

Characterizing and Processing Robot-Directed Speech

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MIT AI Lab Humanoid Robotics Group

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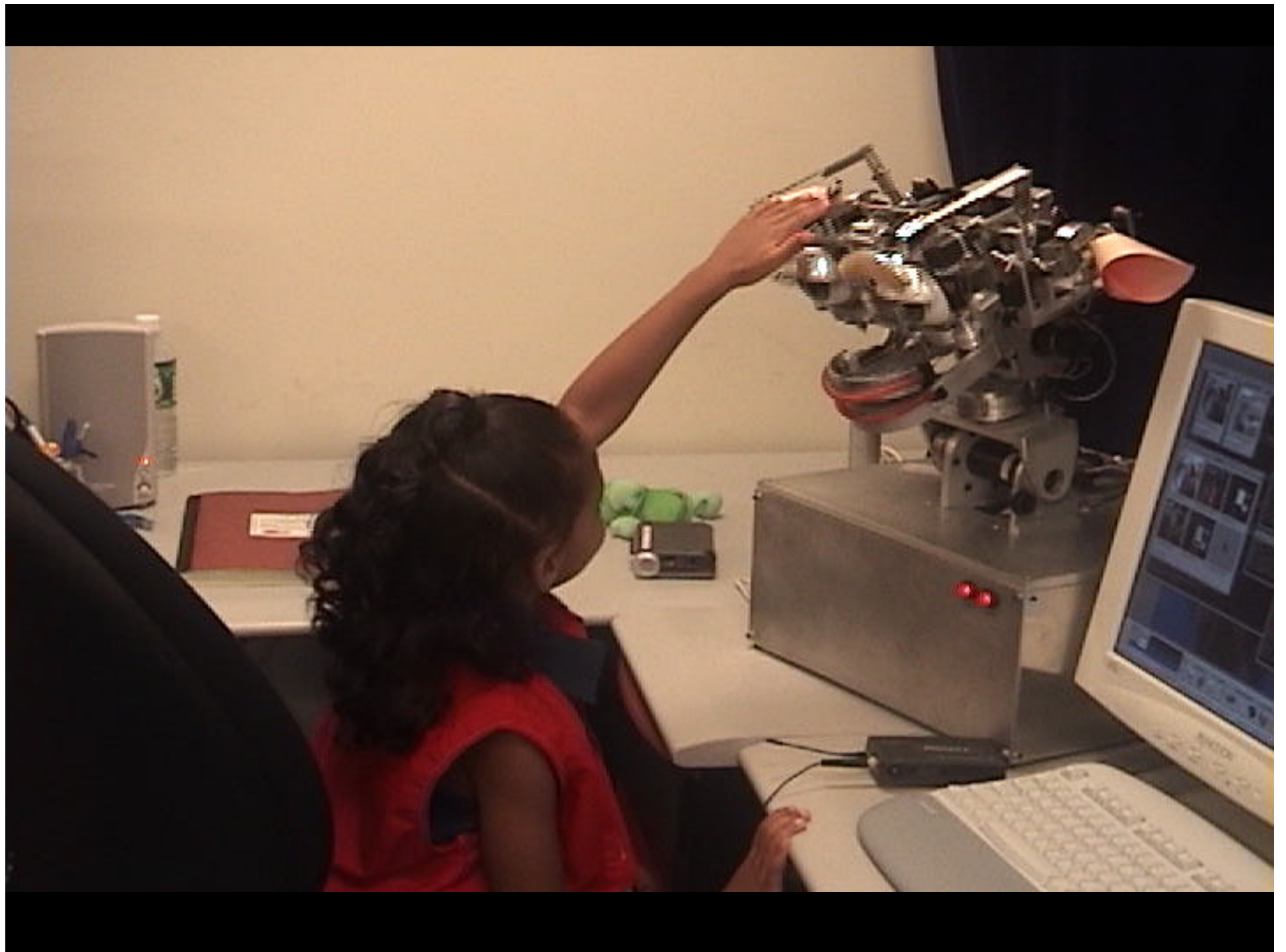
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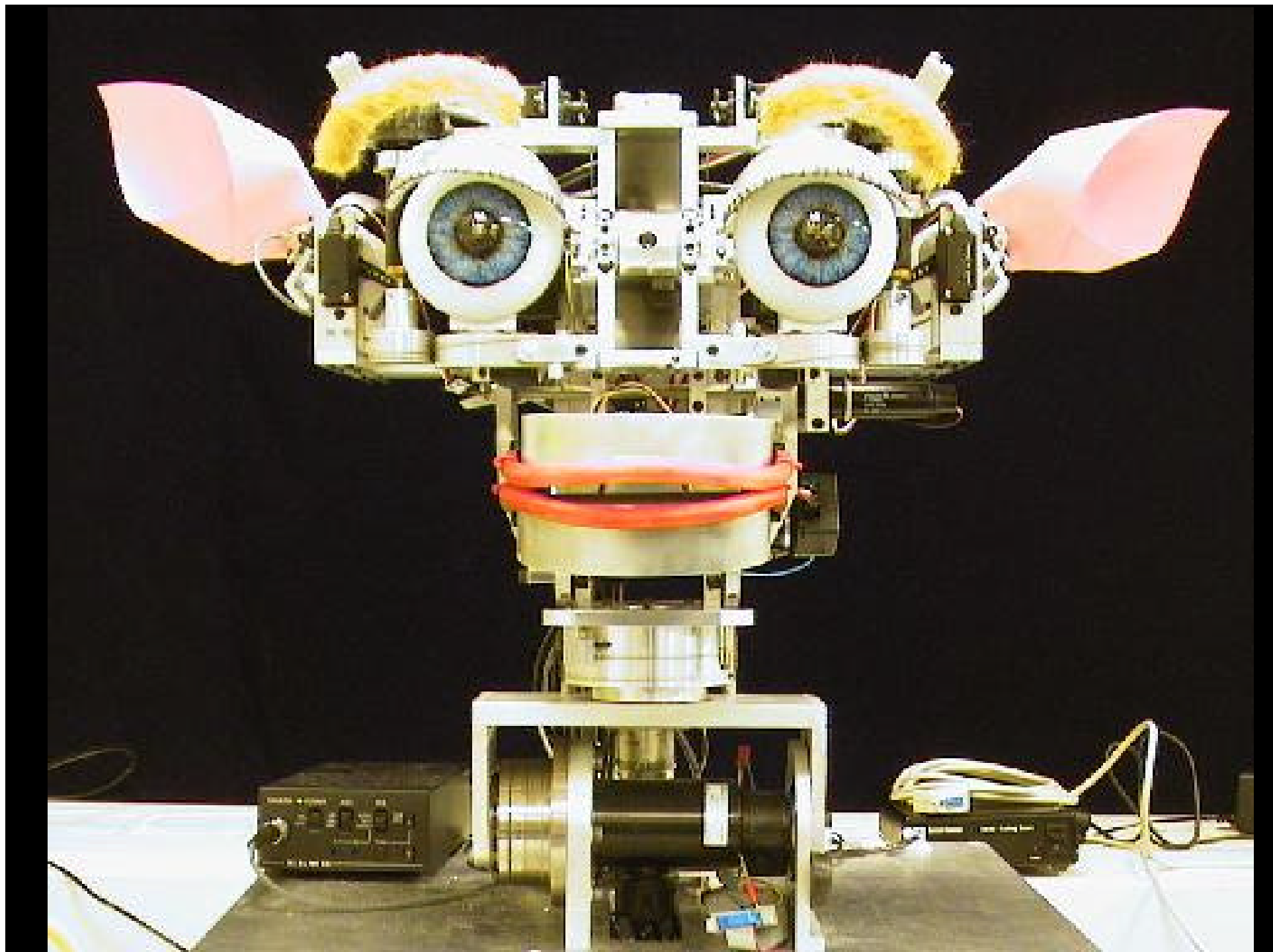
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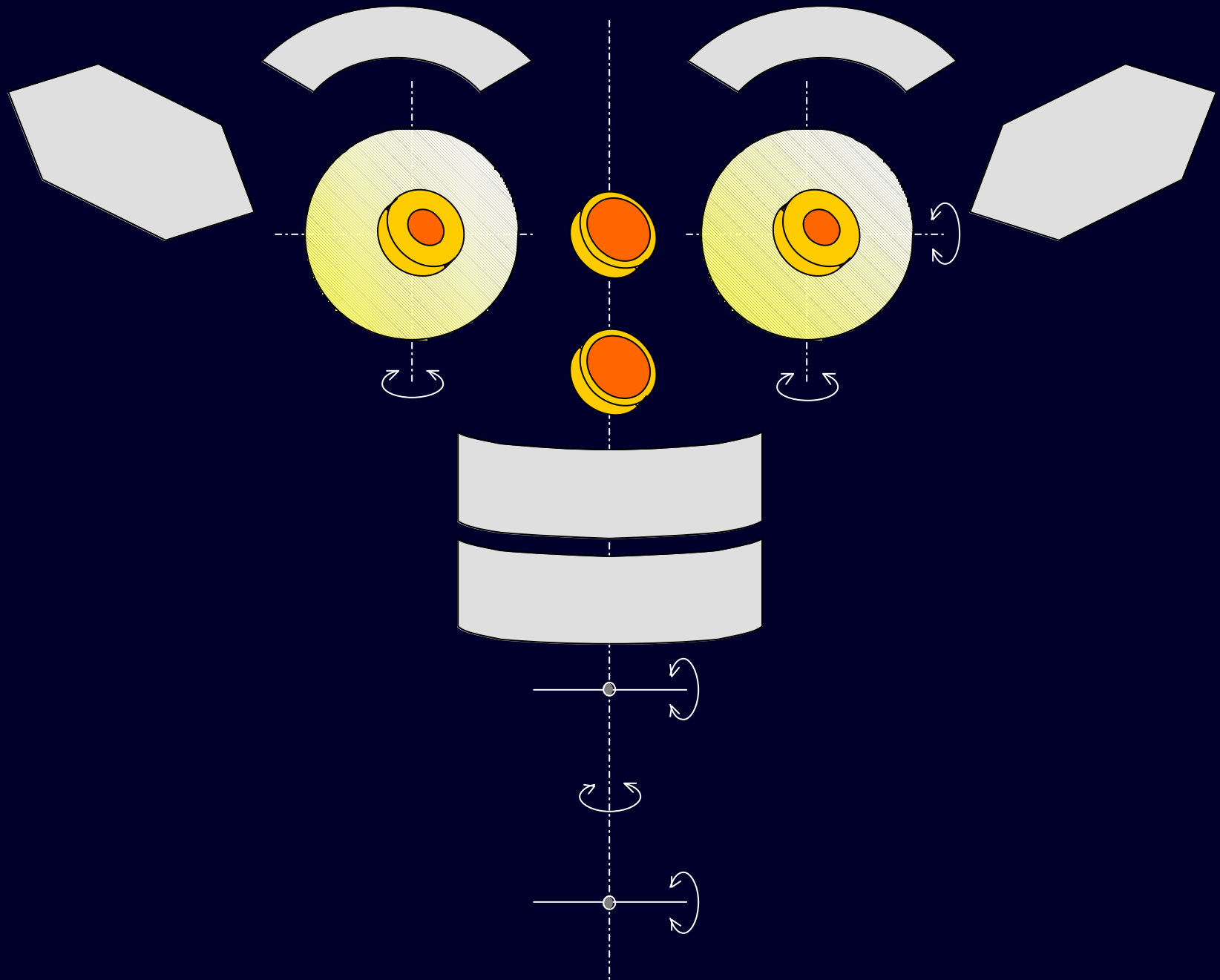
Characterizing and Processing **Robot**-Directed Speech

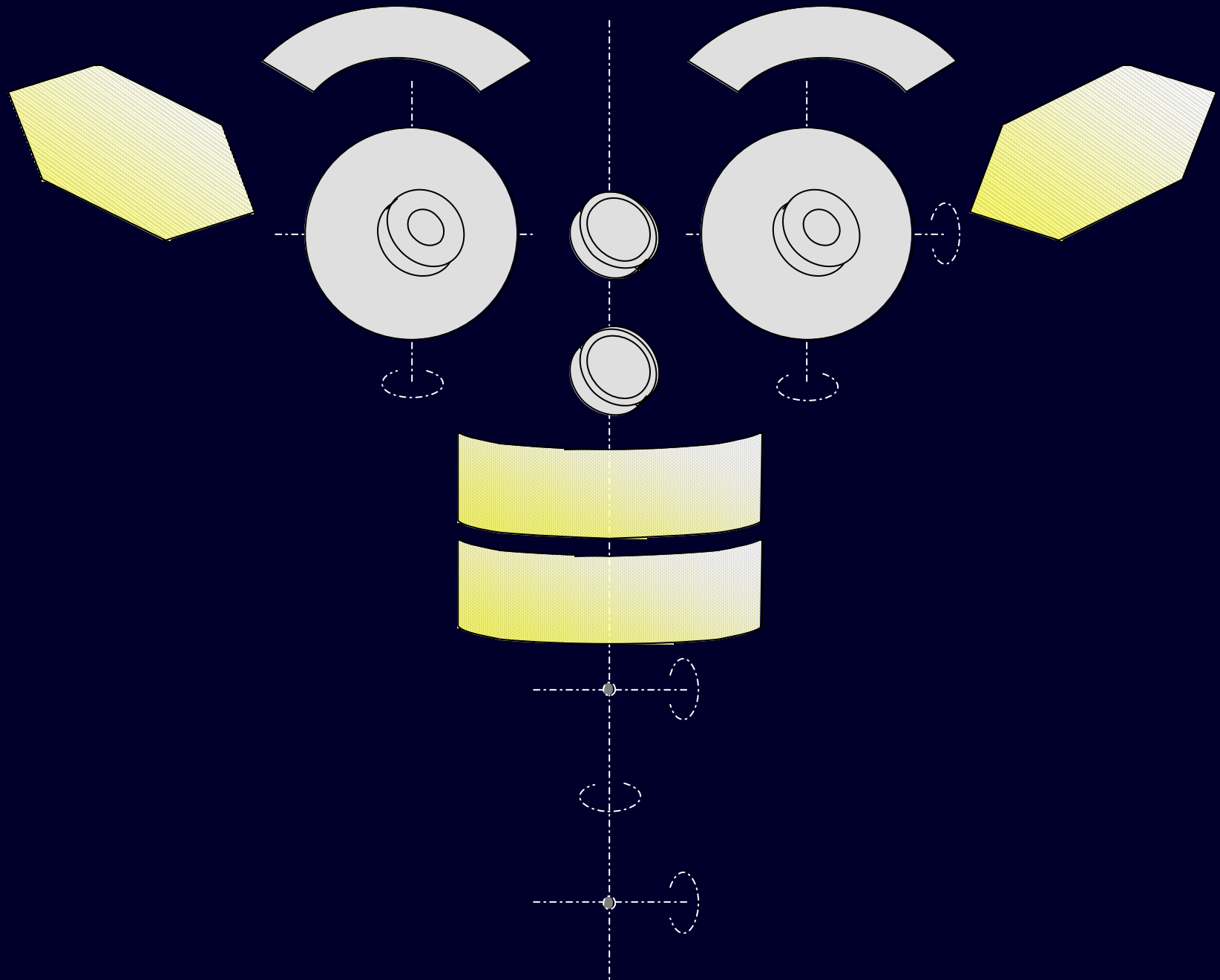
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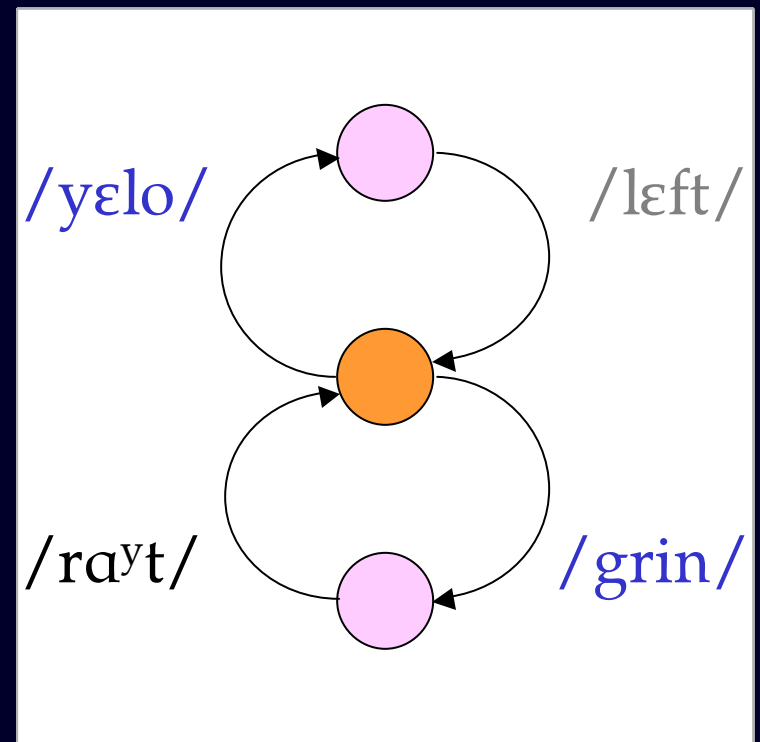
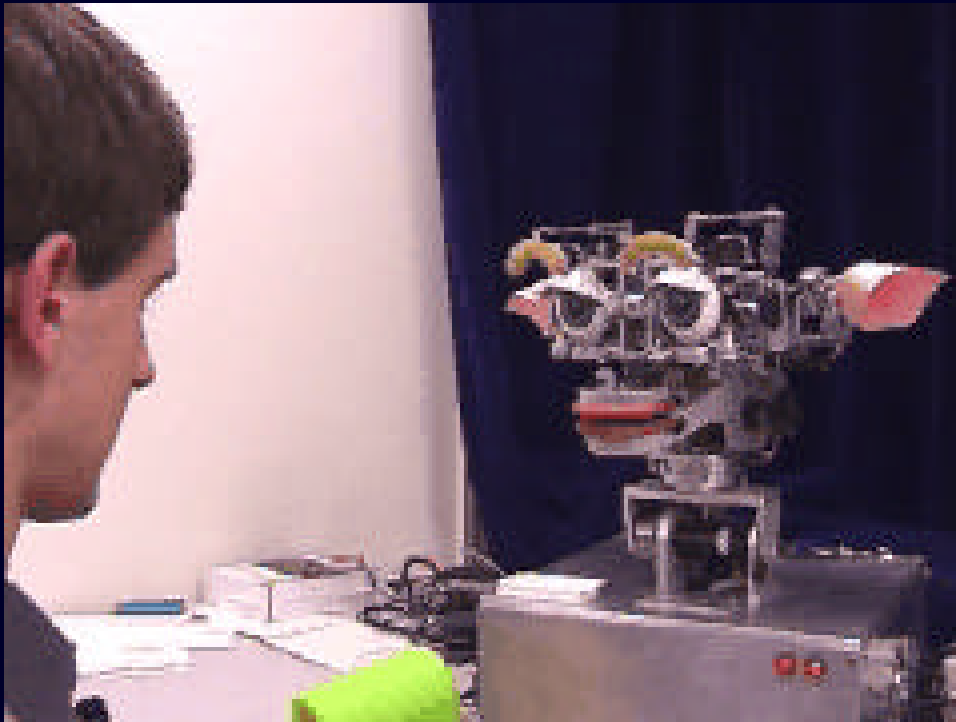




Speech Recognition

- What speech does the robot evoke?
- How can we process that speech?
 - Support a growing vocabulary
 - Without hurting recognition accuracy

Baseline System

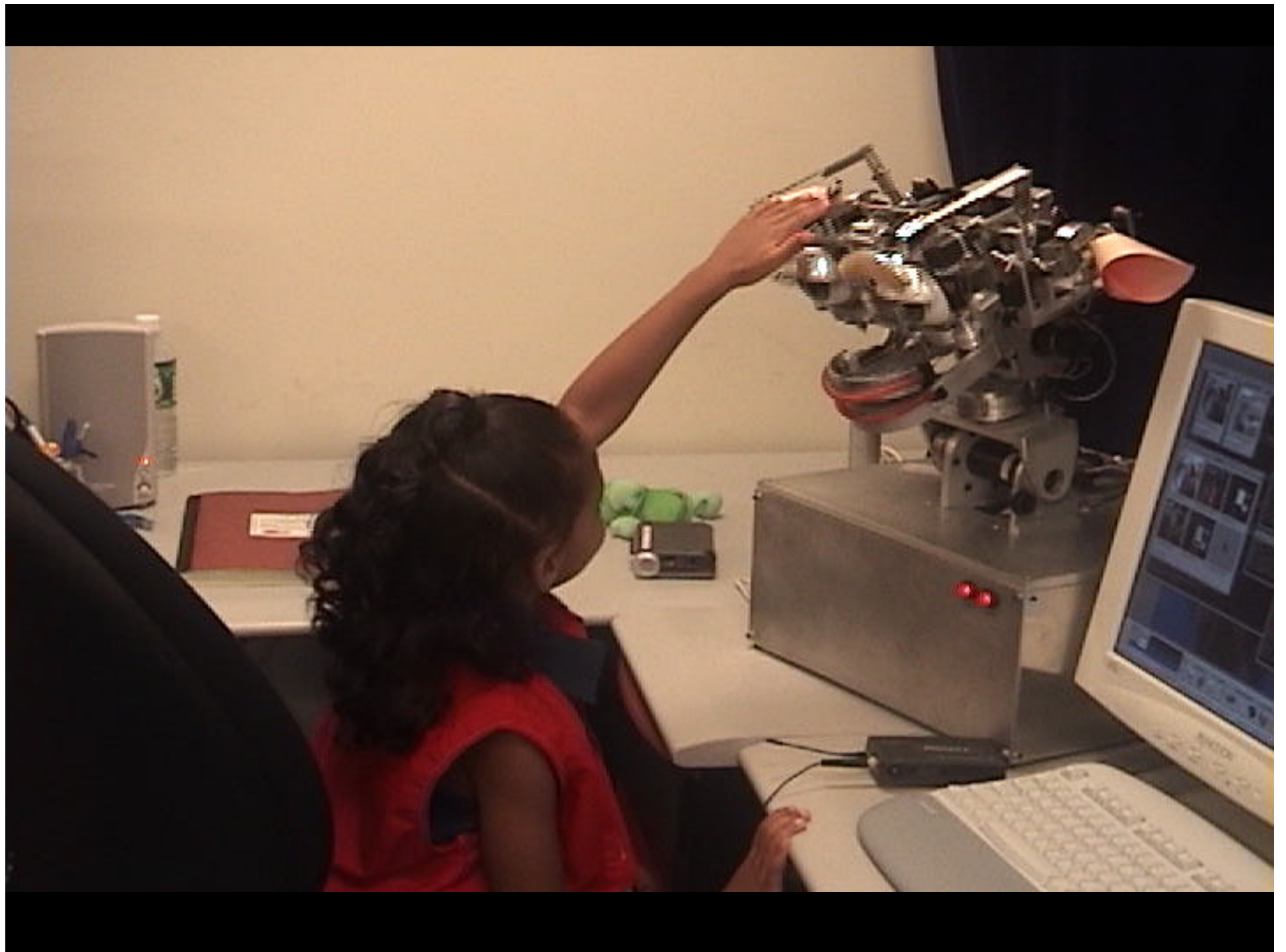


Baseline System

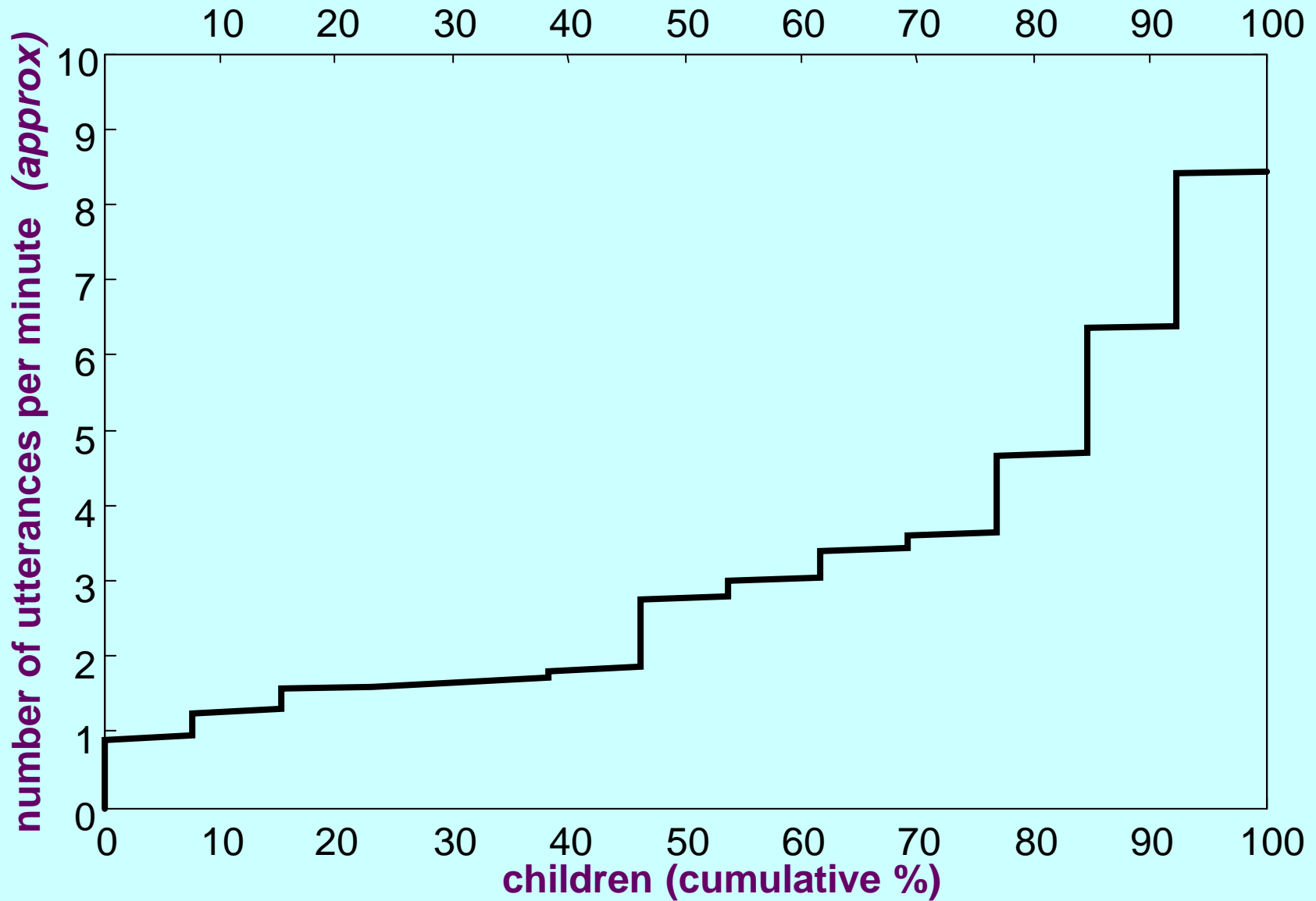
- “Magic word” to introduce vocabulary
- Separation of introduction from use
- Robot confused by unknown/filler words

Study: Characterizing Speech

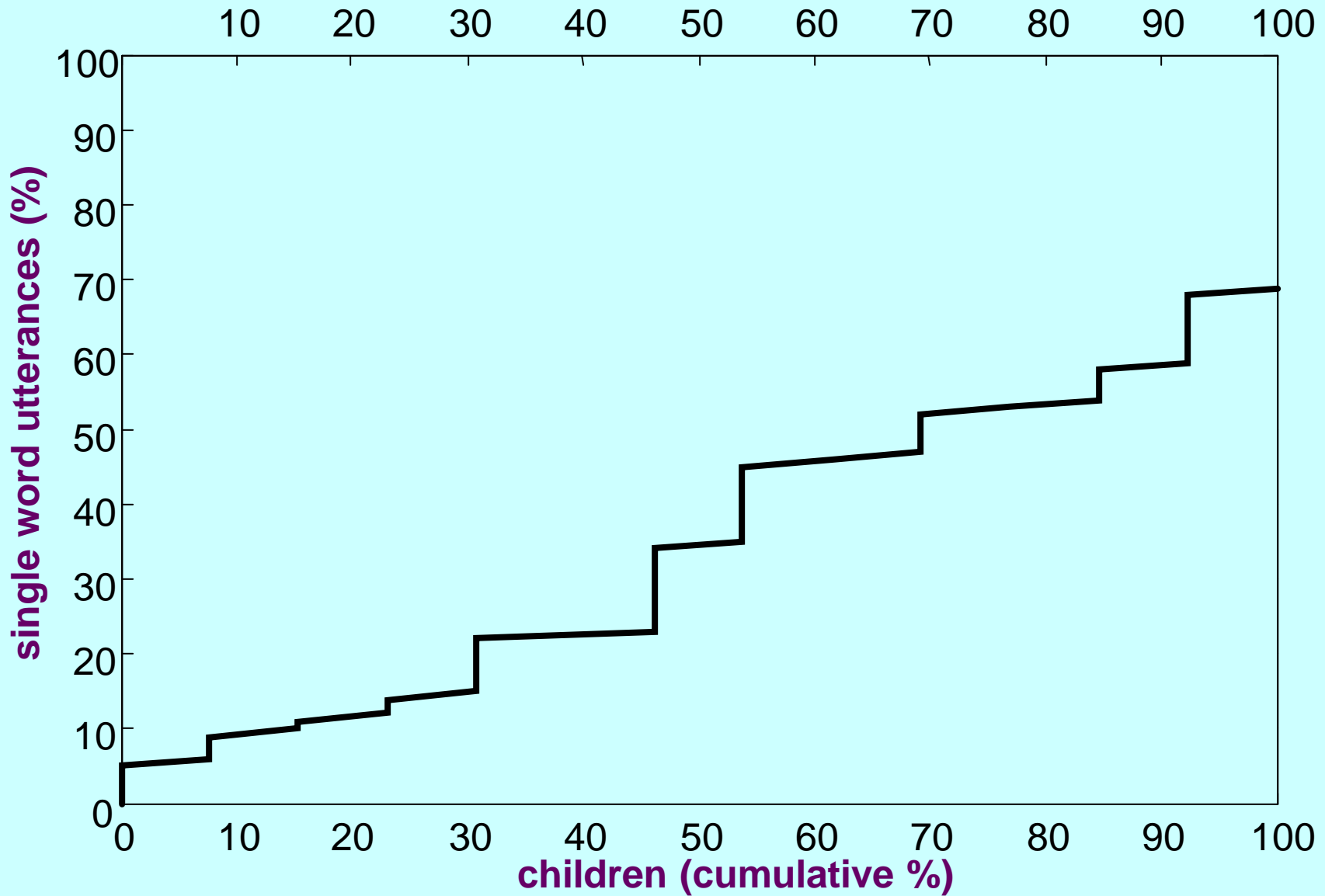
- 13 children
- 5-10 years old
- 20 minute sessions
- Some prompting *(Turkle et al)*



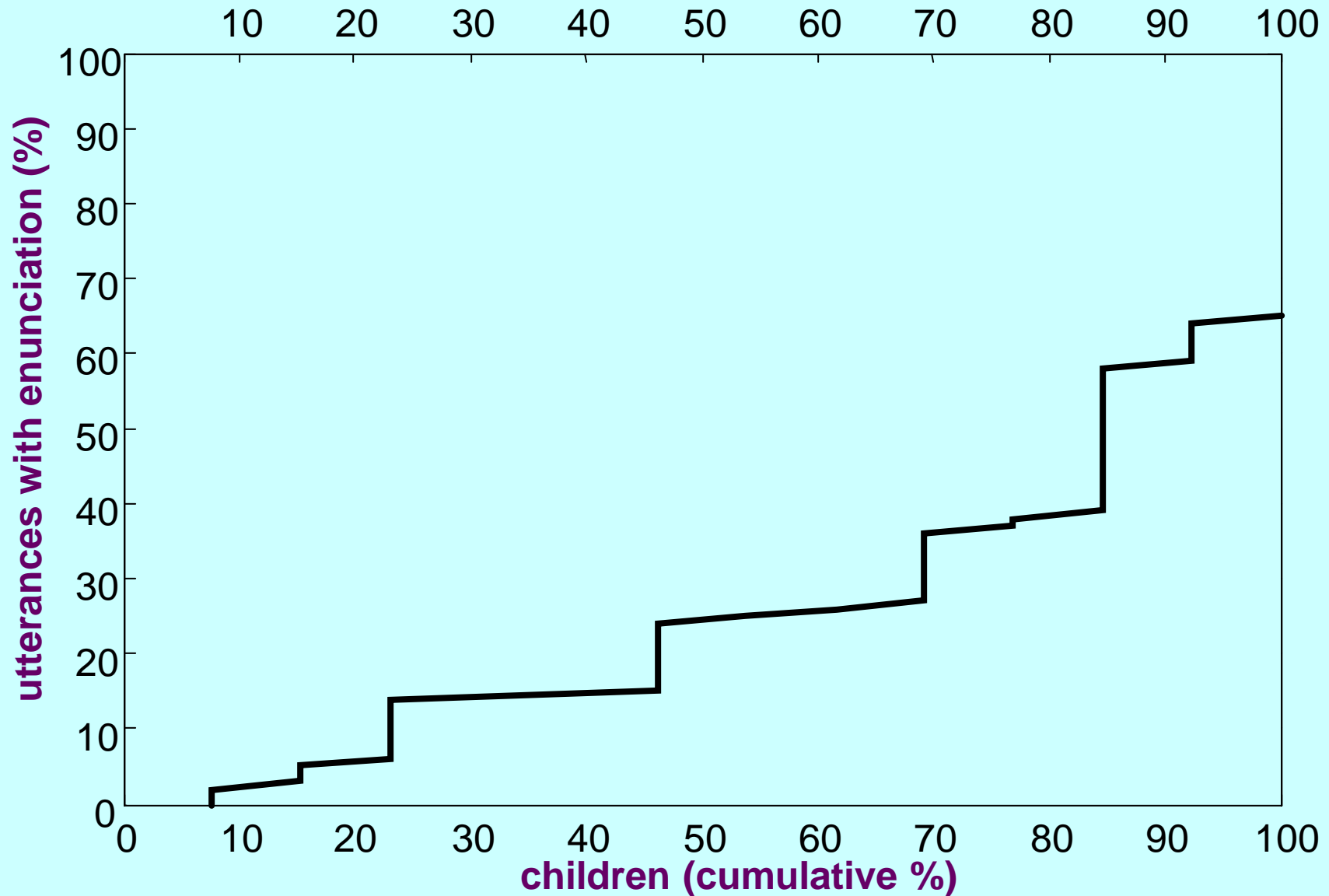
Number of Utterances



Single Word Utterances



Utterances with Enunciation



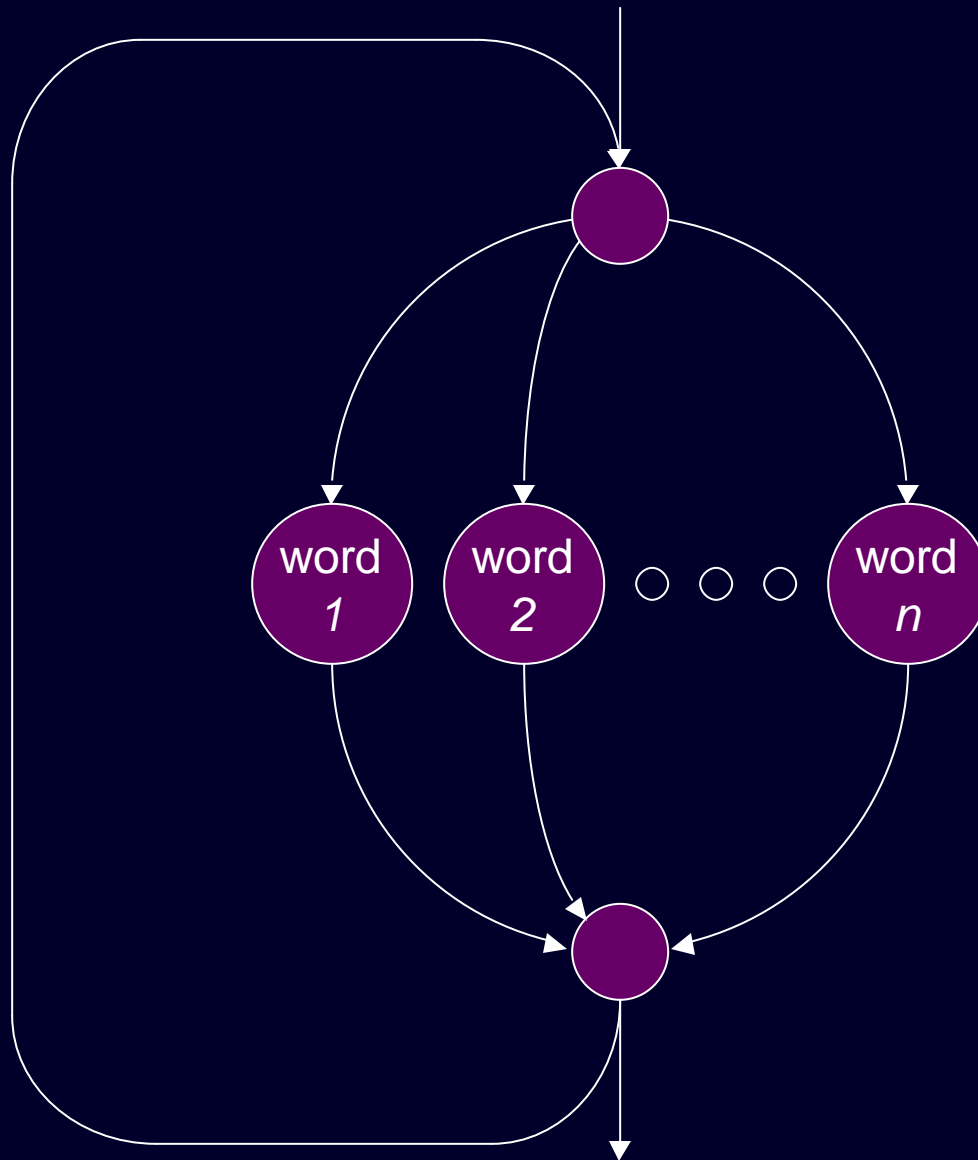
Cooperative Speech Exists

- Some clean word-learning scenarios
 - "Tiffany"
- Can we use them as leverage?
 - "My name is Tiffany"
- What recognition rates are possible?

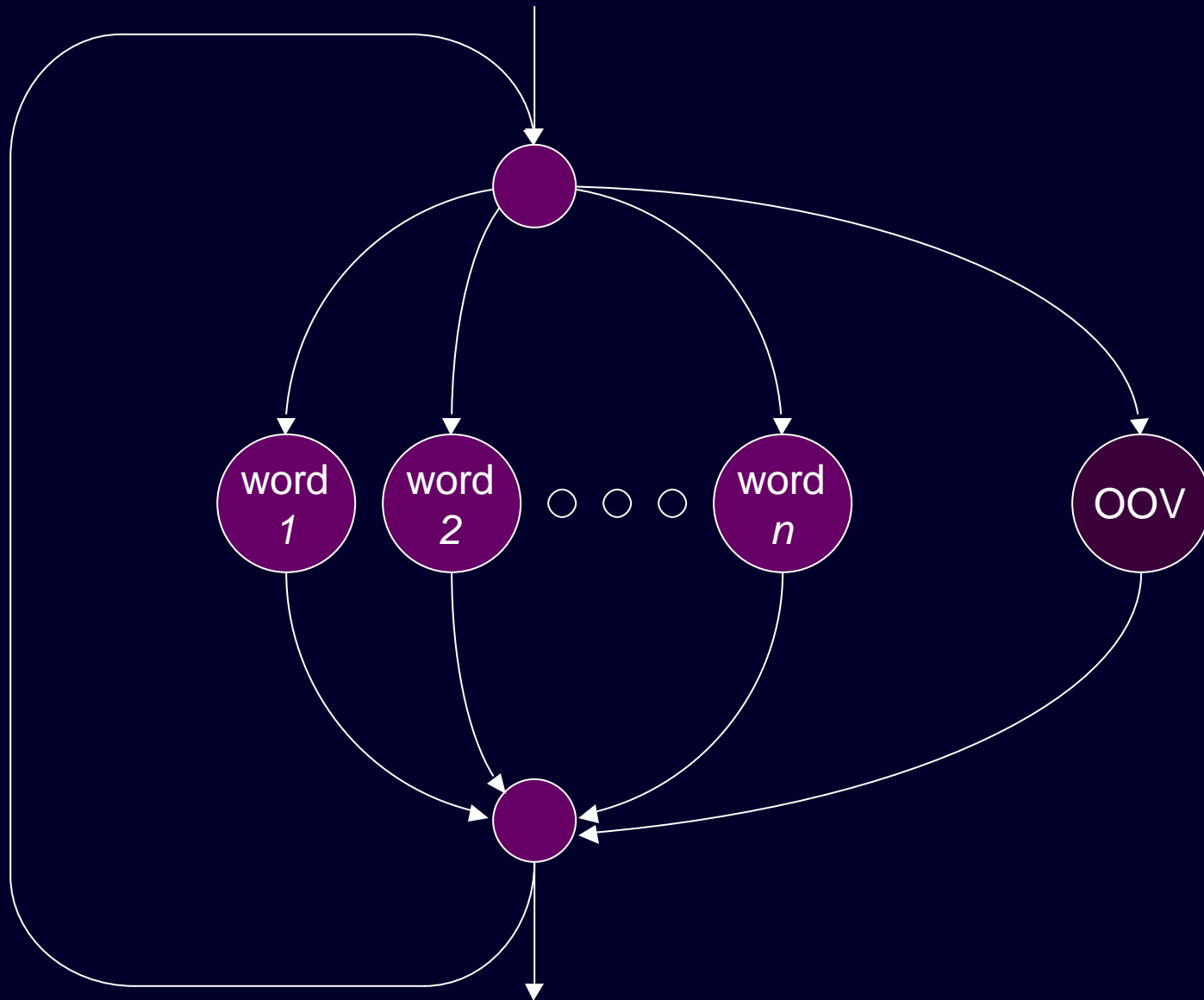
Study: Processing Speech

- “LCSINFO” domain (*Glass, Weinstein*)
- Provide some initial vocabulary
- Build language model without transcripts

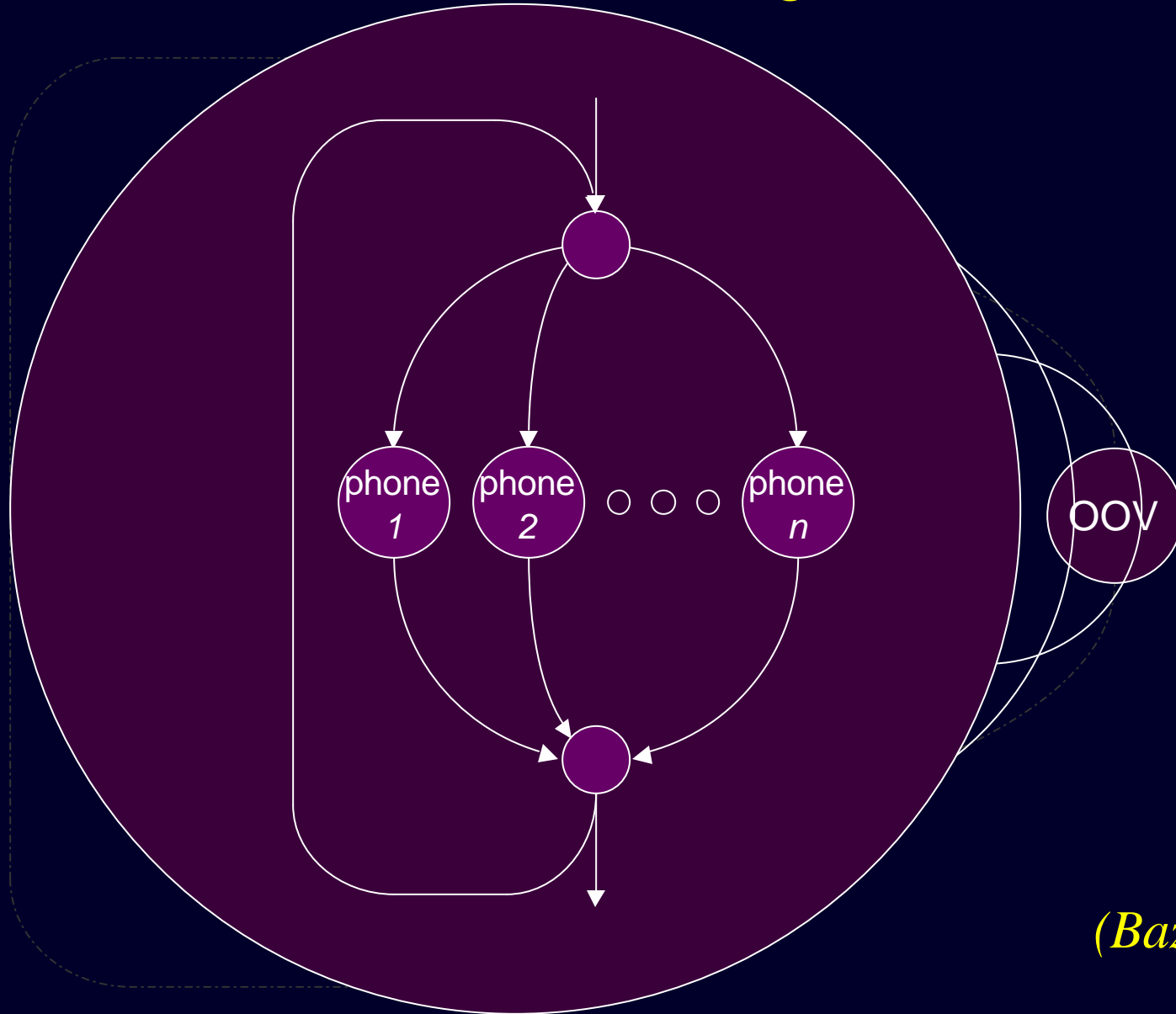
Language Model



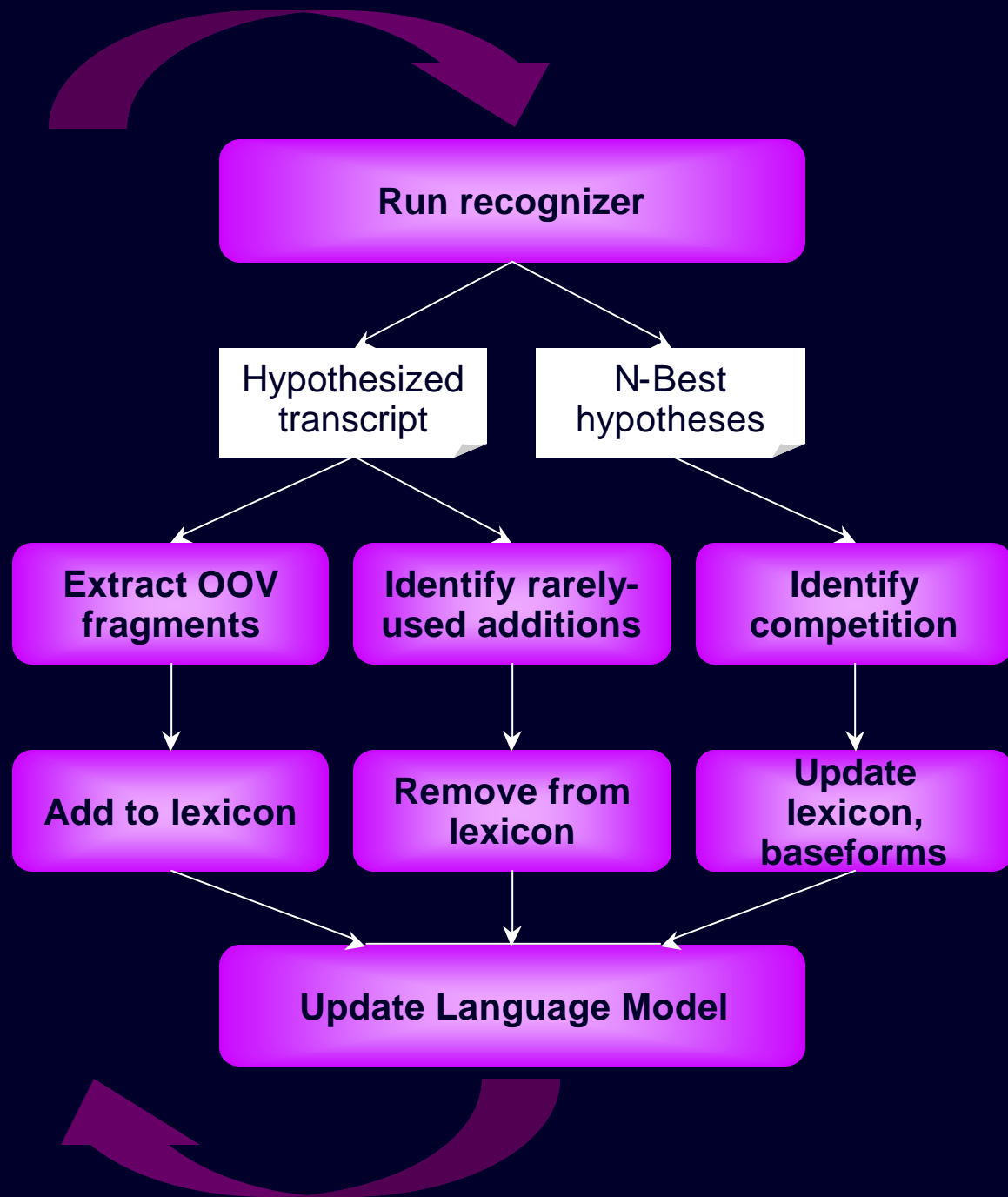
Out Of Vocabulary Model

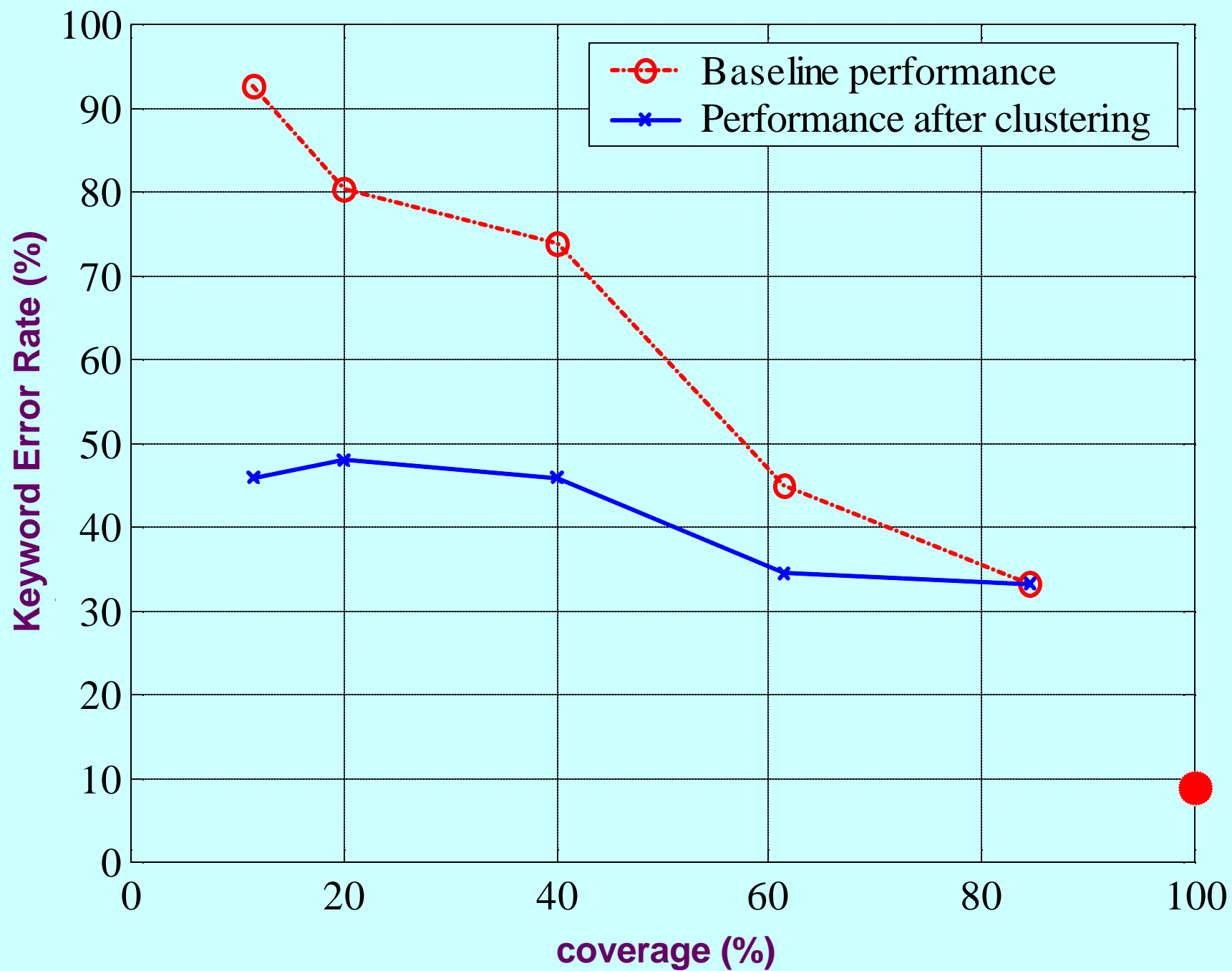


Out Of Vocabulary Model



(Bazzi)





Qualitative Results

Given:

1600 Utterances

"email, phone, room, office, address"

Finds:

- | | | | |
|----|-------------|-----|---------------|
| 1. | n ah m b er | 6. | p l iy z |
| 2. | w eh r ih z | 7. | ae ng k y uw |
| 3. | w ah t ih z | 8. | n ow |
| 4. | t eh l m iy | 9. | hh aw ax b aw |
| 5. | k ix n y uw | 10. | g r uw p |

Conclusions

- What about acoustic models?
- Idiosyncratic vocabulary is important
- Pick a good name for your robot!

Acknowledgements

- MIT Initiative on Technology and Self
- MIT Spoken Language Systems group
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- NTT