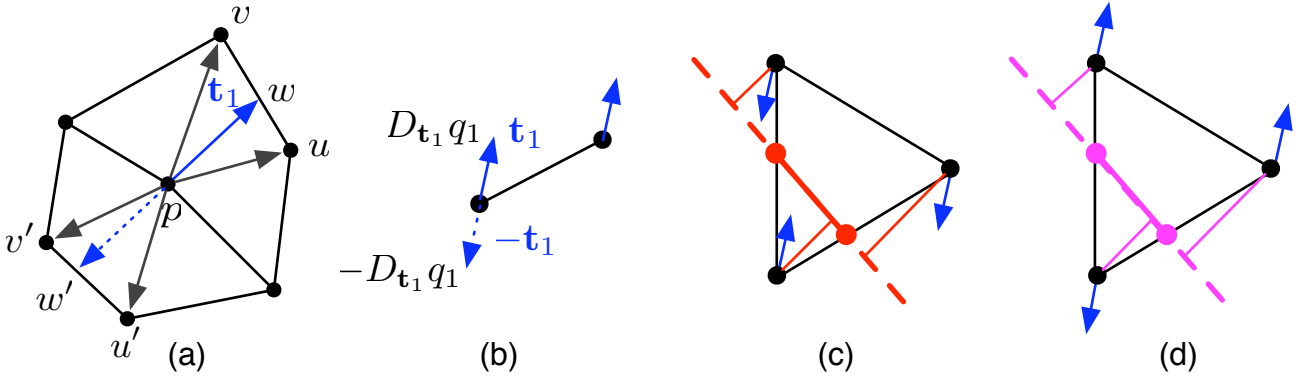
v
$\mathbf{t}_1$
w
u
p
v'
w'
u'
(a)
$D_{\mathbf{t}_1} q_1$
$\mathbf{t}_1$
$-\mathbf{t}_1$
$-D_{\mathbf{t}_1} q_1$
(b)
(c)
(d)