

# Applications

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# Overview

- Denoising
- Tone mapping
- Relighting & texture editing



# Overview

- **Denoising**

Not most powerful application  
Not best denoising, but good & simple



- Tone mapping



- Relighting & texture editing



# Basic denoising

Noisy input



Bilateral filter 7x7 window



# Basic denoising

Bilateral filter



Median 3x3



# Basic denoising

Bilateral filter



Median 5x5



# Basic denoising

Bilateral filter



Bilateral filter – lower sigma



# Basic denoising

Bilateral filter



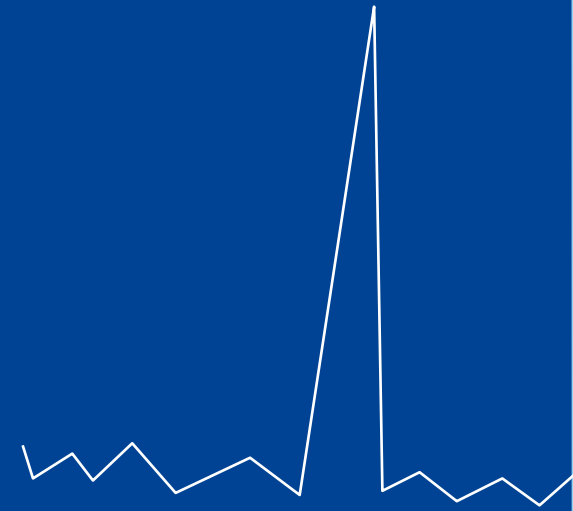
Bilateral filter – higher sigma





# Impulse noise

- High amplitude noise at few pixels
- Outlier rejection of bilateral filter works too well
  - the noise is treated as a strong edge
- Solution:
  - Pre-filter with median filter
  - Use median-filtered image  $M$  as reference for range Gaussians



$$BF[I]_{\mathbf{p}} = \frac{1}{W_{\mathbf{p}}} \sum_{\mathbf{q} \in \mathcal{S}} G_{\sigma_s}(\|\mathbf{p} - \mathbf{q}\|) G_{\sigma_r}(\|\mathbf{M}_{\mathbf{p}} - I_{\mathbf{q}}\|) I_{\mathbf{q}}$$

# Denoising

- Small spatial sigma (e.g. 7x7 window)
- Adapt range sigma to noise level
- Maybe not best denoising method, but best simplicity/quality tradeoff
  - No need for acceleration (small kernel)
  - But the denoising feature in e.g. Photoshop is better
- Pre-filter with median for impulse noise



# Overview

- Denoising



- **Tone mapping**



- Relighting & texture editing



# Real world dynamic range

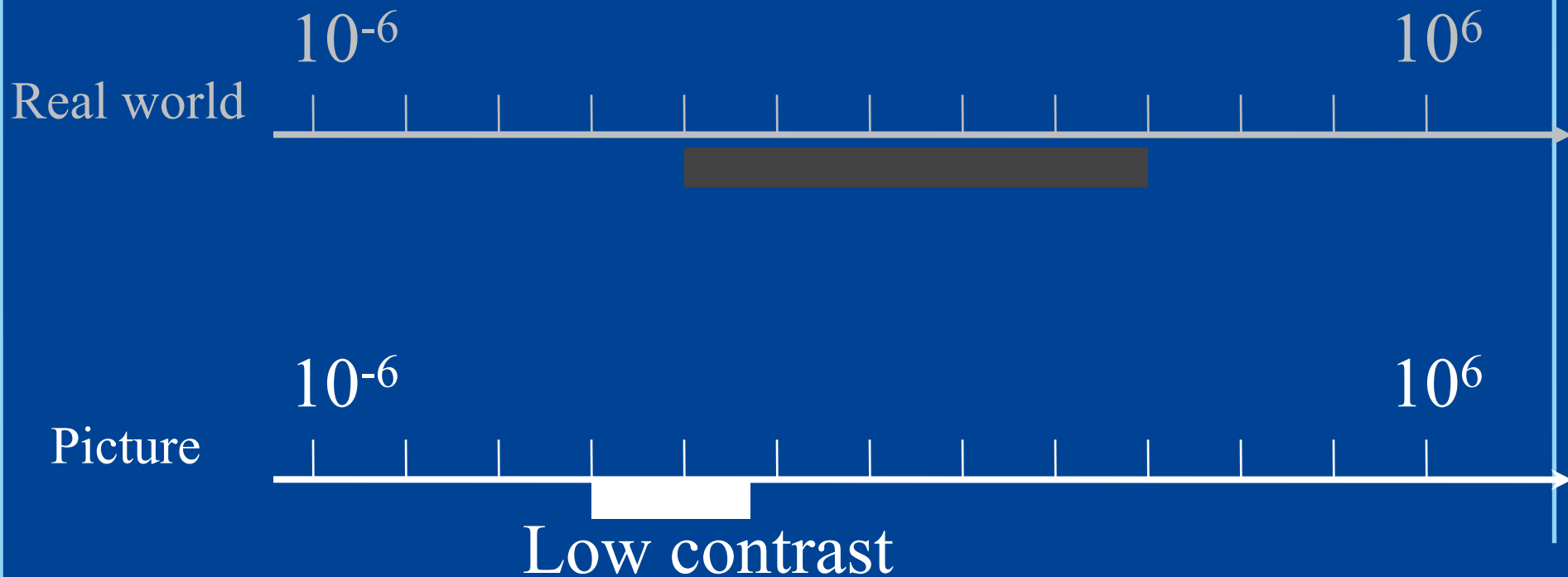
- Eye can adapt from  $\sim 10^{-6}$  to  $10^6$  cd/m<sup>2</sup>
- Often 1 : 10,000 in a scene



# Picture dynamic range

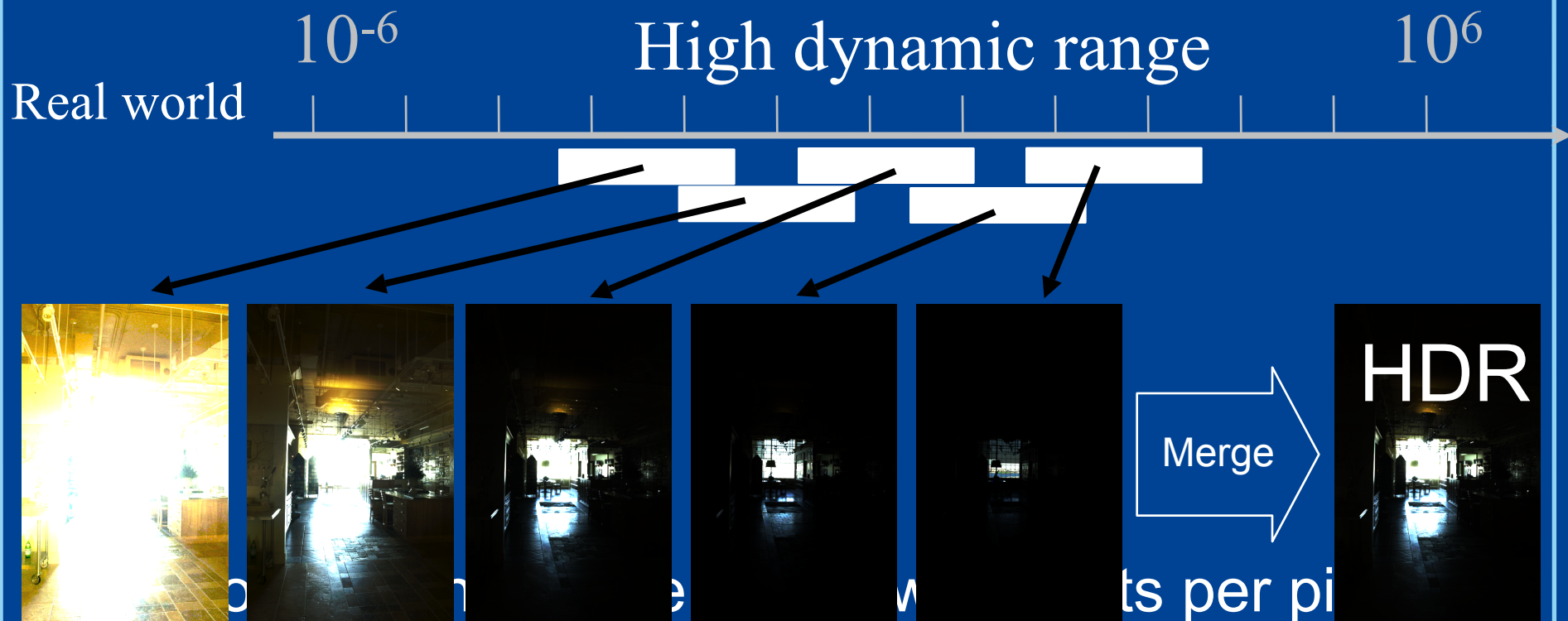
- Typically 1: 20 or 1:50

— Black  is ~ 50x darker than white 



# Multiple exposure photography

- Merge multiple exposure to cover full range



— But we still can't display it

# The future: HDR Cameras

- HDR sensors using CMOS

- Use a log response curve
- e.g. SMaL,

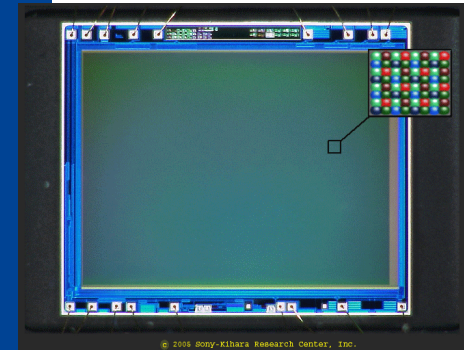


- Assorted pixels

- Fuji
- Nayar et al.

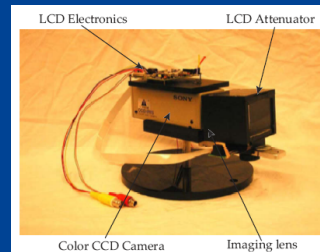


Fuji SuperCCD



- Per-pixel exposure

- Filter
- Integration time



Conventional Camera (without ADR)



Camera with Adaptive Dynamic Range (ADR)



Camera with Adaptive Transmittance Function (LCD Input)

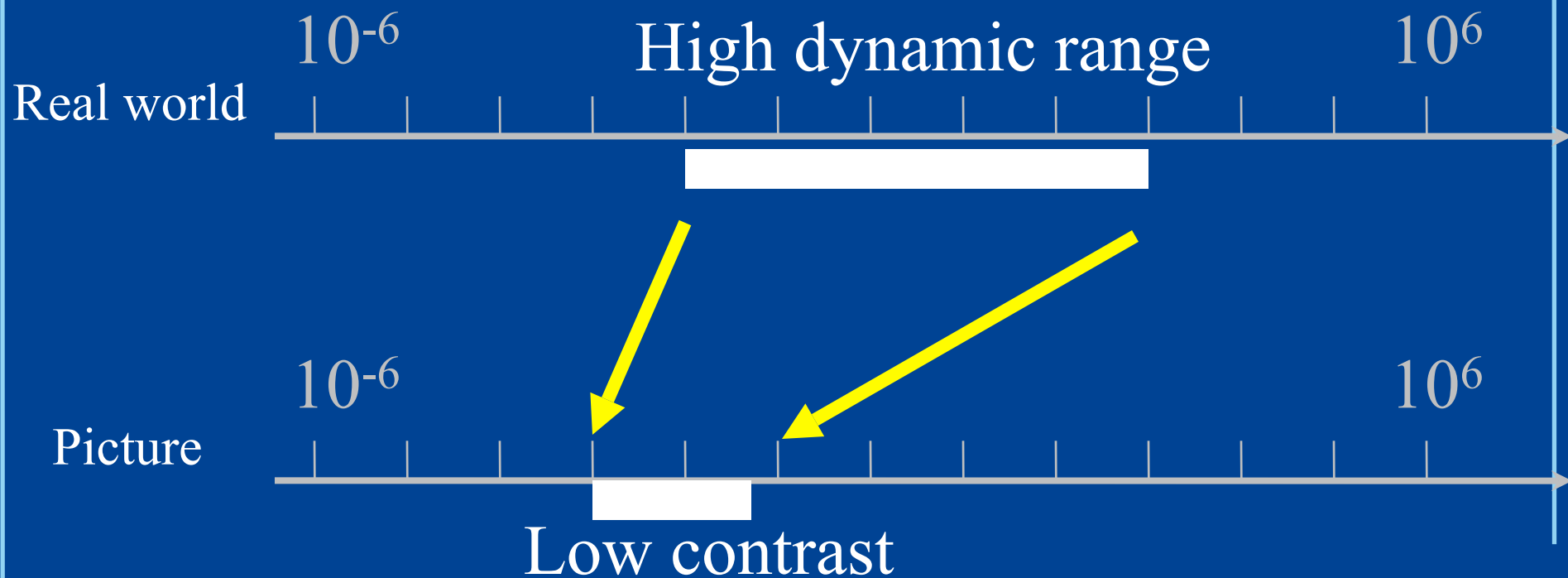


- Multiple cameras using beam splitters

- Other computational photography tricks

# Problem: Contrast reduction

- Match limited contrast of the medium
- Preserve details





# Tone mapping

- Input: high-dynamic-range image
  - (floating point per pixel)



# Naïve technique

- Scene has  $1:10,000$  contrast, display has  $1:100$
- Simplest contrast reduction?



# Naïve: Gamma compression

- $X \rightarrow X^\gamma$  (where  $\gamma=0.5$  in our case)
- But... colors are washed-out. Why?

Input



Gamma



# Gamma compression on intensity

- Colors are OK,  
but details (intensity high-frequency) are blurred

Intensity



Gamma on intensity



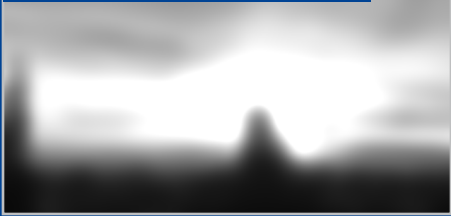
Color



# Oppenheim 1968, Chiu et al. 1993

- Reduce contrast of low-frequencies (log domain)
- Keep high frequencies

Low-freq.



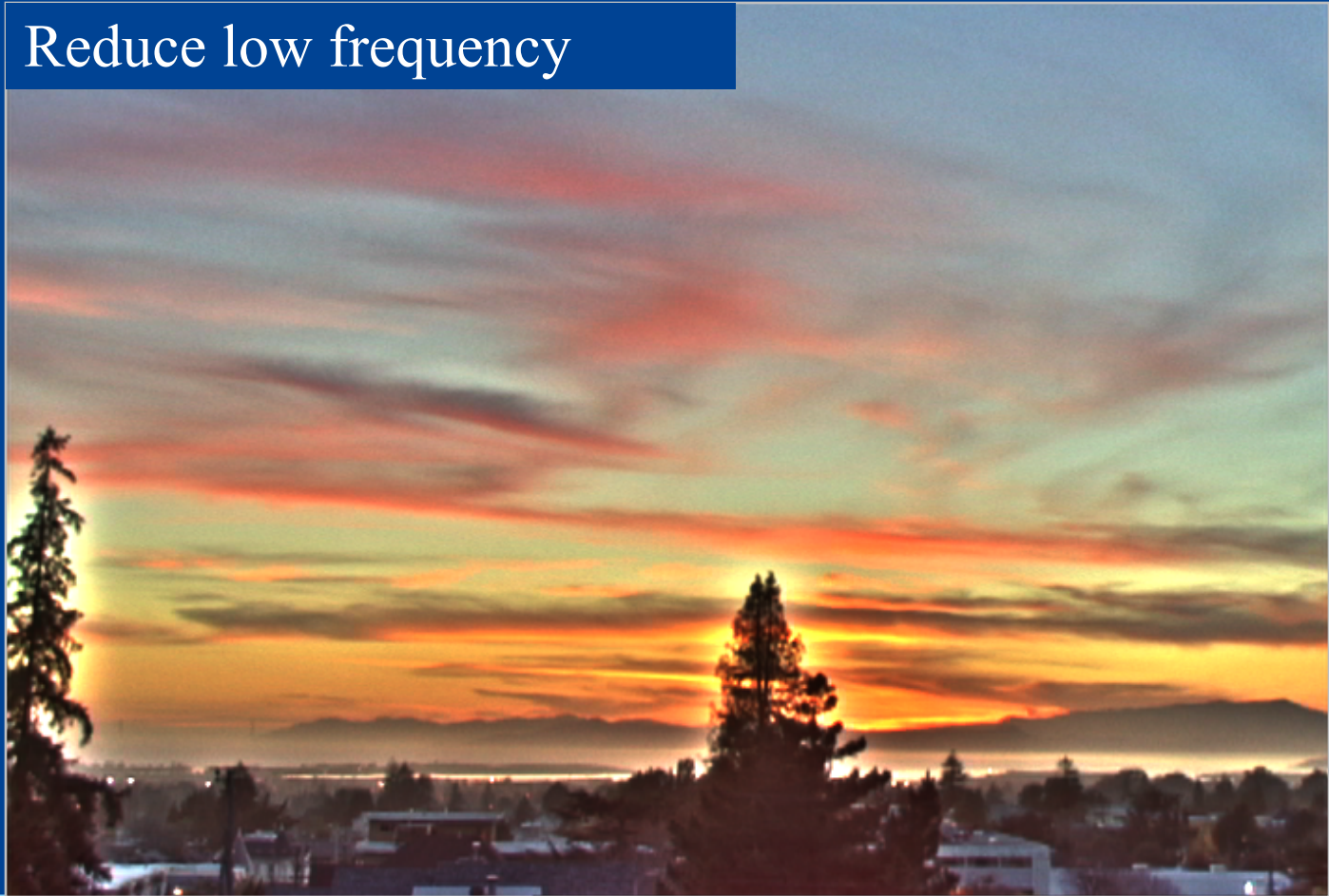
High-freq.



Color



Reduce low frequency



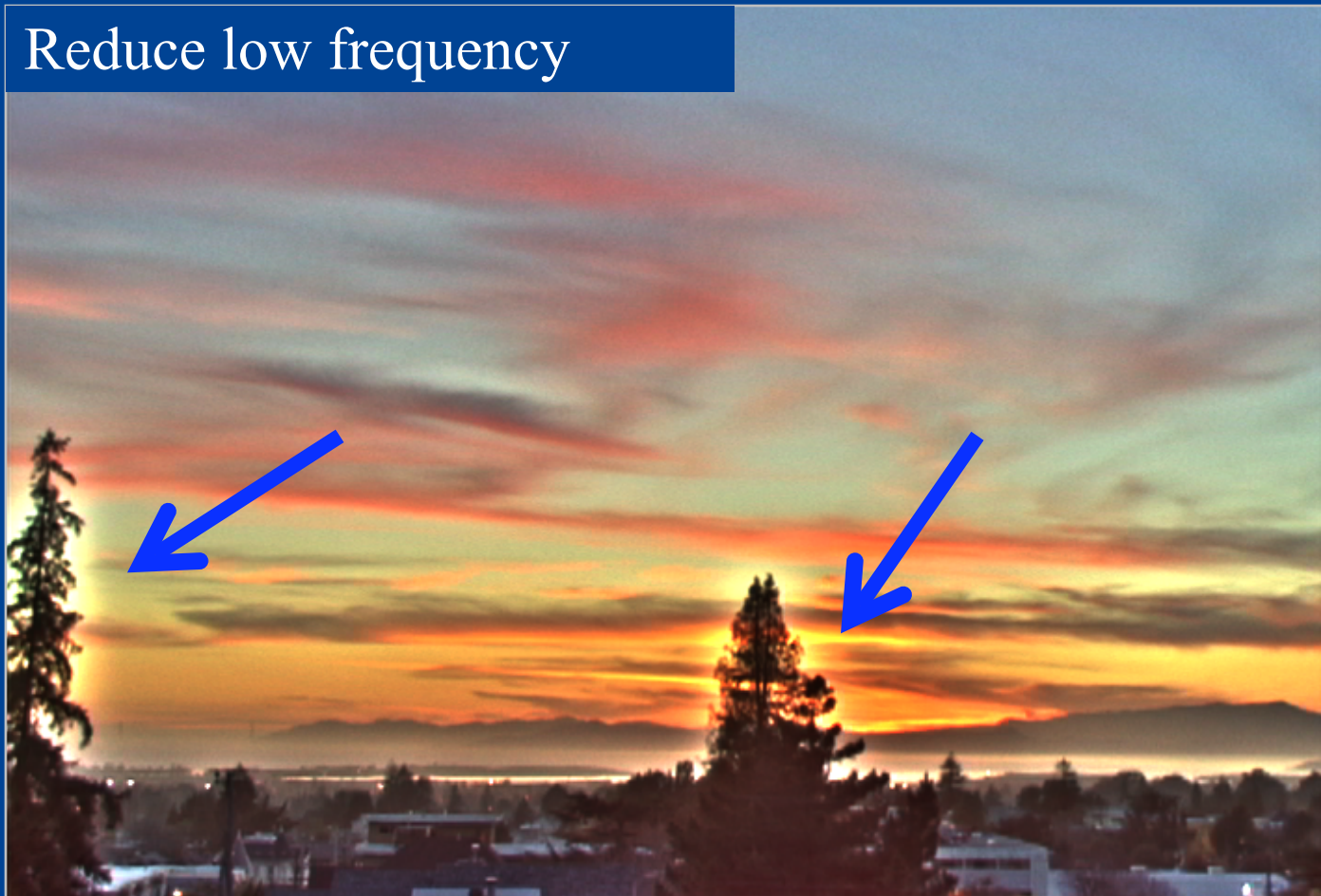
# The halo nightmare

- For strong edges
- Because they contain high frequency

Low-freq.



Reduce low frequency



High-freq.



Color

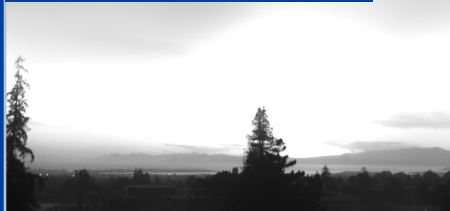


# Bilateral filtering to the rescue

- Large scale = bilateral (log intensity)
- Detail = residual

[Durand & Dorsey 2002]

Large-scale



Detail



Color



Output



# Contrast reduction

Input HDR image



Contrast  
too high!



# Contrast reduction

Input HDR image



Intensity



Color

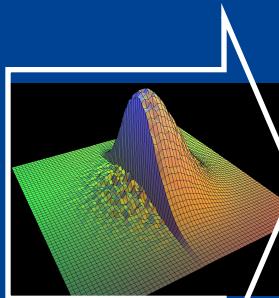


# Contrast reduction

Input HDR image



Intensity



Large scale



Bilateral  
Filter  
(in log domain!)

Spatial sigma: 2 to 5% image size  
Range sigma: 0.4 (in log 10)

Color

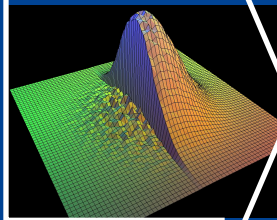


# Contrast reduction

Input HDR image



Intensity



Bilateral  
Filter

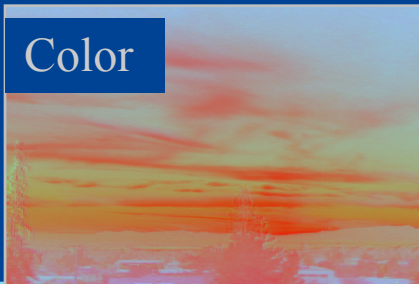
Large scale



Detail



Color



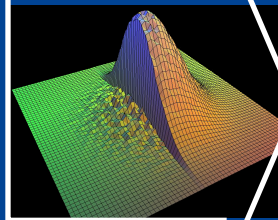
Detail = log intensity – large scale  
(residual)

# Contrast reduction

Input HDR image



Intensity



Bilateral  
Filter

Large scale

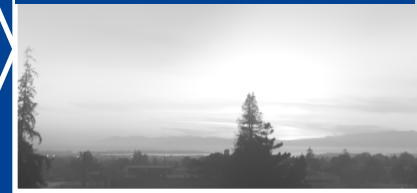


Detail

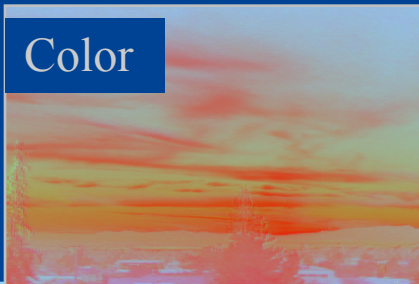


Reduce  
contrast

Large scale



Color

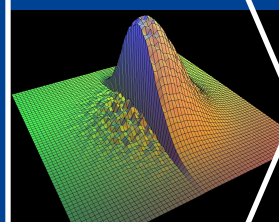


# Contrast reduction

Input HDR image



Intensity



Bilateral  
Filter

Large scale



Detail



Reduce  
contrast

Preserve!

Large scale



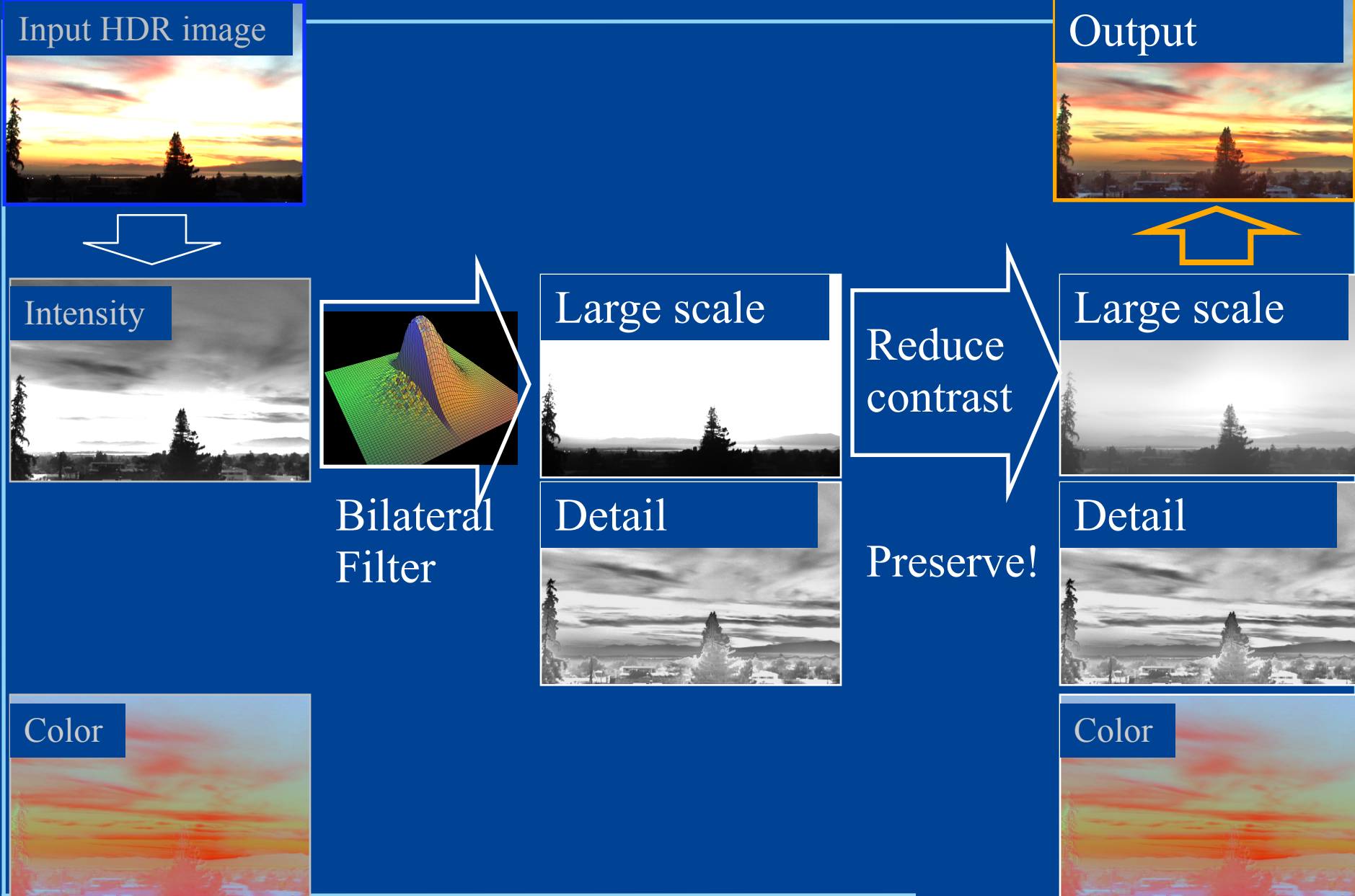
Detail



Color



# Contrast reduction



# Contrast reduction **in log domain**

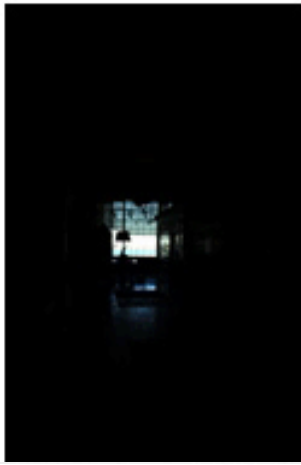
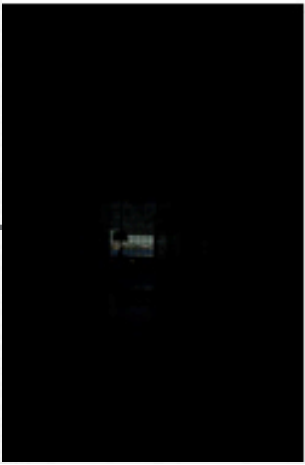
- Set target large-scale contrast (e.g.  $\log_{10} 10$ )
  - In **linear** output, we want 1:10 contrast for large scale
- Compute range of input large scale layer:
  - $\text{largeRange} = \max(\text{inLogLarge}) - \min(\text{inLogLarge})$
- Scale factor  $k = \log_{10}(10) / \text{largeRange}$
- Normalize so that the biggest value is 0 in log

$$\text{outLog} = \text{inLogDetail} + \text{inLogLarge} * k - \max(\text{inLogLarge})$$

# Alternative explanation

- Explanation 1 (previous slides):
  - $\text{outLog} = k \text{ inLogLarge} + \text{inLogDetail}$  (ignoring offset)
- Explanation 2
  - $\text{outLog} = k \text{ inLogIntensity} + (1-k) \text{ detail}$
  - Reduce contrast of full intensity layer
  - Add back some detail
- Same final effect since
  - $\text{inLogDetail} + \text{inLogLarge scale} = \text{inLogIntensity}$
  - But different philosophy:  
decomposition vs. add back detail





# Denoising vs. tone mapping

- Denoising:
  - decompose into noise+signal
  - Throw away noise, keep signal
  - Small kernel
- Tone mapping
  - Decompose into large scale + detail
  - Preserve detail, reduce large scale
    - Opposite of denoising!
  - Large kernel
    - because detail=high+medium frequency
    - →computation challenge



# Crossing lines

- The bilateral filter is influenced by pixels across thin line
- Good for tone mapping

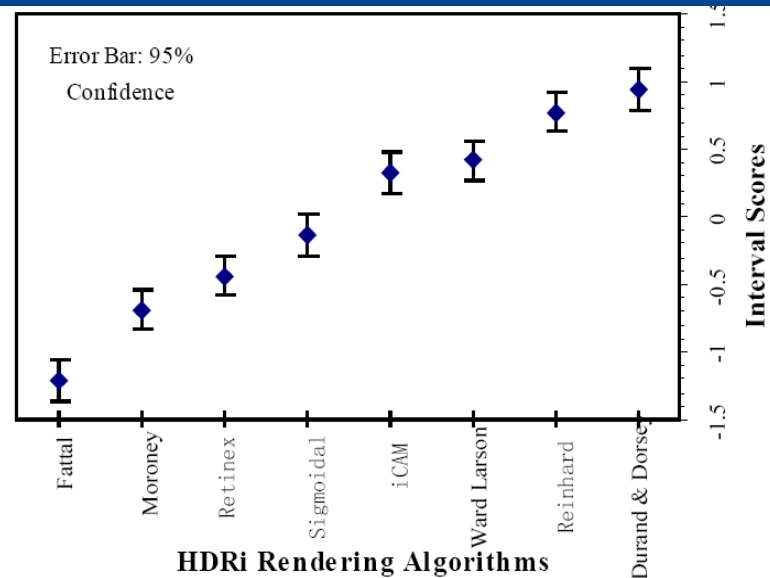


# What matters

- Spatial sigma: not very important
- Range sigma: quite important
- Use of the log domain for range: **critical**
  - Because HDR and because perception sensitive to multiplicative contrast
  - CIE Lab might be better for other applications
- Luminance computation
  - Not critical, but has influence
  - see our Flash/no-flash paper [Eisemann 2004] for smarter function

# Tone mapping evaluation

- Recent user experiments to evaluate competing tone mapping
  - Ledda et al. 2005 <http://www.cs.bris.ac.uk/Publications/Papers/2000255.pdf>
  - Kuang et al. 2004 <http://www.cis.rit.edu/fairchild/PDFs/PRO22.pdf>
- Interestingly, the former concludes bilateral is the worst, the latter that it is the best!
  - They choose to test a different criterion: fidelity vs. preference
- More importantly, they focus on algorithm and ignore parameters



From Kuang et al.

	1st	2nd	3rd	4th	5th	6th
Scene 1	P	B	A	H	I	L
Scene 2	I	P	H	A	B	L
Scene 3	P	I	A	H	L	B
Scene 4	P	L	I	A	H	B
Scene 5	I	H	A	P	L	B
Scene 6	I	H	A	P	L	B
Scene 7	I	A	P	H	B	L
Scene 8	I	P	A	H	L	B
Scene 9	P	A	L	H	B	I

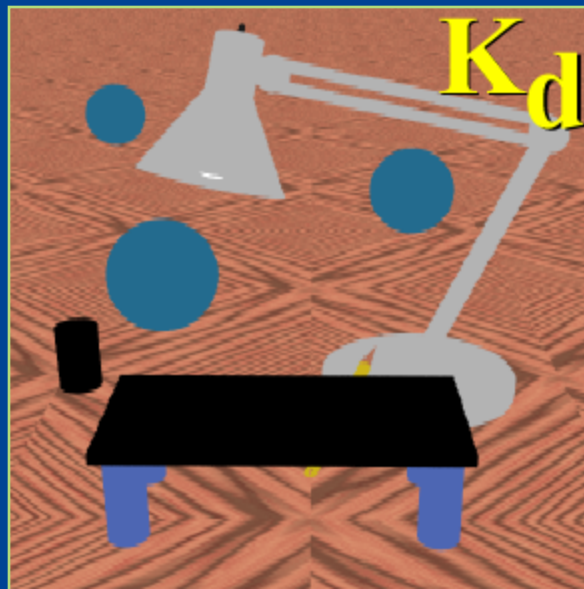
Adapted from Ledda et al.

# Alternative explanation

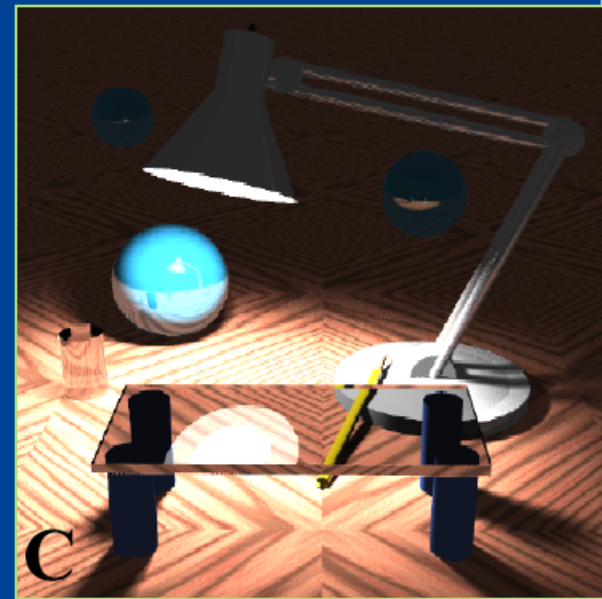
- Contrast reduction w/ intrinsic layers [Tumblin et al. 1999]
- For 3D scenes: Reduce only illumination layer



Illumination layer  
**Compressed**



Reflectance layer



Output

# Dirty vision for cool graphics

Three wrongs make one right

- Analyze image
  - Intrinsic image: albedo & illumination
  - Simple bilateral filter
- Modify
  - In our case, reduce contrast of large-scale (illumination)
- Recombine
  - Get final image



# Overview

- Denoising
- Tone mapping



- **Relighting & texture editing**





# Discounting Existing Lighting

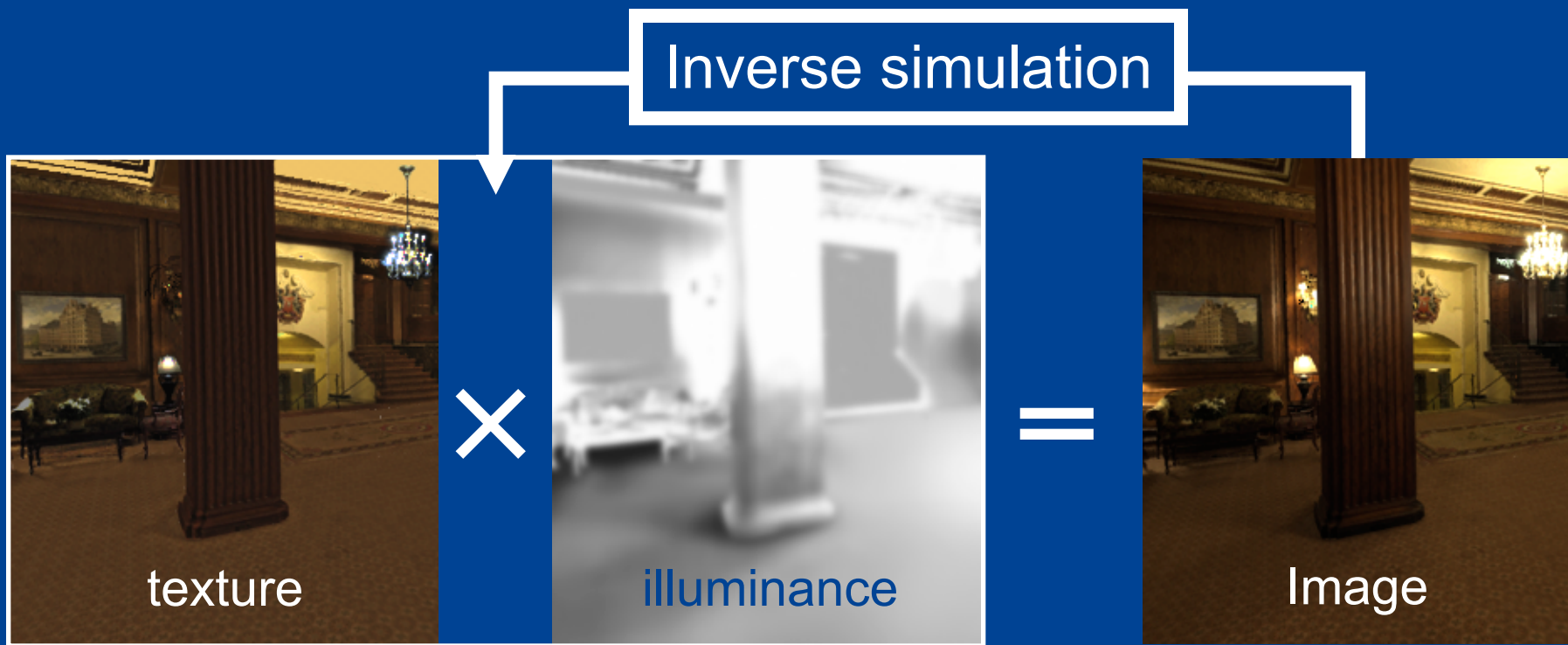
- Motivation
  - Relighting
  - Image manipulation (e.g. clone brush, texture synthesis)
- Context:
  - The following slides are from a project dealing with images +depth



# Inverse Lighting Simulation

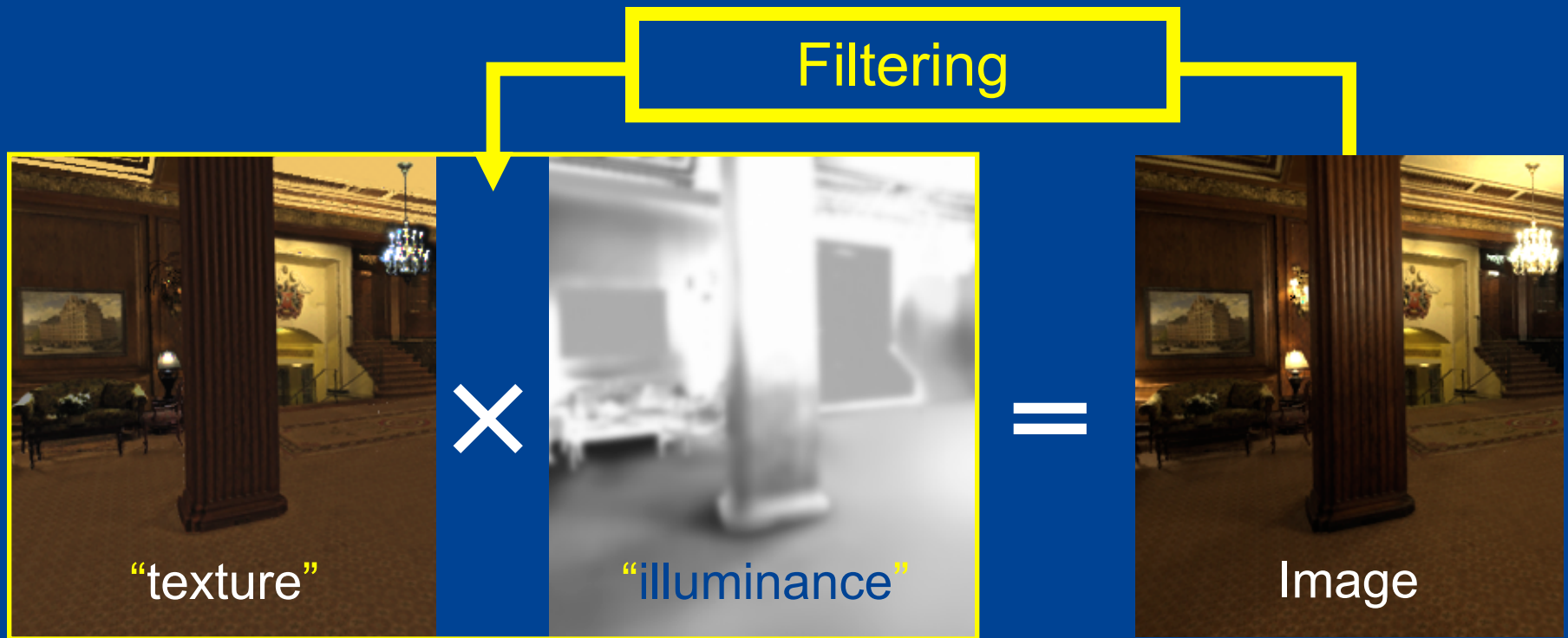
- Physically-based approaches

e.g. [Fournier et al.93, Drettakis et al.97, Debevec.98, Yu et al.99, Loscos et al. 99, Loscos et al.00]



# Texture-Illuminance Decoupling

- Not physically based
  - Our “texture” and “illuminance” are reasonable estimates



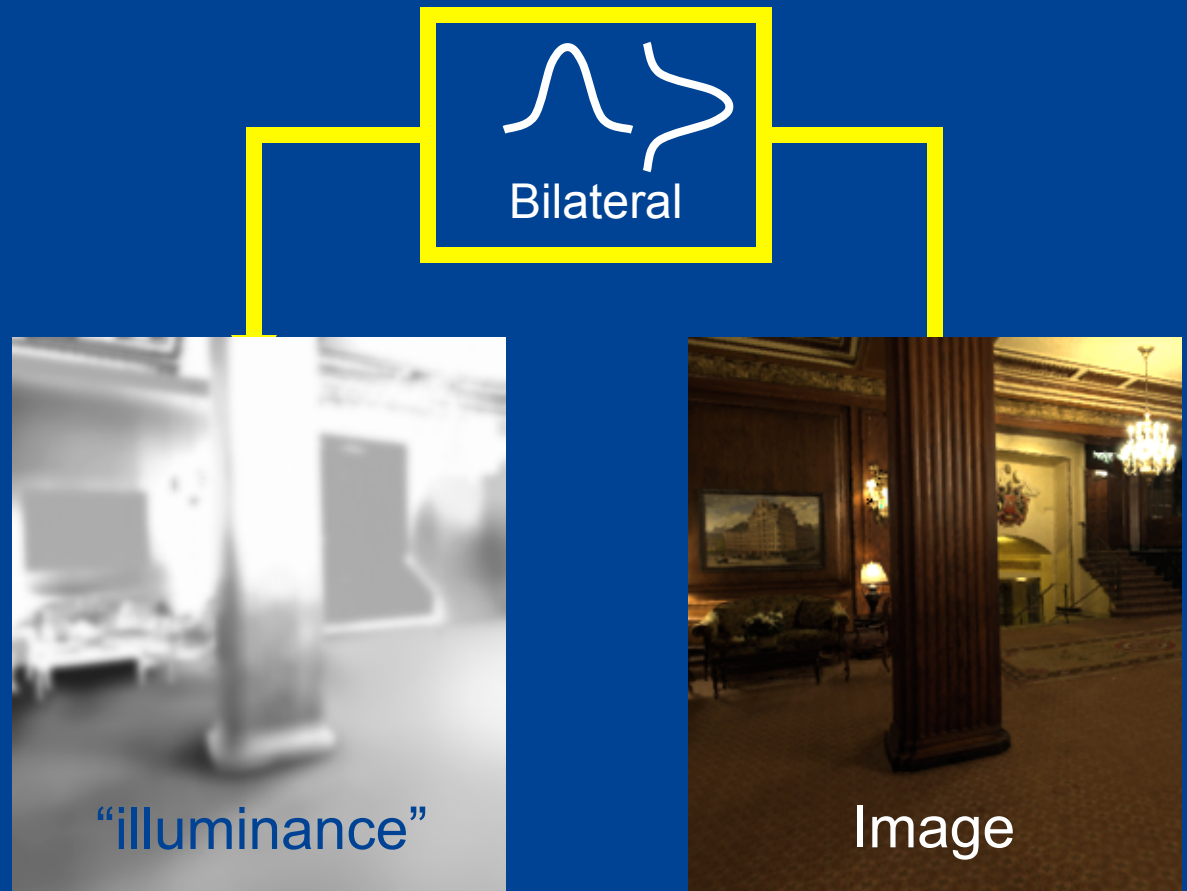
# Texture-Illuminance Decoupling

- Not physically based: Filtering
- Assumptions:
  - Small-scale features → “texture”
  - Large-scale features → “illuminance”



# General Idea

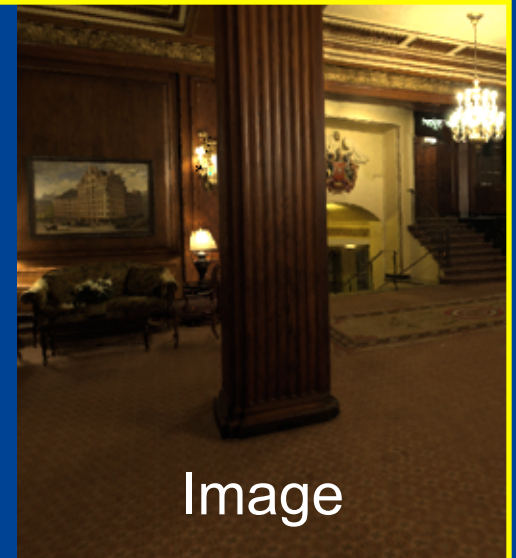
- Large-scale features using low-pass filter
  - Color is assumed to be from texture



# General Idea

- Extract texture from illuminance and input image

Division



# Edge-Preserving Filter

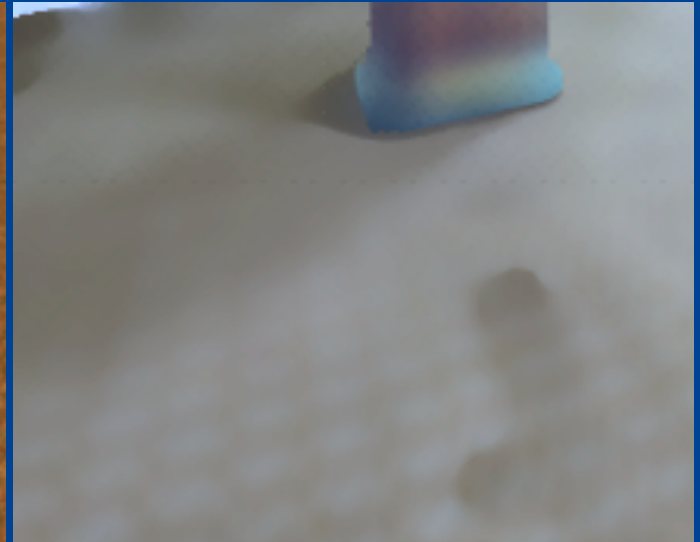
texture

illuminance

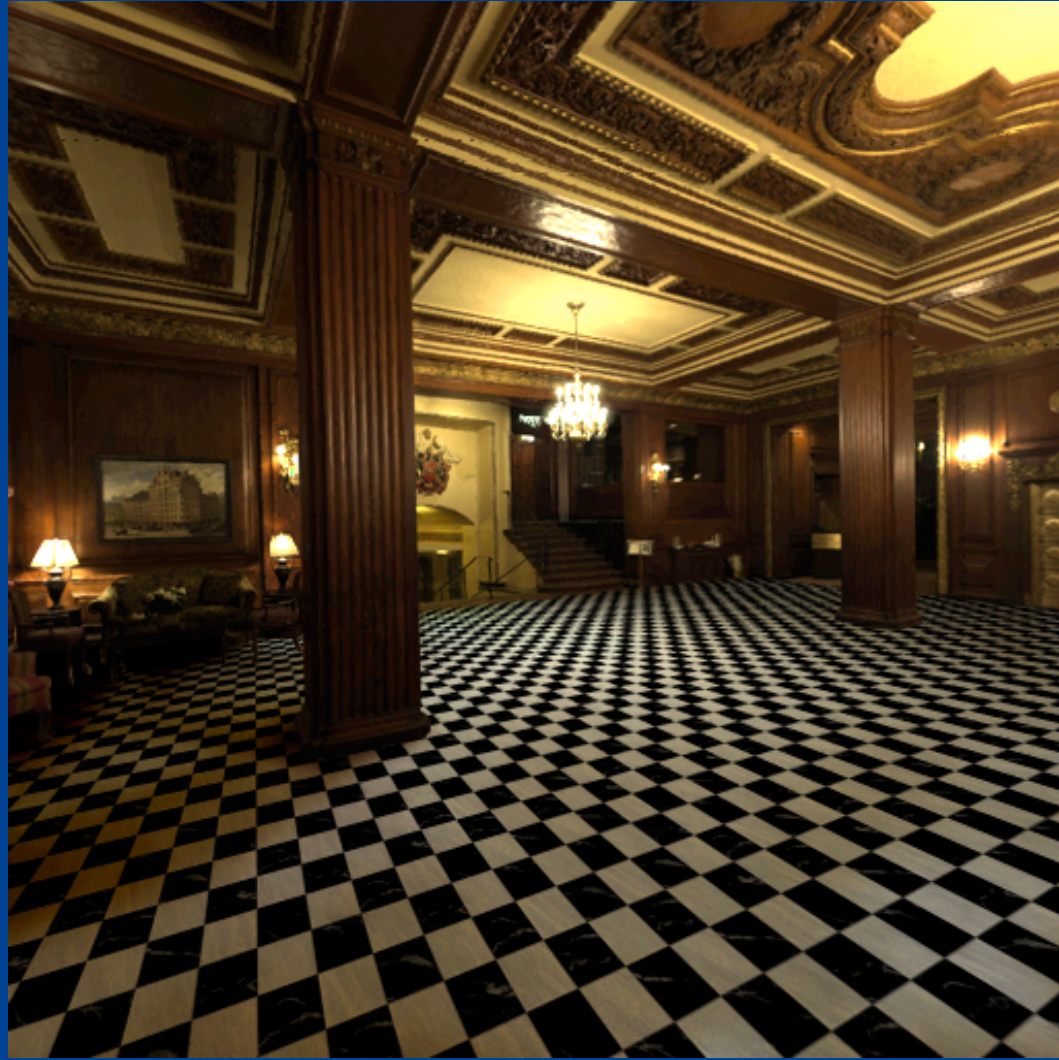
Naïve



Bilateral +  
foreshortening



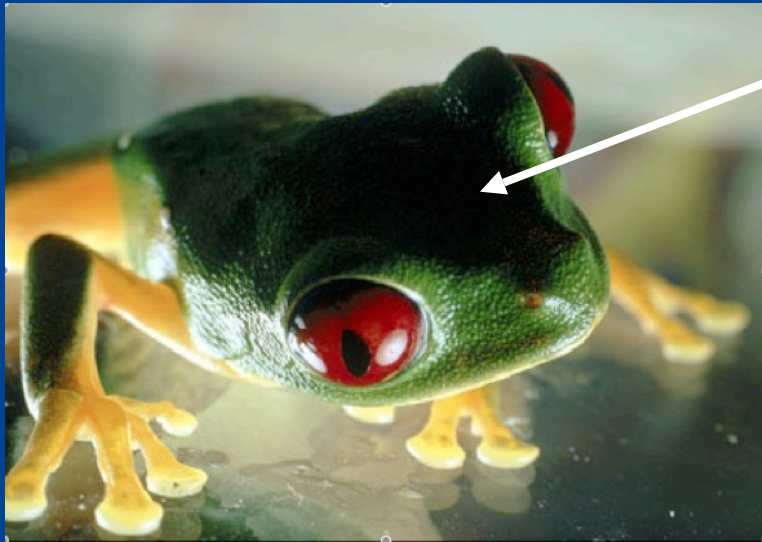
# Examples





# HDR hallucination

- *[Lvdi Wang, Liyi Wei, Kun Zhou, Baining Guo, Heung-Yeung Shum, EGSR 2007]*
- Low-dynamic-range images have under- and over-exposed parts
  - Information missing



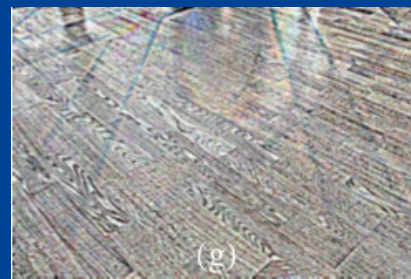
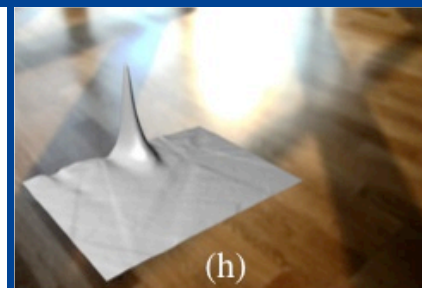
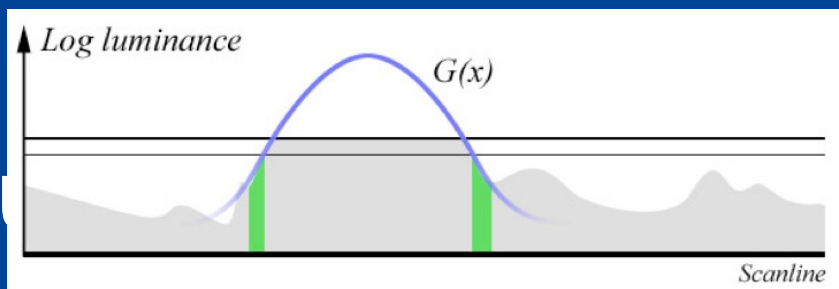
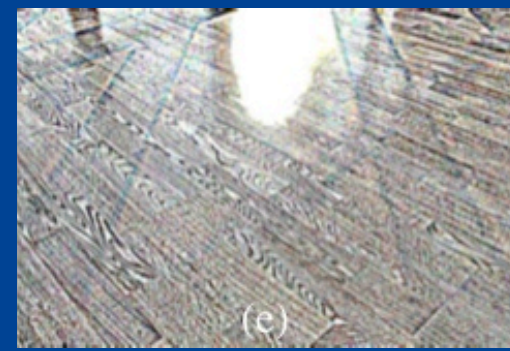
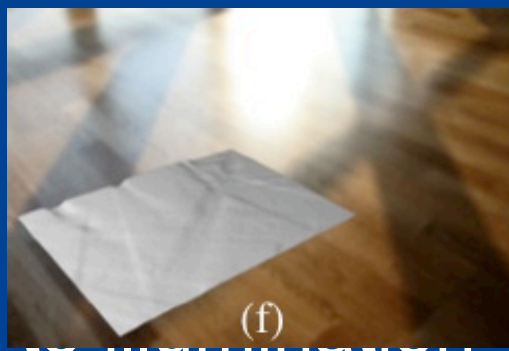
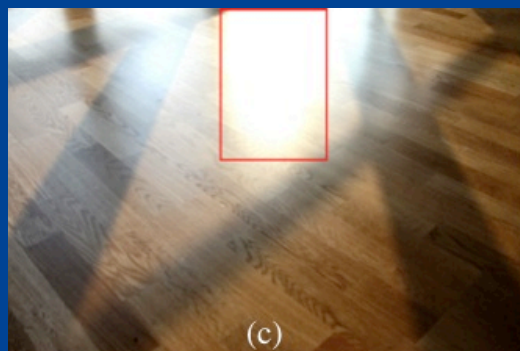
Under-  
exposed



Over-  
exposed

# HDR hallucination

- Separate illumination and texture (Bilateral!)



# HDR hallucination



input



output

# HDR hallucination



input



output

# Recap

- Decompose into
  - Large scale (with bilateral filter)
  - Detail (residual: medium+high frequencies)
    - Use big kernels
- Use appropriate domain (log for HDR)
- Manipulate/process independently
- Tone mapping
- Relighting, HDR hallucination
- HDR hallucination

