Tomasz Malisiewicz

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32 Vassar Street

Cambridge, MA 02139

Research Interests

My research focuses on building visual image understanding systems which can be used for robotic applications as well as organizing large online photo collections. A key goal of my research is to advance the state-of-the-art in visual object detection on real-world problems while utilizing ideas from machine learning, software engineering and psychology.

Education

Carnegie Mellon University, Pittsburgh PA

08/2005 - 08/2011

Ph.D in Robotics Advisor: Alexei A. Efros

Thesis: Exemplar-based Representations for Object Detection, Association and Beyond

Carnegie Mellon University, Pittsburgh PA

08/2005 - 12/2008

MS in Robotics (GPA 4.00)

Rensselaer Polytechnic Institute, Troy NY

08/2001 - 05/2005

B.S. Computer Science and Physics Dual Major & Math Minor (GPA 4.00)

Research Experience

CSAIL, Massachusetts Institute of Technology, Cambridge MA

09/2011 - current

Postdoctoral Research Associate

- Large-scale recognition and learning using videos
- 3D reconstruction using RGB-D sensors and recognition on mobile devices
- Working under the supervision of Antonio Torralba

Robotics Institute, Carnegie Mellon University

08/2005 - 08/2011

Graduate Research Assistant

- Developed object recognition and image segmentation algorithms
- Open sourced Exemplar-SVM framework for object detection: Exemplar-SVM on github
- Developed Visual Memex approach for reasoning about object relationships

Google, Mountain View CA

06/2009 - 09/2009

Software Engineering Intern in Computer Vision Research Group

- Discriminative Group Sparse Coding for Image Classification
- Worked under the supervision of Dr. Dennis Strelow

Google, Mountain View CA

06/2008 - 09/2008

Software Engineering Intern in Computer Vision Research Group

- Large Scale Segmentation and Recognition via MapReduce
- Worked under the supervision of Dr. Thomas Leung

École Normale Supérieure, Paris, France

03/2008 - 05/2008

Visiting Student Researcher in Willow Research Group

• Hosted by Prof. Jean Ponce and Prof. Andrew Zisserman

Rensselaer Polytechnic Institute Computer Science Department Undergraduate Research Assistant - Range Data Registration

05/2004 - 05/2005

- Development of range data registration algorithms in C++
- Worked under the supervision of Charles Stewart

Rensselaer Polytechnic Institute Computer Science Department

05/2003 - 09/2003

- Undergraduate Research Project Retinal Image Segmentation
 Cross-Platform Software Engineering using CMake
 - Medical Imaging/Image Processing using VXL/ITK C++ Libraries/Toolkits

Brookhaven National Laboratory, Upton NY

06/2002 - 09/2002

Energy Research Undergraduate Laboratory Fellowship

- Modeled Relativistic Muons in Electromagnetic Rings via Object Oriented Techniques
- Studied Numerical Solutions to Partial Differential Equations

Teaching Experience

Skolkovo Tech Innovation Workshop at MIT

08/2012 and 08/2013

Computer Vision Technology Consultant

- Helped students get familiar with state-of-the-art object detection techniques
- Consulted two teams using computer vision technology for their final project

Robotics Institute, Carnegie Mellon University

01/2009 - 05/2009

Graduate Teaching Assistant - Learning Based Methods in Vision (Taught by Alexei Efros)

Robotics Institute, Carnegie Mellon University

08/2006 - 12/2006

 ${\it Graduate Teaching Assistant - Graduate Computer \ Vision \ (Taught \ by \ Martial \ Hebert)}$

Rensselaer Polytechnic Institute CS Dept

01/2004 - 05/2004, 01/2003-05/2003

Undergraduate Teaching Assistant - Computer Science II

Rensselaer Polytechnic Institute CS Dept

09/2003 - 12/2003

Undergraduate Teaching Assistant - Data Structures and Algorithms

Rensselaer Polytechnic Institute, Advising and Learning Center

09/2001 - 05/2002

Tutor - Computer Science, Physics, Calculus

Publications

C. Vondrick, A. Khosla, T. Malisiewicz, A. Torralba. "HOGgles: Visualizing Object Detection Features". In ICCV, December 2013.

A. Khosla, T. Zhou, T. Malisiewicz, A. A. Efros, A. Torralba. "Undoing the Damage of Dataset Bias". In ECCV, October 2012.

T. Malisiewicz, A. Shrivastava, A. Gupta, and A. A. Efros. "Exemplar-SVMs for Visual Object Detection, Label Transfer and Image Retrieval. Extended Abstract, ICML, July 2012.

A. Shrivastava, T. Malisiewicz, A. Gupta, A. A. Efros. "Data-driven Visual Similarity for Cross-domain Image Matching." In SIGGRAPH ASIA, December 2011.

- T. Malisiewicz, A.Gupta, A. A. Efros. "Ensemble of Exemplar-SVMs for Object Detection and Beyond." In ICCV, November 2011.
- T. Malisiewicz, A. A. Efros. "Beyond Categories: The Visual Memex Model for Reasoning About Object Relationships." In NIPS, December 2009.
- T. Malisiewicz, A. A. Efros. "Recognition by Association via Learning Per-exemplar Distances." In CVPR, June 2008.

- T. Malisiewicz, A. A. Efros. "Improving Spatial Support for Objects via Multiple Segmentations." In BMVC, September 2007.
- B. King, T. Malisiewicz, C. Stewart, R. Radke. "Registration of Multiple Range Scans as a Location Recognition Problem: Hypothesis Generation, Refinement and Verification." In 3DIM, June 2005.

Technical Reports

- C. Vondrick, A. Khosla, T. Malisiewicz and A. Torralba. "Inverting and Visualizing Features for Object Detection. arXiv Technical Report. December, 2012.
- M. Gharbi, T. Malisiewicz, S. Paris and F. Durand. "A Gaussian Approximation of Feature Space for Fast Image Similarity". MIT CSAIL Technical Report, October 2012.
- T. Malisiewicz "Exemplar-based Representations for Object Detection, Association and Beyond" CMU PhD Thesis, August 2011.
- T. Malisiewicz, J. C. Huang and A. A. Efros, "Detecting Objects via Multiple Segmentations and Latent Topic Models" CMU Technical Report, 2006.
- J. C. Huang and T. Malisiewicz "Fitting a Hierarchical Logistic Normal Distribution" CMU Technical Report, 2006.

Invited Talks

Exemplar-SVMs for Visual Image Matching and Object Detection		
Google Research, Mountain View, CA	May $8, 2013$	
Brown University, Department of Computer Science	April 30, 2013	
Exemplar-SVMs for Visual Object Detection, Label Transfer and Image Retrieval		
MIT Lincoln Labs, LISC Seminar	July 20, 2012	
ICML 2012 Invited Applications Talk	June 29, 2012	
Boston University, School of Computer Science	April 12, 2012	
Data-driven Visual Similarity for Cross-domain Image Matching		
Large Scale Multimedia Search Workshop, IPAM/UCLA	January 9, 2012	
MIT Graphics Group Seminar	December 7, 2011	
Per-exemplar learning: Object Detection and Beyond		
Kernels and Distances Workshop, ICCV 2011	November 13, 2011	
Ensemble of Exemplar-SVMs for Object Detection and Beyond		
MIT Computer Vision Group Seminar	September 20, 2011	
Recognizing and Interpreting Objects with the Visual Memex		
PhD Thesis Defense, Carnegie Mellon University	August 8, 2011	
Recognition by Association		
CMU Machine Learning Department Learning Lunch	October 27, 2008	
Berkeley Computer Vision Seminar	September 2, 2008	
CMU VASC Seminar	May 12, 2008	
Oxford Computer Vision Workshop	April 11, 2008	
Improving Spatial Support for Objects via Multiple Segmentations		
British Machine Vision Conference	September 12, 2007	

Computing Skills

Languages: C/C++ (12+ years), Matlab (8+ years), Java, Javascript, LATEX Systems: Strong Linux/Unix Skills, Mac OS X, Windows, MapReduce

Academic Activities

Reviewer for CVPR, ICCV, ECCV, NIPS, PAMI, IJCV, AAAI, ICML, SIGGRAPH ASIA

Awards

National Science Foundation Graduate Research Fellowship	2006-2009
Rensselaer Polytechnic Institute Alumni Scholarship	08/2001
Rensselaer Polytechnic Institute Mathematics/Science Medal Scholarship	05/2000
Valedictorian of High School (550+ students)	06/2001
National Physics Team Semifinalist (approx 180 students in USA)	05/2001

References

Alexei (Alyosha) Efros, Finmeccanica Associate Professor The Robotics Institute and Computer Science Department School of Computer Science Carnegie Mellon University (412) 268-1234 efros@cs.cmu.edu

Antonio Torralba, Associate Professor

Computer Science and Artificial Intelligence Laboratory Department of Electrical Engineering and Computer Science Massachusetts Institute of Technology (617) 324-0900 torralba@csail.mit.edu

Martial Hebert, Professor

The Robotics Institute School of Computer Science Carnegie Mellon University (412) 268-2585 hebert@ri.cmu.edu

Abhinav Gupta, Assistant Research Professor

The Robotics Institute School of Computer Science Carnegie Mellon University (412) 268-2067 abhinavg@cs.cmu.edu