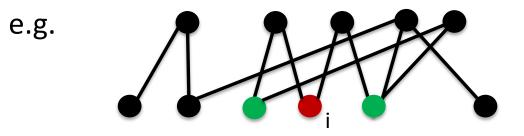
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observed nodes

Because the two-hop neighbors separate i from all the other observed nodes

#### QUANTITATIVE BOUNDS

We say that an Ising model is (lpha, eta)-nondegenerate if

(1) 
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(2)  $\sum_{j} |J_{i,j}| + |h_i| \le \beta$  for all i

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**Key Lemma:** If S does not contain the two-hop neighbors of i, then there is a node j such that

$$I_i(S \cup \{j\}) - I_i(S) \ge \left(\frac{2\alpha^2}{1 + e^{2\beta}}\right)(1 - \tanh(\beta))^2$$

Classic result in approximation algorithms:

**Theorem [Nemhauser et al. '78]**: The greedy algorithm achieves a 1 - 1/e factor approximation for maximizing a monotone submodular function subject to a cardinality constraint

Now, how can we maximize the discrete influence function?

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Idea #3: Run the greedy algorithm to learn a small superset of the two-hop neighbors

Finally when we have a small superset of the two-hop neighbors, we can learn the induced MRF

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The key is, each node no longer participates in n<sup>d</sup> possible order d interactions, but rather at most f(d)

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# THE SMOOTH INFLUENCE FUNCTION

**Definition:** The **smooth influence function** at node i is

$$\mathcal{I}_i(h) \triangleq \mathbb{E}[X_i]$$

where the expectation is taken when we set the external field to h

## THE SMOOTH INFLUENCE FUNCTION

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In retrospect, it is the **multilinear extension** of  $I_i$ 

#### THE GHS INEQUALITY

The Griffith-Hurst-Sherman inequality states

$$\begin{split} \mathbb{E}[X_i X_j X_k X_{\ell}] &- \mathbb{E}[X_i X_j] \mathbb{E}[X_k X_{\ell}] \\ &- \mathbb{E}[X_i X_k] \mathbb{E}[X_j X_{\ell}] - \mathbb{E}[X_i X_{\ell}] \mathbb{E}[X_j X_k] \\ &+ 2 \cdot \mathbb{E}[X_i X_{\ell}] \mathbb{E}[X_j X_{\ell}] \mathbb{E}[X_k X_{\ell}] \le 0 \end{split}$$

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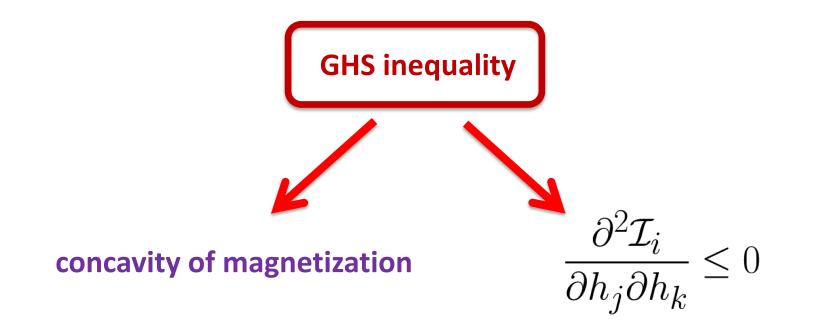
Each of these terms arises as a partial derivative of the log partition function, and so does the smooth influence function

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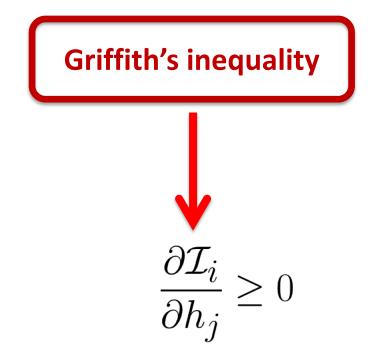
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submodularity

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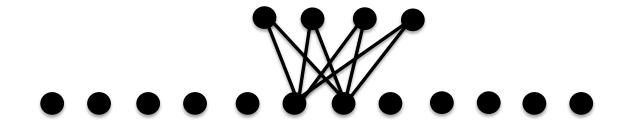
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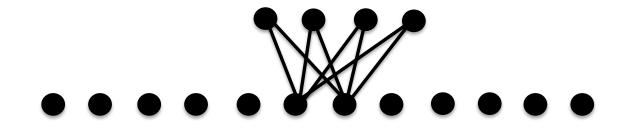
Are there algorithms that learn the graph structure in f(d)poly(n) time, even without ferromagneticity?



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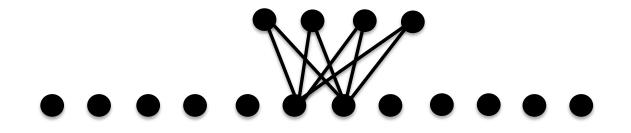


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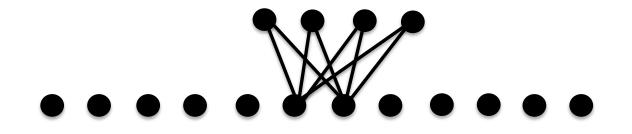
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Besides ferromagneticity, are there other ways (e.g. expansion) that preclude sparse parity with noise?

And can these conditions lead to new algorithms with provable guarantees?



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We are searching for models just as much (if not more) as we are searching for algorithms

#### Summary:

- Precise characterization of distributions that can be represented as bounded degree RBMs
- Lower bounds for learning RBMs with constant number of latent variables
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# Thanks! Any Questions?