

# **Utilizing Semantic Word Similarity Measures for Video Retrieval**

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## **Problem Overview**

#### Motivation

• It's not possible to train detectors for all of the concepts in the real world.

• Available concept detectors can be used for retrieving **new concepts**.

#### Goal

• Retrieving **new concepts** with the help of available (known) concept detectors and semantic word similarity measures.

#### **Problem Definition**



## 1. Visual Co-occurrence

The co-occurrence of concepts in the same scene.

 $p(c_{Car}) = 0.067$  $p(c_{Truck}) = 0.011$ PM  $p(c_{Car} \& c_{Truck}) = 0.0072$ 

 $Sim_{Visual}(c_{Car}, c_{Truck}) = Sigmoid(PMI_{Visual}(c_{Car}, c_{Truck})) = 0.91$ 

# 2. Semantic Word Similarity

Semantic word similarity is the relatedness of two concepts and it's generally a common sense knowledge that we build for years.

#### 2.1. PMI-IR Similarity

Pointwise mutual information using data collected by information retrieval [Turney'01].

 $p(c_{Car}) = 0.097$ 

 $PMI_{IR}(c_{Car}, c_{Truck}) = \log\left(\frac{p(c_{Car} \& c_{Truc})}{p(c_{Car})p(c_{Truc})}\right)$ 

 $Sim_{PMI-IR}(c_{Car}, c_{Truck}) = Sigmoid(PMI_{IR}(c_{Car}, c_{Truck})) = 0.72$ 

#### 2.2. Lin's Similarity Measure

concepts and normalize it [Lin'98].

$$Sim_{Lin}(c_{Car}, c_{Truck}) = \frac{2 \times IC}{IC(c)}$$

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# Similarity Measures

$$H_{Visual}(c_{Car}, c_{Truck}) = \log\left(\frac{p(c_{Car} \& c_{Truck})}{p(c_{Car})p(c_{Truck})}\right) = 2.3244$$

 $p(c_{Truck}) = 0.020$   $p(c_{Car} \& c_{Truck}) = 0.0049$ 

$$\binom{k}{c_{k}} = \log \left( \frac{hits(c_{Car} \ NEAR \ c_{Truck}) \times WebSize}{hits(c_{Car})hits(c_{Truck})} \right) = 0.943$$

The key idea is to find the maximum information shared by two

Vehicle

WordNet

Truck

Car

vehicle  $\mathcal{J}(\overline{LCS(c_{Car}, c_{Truck}))} = 0.78$  $(c_{Car}) + IC(c_{Truck})$ 

# **Retrieving New Concepts**

The score for the **new concept** is the linear combination of scores of **known concepts** and similarities between new concept and known concepts.





### Results



A comparison of different retrieval methods using Average Precision. MAP (Mean Average Precision) is shown at far right





Top 100 retrieval results for the new concept "shouting"

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Semantic Retrieval Method		MAP'06	MAP'07
Vision Based	PMI-IR	3.4%	3.6%
Retrieval	Lin's Similarity	1.1%	2.1%
Text Based Retrieval		1.9%	1.6%
Average Fusion (Text + PMI-IR)		3.7%	3.5%

